

# CS 106X, Lecture 22

## Graphs; BFS; DFS

reading:

*Programming Abstractions in C++*, Chapter 18

# Plan For Today

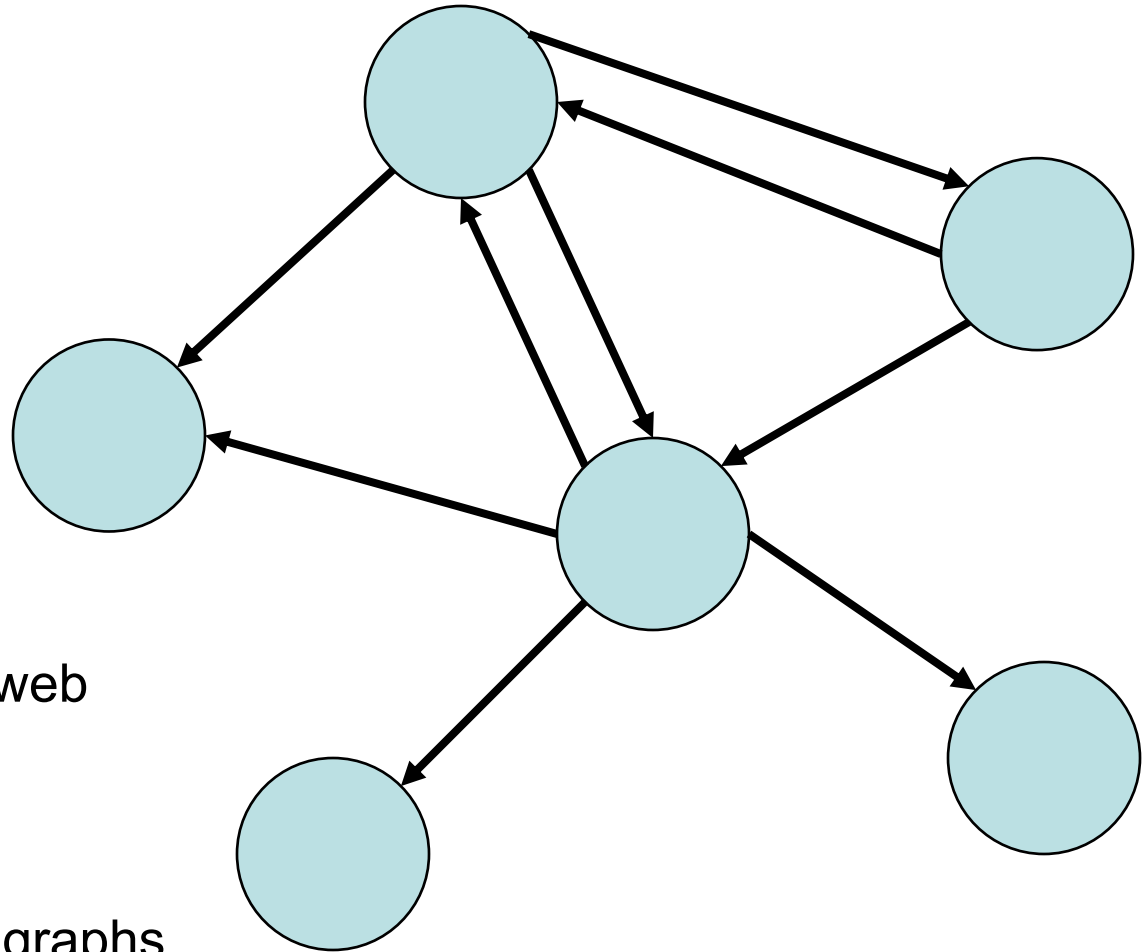
- **Recap:** Graphs
- **Practice:** Twitter Influence
- Depth-First Search (DFS)
- Announcements
- Breadth-First Search (BFS)

# Plan For Today

- **Recap:** Graphs
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# Graphs

A graph consists of a set of **nodes** connected by **edges**.



## Graphs can model:

- Sites and links on the web
- Disease outbreaks
- Social networks
- Geographies
- Task and dependency graphs
- and more...

# Graphs

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**Nodes:** *degree* (# connected edges)

**Nodes:** *in-degree* (directed, # in-edges)

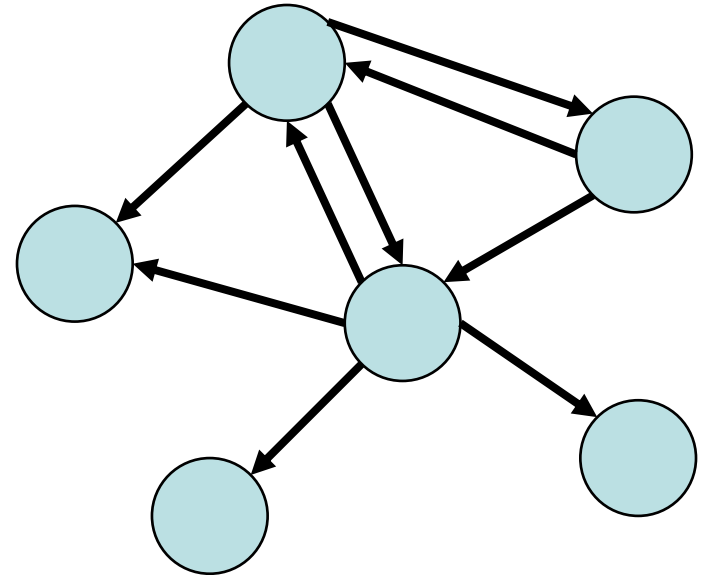
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**Path:** sequence of nodes/edges from one node to another

**Path:** node  $x$  is reachable from node  $y$  if a path exists from  $y$  to  $x$ .

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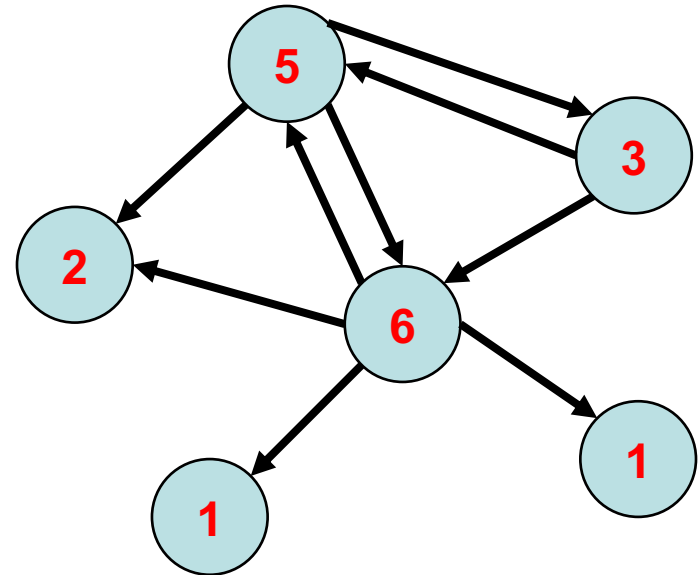
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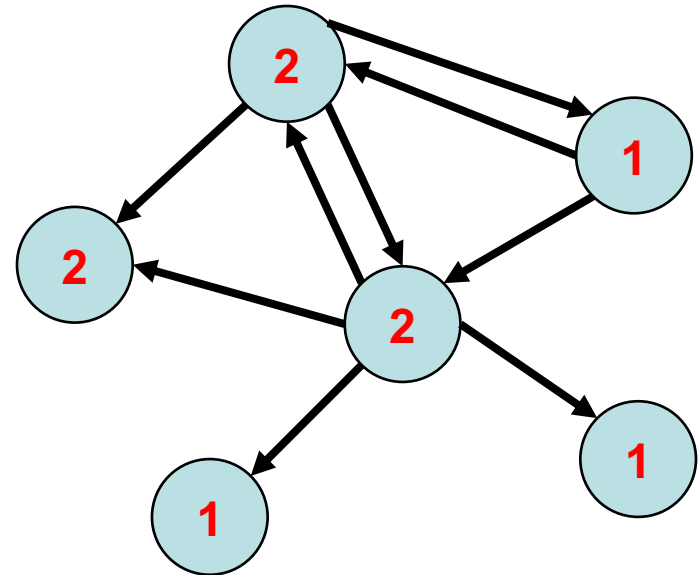
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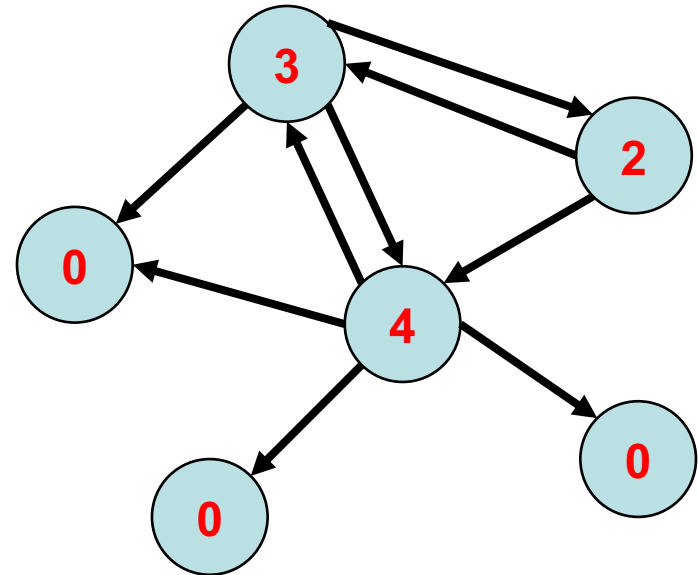
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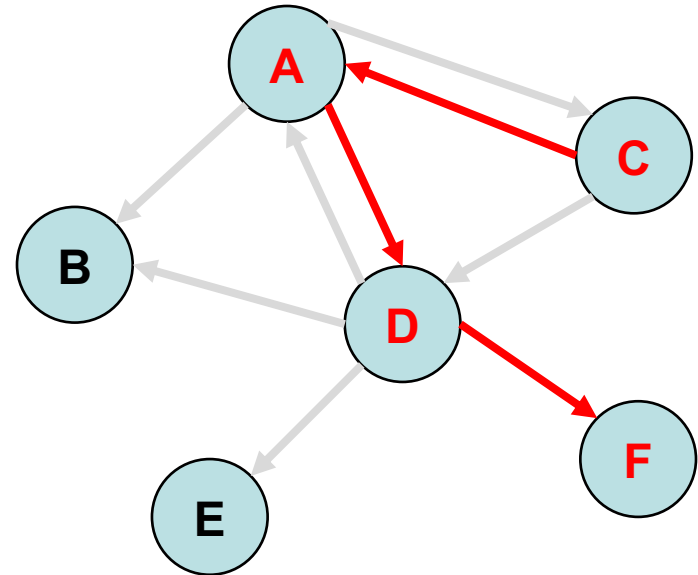
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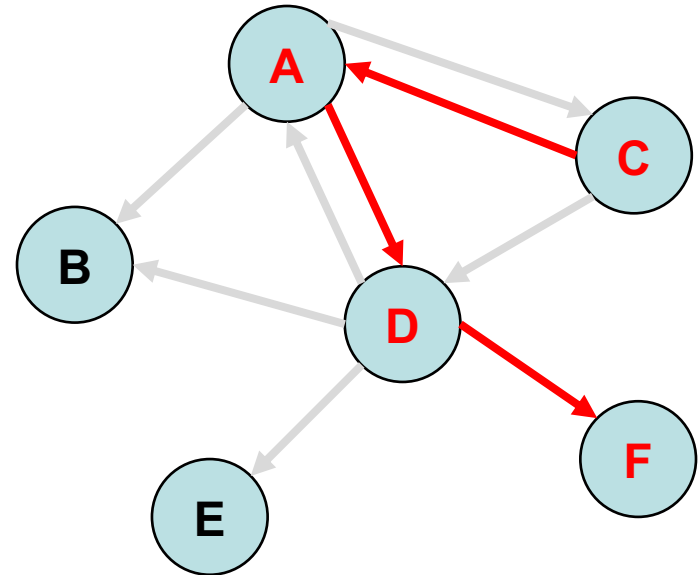
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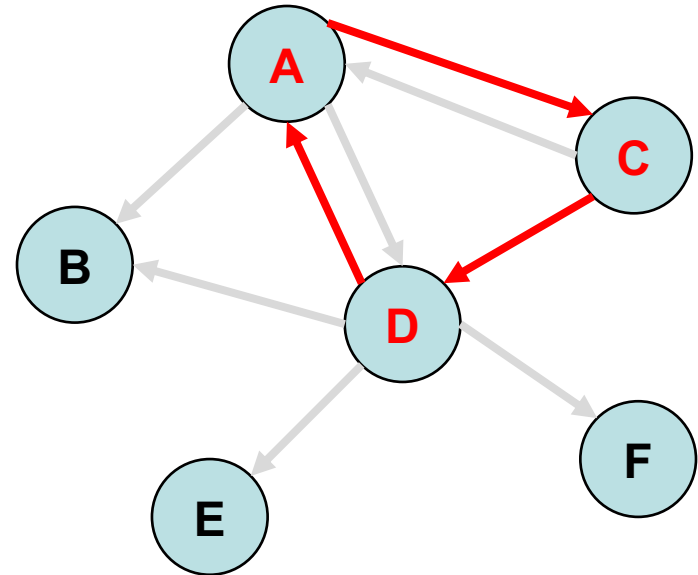
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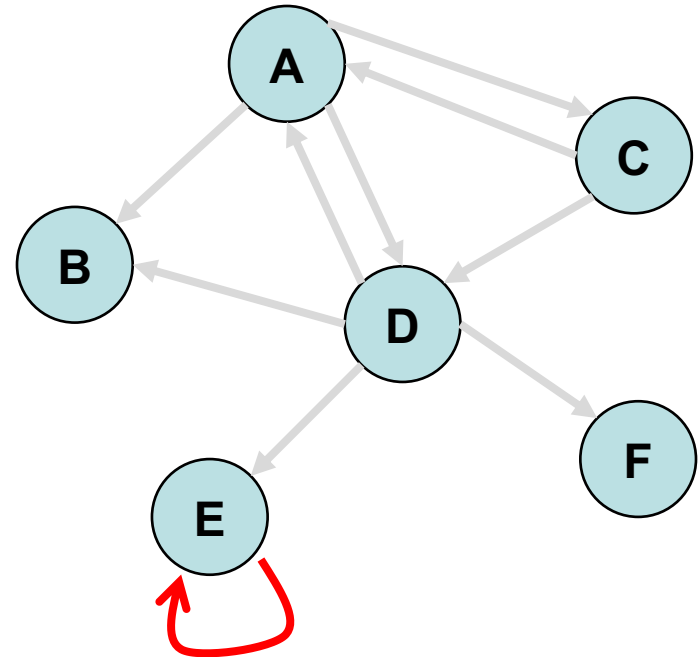
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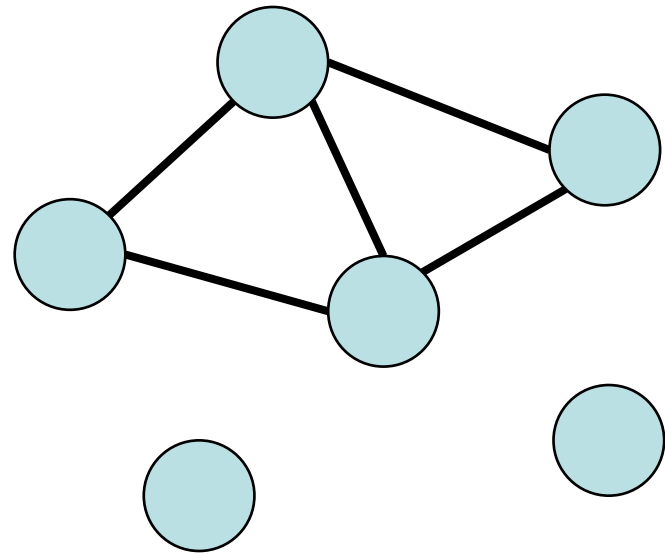
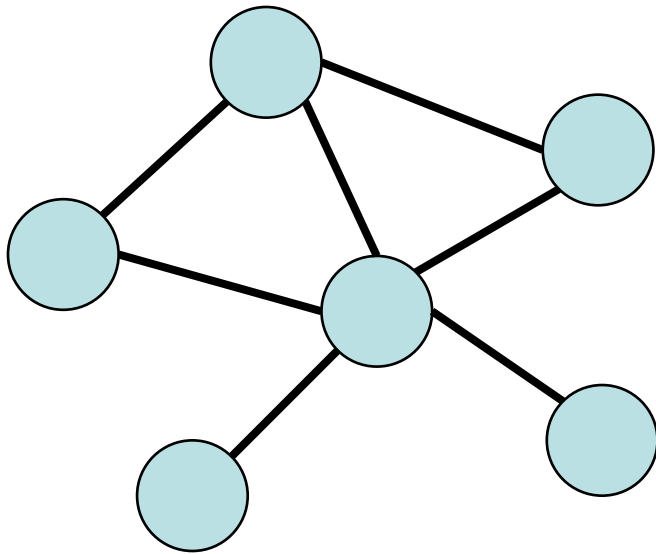
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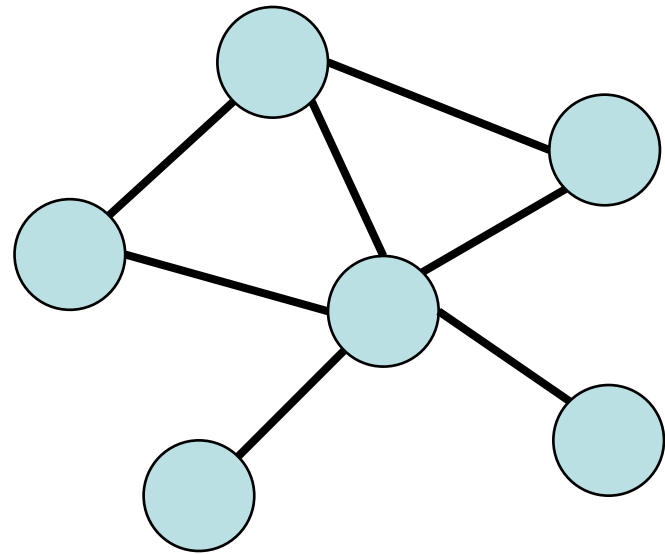
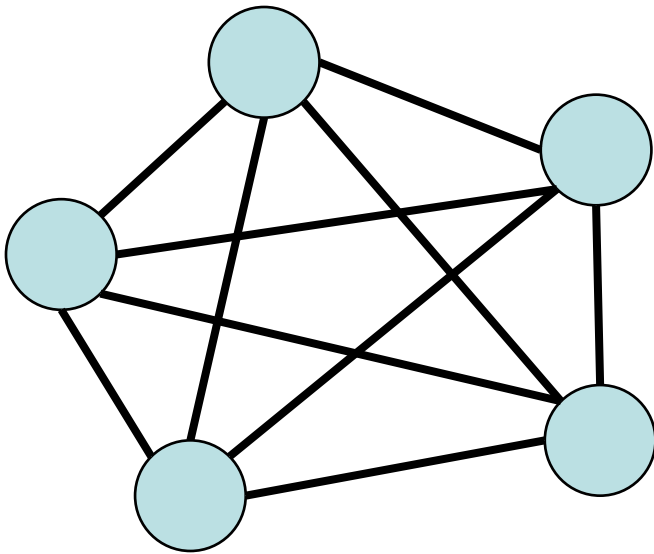
# Graph Properties

A graph is **connected** if every node is reachable from every other node.



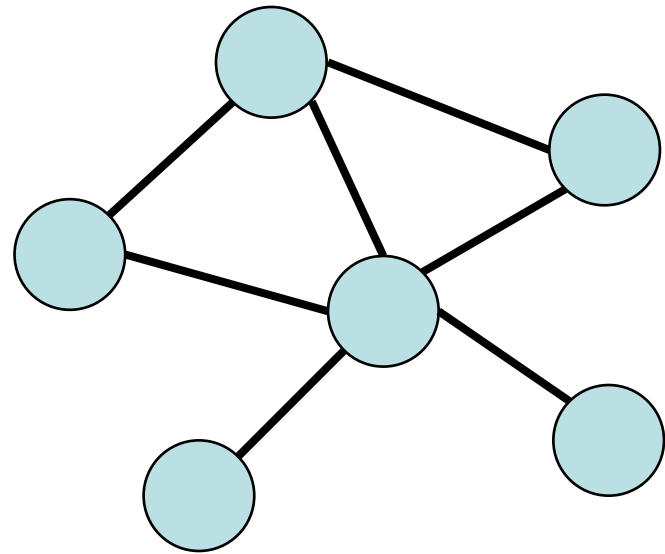
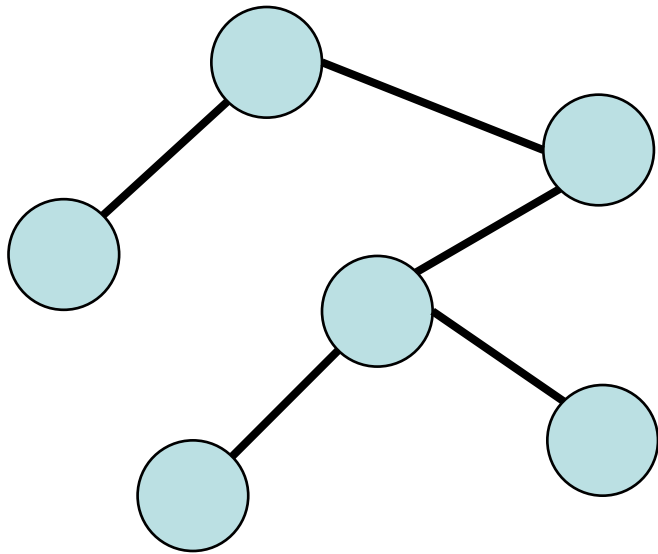
# Graph Properties

A graph is **complete** if every node has a direct edge to every other node.



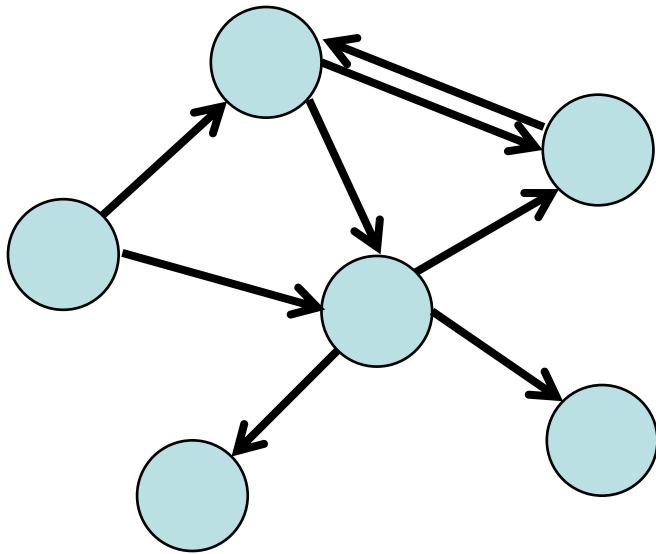
# Graph Properties

A graph is **acyclic** if it does not contain any cycles.

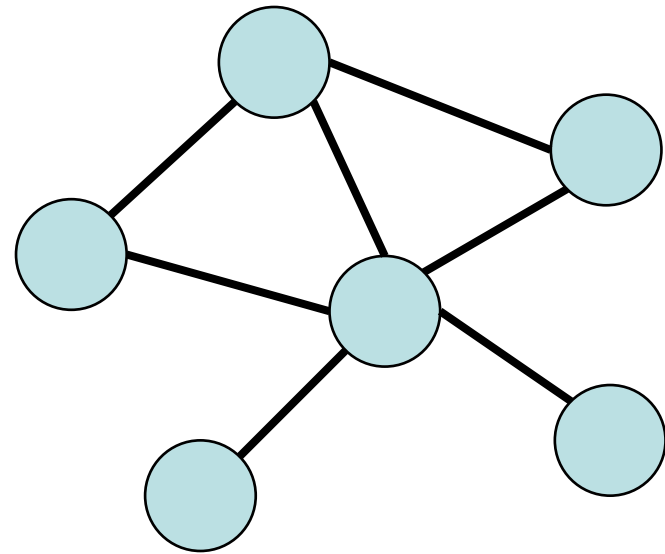


# Graph Properties

A graph is **directed** if its edges have direction, or **undirected** if its edges do not have direction (aka are bidirectional).



**directed**

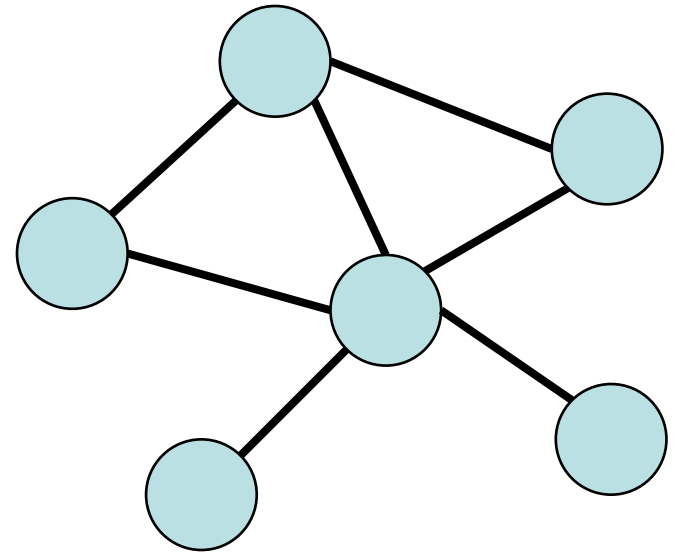


**undirected**



# Graph Properties

- Connected or unconnected
- Acyclic
- Directed or undirected
- Weighted or unweighted
- Complete



# Plan For Today

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# Twitter Influence

- Twitter lets a user follow another user to see their posts.
- Following is directional (e.g. I can follow you but you don't have to follow me back ☹)
- Let's define being *influential* as having a high number of *followers-of-followers*.
  - Reasoning: doesn't just matter how many people follow you, but whether the people who follow you reach a large audience.
- Write a function **mostInfluential** that reads a file of Twitter relationships and outputs the most influential user.



# BasicGraph members

```
#include "basicgraph.h"    // a directed, weighted graph
```

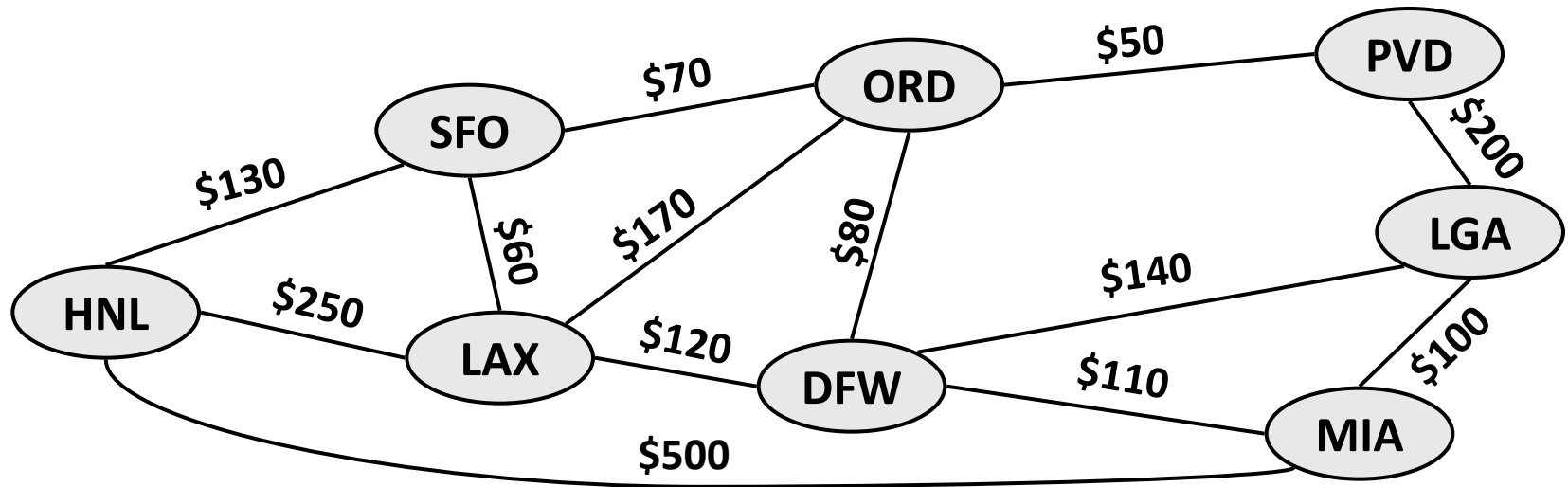
<b><i>g</i></b> .addEdge( <b><i>v1</i></b> , <b><i>v2</i></b> );	adds an edge between two vertexes
<b><i>g</i></b> .addVertex( <b><i>name</i></b> );	adds a vertex to the graph
<b><i>g</i></b> .clear();	removes all vertexes/edges from the graph
<b><i>g</i></b> .getEdgeSet() <b><i>g</i></b> .getEdgeSet( <b><i>v</i></b> )	returns all edges, or all edges that start at <b><i>v</i></b> , as a Set of pointers
<b><i>g</i></b> .getNeighbors( <b><i>v</i></b> )	returns a set of all vertices that <b><i>v</i></b> has an edge to
<b><i>g</i></b> .getVertex( <b><i>name</i></b> )	returns pointer to vertex with the given name
<b><i>g</i></b> .getVertexSet()	returns a set of all vertexes
<b><i>g</i></b> .isNeighbor( <b><i>v1</i></b> , <b><i>v2</i></b> )	returns true if there is an edge from vertex <b><i>v1</i></b> to <b><i>v2</i></b>
<b><i>g</i></b> .isEmpty()	returns true if queue contains no vertexes/edges
<b><i>g</i></b> .removeEdge( <b><i>v1</i></b> , <b><i>v2</i></b> );	removes an edge from the graph
<b><i>g</i></b> .removeVertex( <b><i>name</i></b> );	removes a vertex from the graph
<b><i>g</i></b> .size()	returns the number of vertexes in the graph
<b><i>g</i></b> .toString()	returns a string such as "{a, b, c, a -> b}"

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- **Depth-First Search (DFS)**
- Announcements
- Breadth-First Search (BFS)

# Searching for paths

- Searching for a path from one vertex to another:
  - Sometimes, we just want *any* path (or want to know there *is* a path).
  - Sometimes, we want to minimize path *length* (# of edges).
  - Sometimes, we want to minimize path *cost* (sum of edge weights).



# Finding Paths

- Easiest way: Depth-First Search (DFS)
  - Recursive backtracking!
- Finds a path between two nodes if it exists
  - Or can find all the nodes **reachable** from a node
    - Where can I travel to starting in San Francisco?
    - If all my friends (and their friends, and so on) share my post, how many will eventually see it?

# Depth-first search (18.4)

- **depth-first search (DFS)**: Finds a path between two vertices by exploring each possible path as far as possible before backtracking.
  - Often implemented recursively.
  - Many graph algorithms involve *visiting* or *marking* vertices.

- DFS from *a* to *h* (assuming A-Z order) visits:

- a

- b

- e

- f

- c

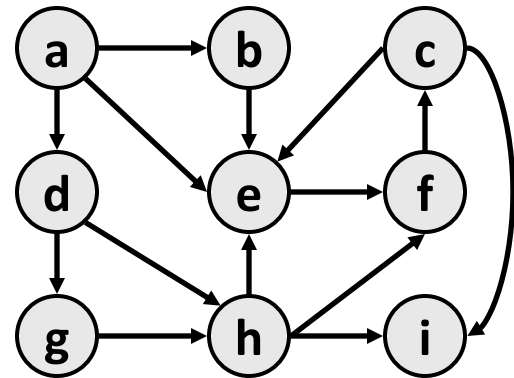
- i

- d

- g

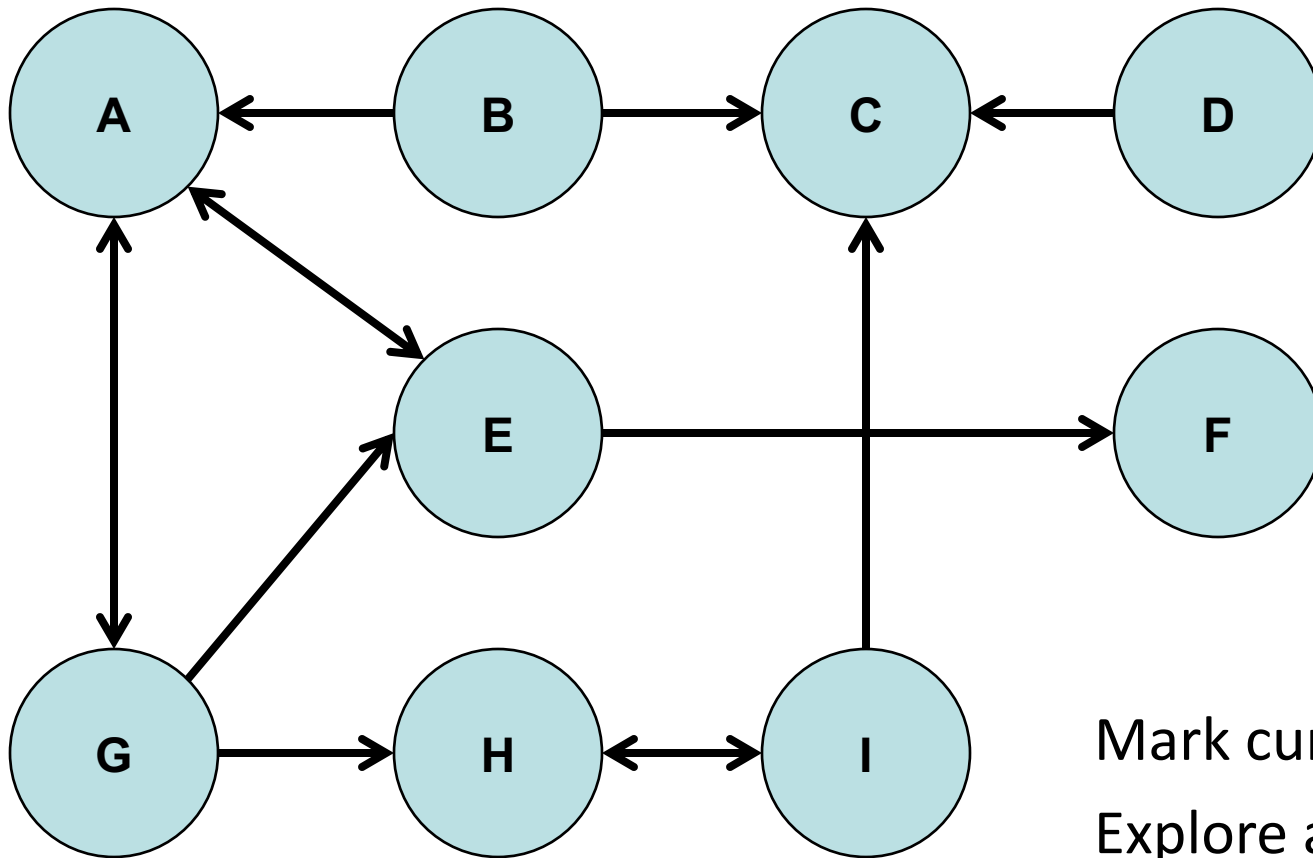
- h

- path found: {a, d, g, h}



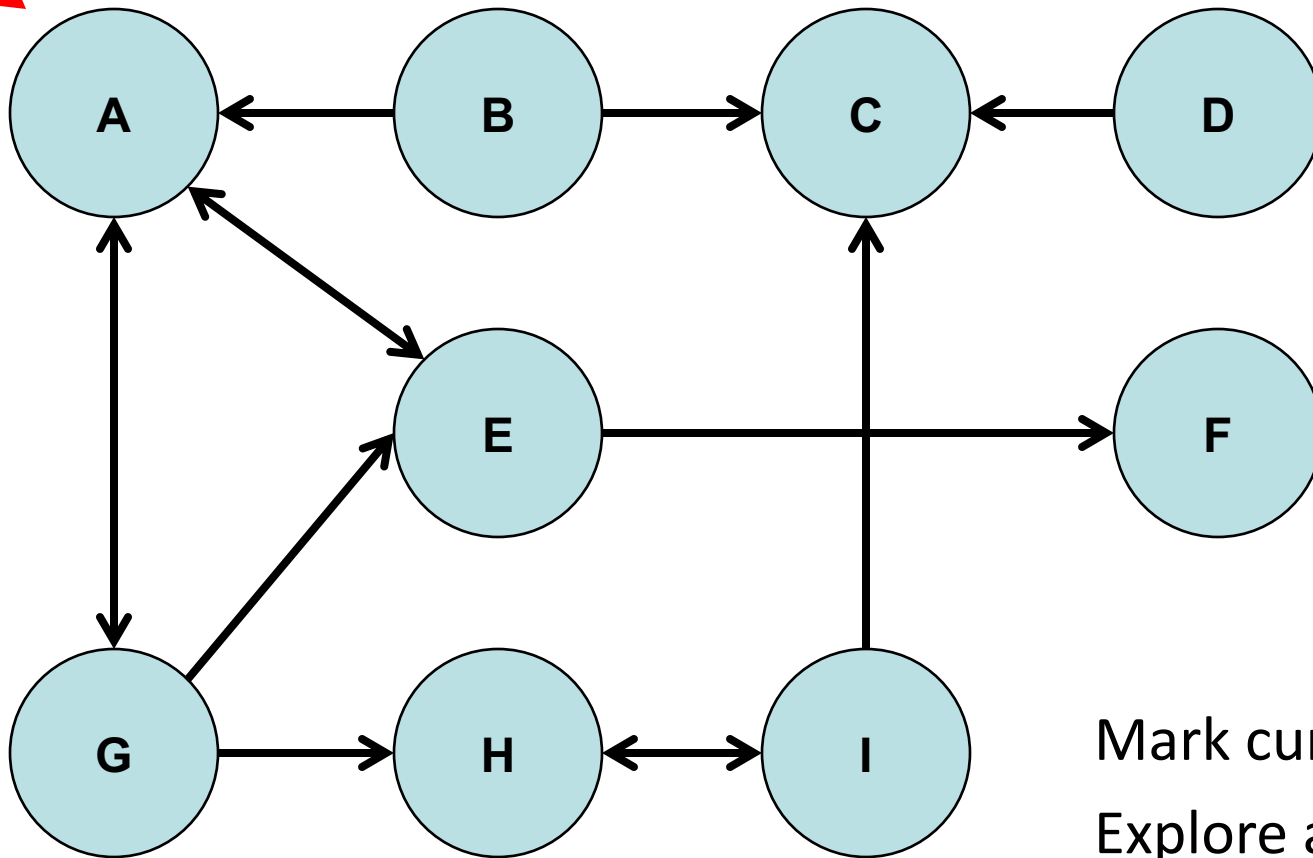


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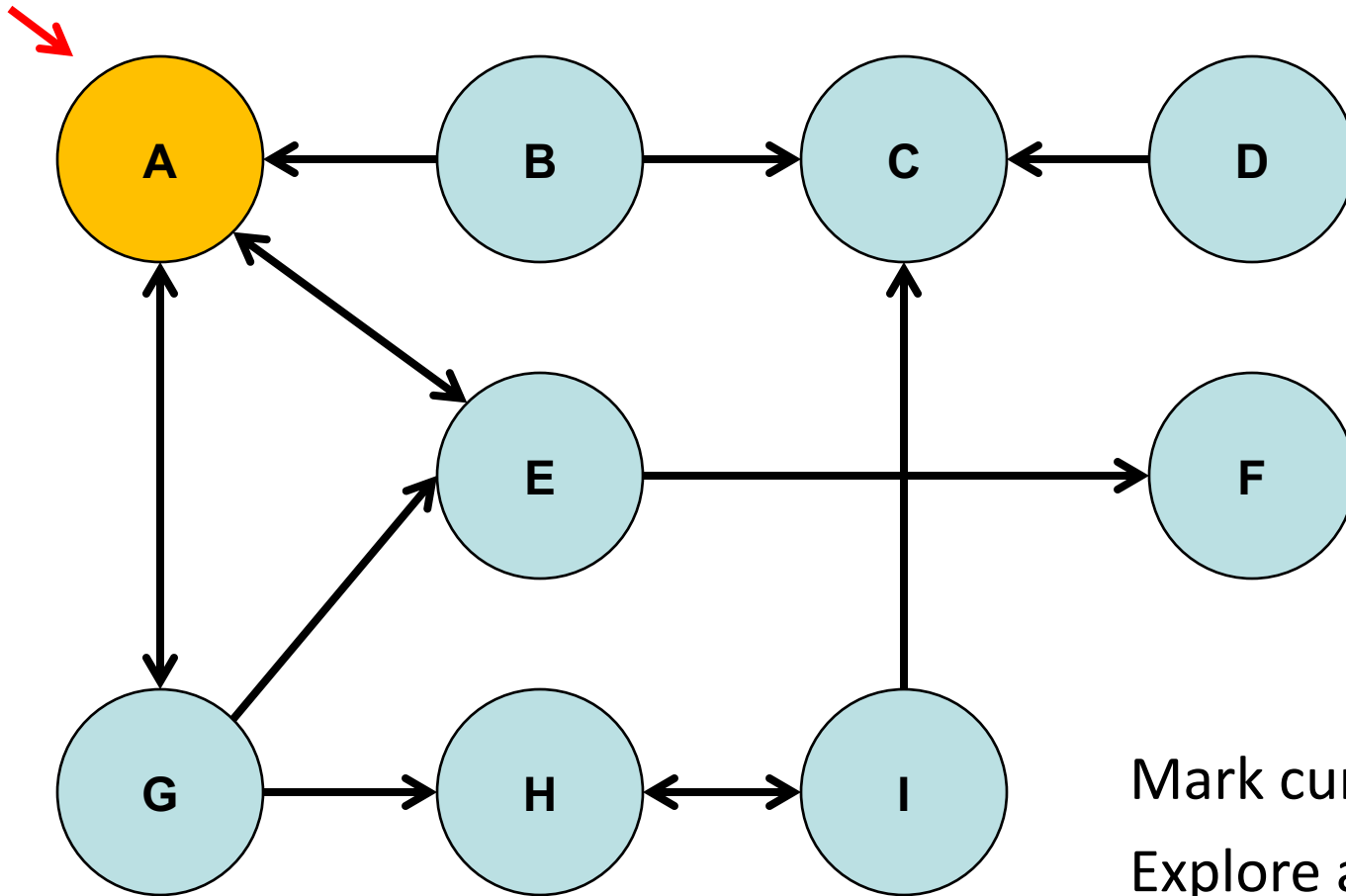
Mark current as visited  
Explore all the unvisited  
nodes from this node

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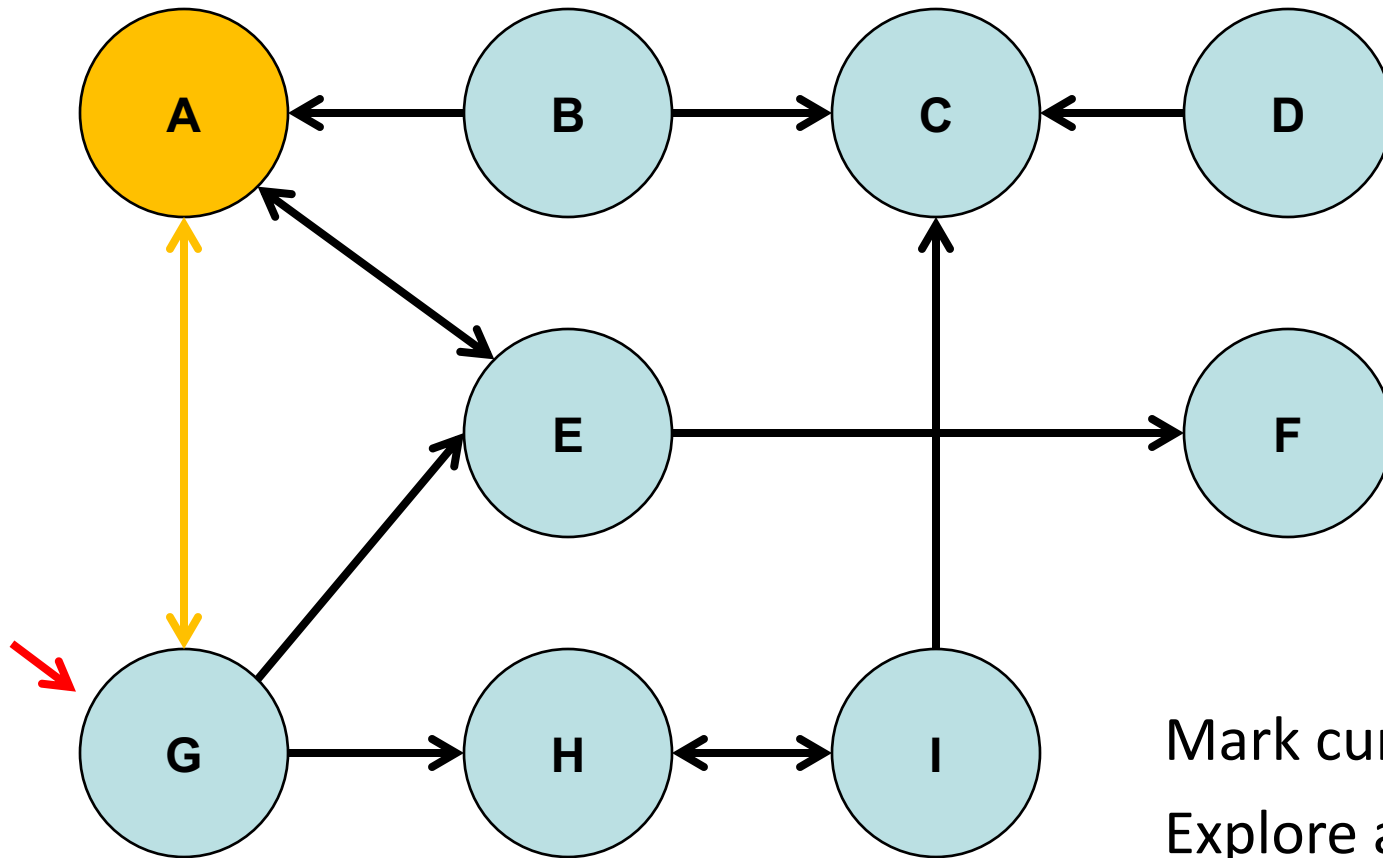
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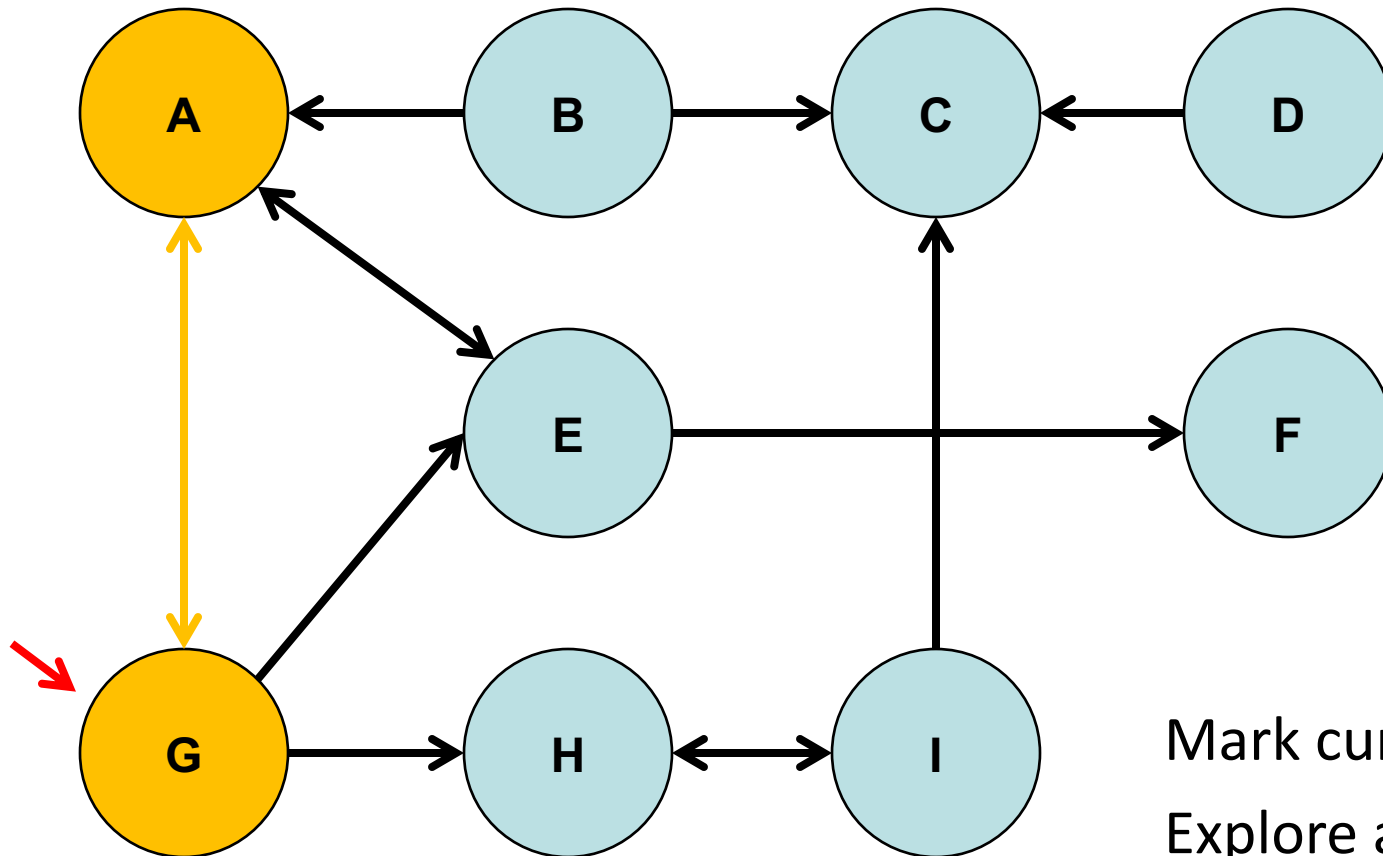
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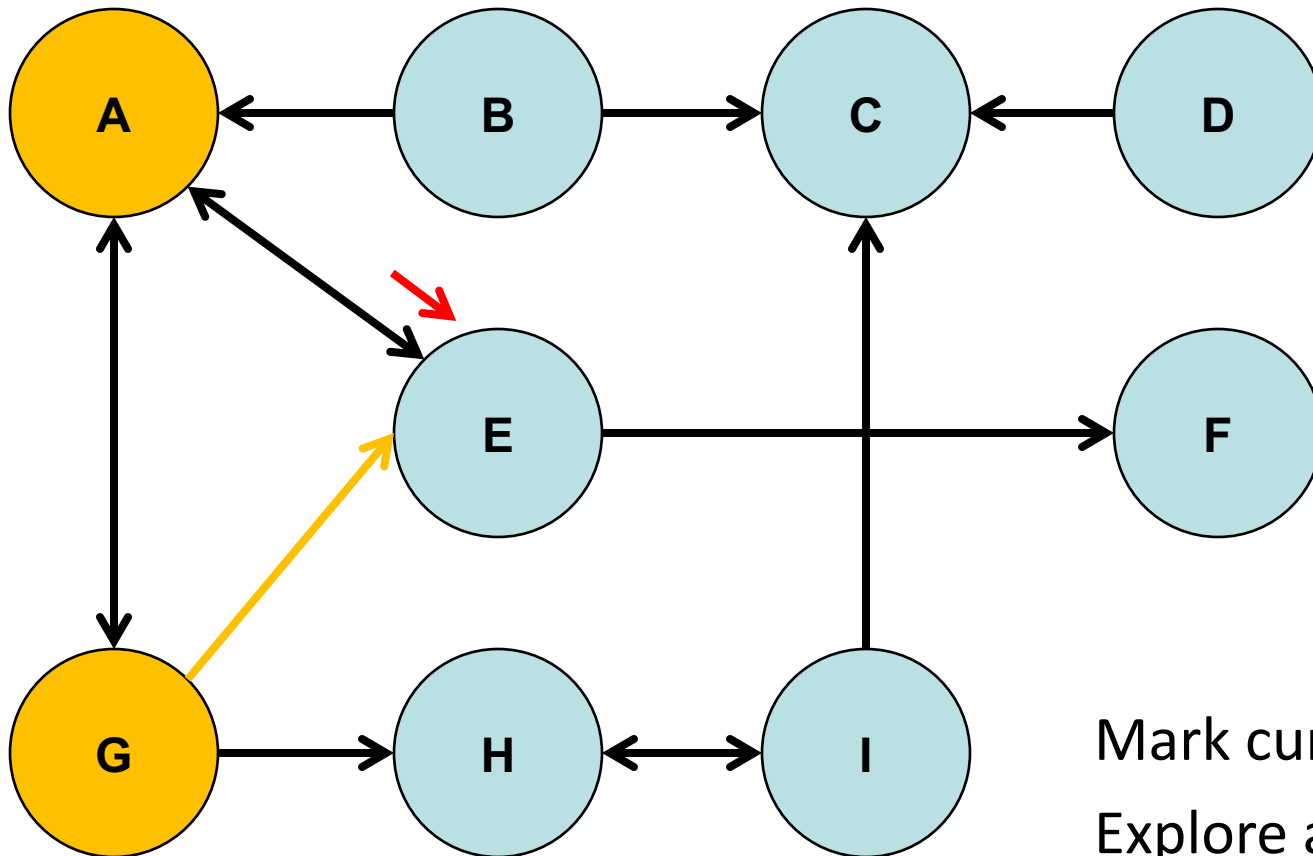
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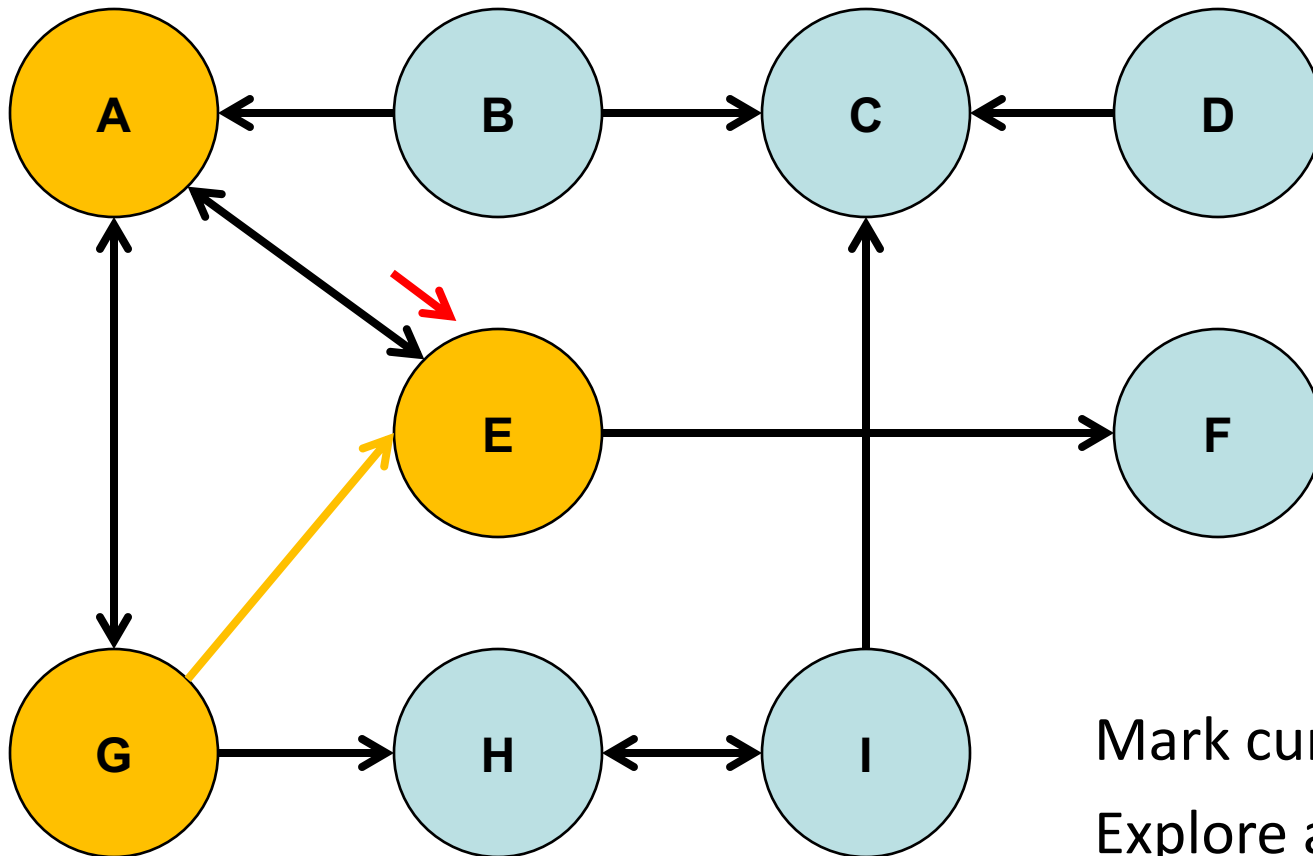
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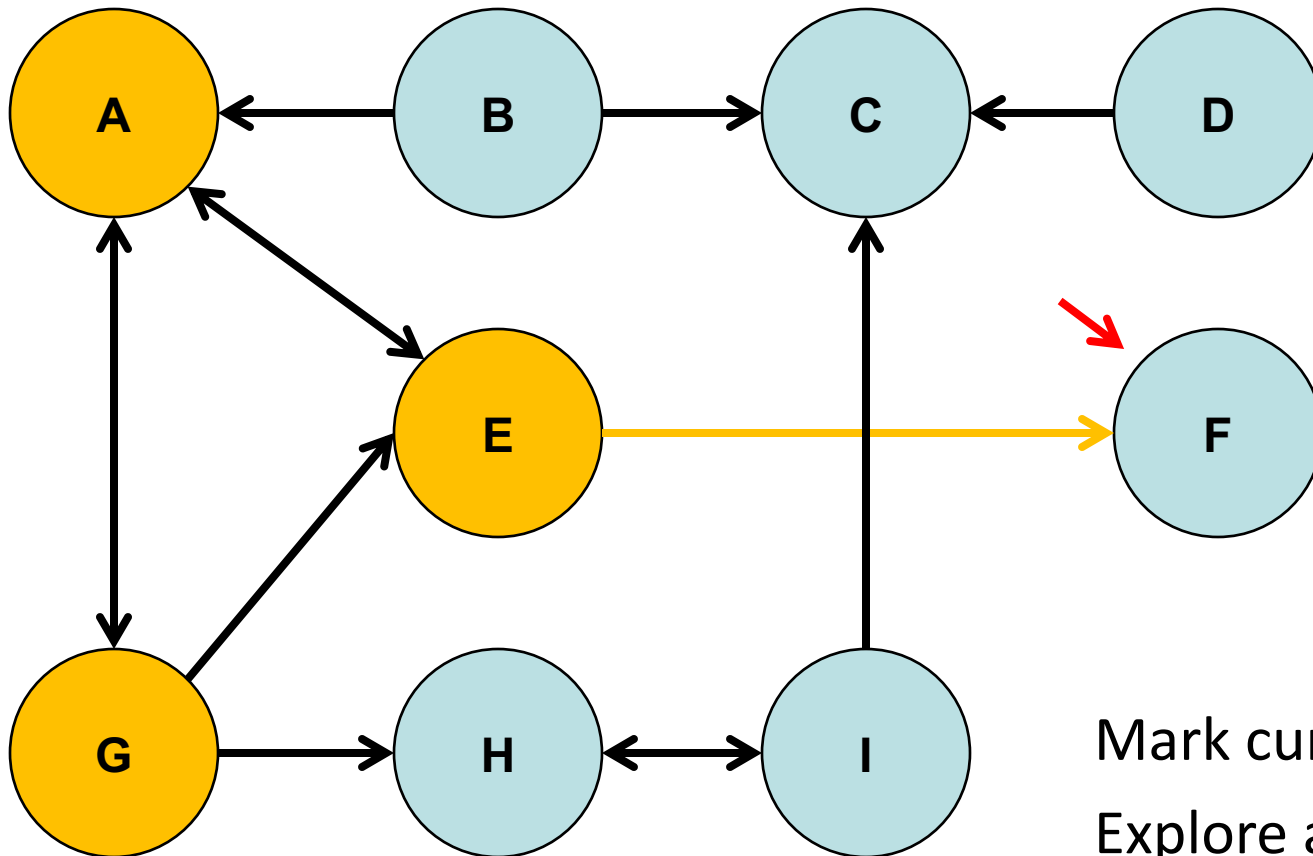
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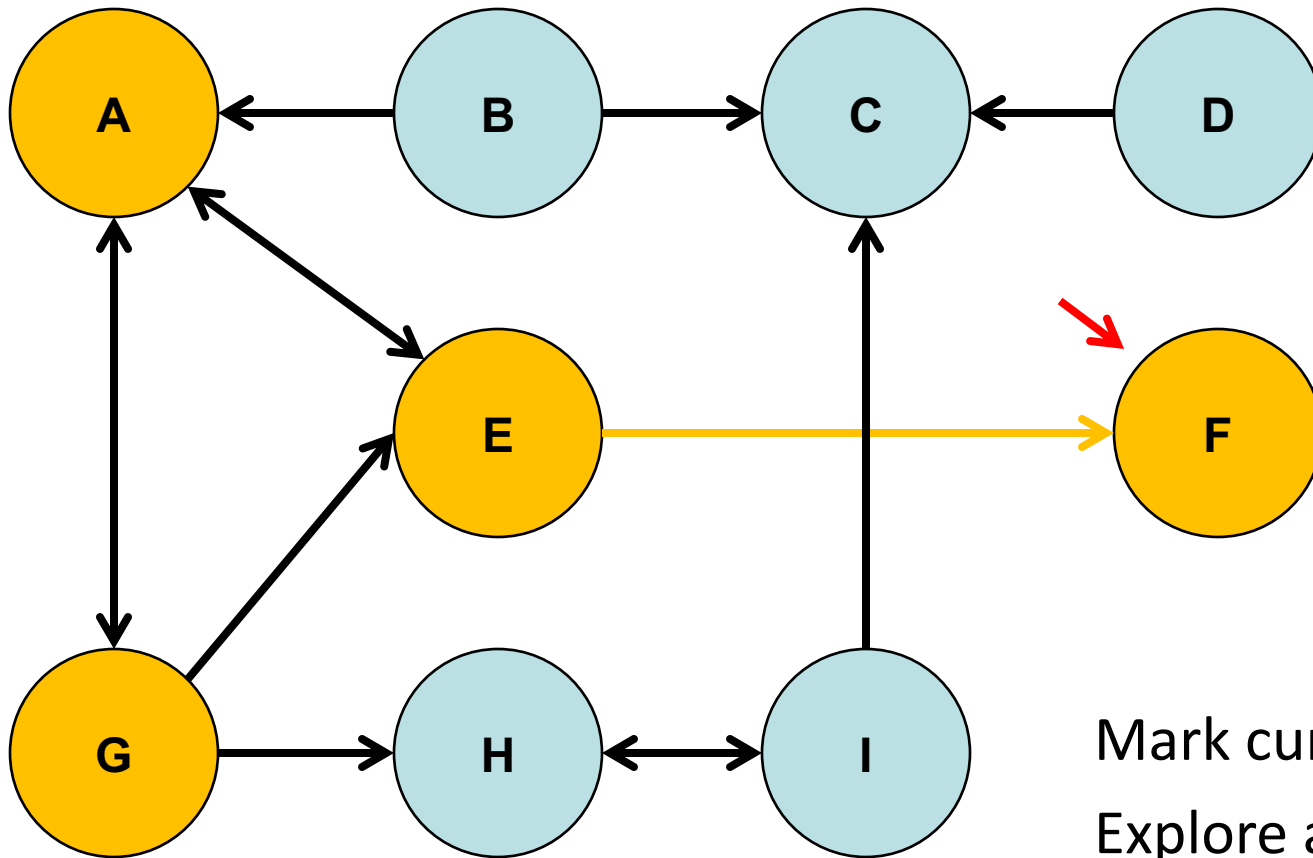
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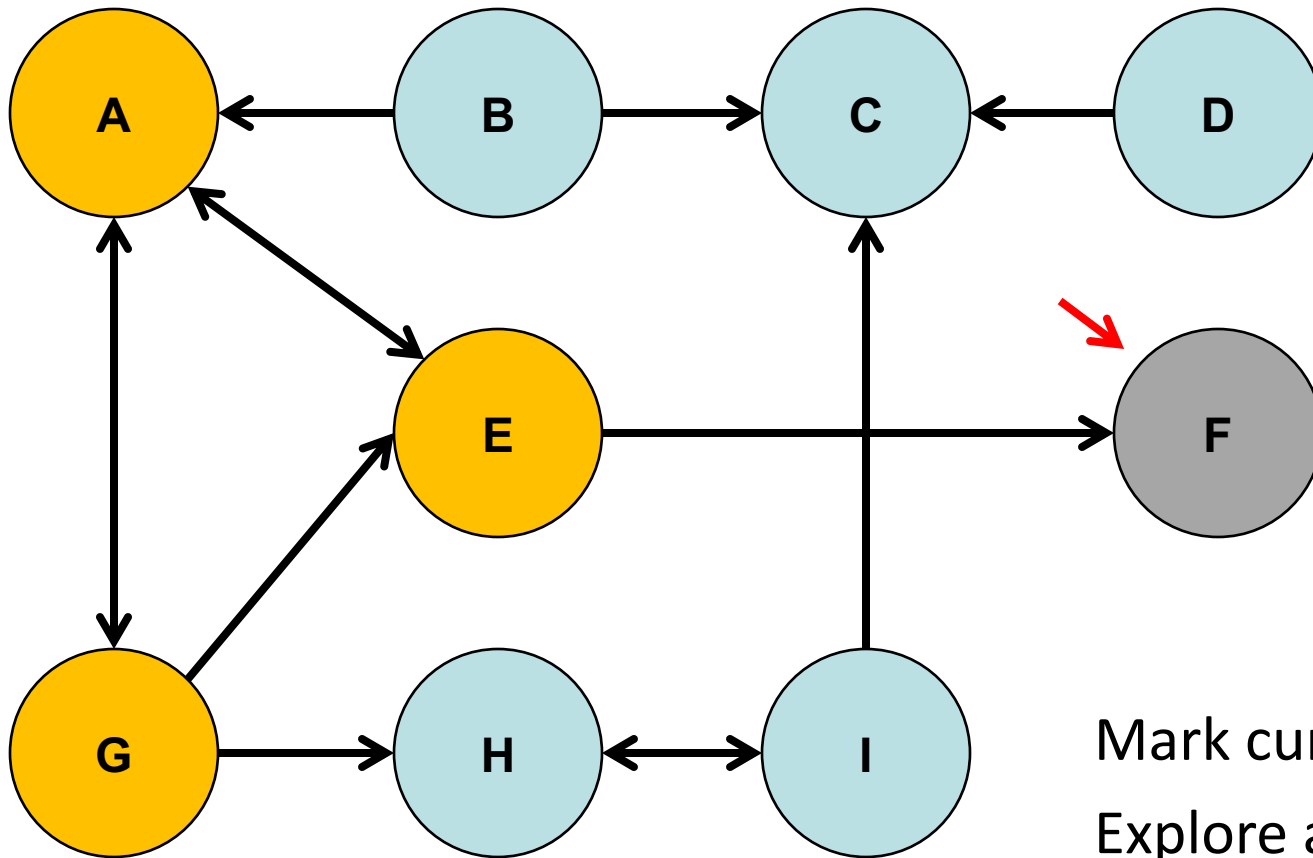


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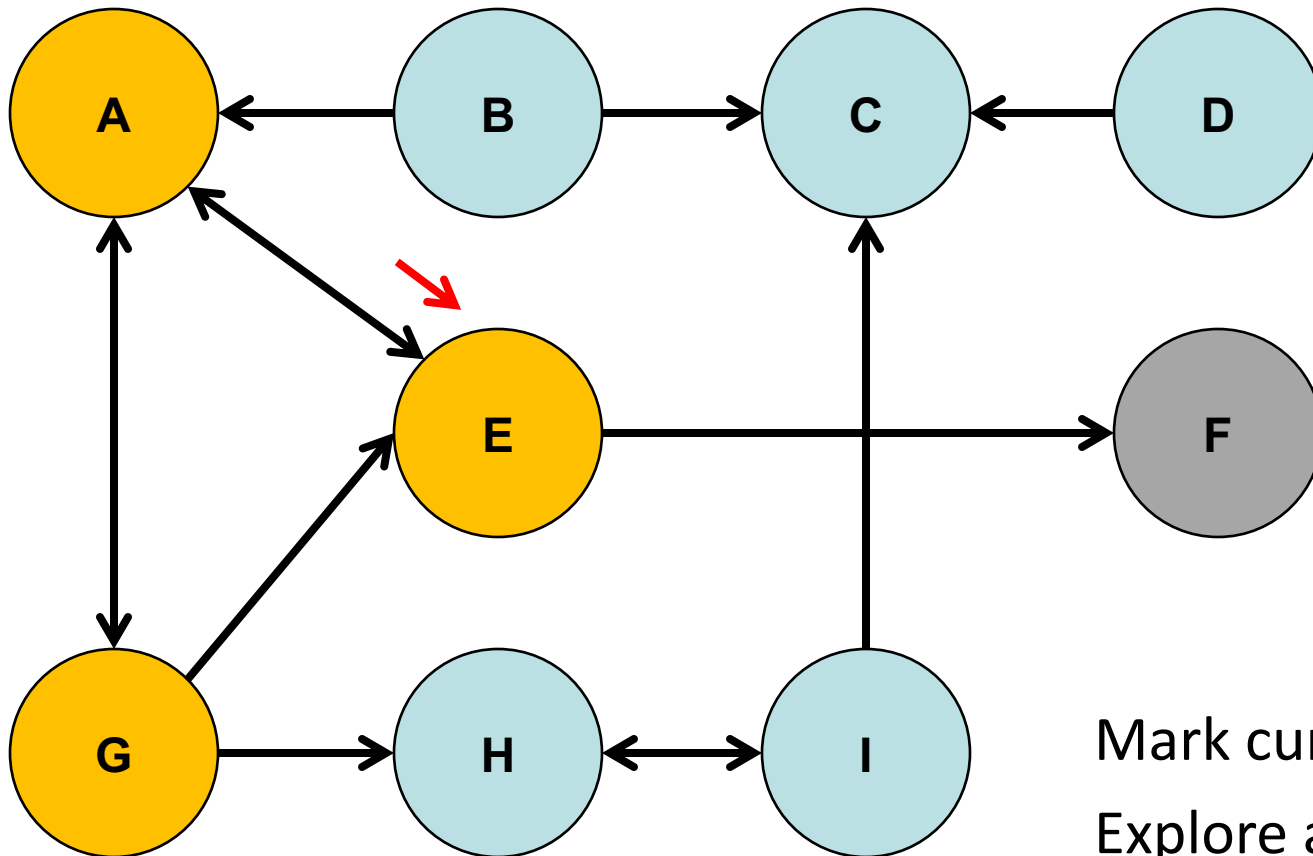
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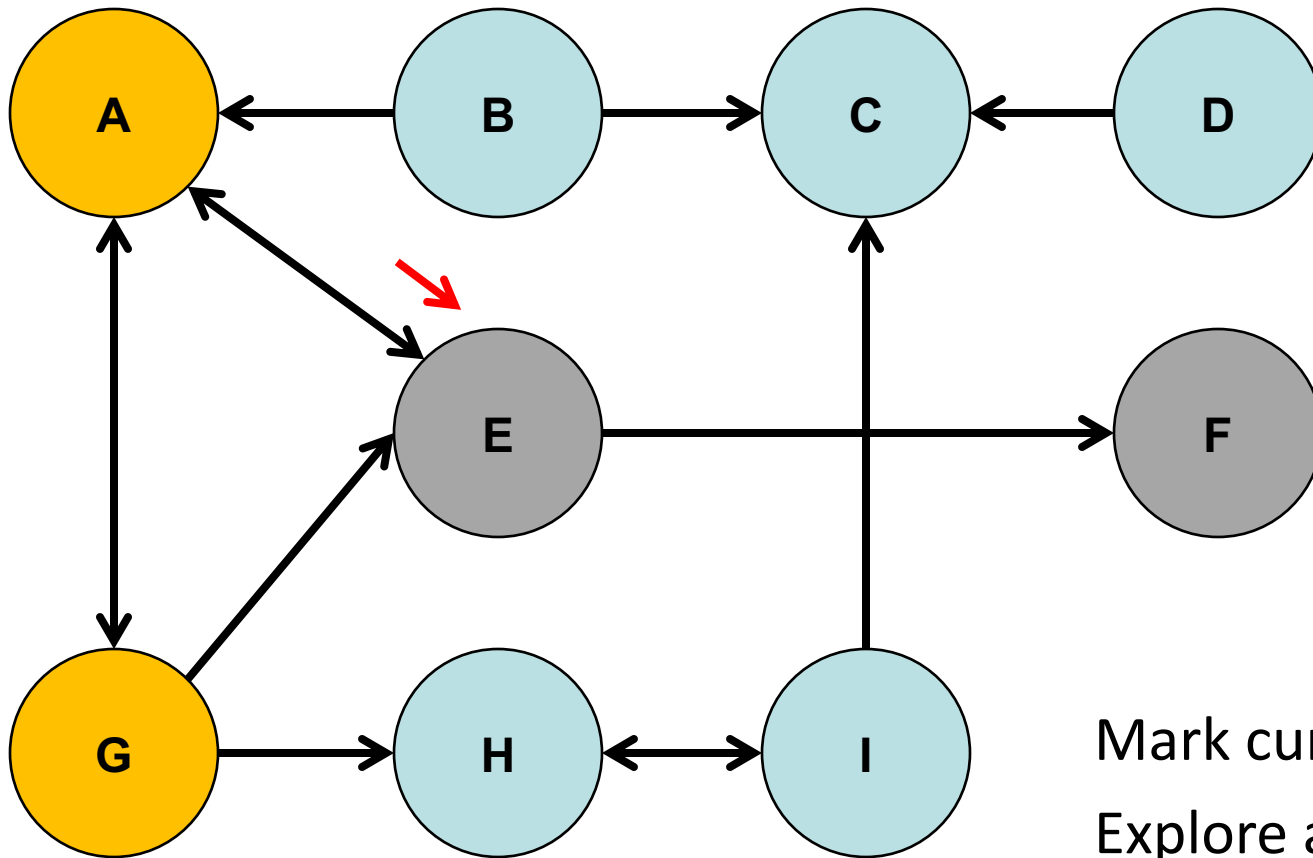
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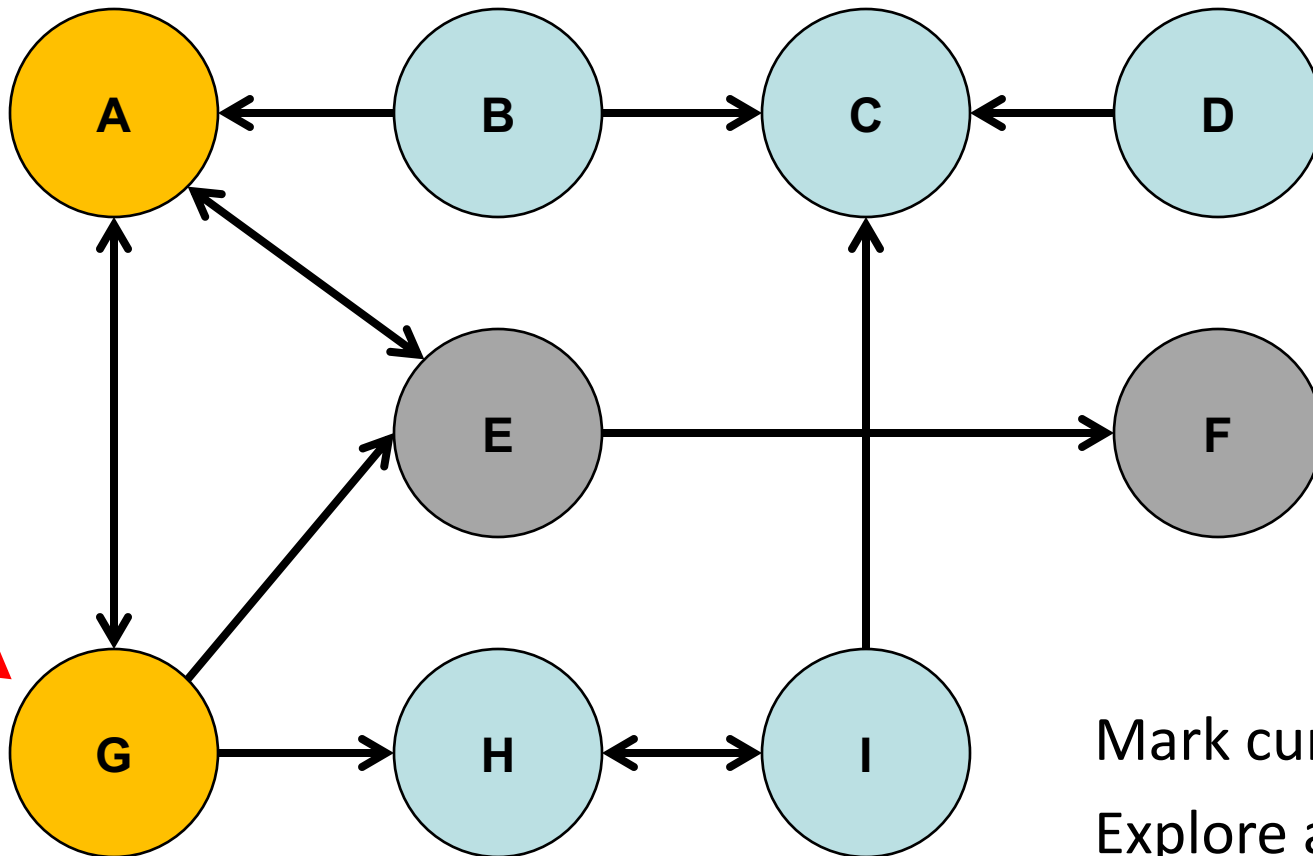
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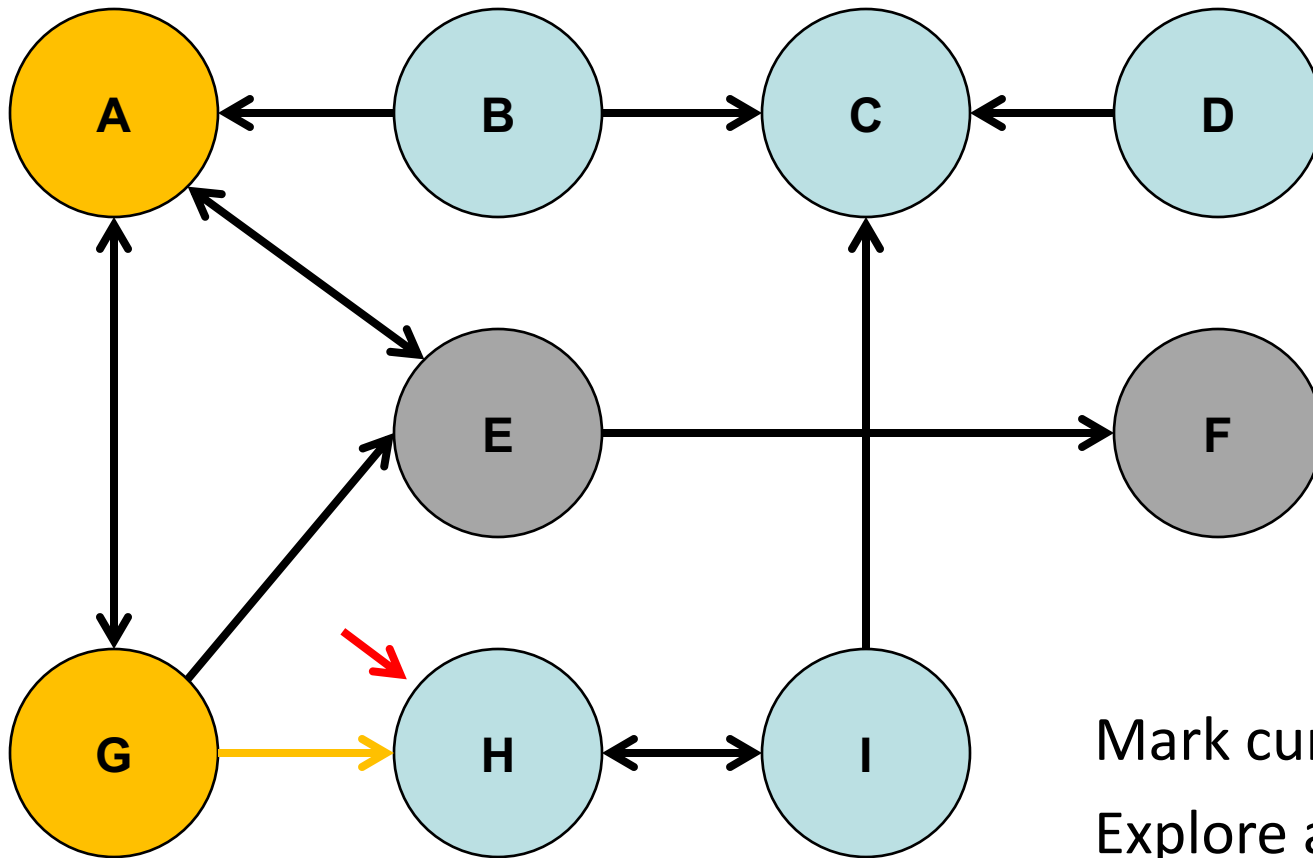
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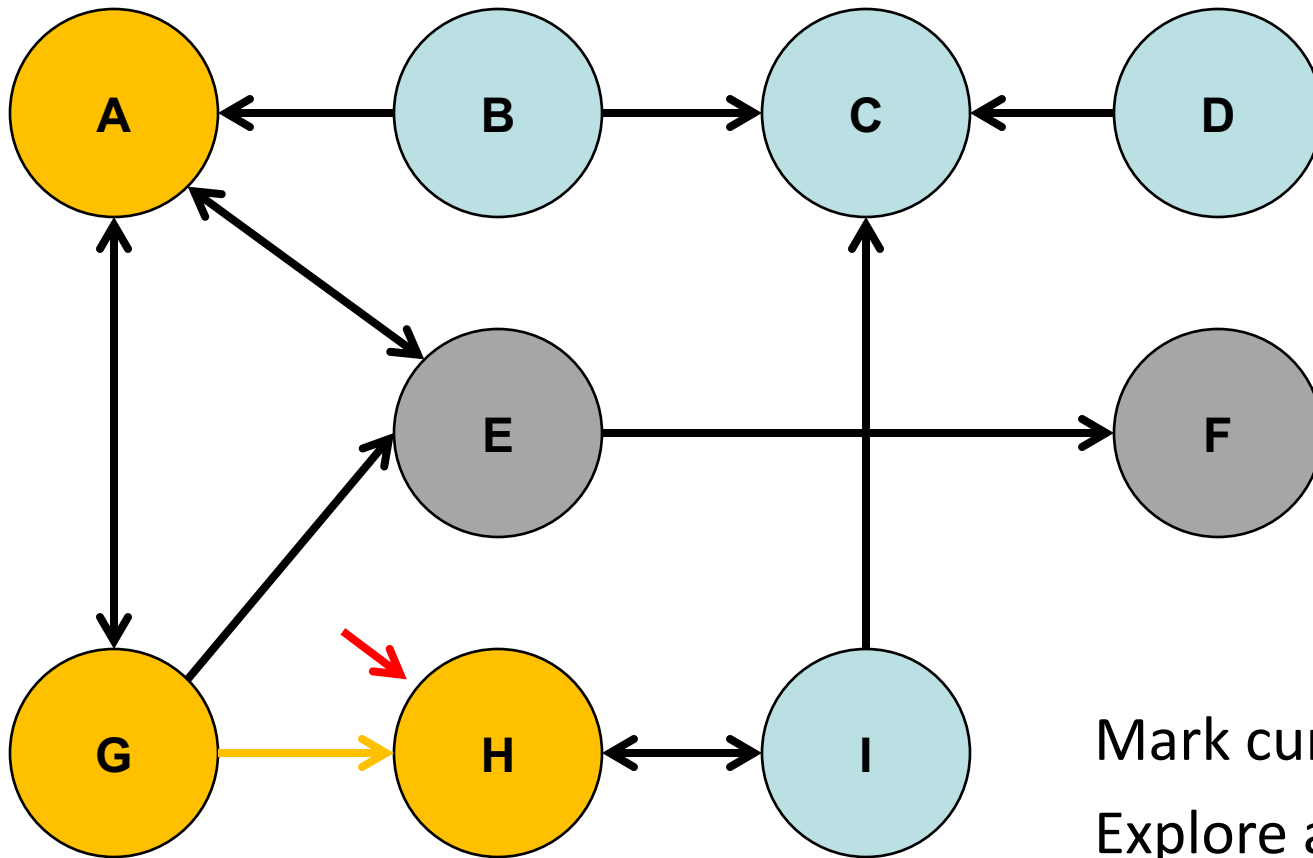
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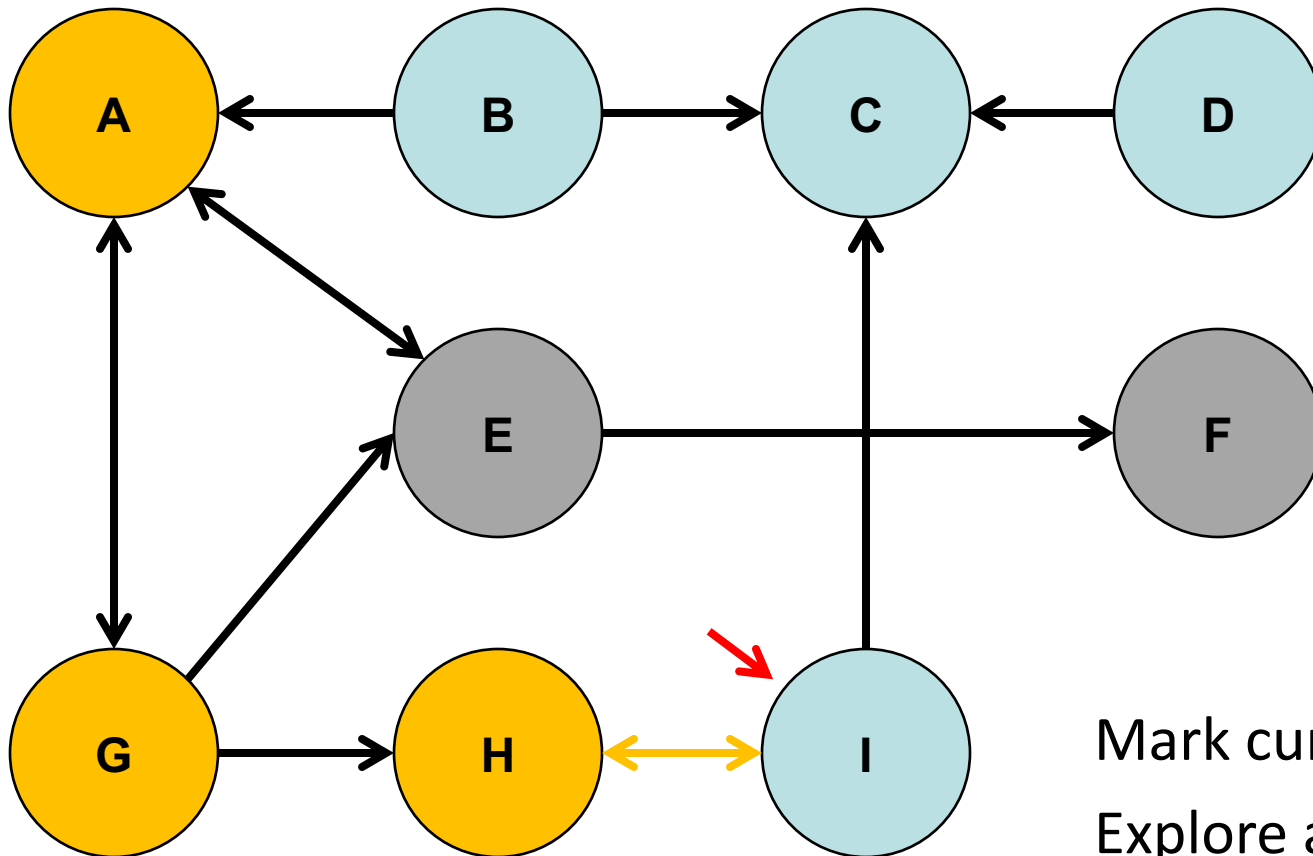
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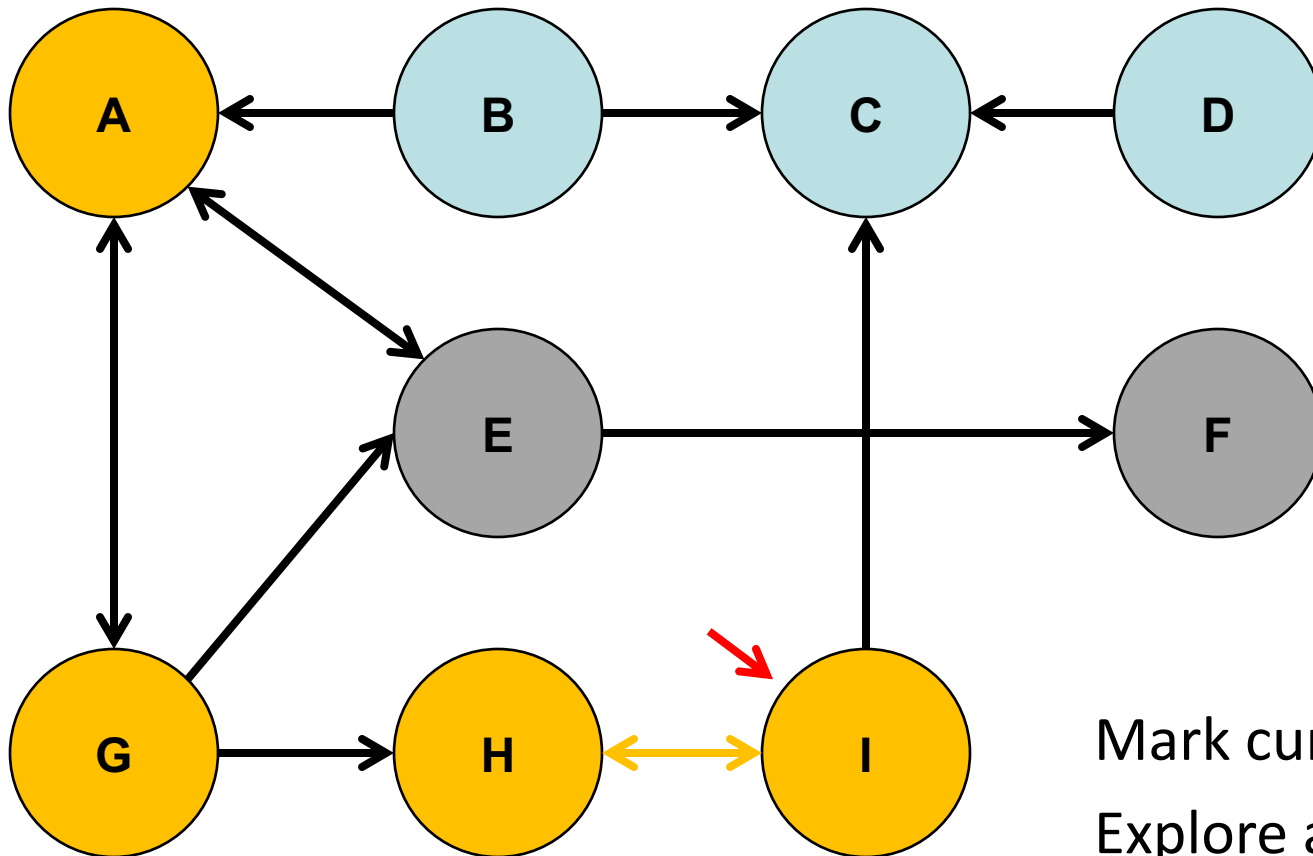
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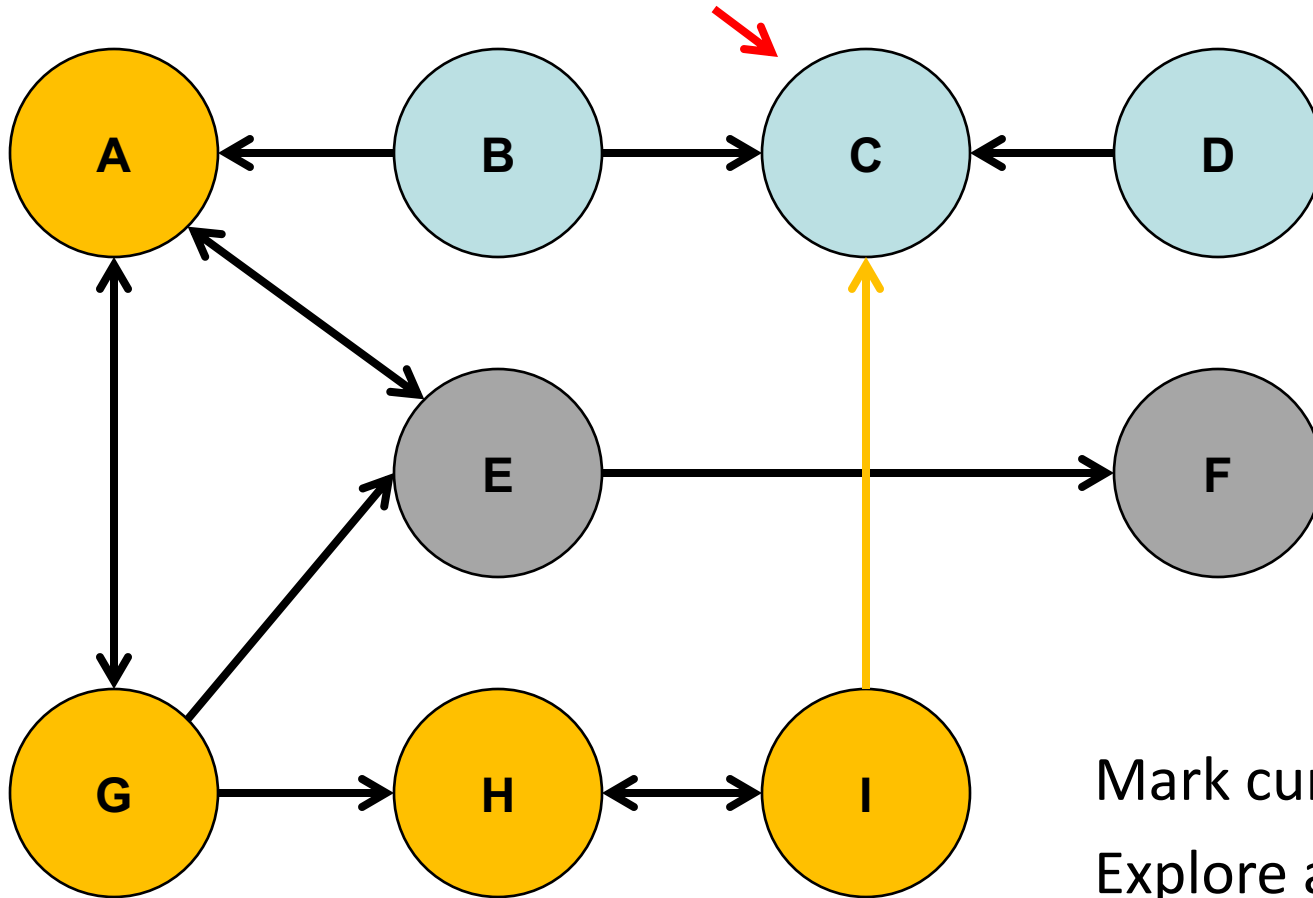


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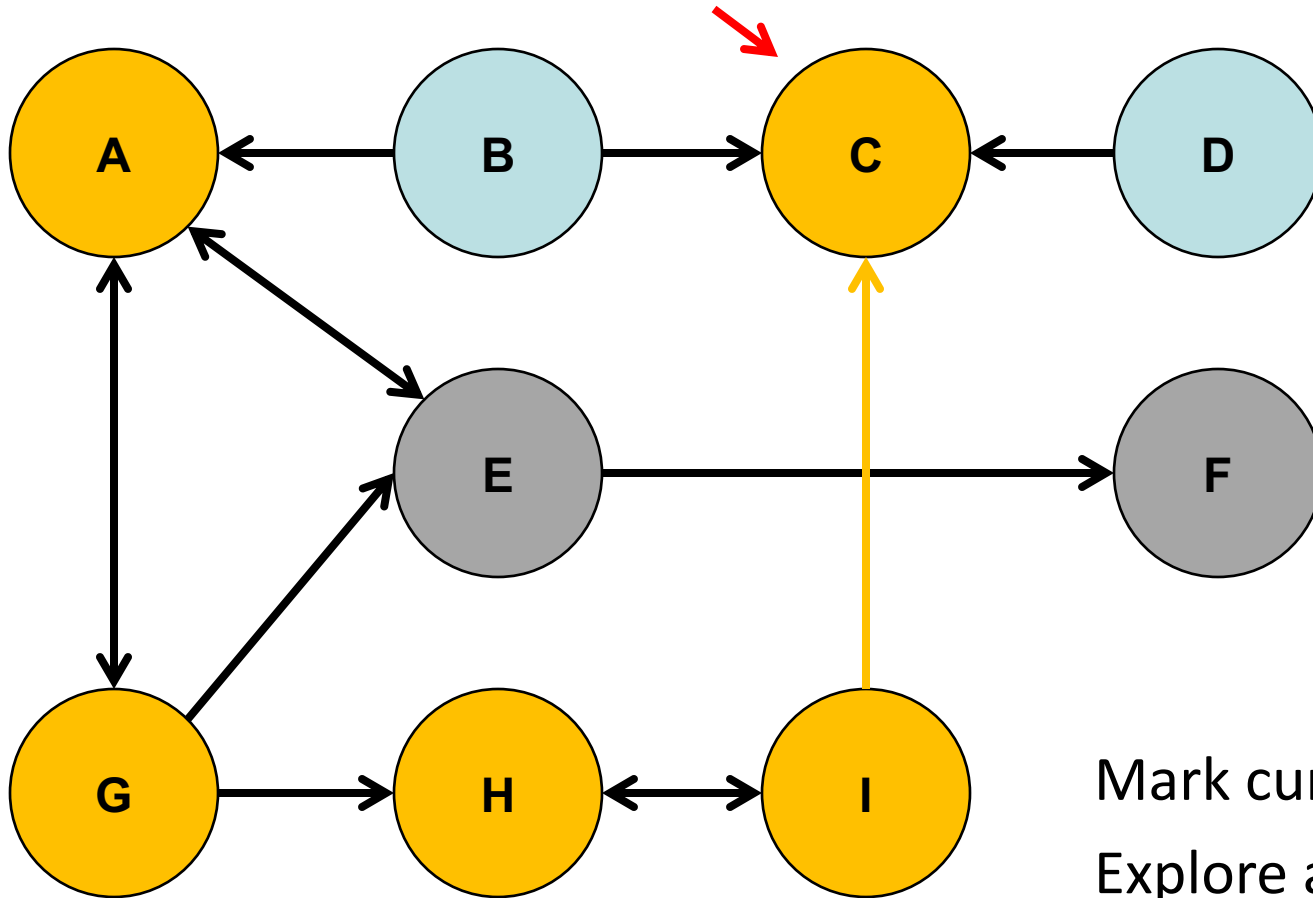
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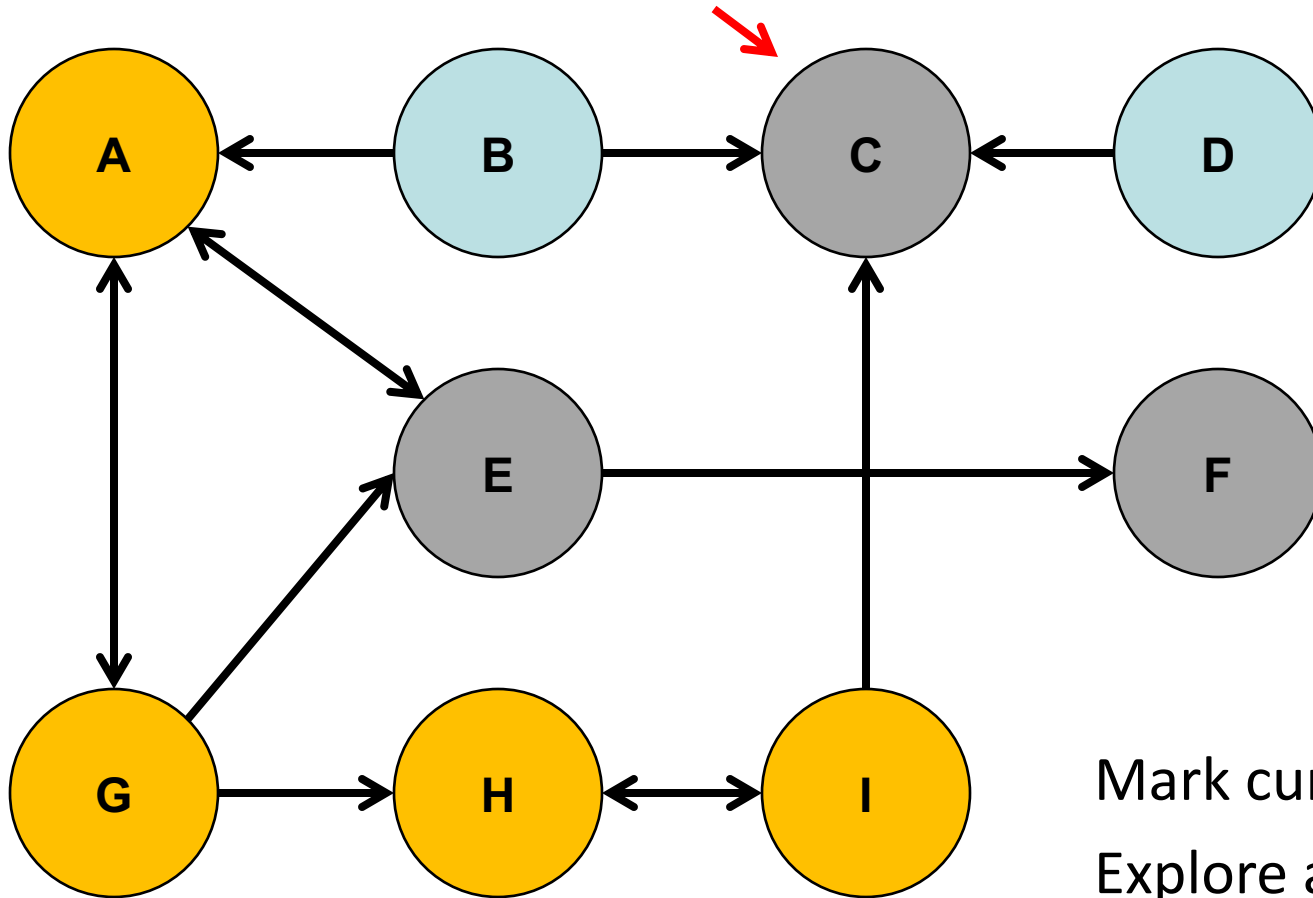
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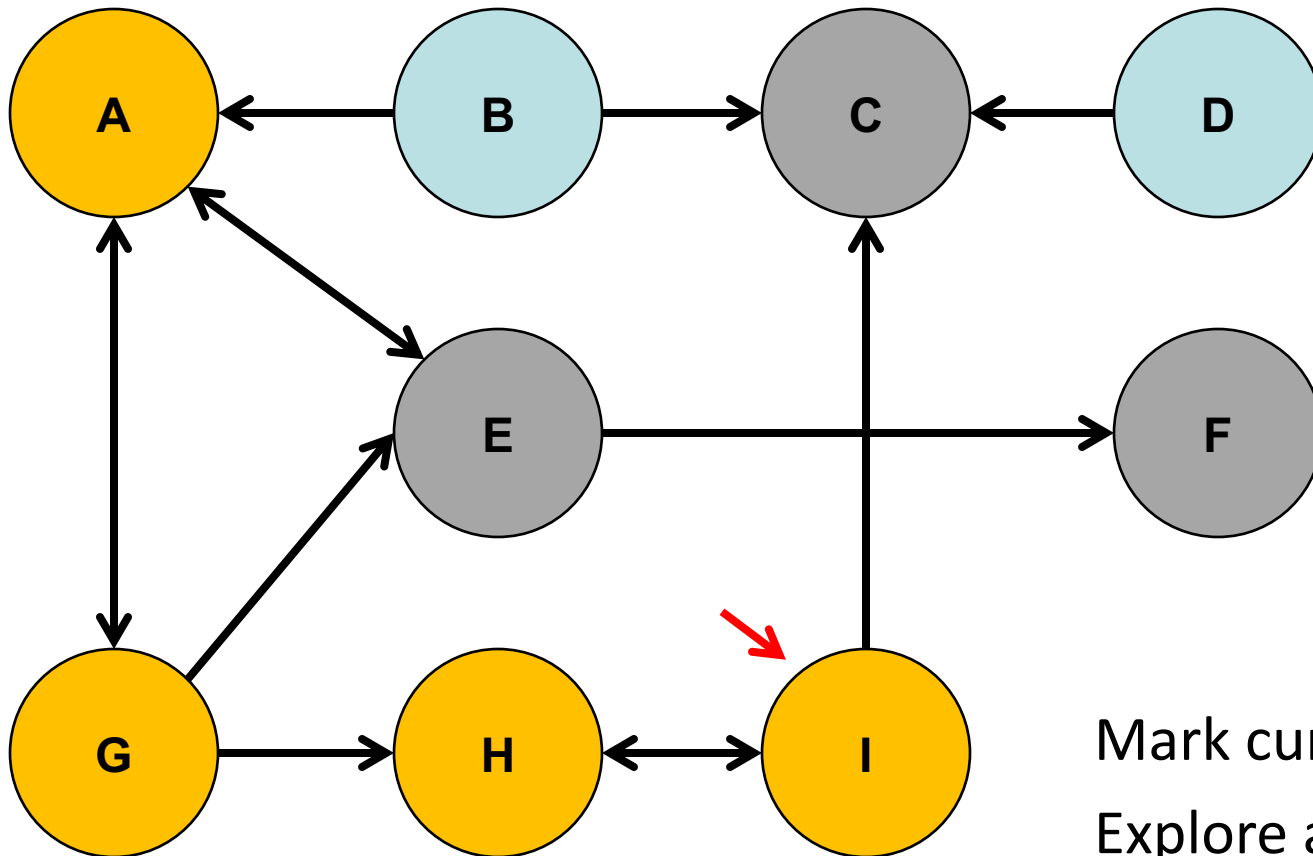
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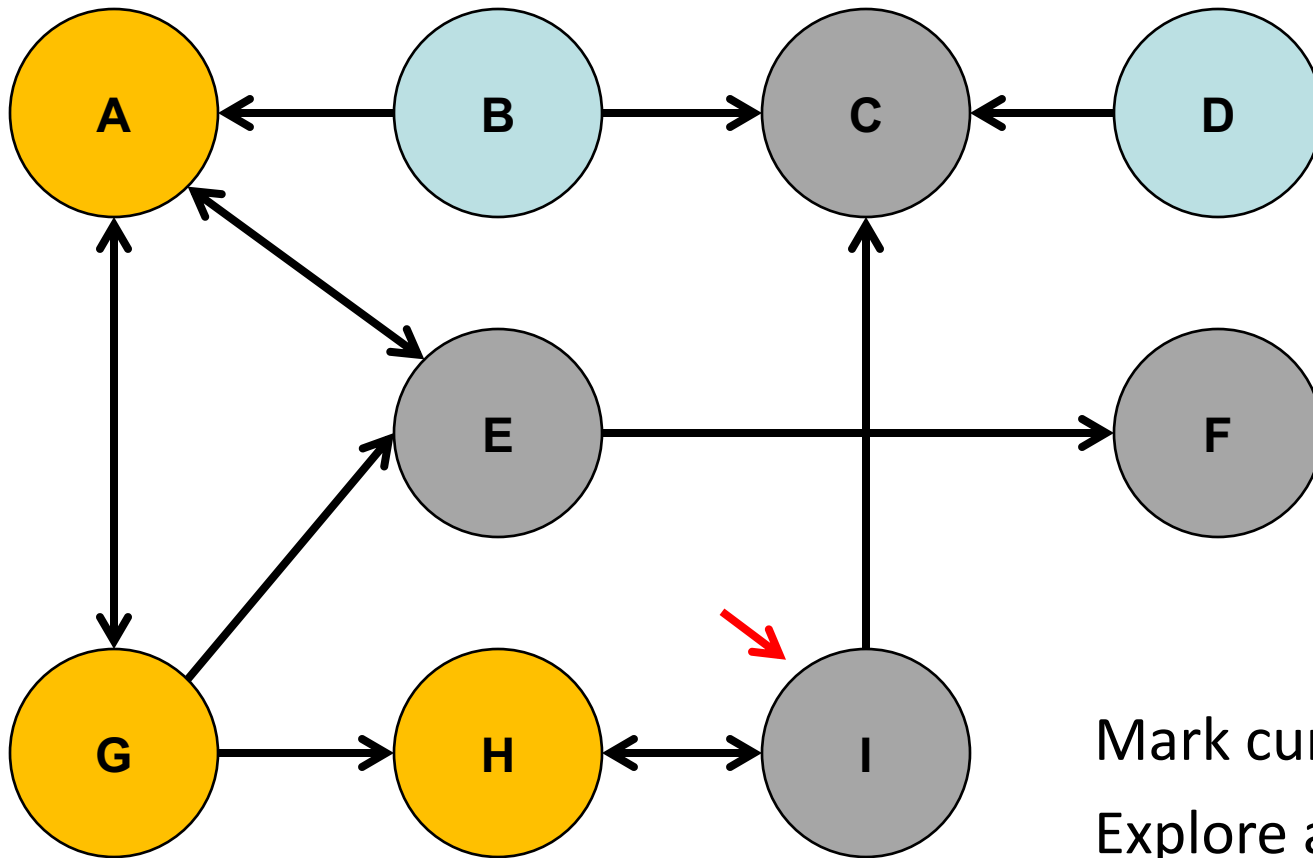
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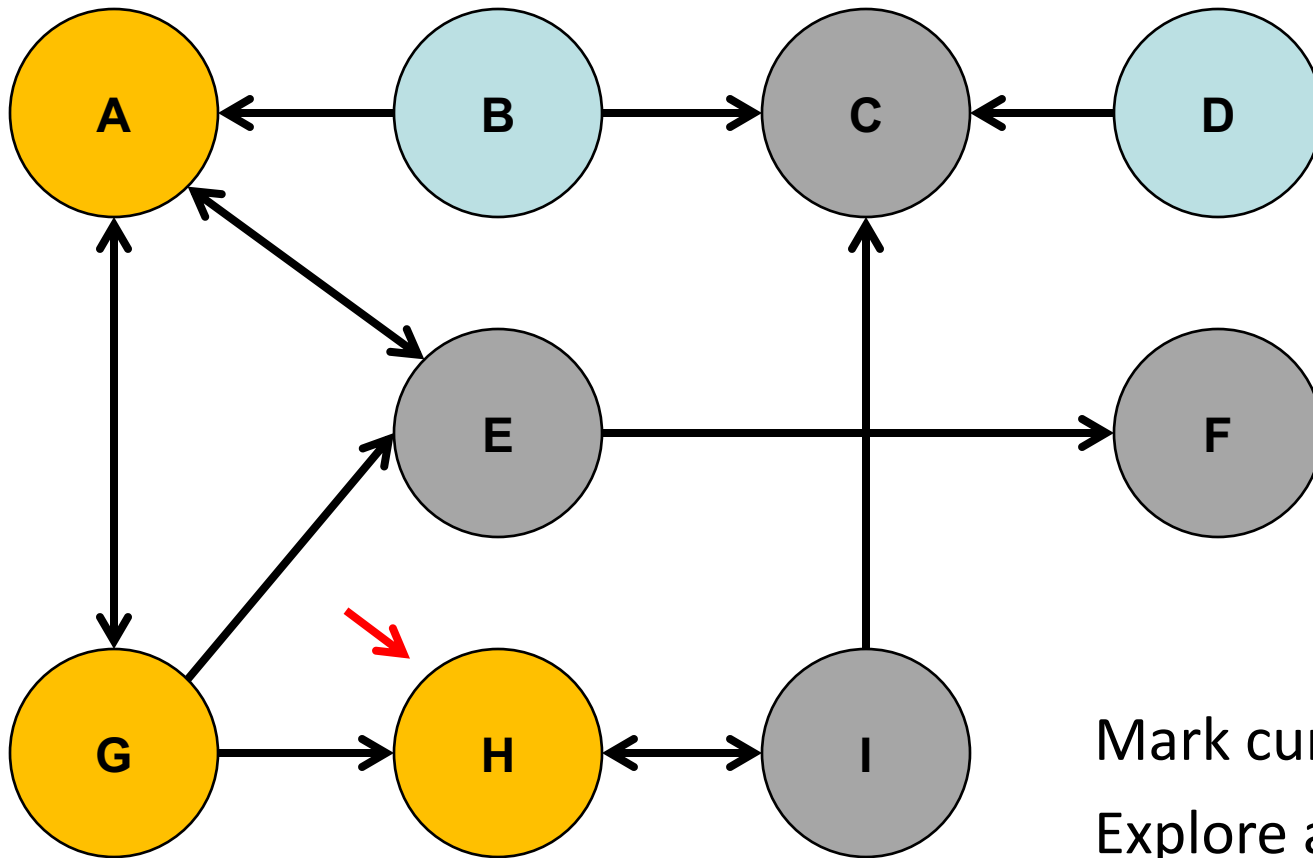
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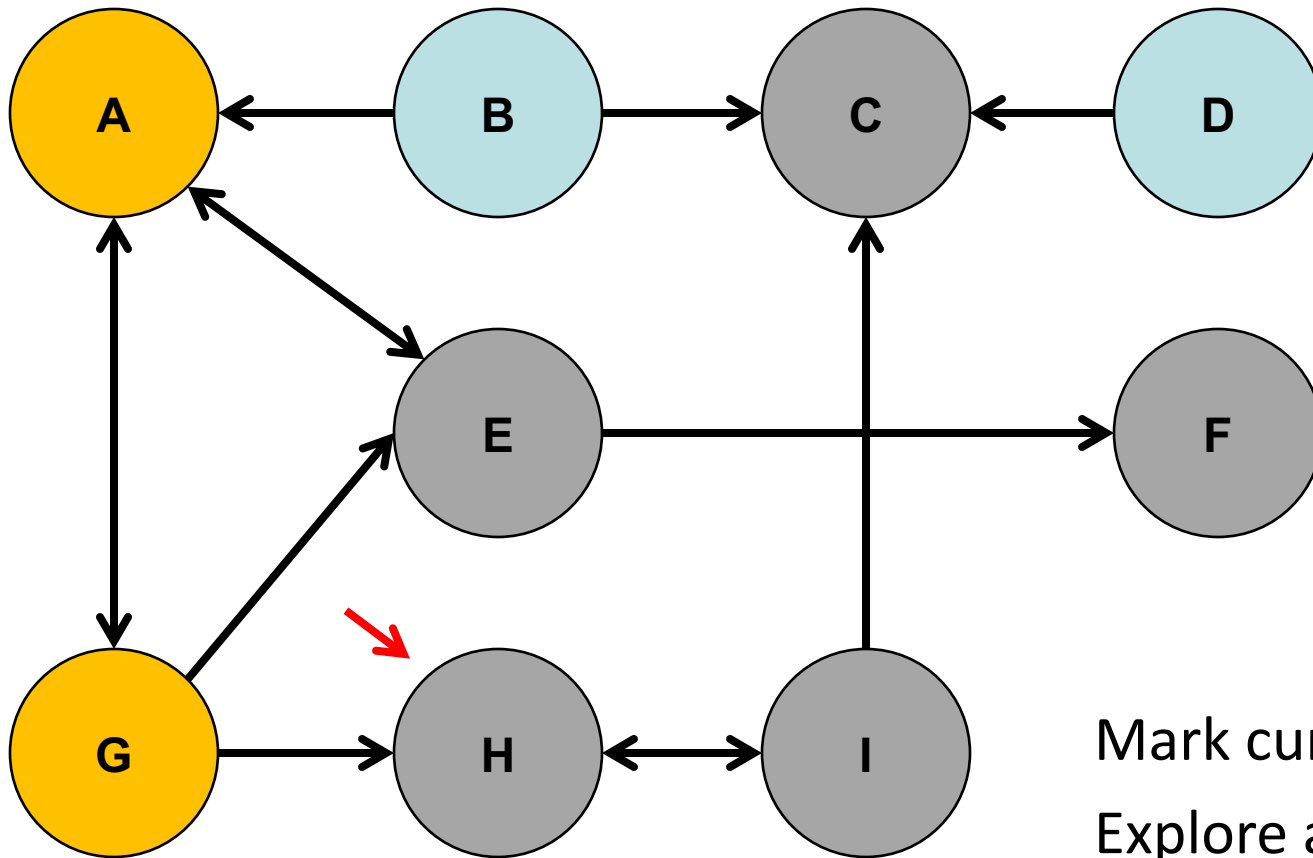
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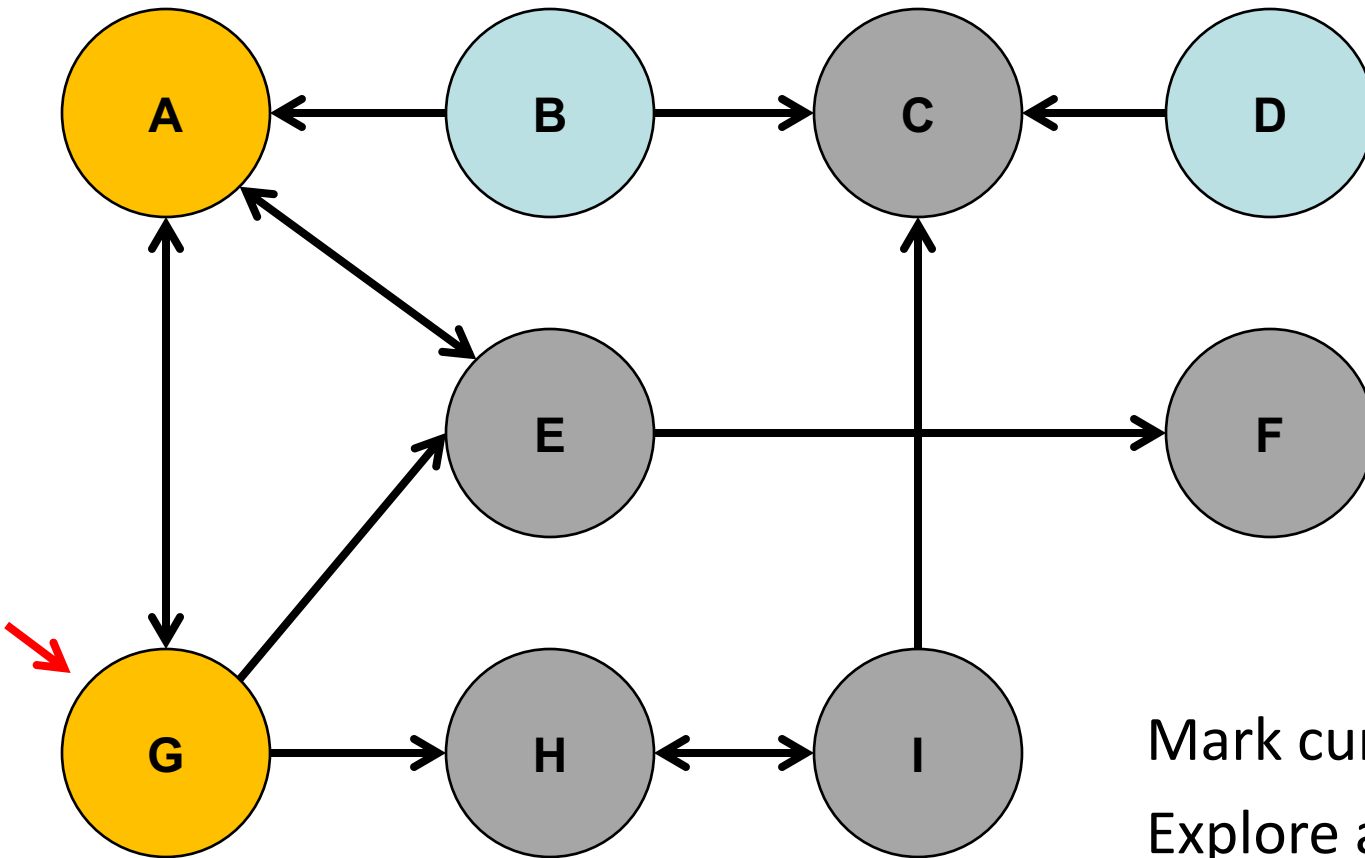
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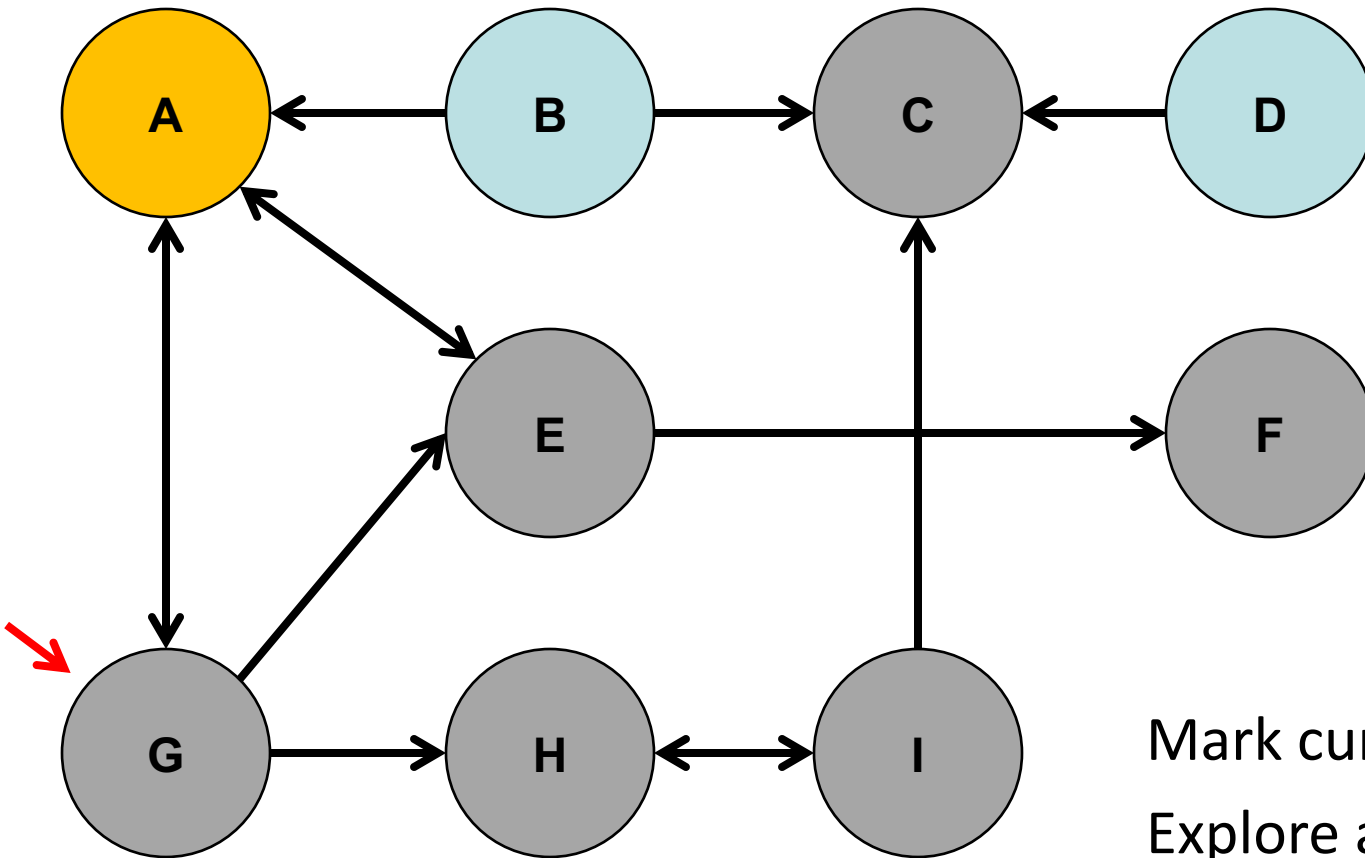


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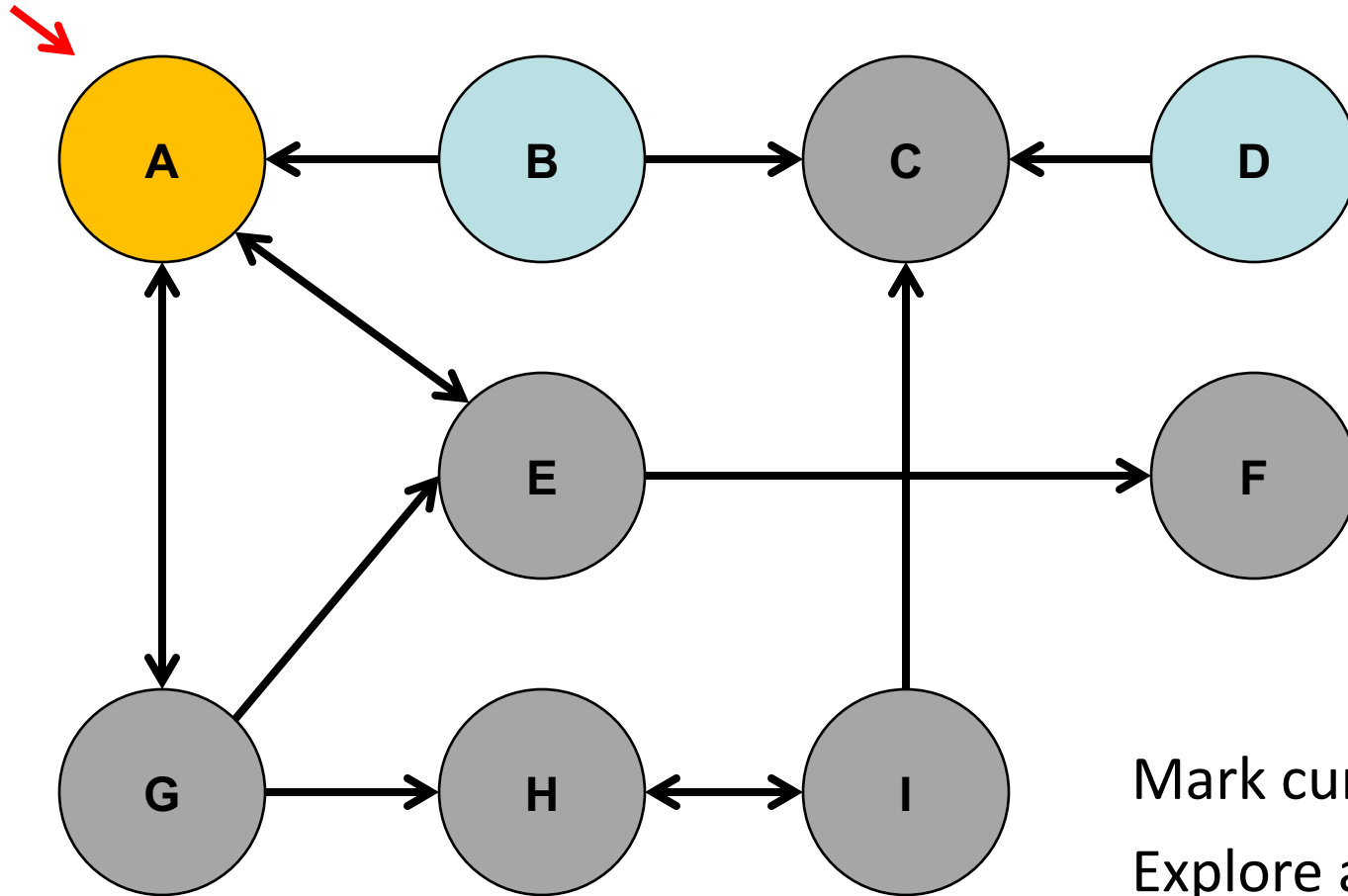
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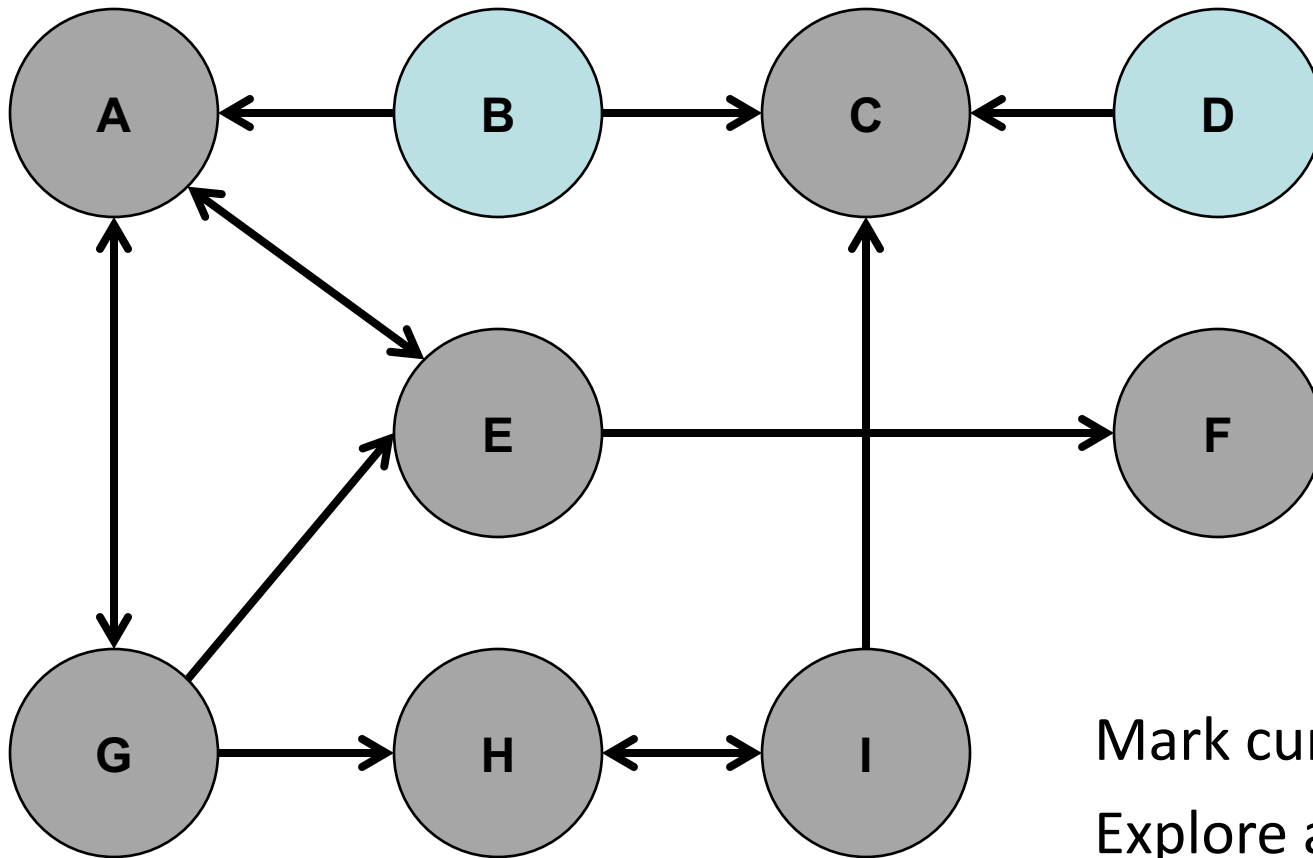
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# DFS Details

- In an  $n$ -node,  $m$ -edge graph, takes  $O(m + n)$  time with an adjacency list
  - Visit each edge once, visit each node at most once
- Pseudocode:  
    **dfs** from  $v_1$ :  
        mark  $v_1$  as **seen**.  
        for each of  $v_1$ 's unvisited neighbors  $n$ :  
            **dfs**( $n$ )
- How could we modify the pseudocode to look for a specific path?

# DFS that finds path

**dfs** from  $v_1$  to  $v_2$ :

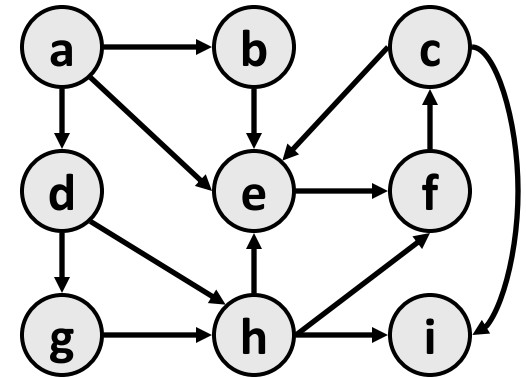
mark  $v_1$  as **visited**, and **add to path**. 选对象

perform a **dfs** from each of  $v_1$ 's  
unvisited neighbors  $n$  to  $v_2$ :

if **dfs**( $n, v_2$ ) succeeds: a path is found! yay!

if all neighbors fail: **remove  $v_1$  from path**.

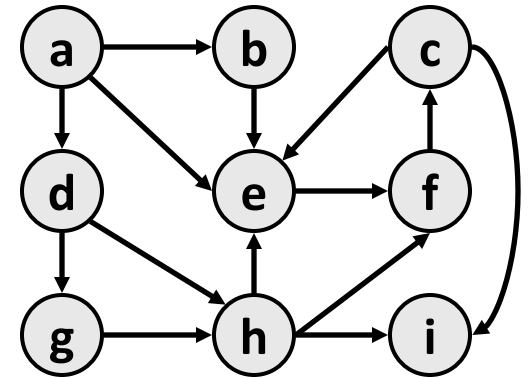
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- To retrieve the DFS path found, pass a collection parameter to each call and choose-explore-unchoose.

# DFS observations

- *discovery*: DFS is guaranteed to find a path if one exists.
- *retrieval*: It is easy to retrieve exactly what the path is (the sequence of edges taken) if we find it
  - choose - explore - unchoose
- *optimality*: not optimal. DFS is guaranteed to find a path, not necessarily the best/shortest path
  - Example:  $\text{dfs}(a, i)$  returns  $\{a, b, e, f, c, i\}$  rather than  $\{a, d, h, i\}$ .



# Plan For Today

- **Recap:** Graphs
- **Practice:** Twitter Influence
- Depth-First Search (DFS)
- **Announcements**
- Breadth-First Search (BFS)



# Announcements

- Assignment 7 will go out this Friday, is due Wed. after break
  - Short graphs assignment (Google Maps!), implementing algorithms from this week
- Assignment 8 will go out the Wed. after break, is due the last day of class (Fri)
  - Graphs and inheritance assignment (Excel!)

# Plan For Today

- **Recap:** Graphs
- **Practice:** Twitter Influence
- Depth-First Search (DFS)
- Announcements
- Breadth-First Search (BFS)

# Finding *Shortest* Paths

- We can find paths between two nodes, but how can we find the **shortest** path?
  - Fewest number of steps to complete a task?
  - Least amount of edits between two words?
- When have we solved this problem before?

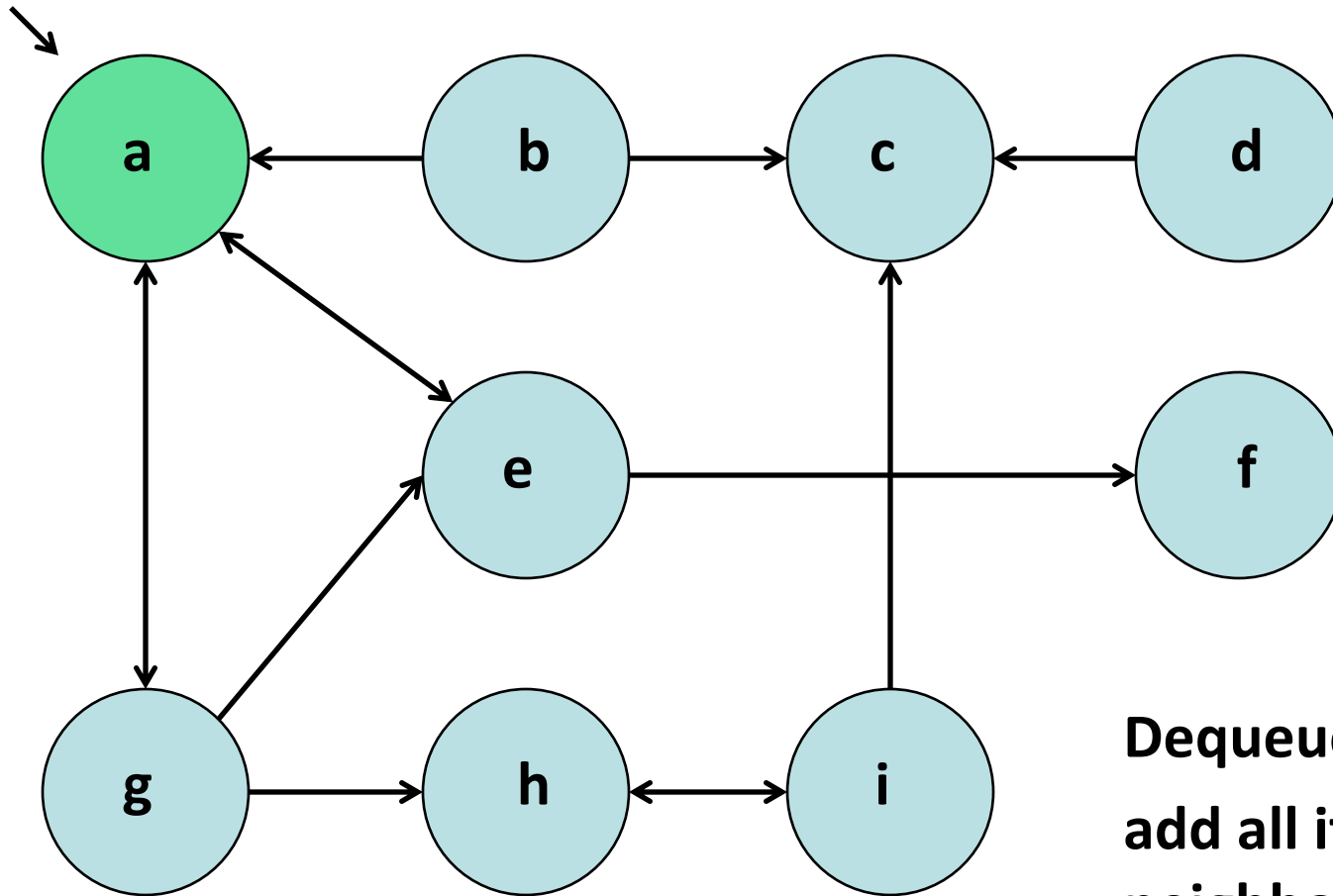
# Breadth-First Search (BFS)

- Idea: processing a node involves knowing we need to visit all its neighbors (just like DFS)
- Need to keep a TODO list of nodes to process

# Breadth-First Search (BFS)

- Keep a Queue of nodes as our TODO list
- Idea: dequeue a node, enqueue all its neighbors
- Still will return the same nodes as reachable, just might have shorter paths

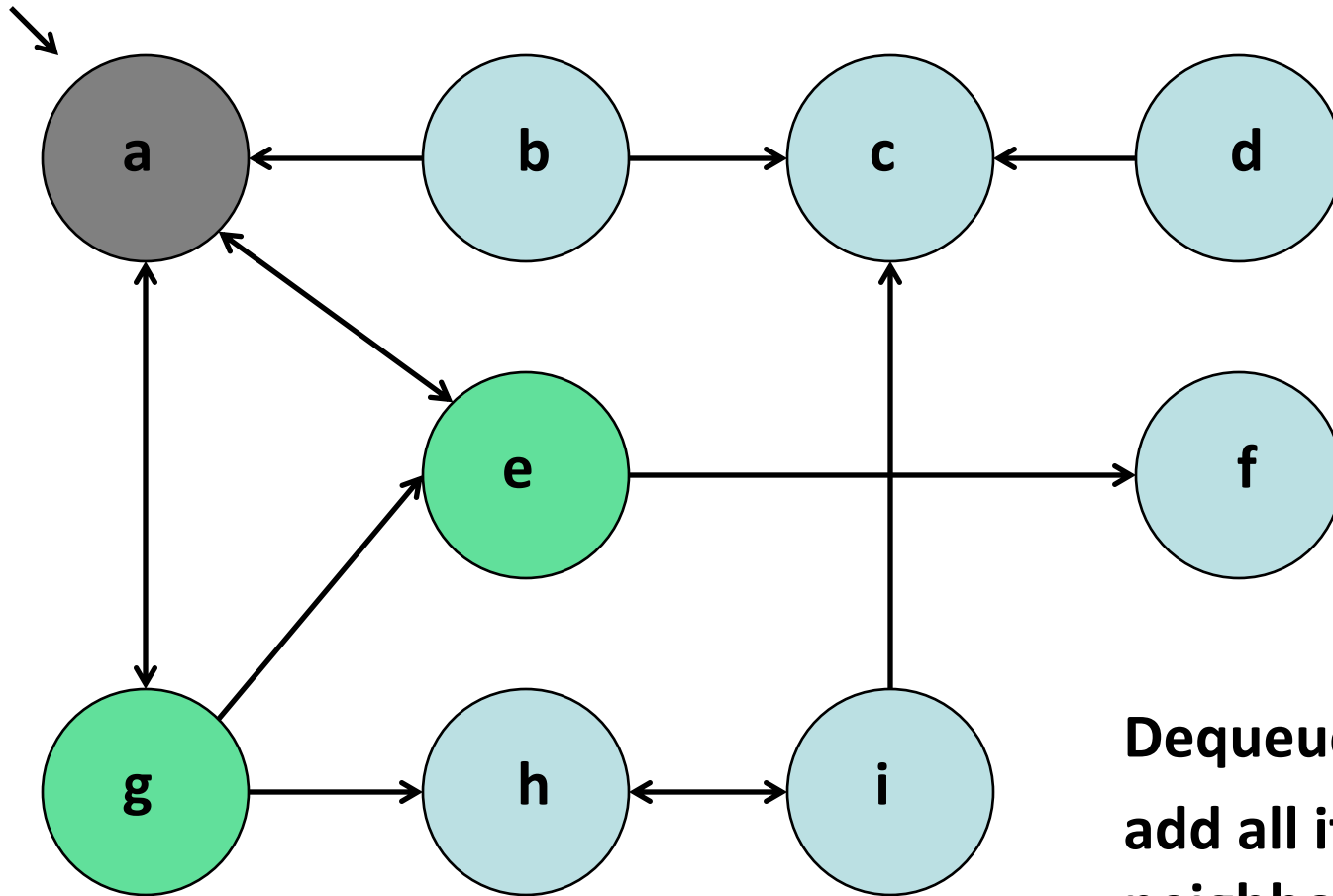
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: a**

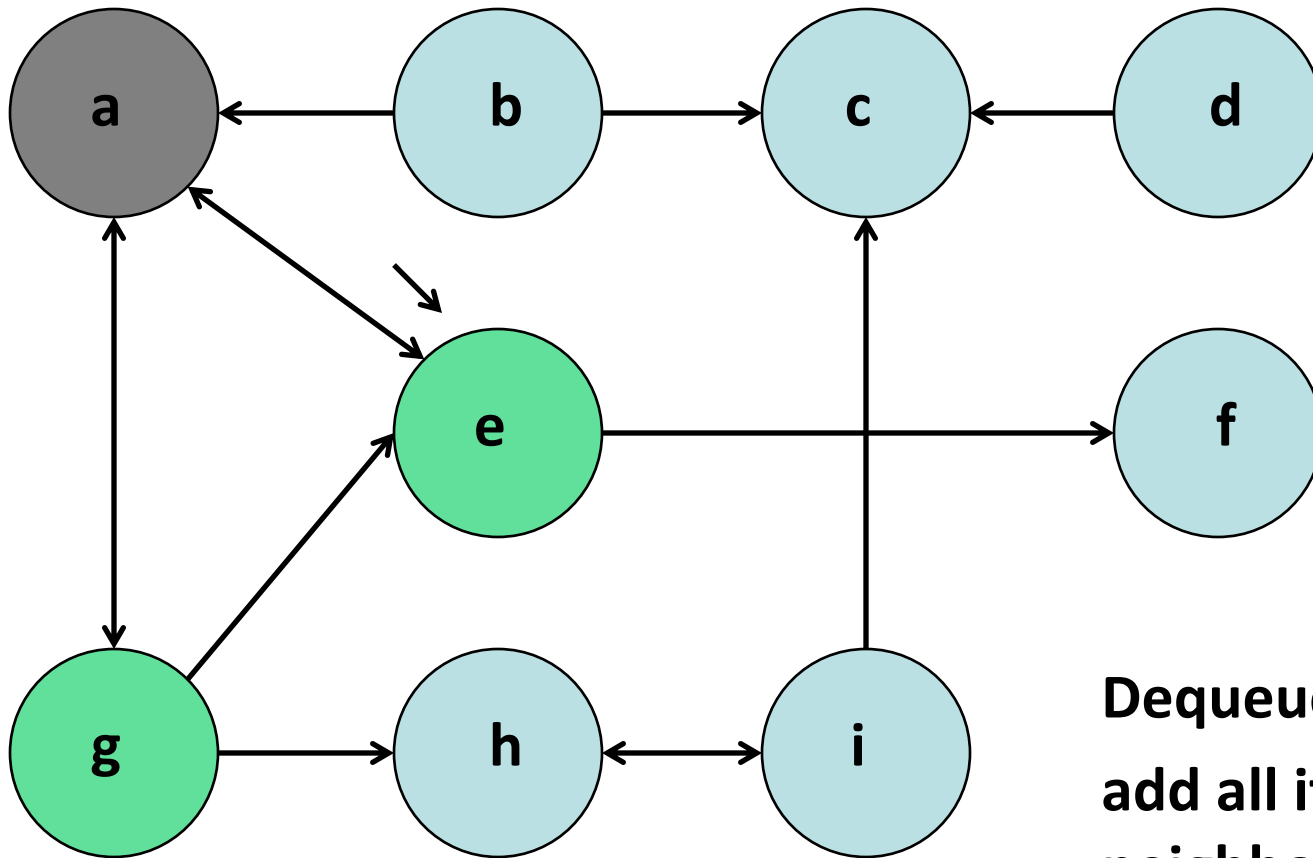
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: e, g**

# BFS

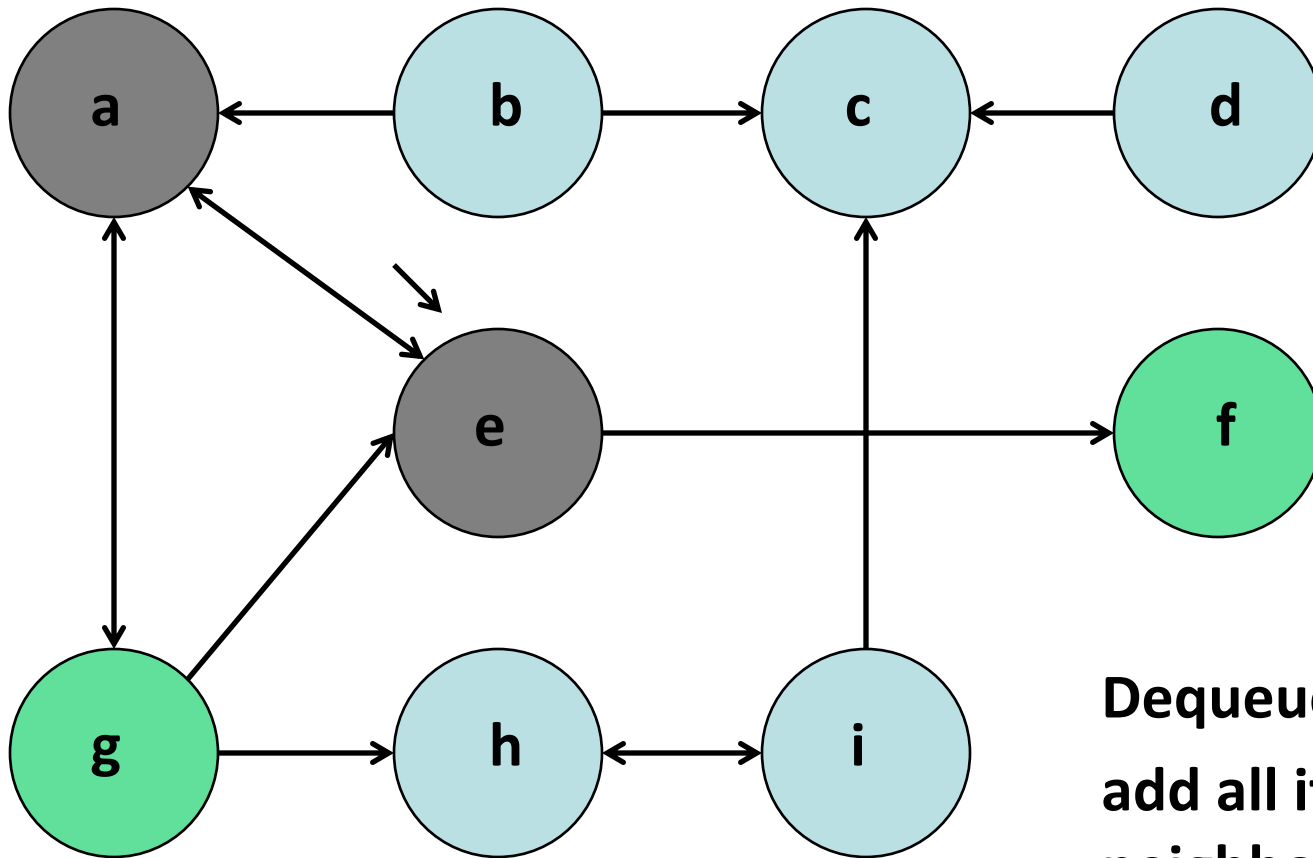


**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: e, g**



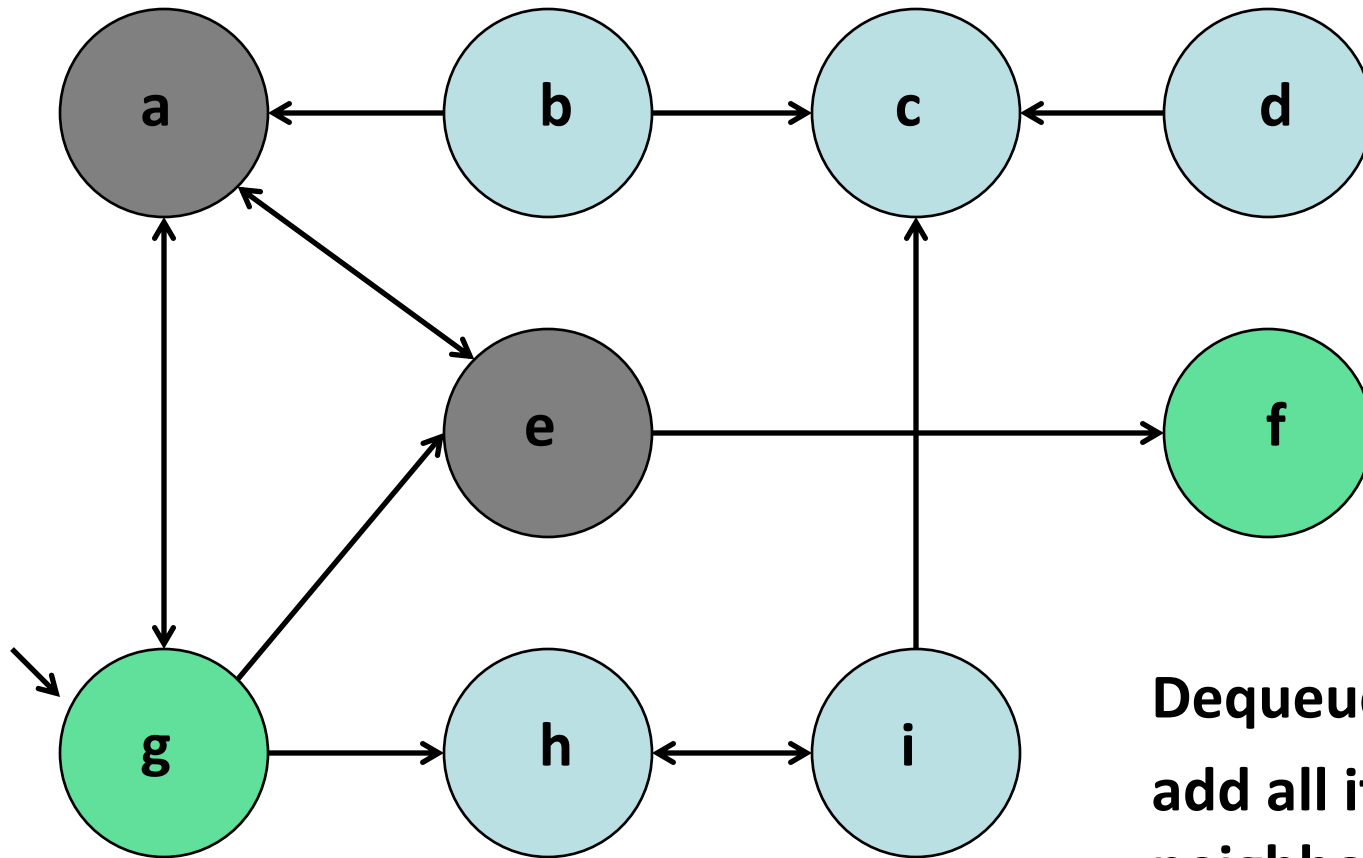
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: g, f**

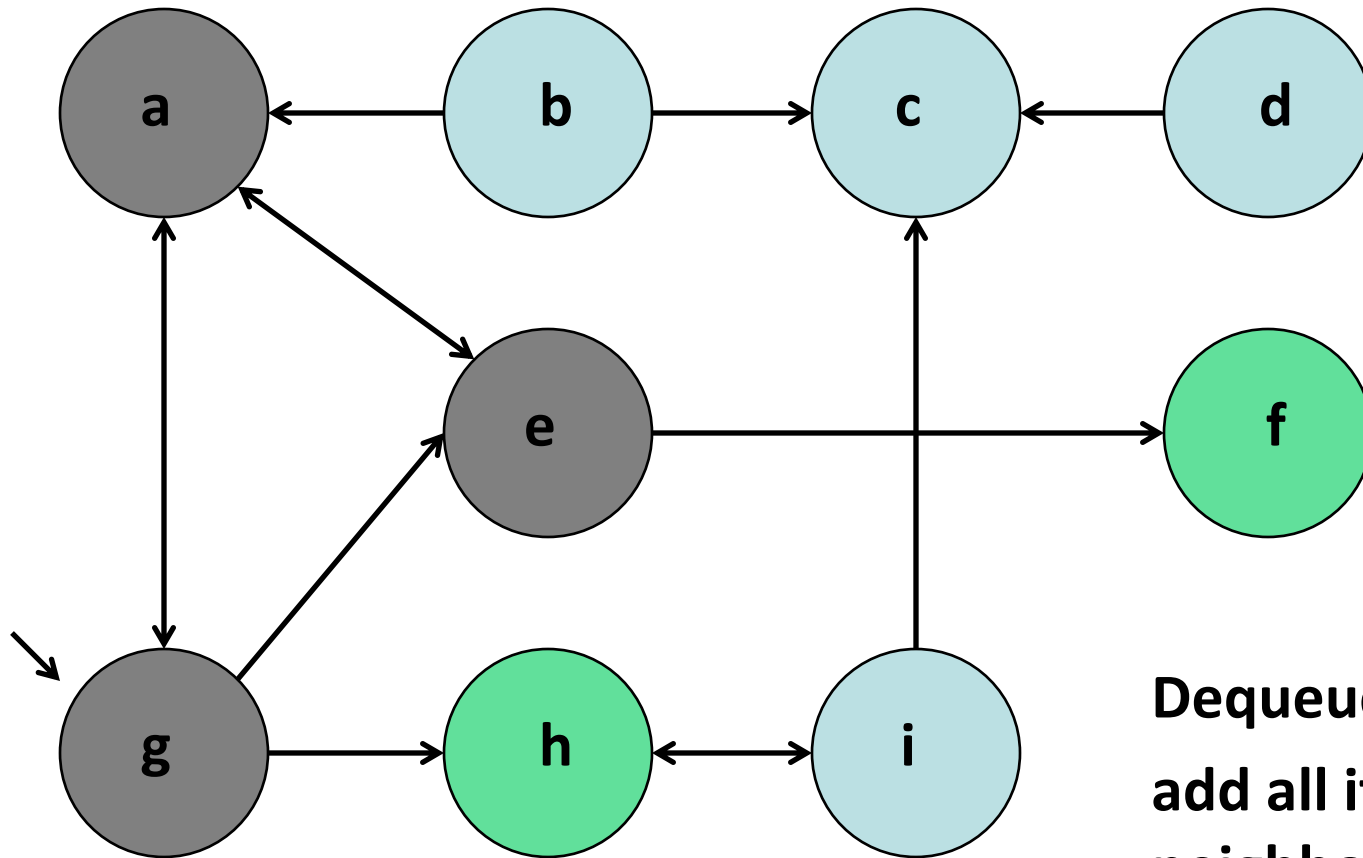
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: g, f**

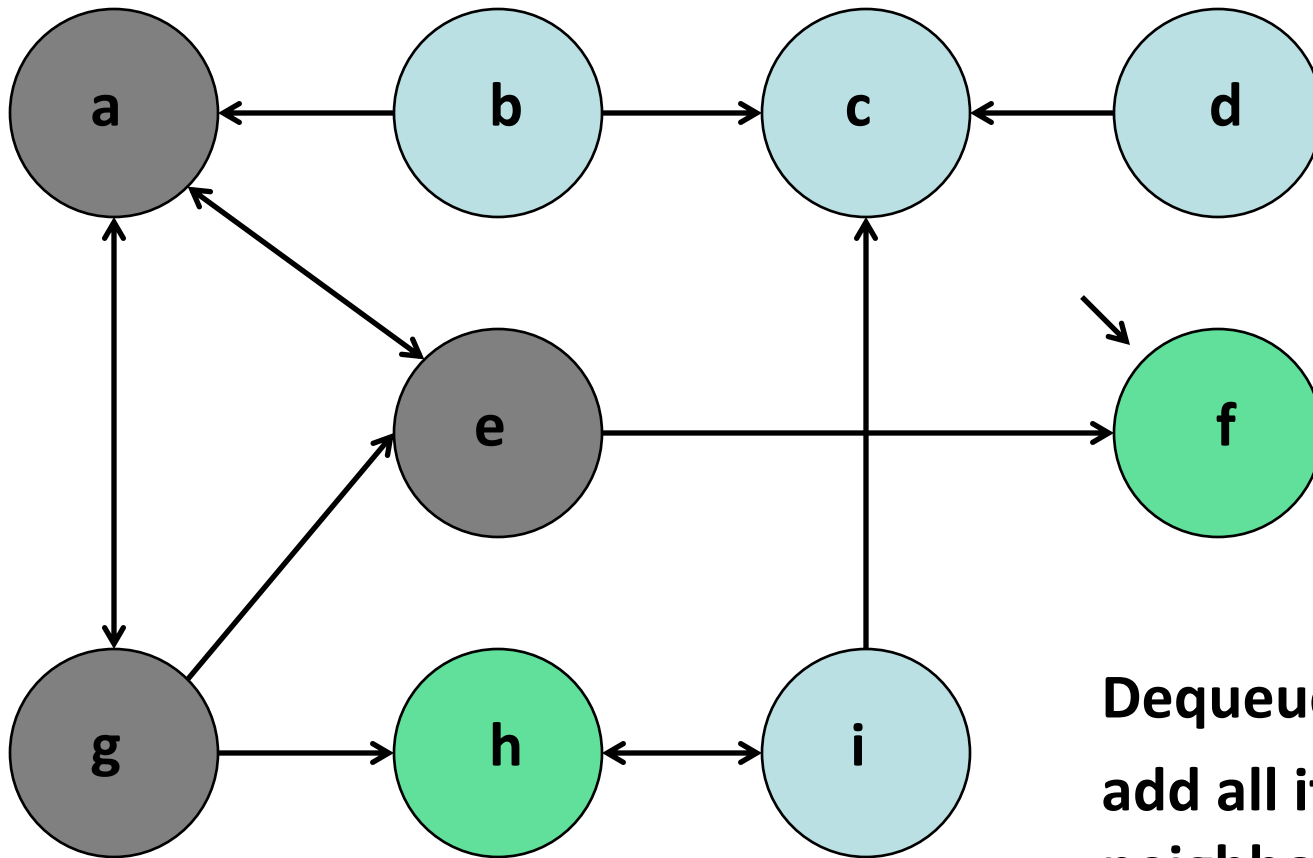
# BFS



queue: f, h

Deque a node  
add all its unseen  
neighbors to the queue

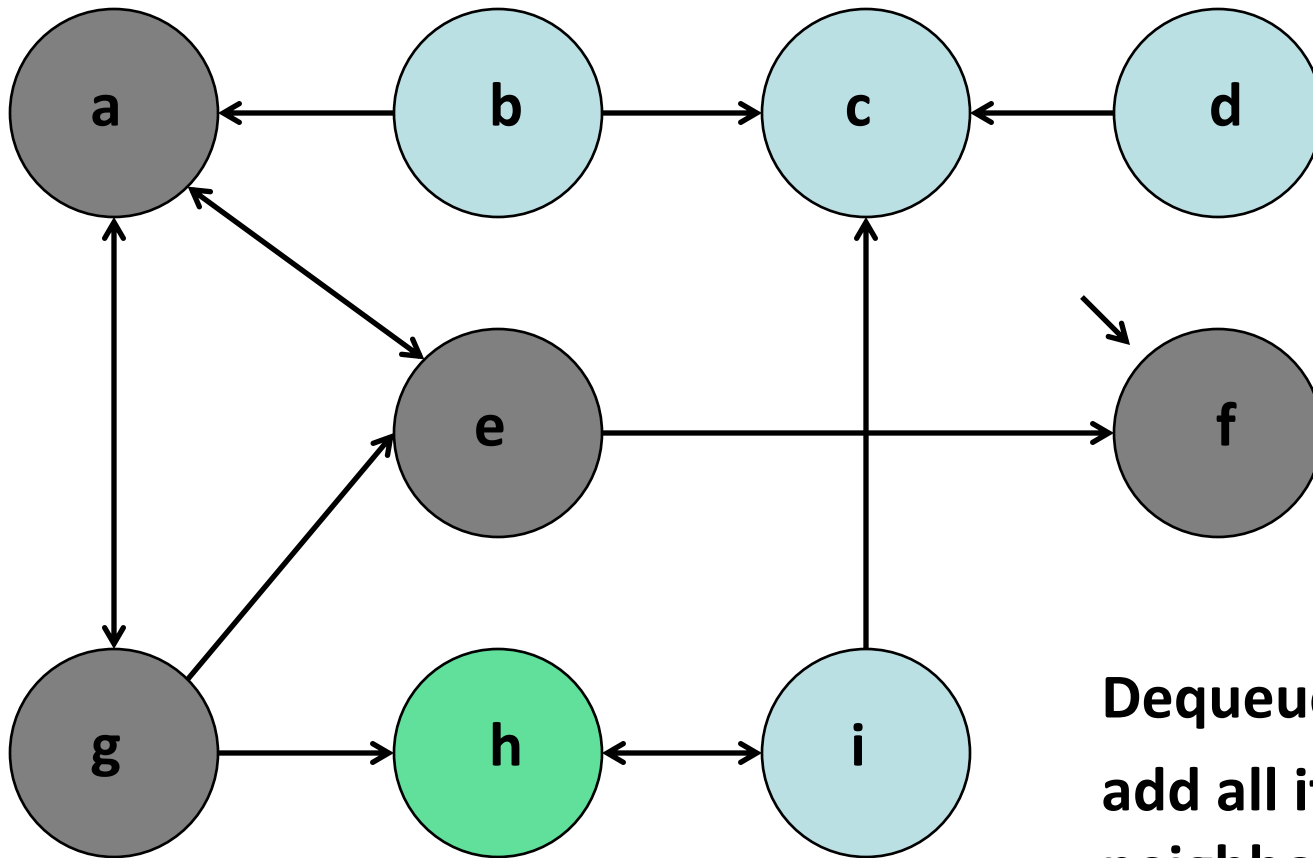
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: f, h**

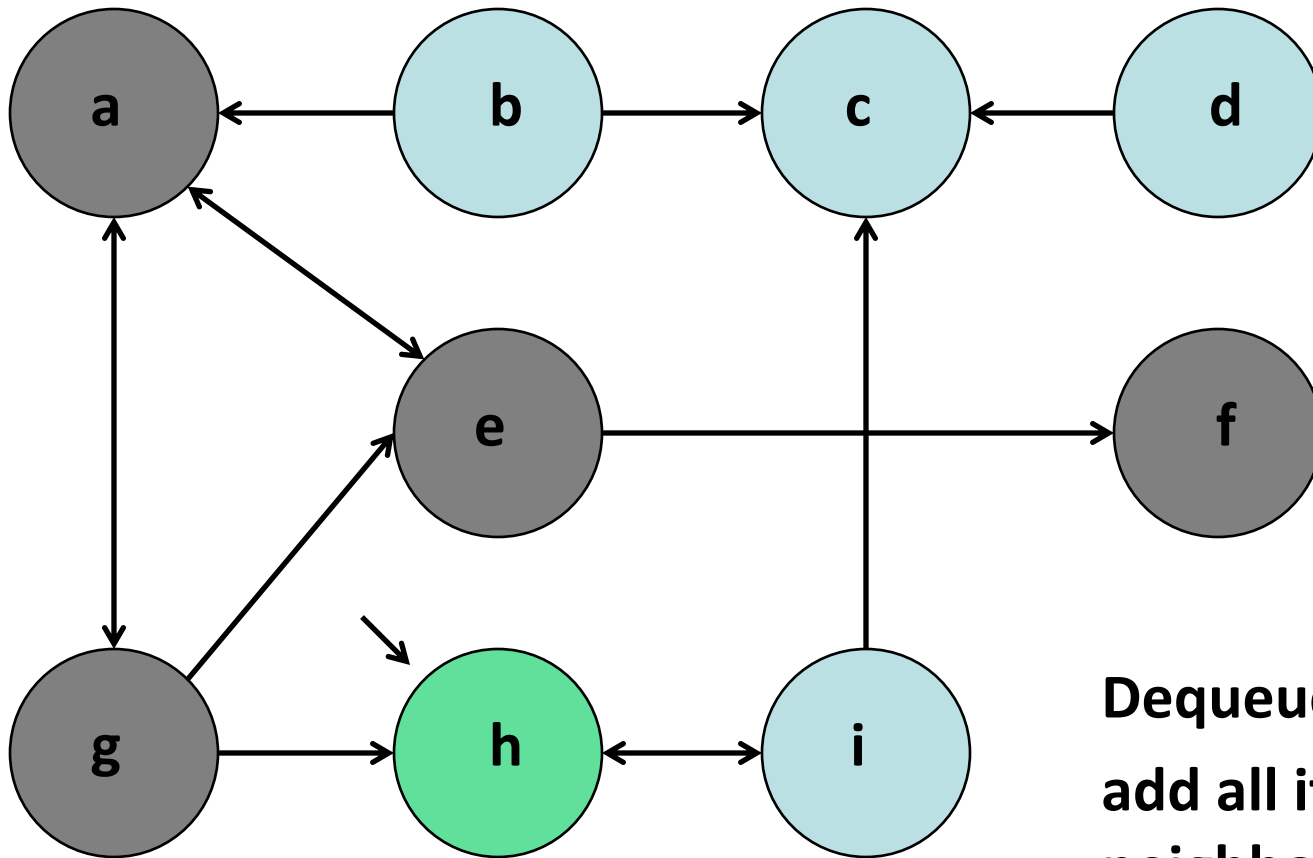
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: h**

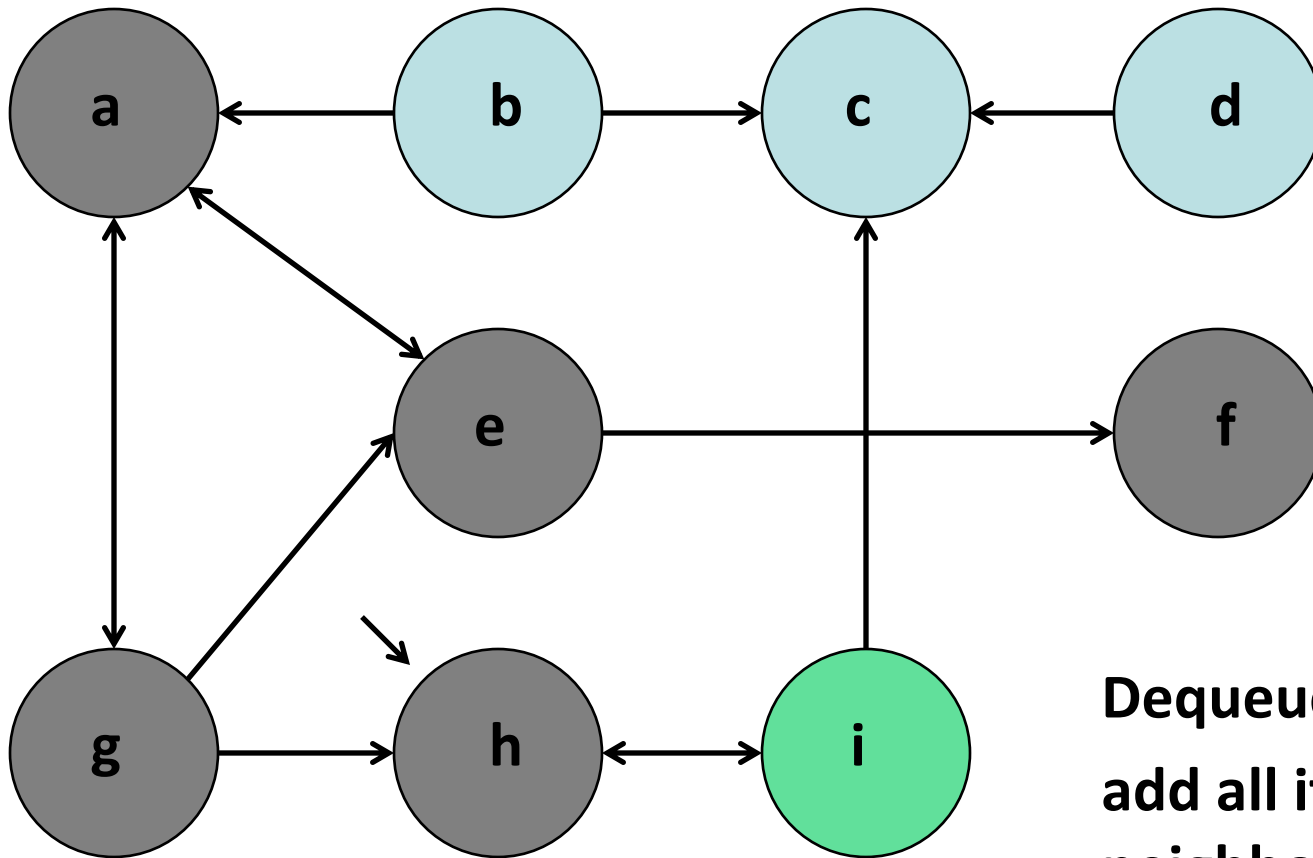
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: h**

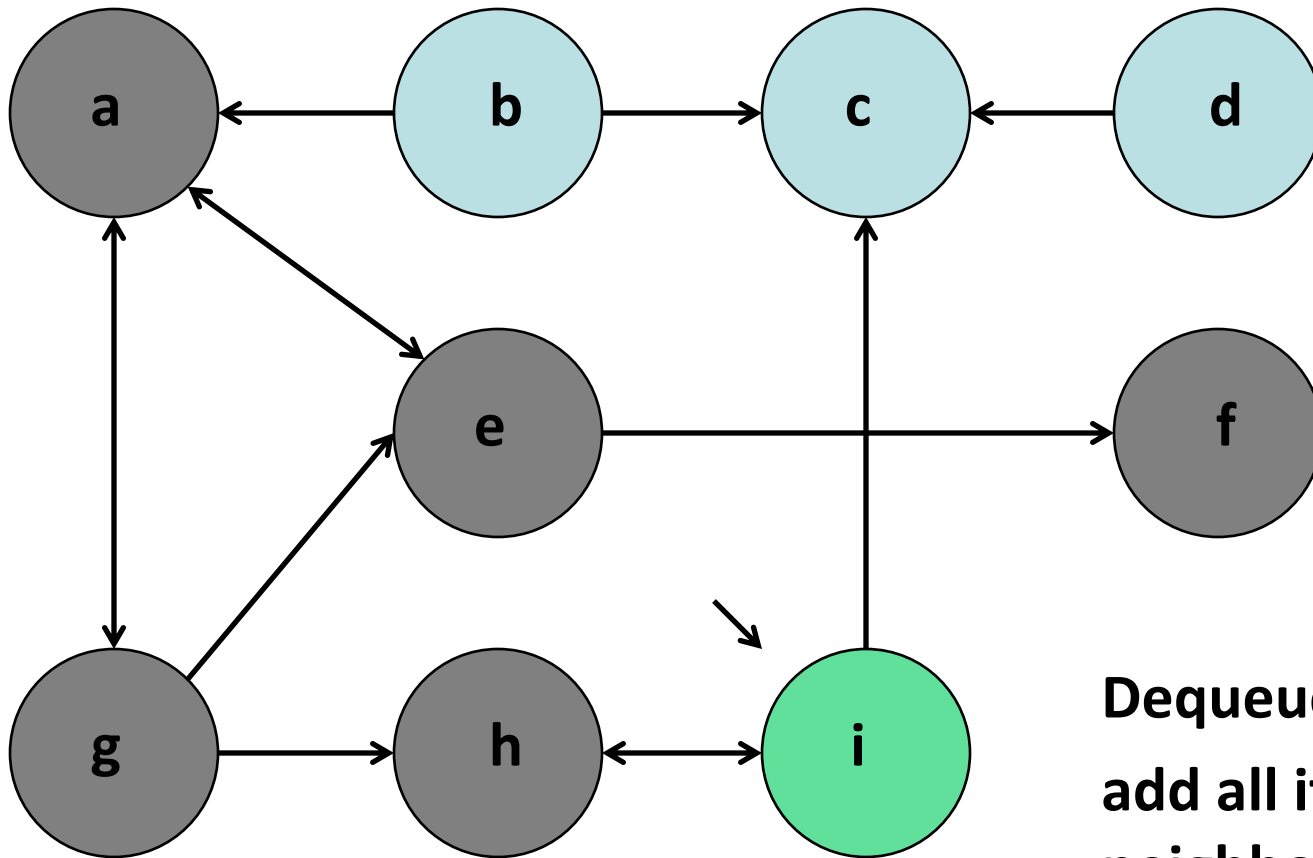
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: i**

# BFS

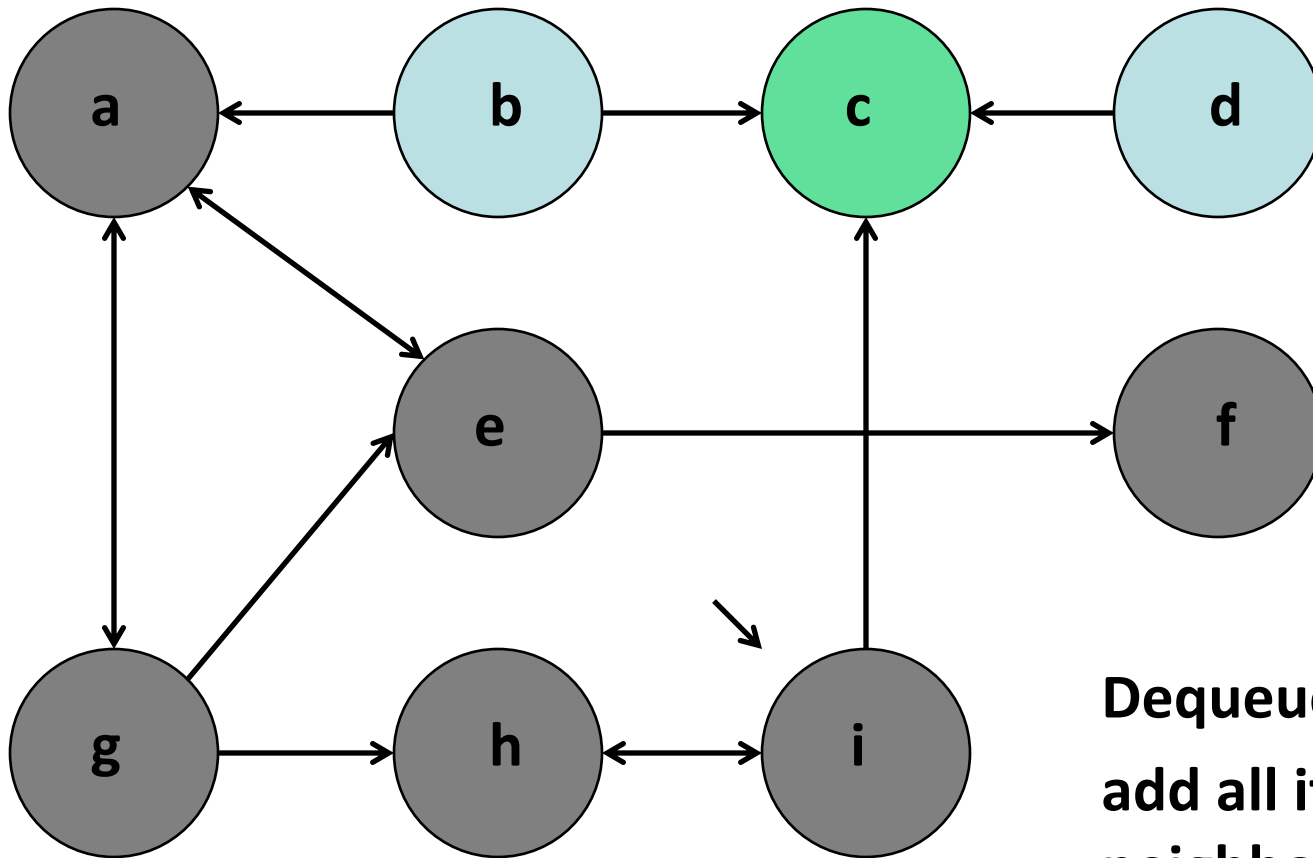


**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: i**



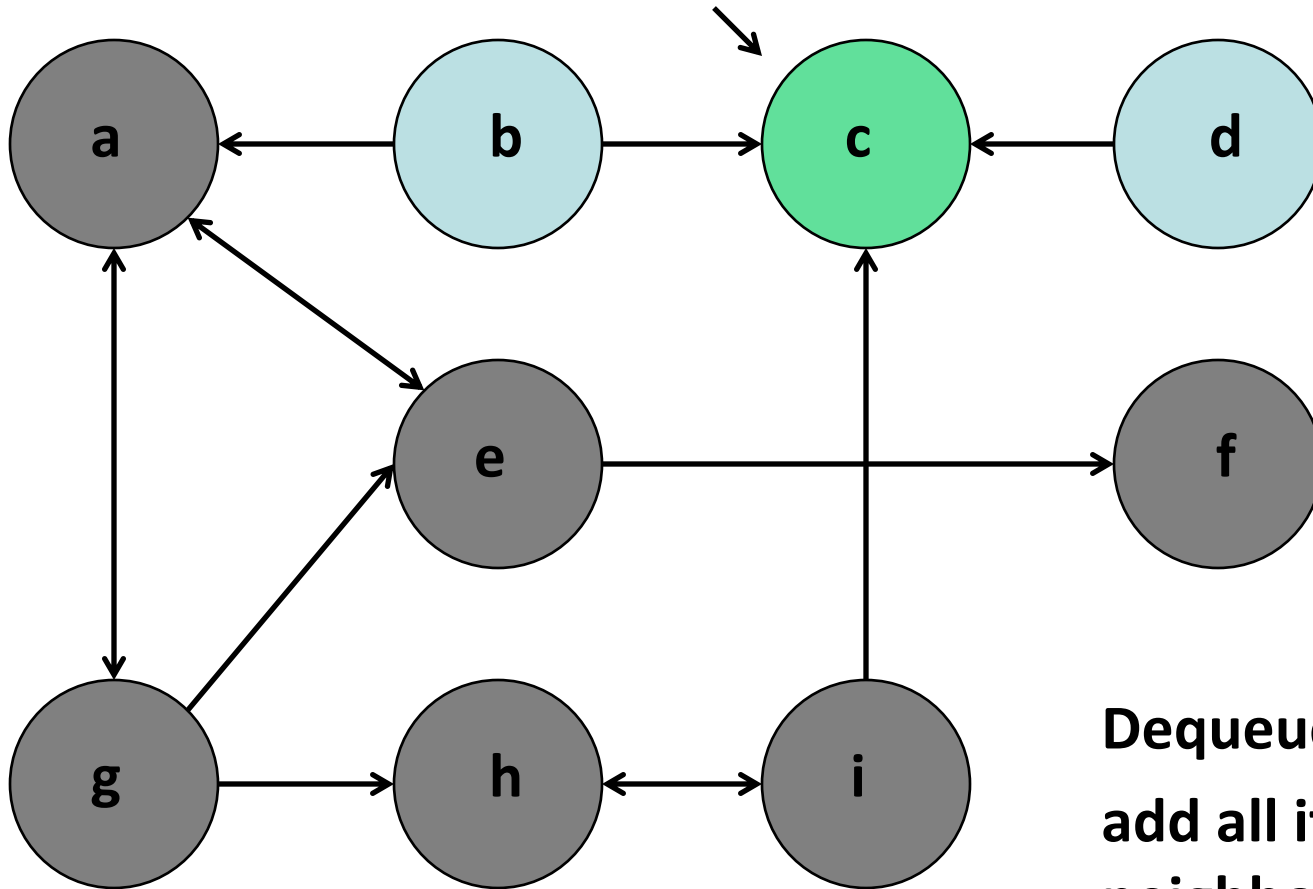
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: c**

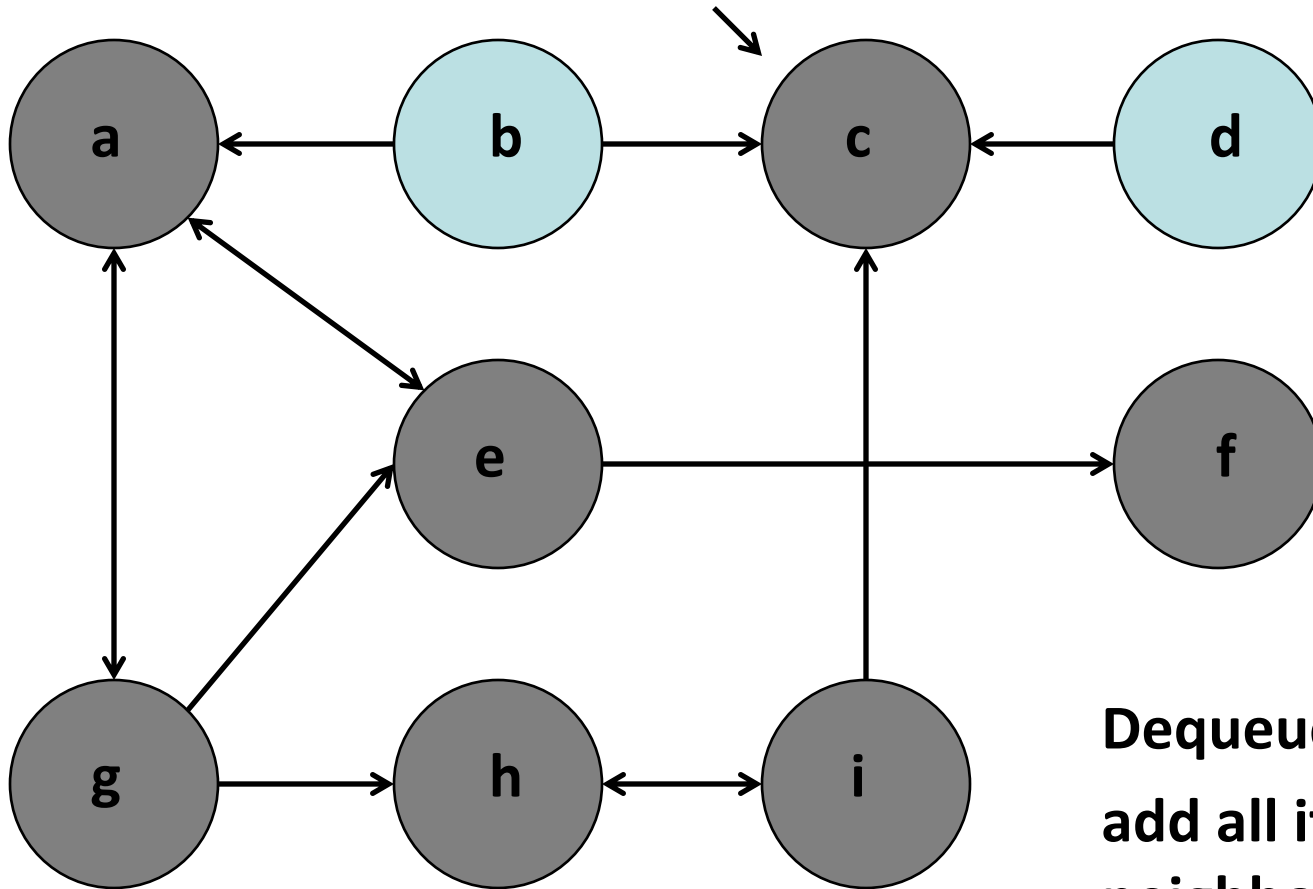
# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: c**

# BFS



**Dequeue a node  
add all its unseen  
neighbors to the queue**

**queue: c**

# BFS Details

- In an  $n$ -node,  $m$ -edge graph, takes  $O(m + n)$  time with an adjacency list
  - Visit each edge once, visit each node at most once

**bfs** from  $v_1$  to  $v_2$ :

create a *queue* of vertexes to visit,  
initially storing just  $v_1$ .

mark  $v_1$  as **visited**.

while *queue* is not empty and  $v_2$  is not seen:

dequeue a vertex  $v$  from it,

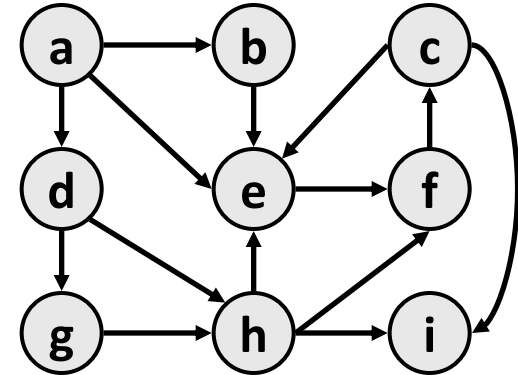
mark that vertex  $v$  as **visited**,

and add each unvisited neighbor  $n$  of  $v$  to the *queue*.

- How could we modify the pseudocode to look for a specific path?

# BFS observations

- *optimality*:
  - always finds the shortest path (fewest edges).
  - in unweighted graphs, finds optimal cost path.
  - In weighted graphs, *not* always optimal cost.
- *retrieval*: harder to reconstruct the actual sequence of vertices or edges in the path once you find it
  - conceptually, BFS is exploring many possible paths in parallel, so it's not easy to store a path array/list in progress
  - solution: We can keep track of the path by storing predecessors for each vertex (each vertex can store a reference to a *previous* vertex).
- DFS uses less memory than BFS, easier to reconstruct the path once found; but DFS does not always find shortest path. BFS does.



# Recap

- **Recap:** Graphs
- **Practice:** Twitter Influence
- Depth-First Search (DFS)
- Announcements
- Breadth-First Search (BFS)

**Next time:** more graph searching algorithms

# Overflow

# BFS that finds path

**bfs** from  $v_1$  to  $v_2$ :

create a *queue* of vertexes to visit,  
initially storing just  $v_1$ .  
mark  $v_1$  as **visited**.

while *queue* is not empty and  $v_2$  is not seen:

dequeue a vertex  $v$  from it,

mark that vertex  $v$  as **visited**,

and add each unvisited neighbor  $n$  of  $v$  to the *queue*,

while setting  $n$ 's **previous** to  $v$ .

