### Problem 1: Search Algorithms

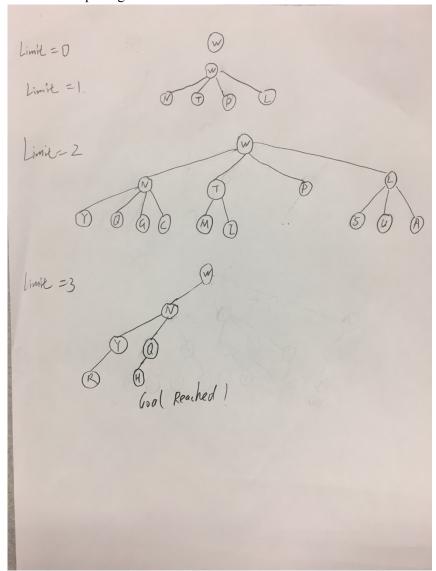
## (a) Depth-First Search

The solution is found.

The squares expanded in order: W-N-Y-R-I-B-M-D-J-S-H

The solution path: W-N-Y-R-I-B-M-J-S-H

### (b) Iterative-Deepening Search



#### (c) Heuristic Function

The h(n) is not admissible. Due to the definition of the admissible heuristic function,  $h(n) \le h^*(n)$ , with  $h^*(n)$  refers to the actual cost of the minimum-cost path from n to goal. However, on the board, the h(n) could sometimes be larger than  $h^*(n)$ . For example, in the board, suppose the knight is at position Q and the goal is at position H, the minimum cost of moving from n to goal is just 1 because

each move of the knight has cost 1 and knight just need one move to reach the goal. However, the heuristic function h(n) would give a value of 3 in this case. h(n) > h\*(n) in this case, so h(n) is not admissible.

# (d) Algorithm A Search {State(fvalue, parent, gvalue)}

Step	Frontier{State(fvalue, parent, gvalue)}	Expanded(State, gvalue)
1	W(3,null,0)	
2	L(3,W,1), N(3,W,1), P(5,W,1),T(5,W,1)	(W,0)
3	C(3,L,2), I(3,L,2), N(3,W,1), A(5,W,2), P(5,W,1), S(5,L,2),	(W,0)(L,1)
	T(5,W,1), U(7,L,2)	
4	I(3,L,2), N(3,W,1), A(5,W,2), F(5,C,3), J(5,C,3), P(5,W,1),	(W,0) (L,1) (C,2)
	S(5,L,2), T(5,W,1), U(7,L,2)	
5	N(3,W,1), A(5,W,2), B(5,I,3), F(5,C,3), J(5,C,3), P(5,W,1),	(W,0) (L,1) (C,2) (I,2)
	R(5,I,3), S(5,L,2), T(5,W,1), U(7,L,2)	
6	G(3,N,2), A(5,W,2), B(5,I,3), F(5,C,3), J(5,C,3), P(5,W,1),	(W,0) (L,1) (C,2) (I,2)
	Q(5,N,2), R(5,I,3), S(5,L,2), T(5,W,1), U(7,L,2), Y(7,N,2)	(N,1)
7	A(5,W,2), B(5,I,3), D(5,G,3),F(5,C,3), J(5,C,3), P(5,W,1),	(W,0) (L,1) (C,2) (I,2)
	Q(5,N,2), R(5,I,3), S(5,L,2), T(5,W,1), U(7,L,2), Y(7,N,2)	(N,1), (G,2)
8	H(3,A,3), B(5,I,3), D(5,G,3),F(5,C,3), J(5,C,3), P(5,W,1),	(W,0) (L,1) (C,2) (I,2)
	Q(5,N,2), R(5,I,3), S(5,L,2), T(5,W,1), U(7,L,2), Y(7,N,2)	(N,1), (G,2), (A,2)
9	B(5,I,3), D(5,G,3),F(5,C,3), J(5,C,3), P(5,W,1), Q(5,N,2),	(W,0) (L,1) (C,2) (I,2)
	R(5,I,3), S(5,L,2), T(5,W,1), U(7,L,2), Y(7,N,2)	(N,1), (G,2), (A,2), (H,3)
		Goal Found!