Chess Game Tracking Using Computer Vision and Deep Learning

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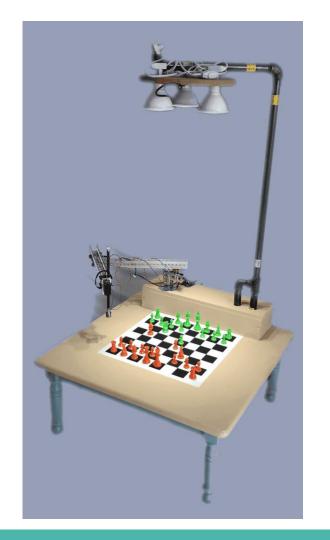
Motivation

- In tournaments, players must manually record every move played
- There are specialized chess sets that automatically record every move played, but they are expensive
- Tracking each game with computer vision is an inexpensive solution



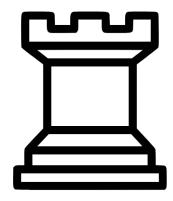
Previous Work

- Previous work has used an overhead view of the chessboard
 - Difficult to distinguish between certain pieces
 (e.g. pawns and bishops)
- Specialized colored chess sets (e.g. red and green pieces)



My Project

- Track a chess game using computer vision
 - Camera mounted over chessboard
 - 45 degree angle
 - Piece Detection
 - Pickle Module and Keras Library
 - Board Detection
 - OpenCV Library





Piece Detection

- Convolutional Neural Network
 - Training with database of chess pieces
 - Google Images
 - Manual Collection
 - Keras



Database of Pieces

- 7 folders of images corresponding to each piece
 - o Empty square, pawn, knight, bishop, rook, queen, king
- Started off using only sample images scraped from Google Images
- Later, added pictures manually taken at angles

Google Images Pictures

- Google Images as source
 - Used Javascript to create a txt file of all the urls of the images for each piece
 - Used Python to download the images into folders of respective pieces
- Folders containing images of each chess piece
- Filtered bad images to approx. 200-300 base examples for each folder







Manual Collection

 Pieces from Google Images were not representative of the pieces I wanted to test

Manually collected data at 30 - 60 degree angles

o 200 samples per piece

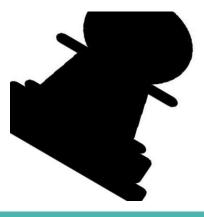


Data Standardization and Magnification

- Using Keras to standardize and augment training examples
 - Standardized to 100 x 100 grayscale .jpg files
 - Reflections and Rotations
 - Augmented to approx. 4500-6000











Saving my Data

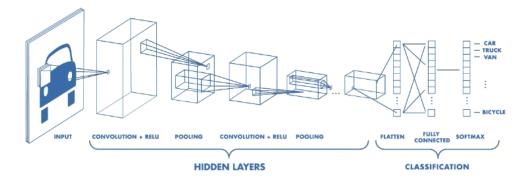
- I used the Python pickle module to save the files of my training folders into individual files
- Each category of piece corresponded to a label
 - o e.g. empty = 0, pawn = 1, knight = 2 etc.
- x.pickle contained each image and y.pickle contains the corresponding label

Convolutional Neural Network (CNN)

 A convolutional neural network is a type of deep neural network, most commonly applied to analyzing pictures and visual data

• Uses hidden see from an

image



Training

- Training remotely to the Duke Computer in Rm 202
 - Strong GPU shorter training time
- CNN structure:
 - o 6 convolutional layers RELU activation function
 - 5 dropout layers
 - Fully-connected layer with 1000 neurons RELU
 - Fully-connected layer with 7 neurons (corresponds to each piece) Softmax
- To about 92% accuracy

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 100, 100, 32)	89 6
max_pooling2d_1 (MaxPooling2 ((None, 50, 50, 32)	0
dropout_1 (Dropout)	(None, 50, 50, 32)	0
conv2d_2 (Conv2D)	(None, 50, 50, 64)	18496
max_pooling2d_2 (MaxPooling2 ((None, 25, 25, 64)	0
dropout_2 (Dropout)	(None, 25, 25, 64)	0
conv2d_3 (Conv2D)	(None, 25, 25, 128)	73856
max_pooling2d_3 (MaxPooling2 ((None, 12, 12, 128)	0
dropout_3 (Dropout)	(None, 12, 12, 128)	0
conv2d_4 (Conv2D)	(None, 12, 12, 256)	295168
max_pooling2d_4 (MaxPooling2 ((None, 6, 6, 256)	0
conv2d_5 (Conv2D)	(None, 6, 6, 512)	1180160
max_pooling2d_5 (MaxPooling2 ((None, 3, 3, 512)	0
dropout_4 (Dropout)	(None, 3, 3, 512)	0
conv2d_6 (Conv2D)	(None, 3, 3, 4024)	18546616
max_pooling2d_6 (MaxPooling2 ((None, 1, 1, 4024)	0
dropout_5 (Dropout)	(None, 1, 1, 4024)	0
flatten_1 (Flatten)	(None, 4024)	0
dense_1 (Dense)	(None, 1000)	4025000
dense 2 (Dense)	(None, 7)	7007

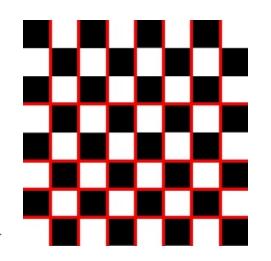
Saving the Model

- I saved my neural network in a file called chess.h5
- Using this file, I created a python classifier program that when given an image, classifies it as one of 7 categories (i.e. empty, pawn, knight...)



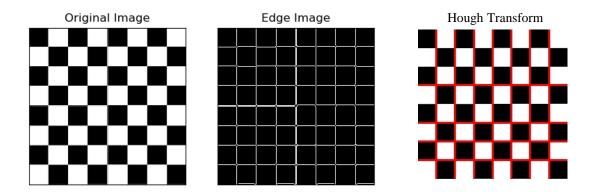
Board Detection

- Line Detection
 - Canny Edge Detector
 - Hough Transform
- Corner Detection
 - Intersections between perpendicular lines
 - Non-maximum suppression





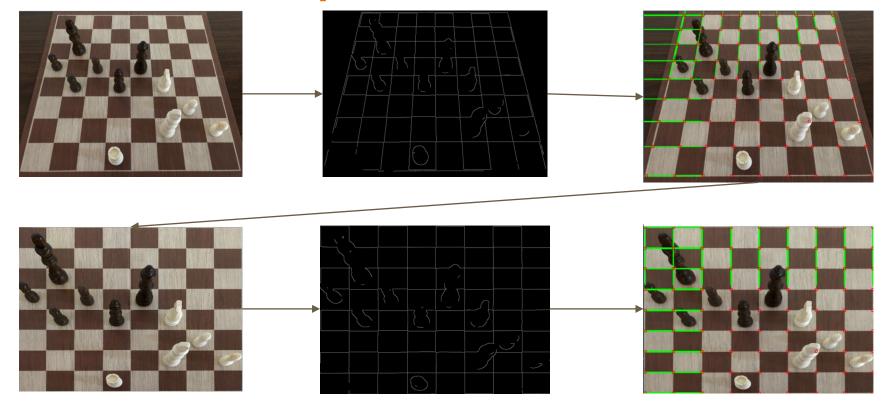
Canny Edge Detector and Hough Transform



Perspective Transform

- I used the far corners of the board to create a perspective transform of the image
- Then, I found the lines and corners again in the new image

Perspective Transform



Process

- 64 images are cut out and processed uses corners
- Each picture is run through the classifier to predict the piece (or if it's an empty square)
- The predicted board is then constructed using this information

Demonstration











```
('A1', 'pawn')
('B1', 'rook')
('C1', 'empty')
('D1', 'rook')
('E1', 'rook')
('F1', 'rook')
('G1', 'rook')
('H1', 'pawn')
('A2', 'knight')
('B2', 'bishop')
('C2', 'empty')
('D2', 'pawn')
('E2', 'empty')
('F2', 'pawn')
('G2', 'knight')
('H2', 'pawn')
('A3', 'knight')
('B3', 'bishop')
('C3', 'pawn')
('D3', 'empty')
('E3', 'empty')
('F3', 'empty')
('G3', 'empty')
('H3', 'empty')
('A4', 'empty')
('B4', 'empty')
('C4', 'empty')
('D4', 'empty')
('E4', 'empty')
('F4', 'empty')
('G4', 'empty')
('H4', 'empty')
('A5', 'empty')
('B5', 'empty')
('C5', 'empty')
('D5', 'empty')
('E5', 'empty')
('F5', 'empty')
('G5', 'empty')
('H5', 'empty')
```

Problems

- Inaccurate Classification
- Piece obstruction
- Difficulty in piece capture for each square
 - Multiple pieces in one picture



Unfinished Work

- Neural network needs fine tuning
- Needs ability to distinguish pieces by color

Acknowledgements

• I would like to acknowledge my Computer Systems Research Lab director,

Dr. Zacharias

Questions?