

A Differentiable POGLM with Forward-Backward Message Passing

Chengrui Li, Weihang Li, Yule Wang, Anqi Wu @ GaTech CSE

Contents

1. Partially observable generalized linear model (POGLM)
2. Variational inference (VI)
 - Inference methods
 - Sampling schemes
3. Experiments

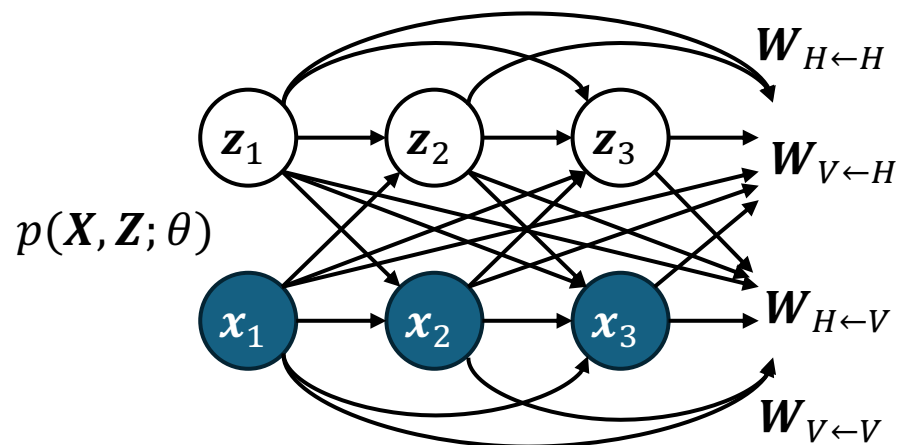
1 Partially observable generalized linear model (POGLM)

Introduction

- The partially observable generalized linear model (POGLM) is a powerful tool for understanding neural connectivity under the assumption of existing hidden neurons.
- POGLM itself is a difficult problem.
- Two main issues and our contributions:
 - The gradient estimator used in variational inference (VI).
 - The sampling scheme of the variational model.
- Comprehensive experiments on one synthetic and two real-world datasets.

POGLM

- V visible neurons and $H = N - V$ hidden neurons.



visible/hidden spike counts $\begin{bmatrix} \mathbf{x}_t \\ \mathbf{z}_t \end{bmatrix} \sim \text{Pois} \left(\begin{bmatrix} \mathbf{f}_t \\ \mathbf{g}_t \end{bmatrix} \right)$ visible/hidden firing rates

$$\begin{bmatrix} \mathbf{f}_t \\ \mathbf{g}_t \end{bmatrix} = \sigma \left(\underbrace{\begin{bmatrix} \mathbf{b}_V \\ \mathbf{b}_H \end{bmatrix}}_{\text{bias}} + \underbrace{\begin{bmatrix} \mathbf{W}_{V \leftarrow V} & \mathbf{W}_{H \leftarrow V} \\ \mathbf{W}_{V \leftarrow H} & \mathbf{W}_{H \leftarrow H} \end{bmatrix}}_{\text{weight}} \underbrace{\left(\sum_{l=1}^L \psi_l \begin{bmatrix} \mathbf{x}_{t-1} \\ \mathbf{z}_{t-1} \end{bmatrix} \right)}_{\text{convolved history}} \right)$$

- Observed variable: visible spike train $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_T]^T \in \mathbb{N}^{T \times V}$.
- Latent variable: hidden spike train $\mathbf{Z} = [\mathbf{z}_1, \dots, \mathbf{z}_T]^T \in \mathbb{N}^{T \times H}$.
- Generative parameter set: $\theta = \{ \mathbf{b} \in \mathbb{R}^{V+H}, \mathbf{W} \in \mathbb{R}^{(V+H) \times (V+H)} \}$.

2 Variational inference (VI)

Variational inference (VI)

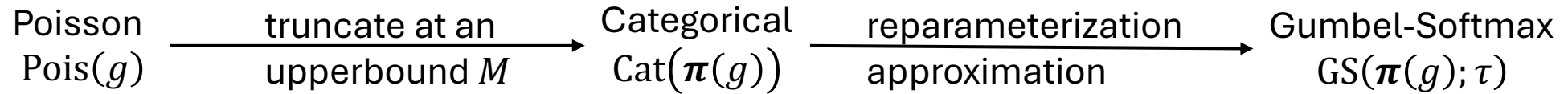
- Variational model $q(\mathbf{Z}|\mathbf{X}; \phi)$ parameterized by ϕ .
- **Inference methods:** $\mathbf{z}_t \sim \text{Pois}(\mathbf{g}_t)$.
- **Sampling schemes:** $\mathbf{g}_t = \text{function}(\mathbf{X}; \phi)$.
- Evidence lower bound:

$$\text{ELBO}(\mathbf{X}; \theta, \phi) = \mathbb{E}_q[\ln p(\mathbf{X}, \mathbf{Z}; \theta) - \ln q(\mathbf{Z}|\mathbf{X}; \phi)]$$

Inference methods: Gradient estimators

	score function	pathwise
distribution	any distribution	continuous distribution with reparameterization trick $\mathbf{Z} \mathbf{X}; \phi = r(\boldsymbol{\epsilon} \mathbf{X}; \phi)$
samples	$\{\mathbf{Z}^{(k)}\}_{k=1}^K \sim q(\mathbf{Z} \mathbf{X}; \phi)$	$\{\boldsymbol{\epsilon}^{(k)}\}_{k=1}^K \sim R(\boldsymbol{\epsilon})$
$\frac{\partial \text{ELBO}(\mathbf{X}; \theta, \phi)}{\partial \phi} \approx$	$\frac{\partial}{\partial \phi} \frac{-1}{2K} \sum_{k=1}^K [\ln p(\mathbf{X}, \mathbf{Z}^{(k)}; \theta) - \ln q(\mathbf{Z}^{(k)} \mathbf{X}; \phi)]$	$\frac{\partial}{\partial \phi} \frac{1}{K} \sum_{k=1}^K [\ln p(\mathbf{X}, r(\boldsymbol{\epsilon}^{(k)} \mathbf{X}; \phi); \theta) - \ln q(r(\boldsymbol{\epsilon}^{(k)} \mathbf{X}; \phi) \mathbf{X}; \phi)]$

Inference methods: Relaxation



- Truncation:

$$\boldsymbol{\pi}(g) = \left(1 - \sum_{m=1}^{M-1} \frac{g^m e^g}{m!}, \frac{g^1 e^g}{1!}, \dots, \frac{g^{M-1} e^g}{(M-1)!} \right)$$

- Gumbel-Softmax soft spike:

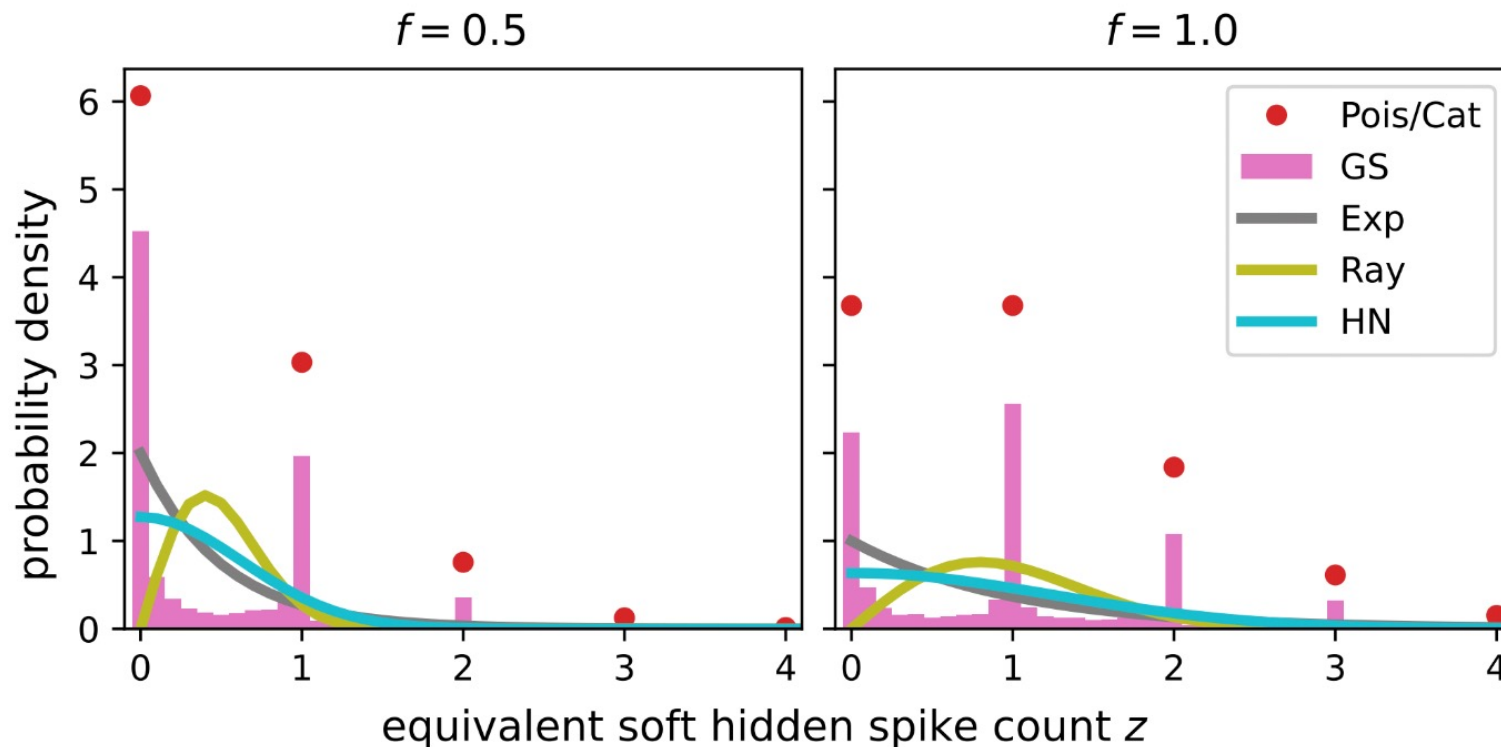
$$\tilde{\mathbf{z}}_{t,h} = (\tilde{z}_{t,h,0}, \dots, \tilde{z}_{t,h,M-1}) \sim \text{GS}(\boldsymbol{\pi}(g_{t,h}); \tau)$$

- Equivalent soft spike count:

$$z_{t,h} = \sum_{m=0}^{M-1} m \cdot \tilde{z}_{t,h,m}$$

Inference methods: Candidate distributions

- Replace the distribution $\mathbb{P}[z; g]$ in the generative and variational model with the following distributions governed by $\mathbb{E}[z] = g$.



distribution	can pathwise
$\text{Pois}(g)$	✗
$\text{Cat}(\boldsymbol{\pi}(g))$	✗
$\text{GS}(\boldsymbol{\pi}(g); \tau)$	✓
$\text{Exp}\left(\frac{1}{g}\right)$	✓
$\text{Ray}\left(\sqrt{\frac{2}{\pi}}g\right)$	✓
$\text{HN}\left(\sqrt{\frac{\pi}{2}}g\right)$	✓

Sampling schemes

- Forward-self (FS)

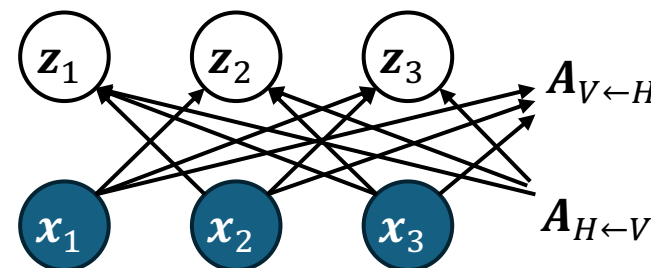
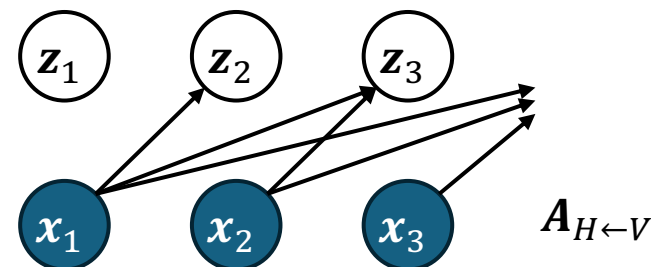
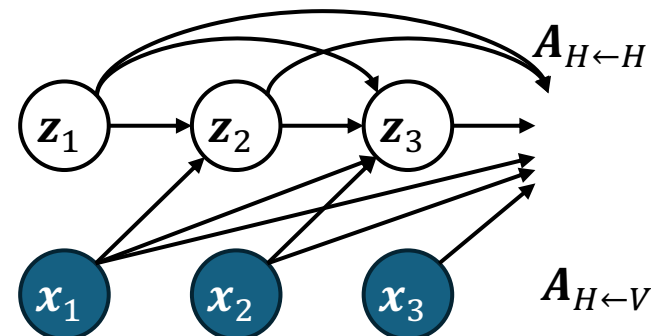
- $\mathbf{g}_t = \sigma \left(\mathbf{c}_H + \mathbf{A}_{H \leftarrow V} \left(\sum_{l=1}^L \psi_l \mathbf{x}_{t-l} \right) + \mathbf{A}_{H \leftarrow H} \left(\sum_{l=1}^L \psi_l \mathbf{z}_{t-l} \right) \right)$
- $\phi = \{ \mathbf{c}_H \in \mathbb{R}^H, \mathbf{A}_{H \leftarrow V} \in \mathbb{R}^{H \times V}, \mathbf{A}_{H \leftarrow H} \in \mathbb{R}^{H \times H} \}$

- Forward (F)

- $\mathbf{g}_t = \sigma \left(\mathbf{c}_H + \mathbf{A}_{H \leftarrow V} \left(\sum_{l=1}^L \psi_l \mathbf{x}_{t-l} \right) \right)$
- $\phi = \{ \mathbf{c}_H \in \mathbb{R}^H, \mathbf{A}_{H \leftarrow V} \in \mathbb{R}^{H \times V} \}$

- Forward-backward (FB)

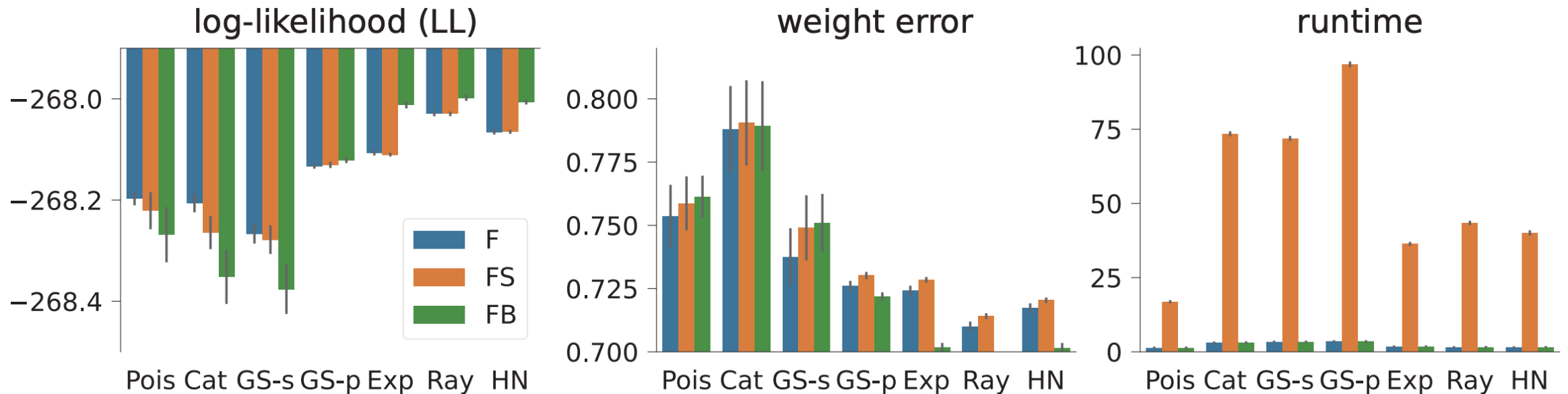
- $\mathbf{g}_t = \sigma \left(\mathbf{c}_H + \mathbf{A}_{H \leftarrow V} \left(\sum_{l=1}^L \psi_l \mathbf{x}_{t-l} \right) + \mathbf{A}_{V \leftarrow H} \left(\sum_{l=1}^L \psi_l \mathbf{x}_{t+l} \right) \right)$
- $\phi = \{ \mathbf{c}_H \in \mathbb{R}^H, \mathbf{A}_{H \leftarrow V} \in \mathbb{R}^{H \times V}, \mathbf{A}_{V \leftarrow H} \in \mathbb{R}^{V \times H} \}$



3 Experiments

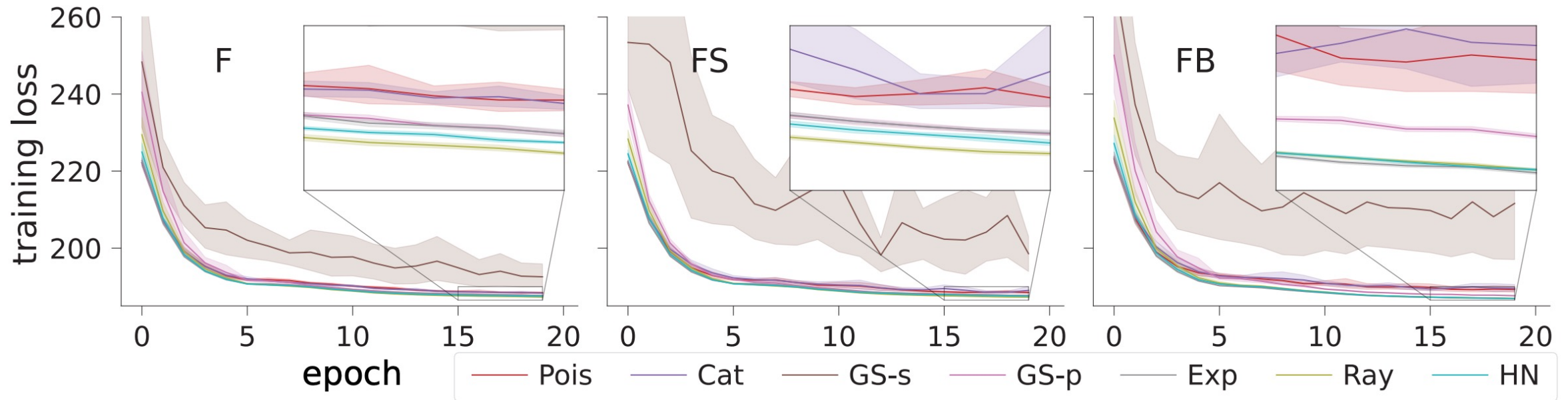
Synthetic

- 3-visible-2-hidden.
- High likelihood and low weight error for differentiable inference methods (GS-pathwise, Exp, Ray, HN).
- Fast runtime for forward (F) and forward-backward (FB).



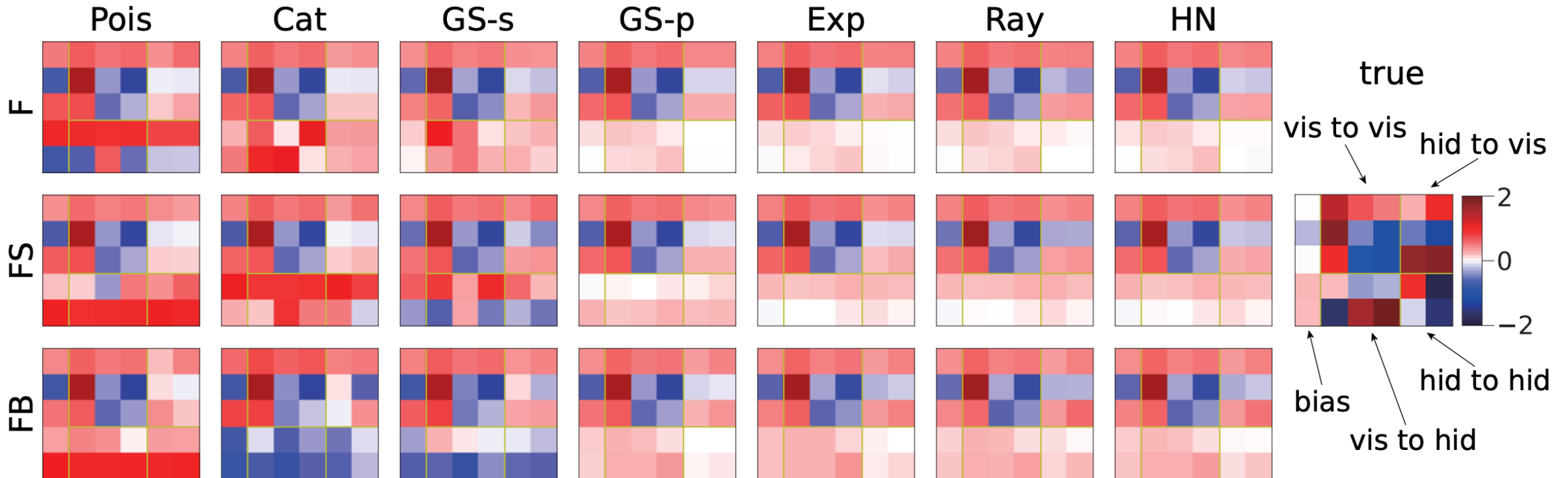
Synthetic

- Better convergence for differentiable inference methods.



Synthetic

- Differentiable inference methods \times FB has better parameter estimation.



Retinal ganglion neurons (Pillow & Scott, 2012)

- Neuron 1-16: OFF cell. Neuron 17-27: ON cell.
- 20 minutes of a visual task on a mouse.
- Assuming $H \in \{1,2,3\}$ hidden neurons.

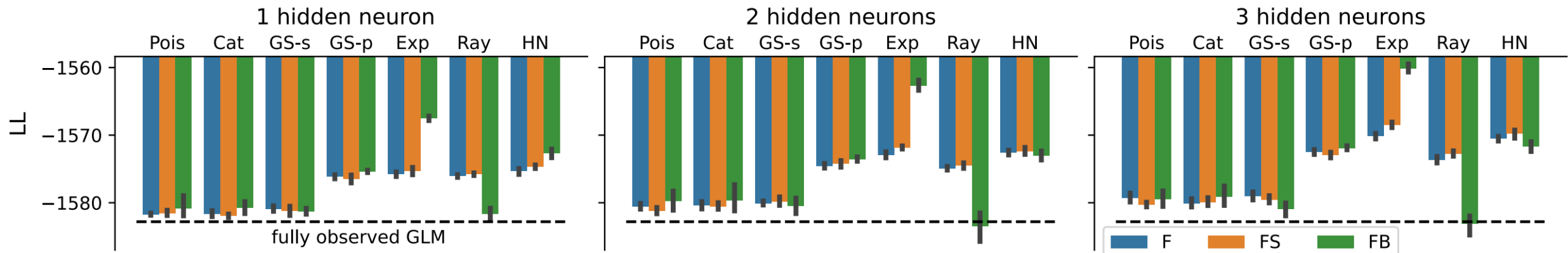
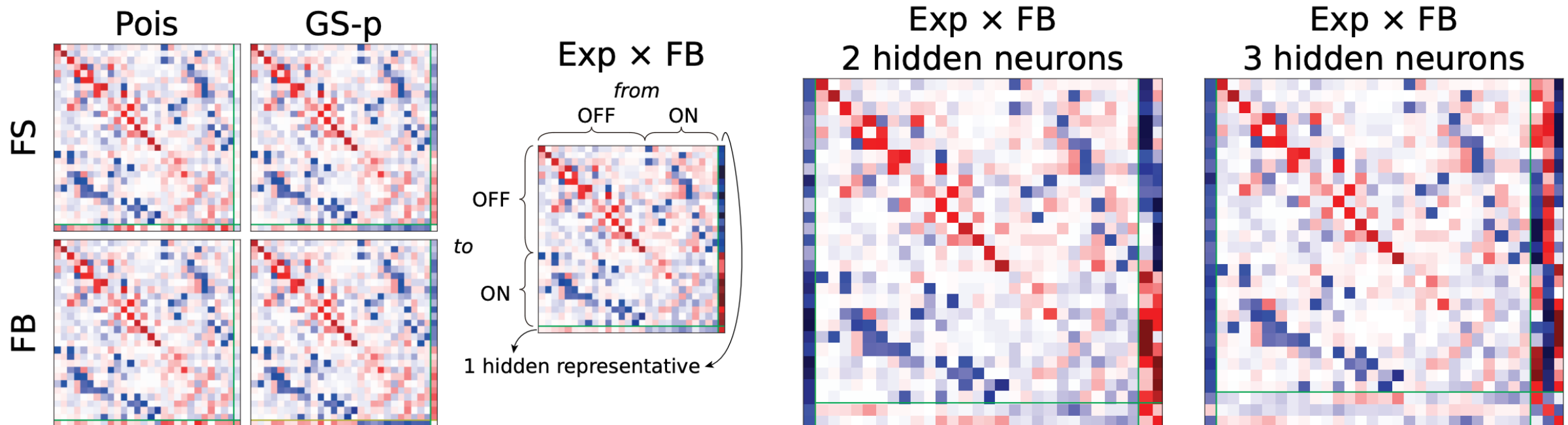


Figure 5. The test log-likelihood (LL) of different method combinations under $H \in \{1, 2, 3\}$ hidden neurons. The dashed black line represents the test LL of the fully observed GLM as the baseline.

Retinal ganglion neurons (Pillow & Scott, 2012)

- The learned weight matrix.
- The learned one hidden representative from $\text{Exp} \times \text{FB}$ serves as a negative feed back regulating unit.



Primary visual cortex (cnrcs: PVC-5)

- Primary visual cortex (V1) recordings from a macaque monkey over a 15-minute duration without presenting any stimuli.
- Only 3 visible neurons
- Assuming $H \in \{1, \dots, 9\}$ hidden neurons. Containing cases where $H \gg V$.

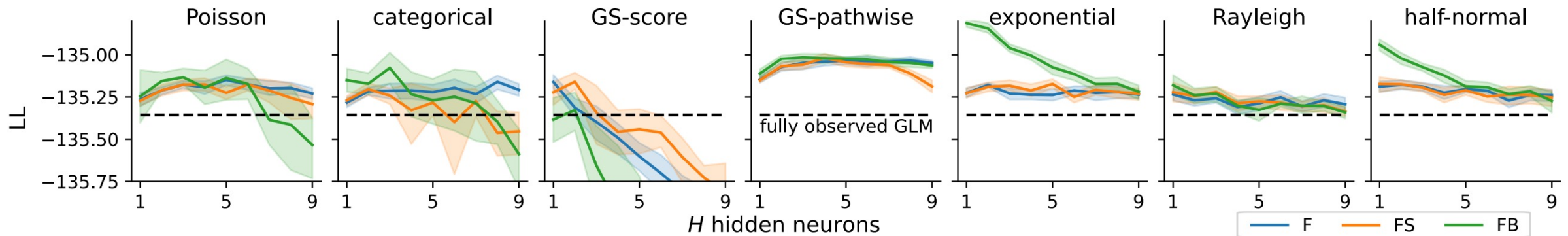


Figure 7. The curves of the test log-likelihood (LL) v.s. the number of hidden neurons H , for different method combinations.

Summary

- A differentiable version of the partially observable generalized linear model (POGLM), in which the pathwise gradient estimator becomes applicable when doing variational inference (VI).
- The new forward-backward message passing sampling scheme is faster and more expressive.
- Note that the relaxation from Gumbel-Softmax distribution to general continuous distributions loses the meaning of \mathbf{Z} as representing spike counts, but can produce better performance. This is worth to be investigated in the future.

Thanks for listening!