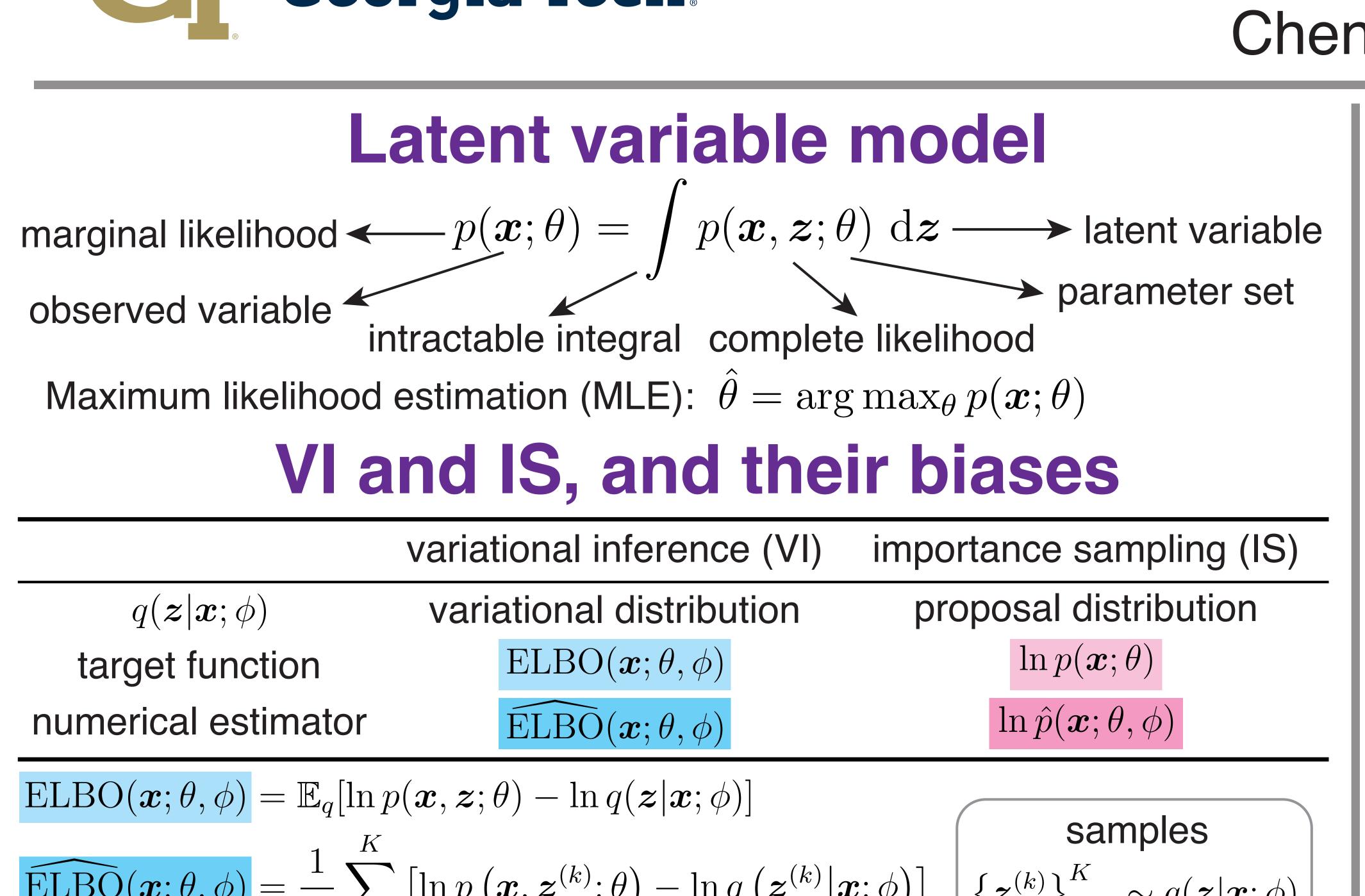


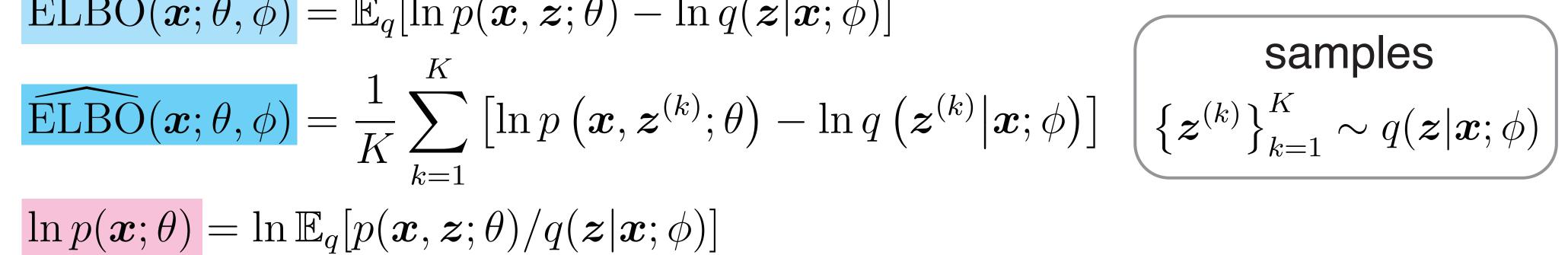
Forward χ^2 Divergence Based Variational Importance Sampling

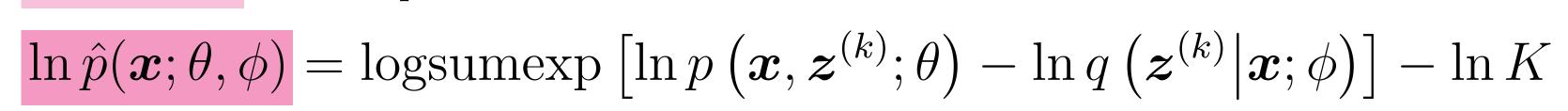
3 ICLR 2024 [Spotlight]

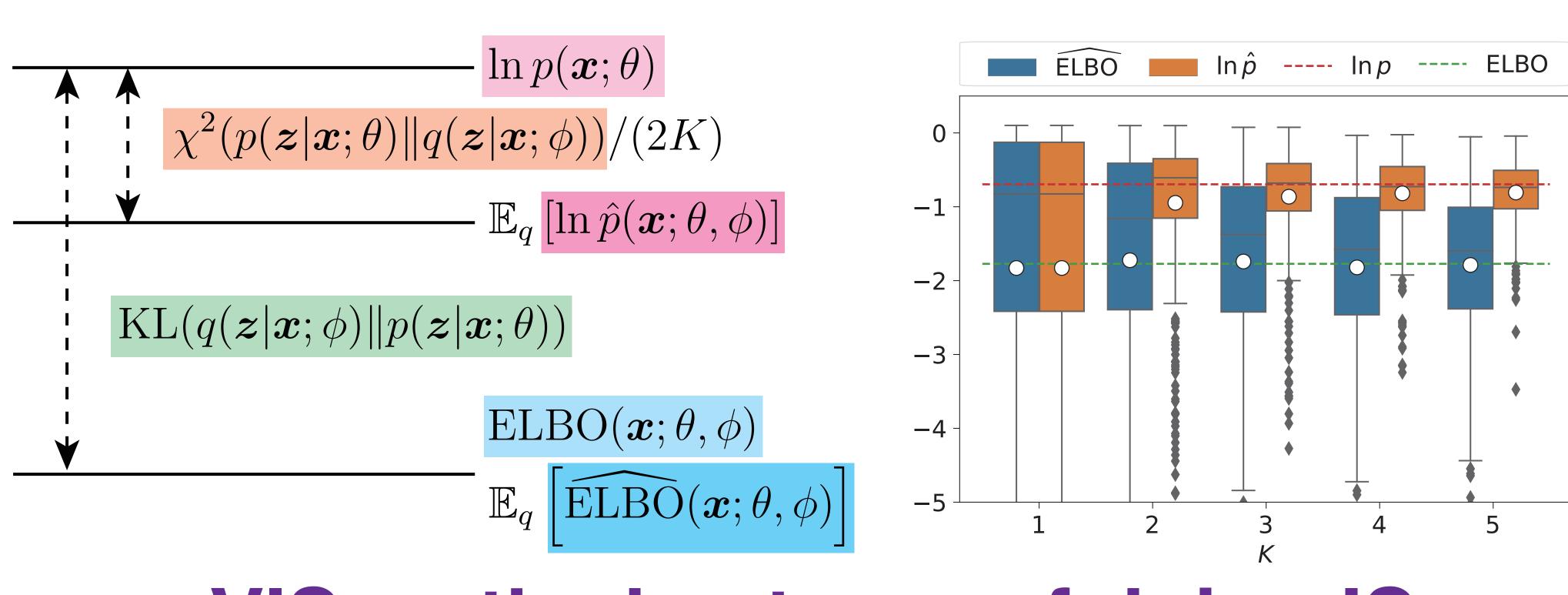


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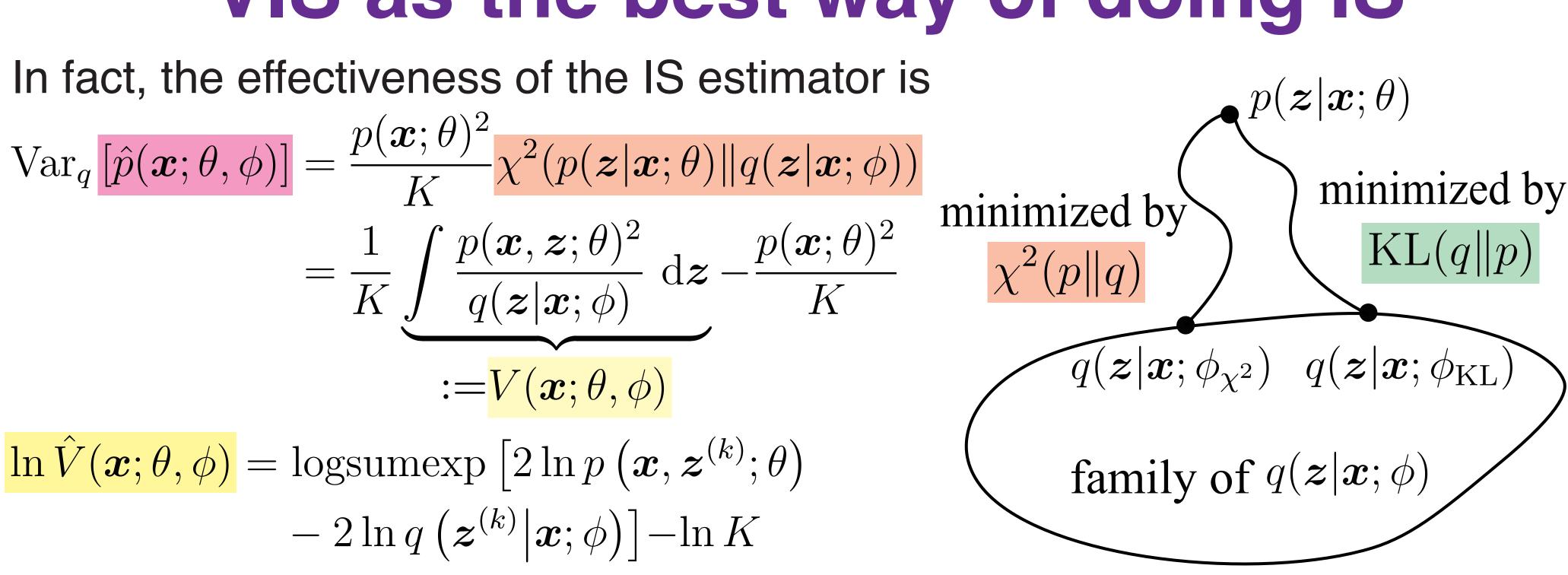




VIS as the best way of doing IS

 $:=V(\boldsymbol{x};\theta,\phi)$ $\ln \hat{V}(\boldsymbol{x}; \theta, \phi) = \operatorname{logsumexp} \left[2 \ln p \left(\boldsymbol{x}, \boldsymbol{z}^{(k)}; \theta \right) \right]$

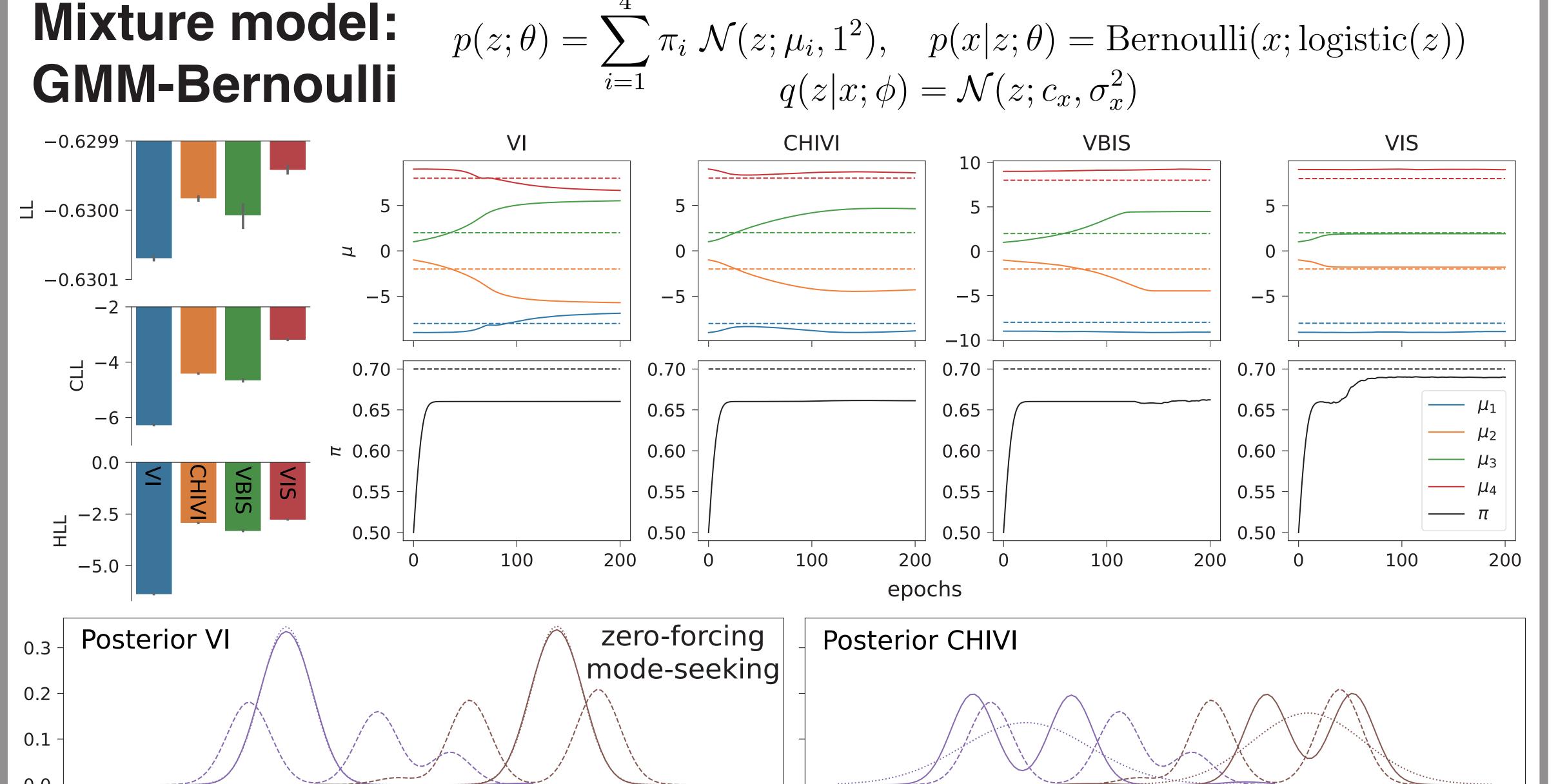
 $-2\ln q\left(\boldsymbol{z}^{(k)}|\boldsymbol{x};\phi\right)$ $-\ln K$



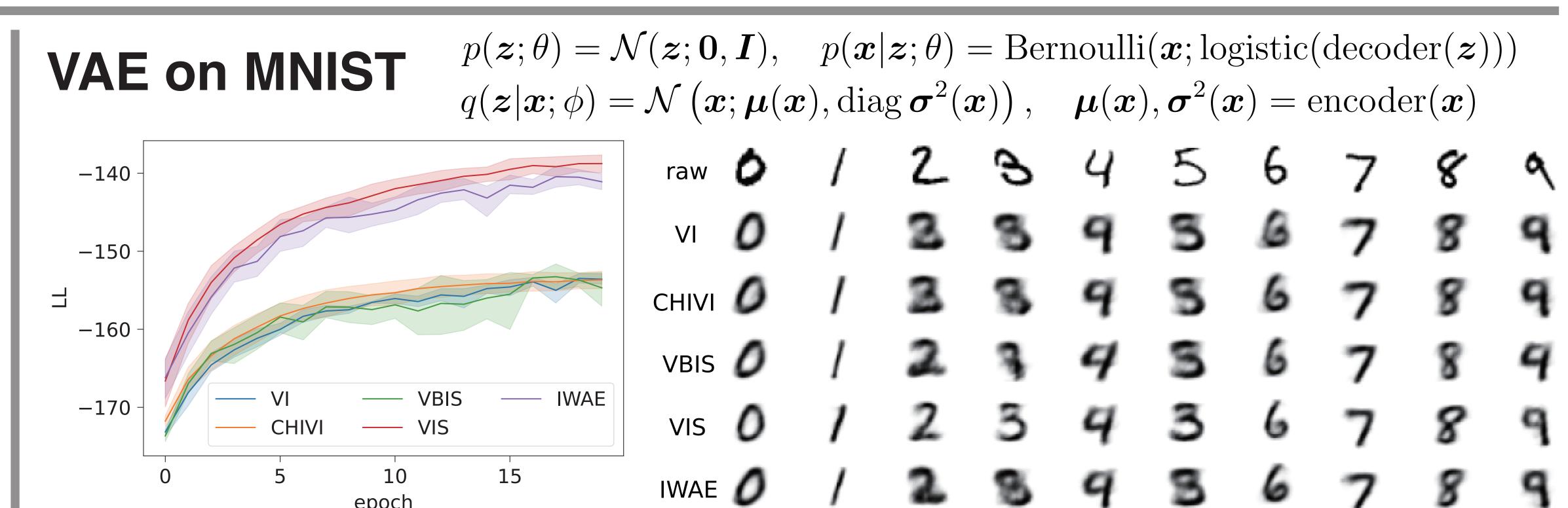
0.3 - Posterior VBIS

VIS algorithm variational importance sampling (VIS) $\left\{ oldsymbol{z}^{(k)} ight\}_{k=1}^K \sim q(oldsymbol{z} | oldsymbol{x}; \phi)$ Sample $\min \chi^2(p(\boldsymbol{z}|\boldsymbol{x};\theta)||q(\boldsymbol{z}|\boldsymbol{x};\phi))$ $\min \mathrm{KL}(q(\boldsymbol{z}|\boldsymbol{x};\phi)||p(\boldsymbol{z}|\boldsymbol{x};\theta))$ $\rightarrow \min \ln V(\boldsymbol{x}; \theta, \phi)$ $\rightarrow \min \text{ELBO}(\boldsymbol{x}; \theta, \phi)$ E-step $\frac{\partial \operatorname{ELBO}(\boldsymbol{x}; \boldsymbol{\theta}, \phi)}{\partial \phi} \approx \frac{\partial}{\partial \phi} \frac{-1}{2K} \sum_{k=1}^{K}$ $\frac{\partial \ln V(\boldsymbol{x}; \boldsymbol{\theta}, \phi)}{\partial \phi} \approx \frac{\partial}{\partial \phi} \frac{1}{2} \ln \hat{V}(\boldsymbol{x}; \boldsymbol{\theta}, \phi)$ $\left[\ln p\left(\boldsymbol{x}, \boldsymbol{z}^{(k)}; \theta\right) - \ln q\left(\boldsymbol{z}^{(k)} | \boldsymbol{x}; \phi\right)\right]^{2}$ $\max_{\boldsymbol{\theta}} \ln p(\boldsymbol{x}; \boldsymbol{\theta})$ $\max \ln p(\boldsymbol{x}; \theta)$ $\rightarrow \max \text{ELBO}(\boldsymbol{x}; \theta, \phi)$ M-step $\partial \operatorname{ELBO}(\boldsymbol{x}; \theta, \phi) \approx \frac{\partial}{\partial \theta} \widehat{\operatorname{ELBO}}(\boldsymbol{x}; \theta, \phi)$ $\frac{\partial \ln p(\boldsymbol{x}; \theta)}{\partial \theta} \approx \frac{\partial}{\partial \phi} \ln \hat{p}(\boldsymbol{x}; \theta, \phi)$

Experiments



Posterior VIS

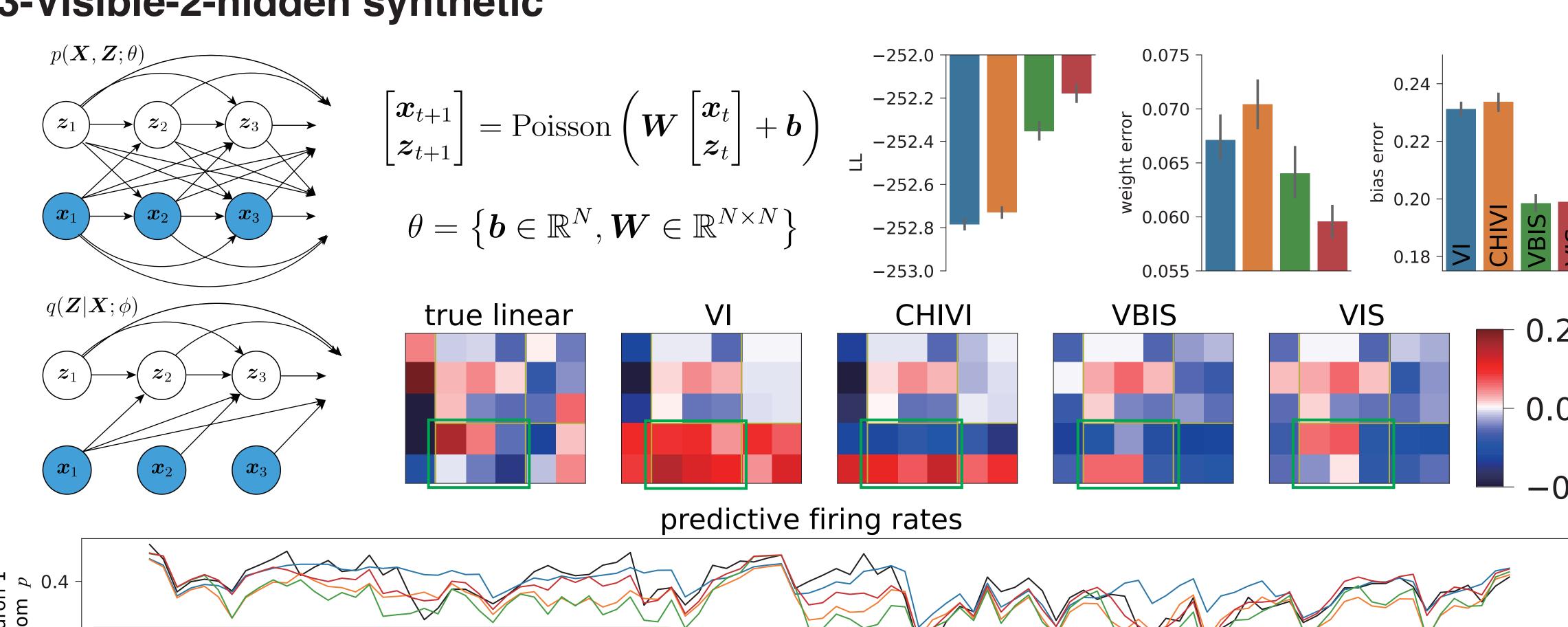


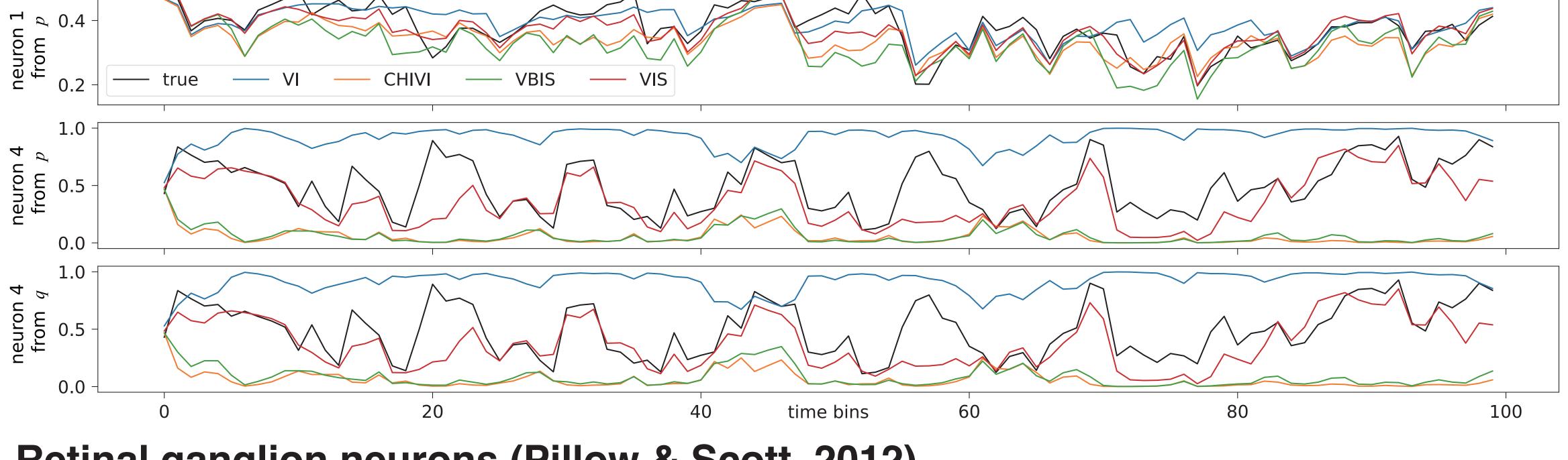
Partially observable GLM

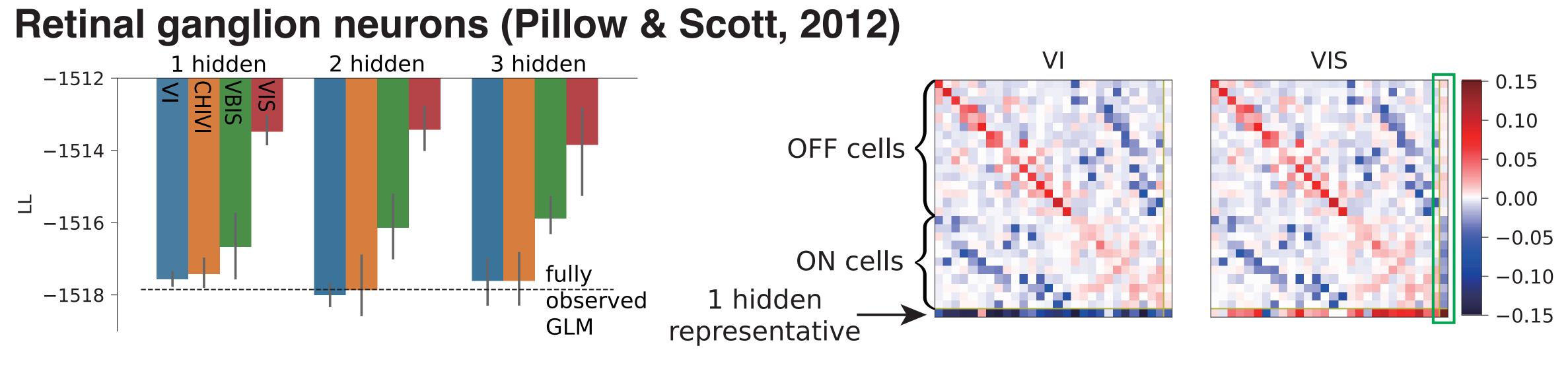
mass-covering

mean-seeking

A very hard problem since $p(\boldsymbol{x}, \boldsymbol{z}; \theta)$ cannot be explicitly factored as $p(\boldsymbol{x}|\boldsymbol{z}; \theta)p(\boldsymbol{z}; \theta)$. 3-Visible-2-hidden synthetic







References: [1] Burda et al., arXiv, 2015. [2] Dieng et al., NeurIPS, 2017. [3] Finke & Thiery, arXiv, 2019. [4] Jerfel et al., PMLR, $---- p(z|x=1;\theta)$ 2018. [5] Domke & Sheldon, NeurIPS, 2021. [6] Su & Chen, Comp. Stat., 2021. [7] Akyildiz & Miguez, Stat. Comp., 2021.