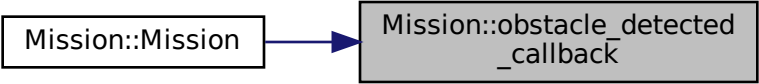


Mission::Mission



```
graph LR; A[Mision::Mission] --> B[Mision::obstacle_detected_callback]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'Mision::Mission'. The right box is light gray with a black border and contains the text 'Mision::obstacle_detected_callback'. A dark blue arrow points from the right side of the left box to the left side of the right box.

Mision::obstacle_detected
_callback