

Mission::Mission

```
graph LR; A[Mission::Mission] --> B[Mission::waypoint_reached_callback]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'Mission::Mission'. The right box is gray with a black border and contains the text 'Mission::waypoint_reached_callback'. A dark blue arrow points from the right side of the left box to the left side of the right box.

Mission::waypoint_reached
_callback