

1.

```

// language: C
// reference: https://www.geeksforgeeks.org/multiply-two-polynomials-2/
#include <stdio.h>
#include <stdlib.h>
#include <time.h>
#include <math.h>
int main() {
    int max_1 = 0, max_2 = 0, max_3 = 0, coef = 0;
    int poly_A[100], poly_B[100], poly_C[100] = {0};

    printf("Enter the power of polynomial A: \n");
    scanf("%d", &max_1);

    printf("Enter each coefficient of polynomial A: (from x^0 to x^n)\n");
    for (int i = 0; i <= max_1; i++) {
        scanf("%d", &poly_A[i]);
    }

    printf("Enter the power of polynomial B: \n");
    scanf("%d", &max_2);

    printf("Enter each coefficient of polynomial B: (from x^0 to x^n)\n");
    for (int i = 0; i <= max_2; i++) {
        scanf("%d", &poly_B[i]);
    }

    // iterative multiplication
    for (int i = 0; i <= max_1; i++) {
        for (int j = 0; j <= max_2; j++) {
            poly_C[i+j] += poly_A[i] * poly_B[j];
        }
    }

    // print out the result
    max_3 = max_1 + max_2;
    coef = 0;
    for (int i = 0; i <= max_3; i++) {
        printf("a%d: %d\n", coef, poly_C[i]);
        coef++;
    }

    return 0;
}

```

2.

```
// language: C++  
// reference: http://algorithm.cs.nthu.edu.tw/~course/Extra\_Info/Divide%20and%20Conquer\_supplement.pdf  
// reference: https://github.com/nextco/cormen-fft/blob/master/pm-divide-and-conquer.cpp
```

```
#include <cstdio>  
#include <cstring>  
#include <iostream>  
#include <chrono>  
#include <time.h>
```

```
using namespace std;  
typedef long long ll;
```

```
// polynomial coefficients are saved in increasing order of degree  
// coefficient of  $x^i$  in polynomial  $p = p[i]$ 
```

```
// multiply polynomials p and q, both of size sz,  
// where sz is multiple of 2  
void karatsuba(ll *res, const ll *p, const ll *q, int sz){  
    ll t0[sz], t1[sz], r[sz<<1];
```

```
    memset(r, 0, (sz<<1) * sizeof(ll));
```

```
    if ( sz <= 4 ){ // base case, no recursion, do basic school multiplication  
        for ( int i = 0 ; i < sz ; i++ )  
            for ( int j = 0 ; j < sz ; j++ ){  
                r[i + j] += p[i] * q[j];  
            }  
    }
```

```
    } else {  
        // let  $p = a \cdot x^{nSz} + b$   
        //  $q = c \cdot x^{nSz} + d$   
        //  $r = ac \cdot x^{sz} + ((a+b)(c+d) - ac - bd) \cdot x^{nSz} + bd$   
        int nSz = (sz >> 1);
```

```
        for ( int i = 0 ; i < nSz ; i++ ){  
            t0[i] = p[i] + p[nSz + i]; // t0 = a + b  
            t1[i] = q[i] + q[nSz + i]; // t1 = c + d  
            t0[i + nSz] = t1[i + nSz] = 0; // initialize  
        }
```

```
        karatsuba(r + nSz, t0, t1, nSz); // r[nSz...sz] = (a+b)(c+d)  
        karatsuba(t0, p, q, nSz); // t0 = bd  
        karatsuba(t1, p + nSz, q + nSz, nSz); // t1 = ac
```

```

        for ( int i = 0 ; i < sz ; i++ ){
            r[i] += t0[i];          // bd
            r[i + nSz] -= t0[i] + t1[i];    // ((a+b)(c+d) - ac - bd) * x**nSz
            r[i + sz] += t1[i];          // ac * x**sz
        }
    }

    memcpy(res, r, (sz<<1) * sizeof(ll));
}

// multiply two polynomials p and q, both of size sz = degree + 1
// save the output in array r
// NOTE: the maximum capacity of p, q, r should be power of two
// NOTE: r should be at least double of p or q in size
void polyMult(ll *r, ll *p, ll *q, int sz){
    if ( sz & (sz - 1) ){ // if size is not power of two
        int k = 1;
        while ( k < sz ) k <<= 1;
        while ( ++sz <= k ) p[sz - 1] = q[sz - 1] = 0;
        sz--;
    }

    karatsuba(r, p, q, sz);
}

// print polynomial in descending order of degree
void polyPrint(ll *p, int sz){
    while ( --sz >= 0 ) cout << p[sz] <<" ";
    puts("");
}

int main(){
    ll p[4] = {4,3,2,1};
    ll q[4] = {4,3,2,1};
    ll r[8];
    int degree = 3;

    polyMult(r, p, q, degree + 1);
    polyPrint(r, degree * 2 + 1);
    return 0;
}

```

3.

```
// language: C++  
// reference: https://www.geeksforgeeks.org/fast-fourier-transformation-polynomial-multiplication/  
// reference: https://hk.saowen.com/a/b6e9f0ca70a669575a8b8e56c746ba63780958c4c12159aec6bfb05a7ff2e409  
// http://www.voidcn.com/article/p-rzrkhhina-boa.html
```

```
#include <cstdio>  
#include <cmath>  
#include <iostream>  
#include <time.h>
```

```
const int MAXN = 4 * 1e5 + 10;  
double Pi = acos(-1);
```

```
struct Complex {  
    double r, i;  
    Complex() {}  
    Complex(double _r, double _i) { r = _r; i = _i; }  
    Complex operator + (const Complex &y) { return Complex(r + y.r, i + y.i); }  
    Complex operator - (const Complex &y) { return Complex(r - y.r, i - y.i); }  
    Complex operator * (const Complex &y) { return Complex(r*y.r - i * y.i, r*y.i + i * y.r); }  
    Complex operator *= (const Complex &y) {  
        double t = r;  
        return Complex(r = r * y.r - i * y.i, i = t * y.i + i * y.r); }  
} a[MAXN], b[MAXN];
```

```
void FFT(Complex* a, long length, int op){  
    if(length == 1)  
        return;  
    Complex * a0 = new Complex[length/2];  
    Complex * a1 = new Complex[length/2];  
    for(long i = 0; i < length; i += 2){  
        a0[i/2] = a[i];  
        a1[i/2] = a[i+1];  
    }  
}
```

```
FFT(a0, length/2, op);  
FFT(a1, length/2, op);
```

```
Complex wn(cos(2*Pi/length),op * sin(2*Pi/length));  
Complex w(1, 0);
```

```
for(long i = 0; i < (length/2); i++){  
    a[i] = a0[i]+w*a1[i];
```

```

        a[i+length/2] = a0[i]-w*a1[i];
        w = w*wn;
    }

    delete[] a0;
    delete[] a1;
}

int main(int argc, const char * argv[]) {
    clock_t start, finish;
    float duration;

    int ordP1,ordP2,length;
    double innc;
    Complex poly_A[100],poly_B[100],poly_C[100];

    printf("Enter the power of polynomial A: \n");
    scanf("%d",&ordP1);
    printf("Enter each coefficient of polynomial A: (from x^0 to x^n)\n");
    for(int i=0;i<=ordP1;i++){
        scanf("%lf",&innc);
        poly_A[i].r=innc;
        poly_A[i].i=0;
    }

    printf("Enter the power of polynomial B: \n");
    scanf("%d",&ordP2);
    printf("Enter each coefficient of polynomial B: (from x^0 to x^n)\n");
    for(int i=0;i<=ordP2;i++){
        scanf("%lf",&innc);
        poly_B[i].r=innc;
        poly_B[i].i=0.0;
    }

    start = clock();
//    FFT ALG
    for(int i=1; i<=abs(ordP1-ordP2) && (ordP1-ordP2!=0) ;i++){
        if(ordP1-ordP2<0){
            poly_A[i+ordP1]*=Complex(0.0,0.0);
        }
        else{
            poly_B[i+ordP2]*=Complex(0.0,0.0);
        }
    }

    length = (ordP1-ordP2)?(ordP1+1):(ordP2+1);

```

```

for(length = 2; length < ordP1+ordP2+2;length*=2);

for(int i =ordP1+1;i<length;i++){
    poly_A[i] = poly_A[i] * Complex(0.0,0.0);
    poly_B[i] = poly_B[i] * Complex(0.0,0.0);
}

FFT(poly_A,length,1);
FFT(poly_B,length,1);

for (int i =0;i<length;i++){
    poly_C[i]=poly_A[i]*poly_B[i];
}

FFT(poly_C,length,-1);
for (int i =0;i<length;i++){
    poly_C[i].r /= length;
}
finish = clock();
duration = (double)(finish - start) / CLOCKS_PER_SEC;
// printf( "%f seconds\n", duration );
int coef = 0;
for(int i = 0;i< ordP1+ordP2+1 ;i++) {
    printf("a%d: %lf \n", coef, poly_C[i].r);
    coef++;
}

printf("\n");
return 0;
}

```

4.

// classical iterative method

// reference: (Cull, Classnote, p.45)

// reference: <http://web.cs.iastate.edu/~cs577/handouts/polymultiply.pdf>

$$P(x) = a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1}$$

$$Q(x) = b_0 + b_1x + b_2x^2 + \dots + b_{n-1}x^{n-1}$$

$$P(x)Q(x) = c_0 + c_1x + \dots + c_{2n-2}x^{2n-2}, \text{ where } c_i = \sum_{\max\{0, i-(n-1)\} \leq k \leq \min\{i, n-1\}} a_k b_{i-k}.$$

because every a_i is multiply with every b_j , for $0 \leq i, j \leq n-1$

$$\Rightarrow \Theta(n^2)$$

// divide and conquer method

// reference: http://algorithm.cs.nthu.edu.tw/~course/Extra_Info/Divide%20and%20Conquer_supplement.pdf

$$P(x) = P_0(x) + P_1(x)x^{n/2}$$

$$Q(x) = Q_0(x) + Q_1(x)x^{n/2}$$

$$P(x)Q(x) = P_0(x)Q_0(x) + (P_0(x)Q_1(x) + P_1(x)Q_0(x))x^{n/2} + P_1(x)Q_1(x)x^n$$

where $P_0(x)$, $P_1(x)$, $Q_0(x)$, $Q_1(x)$ are all polynomials of degree $n/2 - 1$

$$M(n) = 3M(n/2) + cn$$

$$= 3^k(n/2^k) + (1+2+4+\dots+2^{k-1})cn$$

$$\text{when } n/2^k = 1 \Rightarrow M(1) \Rightarrow k = \log_2 n$$

$$\Rightarrow M(n) = 3^{\log n} M(1) + cn(2^{\log n} - 1) = 3^{\log n} M(1) + cn(n - 1)$$

$$\Rightarrow \Theta(3^{\log n})$$

$$\Rightarrow \Theta(n^{\log 3})$$

// FFT method

// reference: <http://web.cs.iastate.edu/~cs577/handouts/polymultiply.pdf>

// reference: (Cull, Classnote, p.50~54)

RECURSIVE-DFT(\mathbf{a}, n)

```
1  if  $n = 1$ 
2      then return  $\mathbf{a}$ 
3   $w_n \leftarrow e^{i\frac{2\pi}{n}}$ 
4   $w \leftarrow 1$ 
5   $\mathbf{a}^{[0]} \leftarrow (a_0, a_2, \dots, a_{n-2})$ 
6   $\mathbf{a}^{[1]} \leftarrow (a_1, a_3, \dots, a_{n-1})$ 
7   $\hat{\mathbf{a}}^{[0]} \leftarrow \text{RECURSIVE-DFT}(\mathbf{a}^{[0]}, \frac{n}{2})$ 
8   $\hat{\mathbf{a}}^{[1]} \leftarrow \text{RECURSIVE-DFT}(\mathbf{a}^{[1]}, \frac{n}{2})$ 
9  for  $k = 0$  to  $\frac{n}{2} - 1$  do
10      $\hat{a}_k \leftarrow \hat{a}_k^{[0]} + w\hat{a}_k^{[1]}$ 
11      $\hat{a}_{k+\frac{n}{2}} \leftarrow \hat{a}_k^{[0]} - w\hat{a}_k^{[1]}$ 
12      $w \leftarrow w w_n$ 
13  return  $(\hat{a}_0, \hat{a}_1, \dots, \hat{a}_{n-1})$ 
```

$$\Rightarrow T(n, |x|) = 2 \cdot T(n/2, |x|) + O(n + |x|)$$

if $T(n/2, |x|/2)$

$$\Rightarrow T(n) = 2T(n/2) + O(n)$$

by the formula of Master Theorem

$$\Rightarrow \Theta(n \log n)$$

By the big theta of three algorithms, I predict that FFT method will be the fastest for large degree polynomials. Because $n \log n$ will be smaller than n^2 if n is large.

5.

case 1: choose $P(x) = 1 + 2x^2 + 3x^3 + 4x^4$, $Q(x) = 1 + 2x^2 + 3x^3 + 4x^4$

// classical iterative method

```
Enter the power of polynomial A:
3
Enter each coefficient of polynomial A: (from x^0 to x^n)
1
2
3
4
Enter the power of polynomial B:
3
Enter each coefficient of polynomial B: (from x^0 to x^n)
1
2
3
4
a0: 1
a1: 4
a2: 10
a3: 20
a4: 25
a5: 24
a6: 16
Program ended with exit code: 0
```

// divide and conquer method
from $x_n \rightarrow$ constant

```
16 24 25 20 10 4 1
Program ended with exit code: 0
```

// FFT method

```
Enter the power of polynomial A:
3
Enter each coefficient of polynomial A: (from x^0 to x^n)
1
2
3
4
Enter the power of polynomial B:
3
Enter each coefficient of polynomial B: (from x^0 to x^n)
1
2
3
4
a0: 1.000000
a1: 4.000000
a2: 10.000000
a3: 20.000000
a4: 25.000000
a5: 24.000000
a6: 16.000000
Program ended with exit code: 0
```

case 2: choose $P(x) = 4 + 3x^1 + 2x^2 + 1x^3$,
 $Q(x) = 4 + 3x^1 + 2x^2 + 1x^3$

// classical iterative method

```
Enter the power of polynomial A:
3
Enter each coefficient of polynomial A: (from x^0 to x^n)
4
3
2
1
Enter the power of polynomial B:
3
Enter each coefficient of polynomial B: (from x^0 to x^n)
4
3
2
1
a0: 16
a1: 24
a2: 25
a3: 20
a4: 10
a5: 4
a6: 1
Program ended with exit code: 0
```

// divide and conquer method
from $x_n \rightarrow$ constant

1 4 10 20 25 24 16
Program ended with exit code: 0

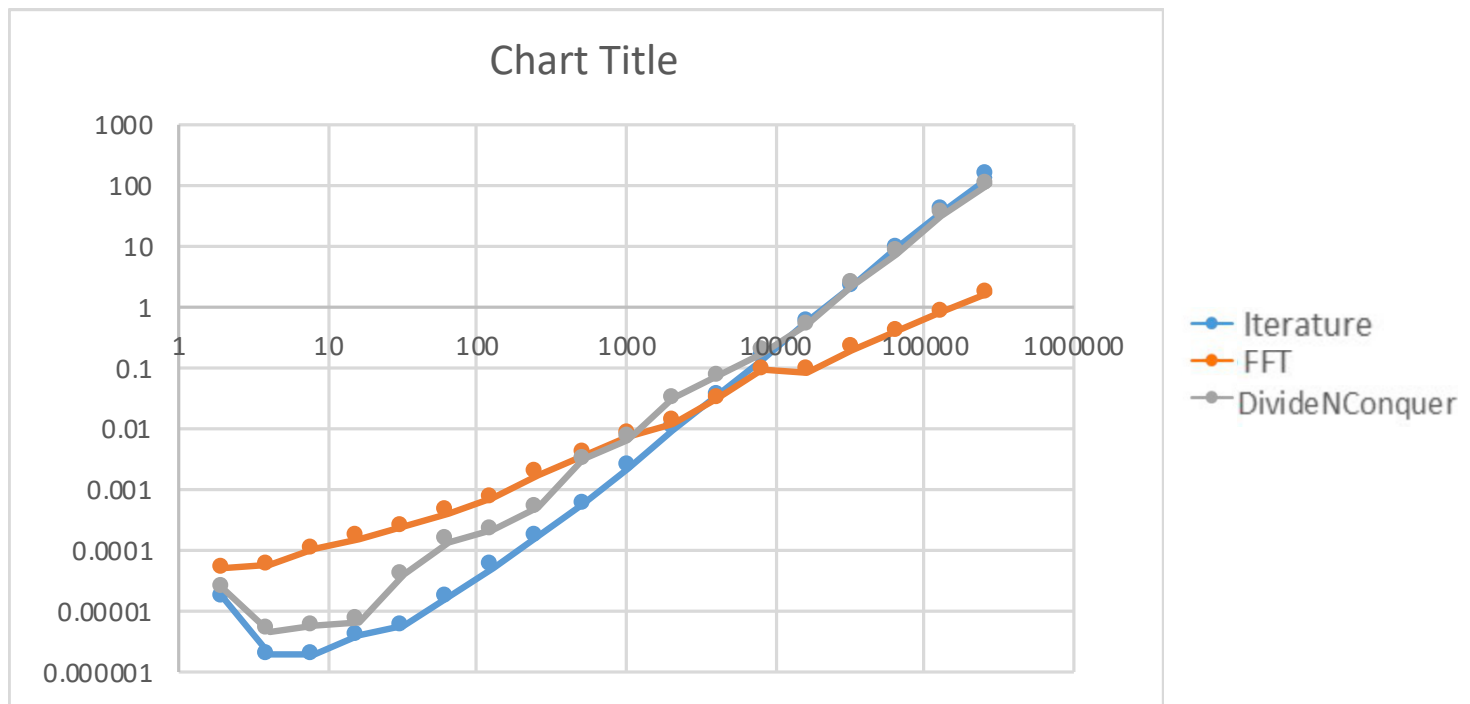
// FFT method

```
Enter the power of polynomial A:
3
Enter each coefficient of polynomial A: (from x^0 to x^n)
4
3
2
1
Enter the power of polynomial B:
3
Enter each coefficient of polynomial B: (from x^0 to x^n)
4
3
2
1
a0: 16.000000
a1: 24.000000
a2: 25.000000
a3: 20.000000
a4: 10.000000
a5: 4.000000
a6: 1.000000
Program ended with exit code: 0
```

The results are the same.

6.

| n | iterative (sec) | divide and conquer (sec) | FFT (sec) |
|--------|-----------------|--------------------------|-----------|
| 2 | 0.000016 | 0.000024 | 0.000051 |
| 4 | 0.000002 | 0.000005 | 0.000058 |
| 8 | 0.000002 | 0.000006 | 0.00011 |
| 16 | 0.000004 | 0.000007 | 0.000166 |
| 32 | 0.000006 | 0.000041 | 0.000247 |
| 64 | 0.000017 | 0.000141 | 0.000421 |
| 128 | 0.000055 | 0.000219 | 0.000746 |
| 256 | 0.000175 | 0.000517 | 0.001839 |
| 512 | 0.000595 | 0.003132 | 0.003755 |
| 1024 | 0.002367 | 0.007071 | 0.007828 |
| 2048 | 0.009903 | 0.031962 | 0.013254 |
| 4096 | 0.036968 | 0.07321 | 0.031336 |
| 8192 | 0.14393 | 0.187103 | 0.09269 |
| 16384 | 0.574414 | 0.530683 | 0.091832 |
| 32768 | 2.25881 | 2.353215 | 0.205122 |
| 65536 | 9.286633 | 7.879021 | 0.406042 |
| 131072 | 37.946583 | 33.402908 | 0.829161 |
| 262144 | 148.39357 | 110.21917 | 1.71501 |



7.

For a small number of coefficient, classical iterative method is faster than divide and conquer and FFT. However, FFT will be the fastest, and divide and conquer will be faster than iterative.

// classical iterative method

$c * n^2$

$$c * (16384)^2 = 0.574414 \implies c \approx 2.10 * 10^{-9}$$

$$c * (65536)^2 = 9.286633 \implies c \approx 2.30 * 10^{-9}$$

$$c * (131072)^2 = 37.946583 \implies c \approx 2.21 * 10^{-9}$$

$$c \approx 2.20 * 10^{-9}$$

$$\implies 2.20 * 10^{-9} * n^2$$

// divide and conquer method

$c * n^2$

$$c * (16384)^2 = 0.530683 \implies c \approx 1.98 * 10^{-9}$$

$$c * (65536)^2 = 9.286633 \implies c \approx 2.17 * 10^{-9}$$

$$c * (131072)^2 = 37.946583 \implies c \approx 2.21 * 10^{-9}$$

$$c \approx 2.12 * 10^{-9}$$

$$\implies 2.12 * 10^{-9} * n^2$$

// FFT method

$c * n(\log n)$

$$c * 16384(\log 16384) = 0.091832 \implies c \approx 4.00 * 10^{-7}$$

$$c * 32768(\log 32768) = 2.353215 \implies c \approx 4.17 * 10^{-7}$$

$$c * 65536(\log 65536) = 7.879021 \implies c \approx 3.87 * 10^{-7}$$

$$c \approx 4.01 * 10^{-7}$$

$$\implies 4.01 * 10^{-7} * n(\log n)$$

by the plot, the crossover point of iterative method and divide and conquer method is approximately at $n = 8192$

by the plot, the crossover point of iterative method and FFT method is approximately at $n = 4096$