(5535 HW 1

P(min{xi} < t) = Fmintris (t) = 1 - P(min{xi} > t) = 1 - P(X, > t, X, > t, ..., X > t)

(11111'=1) = 1-
$$\frac{\pi}{1}$$
P(x;>+) = 1- $\frac{\pi}{1}$ (1-+) (by (df above)

median distance = to.s, by median is the o.T quantile of its edf

$$\Rightarrow 1 - (1 - t_{0.5})^{N} = 0.5 \Rightarrow (1 - t_{0.5})^{N} = 0.5 \Rightarrow -t_{0.5} = \frac{1}{2} \frac{1}{N} - 1 \Rightarrow t_{0.5} = (1 - \frac{1}{2} \frac{1}{N})^{\frac{1}{p}} \quad p = 1 \Rightarrow \text{proved}$$

for p-dimension:
$$P(X \in S_{\Gamma}(\Gamma)) = \left(\frac{\pi^{\frac{p}{2}}}{\Gamma(\frac{p}{2}+1)}F^{p}\right)/\left(\frac{\pi^{\frac{p}{2}}}{\Gamma(\frac{p}{2}+1)}F^{p}\right) = F^{p} \Rightarrow P(||X|| \leq F) = F^{p}$$

P(min {||x|||} <+) = F min {||x|||} (r) = 1 - P (min {||x|||} >+) = 1 - T P(||x||| >+)

median distance =
$$\frac{1}{1}$$
 by median is the 0.5 quantile of its cdf $\frac{(4ip,N1)}{1}$ = $\frac{1}{1}$ =

$$\begin{array}{l} \forall \{x_1 = (x_1 + x_1) \ (x_1 + x_1 + x_1$$

=> only x= (2, -6) Trs the local maximum of fix)

 $f(x) = 8 \times 1 + 12 \times 1 + 2 \times 1^{2} - 2 \times 1^{2}$ $\nabla f(x) = \begin{pmatrix} 8 + 2 \times 1 \\ 12 - 4 \times 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \times_{1} = -4 , \times_{2} = 3 \Rightarrow \text{ stationary point is only } (-4,3)$ $|\nabla^{2}f(x)| = |\begin{pmatrix} 1 & 0 \\ 0 & -4 \end{pmatrix}| = -8 < 0 \Rightarrow \text{ only one stationary point } (-4,3) \text{ for } f(x),$ and it is neither a minimum not a maximum, but is a saddle point where $(x_{1}, x_{2})^{T} = (x_{1}^{T}, x_{2}^{T})^{T} = x_{1}^{T}A \times 1 + x_{2}^{T}B \times 1$ $\times T \begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix} \times = (x_{1}^{T}, x_{2}^{T}) \begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \end{pmatrix} = x_{1}^{T}A \times 1 + x_{2}^{T}B \times 1$ $\times A \cdot B \text{ are positive definite matrices} \Rightarrow x_{1}^{T}A \times 1 + x_{2}^{T}B \times 1 \Rightarrow x_{2}^{T}A \times 1 + x_{2}^{T}B \times 1 \Rightarrow x_{1}^{T}A \times 1 + x_{2}^{T}B \times 1 \Rightarrow x_{1}^{T}A \times 1 + x_{2}^{T}B \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{1}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{1}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{1}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{1}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{2}^{T}A \times 1 \Rightarrow x_{3}^{T}A \times 1 \Rightarrow x_{4}^{T}A \times 1 \Rightarrow x_{4}^{T}A$

= (A B) is also positive definite *

5. forward function:

$$Z_{1} = \frac{1}{1 + \exp(-w_{1}^{2}, \frac{1}{1 + \exp(-w_{1}^{2} - b_{1})} - b_{1})} = \frac{1}{1 + \exp(-(\frac{w_{1}^{2}}{1 + \exp(-(w_{1}^{2} + b_{1})} + b_{1})})}$$

backpropagation functions :

$$\frac{\partial L}{\partial z_1} = \gamma^* \frac{1}{z_1} + (1 - \gamma^*) \frac{-1}{1 - z_1} = \frac{\gamma^* - \gamma^* z_1 - z_1 + \gamma^* z_2}{z_1 (1 - z_1)} = \frac{\gamma^* - z_2}{z_1 (1 - z_2)}$$

$$\left(Q(x) = \frac{1}{1+6-x} \Rightarrow \frac{9x}{9x} = Q(x)(1-Q(x))\right)$$

$$\frac{\partial z_1}{\partial w_1} = z_1 (1-z_1) z_1$$
, $\frac{\partial z_1}{\partial b_1} = z_1 (1-z_1)$, $\frac{\partial z_1}{\partial z_1} = z_1 (1-z_1)_{W_1}$

$$\frac{\partial z_1}{\partial w} = Z_1(1-Z_1) \times , \quad \frac{\partial Z_1}{\partial b_1} = Z_1(1-Z_1)$$

$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial z_1} \frac{\partial Z_1}{\partial w_2} = \frac{y^* - Z_1}{Z_1(1-Z_2)} \cdot Z_2(1-Z_2) Z_1 = Z_1(y^* - Z_2)$$

$$\frac{\partial L(\theta)}{\partial w_1} = \frac{\lambda}{2} \left(\frac{\partial L(\theta)}{\partial w_2} - \frac{\lambda}{2} \frac{\partial L(\theta)}{\partial w_2} \right)$$

$$\frac{\partial L}{\partial h} = \frac{\partial L}{\partial z_1} \frac{\partial z_2}{\partial b_1} = \frac{y^* - z_1}{z_1(1-z_1)} \cdot z_1(1-z_1) = y^* - z_1$$

$$\frac{\partial L}{\partial w} = \frac{\partial L}{\partial z_1} \frac{\partial Z_1}{\partial Z_1} \frac{\partial Z_1}{\partial w} = \frac{\gamma^{*} - z_1}{z_1(1-Z_1)}, \quad w_1^{\mathsf{T}} \cdot z_1(1-Z_1) \cdot z_1(1-Z_1) \times = w_1^{\mathsf{T}} z_1 \times (\gamma^{*} - z_1)(1-Z_1)$$

$$\frac{\partial L}{\partial b_1} = \frac{\partial L}{\partial z_1} \frac{\partial z_1}{\partial z_1} \frac{\partial z_2}{\partial b_1} = \frac{\gamma^* - z_1}{z_1(1 - z_1)} \cdot W_1^T \cdot Z_2(1 - z_2) \cdot Z_1(1 - z_1) = W_1^T \cdot Z_1(\gamma^* - z_1)(1 - z_1)$$

$$W'_{1} = W_{1}^{1-1} - \alpha \frac{\partial \Gamma}{\partial w}$$

$$W'_{2} = W_{1}^{1-1} - \alpha \frac{\partial \Gamma}{\partial w}$$

$$W'_{3} = W_{1}^{1-1} - \alpha \frac{\partial \Gamma}{\partial w}$$

$$W'_{4} = W_{1}^{1-1} - \alpha \frac{\partial \Gamma}{\partial w}$$