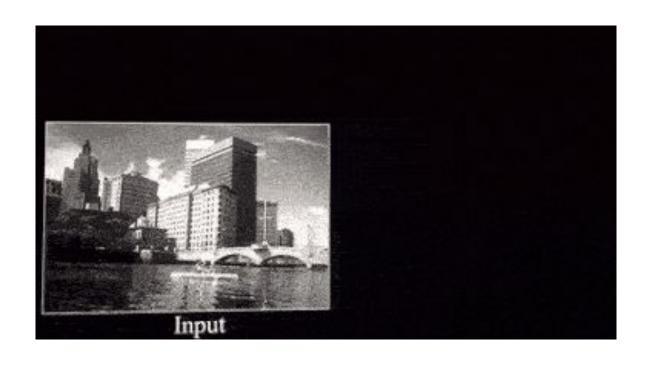
# Practical Deep Learning: A quick glance

Image classification and object detection

Alberto Castillo Lamas albertocl@ugr.es

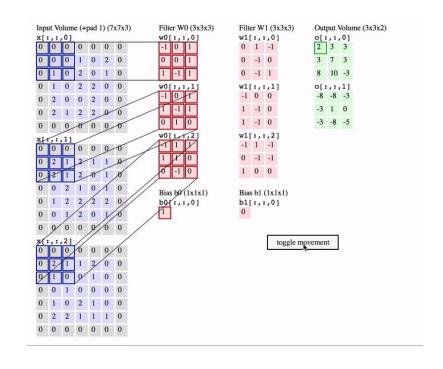
Convolution layers are the eyes of a CNN

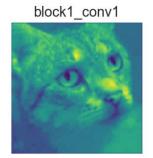


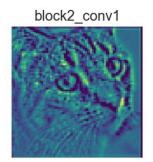
Eyes? How CNNs extract features

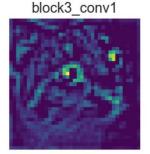
Each kernel extract some features

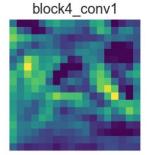
More depth -> more abstraction

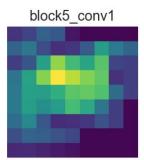








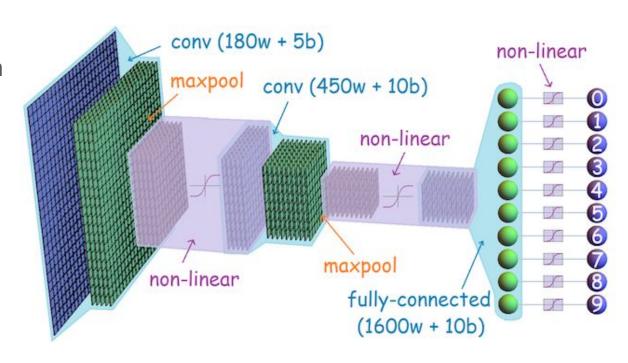




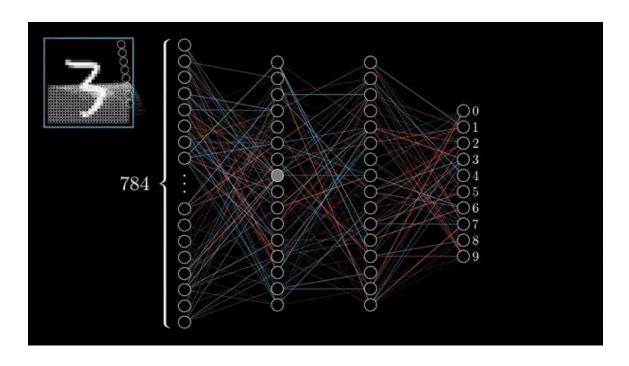
#### Architecture of CNNs:

- Feature extraction
- Dimension reduction

State-of-the-art models



Feature extraction is the input of the dense layer classification stage



Galaxy10 toy dataset

(astroNN web)

```
Galaxy10 dataset (21785 images)

— Class 0 (3461 images): Disk, Face-on, No Spiral

— Class 1 (6997 images): Smooth, Completely round

— Class 2 (6292 images): Smooth, in-between round

— Class 3 (394 images): Smooth, Cigar shaped

— Class 4 (1534 images): Disk, Edge-on, Rounded Bulge

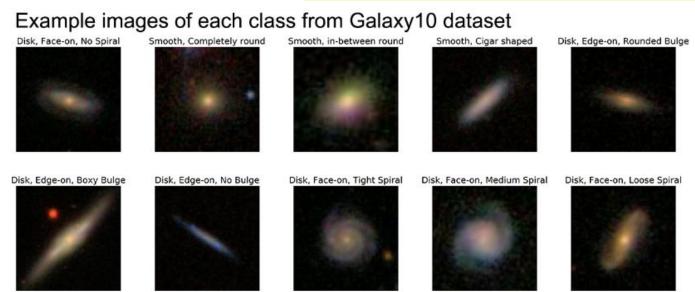
— Class 5 (17 images): Disk, Edge-on, Boxy Bulge

— Class 6 (589 images): Disk, Edge-on, No Bulge

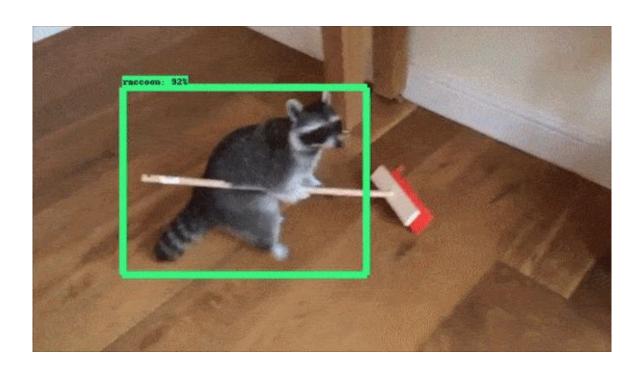
— Class 7 (1121 images): Disk, Face-on, Tight Spiral

— Class 8 (906 images): Disk, Face-on, Medium Spiral

— Class 9 (519 images): Disk, Face-on, Loose Spiral
```



Provide the object (class) and location (bounding box/region)

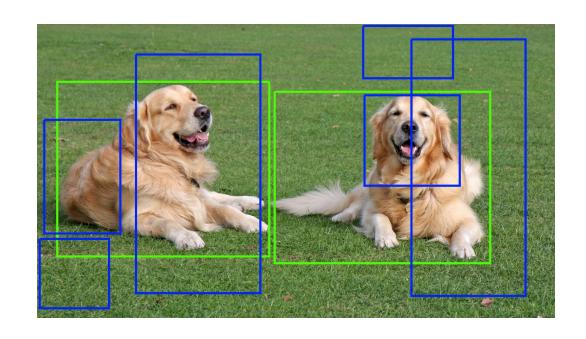


Object detection models:

Simultaneously learns

- Region proposal
- Object classification

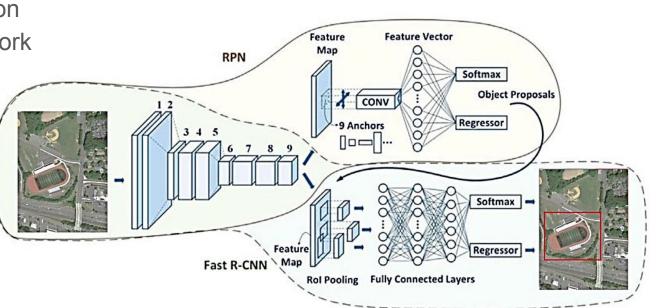
Output a set of candidates regions-class and confidence



Faster R-CNN architecture:

Region proposal based on a Region Proposal Network

- Slower
- More accurate
- Small objects

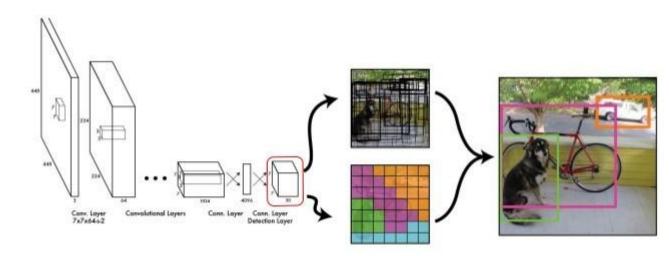


SSD or YOLO

Region proposal based on grid

- Faster
- Less accurate
- Common objects

#### YOLO: You Only Look Once

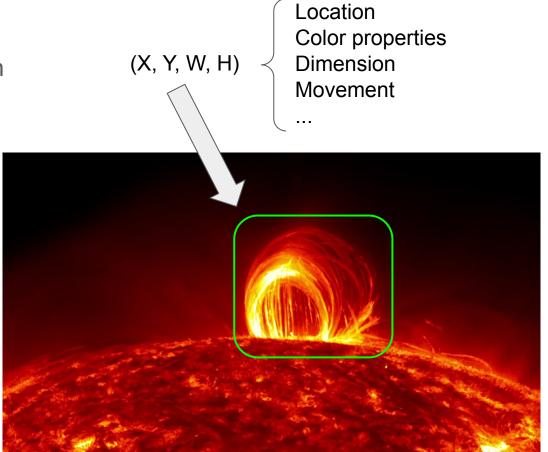


Detect fiery looping rain on the Sun

#### **Video**

A recurrent pattern in a structured signal can be learned

- RGB images
- Texture, color, shape



#### **Detection annotation**

- Image information
- Objects
  - Class
  - Region

```
<folder>train</folder>
<filename>FieryLoopingRainSun-187.jpg</filename>
<path>/home/alcasla/Escritorio/Astro/Solar-FieryLoop/train/FieryLoopingRainSun-187.jpg</path>
    <database>Unknown</database>
    <width>1280</width>
    <height>720</height>
    <depth>3</depth>
<segmented>0</segmented>
    <name>fiery loopw</name>
    <pose>Unspecified</pose>
    <truncated>0</truncated>
        <xmin>699</xmin>
        <ymin>376
        <xmax>820</xmax>
        <ymax>471</ymax>
```

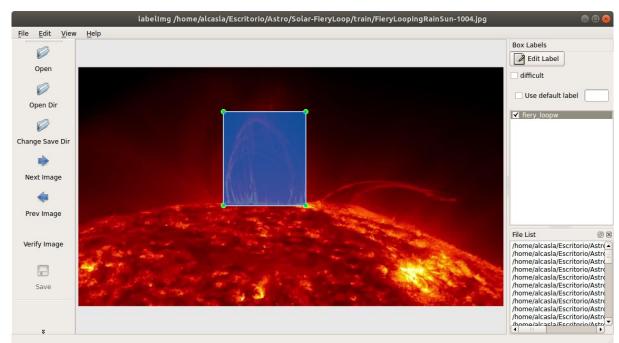
#### Labellmg

#### Repository

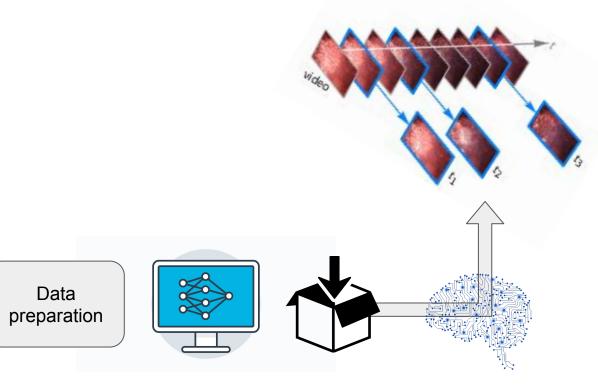
github.com/tzutalin/labellmg

#### Installer file

tzutalin.github.io/labellmg/







#### Object detection framework

<u>github.com/tensorflow/models/tree/master/research/object\_detection</u>

#### **Software configuration**

github.com/spsrc/somachine2020

Build conda environment using .yml file

#### Model Zoo

We provide a large collection of models that are trained on several datasets in the Model Zoo.

#### Guides

- · Configuring an object detection pipeline
- Preparing inputs
- · Defining your own model architecture
- · Bringing in your own dataset
- · Supported object detection evaluation protocols
- · TPU compatible detection pipelines
- Training and evaluation guide (CPU, GPU, or TPU)

#### Extras:

- · Exporting a trained model for inference
- · Exporting a trained model for TPU inference
- · Inference and evaluation on the Open Images dataset
- · Run an instance segmentation model
- Run the evaluation for the Open Images Challenge 2018/2019
- · Running object detection on mobile devices with TensorFlow Lite
- Context R-CNN documentation for data preparation, training, and export