

ELECTRICAL ENGINEERING · AUTOMATIC CONTROL EXPERT

13 Rue du Verger, Illkirch-Graffenstaden, France

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Summary _

Current Master's student in biomedical engineering, design and prototyping of parsimonious technologies for upper-limb muscle activation. With a background in electrical engineering, focusing on automatic control, this scholar is ready for innovation. Embracing challenges from advanced control to robotics and AI, and adept at learning new tech and languages as needed. I am seeking outstanding research programs and ground-breaking topics.

Education

Télécom Physique, Université de Strasbourg

Strasbourg, France

Master of Science (M.Sc.) in Biomedical Engineering - HealthTech program Sep. 2022 - Sep. 2022 - Sep. 2022

- Master's thesis on the design and control of a cost-efficient exoskeleton for upper-limb rehabilitation.
- Specialization in projects involving modeling and simulation of dynamic systems, robotics for surgical applications, computer vision, pose
 estimation and registration, robotic control, and optimization.
- · Training in areas involving biomechanical and physiological system modeling.
- · Acquisition of medical images: MRI, ultrasound, X-ray, CT-scan, nuclear, and optics.
- Advanced medical imaging processing using AI for segmentation, classification, and prediction.
- Insights into medical sector economics, intellectual property, and creativity management.

Universidade Federal da Bahia (UFBA)

Salvador-Bahia, Brazil

BACHELOR OF SCIENCE (B.Sc) IN ELECTRICAL ENGINEERING

Nov. 2016 - Jul. 2022

- Bachelor's thesis in Robust Trajectory Control of an Unmanned Aerial Vehicle.
- Training and experiences in projects involving design, implementation and prototyping of power systems, electronics systems, communication and automatic control systems.
- Specialization in automatic control applied to robotics, covering modeling and identifying dynamic systems, classical control techniques, optimal control, robust control, linear matrix inequality formulation, model predictive control, internal model control, and nonlinear control.
- Supplementary topics include active vibration control, introduction to path planning for mobile robotics, state feedback and estimation using Kalman Filter

Colégio Integrado Polivalente

Salvador-Bahia, Brazil

TECHNICAL COURSE OF ELECTROTECHNICS

Feb. 2022 - Jul. 2022

Feb. 2024 - Aug. 2024

Feb. 2023 - Jul. 2023

· Training in practical projects involving installation of residential power systems and operation of electronic systems.

Research & Project Experience

iCube Strasbourg & Politecnico di Milano.

Strasbourg, France & Milan, Italy

MECHATRONICS DESIGNER INTERN

· Main master's research project.

- Propose an actuation solution based on the use of springs.
- Design CAD model.
- Assembly the mechanical system with a cost-efficiency measurement system.
- Develop a control strategy in ROS2 to assist the patient's voluntary movement.

Robotics, Data Science and Healthcare Technologies (RDH) & Politecnico di Milano.

Strasbourg, France & Milan, Italy

ELECTRONIC DESIGNER INTERN

• Design and prototype a cost-efficient bracelet to measure biceps muscle contraction.

- Designing a printed circuit board, using ESP32 microcontroller and Force-Sensing Resistor (FSR).
- Publishing pre-processed and mapped data to the ROS2 environment via USB and WiFi.
- Developing a graphical user interface for manipulating the prototype.

Télécom Physique.

Illkirch-Graffenstaden, France

SOFTWARE DESIGNER Feb. 2023 - May. 2023

- Design and simulation of a virtual environment and collision model for the Pantograph, a 2-dimensional force-feedback device.
- Developed within the ROS2 Humble environment.
- Focused on robotics and sensory perception, particularly with regard to tactile feedback.

Robotics Laboratory (LAR) - UFBA

Salvador-Bahia, Brazil

CONTROL DESIGNER Sep. 2020 - Jul. 2022

- Research and develop a Robust LQR Trajectory Control for the AR.Drone 2.0.
- $\bullet \ \ \text{Comparing stability and performance between LQR and LQR control with polytope uncertainty-type robustness.}$

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DATA ANALYST AND PROCESS OPTIMIZER

Jul. 2021 - Jul. 2022

- Research and innovation in a private company in data analysis and optimization aiming to increase productivity.
- Fraud detection using machine learning algorithms.
- Development of a virtual assistant to act via voice command and Telegram.

Robotics Laboratory (LAR) - UFBA

Salvador-Bahia, Brazil

Feb. 2022 - Jul. 2022

- Research and prototype a cost-efficient balancing robot that stands on two wheels.
- Using discrete PID implemented into Arduino board, IMU and Kalman Filter.

Robotics Laboratory (LAR) - UFBA

Salvador-Bahia, Brazil

Jul. 2019 - Dec. 2019

ROBOTIC AND CONTROL DESIGNER

ROBOTIC AND CONTROL DESIGNER

• Research and prototype the mobile pioneer robot.

• The robot follows a tag by using one webcam and Raspberry Pi to pose estimate it.

Department of Chemical Engineering (DEQ) - UFBA

Salvador-Bahia, Brazil

FLUID MECHANICS EXPERIMENT DESIGNER

Feb. 2018 - Jul. 2019

• Modeling and prototyping of a water and compressed air rocket using a plastic bottle.

· Aiming to mathematically estimate the distance covered by an oblique launch based on the mass of water and air pressure.

Electric Wave Group - UFBA

Salvador-Bahia, Brazil

May. 2016 - Jul. 2016

ELECTRONIC DESIGNER May. 2017 - Dec. 2017

- · Design and prototype didactic experiments involving electricity, electronics and the laws of physics.
- Present these projects and teach low-income children and teenagers in their schools.

Senai Cimatec Salvador-Bahia, Brazil

Mechanical Designer

• Design and prototype a bench-top scissor-type lifting platform using a microwave motor.

Relevant Research Skills

- Autonomy and self-education to develop research projects.
- · Persistence and commitment.
- Capability to analyze and research state-of-the-art papers.
- Knowledge and experience in the following topics:

Systems and Robotics

- **Programming and Software**
- **Electrical Circuits**

- Windows, Linux and Office.ROS2, Rviz and CoppeliaSim
- Matlab and Simulink.
 ET_FX, VBA and SQL.
- Advanced Design System.Multisim and Protheus.

- Creo CAD and SolidWorks
- VsCode and QtCreator.
- Ltspice and MPlabX.

· C, C++ and Python.

- Slicer and Paraview.
- Arduino IDE and ESP32.

Teaching & Leadership Experience

TEACHING

2015-2022 Volunteer Teacher, High school Mathematics and Physics
 2018 Teaching Assistantship, Elementary School Mathematics.
 2018-2020 Teaching Assistantship, High school Mathematics and Physics
 2018-2020 Private Teaching Assistantship, Calculus, physics, linear algebra for higher education.

Estácio, Brazil

LEADERSHIP

2012-2014 **Volleyball Team Leader**, High School

2015-2019 **Music Group Leader**, Keyboardist and Guitarist at Maranata Baptist Church

2017-2019 **Leader of pre-university education**, at NGO GE

Since 2022 **Theological teaching leader**, at Maranata Baptist Church

Salvador, Brazil

Salvador, Brazil

Languages _

Fluent in English Fluent in Portuguese Advanced Spanish Intermediary French Beginner German

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Honors & Awards

2016	Finalist, Computer Overclocking Competition at Campus Party	São Paulo, Brazil
2022	Best Project of INTEGRATED LABORATORY VII, Balancing robot project requested for inclusion in the	UFBA. Brazil
	electrical engineering course syllabus.	UFDA, DIUZII
2022	Emphasis on Automatic Control, attending master's level classes during B.Sc	UFBA, Brazil
2022	Healthtech Scholarship Student , One of the 7 scholarship students.	Strasbourg, France

Additional Experiences _____

2022-2024 French Language Course , Université de Strasbourg	Strasbourg, France	
2017 Exchange in American Academy of English, English Language Course	San Francisco, U.S.A	
2017-2018 German Language course , PROFICI	UFBA, Brazil	
2013-2015 Spanish Language Course , Colégio Módulo	Salvador, Brazil	
2011-2013 English Language Course , Ebec Salvador, Bra		
2017 Vba and Macro Course in Excel , PRISMA - Student-Run Company from Chemical engineering	UFBA, Brazil	

Academic References

Maciej Bednarczyk Sherpa Mobile Robotics (SMR)

PROFESSOR AND INTERNSHIP SUPERVISOR DURING MASTER'S DEGREE

Robotics Architect • Work Adress: 11, rue ampère, Haguenau, 67500, France.

• Contact: mcbednarczyk@gmail.com

Bernard Bayle Université de Strasbourg

PROFESSOR AND MASTER'S SUPERVISOR.

• Work Adress: Pôle API, 300 Bd Sébastien Brant, 67400 Illkirch-Graffenstaden, France.

• Contact: bernard.bayle@unistra.fr

Antonio Lima Universidade Federal da Bahia

PROFESSOR DURING BACHELOR'S DEGREE IN ELECTRICAL ENGINEERING.

• Work Adress: R. Prof. Aristídes Novis, 2 - Federação, Salvador - BA, 40210-630, Brasil.

• Contact: acdcl@ufba.br

Full Professor

Full Professor