

# OpenGL, GPGPU, and a C++ 0x11 Framework

## Computer Graphics 1 - CS5400

Jesse Victors

**Abstract**—The abstract text goes here.

### I. INTRODUCTION

Prior to this class, C++ 0x11, OpenGL, CMake, and GLM were all relatively unknown to me.

### II. OPENGL

OpenGL

- A. *Vertex and Index Buffers*
- B. *Texture Buffers*
- C. *Lighting*
- D. *Camera*
- E. *Shaders*

### III. C++ 0x11

Here is the text of your introduction.

### IV. GLM

GLM is a library for doing common linear algebra and other mathematical functions in C++. Not only does GLM provide common matrix functions such as camera perspective, translations, rotations, and scaling operations, it is also based on the OpenGL Shading Language, (GLSL) which means that it integrates well with the shaders.

Libraries such as this are fairly common for game development. It's possible that a game studio could have their own libraries, custom-tailored to a particular environment, or the game framework itself could provide one. For example, Microsoft's XNA framework provides access to a Matrix struct that contains methods useful for many camera or model controlling operations.

Before I used GLM in my C++ framework, I had to implement data structures representing graphics objects such as points, triangles, and matrices. Not only did this take additional time and effort, but my implementation of the various related operations proved to host several difficult-to-catch bugs.

### V. FRAMEWORK

1) *Design Principles*: Software engineering principles was one of the main driving factors behind developing an organized framework for my OpenGL applications. In previous assignments, my code was fairly hacked together, although I tried to stay as organized as as neat as I could. I received excellent marks on my peer reviews, but I knew that the approach that I was taking wasn't going to be sufficient in the long run. It was pretty clear that I need to organize the applications into

various classes. Thus, when I began work on the final project, this was something that I strived to develop. I was driven by several principles:

- Focused responsibility. It seemed very unorganized to have a single class execute multiple high-level classes. For example, I wanted one class to build the model I was dealing with, another class to control how it rendered, and another class to contain all objects in scene that I was looking at. If I added a light to the world, everything about the light, including all data and methods, should be contained within its own class.
- Reduction of inter-dependencies. This is a very related to focused responsibilities, but the main distinction is that I don't have any particular variables in one class that are a particular value because of the values of some variables in another class. Such dependencies would make debugging and adjustments very difficult, and I felt was a bad idea overall. Instead, I opted to have all the world entities adjusted by a higher-level class in order to assemble the scene.

1) focused responsibility

2) *Origin*: Work on this final project started in late February. I knew what my scene wanted to look like, but the challenge was how to get there. I started with the code that I had written for my Sierpinski Mountain. That assignment involved what was essentially a vertex buffer, an index buffer, and a vertex-coloring buffer. I could also pitch, yaw, and roll the mountain using the keyboard's WSADQE keys, which gave the appearance of camera controls. That code was based off of the Rotating 3D Cube example in the book, which used some code from the authors as a basic framework. Using the software engineering principles, I wanted to cleanly separate the various elements of the Sierpinski Mountain assignment, and make them flexible enough to support the scene that I wanted for the final project.

In this initial framework, I had a World class, which held various Models. A Model was an abstract class because it contained pure virtual functions, which were defined in subclasses, such as a MandelModel and a GroundModel.

### VI. GIT

Git is a brilliant distributed revision control and source-code management system, and makes it exceptionally easy to branch, merge, and navigating changes. Git is also very amendable to distributed development of a large project. However, in this project I primarily used Git to assist me with developing my framework.

One of my main goals was focused responsibility and separation of dependencies.

## VII. DEVELOPMENT

I developed all of my graphics assignments in Linux Mint 14. I used the Sublime Text editor, and command-line.

## VIII. CMAKE

OpenGL

## IX. RESULTS

### A. Limitations

1) *Lack of support for hierarchical modeling*: My framework does not currently support hierarchical modeling, which is used for animating a large composite object by subdividing it into many smaller pieces. This process involves *boning* (sometimes known as *rigging*) where the object is modeled using a set of bones. Each bone has its own matrix for a three-dimensional transformation, such as position, scaling, and orientation, in addition to a reference to its parent and any children. Boning is useful because the programmer or animator does not have to worry about the positioning and orientation of every individual piece of the overall object, rather each piece knows where it should belong relative to its neighbors in the hierarchy. Thus, the whole model can be rotated or translated, and all the various components will be appropriately transformed.

Boning only produces a thin skeleton of the model, and is typically not sufficient for a full model of the object, and certainly not for animation. The next step in hierarchical modeling involves *skinning*, where a mesh is laid on top of the bones. A simple skin might be a rectangular prism or a cylinder, centered and oriented on the underlying bone. The skin is typically a mesh of vertices. If the model was of a human being, this mesh could be rounded, bulged in the middle, and laid over the humerus bone to model the upper arm.

In order to support the boning and skinning elements of hierarchical modeling, the framework would have to include a tree-like structure for boning. Each bone would need references to other bones, its transformation matrix, and its appropriate skin. Each skin would likely have its own texture, index, and texture buffers. This would require a significant refactoring of my framework, as the `RanderableModel` has its own data buffers and knows how to render itself. To support hierarchical modeling, the `RenderableObject` would need to keep track of a root bone (from which all other bones are descendants) and only the skin would know how to render itself. In addition, in order to support any type of animation, I'd have to be able to access the appropriate bones and pivot them (thus modeling joints) accordingly.

One of the problems with simplistic hierarchical modeling is that 1) there can be visible gaps in the joints between bones, caused by the skin of one bone visually separating from the skin of another bone; and 2) the skin is inflexible, resulting in a movement looking robotic. Both of these can be fixed by having the points of the skin link to one another, and possibly the points of neighboring skins. Then the skin mesh has to flex and move in accordance with the changes of the bones. This becomes very complex, as each point on the mesh has to translate itself relative to its neighboring

points. This could be performed using force fields in physics, or using energy functions. If done correctly, the result can be impressive and highly realistic animation. The downside is that the code becomes much more complex, and there's a significant increase of the computations required on the CPU, the GPU, and the data transfer through the system bus.

2) *Inefficiencies*: One of the disadvantages of my code is its inefficiencies, which become more obvious when the detail is turned up and the program is executed on slower hardware, such as a Nvidia GT 240m (released November 2009).

too many vertices for spiral, rendered even if offscreen

3) *Incompleteness*:

## X. CONCLUSION

Write your conclusion here.

L<sup>A</sup>T<sub>E</sub>X