# Notes on the Bi-Conjugate Gradient Method

#### Jesse Lu

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### 1 The algorithm

The algorithm attempts to solve Ax = b, where the matrix A is indefinite. The algorithm accepts as inputs

- 1. a method to multiply a vector by A,
- 2. a method to multiply a vector by  $A^T$  (note that this is the transpose of A, not its conjugate-transpose), and
- 3. the vector b.

The algorithm begins by initializing the following variables,

$$r_0 = b - Ax_0 \tag{1a}$$

$$\hat{r}_0 = b - A^T \hat{x}_0 \tag{1b}$$

$$p_0 = r_0 \tag{1c}$$

$$\hat{p}_0 = \hat{r}_0. \tag{1d}$$

(2a)

Then loop over the following for k = 0, 1, ...

$$\alpha_k = \hat{r}_k^T r_k / \hat{p}_k^T A p_k \tag{3a}$$

$$x_{k+1} = x_k + \alpha_k p_k \tag{3b}$$

$$\hat{x}_{k+1} = \hat{x}_k + \alpha_k \hat{p}_k \tag{3c}$$

$$r_{k+1} = r_k - \alpha_k A p_k \tag{3d}$$

$$\hat{r}_{k+1} = \hat{r}_k - \alpha_k A^T \hat{p}_k \tag{3e}$$

$$\beta_k = \hat{r}_{k+1}^T r_{k+1} / \hat{r}_k^T r_k \tag{3f}$$

$$p_{k+1} = r_{k+1} + \beta_k p_k \tag{3g}$$

$$\hat{p}_{k+1} = \hat{r}_{k+1} + \beta_k \hat{p}_k. \tag{3h}$$

# A Reference algorithm: From C. T. Kelley

Found in section 3.6.1 of [1]. Initialize as follows:

$$r = b - Ax, \hat{r} = r, \rho_0 = 1, \hat{p} = p = 0, k = 0.$$
 (4)

Repeat the following until a termination condition such as  $||r||_2 < \epsilon ||b||_2$  is satisfied,

$$k = k + 1 \tag{5a}$$

$$\rho_k = \hat{r}^T r, \beta = \rho_k / \rho_{k-1} \tag{5b}$$

$$p = r + \beta p, \hat{p} = \hat{r} + \beta \hat{p} \tag{5c}$$

$$v = Ap (5d)$$

$$\alpha = \rho_k / (\hat{p}^T v) \tag{5e}$$

$$x = x + \alpha p \tag{5f}$$

$$r = r - \alpha v, \hat{r} = \hat{r} - \alpha A^T \hat{p}. \tag{5g}$$

# B Reference algorithm: From Wikipedia

First, choose initial vectors  $x_0, x_0^*$ , and  $b^*$ . Initialize using

$$r_0 = b - Ax_0 \tag{6a}$$

$$r_0^* = b^* - x_0^* A \tag{6b}$$

$$p_0 = r_0 \tag{6c}$$

$$p_0^* = r_0^*. (6d)$$

Then loop over the following for k = 0, 1, ...

$$\alpha_k = r_k^* r_k / p_k^* A p_k \tag{7a}$$

$$x_{k+1} = x_k + \alpha_k p_k \tag{7b}$$

$$x_{k+1}^* = x_k^* + \overline{\alpha_k} p_k^* \tag{7c}$$

$$r_{k+1} = r_k - \alpha_k A p_k \tag{7d}$$

$$r_{k+1}^* = r_k^* - \overline{\alpha_k} p_k^* A \tag{7e}$$

$$\beta_k = r_{k+1}^* r_{k+1} / r_k^* r_k \tag{7f}$$

$$p_{k+1} = r_{k+1} + \beta_k p_k \tag{7g}$$

$$p_{k+1}^* = r_{k+1}^* + \overline{\beta_k} p_k^*. \tag{7h}$$

The residuals  $r_k$  and  $r_k^*$  satisfy

$$r_k = b - Ax_k \tag{8a}$$

$$r_k^* = b^* - x_k^* A, (8b)$$

where  $x_k$  and  $x_k^*$  are the approximate solutions to

$$Ax = b (9a)$$

$$x^*A = b^*. (9b)$$

### References

- [1] C. T. Kelley, "Iterative Methods for Linear and Nonlinear Equations", SIAM (1995).
- [2] http://en.wikipedia.org/wiki/Biconjugate\_gradient\_method