Engineering Project VI
Test Plan
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1. Wireless/Remote
    i. Check remote access to the server by launching the main from:
        i. TigerVNC
        ii. puTTY
        iii. SSH
    ii. R-Pi main script is launched. Print/Display the following details:
        i. Name of System
        ii. Date
        iii. IP Address
        iv. Error Handling Messages
2. R-Pi (Supervisor) CAN Test
    i. Since all the nodes will be listening to the R-Pi, send a command to instruct the node to write a message on the bus.
    ii. Each node will write onto the bus with a unique message
    iii. Wait for a reply from each node connected to the bus.
        i. Front
        ii. Rear
        iii. Steering
        iv. Accumulator
        v. BMS
        vi. Insulation Monitor
        vii. Motor Controller
    iv. When the R-Pi receives a message from a node, the following should be printed on the screen
        i. Node Name
        ii. CAN ID
        iii. Data/Message
    v. Print a Summary:
        i. Successful
        ii. Unsuccessful
            1. Node Name
            2. CAN ID
3. STM32 (Nodes) CAN Test
    i. All nodes must, by default, be able to handle a test command from the R-Pi.
    ii. All nodes must listen to the R-Pi, wait for their turn to write on the CAN bus, and let other nodes write onto the bus.
    iii. Manual Test
        i. Program one of the push buttons to write a test message to the CAN Bus.
        ii. R-Pi prints the received message from the node.

5. Hardware Verification - CAN Bus
    i. Connect an Oscilloscope to the CAN Bus
    ii. Check the message from each node for:
        i. Message ID
        ii. Data
        iii. Bit Rate

CAN Protocol Message Layout				
CAN ID (HEX)	Transmitter	Recipient	DLC	DATA
	R-pi	ALL	TBD	TBD
	Rear Node		TBD	TBD
	Front Node		TBD	TBD
	Steering		TBD	TBD
	Accumulator		TBD	TBD
	BMS		TBD	TBD
	Insulation Monitor		TBD	TBD
	Motor Controller		TBD	TBD