Measuring precise radial velocities and cross-correlation function line-profile variations using a Skew Normal distribution

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Abstract

Stellar activity is the main limitation to the detection of small-mass exoplanets using the radial-velocity (RV) technique. Stellar activity can be probed by measuring the cross-correlation function (CCF) shape variations as a function of time. Those variations are measured using the different moments of the CCF, therefore measuring with the best precision those moments is crucial to decorrelate exoplanet signals from spurious RV signals originating from stellar activity.

We propose here to measure those moments using a Skew Normal (SN) distribution, which compared to the Normal distribution generally used, naturally provides an extra parameter to model the CCF natural asymmetry induced by convective blueshift.

We analyze 5 stars with different activity levels and different signal-to-noise ratio levels. In each case, we compare the results obtained by fitting to the CCF respectively a Normal and a SN. We also estimate rigorous errors for the different moments of the CCF using a bootstrap analysis.

The correlations between the RVs and the CCF asymmetry or RVs and the CCF width is always stronger when using the parameters derived from the SN in the case of real observations. Therefore the CCF asymmetry and width derived using a SN are more sensitive to stellar activity, which allows to probe with a better precision stellar rotational periods, in addition to characterize more precisely stellar activity signals. The precision on the RVs, derived using the median of the fitted SN distributions are on average 10% smaller than the RV errors calculated on the mean of the Normal. In addition, the asymmetry parameter derived from the SN is on average 15% better than the one calculated on the common Bisector Inverse Slope Span (BIS SPAN). We strongly encourage the use of the SN distribution rather than the Normal distribution, because this allows to retrieve in one single fit the different moments of the CCF, because the derived moments probe better stellar activity signals and because the standard errors on the RV and the the asymmetry are smaller.

1 Introduction

When working with radial velocities, the main limitation to the detection of small-mass exoplanets is not anymore the precision of the instruments used, but the different noises induce by the stars we are observing (Dumusque et al. 2017). Indeed, stellar oscillations, granulation phenomena and stellar activity all induce RV signals (e.g. Saar and Donahue 1997; Queloz et al. 2001; Desort et al. 2007; Dumusque et al. 2011; Dumusque 2016) that are beyond the meter-per-second precision reached by the best high-resolution spectrographs. It is therefore mandatory to understand better stellar signals and to find ways to correct for them, if in the near future we want to detect or confirm an Earth-twin planet using the RV technique. This is even more true now that instrument like ESPRESSO (Pepe et al. 2014) and EXPRESS (Fischer et al. 2017) should have the stability to detect such signals. However, if solutions are not found to mitigate the impact of stellar activity, the detection or confirmation of potential Earth-twins will be extremely challenging.

Among the different stellar signals we are aware of, the one that is the most difficult to characterize and to correct for is the signal induced by stellar activity. Stellar activity is responsible for creating magnetic regions on the surface of stars, and those regions change locally the temperature and the convection, inducing spurious RV variations (e.g. Meunier et al. 2010; Dumusque et al. 2014). In theory, it should be easy to differentiate between the pure Doppler-shift induced by a planet, that will shift the entire stellar spectrum, and stellar activity that modifies the shape of spectral lines and by doing so create a spurious shift of the stellar spectrum (Saar and Donahue 1997; Hatzes 2002; Kurster et al. 2003; Lindegren and Dravins 2003; Desort et al. 2007; Lagrange et al. 2010; Meunier et al. 2010; Dumusque et al. 2014). However, on quiet GKM dwarfs, the main target for precise RV measurements, stellar activity induce signals of a few m s⁻¹. This corresponds physically to variations smaller than 1/100th of a pixel on the detector.

To be able to measure such tiny variations, we average the information of all the line in the spectrum by cross correlating the stellar spectrum with a synthetic (Baranne et al. 1996; Pepe et al. 2002) or an observed stellar template (Anglada-Escudé and Butler 2012).

The result of this operation gives us the cross-correlation function (CCF). To measure the Doppler-shift between different spectra, and therefore get the RV of a star as a function of time, we calculate the variations of the CCF barycenter. The barycenter is generally estimated by fitting a Normal distribution to the CCF, and taking its mean. Variation in line shape between different spectra, which indicate the presence of signals induced by stellar activity, is measured by analysing the different moments of the CCF. Generally, the width of the CCF is estimated using the FWHM of the fitted Normal distribution, and its asymmetry using the bisector inverse slope span (BIS SPAN, Queloz et al. 2001).

If a RV signal is induced by activity, generally a strong correlation will be observed between the RV and chromospheric activity indicators like $\log(R'_{HK})$ or H- α (e.g. Boisse et al. 2009; Dumusque et al. 2012; Robertson et al. 2014), but also between the RV and the FWHM of the CCF or its BIS SPAN (Queloz et al. 2001; Boisse et al. 2009; Queloz et al. 2009; Dumusque 2016). It is therefore common now, that when fitting for a planetray signal, in addition to a Keplerian, the model includes in addition linear dependancies with the $\log(R'_{HK})$, the FWHM and the BIS SPAN (e.g. Dumusque

et al. 2017; Feng et al. 2017). It is also common to add a Gaussian process to the model to account for the correlated noise induced by stellar activity. The hyperparameters of the Gaussian process are generally trained on the different activity indicators (e.g. Haywood et al. 2014; Rajpaul et al. 2015). It is therefore essential for mitigating stellar activity to obtain activity indicators that are the most correlated to the RVs but also for which we can obtain the best precision.

Several works have derived indicators that are more sensitive to line asymmetry than the BIS SPAN. In Boisse et al. (2011), the authors develop V_{span} a new indicator to derive the CCF asymmetry, that is more sensitive than the BIS SPAN at low signal-to-noise ratio (SNR). Figueira et al. (2013) studied the use of two new indicators, bi-Gauss and V_{asy} . The authors were able to show that when using bi-Gauss, the amplitude in asymmetry is 30% larger, therefore allowing the detection of smaller-amplitude correlations with radial-velocity variations. They also demonstrated that V_{asy} seems to be the best indicator of line asymmetry at high SNR, as its correlation with RV is more significant than any other asymmetry indictors.

In all the method described above, the RV and the FWHM is derived using a Normal distribution fitted to the CCF, and the asymmetry is estimated using another approach. In this paper we propose to use a Skew Normal (SN) distribution to derive at the same time the RV, the FWHM and the asymmetry of the CCF, as this function includes a skewness parameter (Azzalini 1985). In addition, we know that for solar-type stars and cooler dwarfs, the bisector of the CCF as a "C"-shape due to convective blueshift (e.g. Dravins et al. 1981; Gray 2009). Therefore, fitting the CCF using a model that naturally includes an asymmetry, like the SN distribution, should give more precise results.

The paper is organized as follow. In Sec. 2 and in Sec. 2.1 we introduce the SN distribution and describe its applicability for modeling the CCF, showing that the SN distribution is a better representation of observed CCF than a Normal distribution, and study how the SN parameters relate to the RV, FWHM and BIS SPAN of the CCF. In Sec. ?? we present a simple model to correct from stellar activity. In Sec. 4 we study the SN fit to the CCF using simulation coming from SOAP 2.0. In Sec. 5, we compare on real observations the sensitivity of the SN parameters to stellar activity with respect to other existing indicators. In Sec. 6 we derive error bars for the different CCF parameters, and finally we discuss our results and conclude in Sec. 7 and Sec. 8.

2 The Skew Normal distribution

The Skew Normal (SN) distribution is a class of probability distributions which includes the Normal distribution as a special case (Azzalini 1985). The SN distribution has, in addition to a location and a scale parameter analogous to the Normal distribution's mean and standard deviation, a third parameter which describes the asymmetry, or the skewness, of the distribution. Considering a random variable $Y \in \mathbb{R}$ (where \mathbb{R} is the real line) which follows a SN distribution with location parameter $\mathcal{E} \in \mathbb{R}$, scale parameter $\omega \in \mathbb{R}^+$ (i.e., the positive real line), and skewness parameter

 $\alpha \in \mathbb{R}$, its density at some value Y = y can be written as

$$SN(y;\xi,\omega,\alpha) = \frac{2}{\omega}\phi\left(\frac{y-\xi}{\omega}\right)\Phi\left(\frac{\alpha(y-\xi)}{\omega}\right),\tag{1}$$

where ϕ and Φ are respectively the density function and the distribution function of a *standard* Normal distribution¹ and $\alpha \in \mathbb{R}$ is the skewness parameter which quantifies the asymmetry of the SN. We then write $Y \sim SN(\xi, \omega^2, \alpha)$ to mean that the random variable Y follows the noted SN distribution. Examples of SN densities under different skewness parameter values and the same location and scale parameters ($\xi = 0$ and $\omega = 1$) are displayed in Fig. 1. A usual Normal distribution is the special case of the SN distribution when the skewness parameter, α , is equal to 0.2 For reasons related to the interpretation of the parameters in Equation (1) and computational issues

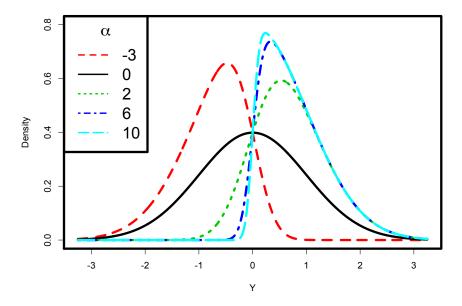


Figure 1: Density function of a random variable $Y \sim SN(\xi, \omega^2, \alpha)$ with location parameter $\xi = 0$, scale parameter $\omega = 1$ and different values of the skewness parameter α indicated by different colors and line types. Note that the solid black line has an $\alpha = 0$, making it a Normal distribution.

with estimating α near 0, a different parametrization is used, which is referred to as the *centered* parametrization (CP). We will be using the CP in this work, which includes a mean parameter μ , a variance parameter σ^2 and a skewness parameter γ . In order to define the CP, we need to express

 $^{^{1}\}mathrm{A}$ standard Normal distribution is a Normal distribution with a mean of 0 and a standard deviation of 1.

²This can be seen from Eq. (1). If $\alpha=0$ then $\Phi\left(\frac{\alpha(y-\xi)}{\omega}\right)=\Phi(0)$; this is the probability a standard Normal random variable is less than or equal to 0, which is 0.5. The 0.5 cancels with the 2 in the denominator and what remains is the usual Normal density, $\frac{1}{\omega}\phi\left(\frac{y-\xi}{\omega}\right)$

the CP parameters (μ, σ^2, γ) as a function of the one used in the Equation (1) with (ξ, ω^2, α) by

$$\mu = \xi + \omega \beta, \quad \sigma^2 = \omega^2 (1 - \beta^2), \quad \gamma = \frac{1}{2} (4 - \pi) \beta^3 \left(1 - \beta^2 \right)^{-3/2},$$
 (2)

where
$$\beta = \sqrt{\frac{2}{\pi}} \left(\frac{\alpha}{\sqrt{1 + \alpha^2}} \right)$$
.

By using Eq. (2), the new set of parameters (μ, σ^2, γ) provides a more clear interpretation of the behavior of the SN distribution. For the α values used in Fig. 1, the corresponding values of μ , σ^2 , γ are displayed in Table 1. In particular, μ and σ^2 are the actual mean and variance of the distribution (rather than simply a location and scale parameter) and γ becomes an index for evaluating the skewness of the SN.

Beyond the mean of the SN, we introduce a second location parameter that will be largely used in the analyses: the median. The median of the SN, and in general the median of an absolute continuous random variable, is defined as that value *m* such that

$$\int_{-\infty}^{m} SN(y;\xi,\omega,\alpha) = \frac{1}{2},\tag{3}$$

where $SN(y; \xi, \omega, \alpha)$ follows Eq. (1).³

α	μ	σ^2	γ	
-3	-0.757	0.427	-0.667	
0	0.000	1.000	0.000	
2	0.714	0.491	0.454	
6	0.787	0.381	0.891	
10	0.794	0.370	0.956	

Table 1: CP values, (μ, σ^2, γ) , corresponding to the α values from Fig. 1 (with location parameter $\xi = 0$ and scale parameter $\omega = 1$) using Eq. (2). Values are rounded to three decimal places.

Further details about the parametrization from Eq. (1) (called *Direct Parametrization* or DP), the CP, and general statistical properties of the SN are treated in rigorous mathematical and statistical viewpoints in the book by Azzalini and Capitanio (2014).

2.1 Fitting the Skew Normal distribution to the CCF

The SN density shape is used to model the CCF. In particular, using least-squares algorithm, we fit the following function:

$$f_{CCF}(y_i) = C - A \times SN(y_i; \mu, \sigma^2, \gamma), \quad i = 1, \dots, n$$
(4)

³We recall that when using a symmetric distribution such as the Normal distribution, the mean and the median are equivalent.

where C is an unknown offset fitting the continuum of the CCF, A is an unknown amplitude parameter and y_1, \ldots, y_n are the set of RV's considered for the CCF. Note that the CCF is expressed in flux as a function of the lag of the cross-correlation template, expressed in RV.

Since the CCF presents a natural asymmetry due the convective blueshift, the SN distribution should in principle better catch this aspect, together with other changes in asymmetry, respect the Normal fit. To initially check this assumption, we compared the CCF residuals after fitting a Normal and a SN distribution for 2 stars. The first star is Alpha Centauri b, whose CCFs have high signal-to-noise ratio (SNR). The second star is Corot-7, whose CCFs have low SNR. Fig. 2 shows that the SN seems to be a slightly better model to explain the shape of the CCF, in particular as the SNR decreases.

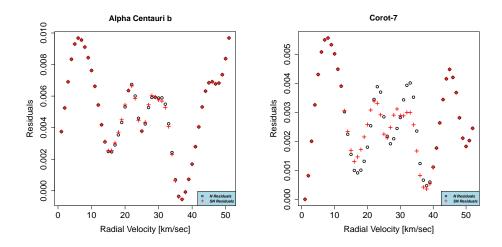


Figure 2: Comparison between the Normal (black circles) and the SN (red crosses) residuals using CCFs from the star Alpha Centauri b (left) and Corot-7 (right). When looking at the residuals corresponding to the tails of the CCF, the results derived by the two fits are comparable. However, when focusing on the center of the CCF, the SN fit leads to slightly better results for both the stars. Moreover, as the SNR decreases, the SN distribution shows smaller residuals respect the Normal ones.

In the following of the paper, we define RV as the mean of the Normal distribution. Concerning the fit of the CCF using the SN, we present at first 2 indicators that define the RV of the star: the mean of the SN, defined as RV mean SN and the median of the SN, defined as RV median SN (i.e. realling Eq.(3), m = RV median SN). We will discuss advantages and limits for both these choices in Section 5 and Section 6. For the width of the CCF, we use the FWHM of the Normal, which is $2\sqrt{(2 \ln 2)\sigma}$. The width of the SN, SN FWHM, is defined in the same way⁴. Being a Normal distribution symmetric, there is not such a parameter that evaluates the asymmetry of

⁴Note that SN FWHM does not correspond to the width of the SN distribution at half maximum like in the Normal case.

the distribution, so the BIS SPAN is used. The BIS SPAN will be compared to the asymmetric parameter γ of the SN, named SN GAMMA. To test the strength of the correlation between the RVs and the different indicators for stellar activity, we calculated the Pearson correlation coefficient, R. A p-value for the statistical test having null hypothesis H_0 : R = 0 (i.e., no correlation) is provided, along with a 95 % confidence interval for R.

3 Radial Velocity correction function for stellar activity

Exoplanets will only produce a variation in RV's induced by a pure doppler shift of stellar spectra. Stellar activity and in particular the presence of active regions on the photosphere of the star, on the contrary, does not produce a blueshift or redshift of the spectra, but creates spurious RV's signal by modifying the shape of the spectral lines. To track these changes in the shape of the line profile, the general approach consists in using the FWHM, the BIS SPAN or the indicators introduced by (Figueira et al. 2013), which provide an information on the average width and asymmetry of the CCF. A strong correlation between the estimated set of RV's and one or more of these parameters provides an indication that the RV's are affected by stellar activity signals.

To test the strength of the correlation between the estimated RV's and the different indicators used to evaluate stellar activity, we calculated the Pearson correlation coefficient, which in its general form is defined as:

$$R(x,y) = \frac{cov(x,y)}{\sigma(x), \sigma(y)},$$
(5)

where x and y are two quantitative variables, cov(x, y) indicates the covariance between x and y, and $\sigma(x)$ and $\sigma(y)$ represent their standard deviations. A p-value for the statistical test having null hypothesis $H_0: R = 0$ is provided, along with a 95 % confidence interval for R. Because of the spurious variations in RV's caused by active regions, a crucial step of the entire analysis is to correct the initially estimated RV's in order to retrieve a set of RV's containing ideally only the possibly pure doppler shift coming from the exoplanets. In order to reach this goal, we propose to consider a linear combination of the RV's having as covariates the amplitude parameter A, the BIS SPAN, the FWHM and the interaction between the BIS SPAN and the FWHM (or γ and SN FWHM and the interaction between γ and SN FWHM in the SN case), as shown in Eq. (6).

$$RV_{\text{stellar activity}} = \beta_0 + \beta_1 A + \beta_2 \gamma + \beta_3 \text{SN FWHM} + \beta_4 (\gamma \text{SN FWHM}) + \epsilon, \tag{6}$$

where β_0 is the intercept and ϵ is the vector of the errors with mean equal to 0 and covariance matrix equal to $\sigma^2 I$ (*I* defined as the identity matrix).

While the parameters γ (or BIS SPAN) and SN FWHM (or FWHM) have already been introduced, in Eq. (6) we propose also two include the amplitude parameter A and a variable that quantifies the interaction between γ (or BIS SPAN) and SN FWHM (or FWHM). The inclusion of the amplitude parameter A is justified by the expected behavior of the CCF in presence of active regions. Fig. 3 show that the presence for instance of a spot produces also changes on the amplitude of the CCF and not only on its asymmetry or width. The reasons for including in Eq. (6) a

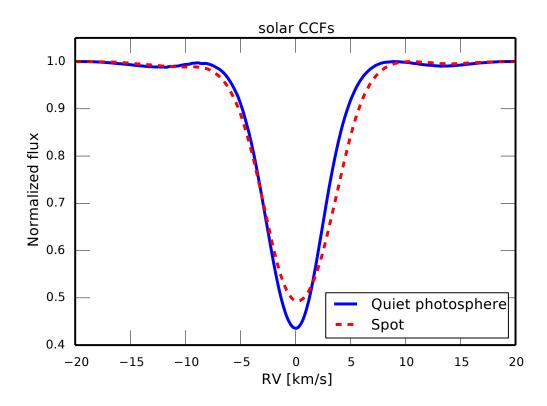


Figure 3: The presence of a spot on the photosphere of a star produces changes on the amplitude of the CCF and not only on its asymmetry or width.

variable that quantifies the interaction between γ (or BIS SPAN) and SN FWHM (or FWHM) will be clarified in the next Section and are related to a first attempt to disentangle spots from faculae.

In order to show the goodness of this correction, a statistical test on the parameters β_0 , β_1 , β_2 , β_3 and β_4 is presented, where the null hypothesis is H_0 : $\beta_i = 0$, for i = 0, ..., 4. The level for not rejecting the null hypothesis is fixed equal to 0.05. The coefficient of multiple correlation R^2 is introduced in order to explain how well this linear combination addresses the variability of the RV's of the star as caused by stellar activity.

4 Simulation Study

In order to evaluate the performance of the proposed SN approach for modeling the CCF, we begin by considering a simulation study using spectra generated from the Spot Oscillation And Planet (SOAP) 2.0 code (Dumusque et al. 2014).

[[Umberto: Add more information on SOAP, the way we retrieve the CCFs with SOAP, the characteristics of the CCF (i.e. how many points, ...) and the reasons why we need CCFs simulated with SOAP.]] [[Umberto: Specify characteristic of the star.]]

4.1 Faculae

[[**Umberto:** Specify characteristic of the faculae.]]

Fig. 4 shows the results obtained when a faculae is present on the photosphere of the star. It is possible to note that, although there is not a planet, the presence of the faculae leads to spurious variations in RVs for all the proposed indicators. SN mean RV seems to have the smallest spurious variations caused by the faculae.

Since in this case we know that the variations in RV are only caused by the faculae, the evaluation of the correlations between the set of RVs and the asymmetry parameters can provide relevant information to understand the cause of the variations observed in RVs. Fig. 5 shows the correlations obtained using as RV respectively RV mean SN, RV median SN and RV. The γ parameter shows a correlation with RV median SN equal to -0.944, which is stronger than the correlations between the other asymmetry indicators and their estimated RVs. The correlation between the width of the CCF and RV mean SN is the strongest one ($R^2 = 0.655$).

Since all the variations in RV's displayed in Fig. 4 are caused by the presence of a faculae on the photosphere of the star, we corrected the originally estimated set of RV's by using Eq. (6)). The results of the correction are displayed in Fig. 6 and the statistical tests on the parameters involved in Eq. (6)) are summarized in Table 2. It is straightforward noticing that the proposed correction almost completely addresses the issue, providing a new set of RV's where there are not anymore spurious variations caused by the presence of the faculae. In particular the R^2 is extremely high regardless the fit that has been use (Normal or SN). We note also that the parameter β_4 , associated with the interaction between γ and SN FWHM (or BIS SPAN and FWHM) is not statistically significant to explain spurious variations caused by a faculae.

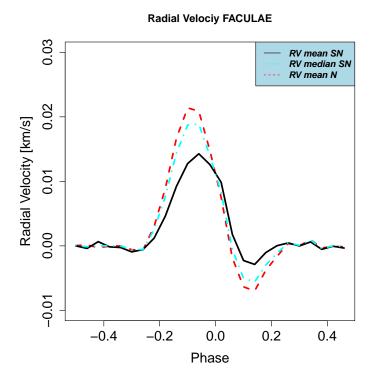


Figure 4: RV's changes as function of the orbital phase in the case in which a faculae is present on the photosphere of the star. SN mean RV seems to have the smallest spurious variations caused by the faculae.

Parameter RV		SN mean RV	SN median RV	
β_0	1.93e - 09	0.03563	0.03600	
β_1	3.75e - 05	0.00681	0.00684	
β_2	0.423	0.24128	0.24112	
β_3	0.281	0.00168	0.00169	
β_4 0.526		0.22108	0.21188	
R^2	R^2 0.9967		0.977	

Table 2: Evaluation of the linear combination used for correcting the RV's from spurious variations caused by a faculae, according to Eq. (6)).

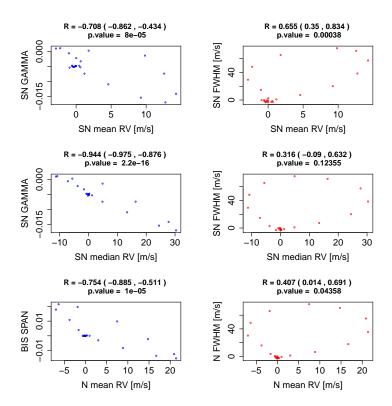


Figure 5: Evaluation of the correlation between the RVs and the asymmetry parameters when a faculae is present on the photosphere of the star. In this case both the shape and the width of the CCF changes as the faculae moves, producing statistically significative correlations between the RVs and respectively the asymmetry parameter and the width parameter.

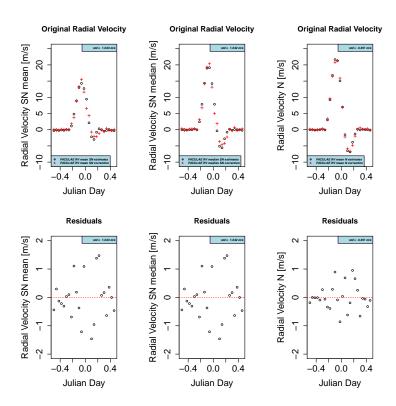


Figure 6: Set of spurious variations in RV's caused by a faculae using a Normal and a SN fit before and once corrected from stellar activity. The correction is done using Eq. (6)).

4.2 Spot

[[Umberto: Specify characteristic of the spot.]]

Fig. 7 shows the results obtained when a spot is present on the photosphere of the star. Similarly to the previous case, the presence of the spot leads to spurious variations in RVs for all the proposed indicators, but N mean RV seems to have the smallest ones. We note however that in this case all the three indicators are similarly effected by the spurious changes in RVs caused by the spot.

Fig. 8 shows the correlations between the asymmetry parameters and respectively RV mean SN, RV median SN and RV. The correlation between γ and RV median SN is equal to -0.89 while the correlation between γ and RV median SN is equal to -0.82. Both these correlations are stronger than the correlation between the BIS SPAN and RV ($R^2 = -0.77$). The correlations between the width of the CCF and the corresponding RVs are slightly stronger when fitting a SN rather than a Normal distribution, as shown in the left series of plots in Fig. 8. The results shows anyway a correlation close to 0, suggesting that the presence of a spot on the photosphere of star changes the shape of the CCF rather than its width.

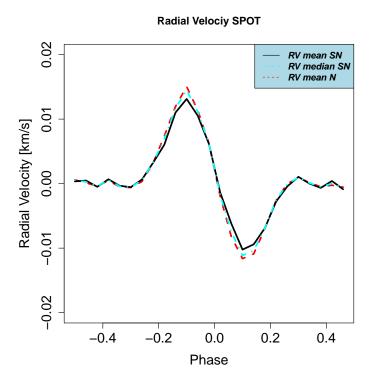


Figure 7: RV's changes as function of the orbital phase in the case in which a spot is present on the photosphere of the star. SN mean RV seems to have the smallest spurious variations caused by the faculae.

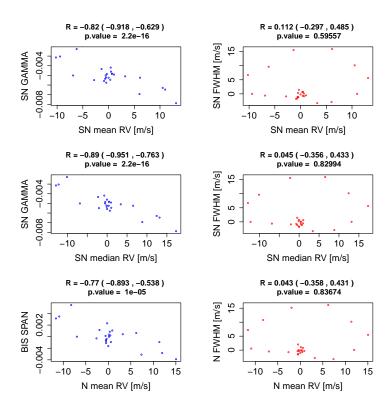


Figure 8: Evaluation of the correlation between the RVs and the asymmetry parameters when a spot is present on the photosphere of the star. In this case only the shape of the CCF changes as the spot moves, producing statistically significative correlations only between the RVs and the asymmetry parameter.

As before, we corrected the originally estimated set of RV's by using Eq. (6)). The results of the correction are displayed in Fig. 9 and the statistical tests on the parameters involved in Eq. (6)) are summarized in Table 3. Also in this case the proposed correction almost completely addresses the issue, providing a new set of RV's where there are not anymore spurious variations caused by the presence of the spot. The R^2 is extremely high regardless the fit that has been use (Normal or SN). The main difference respect to the previous case is that the parameter β_4 , associated with the interaction between γ and SN FWHM (or BIS SPAN and FWHM) is statistically significant to explain spurious variations caused by a spot. This information could be useful in the future for disentangle spots from facuale.

4.3 Spot and planet

The last presented simulation example consists in having not only spurious variations caused by the presence of a spot on the photosphere of the star but also artificially injecting a planet. The purpose

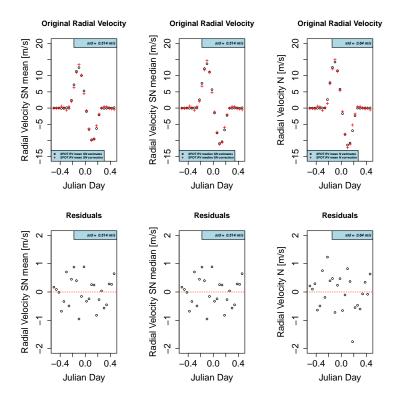


Figure 9: Set of spurious variations in RV's caused by a spot using a Normal and a SN fit before and once corrected from stellar activity. The correction is done using Eq. (6)).

Parameter	RV	SN mean RV	SN median RV	
eta_0	8.62e - 10	7.24e - 09	7.19e - 09	
β_1	0.000354	0.0639	0.0638	
eta_2	1.04e - 07	2.67e - 08	2.66e - 08	
β_3	2.26e - 06	1.72e - 07	1.72e - 07	
eta_4	1.11e - 07	2.85e - 08	2.87e - 08	
R^2	0.9897	0.9914	0.9929	

Table 3: Evaluation of the linear combination used for correcting the RV's from spurious variations caused by a spot, according to Eq. (6)).

of this example is to check if we are able to disentangle the two difference sources of variations in the set of RV's.

Fig. 10 shows the results obtained when a spot is present on the photosphere of the star and a planet is injected. The planet, having an amplitude of 10 m s⁻¹, produces a pure doppler shift on the CCF, without further changing its shape. In this case N mean RV seems to have the largest variations caused by the combined action of spot and planet.

Fig. 11 shows the correlations between γ and respectively RV mean SN and RV median SN and the correlation between BIS SPAN and RV. In this case the correlations are weaker than the ones derived when only a spot is present on the photosphere of the star. Anyway the γ parameter shows a correlation with the median SN of -0.433, which is stronger than what the correlation between the other asymmetry indicators and their corresponding RVs. The correlations between the width of the CCF and the corresponding RVs are comparable and, similarly to the previous case, close to 0.

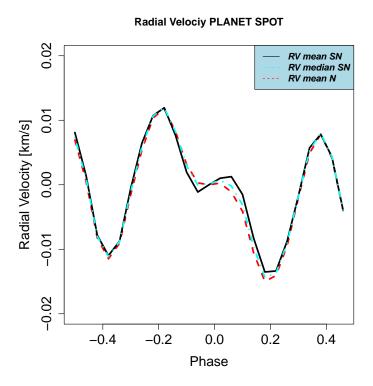


Figure 10: RV's changes as function of the orbital phase in the case in which a spot is present on the photosphere of the star and a planet is injected. N mean RV seems to have the largest variations caused by the combined action of spot and planet.

In order to correct the estimated set of RV's from spurious variations caused by the spot, we

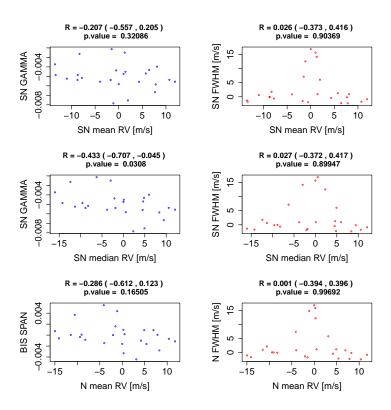


Figure 11: Evaluation of the correlation between the RVs and the asymmetry parameters when a spot is present on the photosphere of the star and a planet is injected. In this case only the shape of the CCF changes as the spot moves, producing statistically significative correlations only between the RVs and the asymmetry parameter. The correlations between the RVs and the width parameter of the CCF is weaker than the previous case that considers only the presence of a spot on the photosphere of the star.

Parameter	RV	SN mean RV	SN median RV	
eta_0	2.89e - 09	2.02e - 07	2.00e - 07	
β_1	0.00105	0.005216	0.005211	
eta_2	6.31e - 07	7.33e - 06	7.32e - 06	
β_3	2.34e - 05	0.000315	0.000315	
eta_4	6.73e - 07	7.78e - 06	7.82e - 06	
K	2e - 16	2e - 16	2e - 16	
P	2e - 16	2e - 16	2e - 16	
t_0	2e - 16	2e - 16	2e - 16	

Table 4: Evaluation of the linear combination used for correcting the RV's, according to Eq. (8)). All the parameters are statistically significants, in particular the amplitude parameter K that provides relevance about the possibly presence of the exoplanet. Note that since non linear least squares are required, the R^2 is not displayed.

need to generalize Eq. (6)), in order to consider also the possibly presence of an exoplanet. Hence, rather than just using Eq. (6)) we add the following function, which represents the pure doppler shift of the exoplanet under the assumption of circular orbit:

$$RV_{\text{exoplanet}} = K \sin\left(\frac{2\pi}{P}(t - t_0)\right),$$
 (7)

where the amplitude K, the orbital period P and the epoch at the periapsis t_0 are three unknown parameters that define the presence of the exoplanet. Overall, the variations in RV's of the star can be defined as

$$RV = RV_{\text{stellar activity}} + RV_{\text{exoplanet}}.$$
 (8)

We note that the p-value associated with the amplitude parameter K is particularly relevant for rejecting or not rejecting the assumption about the presence of an orbiting companion. Finally we note also that Eq. (7)) is non linear, meaning that the estimation of all the parameters involved in Equation (8) has to be done numerically. We used non linear least squares and the results are displayed in Fig.. 12. We can see how in this case we are able to disentangle the spurious variations in RV's caused by stellar activity from the pure doppler shift due to the planet. The statistical tests conducted on the parameters, whose results are summarized in Table 4, are significant. We note in particular that the p-value associate to the amplitude parameter K is 2e - 16. This result can be justify by the fact that the planet artificially injected has amplitude $K = 10 \,\mathrm{m \, s^{-1}}$.

In this Section we presented a first implementation of the SN fit to CCF, using the simulation environment SOAP. Before moving to the next Section, where the analyses on five real stars are presented, we need to provide further considerations. First of all, looking ad the analyses conducted with SOAP, it seems that the largest correlation between an asymmetry parameter and a set of RVs happens to be when respectively γ and RV median SN are used. This is a bit surprising, since as the shape of the CCF changes, we expect RV median SN to be more robust than RV mean SN.

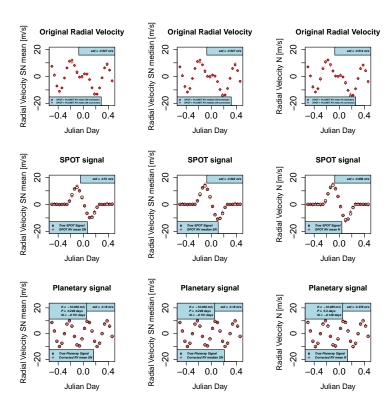


Figure 12: Set of variations in RV's estimated using a Normal and a SN fit before and once corrected from stellar activity. In this case there are spurious variations caused by the spot and pure doppler shift due to the planet. The correction is done using Eq. (8)).

[[Umberto: A possible justification of this ...]]. As second, when searching for stellar activity by deriving the correlation between the set of RVs and either an asymmetry parameter or the width of the CCF, the latter leads to weaker and hence less conclusive results if the active region is a spot. When stellar activity is dominated by faculae, both the shape and the width of the CCF changes as the faculae evolves on the photosphere of the star. The proposed function to correct for stellar activity addressed high level of spurious variations in RV's caused by active regions. In particular, respect to other common linear interpolation, we proposed to use as covariates also the amplitude parameter of the CCF and the interaction between γ and SN FWHM (or BIS SPAN and FWHM). Finally, the correlations involving the common indicators (i.e. RV, FWHM and BIS SPAN) are systematically weaker than the correlations obtained by fitting the SN to the CCF, suggesting that this distribution could be helpful when searching for active regions. We recall moreover that all the quantities needed for conducting the analyses of the CCF are directly available by just fitting the SN.

We remand the reader to Section 6 for the evaluation of the standard errors associated with the parameters estimated for all the three presented cases. This step will point out how RV median SN minimizes the uncertainties respect using both RV mean SN and RV, therefore suggesting its use in order to properly define the set of RVs of the star.

5 Real data application

In this Section we present the analyses conducted on Alpha Centauri b, comparing the result of fitting a CCF using the SN distribution defined in Section 2.1 with the approach based on the Normal distribution. Other four stars have been analyzed with the proposed method and details can be found in the Appendix A. For all the stars that have been considered in the present work, we selected those CCFs having SNR larger than 10.

A comparison with the results obtained by the classic approach is done, where the RVs of the star are estimated by retrieving the mean of the Normal distribution used to fit the CCF, along with the BIS SPAN or the other asymmetric parameters defined in Figueira et al. (2013). The latter parameters are calculated separately from the Normal fit that leads to the set of RVs of the star.

5.1 Alpha Centauri B

A total of 1808 CCFs measured in 2010 have been analysed from the star Alpha Centauri B. Several measurement in 2010 are contaminated by light from Alpha Centauri A. To remove contaminated spectra and thus CCFs, we performed the same selection as presented in Dumusque et al. (2012). Moreover, as noted in Dumusque et al. (2012) and Thompson et al. (2017), this dataset presents a strong stellar activity signal.

We begin the analyses by evaluating the correlation between γ and the BIS SPAN. In Fig. 13, we see that the relationship between γ and the BIS SPAN is linear, with a slope equal to 0.72 and a strong Pearson correlation coefficient of 0.954. This comparison is useful because γ is an adimensional parameter taking information about the asymmetry of the SN while the BIS SPAN,

beyond this, has got unit of measure of km s⁻¹. In other words, by using Fig. 13, it is possible to provide a physical meaning to γ .

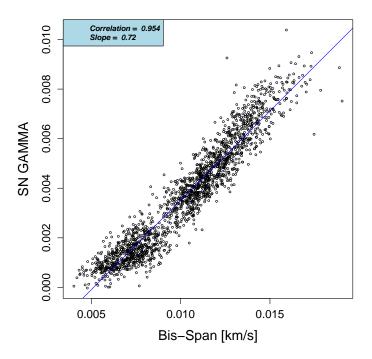
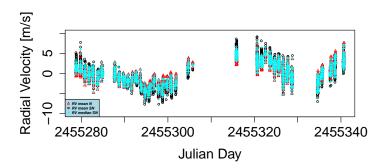


Figure 13: Correlation between γ and the BIS SPAN for Alpha Centauri B. Because γ is adimensional, retrieving the slope between γ and the BIS SPAN, which is expressed in km s⁻¹, allows us to provide physical meaning to γ .

Fig. 14 shows the comparison between the RVs retrieved using the SN shape and the ones obtained with the Normal shape. It is possible to appreciate the presence of a strong stellar activity signal, as expected (Dumusque et al. 2012; Thompson et al. 2017). When using RV mean SN, it is possible to observe more variations than the ones measured by the Normal fitting. This happens because the mean of the SN is more sensitive to stellar activity. In fact, because the SN includes an asymmetry parameter, RV mean SN gets more shifted in the direction of the asymmetry induced by stellar activity. On the other hand, when using RV median SN, smaller variations in RV are caused by changes in the asymmetry of the CCF, because this second location parameter is a more robust indicator than the mean. The bottom plot of Fig. 14 captures this aspect. Both indicators can be used to capture and summarise the different information available in the CCF, as will be shown in the remainder of this work.

Similar to Figueira et al. (2013), we compare the correlation between the different activity



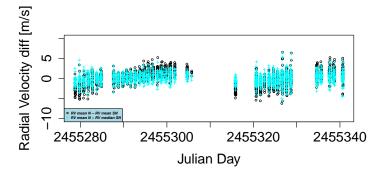


Figure 14: (top) RVs as function of Julian Day for Alpha Centauri b. The RVs are retrieved using the mean of the Normal (red triangles), RV mean SN (black circles), RV median SN (cyan crosses). (bottom) RV differences between Normal RV and RV mean SN (black circles) and between Normal RV and a RV median SN (cyan crosses).

Parameter	RV	SN mean RV	SN median RV	
β_0	2.22e - 16	2.22e - 16	2.22e - 16	
β_1	2.22e - 16	2.22e - 16	2.22e - 16	
β_2	2.22e - 16	2.22e - 16	2.22e - 16	
β_3	2.22e - 16	2.22e - 16	2.22e - 16	
β_4	2.22e - 16	2.22e - 16	2.22e - 16	
R^2	0.57	0.78	0.67	

Table 5: Evaluation of the linear combination used for correcting the RV's, according to Eq. (6)). All the parameters are useful in explaining variations in RV's of the star that can be caused by stellar activity. The evaluation of the R^2 shows that the proposed linear combination better explains variations in RV's due to stellar activity coming from the SN analysis that uses SN mean RV.

indicators and the RVs of the star in Fig. 15. The correlation between γ and RV mean SN and the correlation between γ and RV median SN are much stronger than the correlations calculated between the other asymmetry parameters and their corresponding RVs. In particular the correlation between γ and RV mean SN is almost twice the correlation between the other asymmetry parameters and their corresponding RVs.

Because the median is a more rubust index than the mean, the correlation between γ and RV median SN is not as large as the correlation between γ and RV mean SN, but it is nonetheless 1.5 times larger than the correlation between the other common asymmetry parameters and their corresponding RVs. In other words, changes in the asymmetry of the CCF are better captured when using the RV mean SN. The correlation between FWHM and the RVs, either by using RV mean SN or RV median SN, is as well stronger when fitting a SN distribution rather than a Normal. All the correlations are statistically different from 0. Recalling the analyses presented in Section 4, we could infer that Alpha Centauri b is dominated by faculae, because the correlations between the RVs and the width of the CCF are strong (in particular the correlation between RV mean SN and SN FWHM is 0.817).

Using Equation (6), we provide a new set of RV's corrected from stellar activity. The results are shown in Figure 16. We see that, once corrected for stellar activity, the residuals in the Normal and SN analysis are comparable. However, we note that when using SN mean RV, the correction is more important. In fact, the comparison of R^2 shows that the SN fit accounts for a higher percentage of variability caused by stellar activity (i.e. spurious variations in RV's).

Both the proposed indicators coming from the SN distribution have desirable and undesirable behaviors: RV mean SN better catches changes in the asymmetry of the CCF but the resulting set of RVs ends up being contaminated by those spurious shifts caused by stellar activity that have been shortly presented in Section 1. When using RV median SN, the final set of radial velocity is less affected by those spurious shifts caused by stellar activity, but at the same time this indicator is not able to catch as well as RV mean SN changes in the shape and in the width of the CCF. Anyway, both RV mean SN and RV median SN are useful to catch different aspects of the CCF

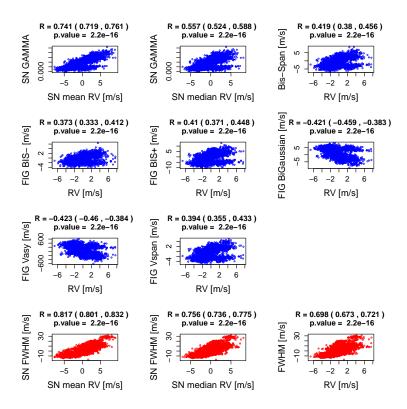


Figure 15: Correlation between the asymmetry parameters and the RVs for Alpha Centauri B. The last three plots show the correlation between the FWHM and the RVs for Alpha Centauri B using respectively the SN (RV mean SN and RV median SN) and the Normal fits. The correlations are always stronger when using parameters derived from the SN fit than the Normal one.

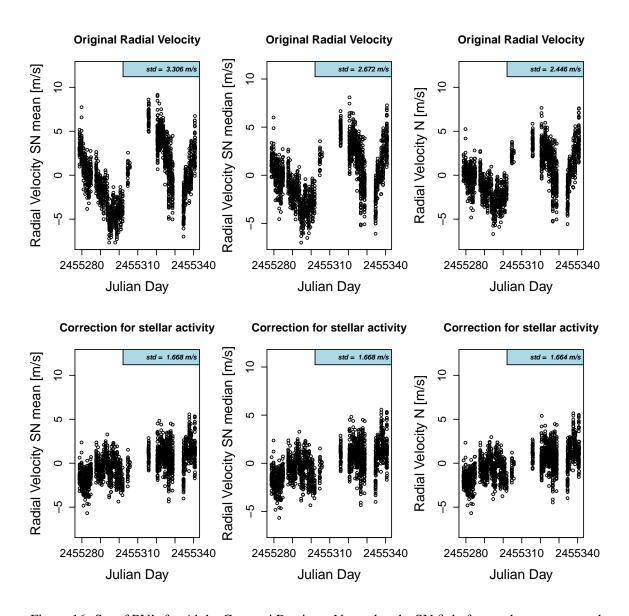


Figure 16: Set of RV's for Alpha Centauri B using a Normal and a SN fit before and once corrected from stellar activity. The correction is done using Equation (6). Once corrected for stellar activity, the residuals in the Normal and SN analyses are comparable.

and our suggestion is to use RV mean SN when interested in retrieving information about changes in the shape and/or the width of the CCF. In order to provide a set of RVs containing the smallest amount of spurious contamination imputable to stellar activity, our suggestion is to use instead RV median SN.

5.2 Doppler shift added to Alpha Centauri B

We also consider a real-data example using HARPS spectra from the star Alpha Centauri B with an imputed Doppler shift added...

[[Umberto: to be done]] [[Umberto: add here correction for stellar activity: table + plot to check if we get the planet]]

In the next Section we further motivate the reasons to define the RVs derived by the CCF by calculating RV median SN. In order to do that, we retrieve the standard errors associated with RV mean SN, RV median SN and RV.

6 Estimation of standard errors for the CCF parameters

In this section, we perform a bootstrap analysis to measure the standard errors associated to RV mean SN, RV median SN, RV, FWHM, SN FWHM, BIS SPAN and γ . Because a CCF is obtained from a cross-correlation, each point in a CCF is correlated with each other. Therefore, we cannot do a bootstrap analysis on perturbing independently each CCF point with a Gaussian distribution scaled to the error of each given point. To bypass this problem, we bootstrap a hundred times the stellar spectrum given the photon-noise error of each wavelength and calculate for each realization a new CCF. We then fit a Normal or a SN to each of these CCFs and then calculate the standard deviations of the distribution for the location parameters (RV, RV mean SN or RV median SN), the width parameters (FWHM or SN FWHM) and the parameters of asymmetry (BIS SPAN or γ). [[Referee: It is not clear what you are doing here. I can understand bootstrapping a time series: you shuffle all the values keeping the time stamps fixed. How do you bootstrap a stellar spectrum? Do you shuffle the intensity values keeping the wavelengths fixed? That would produce a mess. Do you just add different levels of random noise? But the spectra already have noise in them, they are real observations. You need to state more clearly here what you did.]]

6.1 Estimation of standard errors for the CCF parameters for the simulation study

We start by calculating the standard errors of the parameters retrieved in Section 4, where with SOAP we produced CCFs contaminated by a faculae or a spot. In the third and final case we considered, beyond the spot, a planetary signal that produces pure doppler shifts i the CCFs.

Fig. 17 shows the results of the bootstrap analysis performed when a faculae is present on the photosphere of the star. The series of three plots in the top of Fig. 17 show the different errors for the RVs, defined as RV (red triangles), RV mean SN (black circles) or RV median SN (cyan crosses), the width and the asymmetry of the CCFs. In the three plots in the bottomof Fig. 17

we show the ratio between the parameters derived from the bootstrap analysis fitting the SN and the parameters derived from the bootstrap analysis fitting the Normal distribution. Concerning the standard errors related to the RVs, the ratio between the RV error measured by the bootstrap using the SN and Normal fitting is 1.5 when using RV mean SN and 0.9 when using RV median SN. By using RV median SN we get standard errors 10% smaller than using the Normal fit and its corresponding mean. Regarding the errors in width of the CCF, we see that the bootstrap analysis for the Normal and the SN are comparable. Therefore, the precision in the width of the CCF is the comparable if we fit a Normal or a SN to the CCF. Finally, for the errors in evaluating the asymmetry of the CCF, we see that, when fitting the SN to the CCF, the asymmetry errors are 20% smaller. Therefore, the SN fit gives a better precision in CCF asymmetry than what can be reached using BIS SPAN.

Fig. 18 shows the results of the bootstrap analysis performed when a spot is present on the photosphere of the star. The series of plots follows the specifications outlined for the previous case. Concerning the standard errors related to the RVs, the ratio between the RV error measured by the bootstrap using the SN and Normal fitting is 1.4 when using RV mean SN and 0.9 when using RV median SN. Regarding the errors in width of the CCF, we see that the bootstrap analysis for the Normal and the SN are comparable. Therefore, the precision in the width of the CCF is the comparable if we fit a Normal or a SN to the CCF. Finally, for the errors in evaluating the asymmetry of the CCF, we see that, when fitting the SN to the CCF, the asymmetry errors are 20% smaller.

Fig. 19 shows the results of the bootstrap analysis performed when a spot is present on the photosphere of the star. The series of plots follows the specifications outlined for the previous two cases. The conclusions are comparable to the case in which only a spot is present on the photosphere of the star. The ratio between the RV error measured by the bootstrap using the SN and Normal fitting is 1.4 when using RV mean SN and 0.9 when using RV median SN. The errors in width of the CCF are comparable and the errors in evaluating the asymmetry of the CCF are 20% smaller when using the asymmetry parameter γ of the SN.

6.2 Estimation of standard errors for the CCF parameters for real stars

In the top plots of Fig. 20 we show the different errors for the RVs, either defined as RV (red triangles), RV mean SN (black circles) or RV median SN (cyan crosses), the width and the asymmetry of the CCFs for three star, HD215152, HD192310 and Corot-7, that are all at different SNR levels. The parameter SN50 corresponds to the SNR in order 50, which defines a wavelength of 550 nm. In the bottom plots, we show the ratio between the parameters derived from the bootstrap analysis fitting the SN and the parameters derived from the bootstrap analysis fitting the Normal distribution. We first see that the errors on the CCF parameters only depends on the SNR and do not depend on the spectral type. This is true if the spectral type are not too different though, like here where we show the results for G and K dwarfs.

Concerning the standard errors related to the RVs, the ratio between the RV error measured by the bootstrap using the SN and Normal fitting is 1.6 when using RV mean SN and 0.9 when

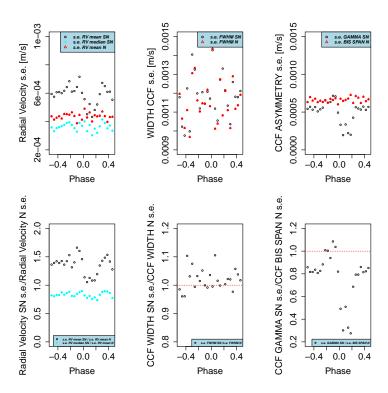


Figure 17: Faculae Case. Comparison between the standard errors using the bootstrap analysis for the RVs, the FWHM and the asymmetry parameter. When using RV mean SN (black circles), the standard errors are in average 50% larger than the standard errors retrieved fitting a Normal (red triangles). However, if using RV median SN (cyan crosses), the standard errors are in average 10% smaller than the standard errors coming from the Normal fit. To use as asymmetry parameter γ of the SN leads to standard errors in average 20% smaller than the standard errors related to the BIS SPAN. [[Umberto: explain what happens for those CCF 15 to 19 where s.e. decrease.]] Note that for the asymmetry, the error in BIS SPAN is in km s⁻¹. To be able to compare the errors in γ and BIS SPAN, we multiplied the error in γ by the slope of the correlation between γ and BIS SPAN.

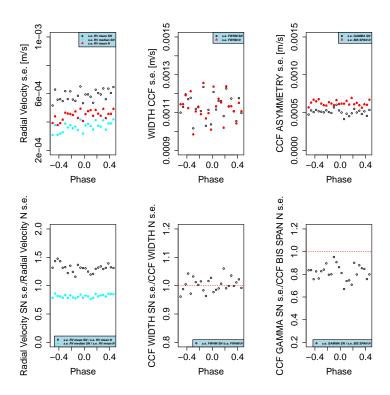


Figure 18: Spot case. Comparison between the standard errors using the bootstrap analysis for the RVs, the FWHM and the asymmetry parameter. When using RV mean SN (black circles), the standard errors are in average 40% larger than the standard errors retrieved fitting a Normal (red triangles). However, if using RV median SN (cyan crosses), the standard errors are in average 10% smaller than the standard errors coming from the Normal fit. To use as asymmetry parameter γ of the SN leads to standard errors in average 20% smaller than the standard errors related to the BIS SPAN. Note that for the asymmetry, the error in BIS SPAN is in km s⁻¹. To be able to compare the errors in γ and BIS SPAN, we multiplied the error in γ by the slope of the correlation between γ and BIS SPAN.

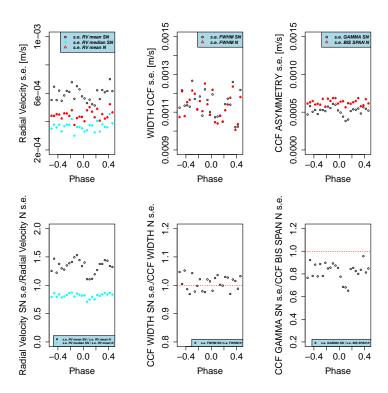


Figure 19: Spot and Planet case. Comparison between the standard errors using the bootstrap analysis for the RVs, the FWHM and the asymmetry parameter. When using RV mean SN (black circles), the standard errors are in average 50% larger than the standard errors retrieved fitting a Normal (red triangles). However, if using RV median SN (cyan crosses), the standard errors are in average 10% smaller than the standard errors coming from the Normal fit. To use as asymmetry parameter γ of the SN leads to standard errors in average 20% smaller than the standard errors related to the BIS SPAN. Note that for the asymmetry, the error in BIS SPAN is in km s⁻¹. To be able to compare the errors in γ and BIS SPAN, we multiplied the error in γ by the slope of the correlation between γ and BIS SPAN.

using RV median SN. In other words, by using RV median SN as parameter that defines the radial velocity of the star given a CCF, we get standard errors 10% smaller than using the Normal fit and its corresponding mean. This result is consistent with what we observed with the simulation from SOAP presented in Section 4.

Regarding the errors in width of the CCF, we see that the bootstrap analysis for the Normal and the SN are comparable. Therefore, the precision in the width of the CCF is the comparable if we fit a Normal or a SN to the CCF.

Finally, for the errors in evaluating the asymmetry of the CCF, we see that, when fitting the SN to the CCF, the asymmetry errors are 15% smaller. Therefore, the SN fit gives a better precision in CCF asymmetry than what can be reached using BIS SPAN. We recall moreover that, using the SN, all parameters are automatically retrieved in 1 single step, while in the common approach the RV and the BIS SPAN are calculated separately.

7 Discussion

An analysis of the CCF residuals after fitting a Normal or SN distribution shows that the SN is a slightly better model to explain the shape of the CCF. This comes from the fact that CCFs present a natural asymmetry due the convective blueshift.

We tested at first our assumptions by using simulated CCFs retrieved using the software SOAP 2.0. We then compared for five real stars the difference between the RVs (defined as mean of a Normal, mean of the SN or median of the SN), FWHM and asymmetry (BIS SPAN in the Normal case and γ in the SN case). The γ parameter is linearly dependent on the BIS SPAN, with always a strong correlation coefficient. The slope of this linear correlation changes depending on the studied star. This is probably because the spectral type is different, therefore the effects from stellar activity are different.

When using as parameter for the RV the mean of the SN, the standard errors are in average 60% larger than the standard errors retrieved fitting a Normal. However, once the RV is defined as the median of the SN (cyan crosses), the standard errors are in average 10% smaller than the standard errors coming from the Normal fit. When looking at the correlation between the asymmetry and width parameters of the CCF (FWHM and BIS SPAN or the alternative indicators in Figueira et al. (2013) in the Normal case, and SN FWHM and γ in the SN case) with respect to the RVs (RVs in the Normal case or SN RVs in the SN case), we observe that the correlations are always stronger for the parameters of the SN. Therefore, the SN parameters are more sensitive to activity. In the case of Tau Ceti, which is at very low activity level, we find a significant correlation of 0.322 between γ and RV mean SN, while for all the other asymmetric parameterization, BIS SPAN or the alternative indicators in Figueira et al. (2013), the correlations are weaker with a maximum of 0.225.

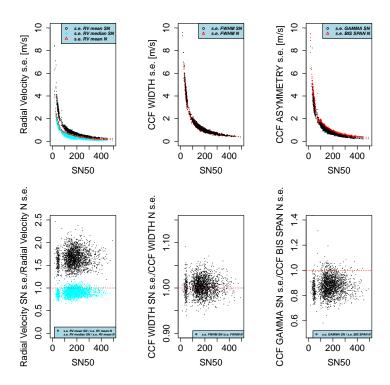


Figure 20: Comparison between the standard errors using the bootstrap analysis for the RVs, the FWHM and the asymmetry parameter. When using RV mean SN (black circles), the standard errors are in average 60% larger than the standard errors retrieved fitting a Normal (red triangles). However, if using RV median SN (cyan crosses), the standard errors are in average 10% smaller than the standard errors coming from the Normal fit. To use as asymmetry parameter γ of the SN leads to standard errors in average 15% smaller than the standard errors related to the BIS SPAN. Note that for the asymmetry, the error in BIS SPAN is in km s⁻¹. To be able to compare the errors in γ and BIS SPAN, we multiplied the error in γ by the slope of the correlation between γ and BIS SPAN.

8 Conclusion

In this paper we introduced a novel approach based on the Skew Normal (SN) distribution for deriving RVs and shape variations in the CCF of stars. When searching for small-mass exoplanets using the RV technique, it is essential to understand the shape variation of the CCF, which is a proxy for stellar activity effects. The standard approach consist at first to adjust a Normal distribution to the CCF to get the RV and FWHM, defined as the mean and the FWHM of the Normal distribution, and then to measure the asymmetry by calculating BIS SPAN. FWHM and BIS SPAN give us information on the line shape that are used to probe stellar activity signals.

In this paper we propose to conduct the analysis fitting a SN distribution to the CCF. Since the CCF presents a natural asymmetry due the convective blueshift, the SN distribution can better catch these aspects respect the Normal fit. On top of that, by using the SN distribution to fit CCFs, we can measure simultaneously the RV of the star, the width and the asymmetry of the CCF.

Starting from the simulation environment SOAP and then moving to real stars, we showed that using the SN distribution to fit CCFs brings a significant improvement in probing stellar activity. While for the Normal distribution mean and median are equivalent, using the SN fit different location parameters can be tested. While the median of the SN is more robust respect variations in the shape of the CCF, the mean of the SN is more sensible to changes in the asymmetry of the CCF. We suggest to use as parameter that defines the RV of the star the median of the SN, since the standard errors related to this parameter are 10% smaller than the standard errors retrieved using the Normal distribution. For evaluating changes in the asymmetry of the CCF, we suggest to use the mean of the SN. The correlations between RV mean SN and SN FWHM, and RV mean SN and γ (the asymmetry parameter of the SN) are much stronger than the correlations between the equivalent parameters derived using a Normal fit (RV, FWHM and BIS SPAN or the asymmetric parameters described in Figueira et al. (2013)). The precision on the asymmetry measured by γ is greater than the one on BIS SPAN by \sim 15%. Therefore when searching for rotational periods in the data, or applying Gaussian Processes to account for stellar activity signals, the SN parameters should be used.

Finally, we also encourage the use of bootstrapping to estimate more realistic errors on the different parameters of the Normal or SN fitted to the CCF, mainly in the low SNR regime where a gain of 50% can be reached. This takes significantly more time, but note that 100 realization are enough to get a good estimation of errors.

9 Acknowledgements

We are grateful to all technical and scientific collaborators of the HARPS Consortium, ESO Headquarters and ESO La Silla who have contributed with their extraordinary passion and valuable work to the success of the HARPS project. XD is grateful to the Society in Science—The Branco Weiss Fellowship for its financial support.

Star	# CCFs	R(SN γ, Bis-Span)	slope(SN γ, Bis-Span)	R(SN γ, RV mean SN)	R(Bis-Span, RV)	R(FIG BiGaussian, RV)	R(SN FWHM, RV mean SN)	R(FWHM, RV)
HD192310	1577	0.888	0.786	0.669(0.64; 0.695)	0.329(0.285; 0.373)	-0.333(-0.376; -0.289)	0.666(0.637; 0.692)	0.476(0.43670.514)
HD10700	7928	0.78	0.604	0.322(0.302; 0.342)	-0.073(-0.095; -0.0051)	0.127(0.105; 0.148)	0.421(0.403; 0.439)	0.529(0.513; 0.545)
HD215152	273	0.763	0.794	0.571(0.485; 0.646)	-0.067(-0.184; 0.052)	0.269(0.155; 0.376)	0.210(0.094; 0.321)	-0.138(-0.253; -0.020)
Corot 7	173	0.814	0.607	0.561(0.450; 0.656)	0.092(-0.058; 0.238)	-0.335(-0.228; -0.082)	-0.709(0.626; 0.776)	0.595(0.489; 0.683)

Table 6: Subset of notable correlations between the asymmetry parameter (and the FWHM) and the RVs for four stars: HD192310, HD10700, HD215152 and Corot 7.

A Appendix

In this Appendix we present the analyses conducted on other 4 stars: HD192310, HD10700, HD215152 and finally Corot-7.

[[**Umberto:** Add further information about the stars here presented.]]

Table 6 summarizes the results obtained by the SN fit and the some of the results based on the Normal fit. The results are all consistent with the conclusions derived by the analyses on Alpha Centauri b. The correlation between γ and RV mean SN is stronger than the correlation between the BIS SPAN and RV for all the considered stars. The correlation between SN FWHM and RV mean SN is stronger than the correlation between FWHM and RV for three of the four stars. The analyses of the correlations for the four stars are are presented Fig. 21, 22, 23 and 24.

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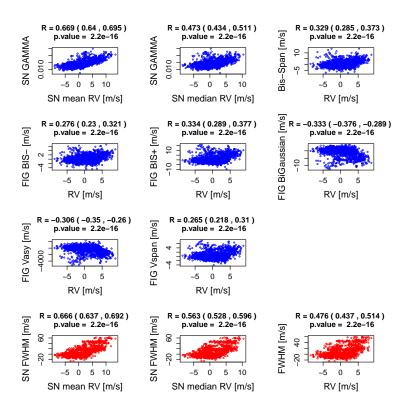


Figure 21: Correlation between the asymmetry parameters and the RVs for HD 192310. The last three plots show the correlation between the FWHM and the RVs for HD 192310 using respectively the SN and the Normal fits. [[Umberto: faculae???]]

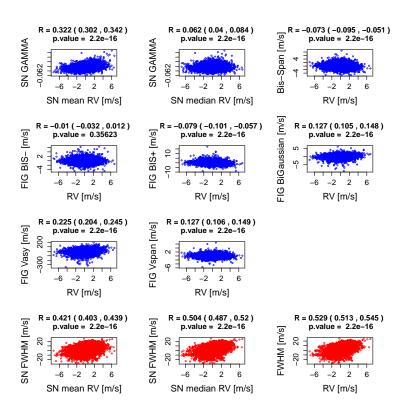


Figure 22: Correlation between the asymmetry parameters and the RVs for Tau Ceti. The last three plots show the correlation between the FWHM and the RVs for Tau Ceti using respectively the SN and the Normal fits.[[Umberto: faculae???]]

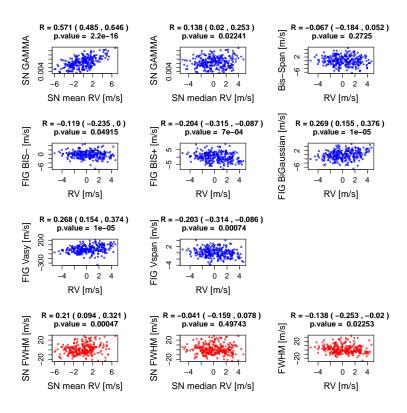


Figure 23: Correlation between the asymmetry parameters and the RVs for HD 215152. The last three plots show the correlation between the FWHM and the RVs for HD 215152 using respectively the SN and the Normal fits.[[Umberto: spot???]]

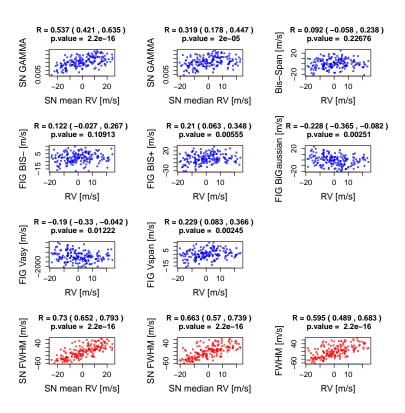


Figure 24: Correlation between the asymmetry parameters and the RVs for Corot-7. The last three plots show the correlation between the FWHM and the RVs for Corot-7 using respectively the SN and the Normal fits.[[Umberto: faculae???]]

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