- 1. Other Indexes and Evaluation of Selections
 - 1. Skiplists
 - 1. Optimized index structure for disk access
 - 2. Skiplist- multiple levels of linked lists
 - 1. Searching
 - 2. Insertion
 - 3. Removal
 - 2. Specialized Index Techniques
 - 1. Multiple Key Index
 - 2. kd tree
 - 3. Bitmap Indices
- 2. Query Optimaization
 - 1. Query Model and Metrics
 - 2. Unary Operators
 - 1. Selection
 - 2. Complex Selection
 - 3. Selections with no Disjunctions
 - 3. External sorting
 - 1. Naive External Merge Sort
 - 4. Projections
 - 5. Joins
 - 1. Join的几种类型:
 - 2. Nested Loop Joins

Other Indexes and Evaluation of Selections

Skiplists

Optimized index structure for disk access

基本特点:

快速的inset和delete算法 Used by MemSQL

在并发性方面具有优势

Skiplist- multiple levels of linked lists

- lowest level 按照顺序包含所有Keys
- higher level包含上一级别的一半的keys数量
 - 。作为向下一级的索引
 - 。 运行时间O(logn),包含range search
 - 。 如果元素x出现在第i层,则所有比i小的层都包含x;

Sorted Linked Lists

• inefficient 虽然是Dynamic 但是运行时间是O(n)

Searching

- skiplists search 一个level最多可以访问两个node
- · start at top level
 - If current node == target go to bottom level and return record
 - If target < next key go down level and repeat
 - If target >=next key go right and repeat
 - If at lowest level linear search until target found or passed

Insertion

- 插入和删除都是problematic的,成本高昂因为要确保1/2的元素在下个level,可能需要重新排列整个列表
- Solution relax the requirement
- Each level is expected to have $\frac{1}{2}$ the nodes of the previous level
- On insertion a node is copied to the higher level with probability of 0.5
 - A randomized data structure two skiplists with the same data inserted in the same order may differ

实际操作:

- Insert into lowest level first
- Then roll dice to see if value is inserted into higher levels
- · Keep track of path to lowest levels (the visited nodes) to insert higher level nodes

- Removal is straightforward
 - If the entry has a tower of nodes remove the entire tower
 - Like insertion, the nodes in the search path need to be retained in the processRemoval is straightforwar

Specialized Index Techniques

There are a number 0f specialized indexes:

- 通常与满足条件复杂的查询相关
 - 。 带连词和/或析取的Where子句
 - 。可能涉及多个属性
- Geographic information systems
 - 。 部分匹配查询
 - 。范围查询
 - 。最近邻查询
- OLAP databases
 - 。多维数据查询

Multiple Key Index

使用常规索引可以满足条件复杂的查询

- 通过使用复合搜索键创建索引
- 或者通过使用多个索引,检索RID并选择其交点
- 或用于析取的并集

An alternative is to create a multiple key index

- 一个属性上的索引构建在另一个属性上的索引之上
- 第一个索引是指第二个属性上的索引页
 - 。 对于与第一个索引不同的搜索键值,可以重复较低索引中的搜索键值

Multiple key indices work well for range queries

But do not support queries where data for the first attribute is missing

An alternative is a kd tree

k维搜索树是用于多维数据的内存结构

- They generalize a binary search tree
- 小于节点值的值位于其左子树中
- 大于节点值的值位于其右子树中
- kd tree nodes contain an attribute name and an associated value

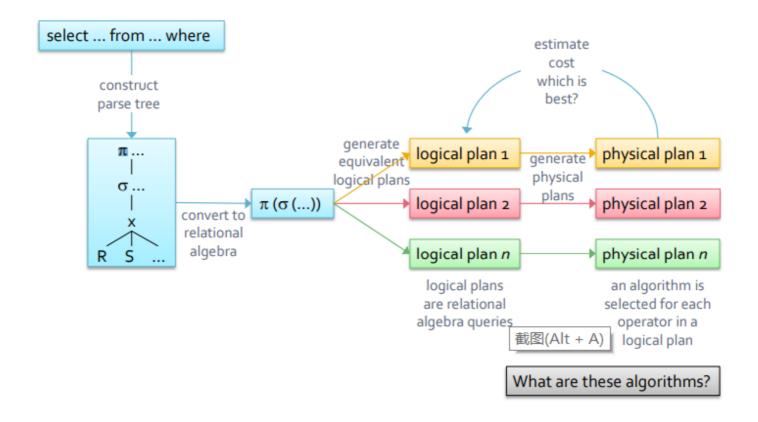
The levels rotate through the attributes of the tree

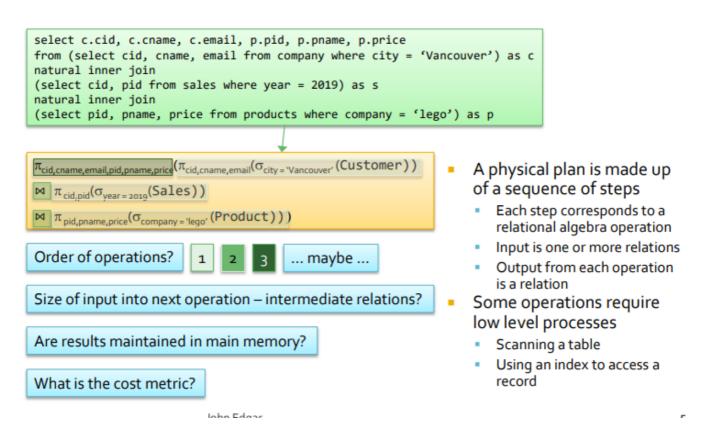
With two attributes, the levels alternate between the attributes

Bitmap Indices

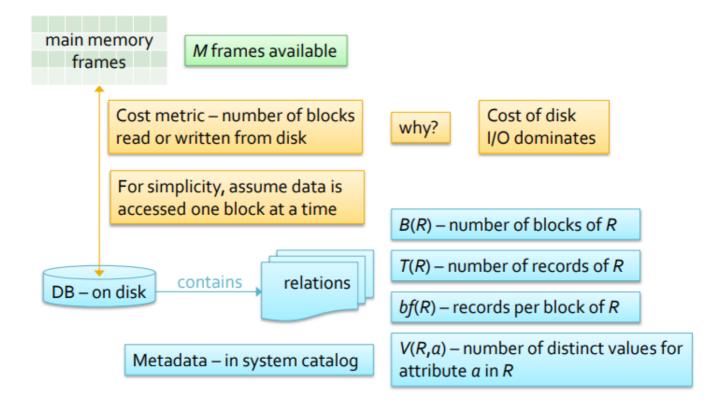
- Bitmap indices通常用于数据库中的数据挖掘和OLAP
 - Which often have low cardinality attributes
 - 。变化相对较少
- Bitmap indices由多个位向量组成
 - 。属性的每个可能值都有一个向量
 - o A bitmap to record if a patient was a smoker would require two bit vectors
 - A bitmap on birth year might require 100 bit vectors
 - The I th bit of the index is set to 1 if the I th row of the table has the vector's
 value for the attribute
- A bitmap index can speed up queries on sparse columns, that have few possible values
 - One bit is allocated for each possible value
- Use indices to answer queries

Query Optimaization





Query Model and Metrics



Computation Model

This section covers algorithms for query operations(often more than one query)

- 单独考虑operations
- 假设数据是从磁盘读取的;实际上,情况并非总是如此,结果保留在内存中,而不是写出来

Unary Operators

一元运算符是具有单个操作数的运算

For SQL operators the operand is a table

- Either a base table or the result of a previous query
 - Either a base table or the result of a previous query operation

包括:

Selection

A simple selection has a single condition

- 通过访问路径检索匹配的记录来满足选择
- 扫描文件并测试每条记录,以确定其是否与所选内容匹配
- 如果文件已排序且没有索引,则使用二进制搜索
- 在条件中的属性上使用索引

cost:

- No index on the selection attribute
 - Linear search by scanning file, cost is B reads
 - 。 如果选择属性是候选键,则一旦找到匹配项,即可终止扫描(cost is B/2)
 - If the file is sorted use binary search to find record (* log2(B) + pages of matching records - 1)
- Index on the selection attribute
 - The cost is dependent on
 - The type of index B+ tree, hash index, ...
 - The height of the index
 - 与所选内容匹配的记录数
 - 索引是主索引还是次索

Cost of using an Index:

- The cost of satisfying a selection with an index is composed of
 - Number of disk reads to use the index
 - i.e. to reach the leaf / bucket that contains the data entry
 - The number of leaves / size of the bucket
 - Number of blocks of the file with records that match the selection
 - Generally larger if the index is secondary
- Assume that indices are
 - Hash index extensible or linear
 - B+ tree index

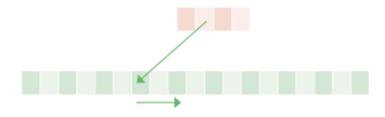
Cost to Search Index

- B+ Tree
 - To find matching RIDs search tree
 - RIDs reside in leaf nodes
 - Cost: 1 disk read per level
- · Additional leaf pages may have to be read
 - 。 如果索引密集或selection不平等
 - selection
- Extensible hash index
 - 。读取目录
 - Probably 1 or 2 blocks
 - Read bucket(one block)

- Linear hash index
 - Read bucket
 - Bucket may have overflow blocks
 - Hash indexes only used for equality selections

Cost to Read Records

- Primary index
 - 。 文件按search key搜索排序
 - 。在连续blocks中存储匹配的记录
 - Blocks read is number of records / records per block
 - 1 + [(records 1) / bf(R)] (upper bound)
 - Assumes worst case



- Secondary index
 - 。匹配的记录不会连续存储
 - 。假设每个匹配记录读取一个磁盘
 - 。因为记录分散在文件中
 - 。 对于较大的选择,可能比文件扫描更糟糕



Access Method	Candidate Key Selection	Non Candidate Key Selection	Notes
Linear search	B/2	В	
Binary search	$\log_2(B)$	$\log_2(B) + x$	Must be sorted on selection attribute x = blocks of matching records
Primary B+ tree index	tree height + 1	tree height + x	x = blocks of matching records
Secondary B+ tree index	tree height + 1	tree height + $w + y$	w = leaf nodes of data entries - 1y = number of matching records
Primary hash index	index height + 1	index height + $w + x$	w = blocks in bucket - 1x = blocks of matching records
Secondary hash index	index height + 1	index height + $w + y$	<pre>w = blocks in bucket - 1 y = number of matching records</pre>

Notes: tree height usually 3 to 5; hash index "height" usually 1 or 2; root node of indexes may be resident in main memory which reduces cost by 1; value for w is usually 1 (particularly for a hash index); difference between x and y can be large; details on how to compute these costs follow

Complex Selection

A complex selection is made of at least two terms connected by and (^) and or (v)

- The terms can reference different or the same attributes
- Conjunctions are more selective (and)
- Disjunctions are less selective (or)

Complex selections的满足方式与 simple selections的满足方式大致相同

- If no index on any of the selection attributes scan the file
- Use indices on selection attributes where possible
- 索引的使用取决于selection和索引的类型

Selections with no Disjunctions

- 如果只有一个索引可用,请使用该索引并在主存中应用其他选择
 - Either there is an index on only one of the attributes
 - 。或具有引用多个选择属性的复合键的索引
 - 。注意哈希索引的使用限制
- If multiple indexes are available
 - Either use the most selective
 - o Or collect RIDs from leaves or buckets of indexes and take the intersection
- Selections with disjunctions are stated in conjunctive normal form (CNF)
 - A collection of conjuncts
 - o Each conjunct consists either of a single term, or multiple terms joined by or
 - $\circ \ (A^{\wedge} \ B) \ v \ C \ v \ D \equiv (A \ v \ C \ v \ D) \ {}^{\wedge} (B \ v \ C \ v \ D)$

- 。这允许独立考虑每个连接
- A conjunct can only be satisfied by indices if there is an index on all attributes of all of its disjunctive terms
 - If all the conjuncts contain at least one disjunction with no matching index a file scan is necessary
- Consider a selection of this form
- \bullet $\sigma_{(a \lor b \lor c) \land (d \lor e \lor f)}(R)$
- Where each of a to f is an equality selection on an attribute
- If each of the terms in either of the conjuncts has a matching index
 - Use the indexes to find the rids
 - Take the union of the rids and retrieve those records
 - For example, if there are indexes just on a, b, c, and e
 - Use the a, b, and c indexes and take the union of the rids
 - Retrieve the resulting records and apply the other criteria

External sorting

在读取时对数据进行排列时有必要的

- 使用Order BY
- ways to sort :
 - Main memory sorting
 - B+ tree index
 - mult-way mergesort

Naive External Merge Sort

对Disk data使用 merge sort

- Initial Step- read 2 pages of data from file
 - 。排序之后写入硬盘
 - 。得到一个B/2的结果

Projections

Joins

Cartesian Product: 设D1、...、Dn是n个域。D1、...、Dn上的笛卡尔乘积定义为集合 D1×...×Dn ={ (d1, ..., dn) | di ∈ Di, 1≤i≤n }。

EX: D1={我, 你} D2={他, 她}

D1xD2: {我,她},{我,他},{你,他}.....

Join: 跟随selection的Cartesian Product, selection作为join的条件

Join的几种类型:

Nature Join: 融合两个tables通过相同的attritubes name 和datatype

Inner Join: 两个table重合的数据,会返回包含所有属性的来自于这两个table的相同的 colums

Nested Loop Joins

有三种nested loop joins的算法,用来比较来自不同表的数据是否相同

- 1. Tuple nested loop join
 - 1. cost = B(R) + (T(R) * B(S))
 - 2. 一次读取 one page of R,scan S 然后将R中的每个record和S中的每个record 作比较,最后返回的结果排序和R相同
 - 3. 进阶版本 就是扫描和对比同时进行,运行时间是Cost = B(R) + (B(R) * B(S))
 - 4. 需要两个input buffer和一个output buffer
- 2. Block Nested Loop Join
 - 1. 相比于上一个算法,这个算法更高效的方法是通过增大input buffer for R