```
set duree 25000
; definit les formes par defaut des agents
set-default-shape Perceptions "circle"
set-default-shape Bases "house"
set-default-shape Explorers "explorer"
set-default-shape RocketLaunchers "rocket launcher"
set-default-shape Harvesters "harvester"
set-default-shape Burgers "hamburger"
set-default-shape Walls "box"
; initialise les variables qui definissent les parametres du jeu
; parametres des bases
set base-nrj 50000
set base-perception 10
set base-speed 0
set base-nb-missiles 1000
set base-max-missiles 1000000
set base-nb-fafs 20
set base-max-fafs 100
set base-waiting 1
set base-burgers 100
; parametres des rocket-launchers
set rocket-launcher-cost 6000
set rocket-launcher-nrj 4000
set rocket-launcher-perception 5
set rocket-launcher-speed 0.5
set rocket-launcher-metabolism 0.1
set rocket-launcher-nb-missiles 100
set rocket-launcher-max-missiles 1000
set rocket-launcher-nb-fafs 2
set rocket-launcher-max-fafs 5
set rocket-launcher-waiting 5
set rocket-launcher-burgers 10
; parametres des explorers
set explorer-cost 1500
set explorer-nrj 1000
set explorer-perception 10
set explorer-speed 1
set explorer-metabolism 0.1
set explorer-burgers 10
; parametres des harvesters
set harvester-cost 3000
set harvester-nrj 2000
set harvester-perception 3
set harvester-speed 0.25
set harvester-metabolism 0.1
set harvester-burgers 10
; parametres des missiles
set missile-cost 10
set missile-range 10
set missile-robot-damage 100
set missile-base-damage 20
set missile-speed 1
; parametres des faf
set faf-cost 50
set faf-range 20
set faf-robot-damage 200
set faf-base-damage 40
set faf-speed 1
; parametre des collisions
set collision-damage 1000
; parametres des burgers
```

to init-parameters

```
set burger-quantity 100
set burger-periodicity 2000
set wild-burger-min-nrj 50
set wild-burger-max-nrj 100
set seeded-burger-min-nrj 100
set seeded-burger-max-nrj 150
set burger-decay 0.1
; parametres des graines
set seed-cost 20
set max-seeds 5
set maturation-time 1000
set wall-cost 100
set wall-nrj 1000
end
```