

Induction Motors

Date

No.

$$1. \quad n_r = (1-s)n_s \quad s = \frac{n_s - n_r}{n_s}$$

At rest $n_r = 0 \quad s = 1 \text{ if } n_r = 0$

$$\Rightarrow 0 = (1-s)n_s$$

$$s = 1 \text{ or } 100\%$$

$$2. \quad 3\phi, 2 \text{ poles}, 60 \text{ Hz}, n_r = 3502 \text{ rpm}$$

$$P_{in} = 15.7 \text{ kW}, I_1 = 22.6 \text{ A}$$

$$r_1 = 0.2 \Omega / \text{phase}$$

$$P_{core} = ?$$

$$P_{core} = 0 \text{ W}$$

$$P_{scL} = 3I_1^2 r_1$$

$$= 3(22.6)^2 (0.2)$$

$$= 306.46 \text{ W}$$

$$= 15393.54 \text{ W}$$

$$P_{AG} = P_{in} - P_{core} - P_{scL}$$

$$= 15.7 \text{ kW} - 0 - 306.46$$

$$= 15393.54 \text{ W}$$

$$P_{AG} = 3I_2^2 \frac{R_2'}{s}$$

$$\downarrow$$

$$s \cdot P_{AG} = 3I_2^2 R_2'$$

$$n_s = \frac{120 \times 60}{2} = 3600 \text{ rpm}$$

$$s = \frac{n_s - n_r}{n_s} = \frac{3600 - 3502}{3600}$$

$$= 0.027 \text{ or } 2.7\%$$

$$s \cdot P_{AG} = 3I_2^2 R_2' = P_{RCL}$$

$$P_{RCL} = 0.027 \times 15393.54 = 419 \text{ W}$$

$$P_{in} = 3V_1 I_1 \cos \theta$$

$$\rightarrow P_{scL} = 3I_1^2 R_1 \quad P_{scL} = \text{stator copper loss}$$

$$\rightarrow P_{core} = \frac{3E_1^2}{R_c} \quad \rightarrow 3I_1^2 R_2'$$

$$P_{AG} \rightarrow P_{MAMP} = P_{in} - P_{scL} - P_{core}$$

$$P_{AG} = 3I_1^2 \cdot \frac{R_2'}{s}$$

$$\rightarrow P_{RCL} = 3I_2^2 R_2'$$

$$P_{elec} = P_{AG} - P_{RCL} = 3I_2^2 \frac{R_2'}{s} - 3I_2^2 R_2'$$

$$= 3I_2^2 R_2' \left(\frac{1}{s} - 1 \right)$$

$$= 3I_2^2 R_2' \left(\frac{1-s}{s} \right)$$

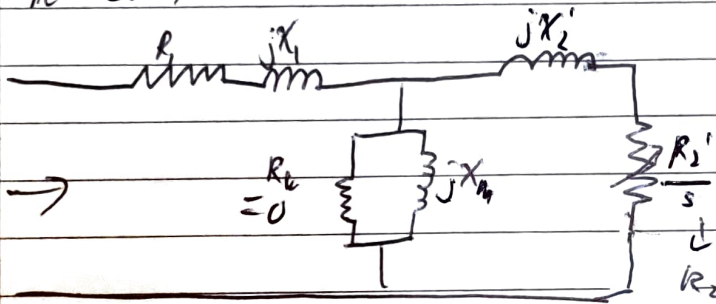
$$\rightarrow P_{rotor \text{ loss}} = P_{mech} + P_{windage}$$

$$P_{out} = P_{elec} - P_{mech \text{ loss}}$$

$$P_{out} = \tau_m \cdot \omega_m = P_{shaft}$$

$$\eta = \frac{P_{out}}{P_{in}}$$

3. $3\phi, Y, 220V, 7.5kW, 60Hz, 6 \text{ pole}$
 $R_1 = 0.1 \Omega, R_2' = 0.1 \Omega, X_1 = 0.2 \Omega, X_2' = 0.2 \Omega$
 $X_m = 10 \Omega, s = 0.01$



$$n_s = \frac{120 f}{p} = \frac{120 \times 60}{6} = 1200 \text{ rpm}$$

$$n_r = (1-s)n_s = (1-0.01)1200 \\ = 1188 \text{ rpm}$$

$$\omega_r = 1188 \times \frac{2\pi}{60} = 124.4 \text{ rad/s}$$

$$\rightarrow \frac{R_2'}{s} + jX_2' \\ Z_s' = \frac{0.1}{0.01} + j0.2 = 10 + j0.2 \Omega$$

$$Z_s' \parallel jX_m = (10 + j0.2) \parallel (j10) = 4.9 + j5 \Omega$$

$$Z_{eq} = Z_1 + (Z_s' \parallel jX_m) = (0.1 + j0.2) + (4.9 + j5) \Omega \\ = 5 + j5.2 \Omega$$

$$Z_{eq} = |Z_{eq}| \angle Z_{eq} \rightarrow \cos(\angle Z_{eq}) \rightarrow \text{p.f. of the line}$$

If load changes $\rightarrow s$ changes $\rightarrow Z_s'$ change

Power factor $\leftarrow \angle Z_{eq}$ changing $\leftarrow Z_{eq}$ change

$$s = \frac{n_s - n_r}{n_s}$$

$$1(n_s) = n_s - n_r$$

$$n_r = 0$$

4.

$$Z_i = 541 + j3.1 \Omega, 7.5 \text{ kW}$$

$$I_1 = 18.8 \text{ A}, s = 2\%, \omega_r = 123.2 \text{ rad/s}$$

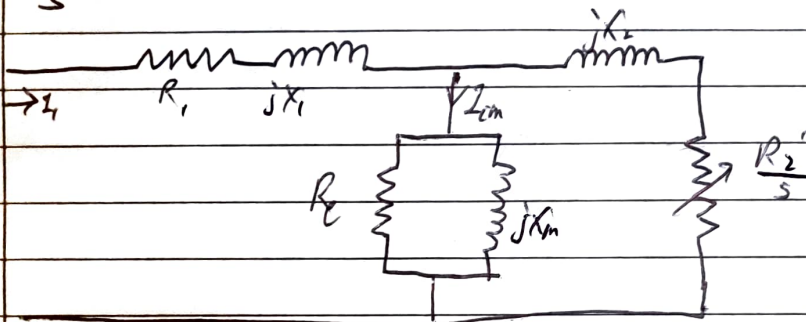
$$P_{\text{dum}} = 403 \text{ W}$$

$$P_{\text{shaft}} = ?$$

$$T_{\text{output}} = ?$$

$$Z_i' = 541 + j3.1$$

$$\frac{R_2'}{s} = 541$$



$$I_1 = I_2' + I_{2m}$$

$$I_{2m} = \text{very small}$$

$$I_2' \approx I_1 = 18.8 \text{ A}$$

$$\begin{aligned} P_{AG} &= 3 I_2'^2 \cdot \frac{R_2'}{s} \\ &= 3 \times 18.8^2 \times 5.41 \\ &= 5736.3 \text{ W} \end{aligned}$$

$$\begin{aligned} P_{\text{elec}} &= P_{AG} - P_{RCL} \\ &= P_{AG} - s \cdot P_{AG} \\ &= 5736.3 (1 - 0.02) \\ &= 5621.6 \text{ W} \end{aligned}$$

$$\begin{aligned} P_{\text{shaft}} &= P_{\text{out}} = P_{\text{elec}} - P_{\text{motor loss}} \\ &= 5621.6 - 403 = 5218.6 \text{ W} \end{aligned}$$

$$P_{in} = 3 V_i I_1 \cos \theta \quad P_{scl} \rightarrow \text{stator copper loss}$$

$$\begin{aligned} \rightarrow P_{scl} &= 3 I_1^2 R_1 \\ \rightarrow P_{\text{core}} &= \frac{361^2}{R_c} \end{aligned}$$

$$P_{AG} = P_{\text{para}} = P_{in} - P_{scl} - P_{\text{core}}$$

$$P_{AG} = 3 I_2'^2 \cdot \frac{R_2'}{s}$$

$$\begin{aligned} \rightarrow P_{RCL} &= 3 I_2'^2 \cdot R_2' \\ &= s P_{AG} \end{aligned}$$

$$\begin{aligned} P_{\text{elec}} &= P_{AG} - P_{RCL} = 3 I_2'^2 \frac{R_2'}{s} - 3 I_2'^2 \cdot R_2' \\ &= 3 I_2'^2 R_2' \left(\frac{1}{s} - 1 \right) \\ &= 3 I_2'^2 R_2' \left(\frac{1-s}{s} \right) \end{aligned}$$

$$\rightarrow P_{\text{motor loss}} = P_{\text{friction}} + P_{\text{windage}}$$

$$P_{\text{out}} = P_{\text{elec}} - P_{\text{motor loss}}$$

$$P_{\text{out}} = \tau_m \cdot \omega_m = P_{\text{shaft}}$$

$$\eta = \frac{P_{\text{out}}}{P_{in}}$$

$$T_m = \frac{P_{shaft}}{\omega} = \frac{5218.6}{132.2} = 42.4 \text{ Nm}$$

5. $\rightarrow 480 \text{ V}, 60 \text{ Hz}, 50 \text{ Hp}, 3\phi, I_L = 60 \text{ A}$

$$\cos \theta_1 = 0.85 \text{ lag}$$

$$P_{scu} = 2000 \text{ W}, P_{rcu} = 700 \text{ W}$$

$$P_{mean loss} = 600 \text{ W}, P_{core} = 1800 \text{ W}$$

$$P_{in} = 3 V_{ph} I_{ph} \cos \theta$$

$$\rightarrow P_{in} = 3 V_L I_L \cos \theta$$

$$P_{in} = 3 V_L I_L \cos \theta$$

$$= 3 \times \frac{480}{\sqrt{3}} \times 60 \times 0.85$$

$$= 42400.6 \text{ W}$$

$$\begin{aligned} \rightarrow P_{scu} &= 3 I_L^2 R_s \\ \rightarrow P_{core} &= \frac{3 E_c^2}{R_c} \end{aligned}$$

$$P_{AG} \rightarrow P_{MRRamp} = P_{in} - P_{scu} - P_{core}$$

$$P_{AG} = 3 I_2'^2 \cdot \frac{R_2'}{s} \quad R_{cl} \rightarrow \text{Rotor copper Loss}$$

$$\rightarrow P_{rcu} = 3 I_1'^2 \cdot R_2'$$

$$P_{elec} = P_{AG} - P_{rcu} = 3 I_2'^2 \cdot \frac{R_2'}{s} - 3 I_1'^2 \cdot R_2'$$

$$= 3 I_2'^2 R_2' \left(\frac{1}{s} - 1 \right)$$

$$= 3 I_2'^2 R_2' \left(\frac{1-s}{s} \right)$$

$$\rightarrow P_{rotor loss} = P_{mech} + P_{windage}$$

$$P_{out} = P_{elec} - P_{rotor loss}$$

$$P_{out} = C_m \cdot \omega_m = P_{shaft}$$

$$\eta = \frac{P_{out}}{P_{in}}$$

a. $P_{AG} = P_{in} - P_{scu} - P_{core}$

$$= 42400.6 - 2000 - 1800$$

$$= 38600.6 \text{ W}$$

b. $P_{elec} = P_{conv} = P_{converted}$

$$= P_{AG} - P_{rcu}$$

$$= 38600.6 - 700$$

$$= 37900.6 \text{ W}$$

c. $P_{out} = P_{elec} - P_{mean loss}$

$$= 37900.6 - 600$$

$$= 37300.6 \text{ W}$$

a. $\eta = \frac{P_{out}}{P_{in}} \times 100\% = \frac{37300.6}{42400.6} \times 100\%$

$$= 87.97\%$$