	Tutorial - Induction Motors
1	
	The slip will be I if the rotor is stationary. The rotor frequency equals to stater.
2.	$P_{\text{Stator}} = 3 I_{i}^{2} R_{i} = 3 \times 22.6^{2} \times 0.2$
	Pace = 306 W
	0 0
	PAGE = Pin - PSEL = 15.7 - 0.3 = 15.4 kw
	Ns = 120 f = 120 x60 = 3600 pm
	S = 3600 - 3502 = 0,0272
	3600
	PRCL = 5PAG = 0.0272 x 15,4 = 419 W.
3.	Ze = Re + jXe = (Re + jXz) // 5Xm
	Ze = 1
****	$(0.1 + j0.2)^{-1} + (1)$
	0,01
	Ze = 4.9 + 35 SZ.
	7 -0 -12 - 11 - 0 - 10 - 25
	$Z_{eq} = R_1 + iX_1 + Z_e = 0.1 + j_0.2 + 4.9 + j_5$
	Zy=5+j5,2 s.
	Wm = (1-5) Ws = (1-0,01) x Ws = 0,9900
	ns = 120 p = 120 x60 = 1200 pm.
-	> W = 1200 x 211 = 125,7 rad/s
	60
	=> Wm=0.99Ws = 0.99 x (25.7)
	Wm = 123.2 rad/s

4. Pag = n. I, Rp = 3x 18,82 x 5,41 PAG = 5740 W. Pahaff = Prony - Losses. = (1-s) PAG - 403 = (1-0,02)x5740-403 Pauf = 5220 W Total = Pshaft = 5220 Wm 123,2 Tsheft = 42.4 Mm 5. a) Pin = 13 V. I. cos 0 = 13 × 480 × 60 × 0.85 Pin = 42,4 kw. PAG = Pin-Psc - Pcore = 42.4 - 2-1.8 Page = 38.6 kW b) Pcon = PACE - PRCL = 38.6 - 0.7 Pcon = 37.9 kW c) Part = Pany - Pfret + wind = 37.9 - 0.6 Part = 37.3 kW d) n = Pout x100= 37.3 x100 n = 88%