

Lecture on Kalman Filter State Observer or State Estimator

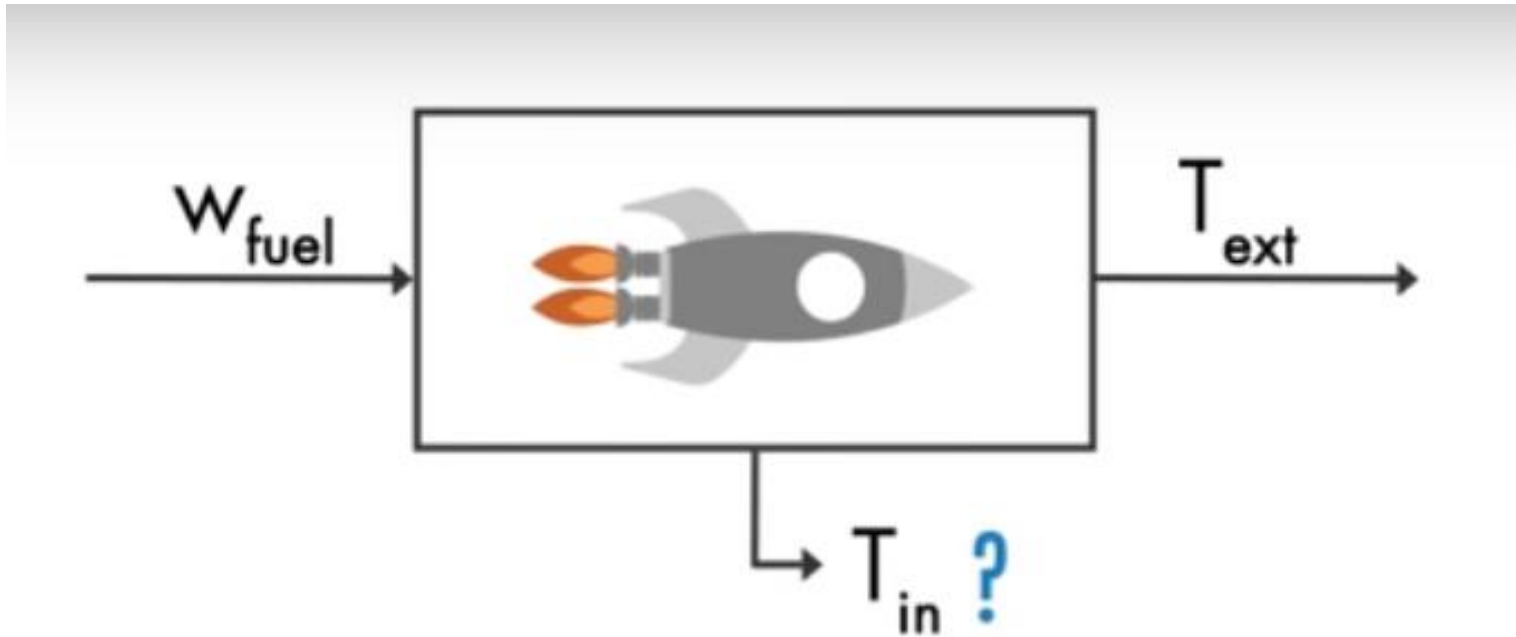
ESP 3201
Dr Ng Gee Wah

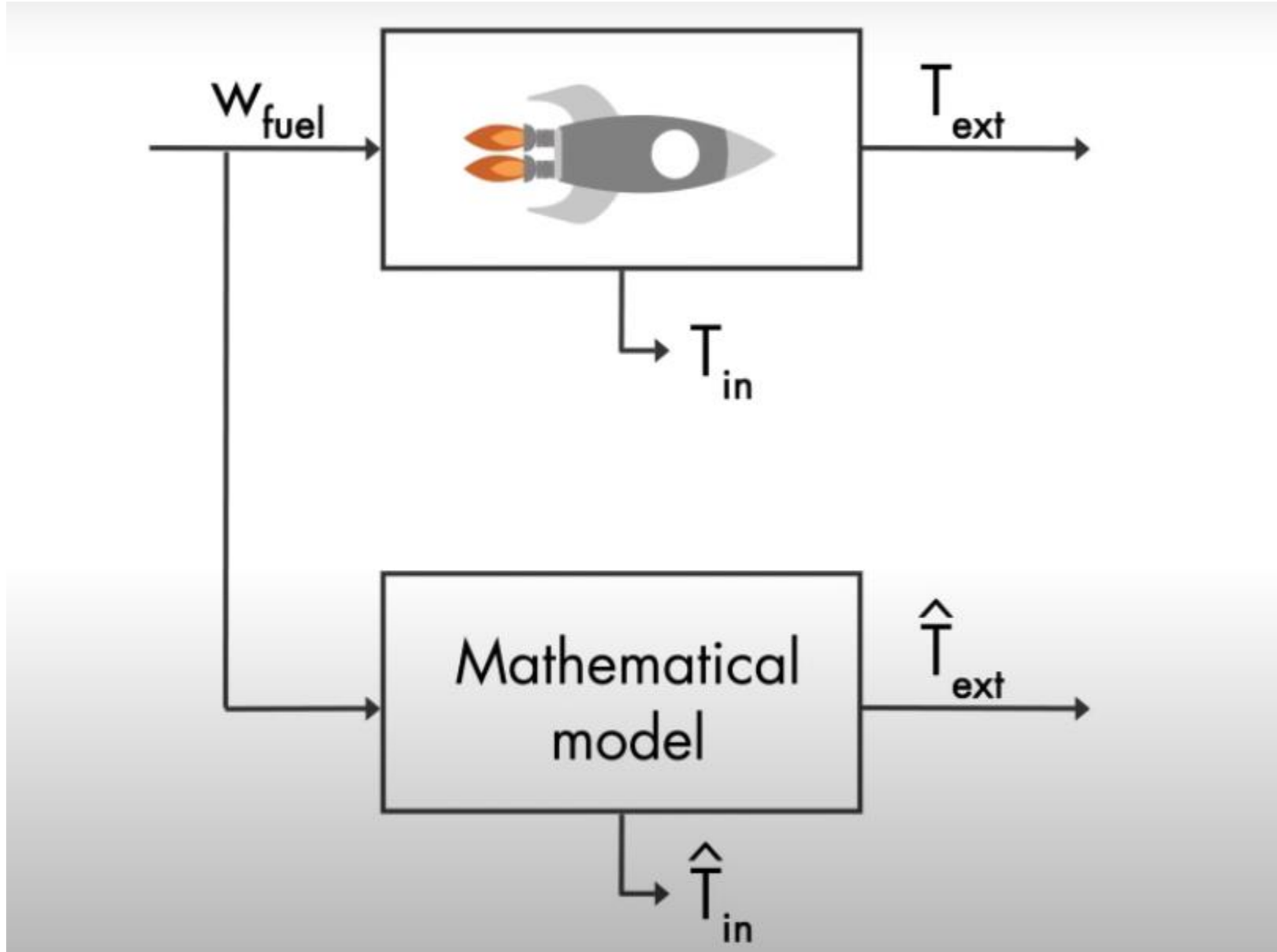
State Observer or State Estimator

- An example when you play guessing game such as guess what is in the cage or guess what is his mood?
 - Give an input such as a cookie and observe his facial expression; this indirectly measure his mood.
- In control theory, a state observer or state estimator is a system that provides an estimate of the internal state of a given real system, from measurements of the input and output of the real system.

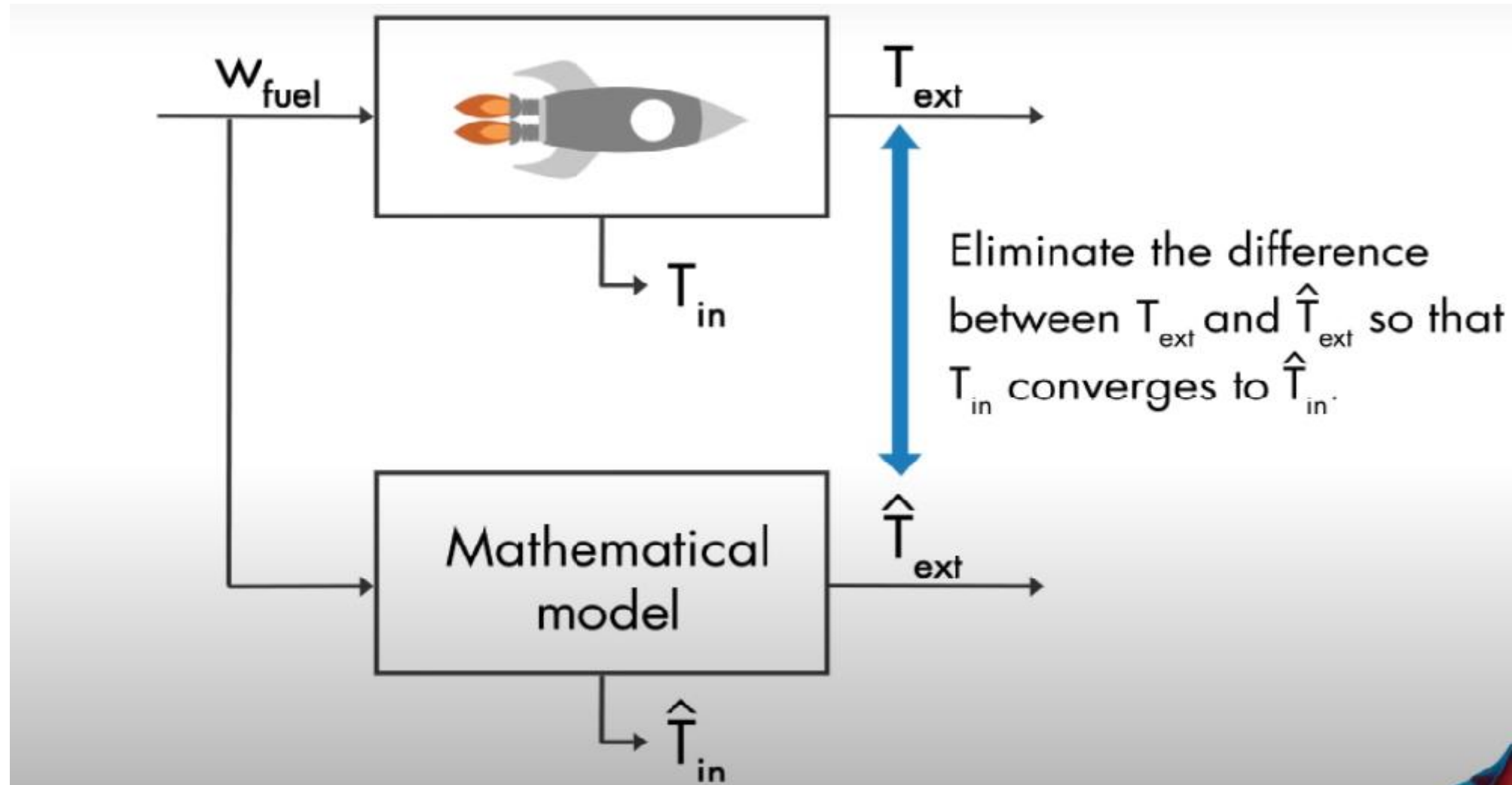
Example of State Observer or State Estimator

- An spacecraft example of estimated state of the internal temperature of its engine \hat{T}





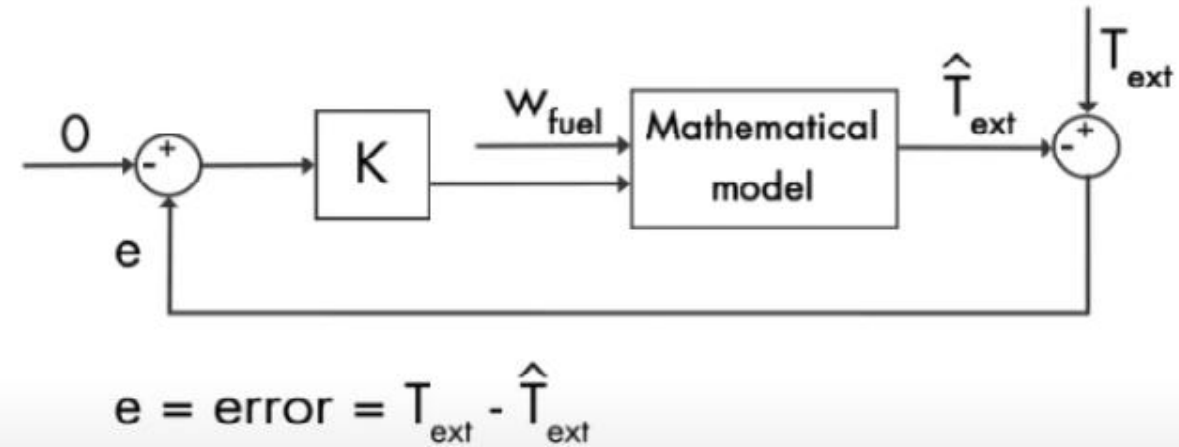
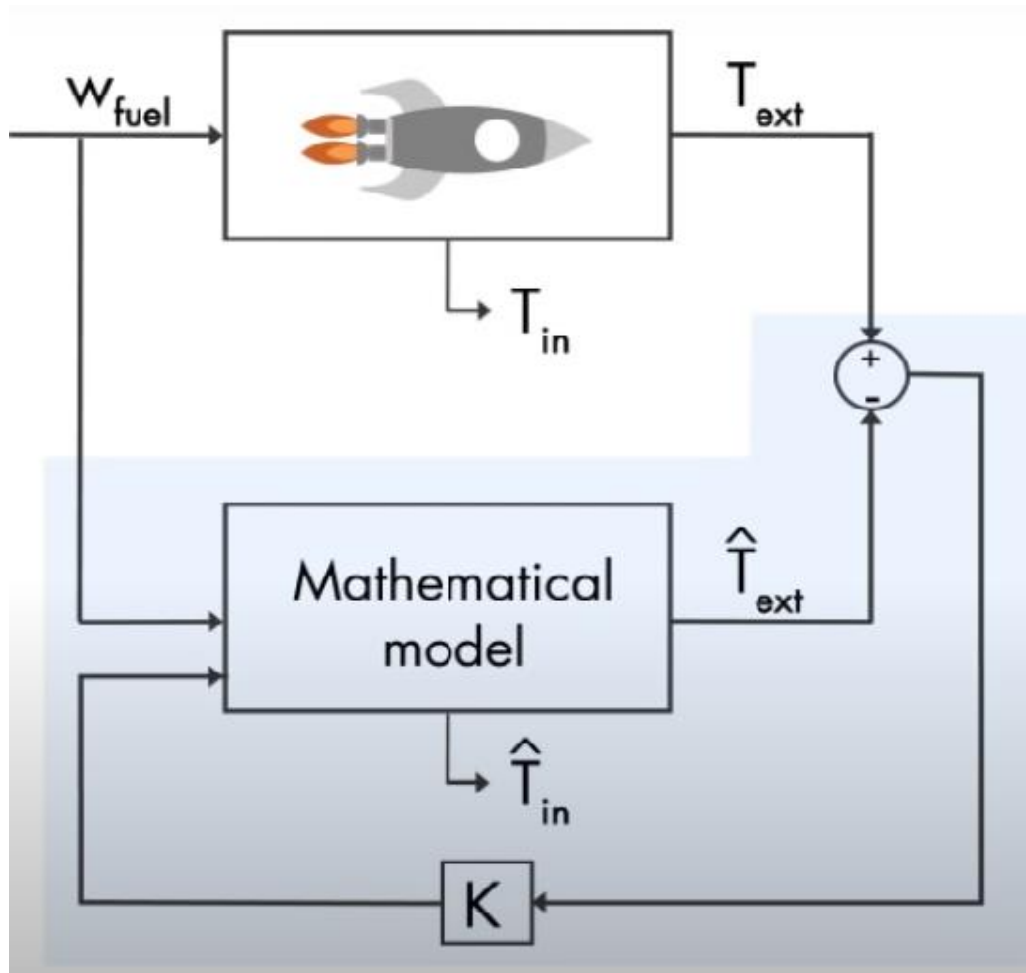
State Observer or State Estimator



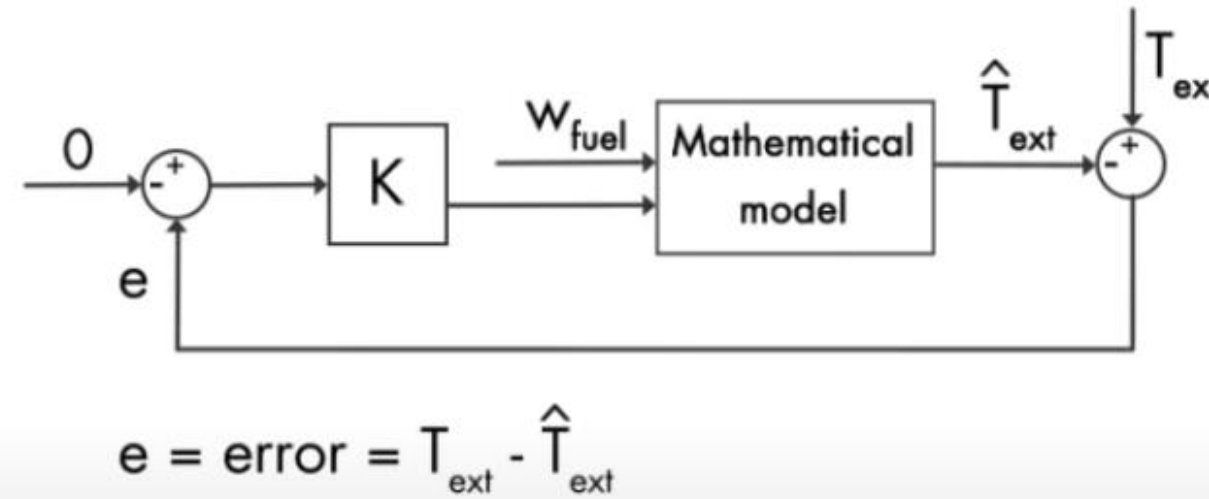
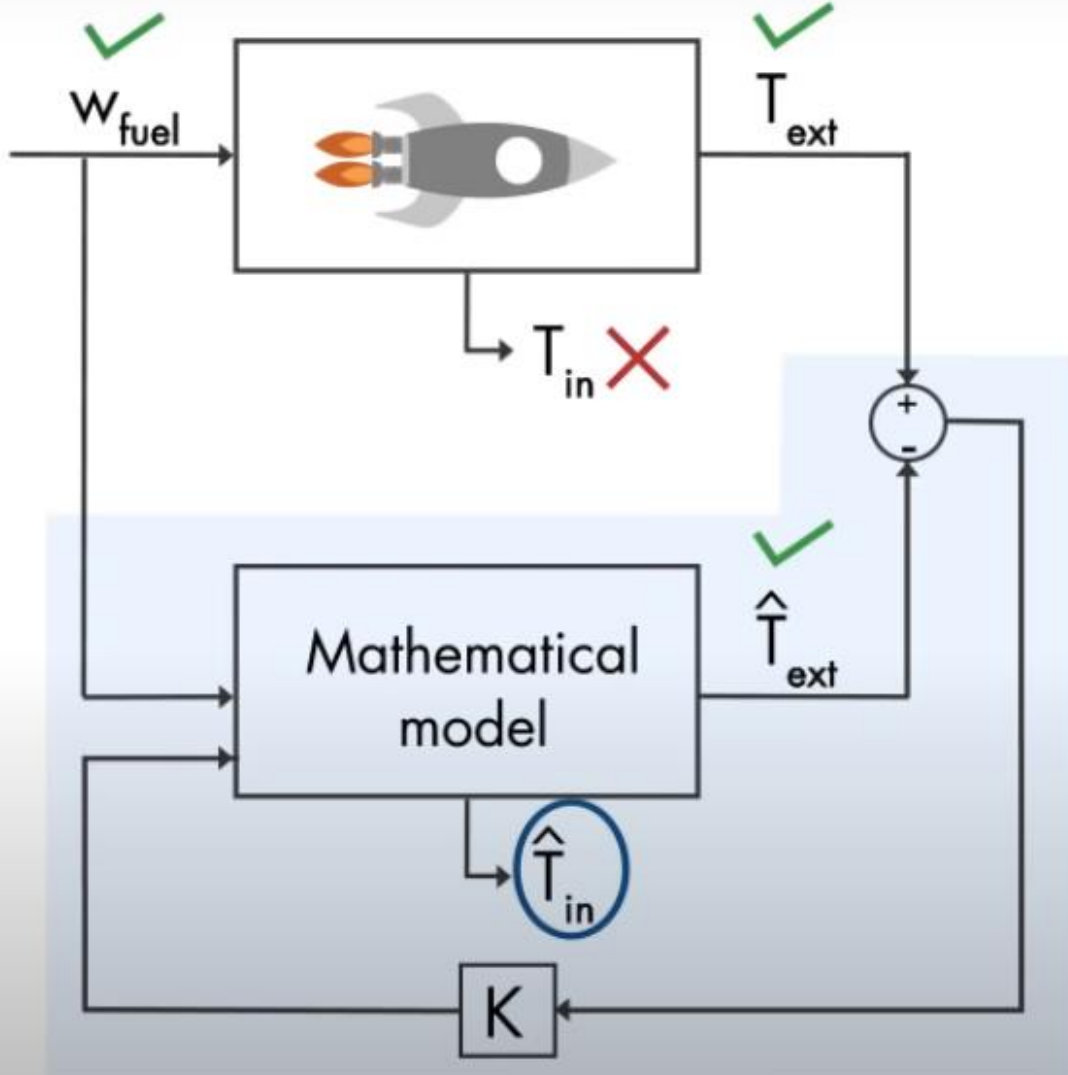
State Observer or State Estimator



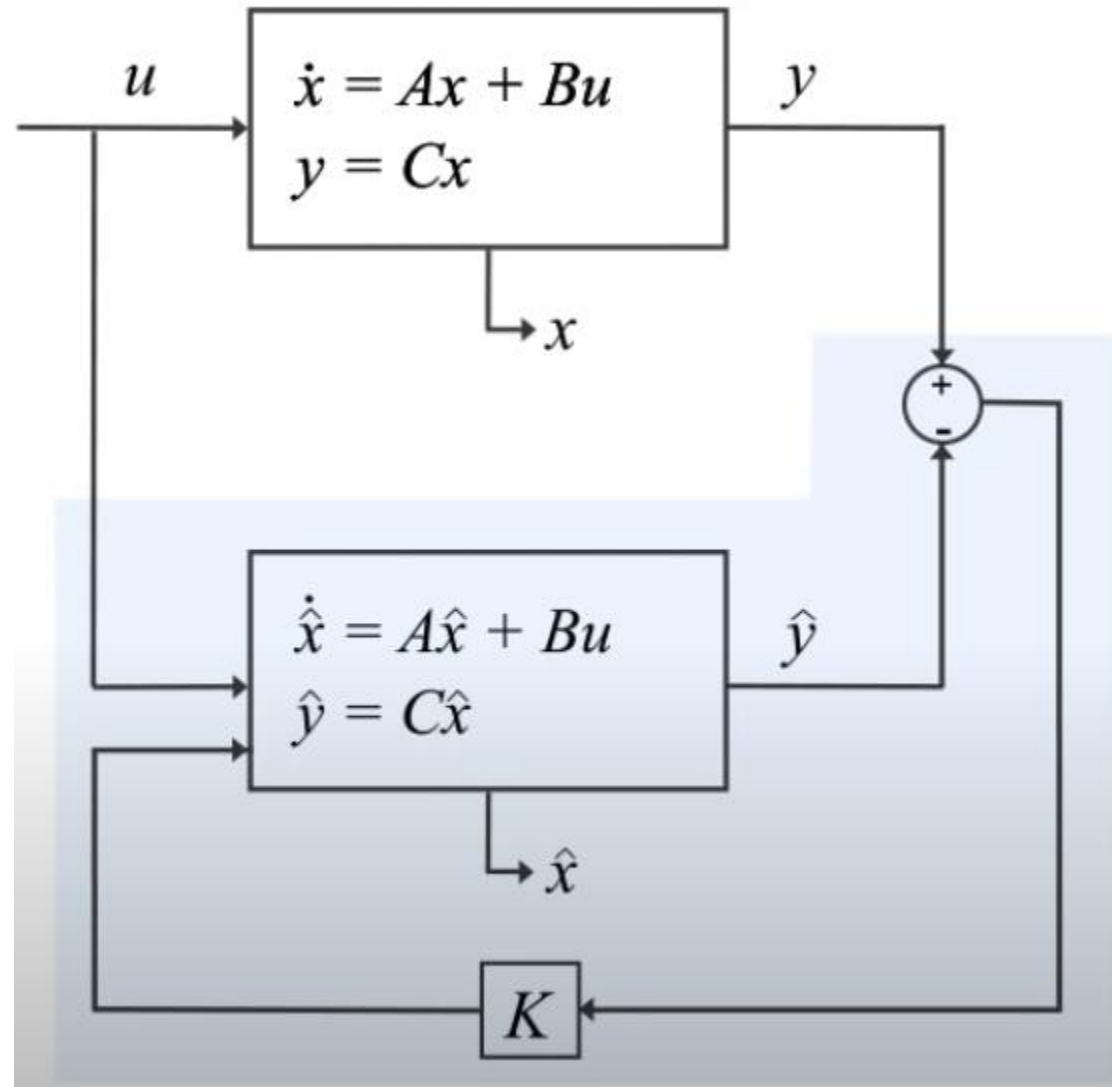
- Estimated state \hat{T}



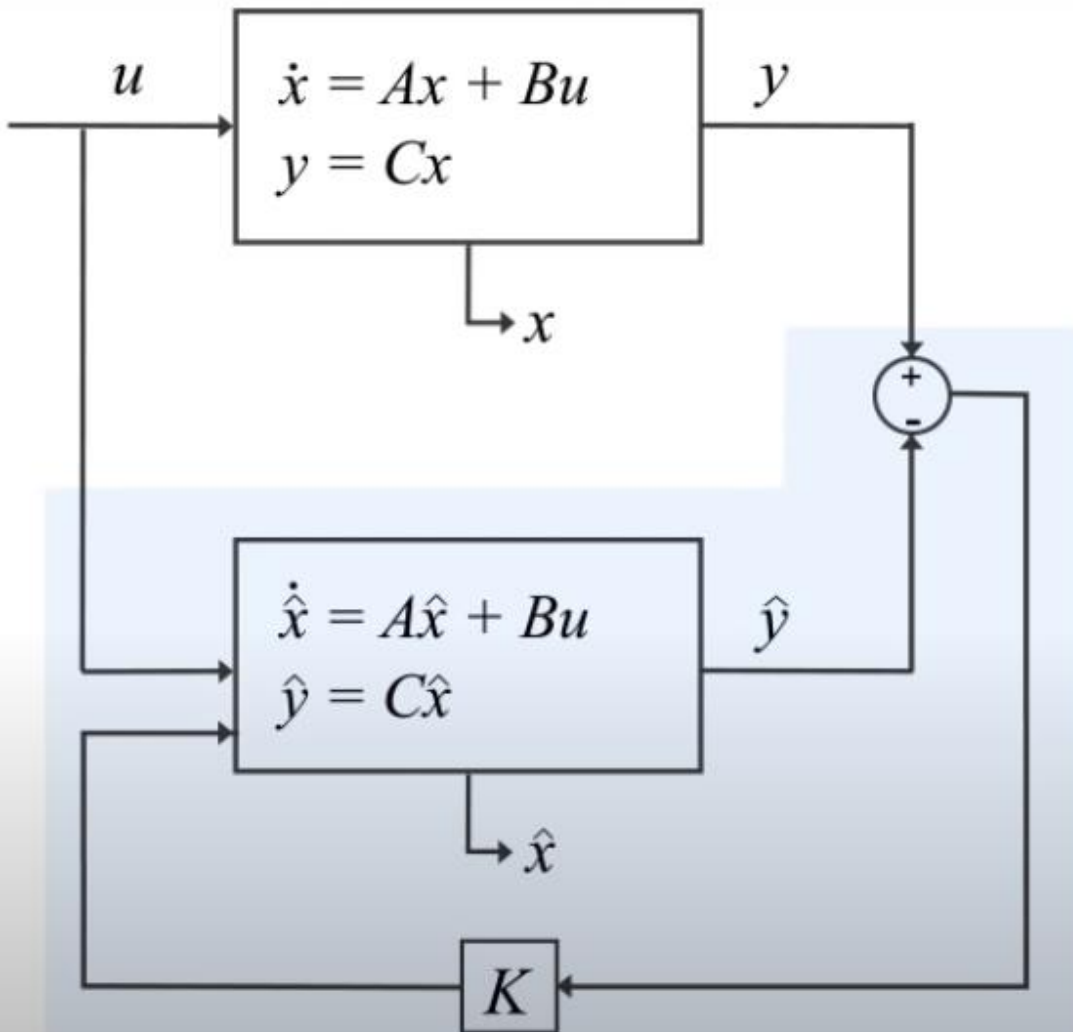
State Observer or State Estimator



State Observer or State Estimator



State Observer or State Estimator



$$e_{obs} = x - \hat{x}$$

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

$$\dot{\hat{x}} = A\hat{x} + Bu + K(y - \hat{y})$$

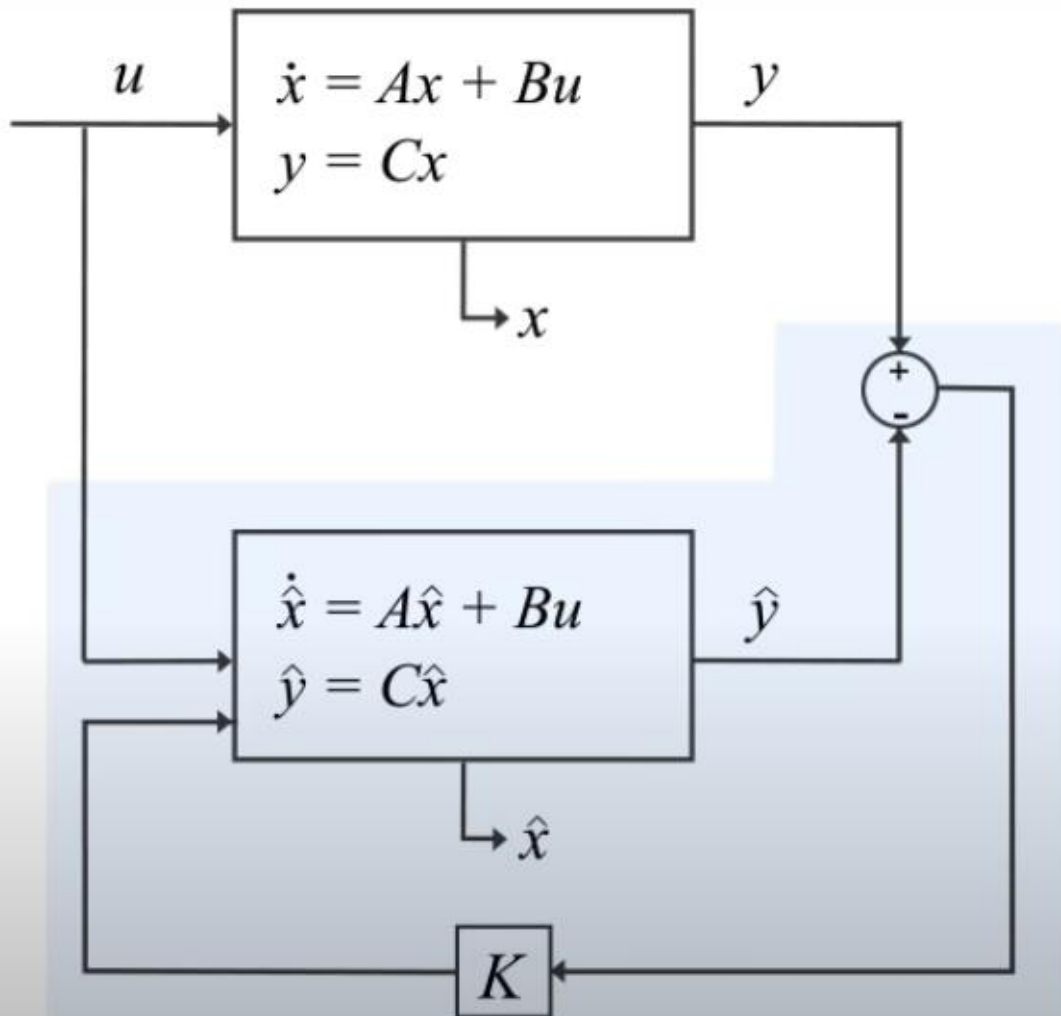
$$\hat{y} = C\hat{x}$$

$$=$$

$$\underbrace{\dot{x} - \dot{\hat{x}}}_{\dot{e}_{obs}} = \underbrace{Ax - A\hat{x}}_{Ae_{obs}} + \underbrace{Bu - Bu}_0 + \underbrace{K(y - \hat{y})}_{K(C(x - \hat{x}))} \quad y - \hat{y} = C \underbrace{(x - \hat{x})}_{e_{obs}}$$

$$\dot{e}_{obs} = Ae_{obs} + Ke_{obs}$$

State Observer or State Estimator



$$e_{obs} = x - \hat{x}$$

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

$$\dot{\hat{x}} = A\hat{x} + Bu + K(y - \hat{y})$$

$$\hat{y} = C\hat{x}$$

$$\begin{aligned} \dot{x} - \dot{\hat{x}} &= \underbrace{Ax - A\hat{x}}_{Ae_{obs}} + \underbrace{Bu - Bu}_0 + \underbrace{K(y - \hat{y})}_{K(C(x - \hat{x}))} & y - \hat{y} &= C(x - \hat{x}) \\ \dot{e}_{obs} &= Ae_{obs} + Ke_{obs} & & e_{obs} \end{aligned}$$

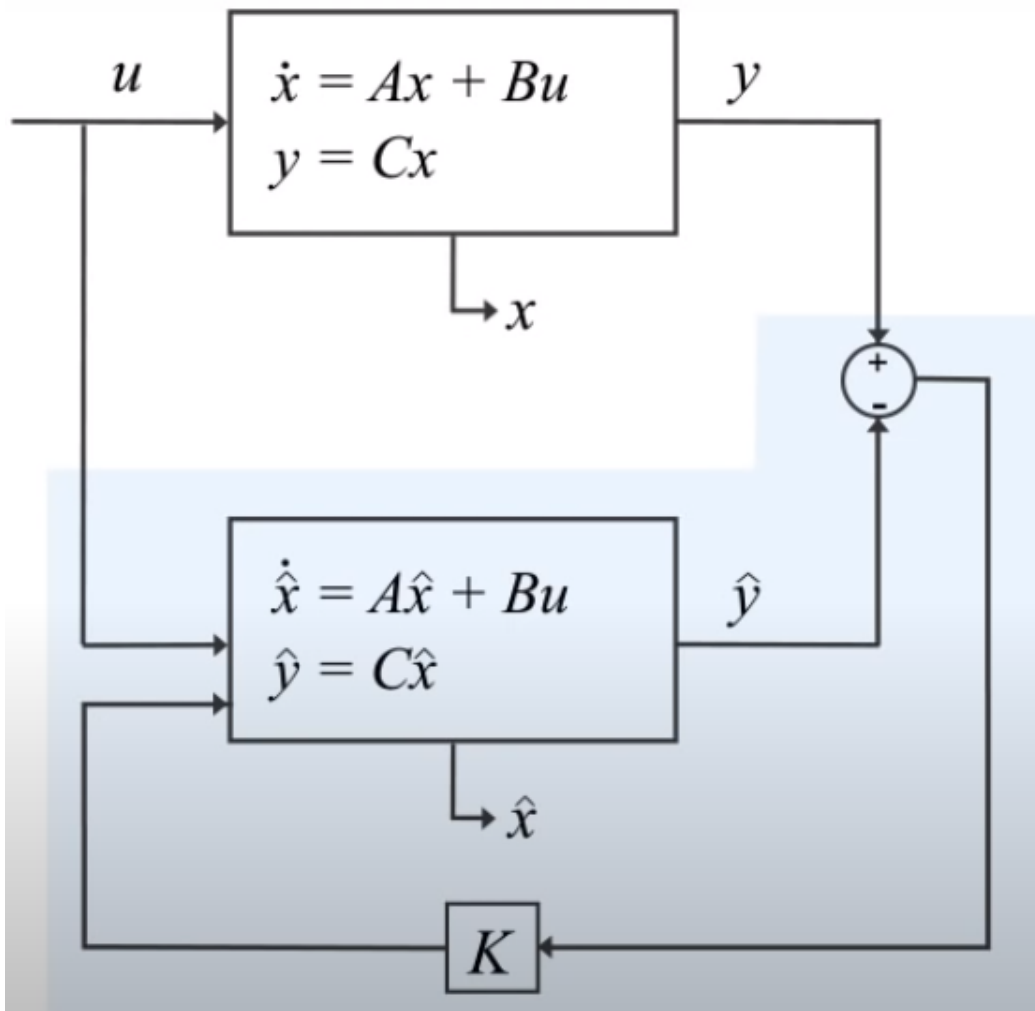
$$\dot{e}_{obs} = (A - KC)e_{obs}$$

$$y - \hat{y} = Ce_{obs}$$

State Observer or State Estimator



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$$e_{obs} = x - \hat{x}$$

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

$$\dot{\hat{x}} = A\hat{x} + Bu + K(y - \hat{y})$$

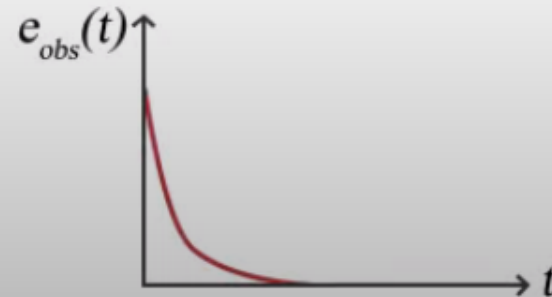
$$\hat{y} = C\hat{x}$$

$$\dot{e}_{obs} = (A - KC)e_{obs}$$

$$y - \hat{y} = Ce_{obs}$$

$$\hookrightarrow e_{obs}(t) = e^{(A - KC)t}e_{obs}(0)$$

If $(A - KC) < 0$, then $e_{obs} \rightarrow 0$ as $t \rightarrow \infty$. So, $\hat{x} \rightarrow x$.



Thank you for your attention