

EnOcean Equipment Profiles (EEP)

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             ■ D2-01-01: Type 0x01 (description: see table)
             ■ D2-01-02: Type 0x02 (description: see table)
             D2-01-03: Type 0x03 (description: see table)
D2-01-04: Type 0x04 (description: see table)
             ■ D2-01-05: Type 0x05 (description: see table)
             ■ D2-01-06: Type 0x06 (description: see table)
             D2-01-07: Type 0x07 (description: see table)
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D2-01-0B: Type 0x0B (description: see table)
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             ■ D2-01-0D: Type 0x0D
             ■ D2-01-0E: Type 0x0E (description: see table)
             ■ D2-01-0F: Type 0x0F (description: see table)
             D2-01-10: Type 0x10 (description: see table)D2-01-11: Type 0x11 (description: see table)
             ■ D2-01-12: Type 0x12 (description: see table)
             ■ D2-01-13: Type 0x13 (description: see table)
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■ D2-01-14: Type 0x14 (description: see table)
 3. D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke
        ■ D2-02-00: Type 0x00
        ■ D2-02-01: Type 0x01 (description: see table)
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        ■ D2-03-10: Mechanical Handle
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        ■ D2-04-01: Type 0x01 (description: see table)
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D2-04-03: Type 0x03 (description: see table)
D2-04-04: Type 0x04 (description: see table)

        ■ D2-04-05: Type 0x05 (description: see table)
        ■ D2-04-06: Type 0x06 (description: see table)
        ■ D2-04-07: Type 0x07 (description: see table)
        ■ D2-04-08: Type 0x08 (description: see table)
        ■ D2-04-09: Type 0x09 (description: see table)

D2-04-10: Type 0x10 (description: see table)
D2-04-1A: Type 0x1A (description: see table)

        ■ D2-04-1B: Type 0x1B (description: see table)
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        ■ D2-04-1D: Type 0x1D (description: see table)
        ■ D2-04-1E: Type 0x1E (description: see table)
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        ■ D2-05-01: Type 0x01 (description: see table)
         ■ D2-05-02: Type 0x02
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        ■ D2-10-02: Type 0x02
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        ■ D2-11-01: Type 0x01

    D2-11-02: Type 0x02 (description: see table)
    D2-11-03: Type 0x03 (description: see table)

        ■ D2-11-04: Type 0x04 (description: see table)
        ■ D2-11-05: Type 0x05 (description: see table)
        ■ D2-11-06: Type 0x06 (description: see table)
        ■ D2-11-07: Type 0x07 (description: see table)
        ■ D2-11-08: Type 0x08 (description: see table)
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        ■ D2-20-00: Type 0x00
        ■ D2-20-01: Type 0x01
        ■ D2-20-02: Type 0x02
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        ■ D2-30-00: Type 0x00

■ D2-30-01: Type 0x01 (description: see table)

■ D2-30-02: Type 0x02 (description: see table)
        ■ D2-30-03: Type 0x03 (description: see table)
■ D2-30-04: Type 0x04 (description: see table)

D2-30-05: Type 0x05 (description: see table)
D2-30-06: Type 0x06 (description: see table)

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        D2-32-00: Type 0x00
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14. D2-33: Intelligent, Bi-directional Heaters and Controllers
        ■ D2-33-00: Type 0x00
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        ■ D2-34-00: 1 Output Channel
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16. D2-40: LED Controller Status
        ■ D2-40-00: Type 0x00
        ■ D2-40-01: Type 0x01
17. D2-50: Heat Recovery Ventilation
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■ D2-50-00: Type 0x00
■ D2-50-01: Type 0x01 (description: see table)
■ D2-50-10: Type 0x10 (description: see table)
■ D2-50-11: Type 0x11 (description: see table)

18. D2-A0: Standard Valve

■ D2-A0-01: Valve Control (BI-DIR)

19. D2-B0: Liquid Leakage Sensor

■ D2-B0-51: Mechanic Harvester

3. Appendix

- 1. RPS Teach-in
- 2. 1BS Teach-in
- 3. 4BS Teach-in
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1) Introduction

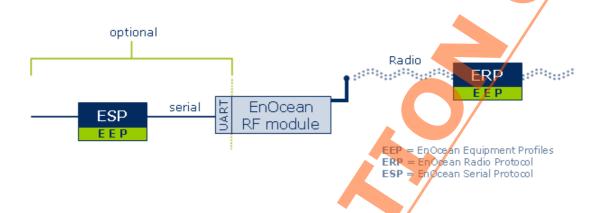
1.1) Terms, Abbreviations

	·
1BS	EnOcean 1 Byte Communication
4BS	EnOcean 4 Byte Communication
BAS	Building Automation System
Choice	Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG
Client	Bidirectional Smart Ack Device
Data	Payload of ERP telegrams or ESP packets
EEP	EnOcean Equipment Profiles
ERP	EnOcean Radio Protocol
ESP	EnOcean Serial Protocol
HTML	Hyper Text Markup Language; HTML can be displayed using a internet browser
MSC	Manufacturer Specific Communication
N/A	Not applicable
ORG	Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface)
RORG	Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice'
RMCC	Remote Management Control Commands
RPC	Remote Procedure Calls
RPS	EnOcean telegram type for Repeated Switch Communication
Smart	Smart Acknowledge EnOcean standard for energy-optimized bidirectional transmission
Ack	
UART	Universal Asynchronous Receiver Transmitter
VLD	EnOcean Variable Length Data telegram
XML	Extensible Markup Language; designed to transport and store data
XSL	Extensible Stylesheet Language; XML based language to visualize XML (data)

1.2) General

The EnOcean radio protocol (ERP) is optimized to transmit information with utmost reliability using extremely little power while ensuring that the products of customers applying EnOcean technology are compatible with each other. Only the very shortest transmission period (< 1ms) for an EnOcean telegram allows the design of, for example, a battery-free radio switch, which can produce a full radio command with just approx. 50 µWs (50 µJ) of energy. At the same time, the reliability of the system increases, as the possibility of data collision is strongly reduced. Every data bit in the radio telegram is essential. For each '0' or '1' state, content descriptions are definied, which must be followed by the sender and the receiver likewise. Depending on the telegram type and the function of the device the user data (payload) is defined in:

EEP (EnOcean Equipment Profiles)



The ERP specification defines the structure of the entire radio telegram. The user data embedded in this structure is defined by the EEP.

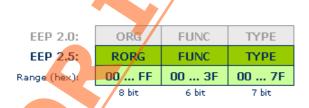
The objective of interoperability is easier to reach with as less profiles as required. Therefore, it is EnOcean Alliance's goal to configure each profile as universally as possible, to target a spectrum of devices in the building automation sector for all manufacturers.

It is of high interest to the EnOcean Alliance that Alliance members verify new devices or newly joined companies verify their products against the existing EEP Profiles and adopt these during testing. Every newly defined EEP would increase diversity and therefore decrease interoperability.

The technical characteristics of a device define three profile elements, which make up the organizational description of all profiles:

- 1. The ERP radio telegram type (RORG)
- 2. Basic functionality of the data content (FUNC)
- 3. Type of device in its individual characteristics (TYPE)

Therefore, every EEP profile has a number, reflecting these three components:



Every field is represented by a hexadecimal number, where the maximum value is limited by the available bits.

Before the definition of a new profile existing profiles should be checked first for suitability. A new profile is to be defined only if the existing profiles would not be adequate.

Once a new profile is to be developed it should be submitted to the TWG of the EnOcean Alliance. The information to

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be provided is

- the XML-data, plus
- the profile as text in a pdf-file (the .pdf-data is to be generated from the XML-data)

The TWG will review and ratify the profile. Following the recommendation by the TWG the BoD will disapprove or approve the profile.

When defining a new profile rules, abbreviations and terms as per this document have to be applied.

To maintain the XML-data and the linked pdf-document in a proper way a document maintenance process is defined. For details refer to appendix 3.14 Data + document maintenance process.

1.3) What's new in EEP 2.6.7?

New VLD profiles:

- D2-34-00: Heating Actuator / 1 Output Channel
 D2-34-01: Heating Actuator / 2 Output Channels
- D2-34-02: Heating Actuator / 8 Output Channels

Modified VLD profile family D2-50-xx:

- Telegram 'Ventilation Control Message' Offset 41: valid range 0...127
- Telegram 'Ventilation Basic Status Message' Offset 40,47,54,61: valid range 0...127
- Telegram 'Ventilation Extended Status Message' Offset 16: valid range / scale modified
- Chapter TYPE 10, 11 -> reference TYPE 00

1.4) Telegram types (RORG)

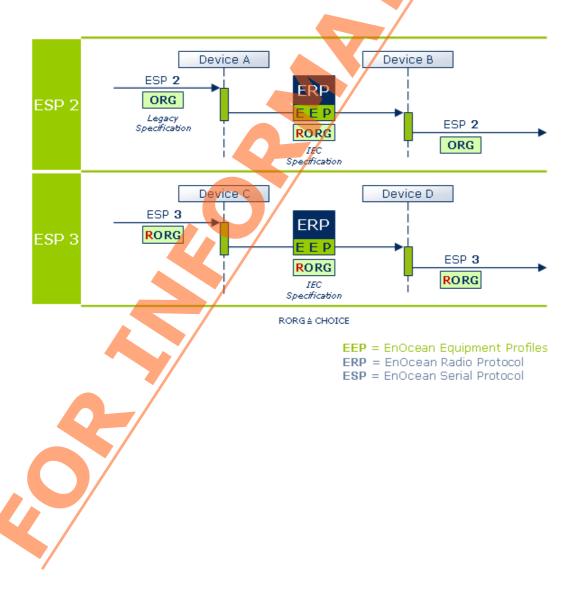
The various Radio-Telegram types are grouped ORGanizationally.

The specifications of ERP (EnOcean Radio Protocol) and of ESP (EnOcean Serial Protocol) group telegram types by 'CHOICE' number. 'RORG' at EEP 2.1(2.5) corresponds to 'CHOICE'.

The following RORG are used in EEP 2.5:

Telegram	RORG	ORG	
RPS	F6	05	Repeated Switch Communication
1BS	D5	06	1 Byte Communication
4BS	A5	07	4 Byte Communication
VLD	D2	=RORG	Variable Length Data
MSC	D1	=RORG	Manufacturer Specific Communication
ADT	A6	=RORG	Adressing Destination Telegram
SM_LRN_REQ	C6	=RORG	Smart Ack Learn Request
SM_LRN_ANS	C7	=RORG	Smart Ack Learn Answer
SM_REC	A7	=RORG	Smart Ack Reclaim
SYS_EX	C5	=RORG	Remote Management
SEC	30	=RORG	Secure telegram
SEC_ENCAPS	31	=RORG	Secure telegram with R-ORG encapsulation

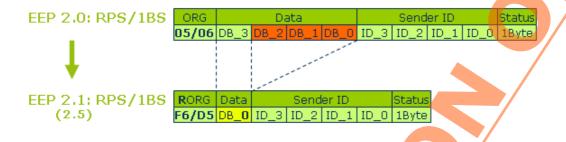
For compatibility reasons, the old ORG values on the serial ESP2 interfaces remain valid. However, on the air interface, each ESP2 telegram is transported with the appropriate RORG (= CHOICE).



1.5) EEP modifications at RPS and 1BS data telegram

Both telegram types carry a one byte payload (DB_0) on the wireless interface (ERP).

EEP 2.0 follows the specification of the serial interface / ESP2, which defines the payload to be carried in DB_3 (see succeeding figure). The trailing bytes, DB_2, DB_1 and DB_0 are marked as 'unused'.



For orthogonal data structural reasons, this deviation will be avoided with EPP 2.1, 2.5 and future versions. The new ESP3 serial interface already respects this.

For reasons of compatibility of end devices, the ESP2 interface remains unaltered, i.e. the DB_0 byte (radio) will continue to be transferred as a DB_3 byte (serial) (including the 3 unused bytes).

The conversation has to happen on the application layer as the XML-data structure of EEP 2.1 / 2.5 only refers to the DB 0 byte.

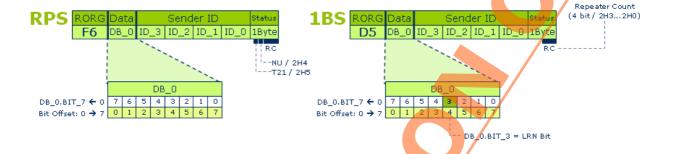
As a consequence of this modification the LRN bit is now described in a row for the 1BS and 4BS telegram types as standardized with the DB_0.BIT_3 position.



EEP 2.6.7 Specification

1.6) Structure and addressing of the telegram types

1.6.1) RPS / 1BS



The RPS and the 1BS telegrams offer only 1 byte user data. These two telegrams differ in the respective learning operations (the 1BS has a LRN bit), and in the way the status byte is used. Comment for RPS status bits:

T21 = 0 = PTM switch module of type 1 / synonymous for module PTM1xx

T21 = 1 = PTM switch module of type 2 / synonymous for module PTM2xx

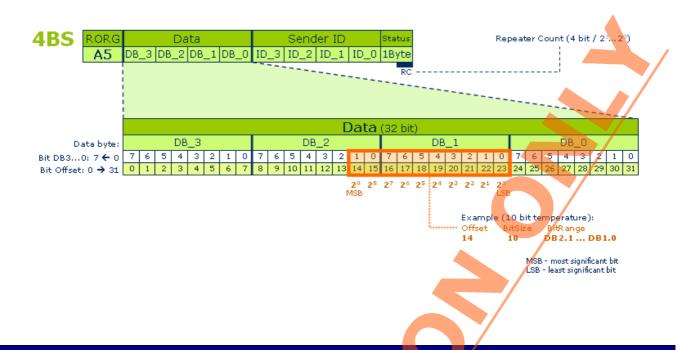
NU = 1 = N-message (N = normal)

NU = 0 = U-message (U = unassigned)

1.6.2) 4BS

A 4BS telegram carries a payload of 4 bytes. The sequence of the 4 data bytes is historically reversed, so that DB_3 appears first and DB_0 last on the radio interface. The bits are addressed in the sequence of the data flow, however (offset). Hence, DB_3.BIT_7 has the offset position 0 and DB_0.BIT_3 (LRN bit) has the offset position 28. The actual content-bits in a byte are not affected by this, i.e., they are described from right (2H0) to left (2H7) in the ascending order.

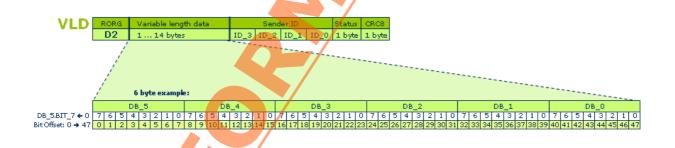
The example of a 10-bit temperature profile (see below) illustrates the binary valuation of the individual bits, so that a number range from 0 ... 1023 can be addressed.



1.6.3) VLD

VLD telegrams carry a variable payload between one and 14 bytes, depending on their design. The teach-in process applies the Smart Ack procedure (see appendices 3.4 and 3.5).

The example following displays a VLD telegram with 6 bytes user data. DB_5.BIT_7 is the first transmitted bit with offset 0.



1.7) Teach-in procedures

The 'Teach-in' defines the mutual communication between wireless devices in an 868 (315) MHz radio network. The 'Teach-in' defines to which transmitter(s) a receiver needs to listen to.

For this purpose of a determined relationship between transmitter and receiver each transmitting device has a unique Sender-ID which is part of each radio telegram. The receiving device detects from the Sender-ID whether the device is known, i.e., was already learned, or unknown.

A telegram with unknown Sender-ID is disregarded.

The 'teach-in' process is different for each telegram type (RPS, 1BS, 4BS, Smart Ack), but the following points are valid for all telegrams:

- First, the receiver must be switched into learning mode. Now, the Sender-ID of an arriving telegram is interpreted as an authorized information source and will be stored at the receiver. The further steps of 'teach-in' are defined by the device type or the telegram type. Thus, normal data telegrams or special teach-in telegrams can be used. Frequently, a learn button triggers the teach-in process.
- The telegram of the respective transmitter should be triggered at least once (by pressing the desired switch

- rocker or triggering a sensor).
- The bits of the payload (data bytes) can have multiple functions depending on the interpretation set by identification or status bits. Only in the 1BS and 4BS telegram the 'LRN BIT' DB_0.BIT_3 is reserved exclusively and must not be used elsewhere.

The following issues are relevant for a number of application but not mandatory for specification perspective:

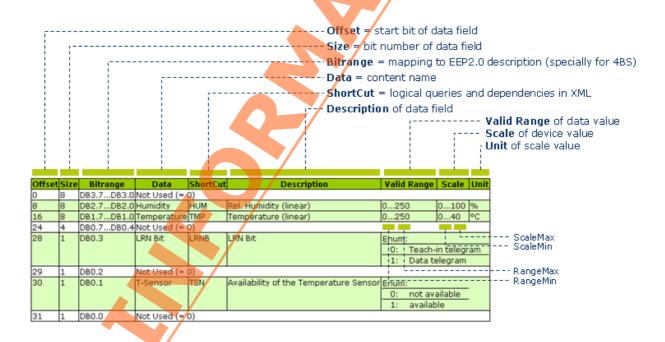
- To prevent unwanted devices from being learned the input sensitivity of the receiver is often restricted, and thus an IN-ROOM operation is created. Typically, the device to be learned is placed close by the receiver.
- Dolphin-based transmitters (e.g. TCM 300 or TCM 2x with Dolphin library) can also be switched into the learn-mode via a remote management command. This remote 'teach-in' mode can only be activated within the first 30 min after receiver power-up. To avoid inadvertent learning the transmitter telegrams have to be triggered 3 times within 2 seconds.

For further details on the 'Teach-in' processes refer to appendices 3.1 to 3.6.

1.8) Viewing XML-data

- The XML-file and all the associated files (CSS, DTD, XSL) and the 'graphics' folder must be stored in the same directory.
- The XML-file is best opened using an Internet browser, generating an HTML-view which displays the describing chapters, graphics and data tables.
- Mozilla Firefox V3.6 or upwards is recommended for optimum screen and print view.

The following example illustrates the HTML-view of the XML-data of a 4BS telegram (= payload of 32 bits).



Data ranges unused are displayed in the table as white rows.

The 'Bit range' column displays the starting-point and the end-point of the respective data.

The 'Valid range', 'Scale' and 'Unit' columns are displayed separately only for measurement values. However, these 3 columns are merged into one if the data comes from an enumeration (enum).

Assuming a linear conversion between the value to be measured and the 'valid range' of data the resolution can be calculated as follows:

Conversion: Valid Range ---> Scale

 $Multiplier = \frac{Scale_{MAX} - Scale_{MIN}}{Range_{MAX} - Range_{MIN}}$

Device value = Multiplier * (rawValue - Range $_{\rm MIN}$) + Scale $_{\rm MIN}$



F6: RPS Telegram

Note for all F6-RPS EEP usage on ERP 2: ERP 2 (EnOcean Radio Protocol 2) is the radio protocol with FSK encoding. It is compatible on the application level with ERP 1. With ERP 2 all EPPs, Protocols (Security / Smart Acknowledge) can be used as it was before. Only difference are the RPS profiles. The ERP 2 (EnOcean Radio Protocol 2) – does not use the RPS telegrams as ERP 1 did. The biggest difference is the usage of the Status Field. The Status field in ERP 2 is defined as a repeater count field (also other position in the telegram). Other functionalities and fields T21 and NU are not present any more. Therefore a new encoding was developed. EEP describe an equipment – device – application. The meaning of the data did not change only the coding. The logic and semantic of the application is still the same. So it is defined that RPS profiles on ERP 2 have different coding of the actual telegram data, but the logic is same on ERP 1 and ERP 2. The new coding is published as new profiles. This is required to keep the same interfaces on the EEP processing (e.g. existing gateways / IP gateways – we do not want have additional information which radio protocol was used – ERP1/ERP2). The exact details are listed below. The profiles are defined in way that a seamless translation between ERP 1 and ERP 2 vice versa is possible without contextual information, what profile it is in particular.

F6-01: Switch Buttons

This profile is used to simple switch design which does not use any rockers. The whole actuation area for the switch is being moved. There are simple two statuses press & hold / released.



RORG	F6	RPS Telegram
FUNC	01	Switch Buttons
TYPE	01	Push Button

Submitter: EnOcean GmbH

Description

This profile represents a very simple push button which has no coding for rockers enabled. Its mechanical construction does not require any coding of rocker status and therefore is not used. It simply sends the energy bow status as push & hold / release. The databyte & status is kept compatible to the F6-02-01 profile, only the energy bow bit is used, status is adjusted to corresponding telegram (no button pressed).

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

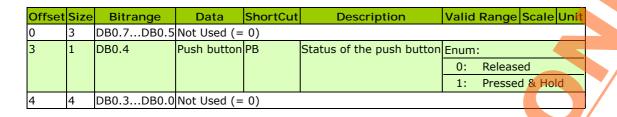
Trigger event: button is pressed / released

Tx delay: -Rx timeout: - Teach-in

Teach-in method: RPS teach-in

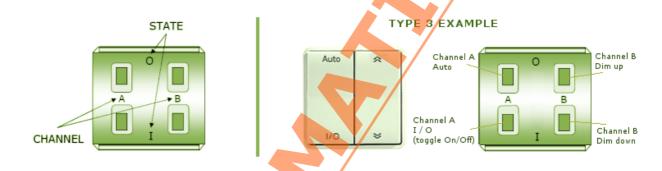
Security

Encryption supported: no Security level format: -



F6-02: Rocker Switch, 2 Rocker

For clarification reasons the following picture shows a PTM200 transmitter module from EnOcean GmbH which transmits RPS telegrams and is one possibility to be used in applications that require an EEP F6-02-xx. Please note that PTM200 does not support transmission of teach-in telegrams.



The button naming used below is referring to CHANNEL and STATE of the PTM200. Thus "Button AI" means STATE "I" on CHANNEL "A".

There are two different message types, the N-message and the U-message, which need to be identified from the Status Field of an EnOcean RPS telegram. For that reason not only the data bytes are given for each EEP but the T21 and NU bits of the Status Field are listed as well.

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitra	nge	Data	ShortCut	Description		Valid Range	Scale	Unit
0	3	DB0.7		Rocker 1st action	R1		0:	: Button AI: "Switch light on" or " "Move blind closed"	Dim light dow	n" or

						1:	Button A0: "Switch light off" or "Dim light up" or "Move blind open" Button BI:
							"Switch light on" or "Dim light down" or "Move blind closed"
						3:	Button B0: "Switch light off" or "Dim light up" or "Move blind open"
	3	1	DB0.4	Energy Bow	EB	 Enum:	
						0:	released
						1:	pressed
Ī	4	3	DB0.3DB0.1	Rocker 2nd	R2	 Enum:	
				action		0:	Button AI: "Switch light on" or "Dim light down" or "Move blind closed"
						1:	Button A0: "Switch light off" or "Dim light up" or "Move blind open"
						2:	Button BI: "Switch light on" or "Dim light down" or "Move blind closed"
						3:	Button B0: "Switch light off" or "Dim light up" or "Move blind open"
	7	1	DB0.0	2nd Action	SA	 Enum: 0: 1:	No 2nd action 2nd action valid

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Datane								
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		3: 30	button or 4 ttons	
3	1	DB0.4	Energy Bow	EB			eased essed	
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6	1	RPS Telegram
FUNC	02		Rocker Switch, 2 Rocker
TYPE	02	Light a	nd Blind Control - Application Style 2

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in an I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset Size Bitrange Data ShortCut Description Valid Range Scale Un	it
---	----

()	3	DB0.7DB0.5	Rocker 1st	R1	 Enum:
				action		0: Button AI: "Switch light on" or "Dim light up" or "Move blind open"
						1: Button A0: "switch light off" or "Dim light down" or "Move blind closed"
						2: Button BI: "Switch light on" or "Dim light up" or "Move blind open"
						3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
1.1	8	1	DB0.4	Energy Bow	EB	 Enum: 0: released 1: pressed
4	1	3	DB0.3DB0.1	Rocker 2nd	R2	 Enum:
				action		0: Button AI: "Switch light on" or "Dim light up" or "Move blind open"
						1: Button A0: "switch light off" or "Dim light down" or "Move blind closed"
						2: Button BI: "Switch light on" or "Dim light up" or "Move blind open"
						3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
7	7	1	DB0.0	2nd Action	SA	 Enum: 0: No 2nd action 1: 2nd action valid

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Jnit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		3: 3 c	button or 4 ctons	
3	1	DB0.4	Energy Bow	EB			eased essed	_
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6		RPS Telegram
FUNC	02		Rocker Switch, 2 Rocker
TYPE	03/	L	ight Control - Application Style 1

Submitter: Servodan

Definition of Auto, I/O for Rocker switch, Dim control (PTM200)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1

3 1 NU 1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Rocker	RA		Enum:			
			action			0x30:	Button A0: Set the controller in a	automatic mod	e
						0x10:	Button A1: Set the controller in r toggles between switch light on and sv	manually mode and	
						0x70:	Button B0: Dim light up		
						0x50:	Button B1: Dim light down		

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RORG	F6	RPS Telegram		
FUNC	02	Rocker Switch, 2 Rocker		
TYPE	04	Light and blind control ERP2		

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range Scale Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum	:
						0:	released
						1:	pressed
1	1	DB0.6	Button coding	BC	Signalize button coding	Enum	:
						0:	button
2	2	DB0.5DB0.4	Not Used (= 0)			
4	1	DB0.3	BI	RBI	State I of the rocker B	Enum	:
						0:	not pressed
						1:	pressed
5	1	DB0.2	В0	RB0	State 0 of the rocker B	Enum	:
						0:	not pressed
						1:	pressed
6	1	DB0.1	AI RAI	RAI	State I of the rocker A	Enum	:
						0:	not pressed
						1:	pressed
7	1	DB0.0	A0	RA0	State 0 of the rocker A	Enum	:
						0:	not pressed
						1:	pressed

F6-03: Rocker Switch, 4 Rocker

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

Datafield:

Datafie Offset		Bitrange	Data	ShortCut	Description	n Valid Range Scale Unit
0		DB0.7DB0.5		R1		Enum:
Ŭ	5	5501711155013	action			0: Button AI:
						"Switch light on" or "Dim light down" or "Move blind closed"
						1: Button A0: "Switch light off" or "Dim light up" or "Move blind open"
						2: Button BI: "Switch light on" or "Dim light down" or "Move blind closed"
						3: Button B0: "Switch light off" or "Dim light up" or "Move blind open"
						4: Button CI: "Switch light on" or "Dim light down" or "Move blind closed"
						5: Button CO: "Switch light off" or "Dim light up" or "Move blind open"
						6: Button DI: "Switch light on" or "Dim light down" or "Move blind closed"
						7: Button D0: "Switch light off" or "Dim light up" or "Move blind open"
3	1	DB0.4	Energy Bow	EB		Enum: 0: released 1: pressed
4	3	DB0.3DB0.1	Rocker 2nd	R2		Enum:
			action			0: Button AI:
						"Switch light on" or "Dim light down" or "Move blind closed"
				4		1: Button A0: "Switch light off" or "Dim light up" or "Move blind open"
						2: Button BI: "Switch light on" or "Dim light down" or "Move blind closed"
						3: Button B0: "Switch light off" or "Dim light up" or "Move blind open"
						4: Button CI: "Switch light on" or "Dim light down" or "Move blind closed"
						5: Button CO: "Switch light off" or "Dim light up" or "Move blind open"
						6: Button DI: "Switch light on" or "Dim light down" or "Move blind closed"
						7: Button D0: "Switch light off" or "Dim light up" or "Move blind open"
7	1	DB0.0	2nd Action	SA		Enum:
						0: No 2nd action
						1: 2nd action valid

Statusfield:

Offset	Size	Data	Value
2	1	T21/	0
3	1	NU	0

Datafield:

Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit

0	3		Number of buttons pressed	R1	 Enum:
			simultaneously		0: no Button pressed
					1: 2 buttons pressed
					2: 3 buttons pressed
					3: 4 buttons pressed
					4: 5 buttons pressed
					5: 6 buttons pressed
					6: 7 buttons pressed
					7: 8 buttons pressed
3	1	DB0.4	Energy Bow	EB	 Enum:
					0: released 1. pressed
4	4	DB0.3DB0.0	Not Used (= 0)		

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	02	Light and Blind Control - Application Style 2

A This EEP definition is based on the assumption that a RPS switch module is installed in a I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	3	B DB0.7DB0.5 Rocker 1st R1		7./	Enum				
			action			0:	Button AI: "Switch light on" or " "Move blind open"	'Dim light up" (or
						1:	Button A0: "Switch light off" or " "Move blind closed"	`Dim light dow	n" or
						2:	Button BI: "Switch light on" or " "Move blind open"	'Dim light up" (or
						3:	Button B0: "Switch light off" or " "Move blind closed"	`Dim light dow	n" or
						4:	Button CI: "Switch light on" or " "Move blind open"	'Dim light up" (or
						5:	Button CO: "Switch light off" or " "Move blind closed"	`Dim light dow	n" or
						6:	Button DI: "Switch light on" or " "Move blind open"	'Dim light up" (or
						7:	Button D0: "Switch light off" or " "Move blind closed"	`Dim light dow	n" or

5	2	1	DB0.4	Energy Bow	ЕВ	Enum:
1	,	1	000.4	Lifergy bow	LD	
						0: released
L						1: pressed
4	1	3	DB0.3DB0.1		R2	 Enum:
				action		0: Button AI:
						"Switch light on" or "Dim light up" or
						"Move blind open"
						1: Button A0:
						"Switch light off" or "Dim light down" or
						"Move blind closed"
						2: Button BI:
						"Switch light on" or "Dim light up" or
						"Move blind open"
						3: Button B0:
						"Switch light off" or "Dim light down" or
						"Move blind closed"
						4: Button CI:
						"Switch light on" or "Dim light up" or "Move blind open"
						5: Button CO:
						"Switch light off" or "Dim light down" or
						"Move blind closed"
						6: Button DI:
						"Switch light on" or "Dim light up" or
						"Move blind open"
						7: Button D0:
						"Switch light off" or "Dim light down" or
						"Move blind closed"
-	7	1	DB0.0	2nd Action	SA	 Enum:
						0: No 2nd action
						1: 2nd action valid
						1: Ziju action vanu

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	0

Datafield:

Datarie	ıu.					
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	3			R1		Enum:
			simultaneously			0: no button pressed
						1: 2 buttons pressed
						2: 3 buttons pressed
						3: 4 buttons pressed
						4: 5 buttons pressed
						5: 6 buttons pressed
						6: 7 buttons pressed
						7: 8 buttons pressed
3	1	DB0.4	Energy Bow	EB		Enum:
						0: released
						1: pressed
4	4	DB0.3DB0.0	Not Used (= 0)			

F6-04: Position Switch, Home and Office Application

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	01	Key Card Activated Switch

Insertion of Key Card generates an N-Message, take-out a U-Message

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

C	Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
C)	8	DB0.7DB0.0	Key Card	KC		Enum:		
							112: inserted	d (0x70)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	8	DB0.7DB0.0	Key Card	KC		Enum	:		
						0:	taken	out	

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	02	Key Card Activated Switch ERP2

Submitter: EnOcean GmbH

When card is inserted field EBO and SOC are both having value 1. When take out, both are having value 0. This coding is required to have a context less translation of RPS profiles between ERP 1 and ERP 2.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum	:		
						0:	taken o	ut	
						1:	card ins	serted	
1	1	DB0.6	Button coding	BC	Signalize button coding	Enum	:		
						0:	button		
2	3	DB0.5DB0.3	Not Used (= 0))					
5	1	DB0.2	State of card	SOC	State of the card	Enum	:		
						0:	taken o	ut	
						1:	card ins	serted	
6	2	DB0.1DB0.0	Not Used (= 0))				•	

F6-05: Detectors

RORG	F6	RPS Telegram
FUNC	05	Detectors
TYPE	00	Wind Speed Threshold Detector

Submitter: ViCOS GmbH

Description

This profile is used to communicate wind speed threshold detection.

The "Alarm ON" message shall be sent when the wind speed exceeds the threshold longer than the specified Delay_Time_AlarmON. If wind speed falls below the specified threshold longer than Delay_Time_AlarmOFF the "Alarm OFF" message shall be sent.

Delay time and threshold have to be set on the device.

Delay_Time_AlarmON: 1 ... 15 s (resolution 1 s) Delay_Time_AlarmOFF: 1 ... 15 min (resolution 1 min)

Threshold: 0 ... 255 km/h

To ensure that the receiver gets the "Alarm On" message under any condition (e.g. AC mains failure), it shall be sent every 60 s in alarm state.

When changing to "Alarm OFF" state the "Alarm OFF" messages shall be sent at least 2 times to avoid losing the "Alarm OFF" signal.

During "Alarm OFF" state the "Alarm OFF" message shall be repeated every 20 minutes.

In case of low energy, the "Energy LOW" message shall be sent every 60 minutes.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered Communication interval: in case of detection

Trigger event: detection

Tx delay: -Rx timeout: -

reacn-in

Teach-in method: RPS teach-in (3 messages within 2s)

Security

Encryption supported: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut		Description	V	alid Range	Scale	Unit
0	8	DB0.7DB0.0	Status				Enum:			
					batte		0x00:	Wind speed belo OFF)	w threshold	(Alarm
							0x10:	Wind speed exce (Alarm ON)	eds thresho	ld
						,	0x30:	Energy LOW		

RORG	F6		RPS Telegram
FUNC	05		Detectors
TYPE	01	Liquid Lea	kage Sensor (mechanic harvester)

Submitter: Afriso / EnOcean

Description:

This profile is used for devices detecting leakage. It is commonly placed on ground where a leakage causes damage. The principle is that "paper rings" swell in water and trigger an ECO 200 (generator) based transmitter.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: NA Trigger event: (water detection) Teach-in method: RPS teach-in

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Water sensor		water leakage	Enum: Wate 0x11: detect		

RORG	F6	RPS Telegram
FUNC	05	Detectors
TYPE	02	Smoke Detector

Submitter: ViCOS GmbH

Description

This profile is used to communicate smoke detection.

The "Alarm ON" message shall be sent immediately when smoke is detected. If smoke detection ends, the "Alarm OFF" message shall be sent.

To ensure that the receiver gets the "Alarm ON" message under any condition (e.g. AC mains failure), it shall be sent every 10 s in alarm state. When changing to "Alarm OFF" state the "Alarm OFF" messages shall be sent at least 2 times to avoid losing the "Alarm OFF" signal.

During "Alarm OFF" state the "Alarm OFF" message shall be repeated every 20 minutes.

In case of low energy, the "Energy LOW" message shall be sent.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered Communication interval: in case of detection

Trigger event: detection

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: RPS teach-in (3 messages within 2s)

Security

Encryption supported: no Security level format: -

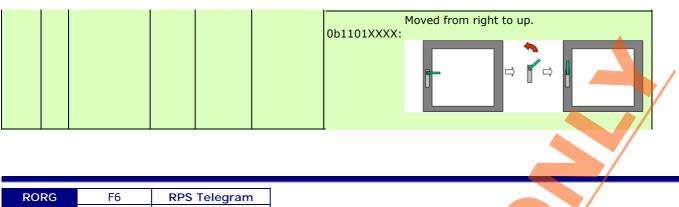
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Status	SMO	Status of detection and battery	Enum:		
						0x00: Smoke A	Alarm Ol	FF.
			, //			0x10: Smoke A	Alarm Ol	V
						0x30: Energy I	_OW	

F6-10: Mechanical Handle

RORG	F6	RPS Telegram	
FUNC	10	Mechanical Handle	
TYPE	00	Window Handle	

Submitter: HOPPE AG

The bits marked with 'X' in DB_0 should not be checked. These bits can be '1' or '0' and should not be assumed to be a defined value, because both of them are allowed and not predictable! Statusfield: Offset Size Data Value T21 1 NU Datafield: Offset Size Bitrange Data ShortCut Description Valid Range Scale Unit DB0.7...DB0.0 Window WIN Movement Enum: of the handle Moved from up to right. window 0b11X0XXXX: handle Moved from right to down. 0b1111XXXX: Moved from down to left. 0b11X0XXXX: Moved from left to up. 0b1101XXXX: Moved from up to left. 0b11X0XXXX: Moved from left to down. 0b1111XXXX: Moved from down to right. 0b11X0XXXX:

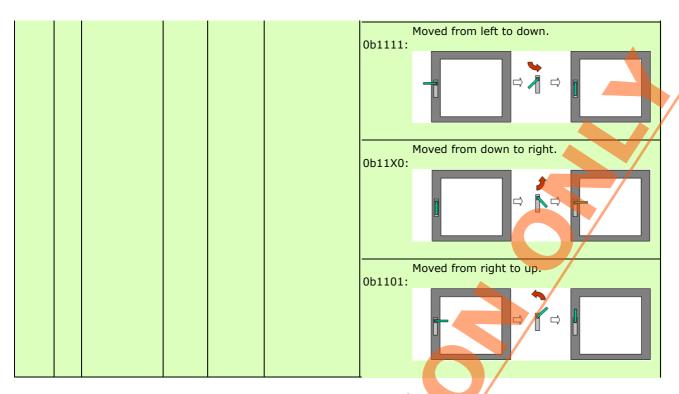


RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
TYPE	01	Window Handle ERP2

Submitter: HOPPE AG

 $\ensuremath{\mathsf{DB0.6}}$ – needs to show that RPS/ERP2 has a different coding as RPS/ERP1.

		Bitrange		ShortCut	Description	Valid Range Scale Unit
0		DB0.7	Not Use			
1	1	DB0.6	Handle	HC	Signalize	Enum:
			coding		window handle coding	1: handle
2	2	DB0.5DB0.4	Not Uso	d (= 0)	county	
		DB0.3DB0.0			Value of the	Enum:
		000.5000.0	value		4MSB of the	Moved from up to right.
					Data field of	0b11X0:
					ERP1 coding	
						Moved from right to down.
						0b1111:
						•
						Moved from down to left. 0b11X0:
						obliko.
						Moved from left to up.
						0b1101:
			4//			
						Moved from up to left.
						0b11X0:
1	/					



D5: 1BS Telegram

D5-00: Contacts and Switches

RORG	D5	1BS Telegram
FUNC	00	Contacts and Switches
TYPE	01	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
4	1	DB0.3	Learn Button	LRN	/	Enum:
						0: pressed
						1: not pressed
7	1	DB0.0	Contact	CO		Enum:
						0: open
						1: closed

A5: 4BS Telegram

A5-02: Temperature Sensors

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	01	Temperature Sensor Range -40°C to 0°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				

16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-400 °C	
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegram	
						1: Data tel	egram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	02	Temperature Sensor Range -30°C to +10°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+10	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	m
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram					
FUNC	NC 02 Temperature Sensor						
TYPE	03 Temperature Sensor Range -20°C to						

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+20	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	04	Temperature Sensor Range -10°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	16	DB3.7DB2.0	Not Used (=	0)						
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-10+30	°C		
24	4	DB0.7DB0.4	Not Used (=	ot Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-	in telegrar	n		
						1: Data to	elegram			
29	3	DB0.2DB0.0	Not Used (=	0)						

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	05	Temperature Sensor Range 0°C to +40°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	06	Temperature Sensor Range +10°C to +50°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear	2550	+10+50	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	1
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	07	Temperature Sensor Range +20°C to +60°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	= 0)				
16	8	DB1.7DB1.0	Temperatur	e TMP	Temperature (linear)	2550	+20+60	°C
24	4	DB0.7DB0.4	Not Used (=	= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		า
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	= 0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	08	Temperature Sensor Range +30°C to +70°C

Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit

0	16	DB3.7DB2.0	Not Used (=	0)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+30+70 °C
24	4	DB0.7DB0.4	Not Used (=	0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach	n-in telegram
						1: Data	telegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	09	Temperature Sensor Range +40°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale /U	Init
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+80 °C	С
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram		
FUNC	02	Temperature Sensor	S	
TYPE	0A	Temperature Sensor Range +50	°C to	+90°C

Offset	Size	Bitrange	Data	ShortC	ut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Te	emperature (linear)	2550	+50+90	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	L	N Bit	Enum:		
							0: Teach-	in telegrar	n
							1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5		4BS Telegram
FUNC	02		Temperature Sensors
TYPE	0B 1	Temperatui	re Sensor Range +60°C to +100°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+60+100	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	10	Temperature Sensor Range -60°C to +20°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-60+20	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	11	Temperature Sensor Range -50°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Descripti	ion	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature	(linear)	2550	-50+30	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
						▼/	0: Teach-	in telegrar	n
							1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	12	Temperature Sensor Range -40°C to +40°C

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
16	DB3.7DB2 <mark>.0</mark>	Not Used (=	0)				
8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-40+40	°C
4	DB0.7DB0.4	Not Used (=	0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-	in telegrar	n
					1: Data t	elegram	
3	DB0.2DB0.0	Not Used (=	0)				
	16 3 4 1	16 DB3.7DB2.0 3 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3	DB3.7DB2.0 Not Used (= 3 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 1 DB0.3 LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 3 DB1.7DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	16 DB3.7DB2.0 Not Used (= 0) 3 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	DB3.7DB2.0 Not Used (= 0)	DB3.7DB2.0 Not Used (= 0) DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 -40+40

RORG		A5	4BS Telegram
FUNC		02	Temperature Sensors
TYPE	/	13	Temperature Sensor Range -30°C to +50°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+50	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)			•	

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	14	Temperature Sensor Range -20°C to +60°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegrar	m
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)		4//		

RORG	A5	4BS Telegram	7	abla	
FUNC	02	Temperature Sensors	5	T	/
TYPE	15	Temperature Sensor Range -10°	C to) 	-70°
		_			_

Offset	Size	Bitrange	Data	ShortCu	ut	Description	Valid R	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)						
16	8	DB1.7DB1.0	Temperature	TMP		Temperature (linear)	2550		-10+70	°C
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB		LRN Bit	Enum:			
							0:	Teach-	in telegrar	n
							1:	Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)						

RORG	A5		7/	4BS Telegram
FUNC	02			Temperature Sensors
TYPE	16	Temp	erat	ture Sensor Range 0°C to +80°C

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
16	DB3.7DB2.0	Not Used (=	0)				
8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+80	°C
4	DB0.7DB0.4	Not Used (=	0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-i	n telegra	m
					1: Data te	legram	
3	DB0.2DB0.0	Not Used (=	0)				
	16 8 4 1	16 DB3.7DB2.0 8 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3	16 DB3.7DB2.0 Not Used (= 8 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 1 DB0.3 LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	16 DB3,7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRN Bit Enum: 0: Teach-i 1: Data te	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 0+80 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRN Bit Enum:

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	17	Temperature Sensor Range +10°C to +90°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)			•	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+10+90	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	1
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	18	Temperature Sensor Range +20°C to +100°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+100	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
				(1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4B\$ Telegram
FUNC	02	Temperature Sensors
TYPE	19	Temperature Sensor Range +30°C to +110°C

Offset	Size	Bitrange /	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)	-	_	_	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+30+110	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
			4 /			0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	7/	A5	4BS Telegram
FUNC		02	Temperature Sensors
TYPE		1A	Temperature Sensor Range +40°C to +120°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+120	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	_
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	1B	Temperature Sensor Range +50°C to +130°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	25 <mark>5</mark> .0	+50+130	°C
24	4	DB0.7DB0.4	Not Used (=	0)	,			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	<u> </u>
29	3	DB0.2DB0.0	Not Used (=	0)				-

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	20	10 Bit Temperature Sensor Range -10°C to +41.2°C
TYPE	20	10 Bit Temperature Sensor Range -10°C to +41.2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5		•/	4BS Telegram
FUNC	02			Temperature Sensors
TYPE	30	10	Bit Te	mperature Sensor Range -40°C to +62.3°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	10230	-40+62.3	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
	1/					1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

A5-04: Temperature and Humidity Sensor

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
TYPE	01	Range 0°C to +40°C and 0% to 100%

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	elegram	
29	1	DB0.2	Not Used (=	0)		_		
30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum:		
						0: not ava	ilable	
						1: availab	le	
31	1	DB0.0	Not Used (=	0)			•	

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
TYPE	02	Range -20°C to $+60$ °C and 0% to 100%

Submitter: Eltako

Description:

In contrast to EEP A5-04-01, the temperature range is extended: -20°C...+60°C.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in temperature, change in humidity

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	-20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	m
						1: Data t	elegram	
29	1/	DB0.2	Not Used (=	0)				

30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum	
						0:	not available
						1:	available
31	1	DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
TYPE	03	Range -20°C to +60°C 10bit-measurement and 0% to 100%

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0255	0100	%
8	6	DB2.7DB2.2	Not Used (= 0)					
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	01023	-20+60	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28 1	28 1 DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in telegram		
						1: Data t	elegram	
29	2	DB0.2DB0.1 Not Used (= 0)						
31	1	DB0.0	Telegram Type	TTP	Telegram Type	Enum:		
						0: Heartbeat		
						1: Event	triggered	

A5-05: Barometric Sensor

RORG	A5	4BS Telegram
FUNC	05	Barometric Sensor
TYPE	01	Range 500 to 1150 hPa

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	6	DB3.7DB3.2	Not Used $(= 0)$)				
6	10	DB3.1DB2.0	Barometer	BAR	Barometer (linear)	01023	5001150	hPa
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Telegram Type	TTP	Telegram Type	Enum:		
						0: Hearth	peat	
						1: Event	triggered	
					•			

A5-06: Light Sensor

RORG	A5	4BS Telegram		
FUNC	06	Light Sensor		
TYPE	01	Range 300lx to 60.000lx		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V	
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	30030000	lx	
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	60060000	lx	
24	4	DB0.7DB0.4	Not Used (= 0)	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in	telegram		
						1: Data tele	gram		
29	2	DB0.2DB0.1	Not Used (= 0)						
31	1	DB0.0	Range select	RS	Range	Enum:			
						0: Range ad	c. to DB_1 (ILL	_1)	
						1: Range ad	cc. to DB_2 (ILL	_2)	

RORG	A5	4BS Telegram		
FUNC	06	Light Sensor		
TYPE	02	Range Olx to 1.020lx		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	01020	lx
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in te	legram	
						1: Data telegr	am	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Range select	RS	Range	Enum:		
						0: Range acc.	to DB_1 (IL	L1)
						1: Range acc.	to DB_2 (IL	L2)

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	03	10-bit measurement (1-Lux resolution) with range 0lx to 1000lx

Submitter: Lutuo Technology

Offset	Size	Bitrange	Data	ShortCut	Description		alid nge	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage (linear) 251255: reserved for error code	025	0	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear) DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	010	00	01000	lx
18	10	DB1.5DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum 0: 1:	Teach telegr		
29	3	DB0.2DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	04	Curtain Wall Brightness Sensor

Submitter: Echoflex Solutions

Description

This EEP is intended for use with wireless daylight sensors, who communicate exterior light levels back to a blind controller.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered and upon lux sensor reading change of more than a few percent

Communication interval: A telegram is transmitted every 1 minute in "day mode" and every 1 hour in "night mode". If the measured light is below a certain threshold for several minutes the sensor goes to night mode.

Trigger event: Heartbeat, change of lux reading

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Temperature	TEMP	Ambient Temperature	0255	-20+60	°C
8	16	DB2.7DB1.0	Illuminance	ILL	Illuminance (linear)	065535	065535	lx
24	4	DB0.7DB0.4	Energy Storage	SV	Energy Storage	015	0100	%
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	n telegram	_
						1: Data tel	egram	
29	1	ĎB0.2	Not Used (= 0)	ot Used (= 0)				

30	1	DB0.1	Temperature	TMPAV Valid temperature data		Enum:
			Availability available on DB3		0: Temperature data is unavailable	
						1: Temperature data is available
31	1		- 5, 5 -		Valid energy storage data	Enum:
			Availability		available on DB0	0: Energy storage data is unavailable
						1: Energy storage data is available

RORG	A5	4BS Telegram		
FUNC	06	Light Sensor		
TYPE	05	Range 0lx to 10.200lx		

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	05100	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	010200	lx
24	4	DB0.7DB0.4	Not Used $(= 0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in to	elegram	
						1: Data teleg	ram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Range select	RS	Range	Enum:		
						0: Range acc	. to DB_1 (IL	L1)
						1: Range acc	. to DB_2 (IL	L2)

A5-07: Occupancy Sensor

RORG <	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	01	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset Size Bitrange Data ShortCut Description Valid Range Scale U	Unit	it
--	------	----

0	8	DB3.7DB3.0	Supply voltage (OPTIONAL)	SVC	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V	
8	8	DB2.7DB2.0	Not Used (= 0)						
16	8	DB1.7DB1.0	PIR Status	PIRS	PIR Status	Enum: 0127: PI 128255: PI	R off R on		
24	4	DB0.7DB0.4	Not Used (= 0)	ot Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram	_	
29	2	DB0.2DB0.1	Not Used (= 0)						
31	1	DB0.0	Supply voltage availability	SVA	Supply voltage availability at DB_3	0: Supply v	oltage is	not	

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	02	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage (REQUIRED)		Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	16	DB2.7DB1.0	Not Used (= 0)					
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum: 0: Uncertai occupan 1: Motion o	cy status	
25	3	DB0.6DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	L RNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram	1
29	3	DB0.2DB0.0	Not Used (= 0)					

RORG	A5		4BS Telegram
FUNC	07		Occupancy Sensor
TYPE	03	Occupan	ncy with Supply voltage monitor and 10-bit illumination measurement

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Supply voltage (REQUIRED)		Supply voltage (linear); 251 – 255 reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear); DB2 = 8 MSB, DB1 = 2 LSB	01000	01000	lx

					1001: over range, 10021024: reserved	
18	6	DB1.5DB1.0	Not Used (= 0)			
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum: 1: Motion detected 0: Uncertain of occupancy status
25	3	DB0.6DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)	•	•	

A5-08: Light, Temperature and Occupancy Sensør

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	01	Range Olx to 510lx, 0°C to +51°C and Occupancy Button

E.g. for ceiling suspended sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		m
						1: Data te	legram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on		
						1: PIR off		
31	1	DB0.0	Occupancy Button	occ		Enum:		
						0: Button	pressed	
						1: Button	released	

RORG	A5		4BS Telegram
FUNC	08	Light,	Temperature and Occupancy Sensor
TYPE	02	Range Olx to :	1020lx, 0°C to +51°C and Occupancy Button

E.g. for wall mounted sensor.

Size	Bitrange		ge	Data	ShortCut	Description	Valid Rang	e Scale	Unit
8	DB3.	7[DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	DB2.	7[DB2.0	Illumination	ILL	Illumination (linear)	0255	01020	lx
8	DB1.	7C	B1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
4	DB0.	7.,.C	B0.4	Not Used (= 0)					
1	DB0.	3		LRN Bit	LRNB	LRN Bit	Enum:		
							0: Teach	-in telegra	m
							1: Data	telegram	
1	DB0.	2		Not Used (= 0)			,		
	8 8 8 4 1	8 DB3. 8 DB2. 8 DB1. 4 DB0. 1 DB0.	8 DB3.7[8 DB2.7[8 DB1.7[8 DB3.7DB3.0 8 DB2.7DB2.0 8 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3	8 DB3.7DB3.0 Supply voltage 8 DB2.7DB2.0 Illumination 8 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit	8 DB3.7DB3.0 Supply voltage SVC 8 DB2.7DB2.0 Illumination ILL 8 DB1.7DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	8 DB3.7DB3.0 Supply voltage SVC Supply voltage (linear) 8 DB2.7DB2.0 Illumination ILL Illumination (linear) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	8 DB3.7DB3.0 Supply voltage SVC Supply voltage (linear) 0255 8 DB2.7DB2.0 Illumination ILL Illumination (linear) 0255 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 0255 4 DB0.7DB0.4 Not Used (= 0) LRN Bit LRN Bit Enum: 0: Teach 1: Data	8 DB3.7DB3.9 Supply voltage SVC Supply voltage (linear) 0255 05.1 8 DB2.7DB2.0 Illumination ILL Illumination (linear) 0255 01020 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 0255 0+51 4 DB0.7DB0.4 Not Used (= 0) LRN Bit LRN Bit Enum: 0: Teach-in telegral 1 DB0.3 LRN Bit LRN Bit DB0.3 DB0.3 </td

30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:	
						0: PIR on	
						1: PIR off	
31	1	DB0.0	Occupancy Button	occ	•••	Enum:	
						0: Button pressed	
						1: Button released	

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	03	Range 0lx to 1530lx, -30°C to +50°C and Occupancy Button

E.g. for outdoor sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	0,5.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01530	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-30+50	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data t	elegram	
29	1	DB0.2	Not Used (= 0)			7/		
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on	 }	
						1: PIR of	f	
31	1	DB0.0	Occupancy Button	осс	/	Enum:		
						0: Button pressed		,
						1: Buttor	released	,

A5-09: Gas Sensor

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	02	CO-Sensor 0 ppm to 1020 ppm

Submitter: Unitronic AG

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Concentration	Conc	Gas concentration	0255	01020	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in teleg	ıram	
	4					1: Data telegram	า	
29	1	DB0.2	Not Used (= 0))				
30	1	DB0.1	T-Sensor	TSN		Enum:		
						0: Temperature : available	Sensor not	
						1: Temperature	Sensor availab	le
31	1	DB0.0	Not Used (= 0))				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	04	CO2 Sensor

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
		DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear), 0.5 % = 1 bit	0200	0100	%
8	8	DB2.7DB2.0	Concentration	Conc	Concentration (linear), increment = 10 ppm	0255	02550	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear), increment = 0.2 °C	0255	0+51.0	°C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegram legram	-
29	1	DB0.2	H-Sensor	HSN		availab	ty Sensor	
30	1	DB0.1	T-Sensor	TSN		availab	ature Sensor	
31	1	DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram		
FUNC	09	Gas Sensor		
TYPE	05	VOC Sensor		

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	VOC	Conc	VOC Concentration	065535	065535	ppb
16	8	DB1.7DB1.0	VOC ID	VOC_ID	VOC identification	Enum:		
						0: VOCT (to	tal)	
						1: Formalde	hyde	
						2: Benzene		
						3: Styrene		
						4: Toluene		
						5: Tetrachlo	roethylene	
						6: Xylene		
						7: n-Hexane	!	
						8: n-Octane		
						9: Cyclopent	tane	
						10: Methanol		
						11: Ethanol		
	ì					12: 1-Pentan	ol	
						13: Acetone		
						14: ethylene		
						15: Acetaldeh		
						16: Acetic Ac		
						17: Propionic		
						18: Valeric Ad		
	7/					19: Butyric A		
						20: Ammonia	С	

					•	,	
						22: Hydrogen Sulfide	
						23: Dimethylsulfide	
						24: 2-Butanol (butyl Alcohol)	
						25: 2-Methylpropanol	
						26: Diethyl ether	
						255: ozone	
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-in telegram	
						1: Data telegram	
29	1	DB0.2	Not Used (= 0)				
30	2	DB0.1DB0.0	Scale Multiplier	SCM	Scale Multiplier	Enum:	
						0: 0.01	
						1: 0.1	
						2: 1	
						3: 10	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	06	Radon

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	10	DB3.7DB2.6	Radon		Radon activity (regulation is an average of 100 Bq/m3/24h)	01023	01023	Bq/m3
10	18	DB2.5DB0.4	Not Use	ed (= 0)				
28	1		LRN Bit	LRNB	LRN Bit	tele	ch-in gram a telegram	1
29	3	DB0.2DB0.0	Not Use	ed (= 0)				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	07	Particles

Submitter: NanoSense

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
9	DB3.7DB2.7	Particles_10	PM10	Dust less than 10 µm (PM10)	0511	0511	µg/m3
9	DB2.6DB1.6	Particles_2.5	PM2.5	Dust less than 2.5 µm (PM2.5)	0511	0511	µg/m3
9	DB1.5DB0.5	Particles_1	PM1	Dust less than 1 µm (PM1)	0511	0511	µg/m3
1	DB0.4	Not Used (=	0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-	in telegr	am
					1: Data t	elegram	
1	DB0.2	PM10 active	PM10a		Enum:		
					0: PM10	not activ	e
					1: PM10	active	
1	DB0.1	PM2.5 active	PM2.5a		Enum:		
					0: PM2.5	not acti	ve
					1: PM2.5	active	,
	9 9 9 1 1	9 DB3.7DB2.7 9 DB2.6DB1.6 9 DB1.5DB0.5 1 DB0.4 1 DB0.3	9 DB3.7DB2.7 Particles_10 9 DB2.6DB1.6 Particles_2.5 9 DB1.5DB0.5 Particles_1 1 DB0.4 Not Used (= 1 DB0.3 LRN Bit 1 DB0.2 PM10 active	9 DB3.7DB2.7 Particles_10 PM10 9 DB2.6DB1.6 Particles_2.5 PM2.5 9 DB1.5DB0.5 Particles_1 PM1 1 DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB 1 DB0.2 PM10 active PM10a	9 DB3.7DB2.7 Particles_10 PM10 Dust less than 10 μm (PM10) 9 DB2.6DB1.6 Particles_2.5 PM2.5 Dust less than 2.5 μm (PM2.5) 9 DB1.5DB0.5 Particles_1 PM1 Dust less than 1 μm (PM1) 1 DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit 1 DB0.2 PM10 active PM10a	DB3.7DB2.7 Particles_10 PM10 Dust less than 10 μm (PM10) 0511	DB3.7DB2.7 Particles_10 PM10 Dust less than 10 μm (PM10) 0511 0511

31	1	DB0.0	PM1 active	PM1a	Enum	:
					0:	PM1 not active
					1:	PM1 active

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	08	Pure CO2 Sensor

Submitter: Afriso / EnOcean

Description

Pure CO2 sensor with 8 bit resolution and 0 – 2000ppm.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: change of value over threshold, heartbeat

Teach-in method: 4BS teach-in 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Use	ed (= 0)				
16	8	DB1.7DB1.0	CO2	CO2	CO2 measurement	0255	02000	ppm
24	4	DB0.7DB0.4	Not Use	ed (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegrai	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Use	ed (= 0)				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	09	Pure CO2 Sensor with Power Failure Detection

Submitter: Afriso / EnOcean

Description

Pure CO2 sensor with 8 bit resolution and 0 - 2000ppm.

1 digital Input – Power failure detection.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: change of value over threshold, heartbeat, change of digital Input

Teach-in method: 4BS teach-in 2

Remark

Power failure detection expresses that the device was cut from power source (unplugged / general power failure) and the device will probably stop functioning very soon. In this case the measured value CO2 is the last valid value.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.	Not Used (= 0)					
16	8	DB1.7DB1.	CO2	CO2	CO2 measurement	0255	02000	ppm
24	4	DB0.7DB0.	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	n-in telegra telegram	ım
29	1	DB0.2	Power Failure detection	PFD	Indicates if power supply has a failure / is not available	Enum: 0: Powe dete	er failure no cted	ot

					1:	Power failure detected	<u> </u>
30	2	DB0.1DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	0A	Hydrogen Gas Sensor

Submitter: SiMICS

Description

Hydrogen Gas Sensor with 16 bit resolution and 0-2000 ppm

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in gas concentration and temp

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: yes

Security level format: PSK, RLC, AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Concentration	Conc	Gas concentration	065535	065535	ppm
16	8	DB1.7DB1.0	Temperature	TEMP	Temperature (linear)	0255	-20+60	°C
24	4	DB0.7DB0.4	Supply voltage	SV	Supply voltage / super cap.	015	2.05.0	V
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegram	_
						1: Data tel	egram	_
29	1	DB0.2	Not Used (= 0)		,			
30	1	DB0.1	Temp sensor	TSA	Temp sensor availability	Enum:		
			availability	·		0: Temp se supporte	nsor is not	
						1: Temp se supporte		
31	1	DB0.0	Supply voltage	SVA	Supply voltage	Enum:		
			availability		availability at SV	0: Supply v	oltage is not	
						1: Supply v	oltage is ed	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	OB-	Radioactivity Sensor

Submitter: SiMICS

Description

Radioactivity Sensor

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in radioactivity level

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: yes

Security level format: PSK, RLC, AES128



RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	0C	VOC Sensor

Submitter: NanoSense

Description

Since this EEP has been released. Total VOC has been regulated by ISO standard. ISO 16000-29 is using weight per cubic metre instead of concentration. This update is for using free bits of this EEP to choose between ppb and µg/m3. Therefore the updated EEP will be compatible with previous version and will provide compliance with ISO standard. Some new VOC have been added in the list especially Naphthalene that will be soon regulated in certain European countries and 4-Phenylcyclohexene because it is part of the LEED (National rating system for sustainable buildings for North America).

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event; value change or time

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

*: For instance, Monthly means the last or the forecast cost of consumption of the last or the next month.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	VOC	Conc	VOC concentration	065535	065535	according to Unit
24		DB1.7DB1.0	Not Used (= 0)	VOC ID	VOC identification	1: Forma 2: Benze 3: Styre 4: Tolue 5: Tetrac 6: Xylen 7: n-Hex 8: n-Oct	ne n	ene ene I Alcohol) ol
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		-in telegra telegram	m_
29	1	DB0.2	Unit		Unit of VOC concentration	Enum: 0: ppb 1: μg/m3	3	
30	2	DB0.1DB0.0	Scale Multiplier	SCM	Scale multiplier	Enum: 0: 0.01 1: 0.1 2: 1 3: 10		

A5-10: Room Operating Panel

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	01	Temperature Sensor, Set Point, Fan Speed and Occupancy Control

Submitter: Kieback + Peter GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	00		Turn-switch for fan speed	FAN	Turn-switch for fan speed	210255; 190209: 165189: 145164:	Stage Auto Stage 0 Stage 1 Stage 2 Stage 3
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telegr 1: Data t	
29	2	DB0.2DB0.1	Not Used (= 0)				
31	1	DB0.0	Occupancy	occ	Occupancy button		n released n pressed

RORG	A5		4	BS Telegram
FUNC	10		Roor	n Operating Panel
TYPE	02	Temperature Sensor,	Set F	Point, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3 <mark>.0</mark>	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:		
			speed			210255: 9	.0	
						190209: 9	Stage 0	
						165189: 9	Stage 1	
						145164: 9	Stage 2	
						0144: 5	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	m
						1: Data te	elegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum:		
					Day/Night	0: Position I / Night Off		it /

	1:	Position O / Day / On
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RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	03	Temperature Sensor, Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Ra	nge :	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				17	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0	255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0	+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ach-in t		m
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	04	Temperature Sensor, Set Point and Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Un	it
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	/	Enum:		
			speed			210255:	Stage Auto	
						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A	4
16	8	DB1.7DB1.0	Temperature /	TMP	Temperature (linear)	2550	0+40 °C	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
			-			0: Teach-in telegram		
						1: Data	telegram	
29	3	DB0.2DB0.0	Not Used (= 0)		·			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	05	Temperature Sensor, Set Point and Occupancy Control
		<u> </u>

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	06	Temperature Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	l Range	Scale	Unit		
0	8	DB3.7DB3.0	Not Used (= 0)								
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	025	5	0255	N/A		
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255	0	0+40	°C		
24	4	DB0.7DB0.4	Not Used (= 0)	t Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:				
						0: Teach-in telegram			า		
						1:	Data tel	egram			
29	2	DB0.2DB0.1	Not Used (= 0)								
31	1	DB0.0	Slide switch	SLSW	Slide switch or Slide switch	Enum	:				
			0/I	4	Day/Night	0:	Position Off	I / Night	/		
						1:	Position On	O / Day ,	/		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	07	Temperature Sensor, Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:	
						210255: S	tage Auto
						190209: S	tage 0
						165189: S	tage 1
						145164: S	tage 2
						0144: S	tage 3
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-ii	n telegram
						1: Data te	legram
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	08	Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:		
			210255; Stage A					
						190209: S	tage 0	
						165189: S	tage 1	
						145164: S	tage 2	
						0144: S	tage 3	
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)	_				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	09	Temperature Sensor, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	/	Enum:		
			speed	//		210255:	Stage Au	to
						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	in telegra	am
						1: Data t	elegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum:		
					Day/Night	0: Positio	on I / Nigh	nt /
						1: Positio	on O / Day	y /

RORG		A5	4BS Telegram
FUNC	7	10	Room Operating Panel
TYPE		0A	Temperature Sensor, Set Point Adjust and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit			
0	8	DB3.7DB3.0	Not Used (= C	ot Used (= 0)							
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C			
24	4	DB0.7DB0.4	Not Used (= 0	ot Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:					
						0: Teach-i	n telegra	m			
						1: Data te	legram				
29	2	DB0.2DB0.1	Not Used (= 0	1)							
31	1	DB0.0	Contact State	CTST	Contact state	Enum:					
						0: closed					
						1: open					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0B	Temperature Sensor and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255) /	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:		n telegra legram	m
29	2	DB0.2DB0.1	Not Used (= 0))					
31	1	DB0.0	Contact State	CTST	Contact state	Enum: 0: 1:	closed open		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0C	Temperature Sensor and Occupancy Control

0661	C:	Dituonos	Data	Ch dut Cut	Decemination	Valid Danse	Caala	11
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1 <mark>.0</mark>	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0D	Temperature Sensor and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ir 1: Data te	n telegram egram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Slide switch		Slide switch 0/I or Slide switch Day/Night	Off	I / Night of O / Day /	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	10	Temperature and Humidity Sensor, Set Point and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ii	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5			47	4BS Telegram
FUNC	10				Room Operating Panel
TYPE	11	Temperatu	re and J	lum	nidity Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
	4					0: Teach-ir	n telegran	n
						1: Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:		
					Day/Night	0: Position Off	I / Night	/
						1: Position On	O / Day ,	/

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	12	Temperature and Humidity Sensor and Set Point

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%//
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

FUNC 10 Room Operating Panel			
10 Room Operating Failer			
TYPE 13 Temperature and Humidity Sensor, Occ	cupancy (Contro	οl

Offset	Size	Bitrange	Data	ShortCut	Description	on	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)					
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity ((linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (I	inear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-in telegram		
				4			1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)					
31	1	DB0.0	Occupancy	OCC	Occupancy but	ton	Enum:		
							1: Button	released	
							0: Button	pressed	

RORG	A5	ABS Telegram
FUNC	10	Room Operating Panel
TYPE	14	Temperature and Humidity Sensor, Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description Valid Range		Scale	Unit			
0	8	DB3.7DB3.0	Not Used (=	t <mark>U</mark> sed (= 0)							
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C			
24	4	DB0.7DB0.4	Not Used (=	0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:					
						0: Teach-in to		elegram			
						1: Data te	egram				
29	2	DB0.2DB0.1	Not Used (=	0)							
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:					
					Day/Night	0: Position	I / Night	/			
						Off					
						1: Position	O / Day /	/			
						On					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	15	10 Bit Temperature Sensor, 6 bit Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	6	DB2.7DB2.2	Set point		Set point (6 bit, linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		-in telegram telegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	16	10 Bit Temperature Sensor, 6 bit Set Point Control; Occupancy Control

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
8	DB3.7DB3.0	Not Used (=	0)				
6	DB2.7DB2.2	Set point	SP	Set point (linear) Min Max+	063	063	N/A
10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
4	DB0.7DB0.4	Not Used (=	0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-	in telegram	
					1: Data t	elegram	
2	DB0.2DB0.1	Not Used (=	0)				
1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
					1: Button	released	_
					0: Button	pressed	_
	8 6 10 4 1	8 DB3.7DB3.0 6 DB2.7DB2.2 10 DB2.1DB1.0 4 DB0.7DB0.4 1 DB0.3	8 DB3.7DB3.0 Not Used (= 6 DB2.7DB2.2 Set point 10 DB2.1DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 1 DB0.3 LRN Bit 2 DB0.2DB0.1 Not Used (=	8 DB3.7DB3.0 Not Used (= 0) 6 DB2.7DB2.2 Set point SP 10 DB2.1DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB 2 DB0.2DB0.1 Not Used (= 0)	8	8 DB3.7DB3.0 Not Used (= 0) 6 DB2.7DB2.2 Set point SP Set point (linear) Min Max+ 063 10 DB2.1DB1.0 Temperature TMP Temperature 10 bit (linear) 10230 4 DB0.7DB0.4 Not Used (= 0) LRN Bit LRN Bit LRN Bit Enum: 0: Teach-1: Data to 1: Da	8 DB3.7DB3.0 Not Used (= 0) 6 DB2.7DB2.2 Set point SP Set point (linear) Min Max + 063 063 10 DB2.1DB1.0 Temperature TMP Temperature 10 bit (linear) 10230 -10+41.2 4 DB0.7DB0.4 Not Used (= 0) Enum:

RORG	A5		4BS Telegram
FUNC	10		Room Operating Panel
TYPE	17	10 Bit Tem	perature Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	t Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		
29	2	ĎB0.2…DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum: 1: Buttor	n released	_

0: Button pressed

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	18	Illumination, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control	_

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
		DB2.7DB2.0	Temp Setpoint	TMPSP	Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25		DB0.6DB0.4	Fan Speed	FAN	Fan Speed LRN Bit	2: Sr 3: Sr 4: Sr 5: Sr	peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
20	1	550.3	LINV DIC	LIND	ENV DIC	0: Te te 1: Da	ach-in legram ata legram	
29	1	DB0.2	Not Used (= 0)					
30	1		Occupancy enable/disable	OED	Occupancy enable/disable; if occupancy is disabled ignore DB0.0 (occu. button)	1: Od	ccupancy abled ccupancy sabled	
31	1	DB0.0	Occupancy button	OB		1: Bu	itton essed itton leased	

RORG	A5		4BS Telegram
FUNC	10		Room Operating Panel
TYPE	19	Humidity, T	emperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Temp Setpoint		Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum:		
	/					0: Auto		
						1: Speed	0	
						2: Speed	1	

						3:	Speed 2	
						4:	Speed 3	
						5:	Speed 4	
						6:	Speed 5	
						7:	Off	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:	
						0:	Teach-in telegram	\ //
						1:	Data telegra	m
29	1	DB0.2	Not Used (= 0)	•				
30	1	DB0.1	Occupancy button	ОВ		Enum 0:	Button press	ed
						1:	Button releas	_
31	1	DB0.0	Occupancy	OED		Enum		
			enable/disable			0:	Occupancy	
							enabled	
						1:	Occupancy disabled	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1A	Supply voltage monitor, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Scale	Unit
0	8		Supply Voltage	SV	0 5.0 V linear (super cap); 251-255 reserved for error code	Range 0250	05	V
8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set Point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)		1			
25	3	DB0.6DB0.4	Fan speed	FAN	F an Speed	1: Sp 2: Sp 3: Sp 4: Sp 5: Sp	peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
28		DB0.3	LRN Bit	LRNB	LRN Bit	te	ach-in legram ata telegra	m
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		1: O	ccupancy labled ccupancy sabled	
31	1	DB0.0	Occupancy button	ОВ		1: Bu	itton essed itton leased	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1B	Supply Voltage Monitor, Illumination, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	SV	(super cap) 251 – 255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	1	DB0.6DB0.4	Fan speed	FAN	Fan Speed	2: Sp 3: Sp 4: Sp 5: Sp 6: Sp 7: Of Enum: 0: Te tel	eed 0 eed 1 eed 2 eed 3 eed 4 eed 5	n
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.2 DB0.1	Occupancy	OED 📐		Enum:		
30	_	553.1	enable/disable			0: Oc	cupancy abled	
							cupancy sabled	
31	1	DB0.0	Occupancy button	ОВ		Enum:		
						pre	tton essed	
						_	tton eased	

RORG	A5				4BS Telegram
FUNC	10				Room Operating Panel
TYPE	1C	III	umin	ation, I	Illumination Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination		Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8		Illumination Set Point	ILLSP		0250	01000	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN		•	ed 0 ed 1	

						3: 4: 5: 6:	Speed 2 Speed 3 Speed 4 Speed 5
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	7: Enum 0: 1:	Off : Teach-in telegram Data telegram
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Occupancy enable/disable	OED		0: 1:	
31	1	DB0.0	Occupancy button	ОВ		0; 1:	Button pressed Button released

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1D	Humidity, Humidity Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Humidity Set Point	HUMSP	Humidity Set Point (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24		DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 2: Speed 3: Speed 4: Speed 5: Speed 6: Speed 7: Off	1 2 3 4	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegrar legram	m
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		0: Occupa enabled 1: Occupa disable	ncy	
31	1	DB0.0	Occupancy button	ОВ			pressed released	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel



RORG A5 4BS Telegram FUNC 10 Room Operating Panel	
FUNC 10 Room Operating Panel	
10011 operating tand	
TYPE 1F Temperature Sensor, Set Point, Fan Speed, Occupancy and Unoccupancy Con	rol

Submitter: Distech Controls

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit			
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:			
			speed			210255: Stage auto			
						1902 <mark>0</mark> 9: Stage 0			
						165189: Stage 1			
						145164: Stage 2			
						0144: Stage 3			
8	8	DB2.7DB2.0	Set Point	SP	Set point (linear) Min Max+	0255 0255 N/A			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550 0+40 °C			
24	1	DB0.7	Not Used (= 0)						
25	1	DB0.6	Temperature flag	emperature flag TMP_F Temperature flag	Temperature flag	Enum:			
					1: Temperature present				
						0: Temperature absent			
26	1	DB0.5	Set point flag	SP_F	Set point flag	Enum:			
						1: Set point present			
						0: Set point absent			
27	1	DB0.4	Fan speed flag	FAN_F	Fan speed flag	Enum:			
						1: Fan speed present			
			•			0: Fan speed absent			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in telegram			
						1: Data telegram			
29	1	DB0.2	Not Used (= 0)	5/					
30	1	DB0.1	Unoccupancy	UNOCC	Unoccupancy button	Enum:			
						0: Button pressed			
						1: Button released			
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:			
						0: Button pressed			
						1: Button released			

RORG	A5		4BS Telegram
FUNC	10		Room Operating Panel
TYPE	20	Temp	erature and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, User Activity.

This EEP defines a Room Operating Panel that contains a sensor for temperature measurement. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication intervall: 1200 s Trigger event: change of any input signal

Tx delay: n/a

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: 4BS teach-in 2 / Universal teach-in

Security Encryption supported: no

Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Set Point	SP	Set point (linear) Min Max+	0255	0255 N/A
8	8	DB2.7DB2.0	Not Used (= 0)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40 °C
24	1	DB0.7	Not Used (= 0				
25	2	DB0.6DB0.5	Set point mode	SPM	Selection of heating mode	SP 1: Frost protect	ontrol (e.g. defined
27	1	DB0.4	Battery state	BATT	Battery change needed	0: Battery ok 1: Battery low	_
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in tele 1: Data telegra	
29	2	DB0.2DB0.1	Not Used (= 0)			
31	1	DB0.0	User activity	ACT	User intervention action on device	Enum: 0: No user action 1: User interaction	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	21	Temperature, Humidity and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, Humidity, User Activity.

This EEP defines a Room Operating Panel that contains sensors for temperature and humidity. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication intervall: 1200 s Trigger event: change of any input signal

Tx delay: n/a

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: 4BS teach-in 2 / Universal teach-in

Security Encryption required: no

Security level format: -

Offset	Siz	e	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		DB3.7DB3.0	Set Point		Set point (linear) Min Max+	0255	0255	N/A
8	8	I	DB2.7DB2.0	Humidity	HUM	Rel. humidity (linear)	0250	0100	%
16	8	I	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C

24	1	DB0.7	Not Used (= 0)		
25	2	DB0.6DB0.5	Set point mode	SPM	Selection of heating mode	Enum: 0: Room temperature defined by SP 1: Frost protection 2: Automatic control (e.g. defined by time program) 3: Reserved
27	1	DB0.4	Battery state	BATT	Battery change needed	Enum: 0: Battery ok 1: Battery low
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in-telegram 1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0)		
31	1	DB0.0	User activity	ACT	User intervention action on device	0: No user action 1: User interaction

RORG	A5	4BS Telegram		
FUNC	10	Room Operating Panel	Z	
TYPE	22	Temperature, Setpoint, Humidity and F	an	Speed

Submitter: Thermokon Sensortechnik GmbH

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: time-triggered (configurable at the device) & event-triggered

Trigger event: setpoint change, fan speed change

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Product Description

The device represented by this EEP is a "Room Operating Panel with Display". It is powered by solar cell.

It is equipped with the following features:

- Temperature Sensor
- Humidity Sensor
- Temperature Setpoint Adjustment
- Fanspeed Adjustment

For pairing the unidirectional "4BS Teach-In Variation 2" method is used.

The device transmits the actual sensor values periodically (Default: 1000s) or on an event like "Temperature Setpoint Adjustment" or "Fanspeed Adjustment".

Temperature Sensor, Humidity Sensor:

The environmental sensors are updated periodically (adjustable, default: 100s) and, if there is a change, the updated values will be send immediately.

Offset	Si	ze	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		DB3.7DB3.0	Relative Setpoint	SP	Setpoint (linear) Min Max+	0255	0255	N/A
8	8		DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%

16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250 0+40 °C
24	3	DB0.7DB0.5	Fanspeed	FAN	Fanspeed	Enum:
						0: Auto
						1: Speed 0 / OFF
						2: Speed 1
						3: Speed 2
						4: Speed 3
						5 7: Reserved
27	1	DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	23	Temperature, Setpoint, Humidity, Fan Speed and Occ	upancy

Submitter: Thermokon Sensortechnik GmbH

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: time-triggered (configurable at the device) & event-triggered

Trigger event: setpoint change, fan speed change, change of occupancy-state

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Product Description

The device represented by this EEP is a "Room Operating Panel with Display". It is powered by solar cell.

It is equipped with the following features:

- Temperature Sensor
- Humidity Sensor
- Setpoint Adjustment
- Fanspeed Adjustment
- Occupancy-State Adjustment

For pairing the unidirectional "4BS Teach-In Variation 2" method is used.

The device transmits the actual sensor values periodically (Default: 1000s) or on an event like "Setpoint Adjustment" or "Fanspeed Adjustment".

Temperature Sensor, Humidity Sensor:

The environmental sensors are updated periodically (adjustable, default: 100s) and, if there is a change, the updated values will be send directly.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Relative Setpoint	SP	Setpoint (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	3	DB0.7DB0.5	Fanspeed	FAN	Fanspeed	Enum:		
						0: Auto		
						1: Spee	d 0 / OFF	=
						2: Spee	d 1	
						3: Spee	d 2	

						4: Speed 3 5 7: Reserved
27	1	DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0)			
31	1	DB0.0	Occupancy	occ	Occupancy	Enum: 0: Unoccupied 1: Occupied

A5-11: Controller Status

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	01	Lighting Controller

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
8	8	DB2.7DB2.0	Illumination Set Point	ISP	Illumination Set Point (Min Max.) (linear)	0255	0255	N/A
16	8	DB1.7DB1.0	Dimming Output Level	DIM	Dimming Output Level (Min Max.) (linear)	0255	0255	N/A
24	1	DB0.7	Repeater	REP	Repeater	Enum: 0: disab 1: enab		
25	1	DB0.6	Power Relay Timer	PRT	Power Relay Timer	Enum: 0: disab 1: enab		
26	1	DB0.5	Daylight Harvesting	DHV	Daylight Harvesting	Enum: 0: disab 1: enab		
27	1	DB0.4	Dimming	EDIM	Dimming		hing load	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach teleg 1: Data		n
29	1	DB0.2	Magnet Contact	MGC	Magnet Contact	Enum: 0: open 1: close		
30	1	DB0.1	Occupancy	occ	Occupancy	Enum: 0: unoco 1: occup	cupied pied	_
31	1	DB0.0	Power Relay	PWR	Power Relay	Enum: 0: off 1: on		

RORG	A5	4BS Telegram
FUNC	11	Controller Status

Temperature Controller Output 02

<u>Submi</u>	tter: T	Thermokon Sen	isortechnik Gn	<u>nbH</u>			(
Offset	Sizo	Bitrange	Data	ShortCut	Description	Valid	Scale	Unit
0	8	DB3.7DB3.0	Control	CVAR	Actual value of controller	Range 0255	0100	%
8	8	DB2.7DB2.0	Variable FanStage	FAN	Actual value of fan	1: Stag 2: Stag 3: Stag 16: Stag 17: Stag 18: Stag	e 0 Manual e 1 Manual e 2 Manual e 3 Manual e 0 Automat e 1 Automat e 2 Automat e 3 Automat Available	ic ic
16	8	DB1.7DB1.0	Actual Setpoint	ASP	Occupied: Basic setpoint occupied + Setpoint shift + Sensor offset StandBy: Basic setpoint standBy + Setpoint shift Unoccupied: Basic setpoint unoccupied + setpoint shift	0255	0+51.2	°C
24	1	DB0.7	Alarm	ALR	In case of internal error alarm is set	Enum: 0: No al 1: Alarn		
25	2	DB0.6DB0.5	Controller mode	СТМ	Actual state of controller	Enum: 1: Heat 2: Cooli 3: Off		
27	1	DB0.4	Controller state	CST	Automatic control, or is controlled from another device	Enum: 0: Auto 1: Over	matic ride	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	n-in telegran telegram	n
29	1	DB0.2	Energy hold-off	ERH	Stop control if window is opened		nal gy hold-off/ point	
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum: 0: Occu	pied cupied dBy	

RORG	A5	4BS Telegram
FUNC	1/1	Controller Status
TYPE	03	Blind Status

Submitter: PEHA / infratec

This controller status is specific for blinds, awning and shutter modules. All modules can use this 4BS telegram to send all information about the status, the position and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Blind/shutter pos.	BSP		0100	0100	%
8	1	DB2.7	Angle sign	AS		Enum:		
						0: Positive sign		
						1: Negative sign	1	
9	7	DB2.6DB2.0	Angle	AN	Angle in 2° steps (e.g. 0 = 0°, 90 = 180°) (EEP 2.6.5: valid range 0 180 -> 0 90 scale 0 360 -> 0 180)	090	0180	°
16	1	DB1.7		PVF		Enum:		
			flag			0: No Position v	alue available	<u> </u>
						1: Position value	e available	
17	1	DB1.6	Angle value flag	AVF		0: No Angle value a		_
18	2	DB1.5DB1.4	Error state	ES		Enum:		
						0: No error pres		
						configured	are not	
						2: Internal failu	re	
						3: Not used		
20	2	DB1.3DB1.2	End-position	EP		Enum:		
						0: No End-positi	on available	
						1: No End-positi	on reached	
						2: Blind fully op	en	
						3: Blind fully clo	sed	
22	2	DB1.1DB1.0	Status	ST		Enum:		
						0: No Status ava	ailable	
						1: Blind is stopp	ed	
						2: Blind opens		
						3: Blind closes		
24	1	DB0.7	Service Mode	SM		Enum:		
						0: Normal mode	:	
						1: Service mode example for r		
25	1	DB0.6		МОТР		Enum:		
			position			0: Normal mode 0% Blind fully Blind fully clo	open / 100 ^o	%
		4				1: Inverse mode 100% Blind f Blind fully clo	ully open / 0°	%
26	2	DB0.5DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in tele	gram	
						1: Data telegrar	n	
29	3	DB0.2DB0.0	Not Used (= 0)					
								·

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	04	Extended Lighting Status

Submitter: PEHA / infratec

This status is an extended answer of new lighting-controllers. All modules can use this 4BS telegram to send all information about the status and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0		DB3.7DB3.0		P1	Description	Enum:
		333771133313	r drameter 1			Mode 0: Dimm-Value (0 255) Mode 1: R - Red (0 255) Mode 2: Energy metering value (MSB 15 8) Mode 3: Not used
8	8	DB2.7DB2.0	Parameter 2	P2		Enum:
						Mode 0: Lamp operating hours (MSB 15 8) Mode 1: G - Green (0 255) Mode 2: Energy metering value (7 0 LSB) Mode 3: Not used
16	8	DB1.7DB1.0	Parameter 3	P3		Enum: Mode 0: Lamp operating hours (7 0 LSB) Mode 1: B - Blue (0 255) Mode 2: Unit for energy values: Enum: 0 = mW 1 = W 2 = kW 3 = MW 4 = Wh 5 = kWh 6 = MWh 7 = GWh 8 = mA 9 = 1/10 A 10 = mV 11 = 1/10 V 12 15 Not used
						Mode 3: Not used
24	1	DB0.7	Service Mode	SM		Enum: 0: Normal mode 1: Service mode is activated. (For example for maintenance)
25	1		Operating hours flag	OHF	For Mode 0	Enum: 0: No lamp operating hours available 1: Lamp operating hours available
26	2	DB0.5DB0.4	Error state	F S		Enum: 0: No error present 1: Lamp-failure 2: Internal failure 3: Failure on the external periphery
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Parameter Mode	PM		Enum: 0: 8 Bit Dimmer Value and Lamp operating hours 1: RGB Value 2: Energy metering value 3: Not used
31	1	DB0.0	Status	ST		Enum: 0: Lighting off 1: Lighting on

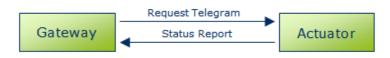
RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	05	Dual-Channel Switch Actuator (BI-DIR)

Submitter: Nanjing Putian Telecommunications CO., Ltd.,

Description

This EEP is used for sending the latest relay status (including current working mode) of a dual-channel switch actuator. The telegram is sent when the relay status changes or a gateway request is received. Each time the gateway is powered on, it will send a request telegram to request that the actuator reports its latest relay status, while in normal working state, it won't send any telegram to the actuator and only receive the relay status from the actuator.

1) Gateway first power on:



2) When the actuator receives a switch telegram and its status changes:



Data exchange

Direction: bi-directional Addressing: broadcast

Communication trigger: event & request

Communication interval: -

Trigger event: change of relay status

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format:

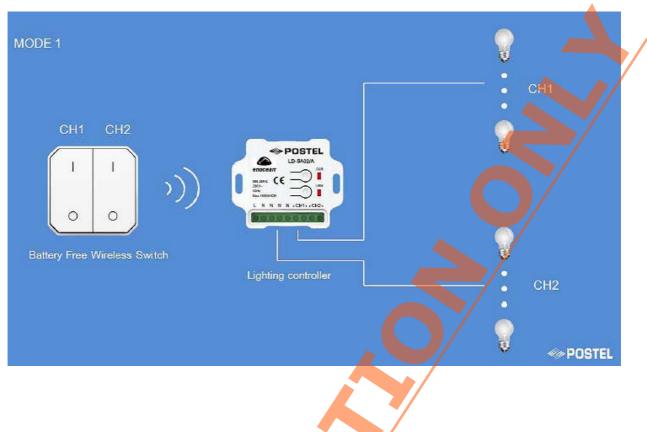
Appendix

Operation mode description:

Mode 1:

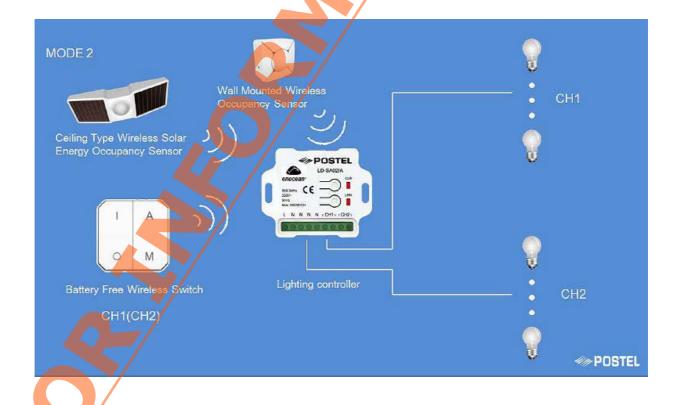
One switch controls one dual-channel actuator. Each rock controls one channel.

I: power ON, O: power OFF



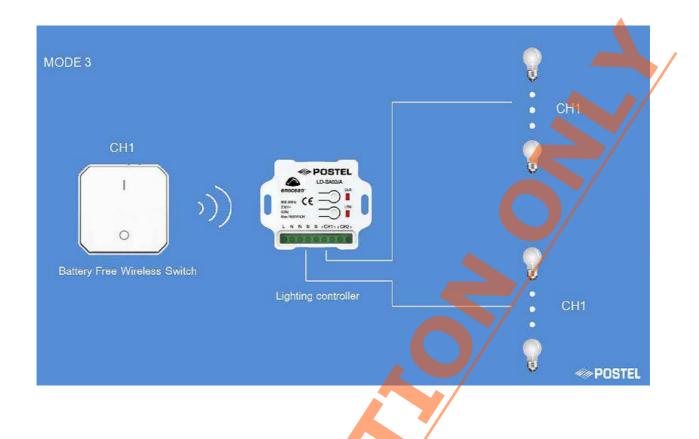
Mode 2:

In this mode, actuator can be controlled by both switch and occupancy sensor, also can be set "Auto" control by occupancy sensor or "Manual" control by switch through button "A" or "M". Each channel can be controlled independently.



Mode 3:

A bit like mode 1, but single rocker button controls two channels one time.



Mode 4:

One dual-rock switch button can control two dual-channel actuators as 4 channel lighting in all. We can control one channel only through trigger the rock angle.



DIRECTION-1 = Gateway request telegram; from gateway to actuator

DIRECTION-2 = Actuator status report; from actuator to gateway

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach- telegri 1: Data t		
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1		Message Type		Defines if the telegram is a request or contains data	Enum: 0: Reque	st	

DIRECTION-2

DIKECI	1011							
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	25	DB3.7DB0.7	Not Used (=	0)				
25	3	DB0.6DB0.4	Working Mode	WM	Actuators current working mode	Enum: 0b001:r 0b010:r 0b011:r 0b100:r	node 2 node 3	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tele	ch-in gram a telegrar	n
29	2	DB0.2DB0.1	Relay Status		Actuators current relay status Bit 0.1: CH1 Bit 0.2: CH2	0b00: off CH 0b01: off CH 0b10: on	11 on, CH 11 off, CH 11 on, CH	2
31	1	DB0.0	Message Type	MT	Defines if the telegram is a request or contains data	Enum: 1: Sta	tus Repor	

A5-12: Automated Meter Reading (AMR)

The meter reading is represented by 3 data bytes, a divisor and a flag that indicates it as a cumulative or a current value. A 4 bit info field gives additional information and is TYPE specific.

RORG	A5		4BS Telegram		
FUNC	12	Aut	Automated Meter Reading (AMR)		
TYPE	00	Counter			

Submitter: EnOcean GmbH

Offs	set	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		24	DB3.7DB1.0	Meter reading		Current value or cumulative counter value	016777215	9	according to DT
24	< \	4		Measurement channel	CH		015	015	1

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Data type (unit)	DT	Current value or cumulative counter value	Enum: 0: Cumulative value 1
						1: Current value 1/s
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for counter value	Enum: 0: x/1 016777215 1: x/10 01677721.5 2: x/100 0167772.15 3: x/1000 016777.215

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	01	Electricity

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0	24	DB3.7DB1.0	Meter reading		current value in W or cumulative value in kWh	01677		according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015		015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-		in telegram elegram	_
29	1	DB0.2	Data type (unit)		Current value or cumulative value	0: 0		ative value t value	W
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	2: >	10 </100 </1000</td <td>01677721 01677721 0167772.</td> <td>1.5</td>	01677721 01677721 0167772.	1.5

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	02	Gas

Submitter: EnOcean GmbH

Of	ffset	Size	е	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	24	DI	B3.7DB1.0	meter	MR	Cumulative value in m ³ or	016777215	according to	according to
					reading		Current value in liter/s		DIV	DT
24		4//	DI	B0.7DB0.4	Tariff info	TI		015	015	1

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	data type (unit)	DT	Current value or cumulative value	
30	2	DB0.1DB0.0	divisor (scale)	DIV	Divisor for value	Enum: 0: x/1

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	03	Water

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter	MR	Cumulative value in m³ or	016777215	according to	according to
			reading		Current value in liter/s		DIV	DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	1	DB0.2	Data type	DT	Current value or cumulative	Enum:		
			(unit)		value	0: Cumul	ative value	m³
						1: Currer	it value	Liter/s
30	2	DB0.1DB0.0		DIV	Divisor for value	Enum:		
			(scale)			0: x/1		
							0167772	15
						1: x/10		
							0167772	1.5
						2: x/100		
				7			0167772	.15
						3: x/1000		
							016777.2	215

RORG	A5	4BS Telegram		
FUNC	12	Automated Meter Reading (AMR)		
TYPE	04	Temperature and Load Sensor		

Submitter: SIMICS, NTT East

Temp and Load Sensor aimed for fridge and other application.

E.g. milk carton puts on this sensor in fridge. The sensor sends a signal of temp and remaining amount of milk (in gram). Since this sensor is battery-powered, battery level information is transmitted with Temp and Load information, too.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -Trigger event: load changed

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: yes

Security level format: RLC + AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Meter reading	MR	Current value in gram	016383	016383	gram
14	2	DB2.1DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-40+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	n
						1: Data t	elegram	
29	1	DB0.2	Not Used (= 0)				
30	2	DB0.1DB0.0	Battery Level	BL	Battery level	Enum:		
						0: 100-7	5%	
						1: 75-50	%	
						2: 50-25	%	
						3 : 25-0%)	

RORG	A5	4BS Telegram				
FUNC	12	Automated Meter Reading	(AMR)			
TYPE	05	Temperature and Container	Sensor			

Submitter: SIMICS, NTT East

Temp and Container Sensor aimed for fridge and other application.

E.g. eggs or egg carton puts on the Container Sensor in fridge. The sensor sends a signal of temp and remaining of eggs. Since this sensor is battery-powered, battery level information is transmitted with other information, too.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -Trigger event: load changed

Tx delay: -Rx timeout: -

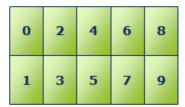
Teach-in method: 4BS teach-in 2

Encryption supported: yes

Security level format: RLC + AES128

Appendix

Location 0 - 9 are assigned as follows:



		Bitrange DB3.7		orior tout	Description	Valid Range Scale Unit
	-	11 11 2 2 7	Position Sensor 0	PS0	Location 0	Enum:
		003.7	r osition sensor o	1 50	Location	0: not possessed
						1: possessed
1	1	DB3.6	Position Sensor 1	PS1	Location 1	Enum:
_	-	DD3.0	1 0310011 3011301 1	1 31	Location 1	0: not possessed
						1: possessed
2	1	DB3.5	Position Sensor 2	DC2	Location 2	Enum:
_	-	003.3	1 OSICION SCHSOL Z	1 32	Location 2	0: not possessed
						1: possessed
3	1	DB3.4	Position Sensor 3	DC3	Location 3	Enum:
	_	DD3.4	1 OSICION SENSON S	1 33	Location 5	0: not possessed
						1: possessed
4	1	DB3.3	Position Sensor 4	DCA	Location 4	Enum:
7	_	003.3	1 OSICION SENSON 4	1 54	Location	0: not possessed
						1: possessed
5	1	DB3.2	Position Sensor 5	DCE	Location 5	'
.	1	DB3.2	FOSICION SENSON S	F33	Locations	Enum: 0: not possessed
						1: possessed
6	1	DB3.1	Position Sensor 6	DC6	Location 6	
0	1	DB3.1	Position Sensor 6	P30	Location 6	Enum: 0: not possessed
						<u> </u>
7	1	DB3.0	Position Sensor 7	DC 7	Location 7	
′	1	DB3.0	Position Sensor 7	P37	Location 7	Enum:
						0: not possessed 1: possessed
8	1	DB2.7	Dagitian Cassau C	DCO	Lagation O	'
8	1	DB2.7	Position Sensor 8	P58	Location 8	Enum:
						0: not possessed
0		DD2 6	De illi Como	DCO	1 1 0	1: possessed
9	1	DB2.6	Position Sensor 9	P\$9	Location 9	Enum:
						0: not possessed
	_					1: possessed
			Not Used (= 0)	TMD	Tamana amaka a di a a	0 355 40 4000
-		DB1.7DB1.0		TMP	Temperature (linear)	0255 -40+40 °C
		DB0.7DB0.4 DB0.3	Not Used (= 0)	LRNB	LRN Bit	F
28	T	DB0.3	LKN bit	LKIND	LKIN DIL	Enum:
						0: Teach-in telegram
20	1	DB0 2	Not Llood (O)			1: Data telegram
		DB0.2	Not Used (= 0)	DI	Pattony lovel	F
30	2	DB0.1DB0.0	Dattery Level	BL	Battery level	Enum:
						0: 100-75%
						1: 75-50%
						2: 50-25%
						3: 25-0%

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)



Submitter: Ewattch

Description

This profile is used for up to 16 channels current meters.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered Communication interval: can be defined by user Trigger event: 10 or 20 % delta for observed value

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Recommendation

Channels not used should not be transmitted.

Appendix

Our new product is a 12 channels current meter. It is able to measure, using a maximum of 12 current transformers, the current (mA) or cumulative current (mAh) of all of his channels. It is however not sending data for not configured channels (e.g. channels 12 to 15). The meter is sending values every 5 or 10 seconds, and in order to improve accuracy, a current fluctuation of more than 10 or 20 % will trigger a new transmission of the corresponding channel.



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading	MR	Current value in mA or cumulative value in A.h	016777215	_	according to DT
24	4	DB0.7DB0.4	Measurement channel	СН	Channel no.	015	015	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data to	elegram	
29	1	DB0.2	Data type (unit)	DT	Current value or	Enum:		_
					cumulative value	0: Cumul	ative value	A.h
						1: Curren	t value	mA
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	Enum:		
						0: x/1		
							0167772	15
						1: x/10		_
							0167772	1.5

	2:	x/100	
		0167772.15	
	3:	x/1000	
		016777.215	

A5-13: Environmental Applications

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	01	Weather Station

A receiver that accepts EEP A5-13-01 at teach-in automatically needs to accept telegrams from the same ID that comply to the definitions of EEP A5-13-02 thru EEP A5-13-06. Different telegrams received from that ID need to be distinguished by their 4 bit identifiers.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Dawn sensor	DWS	Dawn sensor	0255	0999	lx
8	8	DB2.7DB2.0	Temperature	TMP	Outdoor Temp	025	-40+80	°C
16	8	DB1.7DB1.0	Wind speed	WND	Wind speed	0255	070	m/s
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x1:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegrai elegram	m
29	1	DB0.2	Day / Night	D/N	Day / Night	Enum: 0: Day 1: Night	_	
30	1	DB0.1	Rain Indication	RAN	Rain Indication	Enum: 0: No Rai 1: Rain	n	
31	1	DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	02	Sun Intensity

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Sun - West	SNW	Sun - West,linear	0255	0150	klx
8	8	DB2.7DB2.0	Sun – South	SNS	Sun - South,linear	0255	0150	klx
16	8	DB1.7DB1.0	Sun – East	SNE	Sun - East,linear	0255	0150	klx
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x2:	_	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: D	each-in legram ata legram	
29	1	DB0.2	Hemisphere	HEM	0 = north / 1 = south, then swith Sun south to Sun North when in southern hemisphere		orth outh	
30	2	DB0.1DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	03	Date Exchange

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Not Used	(= 0)				
3	5	DB3.4DB3.0	Day	DY	Day	131	131	N/A
8	4	DB2.7DB2.4	Not Used	(= 0)				
12	4	DB2.3DB2.0	Month	MTH	Month (1->January)	112	112	N/A
16	1	DB1.7	Not Used	(= 0)				
17	7	DB1.6DB1.0	Year	YR	Year (0->Year 2000)	099	20002099	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x3:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in teleg 1: Data telegram		
29	2	DB0.2DB0.1	Not Used	(= 0)				
31	1	DB0.0	Source	SRC	Source	Enum: 0: Real Time Clo 1: GPS or equiva	ck ılent (e.g. DCF77, W	/WV)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	04	Time and Day Exchange

Submitter: Elsner electronics

Recommendation: always transmit time in 24 hrs format

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Weekday	WDY	Weekday (1 ->	Enum:		
					Monday)	1: Monday		
						2: Tuesday		
						3: Wednesday		
						4: Thursday		
						5: Friday		
						6: Saturday		
						7: Sunday		
3	5	DB3.4DB3.0	Hour	HR	Hour	023	023	N/A
8	2	DB2.7DB2.6	Not Used (=	: 0)				
10	6	DB2.5DB2.0	Minute	MIN	Minute	059	059	N/A
16		DB1.7DB1.6	Not Used (=	: 0)				
18	6	DB1.5DB1.0	Second	SEC	Second	059	059	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x4:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegra	m	
						1: Data telegram		
29	1	DB0.2	Time	TMF	Time Format	Enum:		
			Format			0: 24 hours		
						1: 12 hours		
30	1	DB0.1	AM/PM	A/PM	AM or PM	Enum:		
	7/					0: AM		
						1: PM		
						J.		

31	1	DB0.0	Source	SRC	Source	Enum:	
						0:	Real Time Clock
						1:	GPS or equivalent (e.g. DCF77, WWV)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	05	Direction Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Elevation	ELV	Elevation (0° -> horizon)	0180	-90+90	0
8	7	DB2.7DB2.1	Not Used	(= 0)				
15	9	DB2.0DB1.0	Azimut	AZM	Azimuth (0° -> True north; clockwise)	0359	0359	0
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x5:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegrar elegram	n
29	3	DB0.2DB0.0	Not Used	(= 0)				

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	06	Geographic Position Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	DB3.7DB3.4	Latitude(MSB)	LAT(MSB)	Latitude MSB	according to LAT(LSB)	according to LAT(LSB)	according to LAT(LSB)
4	4	DB3.3DB3.0	Longitude(MSB)		_	according to LOT(LSB)	according to LOT(LSB)	according to LOT(LSB)
8	8	DB2.7DB2.0	Latitude(LSB)	LAT(LSB)	Latitude LSB	04095	-90+90	0
16	8	DB1.7DB1.0	Longitude(LSB)	LOT(LSB)	Longitude LSB	04095	-180+180	o
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x6:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram	
29	3	DB0.2DB0.0	Not Used (= 0)		_			

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	07	Wind Sensor

Submitter: Hideki Electronics Limited

Description

This profile provides wind sensor information.

That includes the current wind direction, the average and the maximum wind speed.

Data exchange

Direction: unidirectional

Addressing: broadcast

Communication trigger: time-triggered Communication interval: 33 seconds

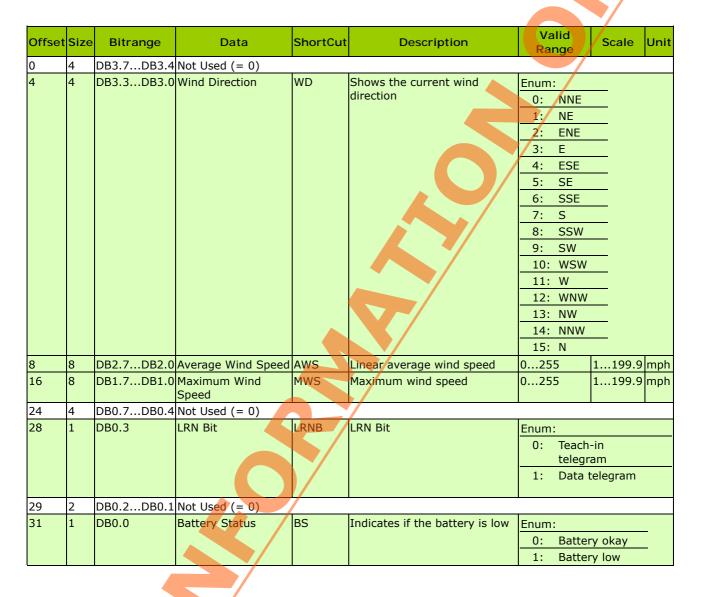
Trigger event: timer Tx delay: N/A Rx timeout: N/A

Teach-in

Teach-in method: 4BS teach-in 1

Security

Encryption supported: no Security level format: N/A



RORG	A5		4BS Telegram
FUNC	13	Envir	onmental Applications
TYPE	08		Rain Sensor

Submitter: Hideki Electronics Limited

Description

This profile provides rain sensor information.

That includes the current rainfall count value and the rainfall count correction.

Using these values, the receiver of the information can calculate the currently measured amount of rainfall.

 $Rainfall = (Rainfall Count \times 0.6875 mm) \times (1 + (Rainfall Adjust Sign) Rainfall Adjust)$

Example:

Rainfall Count = 10 Rainfall Adjust = 26 Rainfall Adjust Sign = 1

Rainfall = $10 \times 0.6875 \text{ mm X } (1 + 2.6/100) = 7.05375 \text{ mm}$

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered Communication interval: 183 seconds

Trigger event: timer Tx delay: N/A Rx timeout: N/A

Teach-in

Teach-in method: 4BS teach-in 1

Security

Encryption supported: no Security level format: N/A



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	DB3.7	Not Used (= 0)					
1	1		Rainfall Adjust Sign		Provides the sign of the rainfall adjust value	0: Negative 1: Positive		
2	6	DB3.5DB3.0	Rainfall Adjust		Provides the rainfall count correction value	Enum: 039: Rese 4063:	03. rved	9 %
8	16	DB2.7DB1.0	Rainfall Count	RFC	Number of counted rain drops	065535	065535	
24	4	DB0.7DB0.4	Not Used (= 0)	•				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data te	n telegram egram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Battery Status	BS	Indicates if the battery is low	Enum: 0: Battery 1: Battery		

RORG	A5	4BS	Telegran	n /
FUNC	13	Environme	ntal Appli	cations
TYPE	10	Sun positi	on and ra	diation

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	DB3.7DB3.1	Sun Elevation		Sun Elevation (linear); 91 - 127: reserved	090	090	o
7	1	DB3.0	Day / Night	D/N	Day / Night	Enum:	_	
						0: Day 1: Night	_	
8	8	DB2.7DB2.0	Sun Azimuth		Sun Azimuth 181 - 255: reserved	0180	-90+90	o
16	8	DB1.7DB1.0	Solar Radiation (MSB)	_		according to SRA (LSB)	according to SRA (LSB)	according to SRA (LSB)
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x7:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	telegram	
						1: Data tel	egram	

29	3	DB0.2DB0.0	Solar	SRA	Solar Radiation	02000	02000	W/m2
			Radiation (LSB)	,	(LSB) (Linear); 20012048: reserved			

A5-14: Multi-Func Sensor

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	01	Single Input Contact (Window/Door), Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ii telegrar 1: Data te	n	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact 0b1: Contact		_

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	02	Single Input Contact (Window/Door), Supply voltage monitor and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach- telegra 1: Data to		
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0,0	Contact	СТ		Enum: 0b0: Contac 0b1: Contac		

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	03	Single Input Contact (Window/Door), Supply voltage monitor and Vibration

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm, Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele		
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Vibration	VIB		No vibration 0b1:		
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact (0b1: Contact (-

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	04	Single Input Contact (Window/Door), Supply voltage monitor, Vibration and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm, Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegram	<u> </u>
						1: Data te	legram	
29	1	DB0.2	Not Used (= 0))				
30	1	DB0.1	Vibration	VIB		Enum:		
						No vibr	ation	
						0b0: detecte		
						Vibration 0b1:	n detected	į
21	- 4	DD0 0	C	СТ				
31	1	DB0.0	Contact	СТ		Enum:		_
						0b0: Contact		-
						0b1: Contact	t open	

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	05	Vibration/Tilt, Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code		05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele		
29	1	DB0.2	Not Used (= 0)			7	
30	1	DB0.1	Vibration	VIB		No vibrat 0b0: detected Vibration 0b1:		d
31	1	DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram	
FUNC	14	Multi-Func Sensor	
TYPE	06	Vibration/Tilt, Illumination and Supply volta	ge monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ii 1: Data te	n telegram legram	<u> </u>
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Vibration	VIB		Enum: No vibrous detecte Vibration (Ob1:)		i i
31	1	DB0.0	Not Used (= 0))				

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	07	Dual-door-contact with States Open/Closed and Locked/Unlocked, Supply voltage monitor

Submitter: EiMSIG eine Marke der EFP GmbH

Description

Door-sensor with the door-states open/closed and sensor for the door-lock with states locked/unlocked. Additional supply-voltage-monitor.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: N/A

Trigger event: timer and change on state

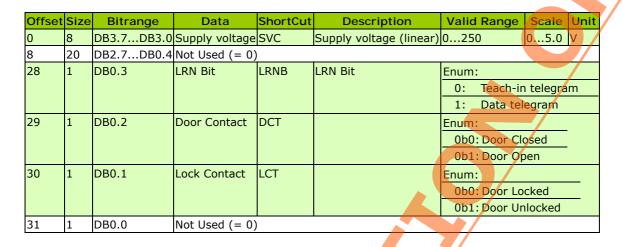
Tx delay: N/A Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: yes Security level format: -



RORG	A5	ADC Tolograms
RURG	AS	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	80	Dual-door-contact with States Open/Closed and Locked/Unlocked, Supply voltage monitor and Vibration detection

Submitter: EiMSIG eine Marke der EFP GmbH

Description

Door-sensor with the door-states open/closed and sensor for the door-lock with states locked/unlocked. Additional supply-voltage-monitor and vibration-sensor for glass-breakage detection.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: N/A

Trigger event: timer and change on state

Tx delay: N/A Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: yes Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage	0250	05.0	V
					/ super cap. (linear)			
8	20	DB2.7.,.DB0.4	Not Used (= 0)	1				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in t	elegram	
						1: Data teleg	gram	
29	1	DB0.2	Door Contact	DCT		Enum:		
	7/					0b0: Door Clos	ed	
						0b1: Door Ope	n	

30	1	DB0.1	Lock Contact	LCT		Enum:
						0b0: Door Locked
						0b1: Door Unlocked
31	1	DB0.0	Vibration	VIB		Enum:
						0b0: No vibration detected
						0b1: Vibration detected

RORG	A5	4BS Telegram	
FUNC	14	Multi-Func Sensor	
TYPE	09	Window/Door-Sensor with States Open/Closed/Tilt, Supply voltage mo	onitor

Submitter: EiMSIG eine Marke der EFP GmbH

Description

Door/window-sensor with states open/closed/tilt and supply-voltage-monitor.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: N/A

Trigger event: timer and change on state

Tx delay: N/A Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: yes Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear)		05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	n telegra	m
						1: Data tel	egram	
29	2	DB0.2DB0.1	Contact	СТ		Enum:		
						0b00: Closed	<u> </u>	
						0b01: Tilt		
						0b10: Reserv	red	
						0b11: Open		
31	1	DB0.0	Not Used $(= 0)$					

RORG	A5		4BS Telegram
FUNC	14		Multi-Func Sensor
TYPE	0A	Windo	ow/Door-Sensor with States Open/Closed/Tilt, Supply voltage monitor and Vibration detection

Submitter: EiMSIG eine Marke der EFP GmbH

Description 1 4 1

Door/window-sensor with states open/closed/tilt.

Additional vibration-sensor for the detection of glass-breakage and supply voltage monitor.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: N/A

Trigger event: timer and change on state

Tx delay: N/A Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

<u>Security</u> Encryption supported: yes Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear)	0250	05.0	>
8	20	DB2.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in t 1: Data teleg		
29	2	DB0.2DB0.1	Contact	СТ		Enum: 0b00: Closed 0b01: Tilt 0b10: Reserve	d	
31	1	DB0.0	Vibration	VIB		Enum: 0b0: No vibrati 0b1: Vibration		ted

A5-20: HVAC Components

RORG	RORG A5 4BS Telegram	
FUNC	20	HVAC Components
TYPE	01	Battery Powered Actuator (BI-DIR)

Submitter: Kieback + Peter GmbH

DIRECTION-1 = Transmit mode: Message from the actuator to the controller

DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Current Value	CV	Current value	0100	0100	%
8	1	DB2.7	Service On	SO SO	Service On	Enum: 1: on	_	
9	1	DB2.6	Energy input enabled	ENIE	Energy input enabled	Enum: 1: true		
10	1	DB2.5	Energy Storage	ES	Energy storage sufficiently charged	Enum: 1: true	<u> </u>	
11	1	DB2.4	Battery capacity	BCAP	Battery capacity; change battery next days	Enum: 0: true		
12	1	DB2.3	Contact, cover open	ССО	Contact, cover open	Enum: 1: true	<u> </u>	
13	1	DB2.2	Failure temperature sensor, out off range	FTS	Failure Temperature sensor, out off range	Enum: 1: true		
14	1	DB2.1	Detection, window open	DWO	Detection, window open	Enum: 1: true		
15	1	DB2.0	Actuator obstructed	ACO	Actuator obstructed	Enum: 1: true		

16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Teach-in telegram Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)				

DIREC	IRECTION-2										
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit			
0	8	DB3.7DB3.0	Valve position or Temperature Setpoint	SP	point (linear); selection with DB1.2 Valve position 0100% in combination with compatible classic controllers the actuator used DB_3; Temperature set point: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).	0100 or 255	0100 or +40	% or °C			
8	8	DB2.7DB2.0	Temperature from RCU	ТМР	Temperature actual from RCU = 0b0 (Room controller-unit), see DB1.0 Maintenance mode ('service on'): DB_2.BIT_5: energy memory sufficiently charged =1 DB_2.BIT_4: battery capacity changing battery in the next days, need changing batteries = 0 Status feedback signal (service on, DB_2.BIT_7	2550	0+40	°C			
16	1	DB1.7	Run init sequence	RIN	The limit switching measures the travel and signals when an end position has been reached. This end position (valve zero point) in the actuator is stored.	Enum: 1: tru	e				
17	1	DB1.6	Lift set	LFS	Initialization, adjustment to the valve stroke. The Initialization is switched after receiving the command. The valve is completely opened and closed during initialization.	Enum: 1: tru	e				
18	1	DB1.5	Valve open / maintenance	vo	After receiving an operation command, the actuator moves the valve in direction open or close. when reaching the end position, an automatic switch-off procedure is started. In service mode the valve can be set to open or closed always.	Enum: 1: tru	e				
19	1	DB1.4	Valve closed	VC	valve closed	Enum: 1: tru	<u></u>				
20		DB1.3	Reduction of energy consumption	SB	The radio communication between the actuator and the controller is restricted, sleep mode is extended. This functionality can be used for battery powered actuators.	Enum: 1: tru					
21	1	DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	(0-	ve position 100%). Un spond to				

							controller.
						1:	Temperature set
							point 040°C.
							Unit respond to
							room sensor and
							use internal PI
22		DD4 4		CDN		_	loop.
22	1	DB1.1	Set point	SPN		Enum:	
			inverse		actuator normal or inverted. The selection is done by DB_1.Bit1. The	1:	true
					implementation is done and is		
					controlled in the actuator with		
					DB_3. This function is used in		
					dependence on the type of valve.		
23	1	DB1.0	Select function	RCU	RCU or 'Service on': After	Enum:	
					transmitting the command to the	0:	RCU
					actuator, it can be send from the	1:	service on
					controller or a service device, the		Service on
					actuator sends a status feedback		
					signal (service on, DB_2.BIT_7).		
24	4		Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in
							telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used $(= 0)$				

RORG	A5	4BS Telegram		
FUNC	20	HVAC Components		
TYPE	02	Basic Actuator (BI-DIR)		

Submitter: Spartan Peripheral Devices

Basic Actuator can be used by any manufacturer for linear or rotary actuator.

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator. To use with a BAS/Gateway system; max. reponse time 1 sec.

DIRECTION-1

Offset			Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual Value		Actual value (linear); can be a linear or rotation motion.	0100	0100	%
8	14	DB2.7DB1.2	Not Used	(=0)				
22	1	_	Set point inverse		Set point inverse (Needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer	Enum: 1: tr	rue	
24	4	DB0.7DB0.4	Not Used	(= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: D	each-in elegram ata elegram	
29	3	DB0.2DB0.0	Not Used	(= 0)				

Of	fset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	~	8		Valve Set point	VSP	Valve set Point (linear)	0100	0100	%
8		8	DB2.7DB2.0	Not Used	d (= 0)				

16	6	DB1.7DB1.2	Not Used	d (= 0)		
22	1	DB1.1	Set point inverse	VSP	'Set point inverse' needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer. It can send a command to invert functionality of the unit. In some instance some equipment might need 100% to represent fully extracted, in other fully retracted.	Enum: 1: true
23	5	DB1.0DB0.4	Not Used	d (= 0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used	d (= 0)		

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	03	Line powered Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual valve	AV	Actual valve	0 100	0100	%
8	8	DB2.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actuator or Temperature Setpoint		Actuator Setpoint: in combination with BAS/Gateway controllers. Temperature Setpoint: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).	0100 or 255	0100 or +40	% or °C
8	8	DB2.7DB2.0	Temperature from RCU	TMPRC	Temperature actual from RCU = 0b0 (Room controller-unit)	2550	0+40	°C
16	5	DB1.7DB1.3	Not Used (= 0)				
21		DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	(0- res cor 1: Ter Se 0	tuator Setpo (100%); Un spond to ntroller. mperature tpoint .+40°C; Ur spond to roo	nit

22	1	DB1.1	Set Point Inverse		Valve set point can be sent to the actuator normal or inverted through BAS/Gateway controller. The selection is done by DB_1.Bit1. in the actuator with DB_3. This function is used in dependence on the type of valve.	sensor and use internal PI loop. Enum: 1: true
23	5	DB1.0DB0.4	Not Used (= 0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)		

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	04	Heating Radiator Valve Actuating Drive with Feed and Room Temperature Measurement, Local Set Point Control and Display (BI-DIR)

Submitter: Holter Regelarmaturen GmbH & Co. KG

Description

The following document describes the communication between a controller and an intelligent heating radiator valve actuating drive with the following features:

- Feed temperature measurement
- Room temperature measurement
- Current position feedback
- Display
- Button
- On device temperature set point selection

In order to be able to process this information and control the actuator, every command has been included in this document. Each customer can use his own controller by implementing the EEP of this document.

Data exchange

Direction: bidirectional Addressing: unicast (ADT)

Communication trigger: event- & time-triggered

Communication interval: can be configured by the controller

Trigger event: a trigger event occurs when the button is pressed or the local set point is used

Tx delay: 550 ms is the maximum response time for Smart-Ack Devices and 1100 ms for devices which use the 4BS

teach-in method

Rx timeout: just 1 message per wake-up cycle

leach-in

Teach-in method: Smart-Ack teach-in and 4BS teach-in Variation 3

Security

Encryption supported: no Security level format:

Telegram Description of Direction 1 (Transmit mode / Message from the actuator to the controller)

This direction initializes the communication, shares the needed data and waits for an answer from the controller. This allows the device to work in deep sleep mode the rest of the time.

Each message from the actuator contains the following information:

Current Position (CP)

The current position is a feedback value from the actuator. It indicates the actual per cent position of the valve. The value 0 % means that the valve is completely closed and 100 % completely open. The controller can use this information for the room temperature regulation.

Temperature Set Point OR Feed Temperature (FTS)*

*This byte is shared by the Temperature Set Point and the Feed Temperature value. Only one of these values is sent in the same message. Which value is transmitted is indicated by DB0.1 (TS bit).

The feed temperature is the water temperature in the radiator input, which can be useful for implementing

several features in the home automation system.

The temperature set point is only sent when the user specifies a new room temperature by using the local temperature set point on the device.

• Room Temperature (TMP) OR Failure Code (FC)*

* This byte is shared by the Room Temperature and Failure Code Value. Only one of these values is sent in the same message. The value transmitted is indicated by DB0.0 (FL). By default it is the room temperature. The room temperature is the ambient temperature of the place in which the device is used and is measured by the actuator. This value is transmitted if no error occurred.

The Failure Code is transmitted instead of the Room Temperature if an error occurs.

• Measurement Status (MST)

The temperature measurements (room and feed temperature) can be deactivated in order to reduce the energy consumption. This can be specified only by the controller i.e. to implement summer mode or to replace the internal room temperature measurement of the actuator by an external one.

• Status Request (SRT)

The status request bit can be used to ask the controller about its status. If the controller does not send back the correct reply, the actuator will start its own room temperature regulation. With this feature, a frozen actuator would not interrupt the room temperature regulation.

• Teach-in Bit (LRNB)

For establishing the radio link between the controller and the actuator, a teachin message has to be sent from the actuator to the controller. If the binary value 0 is transmitted, the message will be identified as a teach-in one and will allow the controller to receive the EnOcean-ID of the actuator.

• Button Lock Status (BLS)

The button lock status can be set by the controller. This enables or disables the manual room temperature selection. If locked, the manual room temperature selection on the actuator will be disabled and the user will be notified with a symbol on the display.

• Temperature Selection (TS)

If the user specifies a temperature set point manually on the device, this will be sent to the controller and indicated on the temperature selection field (TS). It can indicate that the field FTS contains the temperature set point (binary value = 1) or the feed temperature (binary value = 0).

• Failure (FL)

Indicates the occurrence of a failure. The room temperature value is replaced by the failure code if the bit FL has the binary value 1.

Telegram Description of Direction 2 (Receive mode / Commands from the controller to the actuator)

The messages from the controller to the actuator are sent in this direction. A message in this direction has to be sent after receiving a message from the actuator, in order to achieve a successful communication. If the controller message is not received by the actuator in a specific time after a direction 1 message, no information will be received by the actuator. The time that the actuator will wait for a reply is defined by the Smart-Ack Teach-In process. For controllers which cannot use Smart-Ack, the 4BS Teach-in Variation 3 has to be used, with a maximum response time of 1100 ms.

Each message from the controller contains the following information:

• Valve Position (POS)

The valve position is a set point position for the valve. It indicates the per cent position of the valve, which the actuator has to reach. The value 0 % means that the valve is completely closed and 100 % completely open. The controller should be able to regulate the room temperature by adjusting this value.

• Temperature Set Point (TSP)

The controller can send the temperature set point to the actuator in order to allow the user to see the actual specified temperature in the device display. This value does not affect room temperature regulation.

Measurement Control (MC)

The temperature measurements (room and feed temperature) can be deactivated in order to reduce energy consumption. This can be specified only by the controller i.e. to implement summer mode or to replace the internal room temperature measurement by the device with an external one. The measurement control bit enables the controller to activate or deactivate the measurements.

Wake-up Cycle (WUC)

To save energy, the actuator works in deep sleep mode the most of the time. Nevertheless it has to wake up to communicate with the controller and to reach the valve position specified by the controller. The longer the actuator remains in deep sleep mode, the more energy efficient will be your batteries. If fast response is required, the actuator has to communicate more frequently with the controller and that is why it should use a shorter wake-up cycle. If a fast room temperature control is not required, the wake-up cycle should be set by the controller as long as possible.

Display Orientation (DSO)

The heater valves can be installed in different directions. That is why it can be useful to have the option to choose the fitting display orientation. This feature makes reading the display easier.

• Teach-in Bit (LRNB)

For establishing a radio link between the controller and the actuator, a teach-in telegram has to be sent from the controller to the actuator. If the binary value 0 is transmitted, the message will be identified as a teach-in one and will allow the device to receive the EnOcean-ID from the controller.

• Button Lock Control (BLS)

The button lock status can be set by the controller. This enables or disables the manual room temperature selection. If locked, the manual room temperature selection on the actuator will be disabled and the user will be notified with a symbol on the display.

• Service Command (SER)

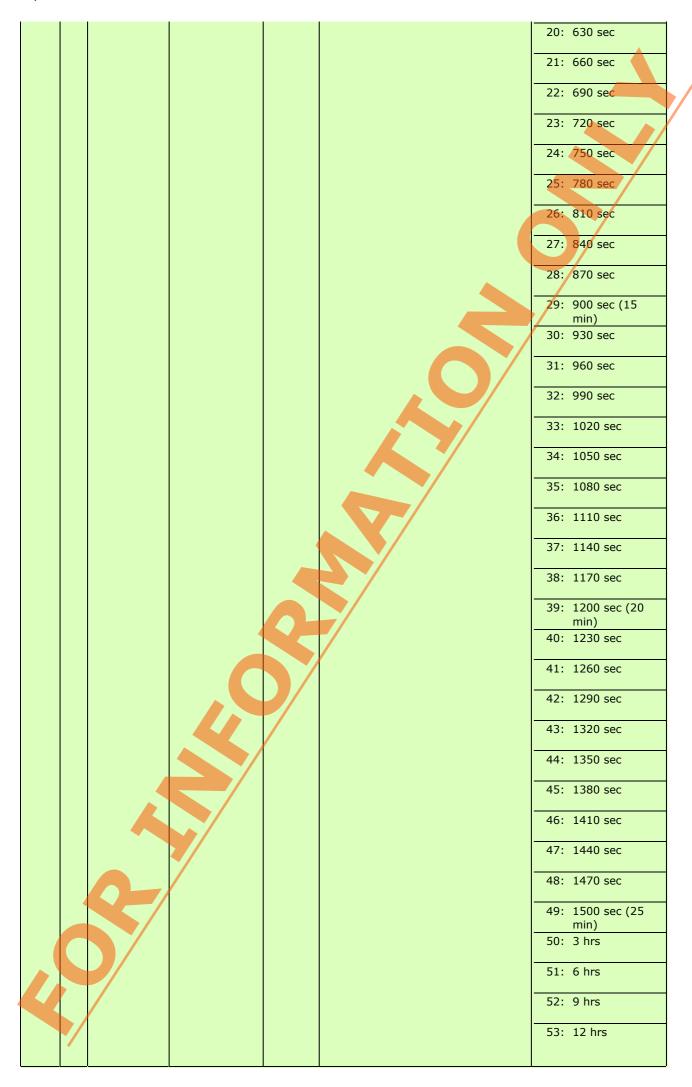
In order to adapt the actuator to a new valve, the controller can order the execution of some functions of the actuator:

- run initialisation: This function has to be executed for adapting the actuator to the length of the valve stroke.
- open valve: To facilitate the installation or maintenance of the valve, the actuator can open the valve completely. After completely opening the valve it is necessary to run the initialisation.
- close valve: Completely close the valve.

0 8 DB3.7DB3.0 Current Position CP Current valve position 0100 0100 8 8 DB2.7DB2.0 Feed FTS Either current feed temperature Value or 10255 20 80 or 10 30	% °C
8 B DB2.7DB2.0 Feed FTS Either current feed 0255 20 80 or 10 30	0.0
Temperature Set temperature set point (defined by DB0.1)	
TMPFC Temperature TMPFC TMPFC Current room temperature Value (1030°C) OR Failure Code (Enum) (1030°C) OR Failure OR	30 °C
24 1 DB0.7 Measurement Status MST Shows if the temperature measurement (feed temperature and room temperature) is active DB0.7	
25 1 DB0.6 Status Request STR Request for status from the controller 0: No change 1: Status requested	
26 2 DB0.5DB0.4 Not Used (= 0)	

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Button Lock Status	_	Shows if all buttons on the actuator are locked	Enum: 0: Unlocked 1: Locked
30	1	DB0.1	Temperature Selection		Defines which temperature value is transmitted in DB2	Enum: 0: Feed temperature 1: Temperature set point
31	1	DB0.0	Failure		A failure occurred, see DB1.7-DB1.0 for Failure Code	Enum: 0: No failure (TMP is transmitted) 1: failure (FC is transmitted)

Description Size Bitrange Data ShortCut Description Range Scale U	DIRECT	TION-	2						
B			ŭ			Description			
Point Poin	0	8	DB3.7DB3.0	Valve Position	POS	Valve position	0100	0100	%
DB1.6	8	8	DB2.7DB2.0		TSP	Temperature set point	0255	1030	°C
17	16	1	DB1.7	Not Used (= 0)					
Control					МС	Control the temperature	Fnum:		
room temperature) 1: Disable 1: Disable 1: Disable 1: Disable 1: Disable 1: Disable 1: 60 sec 1: 60 sec 2: 90 sec 3: 120 sec 4: 150 sec 5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 11: 360 sec 12: 390 sec 11: 420 sec 12: 390 sec 13: 420 sec 15: 480 sec 16: 510 sec 17: 540 sec								hla	
18 6 DB1.5DB1.0 Wake-up Cycle WUC Defines the cyclic wake-up time Enum: 0: 10 sec 1: 60 sec 2: 90 sec 3: 120 sec 4: 150 sec 5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 15: 480 sec 16: 510 sec 17: 540 sec									
0: 10 sec 1: 60 sec 2: 90 sec 3: 120 sec 4: 150 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 17: 540 sec	1.0	_	DD1 F DD1 0	Mala Coala	WILL	Defines the valie well as the s		inie	
1: 60 sec 2: 90 sec 3: 120 sec 4: 150 sec 5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 12: 390 sec 14: 450 sec 15: 480 sec 15: 480 sec 16: 510 sec 17: 540 sec	18	О	061.5061.0	wake-up Cycle	WUC	Defines the cyclic wake-up time			
2: 90 sec 3: 120 sec 4: 150 sec 5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 14: 450 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							0: 10 s	sec	
3: 120 sec 4: 150 sec 5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec							1: 60 s	sec	
4: 150 sec 5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							2: 90 s	sec	
5: 180 sec 6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							3: 120	sec	
6: 210 sec 7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							4: 150	sec	
7: 240 sec 8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							5: 180	sec	
8: 270 sec 9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							6: 210	sec	
9: 300 sec (5 min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							7: 240	sec	
min) 10: 330 sec 11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							8: 270	sec	
11: 360 sec 12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec									
12: 390 sec 13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							10: 330	sec	
13: 420 sec 14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							11: 360	sec	
14: 450 sec 15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							12: 390	sec	
15: 480 sec 16: 510 sec 17: 540 sec 18: 570 sec							13: 420	sec	
16: 510 sec 17: 540 sec 18: 570 sec		4		/			14: 450	sec	
17: 540 sec 18: 570 sec							15: 480	sec	
18: 570 sec							16: 510	sec	
19: 600 sec (10		/							
min)							Hilli)	



						54: 15 hrs
						55: 18 hrs
						56: 21 hrs
						57: 24 hrs
						58: 27 hrs
						59: 30 hrs
						60: 33 hrs
						61: 36 hrs
						62: 39 hrs
						63: 42 hrs (max)
24	2	DB0 7 DB0 6	Not Used (= 0)			
26	2	DB0.5DB0.4		DSO	Adjusts the display orientation	Enum:
			Orientation		Trajusta dile display	0: 0°
						1: 90°
						2: 180°
						3: 270°
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data
						telegram
29	1	DB0.2	Button Lock	BLC	Set the button lock status	Enum:
			Control			0: Unlocked
				•		1: Locked
30	2	DB0.1DB0.0		SER	Initiates certain temporary service	Enum:
			Command		operations	0: No change
				0		1: Open valve
						2: Run
						initialisation
						3: Close valve

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	05	Ventilation Unit (BI-DIR)

Submitter: Itho Daalderop

Description

The device represented by this EEP is a stand-alone ventilation unit.

Smart-Ack is not supported/required.

The ventilation unit itself does not send messages on a regular (time or event triggered) base but will always send a response message after it receives a message from e.g. a remote control or gateway.

When the controller only wants to know the status of the ventilation unit and does not want to change the ventilation setting this can be requested by sending a message from controller to the fan unit with new fan speed setting NSP = 7 = "no change".

When more than one controller is connected to the unit the last received speed setting will be the new speed setting.

When a ventilation unit supports auto speed this means that the speed is influenced / calculated by sensor values which are directly connected to the ventilation unit (e.g. CO2 or RH sensors).

How the timer setting for a new fan speed (NSPT) is handled by the ventilation unit is depending on the unit and legislation.

When the timer period has expired the ventilation unit will go back to the previous or auto setting, this behavior is depending on the ventilation unit and legislation.

Data exchange

Direction: bidirectional Addressing: addressed

Communication trigger: event-triggered

Communication interval: N/A Trigger event: received message

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in variation 3 (bidirectional)

Security

Encryption supported: no Security level format: -

Directions

DIRECTION-1 = Transmit mode: Message from ventilation unit to controller

DIRECTION-2 = Receive mode: Commands from controller to ventilation unit

Offset				ShortCut		Val	Valid Range Scale Uni		
0	3	DB3.7DB3.5		ASP	Actual speed setting of	Enum	:		
			setting		ventilation unit	0:	Minimum s away	peed /	
						1:	Speed 1 / I	ow	
						2:	Speed 2 / ı	mid	
						3:	Speed 3 / I	nigh	
						4:	Max speed		
						5:	Auto		
						6:	Not used		
						7:	Not used		
3	3	DB3.4DB3.2		ASPT	Actual timer value for actual	Enum	:		
			timer setting		speed	0:	No timer se expired	et or	
						1:	110 min l	eft	
						2:	1120 min	left	
						3:	2130 min	left	
						4:	3140 min	left	
						5:	4150 min	left	
						6:	5160 min	left	
						7:	> 60 min le	eft	
6	2	DB3.1DB3.0	Not Used (= 0)						
8	3	DB2.7DB2.5	Not Used (= 0)						
11	1	DB2.4	Node low battery	E-NBAT	External node low battery	Enum	:		
					error	0:	No error		
						1:	Error		

12	1	DB2.3	Node comm. error	E-NCOM	External node communication error	Enum: 0: No error
						1: Error
13	1	DB2.2	Sensor error	E-SENS	Internal sensor error	Enum:
						0: No error
						1: Error
14	1	DB2.1	Fan speed error	E-FSPD	Desired fan speed not	Enum:
					reached error	0: No error
						1: Error
15	1	DB2.0	Error	ERR	Unit has an error	Enum:
						0: No error
	_					1: Error
16	8	DB1.7DB1.0	Filter condition	FLTR	Indication of the air filter's condition	Enum:
					Condition	0: Filter needs replacement
						1100: % dirtyclean
					•	filter
						Not used
						101254: 255: No filter present
						No filter present
24	1	DB0.7	Auto speed	AUTO	Ventilation unit supports	Enum:
			supported		auto speed or not	0: Auto speed not
						supported
						1: Auto speed supported
25	1	DB0.6	By-pass active	BPASS	Summer bypass active or	Enum:
					not	0: Summer bypass not
						active
						1: Summer bypass active
26	1	DB0.5	Frost protection	FROST	Frost protection active or	Enum:
					not	0: Frost protection not
						active
						1: Frost protection active
27	1	DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

Offset Size

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0			New speed setting		New speed setting for ventilation unit	6: 7:	Minimum away Speed 1 Speed 2 Speed 3 Max speed Auto Not used	/ low / mid / high	
3	5		New speed timer setting	NSPT	Timer setting for new speed	Enum 0:		ner / no je	

8 16	8		Not Used (= 0) Not Used (= 0)			16: 1060 min 729: 224 hrs Not used 3031:
24	1	DB0.7	Reset error	RSTE	Reset the unit when error present	Enum: 0: Don't reset error 1: Reset error
25	1	DB0.6	Reset filter timer	RSTF	Reset the filter timer	Enum: 0: Don't reset filter timer 1: Reset filter timer Reset only possible when timer expired (FLTR=0)
26	2	DB0.5DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram				
FUNC	20	HVAC Components				
TYPE	10	Generic HVAC Interface (BI-DIR)				

Submitter: Intesis Software SL

Functions: Mode, Vane Position, Fan Speed, Sensors and On/Off; With this EEP plus the already existing EEP A5-10-03 and A5-20-11 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0	8	DB3.7DB3.0	Mode		and LON allowing a more transparent integration with this protocols and it	Enum: 0:	Auto		
				has plenty of free positions for future expansion	1:	Heat			
						2:	Mornii	ng Warm	nup
						3:	Cool		
						4:	Night	Purge	
						5:	Precod	ol	
						6:	Off		
						7:	Test		
						8:		jency He	at
						9:	Fan or		
						10:	Free c	ool	

						I 					
						11:	Ice				
						12:	Max	heat			
						13:	Econ heat/				
						14:	Dehu (dry)	ımidificati	ion		
						15:		ration			
						16:	Emer	gency co	ol		
						17:	Emer stear	gency n			
						18:	max	cool			
						19:	Hvc I	oad			
						20:	no lo	ad			
						2130:	reser	ved			
						31:	Auto	Heat			
						32:	Auto	Cool			
						33254	reser 4:	ved			
						255:	N/A				
3	4	DB2.7DB2.4		VPS		Enum:					
			position			0:	Auto				
						1:	Horizor	ntal			
						2:	Pos2				
						3:	Pos3				
					4			4:	Pos4		
						5:	Vertica	I			
						6:	Swing				
						710:	Reserv	ed			
							Vertica	l swing			
						12:	Horizor	ntal swing]		
						13:		ntal and I swing			
						14:	Stop s				
						15:	N/A				
12	4	DB2,3DB2,0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1	Enum:					
					is the lowest fan speed allowed by the AC and from there it increments with		Auto				
					the value of this variable. Typically AC units have up to 5-6 speeds. Any	1 14.	Up to 1	.4 fan	the		
					speed higher than the maximum the AC allows would set it to the higher		speeas lowest	being 1 t	.ne		
					speed. 0 is auto and 15 is N/A	15:	N/A				
16	8	DB1.7DB1.0	Control variable	CVAR	Control variable; value 255 = auto	0100,	255	0100	%		

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	Teach-in telegram Data telegram
29	2	DB0.2DB0.1	Room occupancy	RO	The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to presence/movement sensors.	1:	Occupied StandBy (waiting to perform action) Unoccupied (action performed) Off (no occupancy
31	1	DB0.0	On/Off	O/I	On/Off	Enum: 0: 1:	off (the unit is not running)

Offset 0			Data		Description	valiu iv	ange Scale Unit
	0	DB3.7DB3.0		ShortCut MD	The modes are the same as in KNX	Enum:	
					and LON allowing a more transparent integration with this protocols and it	0:	Auto
					has plenty of free positions for future expansion	1:	Heat
						2:	Morning Warmup
						3:	Cool
						4:	Night Purge
						5:	Precool
						6:	Off
						7: 8:	Test Emergency Heat
						9:	Fan only
						10:	Free cool
						11:	Ice
						12:	Max heat
						13:	Economic heat/cool
						14:	Dehumidification (dry)
						15:	Calibration
						16:	Emergency cool
						17:	Emergency steam
						18:	max cool
						19:	no load
						20.	reserved
						2130:	10001100
						31:	Auto Heat

						32:	Auto Cool
						22 25	reserved
						3325 255:	N/A
8	4	DB2.7DB2.4	Vane	VPS		Enum:	
J	•		position			0:	Auto
						1:	Horizontal
						2:	Pos2
						3:	Pos3
						4:	Pos4
						5:	Vertical
						6:	Swing
						710:	Reserved
						11:	Vertical swing
						12:	Horizontal swing
						13:	Horizontal and vertical swing
						14:	Stop swing
						15:	N/A
12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1	Enum:	
					is the lowest fan speed allowed by the AC and from there it increments	0:	Auto
					with the value of this variable. Typically AC units have up to 5-6	1 1/1.	Up to 14 fan speeds being 1 the lowest
					speeds. Any speed higher than the maximum the AC allows would set it	15:	
					to the higher speed. 0 is auto and 15		
16	8	DB1.7DB1.0		CVAR	is N/A Control variable (linear); value 255 =	0100	, 255 0100 %
- 1	_		variable		auto		
24 28	4	DB0.7DB0.4 DB0.3	LRN Bit	LRNB	LRN Bit	Ганта	
20	1	DB0.3	LKIV DIL	LNIVD	LININ DIL	Enum:	Teach-in telegram
						1:	Data telegram
29	2	DB0.2DB0.1	Room occupancy	RO	Room occupancy	Enum:	0
			occupancy			0: (Occupied
							StandBy (waiting to perform action)
			7/			2:	Unoccupied (action performed)
						3:	Off (no occupancy and no action)
31	1	DB0.0	On/Off	O/I	On/Off	Enum:	and no action)
			311, 311	3,1	5, 5		off
							on

		_				
RORG	A5	4BS Telegram				
FUNC	20	HVAC Components				
TYPE 11		Generic HVAC Interface – Error Control (BI-DIR)				

Submitter: Intesis Software SL

Error Control: AC Error Code, Error States and Disablements. With this EEP plus the already existing EEP A5-10-03 and A5-20-10 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	23	DB3.7DB1.1	Not Used (= 0)					
23	1	DB1.0	External disablement	EXDS	External disablement		disable	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tele 1: Data	ch-in gram a gram	
29	1	DB0.2	Disable remote controller	DRC	Disable remote controller (When in receive mode it controls if the interface overwrites the remote controller commands.)	1: Disa		ote
30		DB0.1	Window contact	WC	Window contact	ope	dows	
31	1	DB0.0	Not Used $(= 0)$					

DIKECI	TOIN-							
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rang	Scale	Unit
0	16	DB3.7DB2.0	Error Code	ERR	Error Code (DB3 HI,DB2 LO); generated by A.C.	0655	35 065535	N/A
16	4	DB1.7DB1.4	Reserved	RES	Reserved (0b0000)	Enum:		
						:	Reserved	
20	1	DB1.3	Other disablement OD	OD /	Manufacturer defined. It is just to	Enum:		
					provide an extra "disablement signal" that could be used for other devices. People would not have to change anything then as this is already an established "signal"	0:	Not disabled	
						1:	Disabled	
21	1	DB1.2	Window	WCD	Window contact disablement	Enum:		
	_		contact		William contact disastement	0: Not disabled		
			disablement				Disabled	
22	1	DB1.1		KCD	Key carddisablement	Enum:		
			disablement			0:	Not disabled	
						1:	Disabled	
23	1	DB1.0		ED	External disablement	Enum:		
			disablement				0: Not disabled	
						1:	Disabled	
24	4	DB0.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						-	Teach-in	
							telegram	
	/					1:	Data telegram	1

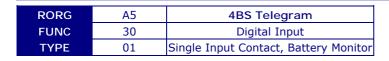
	29	1	DB0.2	Remote	RCD	Remote controller Disablement	Enum:	
	30 1			controller Disablement		(In transmit it sends the status of this parameter. If the manufacturer doesn't support this option, it will	0:	Remote controller enabled
						send allways 0, no matter what it receives.)		Remote controller disabled
	30	1	DB0.1	Window contact	WC	Window contact	0: 1:	Windows opened Windows closed
	31	1	DB0.0	Alarm State	AS	Alarm State	_	Ok Error

RORG	A5	4BS Telegram
FUNC 20		HVAC Components
TYPE	12	Temperature Controller Input

Submitter: Thermokon Sensortechnik GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8		Control Variable override	CV	Actual value for controller	0255	0100	%		
8	8	DB2.7DB2.0	FanStage override	FANOR	FanStage override	Enum:				
						0: Stage (
						2: Stage 2				
						3: Stage 3	3			
						31: auto	<u> </u>			
						255: not ava				
16	8	DB1.7DB1.0		SPS	Actual set point could be shifted	0255	-10+10	°K		
24	1	DB0.7	Fan override	FANOR		Enum:				
						0: Automa	ntic			
						1: Overrio	e Fan DB2			
25	2	DB0.6DB0.5	Controller mode	СТМ		Enum:				
						0: Auto mode				
						1: Heating				
						2: Cooling				
						3: Off				
27	1	DB0.4	Controller state	CST	Controller state	Enum:				
						0: Automa	atic			
						1: Overrio variable	e control e DB3			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-i	n telegram			
						1: Data te	legram			
29	1	DB0.2	Energy hold-off /	ERH	Energy hold-off / Dew	Enum:				
			Dew point		point	0: Normal				
						1: Energy point	hold-off/ De	ew		
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum:				
						0: Occupie	ed			
						1: Unoccu	pied			
	1					2: StandB	У			
						3: Frost				

A5-30: Digital Input



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale U	nit
0	8	DB3.7DB3.0	Not Used (= 0)	1				
8	8	DB2.7DB2.0	Supply voltage	SVC	Supply voltage (linear)	_	tery LOW	<u>-</u> -
16	8	DB1.7DB1.0	Input State	IPS	Input State	Enum: 0195: Con 196255: Con	tact closed tact open	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach-in t	-	- - -
29	3	DB0.2DB0.0	Not Used (= 0)	1				

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	02	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegra	m
						1: Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	= 0)				
31	1	DB0.0	Input State	IPS /	Input State	Enum:		
						0: Contact	closed	
						1: Contact	open	

RORG	A5	2	4BS Telegram
FUNC	30		Digital Input
TYPE	03	4 Di	gital Inputs, Wake and Temperature

Submitter: Afriso / EnOcean

Description:

This is used for universal modules with 4 digital inputs and a room temperature. The wake input signal of the device is provided to show the telegram transmission trigger. The application meaning and exact data interpretation of the digital channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered Trigger event: wake event – application dependent Teach-in method: 4BS teach-in 2

Appendix:

D1.4 – The Status of Wake signalizes the status of the WAKE PIN which has a special meaning in an ultra low application. Usually, by a status change of this input the module is triggered to perform a predefined operation.

Applications using this profile:

- water sensor conductive Wake Status = 0 (water detected)
- pressure gauge with minimum or maximum (wake signal, configurable if min or max)
- indication and individual switching points (digital channels show different areas)

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Not Used (= 0)				
8	8	DB2.7DB2.0	Temperature	TMP	Temperature (linear)	2550	040 °C
16	3	DB1.7DB1.5	Not Used (= 0)				
19	1	DB1.4	Status of Wake	WA0	Value of wake signal	Enum: 0: Low	
						1: High	
20	1	DB1.3	Digital Input 3	DI3	Digital Input 3	Enum:	/
						0: Low 1: High	
21	1	DB1.2	Digital Input 2	DI2	Digital Input 2	Enum:	
						0: Low 1: High	
22	1	DB1.1	Digital Input 1	DI1	Digital Input 1	Enum:	
						0: Low 1: High	
23	1	DB1.0	Digital Input 0	DI0	Digital Input 0	Enum:	
						0: Low	
						1: High	
	4	DB0.7DB0.4	Not Used $(= 0)$				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-in	telegram
						1: Data tele	egram
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	04	3 Digital Inputs, 1 Digital Input 8 Bits

Submitter: Afriso / EnOcean

Description

This profile is used for universal module with 1 analog input (= 8 bits resolution digital) and 3 digital inputs. The application meaning and exact data interpretation of the input channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: values have changed Teach-in method: 4BS teach-in 2

(Offse	tS	ize	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
(0	1	6	DB3.7DB2.0	Not Used (= 0)					
4	16	8		DB1.7DB1.0	Digital value-input	DV0	Digital value 1 byte	0255	0255	N/A
	24	4		DB0.7DB0.4	Not Used (= 0)					

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:	
						0:	Teach-in t	elegram
						1:	Data teleg	ıram
29	1	DB0.2	Digital Input 2	DI2	Measured digital Input 2	Enum	:	
						0:	Low	
						1:	High	
30	1	DB0.1	Digital Input 1	DI1	Measured digital Input 1	Enum	:	
						0:	Low	
						1:	High	
31	1	DB0.0	Digital Input 0	DI0	Measured digital Input 0	Enum	:	
						0:	Low	
						1:	High	

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	05	Single Input Contact, Retransmission, Battery Monitor

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval:

- retransmission: 5 ... 255 seconds (one time configuration)

- number of retransmission times: 0 ... 127 times (one time configuration)

- heartbeat: 60 ... 65535 seconds (one time configuration) Trigger event: digital input, retransmission, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used $(=0)$					
8	8	DB2.7DB2.0	Supply voltage		Supply voltage	0255	03.3	V
16	1	DB1.7	Signal type	ST	Signal type	Enum: 0: Normal signal 1: Heart beat signal	_	
17	7	DB1.6DB1.0	Index of Signals	IOS		Enum: Increment a co 0127: telegram	unter by new	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram	_	
29	3	DB0.2DB0.0	Not Used (= 0)					

A5-37: Energy Management

RORG	A5	4BS Telegram		
FUNC	37	Energy Management		



Submitter: Echoflex Solutions Inc.

Purpose of EEP:

Demand Response is a developing standard to allow utility companies to send requests for reduction in power consumption during peak usage times. It is also used as a means to allow users to reduce overall power consumption as energy prices increase. Having an EEP for this will allow ease of integration with EnOcean products to this standard. The EEP was designed with a very flexible setting for the level (0-15) as well as a default level whereby the transmitter can specify a specific level for all controllers to use (0-100% of either maximum or current power output, depending on the load type). This EEP also includes a timeout setting to indicate how long the DR event should last if the DR transmitting device does not send heartbeats or subsequent new DR levels.

Description:

This EEP is included under a new function of Energy Management. Additional types could be added in future for power, voltage, and current data. The proposed EEP type 01 only deals with demand response activation at this point. Data Byte 3 is the default DR value for devices that implement a control algorithm that uses a set-point. It will be used for any controllers not supporting the current DR Level in the message and having an adjustable set-point.

Data Byte 2 is the default DR Level for any controllers not supporting the current DR Level in the message and having an adjustable control. It can be defined as either a percentage of the maximum power or a percentage of the current power, depending on the value of bit 7 in Data Byte 2. Bits 0 through 6 contain the percentage of power (either relative or absolute) that should be used. A value of 0 corresponds to 0% and a value of 100 corresponds to 100%. Any value higher that n100 should be interpreted as 100%. For example, if the current DR level is not supported by the controller and Data Byte 2 bit 7 is 0 and Data Byte 2 bits 0 through 6 are set to 55, then the controller should try to use 55% of its maximum power usage. In the case of a lighting load with 0-10V dimming, this would correspond to 5.5V on the dimming line. In the case of a heating controller with a maximum set back of 5 degrees C, this would correspond to a set back of 2.75 degrees C (this would most likely be rounded to 3).

Data Byte 1 is the timeout for this DR event. After this command is sent the controller will stay at the DR level for Data Byte 1 multiplied by 15 minutes. Once this time has elapsed the controller will return to normal operation. If Data Byte 1 is 0 then the controller will remain in the DR event until the next DR command is received. This timeout allows DR devices to leave or turn off after setting controllers into a DR state, thus the DR transmitter is not needed to take the devices out of the DR state and the controllers will automatically recover. For example a DR transmitter that only sends messages when a DR event is active could be used with the timeout to create a successful DR system.

Data Byte 0, Bits 7 through 4 make up a nibble that will be used as the DR level. Levels 0 through 15 will be possible using these bits. Bit 4 will be the lowest bit in this nibble and bit 7 will be the highest. If any level is not supported by a controller then that controller should use the default settings sent in this message or map the level to one that it supports.

Data Byte 0 Bits 2 and 1 indicate whether the power adjustment at start and end of the DR event should be randomized or not. This feature is intended to minimize rapid changes on the power distribution equipment by delaying each controller's response. If random start or end is enabled, each controller will delay starting or ending the DR event by a random time that will vary uniformly over a specific time period (for example, 5 seconds, 60 seconds, or 15 minutes).. The maximum length of these random delays will depend on the implementation in the controller.

Data Byte 0, Bit 0 is the state for loads that are not adjustable for the default DR level. If a controller does not support the current DR level and does not have adjustable control then it should use this bit. The two states of this bit are defined as follows: 1 = maximum power usage by controller, 0 = minimum power usage by the controller. If for example lights are being controlled, then a setting of 1 will mean the lights should be ON, where as a setting of 0 will mean the lights should be OFF. For a thermostat application with non adjustable set back, a setting of 1 will mean that no set back should be applied, whereas a setting of 0 will mean that the full set back should be applied. This setting only applies to the maximum power usage of the controller, if for example the lights are currently off and the controller receives a DR event with this bit set, then the lights should not turn ON as the DR event has only set the maximum power usage for the device.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Temporary default		New Temporary default DR set point Min Max. (linear)		0255	N/A
8			Absolute/relative power usage	SPWRU		percentage power use. 1: Relative power DB_2.BIT_6	wer usageDB_2.BIT_0 of the maximu wer usage. InteDB_2.BIT_0 of the current	rpret

9	7	DB2.6DB2.0	Power Usage	PWRU	0% to 100% power usage in 1% increments; 101127 = interpreted as 100%	0100	0100	N/A
16	8	DB1.7DB1.0	Timeout Setting	TMOS	Time in 15 min. intervals; 0 = No time specified; 1255 = increasing 15 min. intervals. Max value: 3825 = 255*15	1255	153825	min
24	4	DB0.7DB0.4	DR Level	DRL	DR Level	015	015	N/A
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in tel 1: Data telegra		
29	1	DB0.2	Random start delay	RSD		Enum: 0: False 1: True		
30	1	DB0.1	Randomized end delay	RED		Enum: 0: False 1: True		
31	1	DB0.0	Max/Min Power Usage for Default DR State	MPWRU		0: Minimum Po		-

A5-38: Central Command

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	08	Gateway

Communication between gateway and actuator uses byte DB_3 to identify Commands. Commands 0x01 to 0x7F shall be common to all types belonging to this profile. Commands 0x80 to 0xFE can be defined individually for each device type.

0x01 Switching

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x01:	_	
8	16	DB2.7DB1.0	Time/	TIM	Time in $1/10$ seconds. $0 = no$ time specifed	165535	0.16553.5	S
24	4	DB0.7DB0.4	Not Used (= (0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tel	ach-in egram ta telegram	
29	1	DB0.2	Lock/Unlock	LCK	Lock for duration time if time >0, unlimited time of no time specified. Locking may be cleared with "unlock". During lock phase no other commands will be accepted or executed	Enum: 0: Ur 1: Lo	lock ck	

30	1	DB0.1	Delay or duration	DEL	Delay or duration (if Time > 0); 0 = Duration (Execute switching command immediately and switch back after duration) 1 = Delay (Execute switching command after delay)	Enum: 0: Duration 1: Delay
31	1	DB0.0	Switching Command	SW	Switching Command ON/OFF	Enum: 0: Off 1: On

0x02 Dimming

REMARK:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x02:	_	
8	8	DB2.7DB2.0	Dimming value	EDIM	Dimming value (absolute [0255] or relative [0100])	0255	0100	%
16	8	DB1.7DB1.0	Ramping time	RMP	Ramping time in seconds, 0 = no ramping, 1 255 = seconds to 100%	0255	0255	S
24	4	DB0.7DB0.4	Not Used $(= 0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tele 1: Dat	ech-in egram ta egram	
29	1	DB0.2	Dimming Range	EDIM R	Dimming Range	val	ative	
30	1	DB0.1	Store final value	STR	Store final value	Enum: 0: No 1: Yes		
31	1	DB0.0	Switching Command	SW	Switching Command ON/OFF	Enum: 0: Off 1: On		

0x03 Setpoint shift

Submitter: Thermokon Sensortechnik GmbH

Used for changing set point, for example summer / winter compensation

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x03:		
8	8	DB2.7DB2.0	Not Used ((= 0)				
16	8	DB1.7DB1.0	Setpoint	SP	Setpoint shift	0255	-12.712.8	K
24	4	DB0.7DB0.4	Not Used ((= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used ((= 0)				
	/				•	•	•	

0x04 Basic Setpoint

Submitter: Thermokon Sensortechnik GmbH

Send a new basic set point via DDC to an actuator

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x04:		
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Basic Setpoint	BSP	Basic Setpoint	0255	0+51.2	°C
24	4	DB0.7DB0.4	Not Used (= 0)	_	_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (= 0)				

0x05 Control variable

Submitter: Thermokon Sensortechnik GmbH

Set occupancy, energy holdoff and control directly actuator

Offset			Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x05:		
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	Control variable override	CVOV	Control variable override	0255	0100	%
24	1	DB0.7	Not Used (= 0)					
25	2	DB0.6DB0.5	Controller mode	СМ	Controller Mode	Enum: 0: Automatic selection 1: Heating 2: Cooling 3: Off	: mode	
27	1	DB0.4	Controller state	CS	Controller state	Enum: 0: Automatic 1: Override	<u></u>	
28	1	DB0.3	LRN Bit	L RNB	LRN Bit	Enum: 0: Teach-in t 1: Data teleg		_
29	1	DB0.2	Energy hold off	ENHO	Energy Hold Off	Enum: 0: Normal 1: Energy ho point	oldoff/ Dew	,
30	2	DB0.1DB0.0	Room occupancy	RMOCC	Room occupancy	Enum: 0: Occupied 1: Unoccupie 2: Standby	ed	

0x06 Fan stage

Submitter: Thermokon Sensortechnik GmbH

Set directly fan stage

Offset Size Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
----------------------	------	----------	-------------	-------------	-------	------

0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x06:
8	8	DB2.7DB2.0	Not Used (= 0)			
16	8	DB1.7DB1.0	FanStage override	FO	FanStage override	Enum: 0: Stage 0 1: Stage 1 2: Stage 2 3: Stage 3 255: Auto
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

0x07 Blind Central Command

Submitter: PEHA / infrated

With this central command all blinds, awnings and shutters can be manipulated.

Remarks for data table:

REMARK 1:

The angle is usually available in blinds and awning modules.

Normally, in shutter modules the angle value is ignored.

The angle value can be set from -180° (e.g. maximum slat angle at the fully SHUT position) to 180° (e.g. maximum slat angle at the fully OPEN position).

The byte is set with following rule:

Bit7: Sign of the slat angle (0 = positive value, 1 = negative value)

Bit6..0: Slat angle value in 2° steps (e.g. $50 = 100^{\circ}$)

REMARK 2:

If this function (Blind drives to position with angle value) is not supported or not configured, use following rule:

- Position is 0 to 49% -> The blind opens
- Position is 50 to 100% -> The blind closes.

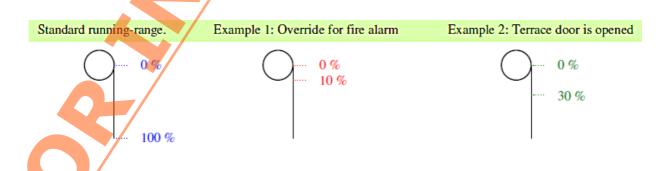
REMARK 3:

Conventional blinds and shutters can be configured with these 3 parameters to calculate the sufficiently accurate position and angle of the blind.

REMARK 4:

With this command you can adjust the minimal and maximal position of the blinds. So it's possible to override the running-range of blinds via a central control unit. Local operations are restricted and increase safety (e.g. to open blinds in case of wind or fire).

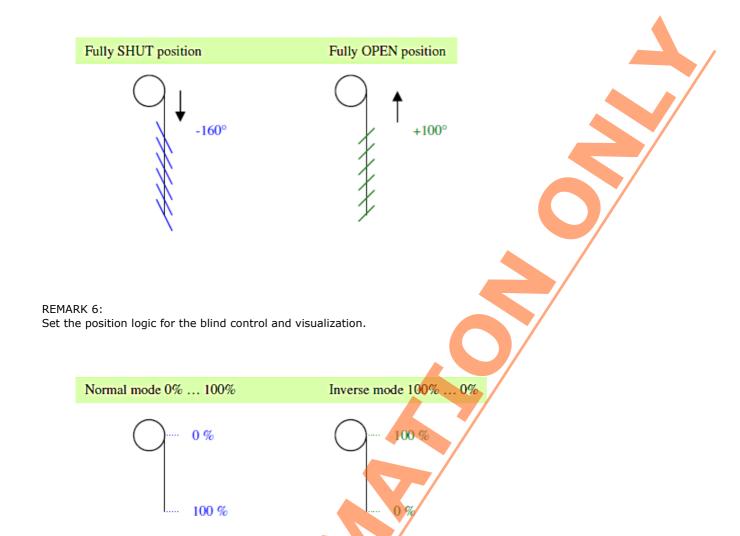
Condition: The Minimal value must be smaller or equal the maximal value.



Example to lock the local functionality: Drive the shutters to a define position and set the minimal and maximal values to this position.

REMARK 5:

These to angle values describe the maximum slat angle at the fully SHUT position and the maximal slat angle at the fully OPEN position. With the time parameter, e.g.:



Note: If the mode is changed, the minimum and maximal values (function 9) are converted as well!

REMARK 7:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

						ı		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x07: Shutters / Blinds		
8	8	DB2.7DB2.0	Parameter 1			Enum:		
					parameter value	Func. 00: not used	l	
			5/			Func. 01: not used	l	
		_				Func. 02: not used	l	
						Func. 03: not used	l	
	4					Func. 04: 0% 100	%	
						e.g.: 0% = Blind fully Blind fully closed	open / 100	0% =
						Billia fally closed		
						Func. 05: 0 255 se	econds	
						Func. 06: 0 255 se	econds	
						Func. 07: Runtime va blind 0 255 seconds	alue to close	e the

								Func. 08: Runtime value for the sunblind reversion time This is the time to revolve the sunblind from one
								slat angle end position to the other end position: 0.0 25.5 seconds (0.1s steps)
								Func. 09: Set minimal position value 0 100%
								Func. 10: Angle at the fully SHUT position Bit7 0 = positive sign
								Bit 7 1 = negative sign Bit60 0 90 Angle in 2° steps (e.g. 0 = 0°, 90 =
								180°) Func. 11: Position logic
								0 = Highest position = 0% / Lowest position = 100% 1 = Highest position = 100% / Lowest
-	16	8	DB1.7DB1.0	Parameter 2	P2	Function defined parameter value	Enum	position = 0% Func. 00: not used
								Func. 01: not used
								Func. 02: not used
								Func. 04: Angel (see remark 1) Bit7 0 = positive sign
								Bit7 1 = negative sign Bit60 0 90 Angle in 2° steps (e.g. 0 = 0°, 90 =
								180°) Func. 05: 0.0 25.5 seconds
								Func. 06: 0.0 25.5 seconds
								Func. 07: Runtime value to open the blind 0 255 seconds
								Func. 08: not used
								Func. 09: Set maximal position value 0 100%
								Func. 10: Angle at the fully OPEN position
				/-				Bit7 0 = positive sign Bit7 1 = negative sign Bit60 0 90
								Angle in 2° steps (e.g. 0 = 0°, 90 = 180°)
ļ								Func. 11: not used
	24	4	DB0.7DB0.4	Function	FUNC		Enum: 0:	Do nothing, status request
							1:	Blind stops
							2:	Blind opens
1	7	/					3:	Blind closes

						4:	Blind drives to position with angle value (see remark 2)
						5:	Blind opens for time (position value) and angle (angle value)
						6:	Blind closes for time (position value) and angle (angle value)
						7:	Set Runtime parameters (see remark 3)
						8:	Set angle configuration (see remark 3)
						9:	Set Min, Max values (see remark 4)
						10:	Set slat angle for SHUT and OPEN position (see remark 5)
						11:	Set position logic (see remark 6)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Send status	SSF	see remark 7	Enum:	
			flag			0:	Send new status of device
						1:	Send no status (e.g. Global central commands)
30	1	DB0.1	Pos. and	PAF		Enum:	. //
			Angle flag			0:	No Angle and position value available
						1:	Angle and position value available
31	1	DB0.0	Service	SMF		Enum:	
			Mode Flag			0:	Normal operation
						1;/	Service mode: The module disables all
							senders, except this sender, which has
							set the service mode. (For example for maintenance)
-							

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	09	Extended Lighting-Control

Submitter: PEHA / infrated

With this central command all lighting actors can be manipulated.

Remarks for data table:

REMARK 1:

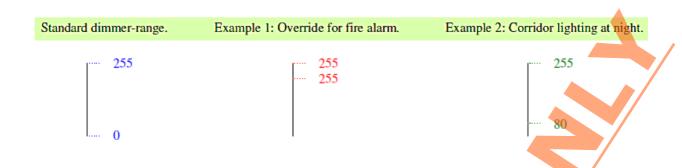
Set the RGB level for corresponding lighting-control. Devices without this feature ignore this command.

REMARK 2:

Up to 16 different scenes can be selected and configured.

REMARK 3:

Change the minimal and maximal dimmer-value. Example:



General for switchers:

The values 0 .. 127 are defined to "Off". The values 128.. 255 are defined to "On".

REMARK 4

Example: If the lamp was replaced, the operating hours are reset to 0.

REMARK 5:

This function blocks all other commands from the other taught-in transmitters. The transmitter, which has called this function, must delete the blocking state, before the other transmitters can use the device again.

REMARK 6

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

REMARK 7:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

			_					
Offset			Data	ShortCut		Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Parameter	P1		Enum:		
			1		parameter value	Func. 00: not us	ed	
				•		Func. 01: not us	ed	
						Func. 02: not us		
						Func. 03: not us	ed	
						Func. 04: not us	ed	
						Func. 05: not us	ed	
			- 44			Func. 06: Dimm-Va	lue (0 255)
						Func. 07: R - Red (0 255)	
		4				Func. 08: not us	ed	
						Func. 09: Dimm-Va	lue (0 255)
						Func. 10: Lamp op 158)	erating hours	(MSB
						Func. 11: not us	ed	
						Func. 12: Energy m 158)	netering value	(MSB
8	8	DB2.7DB2.0	Parameter	P2	Function defined	Enum:		
			2		parameter value	Func. 00: not us	ed	
						Func. 01: not us	ed	
						Func. 02: not us	ed	
						Func. 03: Ramping (65535 s)	time (MSB 15	58)

						Func. 04: Ramping time (MSB 158)
						(65535 s)
						Func. 05: not used
						Func. 06: Ramping time (MSB 158) (65535 s)
						Func. 07: G - Green (0 255)
						Func. 08: not used
						Func. 09: Dimm-Value (0 255)
						Func. 10: Lamp operating hours (70 LSB)
						Func. 11: not used
						Func. 12: Energy metering value (70 LSB)
16	8	DB1.7DB1.0	Parameter	Р3	Function defined	
			3		parameter value	Func. 00: not used
						Func. 01: not used
						Func. 02: not used
						Func. 03: Ramping time (70 LSB) (65535 s)
						Func. 04: Ramping time (70 LSB) (65535 s)
						Func. 05: not used
						Func. 06: Ramping time (70 LSB) (65535 s)
						Func. 07: B - Blue(0 255)
						Func. 08:
						Bit7: 0 = Drive to scene-value Bit7: 1 = Stores actual value in the
						scene
						Bit30: Scene number 0 15
						Func. 09: not used
						Func. 10: not used
						Func. 11: Blocks the local operations Enum:
						0 = Unlock local operations
						1 = Locking switch on commands2 = Locking switch off commands
						3 = Locking local operations
						Func. 12: Unit of energy metering value
						Enum: 0 = mW
						1 = W
						2 = kW 3 = MW
						4 = Wh
						5 = kWh
						6 = MWh 7 = GWh
						8 = mA
						9 = 1/10 A 10 = mV
						11 = 1/10 V
						12 15 Not used

24	4	DB0.7DB0.4	Function	FUNC		Enum:	
						0:	Do nothing, status request
						1:	Switched off
						2:	Switched on (Memory value)
						3:	Dimming up with ramping time
						4:	Dimming down with ramping time
						5:	Dimming stops
						6:	Set dimmer-value and ramping time
						7:	Set RGB values (see remark 1)
						8:	Scene function (see remark 2)
						9: 	Set minimal and maximal dimmer-value (see remark 3)
							Set the operating hours of the lamp (see remark 4)
							Locking local operations (see remark 5)
						12:	Set a new value for the energy metering (overwrite the actual value with the selected unit)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in telegram
20		DD0 2	C	CCE	1.0	1:	Data telegram
29	1	DB0.2	Send status flag	55F	see remark 6	Enum: 0:	Send new status of device
						1:	Send no status (e.g. Global central commands)
30	1	DB0.1	Store final	SFV		Enum:	<u> </u>
			value			0:	No
						1:	Yes
31	1	DB0.0	Service	SMF		Enum:	
			Mode Flag			0:	Normal operation
						1:	Service mode: The module disables all senders, except this sender, which has
							set the service mode. (For example for maintenance)
							•

A5-3F: Universal

RORG	A5	4BS Telegram
FUNC	3F	Universal
TYPE	00	Radio Link Test (BI-DIR)

Submitter: PROBARE

Units supporting the EEP Radio Link Test shall offer a functionality that allows for radio link testing between them (Position A to Position B, point-to-point only). Testing shall be possible without the need for prior teach-in and as an option it shall cover two way communications.

Further, testing shall be backward compatible to existing EnOcean installations that support at least 1BS (RORG=0xD5) and 4BS (RORG=0xA5) EnOcean messages.

The main area of RLT application are in-field testing of radio links between portable test equipment placed at different locations as well as between portable test equipment and fixed installation, e.g. an EnOcean Gateway.

Functional description of RLT:

When two units perform radio link testing one unit needs to act in a mode called RLT Master and the other unit needs to act in a mode called RLT Slave. On a RLT enabled unit one or both modes may be supported. The mode(s) supported shall require explicitly activation at run time.

After activation a RLT Master listens for RLT_Query messages. On reception of at least one RLT_Query message a RLT Master responds with an RLT_Response message. Following that it starts transmission of RLT_MasterTest messages within a maximum time frame of 250ms and awaits the response from the RLT Slave for each RLT_MasterTest message sent. A radio link test communication consists of a minimum of 16 and a maximum of 256 RLT_MasterTest messages. Timing distance between individual RLT_MasterTest messages shall not exceed 250ms. When the radio link test communication is completed the RLT Master gets deactivated automatically.

After activation a RLT Slave periodically transmits RLT_Query messages (1 message / 2s). It stops transmission of RLT_Query messages as soon as it has received at least one RLT_Response message. It then waits for RLT_MasterTest messages from the same EnOcean ID and replies to them within a maximum delay of 100ms thru RLT_SlaveTest messages. If it does not receive RLT_MasterTest messages from the same EnOcean ID for a time period of 5s, the RLT Slave restarts periodic transmission of RLT_Query messages. The RLT Slave requires explicit deactivation.

RLT_Query Message

This Message is a "4BS Teach-In Query" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process.

RLT_Response Message

This Message is a "4BS Teach-In Response" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process. As a RLT Master does accept teach-in of a RLT Slave only for the time period required by a single RLT communication it shall indicate the EEP to be supported but the EnOcean ID of the RLT Slave not to be stored permanently.

RLT_MasterTest_4BS

This is the 4BS message sent by the RLT Master during a radio link test communication DIRECTION- 1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	28	DB3.7DB0.4	Not Used (=	0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	2	DB0.2DB0.1	MSG_ID	MSGID	Message ID	Enum:
						2:
31	1	DB0.0	MSG-Source	MSGS	Message Source	Enum:
						0: RLT-Master

RLT_SlaveTest_4BS

This is the 4BS message sent by the RLT Slave in reply to an RLT_MasterTest_4BS message. DIRECTION- 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	2	DB3.7DB3.6	Sub-Telegram Counter		related to RLT_MasterTest_4BS message received Repeater level 2	1: 1 si tele 2: 2 si tele 3: ≥ 3	not supported 1 sub telegram 2 sub telegram ≥ 3 sub telegram	
2	6	DB3.5DB3.0	RSSI Level in dBm		related to RLT_MasterTest_4BS message received Repeater level 1	Enum: not 0x00: sup ≥-3 0x01:	ported 1	dBm

							32	JD
						0x02:	02	dBm
						0x3F:	-93	dBm
8	8	DB2 7 DB2 0	Sub-Telegram	RSLV	Related to RLT MasterTest 4BS	Enum:		dDIII
J	O	002.7002.0	Counter/RSSI Level in dBm	NSEV	message received Repeater level 1 (for details see DB3)		ee prev	
16	8	DB1.7DB1.0	Sub-Telegram	RSLV	Related to RLT_MasterTest_4BS	Enum:		
			Counter/RSSI Level in dBm		message received direct link	: Se	ee prev	
24	4	DB0.7DB0.4	RSSI Level in dBm	RSLV	Non-EnOcean signal detection since	Enum:		
					last RLT_MasterTest message RSSI Level with 6dB quantization steps	0x00: si	ot upported	
						0x01:	-31	dBm
						0x02:	3237	dBm
						0x03:	3843	dBm
						0x04:	1449	dBm
							5055	
						0x05:		dBm
						0x06:	5661	dDm
							5267	dBm
						0x07:		dBm
						0x08:	5873	dBm
						0x09:	7479	dBm
						0x0A:	3085	dBm
							-92	ID.
20	1	DB0 3	LDN Dit	LDND	I DNI Dib	0x0B:		dBm
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	and in	
							each-in elegram	
							ata telegra	am
29	2	DB0.2DB0.1	MSG_ID	MSGID		Enum:	_	
						2:		
31	1	DB0.0	MSG-Source	MSGS		Enum:		_
						1: RI	LT-Slave	

RLT_MasterTest_1BS

This is the 1BS message sent by the RLT Master during a radio link test communication.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION- 1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	4		RLT MSG-Counter MSB		Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
5	2		RLT MSG-Counter LSB		Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :

7	•	1	DB3.0	MSG-Source	MSGS	Message Source	Enum:
							0: RLT Master

RLT_SlaveTest_1BS

This is the 1BS message sent by the RLT Slave in reply to an RLT_MasterTest_1BS message.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION-2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	4		RLT MSG-Counter MSB	MC-MSB	Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum:
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
5	2	DB3.2DB3.1	RLT MSG-Counter LSB	MC-LSB	Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum:
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum: 1: RLT-Slave

RORG	A5	4BS Telegram
FUNC	3F	Universal
TYPE	7F	Universal

Submitter: EnOcean GmbH

Description

This profile was intended for manufacturer specific applications. Every manufacturer may independently define the types within this profile.

This profile was replaced by the use of MSC-Telegrams with the advantage of more payloads and the manufacturer Id as identification. For future applications only use MSC-Telegrams.

This description is only necessary for legacy reasons.

Data exchange

Direction: unidirectional / bidirectional Addressing: unicast (ADT) / broadcast

Communication trigger: event- & time-triggered Communication interval: application specific

Trigger event: application specific

Tx delay: not specified Rx timeout: not specified

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: no Security level format:

0	ffse	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
O		28	DB3.7DB0.4	undefined	undef	undefined			
28	3	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							0: Teach-ir	telegra	m
		1/					1: Data tel	egram	
29)	3	DB0.2DB0.0	undefined	undef	undefined			

D2: VLD Telegram

D2-00: Room Control Panel (RCP)

The Communication is based on the Smart Ack concept. Some basics related hereto are included in this document for convenience but for details please consult the Smart Ack specification.

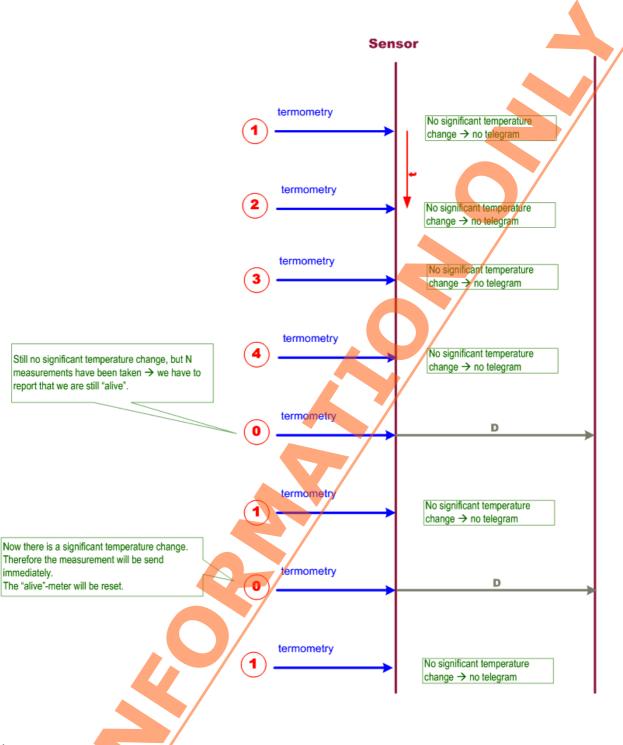
A Room Control Panel (RCP) compliant to this EEP offers the following features:

- Multi symbol, multi segment LC display (or equivalent)
- 1 temperature measurement channel, remote configurable
- 1 temperature set point control (e.g. key pad based)
- 1 fan speed control (e.g. key pad based)
- 1 presence control (e.g. key pad based)

Repeater operation shall work in compliance with the Smart Ack specification.

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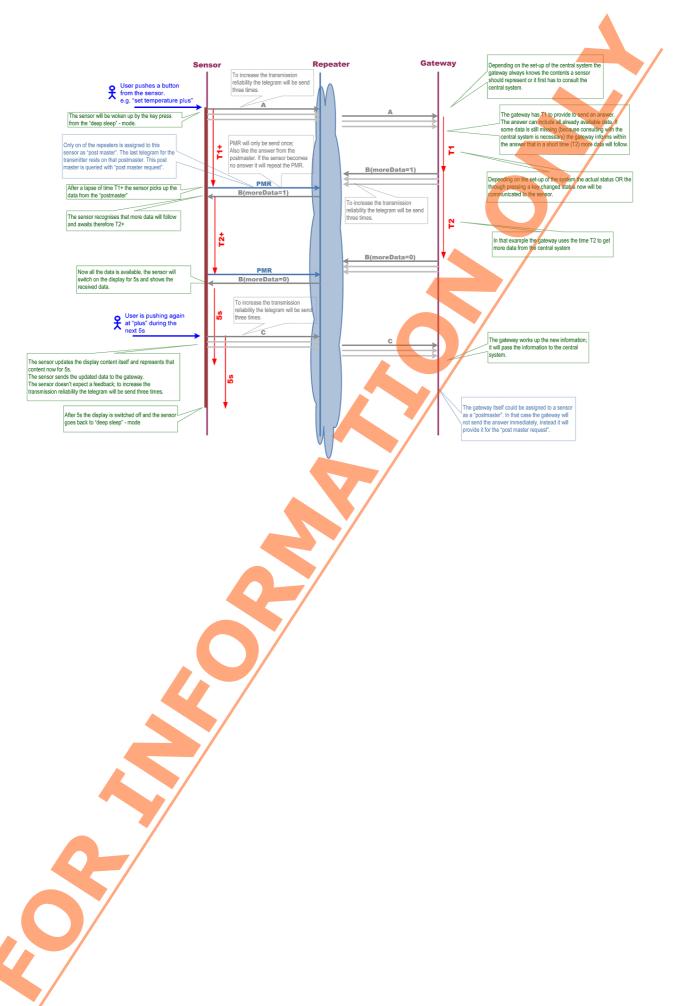
Use Case: Temperature Measurement



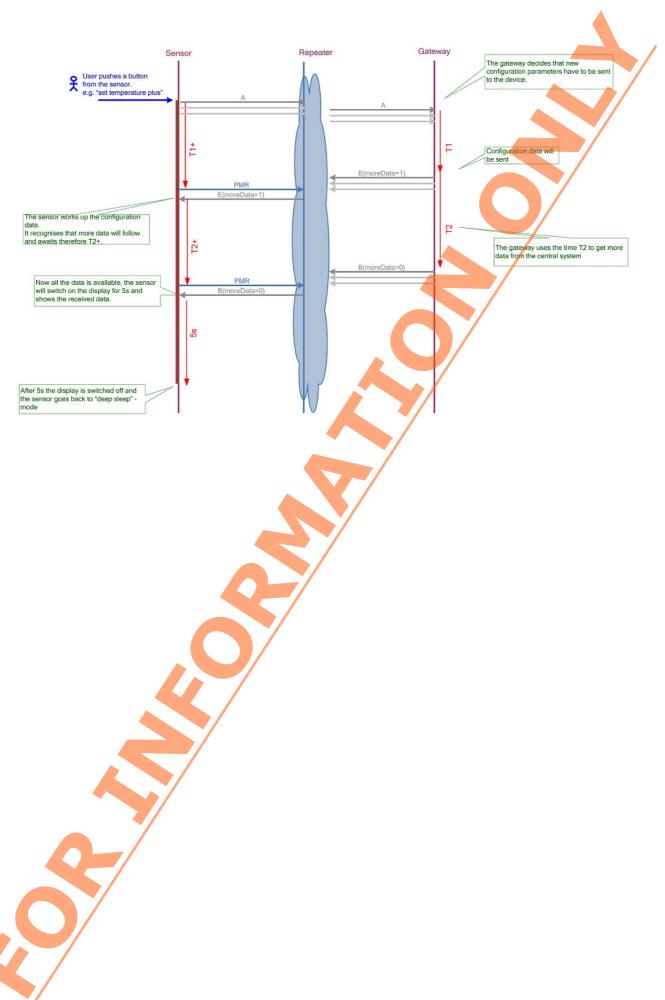
REMARK:

Temperature measurement may be configured by the Gateway, see chapter "Message Type E – RCP Configuration".

Use Case: User Interaction



Use Case: User Interaction including transfer of configuration data



RORG	D2	VLD Telegram
FUNC	00	Room Control Panel (RCP)
TYPE	01	RCP with Temperature Measurement and Display (BI-DIR)

Submitter: Fr. Sauter AG

Note: EEP Release 2.1, 2.5, and 2.6 reflected a wrong byte-order for all messages of this EEP!

Example Message Type A:

Instead of DB_1 = 0x01 DB_0 = 0x81 (which is correct for KP=1 and CV=1)

by mistake $DB_1 = 0x81 DB_0 = 0x11$ (which is wrong) was printed.

We apologize for the mistake.

Message type A / ID 01 (First User Action on RCP)

Direction: Sensor -> Gateway

Transaction Response: Message Type B or Type E

Chaining: No

Timing: T1+ = 170ms

Message A / ID 01

Data[0] Data[1] Original Identifier:

				DB	_1							DB	_0			
$DB_1.BIT_7 \leftarrow 0$	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
							MI		CV					ΚP		

Offset	Size	Data	ShortCut	Description	Va	lid Range	Scale	Unit
0	5	Not Used (=	= 0)					
5	3	MsgId		Message Id; 0x01	Enum: 1: Message	ge Id		
8	1	ConfigValid	CV		0x00: messa	guration data not valid age of type E) guration data valid	(e.g. never receiv	ed
9	2	Not Used (=	= 0)					
11	_	User Action	KP		Enum: 0x00: 0x01: 0x02: 0x03: 0x04: 0x05: 0x06: 0x070x1F	not used Presence Temperature Set Point used not used Temperature Set Point used Temperature Set Point Fan		

Message Type B / ID 02 (Display Content)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms

	М	ess	sa	ge	В	1	IC	0:	2																													1		
Original Identifier:				Dat	a[(0]						Dat	a[1]							Dat	a[2	2]						Dat	a[3]						Dat	ta[4	1]		
				DE	3_4	4			Γ			DB	3_3				Г			DB	_2	2						DB	_1							DI	3_0			
DB_4.BIT_7 \leftarrow 0	7	6	5	4	3	2	1	. 0	7	7 6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 39	0	1	2	3	4	5	6	7	8	3 9	10	11	12	13	14	15	1	6 17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39
	М		F		MI	D	M.	I	Г	PR				TΑ			7			Z	Ą		- 1	0	15			- 2	A.			8				Se	Sd	Sc	ЗЬ	Sa
																																	-	4						7

IMPORTANT NOTE:

The symbols Sa, Sb, Sc, Sd, Se are optional. One or more of those symbols are available on the display only if the manufacturer of a RCP implements them in a specific design. Thus, they are NOT mandatory for a RCP in order to comply with this EEP.

Unidet.	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	1	Fan manual	М		Enum:			
					0: Auto			
					1: Fan ma	anual		
1	3	Fan	F		Enum:			
					0x00:	Do not displa	ay	
					0x01:	Speed Level	0	
					0x02:	Speed Level	1	
					0x03:	Speed Level	2	
					0x04:	Speed Level	3	
					0x050x07	not used		
4	1	MoreData	MD		Enum:			
					0x00: no mo	ore data		
					0x01: more	data will follow	w after T2+	
5	3	MsgId	MI	Message Id;0x02	Enum:			
					2: Messag	ne Id		
8	3	Presence	PR		Enum:	, - ·		
	Č				0x00:	Do not displa		
					0x01:	Present		
					0x02:	Not present		
					0x03:	Night time re	eduction	
					0x040x07			
11	5	Figure A Type	TA		Enum:			
	Č		., .		0x00:	Do not displa	V	
					0x01:	Room Tempe		°C
					0x02:	Room Tempe		°F
					0x03:	Nominal Tem		°C
					0x04:	Nominal Tem		°F
					0x05:		rature Set Point	°C
					0x06:		rature Set Point	°F
					0x07:	Delta Temper		
						Point(graphic		
					0x08:	Time 00:00 t	o 23:59 [24h]	
					0x09:	Time 00:00 t	o 11:59 [AM]	
					0x0A:	Time 00:00 t	o 11:59 [PM]	
					0x0B:	Date 01.01 to	o 31.12 [DD.MM]	
					0x0C:	Date 01.01 to	o 12.31 [MM.DD]	
					0x0D:	Illumination ((linear) 0 to 9999	lx
					0x0E:	Percentage 0	to 100	%
					0x0F:		ion 0 to 9999	ppm
					0x10:	Relative Hum	nidity 0 to 100	% rH
					0x110x1F:	not used		
16	16	Figure A Value	ZA	Format according to				
16	10	rigule A value	ZA	TA:	Enum:	7.0 4000	0.010	
				Byte-Order: Little-	-	7: 0 4000	0.01°	
				Endian!		A: Time 0000 .		
						0 9999		
					0x0D:	0 9999	lx	

					0x0E0x10: 0 10000	0.01%
					0x0F: 0 9999	ppm
32	3	Not Used (= 0)			
35	1	User Notification	Se	optional	Enum: 0x0: Off 0x1: On	
36	1	Window	Sd	optional	Enum: 0x0: Closed 0x1: Opened	
37	1	Dew-Point	Sc	optional	Enum: 0x0: Warning 0x1: No warning	
38	1	Cooling	Sb	optional	Enum: 0x0: Off 0x1: On	
39	1	Heating	Sa	optional	Enum: 0x0: Off 0x1: On	

Message Type C / ID 03 (Repeated User Action on RCP)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No

Timing: may only be sent within 5s from latest receipt of a Message Type B

Message C / ID 03

Original Identifier:			[Dat	a[0]]						Dat	a[1]	<u> </u>					Data	1[2]						Data	a[3]		
				DB	_3							DB	_2	7/						DB	_1							DB.	_0			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	F MI						PR				TA			7			Z	4			. 0	15			Z.	A			8			

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0)					
1	3	Fan	F		Enum:		
					0x00: r	no change	
					0x01: 9	Speed Level 0	
					0x02:	Speed Level 1	
					0x03:	Speed Level 2	
					0x04:	Speed Level 3	
					0x05: S	Speed Level Auto	
					0x060x07: r	not used	
4	1	Not Used (= 0)					
5	3	MsgId	MI	Message Id; 0x03	Enum:		
					3: Message	Id	
8	3	Presence	PR		Enum:		
					0x00: r	no change	
					0x01: F	Present	
					0x02:	lot present	
					0x03: N	light time reduction	
					0x040x07: r	not used	
11	5	Set Point A	TA		Enum:		
		Type			0x00: r	o change	

				0x010x04: 0x05:	Temperature Set Point olimitation of the control o
16	16	Set Point A Value	Format according to TA: 0x05 [0.01°] Byte-Order: Little-Endian!	-1270+1270	-12.70+12.70 °

Message Type D / ID 04 (Measurement Result)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No Timing: None

Message D / ID 04

Original Identifier:				Dat	a[0]				Data[1]					A	Data[2]									
DB_2							DB_1										DB	_0						
DB_3.BIT_7 ← 0		6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🔿 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
,							ΜI		7 VA			0		Ť	Ä_		11	\	/A	8				

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	5	Not Used (= 0)					
5	3	MsgId	MI	Message Id;0x04	Enum:		
					4: Message Id		
8	8	Channel A Value	VA (LSB)	Format according to TA:	04000	040.00	0
				LSB (Bit 7 , 0)			
16	4	Channel A Type	TA		Enum:		
					0x00: Temper	ature [°C]	
					0x010x0E: not use	ed .	
					0x0F: Measur	ement result not	valid
20	4	Channel A Value	VA (MSB)	See: VA (LSB)			
				MSB (Bit 11 8)			

Message Type E / ID 05 (Sensor Configuration)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4		MoreData	MD		Enum: 0x0: no more data 0x1: more data will for	ollow after T2+	
5	3	MsgId	MI	Message Id; 0x05	Enum: 5: Message Id		
8	1	Not Used (= 0)					
9	7	Set Point Range Limit	SPR	Limit of Set Point Range, absolute value: REMARK: Set Point Range shall be symmetrical to 0°	Enum: 0x00: Set Poin 0,1° 1 0x010x7F: [0,1°]		12.7°
16	1	Not Used (= 0)					
17	7	Set PointSteps	SPS	Number of Set Point Steps: REMARK: Specifies the number of equidistant steps between 0 and Set Point Range Limit	Enum: 0x00: Set Poir 0x010x7F:1 127	at disabled	127
24	4	Temperature Measurement Timing	TT (LSB)	Time between two subsequent Temperature measurements LSB (Bit 3 0)	Enum: 0x00: Temperat measure disabled 10 600 0x010x3C:	ment Os [10s])600 s
28	4	Not Used (= 0)					
32	3	Presence	PR	Number of Presence Levels available to user	Enum: 0x0: Presence of 0x10x7: 1 7	disabled	-
35	3	Fan	F	Number of Fan Speed Levels available to user:	Enum: 0x0: Fan Speed 0x10x7: 1 7	disabled	_
38	2	Temperature Measurement Timing	TT (MSB)	Time between two subsequent Temperature measurements MSB (Bit 5 4)			
40	4	Significant Temperature Difference	ST	Difference between two subsequent temperature measurements to trigger a Message Type D [0.2°]	0x00xF	0.03.0	O
44		Not Used (= 0)					
45	3	Keep Alive Timing	KA	Number of measurements (without trigger of a message Type D) between two subsequent "Keep Alive messages":	OXO: ITUIISIIIISSIO	nt result with rature nt	
					0x10x7: [step-size 1		1070

D2-01: Electronic switches and dimmers with Energy Measurement and Local Control

This EEP family shall be used for bidirectional actuators that control electric loads, e.g. for lightning purposes. Switching and dimming is controlled and high-resolution energy measurement is supported. Local Control, either thru a user interface or thru other measures shall be supported on the actuator. This may include other EnOcean enabled devices taught-in to a device belonging to the EEP family, e.g. a simple rocker switch or more sophisticated devices

like occupancy sensors with timing control. The proposed EEP family serves up to 30 output channels and allows controlling them either individually or as a bulk. Extension of this EEP family is possible in different ways:

- 1. A new device with a different feature mix creates a new TYPE within this EEP family
- -> new column in following table
- 2. An additional feature is added and a new device with a new TYPE is created
- -> new column and new line in following table
- 3. Like 2, but EnOcean communication of the EEP family needs to be extended
- -> new column and new line in following table
- -> one or more additional messages need to be defined

For teach-in and teach-out UTE (Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication) shall be used.

Туре	00	01	02	03	04	05	06	07	80	09	OA	οв	ос	OD	OE	OF	10	11	12	13	14
No. of output channels	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	2	2	2	4	8
Switching	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	X	Χ	Χ	Χ	X	X	Χ	Χ
Dimming	-	-	Χ	Χ	Χ	Χ	-	-	-	Χ	-	-	-	-	-	-	-	-/	-	-	-
Dimming configurable	-	-	-	-	Χ	Χ	-	-	-	Χ	-	-	-/	-	-	-	7/		-	-	-
Pilot wire	-	-	-	-	-	-	-	-	-	-	-	-	X	-		-	_	-	-	-	-
Local control	Χ	Χ	Χ	Χ	Χ	Χ	-	-	Χ	Χ	Χ	X	X	X	X	X	Χ	Χ	Χ	Χ	Χ
Local control enable/disable	-	-	-	-	Χ	Χ	-	-	Χ	-	X	X	X	Х	Х	X	-	-	Χ	-	-
External Switch / Push Button Control	-	-	-	-	-	-	-	-	-	-	- \	-	-	-	-/	Χ	-	-	Χ	-	-
External Switch / Push Button Type	-	-	-	-	-	-	-	-	-	-	-	/	-	-/	-	Χ	-	-	Χ	-	-
Auto OFF Timer	-	-	-	-	-	-	-	-	- ,	45	-	-	-	_	-	Χ	-	-	Χ	-	-
Delay OFF Timer	-	-	-	-	-	-	-	-		,	/	-	7/	-	-	Χ	-	-	Χ	-	-
Taught-in devices enable/disable 2)	-	-	-	-	Χ	Χ	-	-	X	X	Χ	X	X	Χ	Χ	Χ	-	-	Χ	-	-
User interface day/night mode	-	-	-	-	-	Χ	-	-	X		Χ	X	Χ	Χ	Χ	Χ	-	-	Χ	-	-
Over current reporting	-	-	-	-	Χ	Χ	-	-	Χ	Χ	- //	_	Χ	-	-	-	-	-	-	-	-
Over current configurable	-	-	-	-	Χ	Χ		-	Χ	_	-/	-	Χ	-	-	-	-	-	-	-	-
Energy measurement	Χ	-	Χ	-	Χ	Χ	X	7	X-	X	-	Χ	Χ	-	Χ	-	Χ	-	-	-	-
Power measurement	-	-	-	-	X	Χ	-	-	X	X	-	Χ	Χ	-	Χ	-	-	-	-	-	-
Measurement Roll Over 1)	Χ	-	Χ	-	- \	-	X	-	7/	-	-	Χ	-	-	Χ	-	Χ	-	-	-	-
Measurement Auto Scaling 1)	-	-	-	-	X	Χ		-	X	Χ	-	-	Χ	-	-	-	-	-	-	-	-
Measurement configurable	-	-	-	4		Χ	_	-/	Χ	Χ	-	Χ	Χ	-	Χ	-	-	-	-	-	-
Measurement report on query	Χ	-	Χ		Х	Χ	X	-	Χ	Χ	-	Χ	Χ	-	Χ	-	Χ	-	-	-	-
Measurement auto reporting	-	-	-	-	X	X_	_	-	Χ	Χ	-	Χ	Χ	-	Χ	-	-	-	-	-	-
Default state configurable	-	- (-	4	-	X	-	-	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	-	-	Χ	-	-
Error level reporting	-	-	-	-	-	X	-	-	Χ	Χ	-	-	Χ	-	-	-	-	-	-	-	-
Power Failure Detection		-	-	-	-/	-	-	-	-	-	Χ	Χ	-	-	-	-	-	-	-	-	-
Power Failure Detection enable/disable	-(`	-	- /	_	-	-	-	-	-	Χ	Χ	-	-	-	-	-	-	-	-	-

- 1) A device may either support Measurement Roll Over or Measurement Auto Scaling.
- 2) Enable / disable only effects devices that are taught-in to a device belonging to this EEP family; it does not effect communication between a device belonging to this EEP family and any other entity where this device has been taught-in by itself.

RORG	D2		VLD Telegram
FUNC	01	Electro	nic switches and dimmers with Energy Measurement and Local Control
TYPE	00		Type 0x00

Submitter: Team

CMD 0x1 - Actuator Set Output

This message is sent to an actuator. It controls switching / dimming of one or all channels of an actuator.

Command ID 01 (CMD)

				DΒ	_2							DΒ	_1							DB	_0			
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
						a	4D		din) va	ue		Į/O	cha	nne				0	тфu	t Va	lue	96	

REMARK:

In case an Actuator Set Output message specifies a parameter that is not supported by the device being addresses, such device shall react as following:

- channel not supported by device -> ignore message
- dimming command to switching device -> no change of status
- dimming command with non supported speed -> dim with regular speed

RECOMMENDATION:

Dimmers should take things like phase shifting into account to provide dimming based on power consumption (results in brightness for lamps) rather than interpreting percentage values as phase angle only.

Offset	Size	Data	ShortCut	Description	Valid	d Range		Scale	Unit
0	4	Not Used (=	0)						
4	4	Command ID	CMD	command identifier	Enum: 0x01: ID 01				
8	3	Dim value	DV		Enum: 0x00: 0x01: 0x02: 0x03: 0x04: 0x050x07	Dim to new o Dim to new o Stop dimming	utput utput utput	out value value – dim tin value – dim tin value – dim tin	ner 2
11	5	I/O channel	I/O	2	Enum: 0×000×1D: 0×1F: 0×1F:	device	annels	o load) s supported by t m mains supply	
16	1	Not Used (=	0)						
17	7	Output value	OV		Enum: 0x00: 0x010x64: 0x650x7E:	: Not used	1% t	or OFF o 100% or ON alid / not applic	able

CMD 0x2 - Actuator Set Local

This message is sent to an actuator. It configures one or all channels of an actuator.

Response Timing: None

RECOMMENDATION:

In case the device implements an internal order for dim timers, this order should be from "dim timer 1" (fast) to "dim timer 3" (slow). The configured time shall always be interpreted for a full range (0 to 100%) dimming.



Offset	Size	Data	ShortCut	Description	V	alid Range	Scale Unit
0	1	Taught-in devices	d/e		Enum:		
						isable taught-in d <mark>evic</mark> EP)	es (with different
						nable taught-in device EP)	es (with different
1	3	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x02:1	ID 02	
8	1	Over current shut down	ОС		Enum:		
					Ob0:	ver current shut down	n: static off
					0b1: re	ver current shut down	n: automatic
9		reset over current shut	RO		Enum:		
		down			0b0:	eset over current shu	
					0b1: si	eset over current shu gnal	t down: trigger
10	1	Local control	LC		Enum:		_
						isable local control	_
					/	nable local control	
11	5	I/O channel	I/O		Enum:	0	1.7. 1. 1)
					0x000	Output channe	I (to load)
					0x1E:		nels supported by
					0x1F:	Input channel (supply)	(from mains
16	4	Dim timer 2	DT2		Enum:		
					0x00:	Not used	
					0×010		,5 7,5s / steps
20	4	Dim timer 3	DT3		Enum:		
					0x00:	Not used	
					0×010		,5 7,5s / steps
24			d/n		Enum:		
		indication				ser interface indicatio	
					0b1:U	ser interface indicatio	n: night operation
25	1	Power Failure	PF		Enum:		
					-	isable Power Failure D	
						nable Power Failure D	etection
26	2	Default state	DS		Enum:		
					l	Default state: 0% or 0	
						Default state: 100% o	
					-	Default state: remem	ber previous state
					Ub11:	Not used	

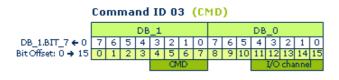
28	4	Dim timer 1	DT1	i	Enum:	
					0x00:	Not used
				-		Dim timer 1 [0,5 7,5s / steps
				(0x010x0F:	0,5s]

CMD 0x3 - Actuator Status Query

This message is sent to an actuator. It requests the status of one or all channels of an actuator.

Response Timing:

An Actuator Status Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid	d Range	Scale	Unit
0	4	Not Used (=	0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x03: ID 03	<u> </u>		
8	3	Not Used (=	0)					
11	5	I/O channel	I/O		0x00,0x1D: 0x1E: 0x1F:	Output channel (to All output channel device Input channel (fro	s supported by t	

CMD 0x4 - Actuator Status Response

This message is sent by an actuator if one of the following events occurs:

- Status of one channel has been changed locally
- Message Actuator Status Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Status Query message.



REMARK 1:

In case an Actuator Status Query message specifies a parameter that is not supported by the device being addresses, such device shall ignore the message and shall not answer using the Actuator Status Response message.

REMARK 2:

In case an Actuator Status Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Power Failure	PF		Enum:		
					Power Failure Detection	n disabled/not	
					0b0: supported		
					Power Failure Detection	n enabled	
					0b1:		
1	1	Power Failure Detection	PFD		Enum:		
		Detection			Power Failure not dete 0b0: supported/disabled	cted/not	
					Power Failure Detected		
					Ob1:	' /	
2	2	Not Used (= 0)					
4	4	Command ID	CMD	Command	Enum:		
				identifier	0x04: ID 04		
8	1	Over current switch	ОС		Enum:		
		off			Over current switch of	f: ready / not	
					0b0: supported		
					Over current switch of	f: executed	
					0b1:		
9	2	Error level	EL		Enum:		
					0b00: Error level 0: hardwa		
					0b01: Error level 1: hardwa		
					0b10: Error level 2: hardwa		
	_				0b11: Error level not suppor	rted	
11	5	I/O channel	I/O		Enum:		
					0x000x1D: Output channe		
					0x1E: Not applicable		
1.0					0x1F: Input channel	(from mains s	supply)
16	1	Local control	LC		Enum:	,	
					0b0: Local control disabled	/ not supported	<u>d</u>
	_		4		0b1: Local control enabled		
17	7	Output value	ov		Enum:		
					0x00: Output value (
					0x010x64: Output value 1	1% to 100% o	r ON
					0x650x7E: Not used		
					0x7F: output value n	iot valid / not s	set

CMD 0x5 - Actuator Set Measurement

The command defines values at offset 32 and at offset 40 which are the limits for the transmission periodicity of messages. MIT must not be set to 0, MAT \geq MIT.

Response Timing: None



Measurement delta to be reported

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x05: ID 05		
8	1	Report measurement	RM		Enum:		
					0b0: only	urement: que	
					0b1: auto reportin	urement: que ig	ry/
9	1	Reset measurement	RE		Enum:		
					Reset measu 0b0:	rement: not a	ctive
					Reset measu 0b1: signal	rement: trigg	er
10	1	Measurement mode	e/p		Enum:		
					0b0: Energy meas	surement	
					0b1: Power measu	urement	
11	5	I/O channel	I/O		Enum:		
					Outpu	ut channel (to	
					0x000x1D: load)		
						tput channels	
						orted by the d	
						channel (from	n
1.5	_		MD 100			s supply)	la. / a
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)			4 //		
21	3	Unit	UN		Enum:		
					0x00: Ener	gy [Ws]	
					0x01: Ener	gy [Wh]	
					0x02: Ener	gy [KWh]	
					0x03: Powe	er [W]	
					0x04: Powe	er [KW]	
					0x050x07: Not	used	
24	8	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32	8		MAT	Measurement	Enum:		
		subsequent actuator		Response messages	1255:	S	
		messages		[10s]		102550	
					0: Reserved		
40	8	Minimum time between two	MIT	Measurement	Enum:		
		subsequent actuator		Response messages	1255:	S	
		messages		[s]		1255	
					0: Reserved		

CMD 0x6 - Actuator Measurement Query

This message is sent to an actuator. The actuator replies with an Actuator Measurement Response message.

Response Timing:

An Actuator Message Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (=	0)		
4		Command ID	_	Command identifier	Enum: 0x06: ID 06
8	2	Not Used (=	0)		
10	1	Query	qu		Enum: 0b0: Query energy 0b1: Query power
11	5	I/O channel	I/O		Enum: Output channel (to load) 0x000x1D: Ox1E: All output channels supported by the device Ox1F: Input channel (from mains supply)

CMD 0x7 - Actuator Measurement Response

This message is sent by an actuator if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Measurement Query message.

Command ID 07 (CMD)

				DB,	_5							DB_	4		H,					DB,	_3							DB	_2							DB,	_1							DB	_0			
DB_5.BIT_7 ← 0 Bit Offset: 0 → 47	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	न	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	-7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	ᄀ
Bit Offset: 0 → 47	0	1	2	3	4	5	6	7	8	9	10	11	12	13	[4	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
				П		av	1D/			Jnit		I/	O d	hani	nel		(M	SB)		_										Mea	sur	eme	nt v	alu												((LSE	3)
								_					_	7																																		_

REMARK 1:

In case an Actuator Measurement Query message specifies a parameter that is not supported by the device addressed, such device shall ignore the message and shall not answer using the Actuator Measurement Response message.

REMARK 2:

In case an Actuator Measurement Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0	4	Not Used (= 0)						
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07	_		
8	3	Unit	UN		Enum: 0x00: 0x01: 0x02: 0x03:	Energy [Ws] Energy [Wh] Energy [KWh Power [W]]	

					0x04: 0x050x07	Power [KW] : Not used
11	5	I/O channel	I/O		Enum: 0x000x1D:	Output channel (to load)
					0x1E:	Not applicable, do not use
					0x1F:	Input channel (from mains supply)
16		Measurement value (4 bytes)		DB3 = MSB / DB0 = LSB	0429496729	95 N/A

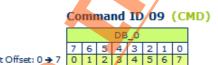
CMD 0x8 - Actuator Set Pilot Wire Mode

Command ID 08 (CMD)

				DB	_1							DB	_0			
	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						CI	ИD								PM	

0.66	۵.				
Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used $(= 0)$)		
4	4	Command ID	CMD	Command identifier	0x08: ID 08
8	5	Not Used (= 0)			
13	3	Pilotwire mode	PM		Enum: 0x00: Off 0x01: Comfort 0x02: Eco 0x03: Anti-freeze 0x04: Comfort-1 0x05: Comfort-2

CMD 0x9 - Actuator Pilot Wire Mode Query



O	ffset	Size		Data	ShortCut	Description	Valid Range	Scale	Unit
0		4	Not	Used (=	0)				
4		4	Con	nmand ID	CMD	Command identifier	Enum:		
							0x09: ID 09)	
		-/							

EEP 2.6.7 Specification

CMD 0xA - Actuator Pilot Wire Mode Response

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum:
					0x0A: ID 0A
8	5	Not Used (= 0)			
13	3	Pilotwire mode	PM		Enum:
					0x00: Off
					0x01: Comfort
					0x02: Eco
					0x03: Anti-freeze
					0x04: Comfort-1
					0x05: Comfort-2

CMD 0xB - Actuator Set External Interface Settings

		_					
Size	Data	ShortCut	Description	Valid F	Range	Scale	Unit
4	Not Used (= 0)						
4	Command ID	CMD	Command identifier	Enum:			
				0x0B: ID 0B			
3	Not Used (= 0)						
5	I/O channel	I/O		Enum:			
				0x000x1D:	Output chann	nel (to load)	
				0x1E:			orted
	0-/			0x1F:	Input channe supply)	l (from mai	ns
16	Auto OFF Timer	AOT	Timer to automatically set	Enum:			
			OFF output channel when it	0x0000:	Timer		
			is set ON		deactivate	ed	
				0x00010xFF	FE:	0.1	.6553.4 s
				0xFFFF:	•	ved	
	4 4 3 5	4 Not Used (= 0) 4 Command ID 3 Not Used (= 0) 5 I/O channel	4 Not Used (= 0) 4 Command ID CMD 3 Not Used (= 0) 5 I/O channel I/O	4 Not Used (= 0) 4 Command ID CMD Command identifier 3 Not Used (= 0) 5 I/O channel I/O 16 Auto OFF Timer AOT Timer to automatically set	4 Not Used (= 0) 4 Command ID Command identifier Enum: 0x0B: ID 0B 3 Not Used (= 0) Enum: 0x000x1D: 0x000x1D: 0x1E: 0x1F: 16 Auto OFF Timer AOT Timer to automatically set OFF output channel when it is set ON Enum: 0x0000: 0x0000:	4 Not Used (= 0) Command ID CMD Command identifier Enum: 0x0B: ID 0B 3 Not Used (= 0) I/O Enum: Output channows of the device of the part	4 Not Used (= 0) 4 Command ID CMD Command identifier Enum:

32	16	Delay OFF Timer	DOT	Delay timer before setting output channel to OFF value received by radio cmd	Enum: 0x0000: Timer deactivat	ted
				Cilia	0x00010xFFFE:	0.16553.4 s
					0xFFFF: Does not modify so value	
48	2	External Switch/Push Button	EBM	External interface mode	Enum: 0b00: Not applicable 0b01: External Switch	
					0b10: External Push Butt 0b11: Auto detect	on
50	1	2-state switch	SWT	Switching state	Enum: 0b00: Change of key stat	e sets ON or OFF
					0b01: Specific ON/OFF po ON when contacts OFF when contacts	ositions. are closed.
51	5	Not Used (= 0)				

CMD 0xC - Actuator External Interface Settings Query

Command ID OC (CMD)

				DB	_1							DB	_0			
DB Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						CI	ИD					I	/0	Cha	nne) /

Offset	Size	Data	ShortCut	Descript	tion	Valid	d Range	Scale	Unit
0	4	Not Used (=	0)						
4	4	Command ID		Command identifier		Enum: 0x0C: ID 0C	_		
8	3	Not Used (=	0)						
11	5	I/O channel	I/O			Enum: 0x000x1D:	Output channel (t	o load)	
						0x1E:	All output channe device	ls supported by t	he
						0x1F:	Input channel (fro	om mains supply)

CMD 0xD - Actuator External Interface Settings Response

Offset	Size	Data	ShortCut	Description	Valid Ra	ange	Scale	Unit
0	4	Not Used (= 0)						_
4	4	Command ID	CMD	Command identifier	Enum: 0x0D: ID 0D			
_	_				0x0D:1D 0D			
8	3	Not Used (= 0)						
11	5	I/O channel	I/O		0x000x1D: 0x1E:	Output chan		d)
					0x1F:	Input channe supply)	el (from m	ains
16	16	Auto OFF Timer	АОТ	Timer to automatically set OFF output channel when it is set ON	0x0000:	Timer deactivate	ed	
					0x00010xFFF 0xFFFF:	Does not modify sa value		6553.4 s
32	16	Delay OFF Timer	DOT	Delay timer before setting output channel to OFF value received by radio cmd	Enum: 0x0000: 0x00010xFFF 0xFFFF:	Timer deactivate To Does not modify sa value	0.1	6553.4 s
48	2	External Switch/Push Button	EBM	External interface mode	Enum: 0b00: Not ap 0b01: Extern 0b10: Extern 0b11: Auto d	plicable al Switch al Push Butto	in	
50	1		SWT	Switching state			sitions. are closed.	,
51	5	Not Used $(= 0)$						

		_			
RORG	D2				VLD Telegram
FUNC	01	Electronic	c şwi	itches	and dimmers with Energy Measurement and Local Control
TYPE	01				Type 0x01 (description: see table)

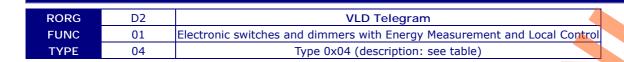
See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	02	Type 0x02 (description: see table)

See profile: D2-01-00

		_
RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	03	Type 0x03 (description: see table)

See profile: D2-01-00



See profile: D2-01-00

RORG	D2	VLD Telegram	
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local C	Control
TYPE	05	Type 0x05 (description: see table)	

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	06	Type 0x06 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	07	Type 0x07 (description: see table)

See profile: D2-01-00

RORG	D2		7		VLD Telegram
FUNC	01	Electronic	C SW	itches	and dimmers with Energy Measurement and Local Control
TYPE	08				Type 0x08 (description: see table)

See profile: D2-01-00

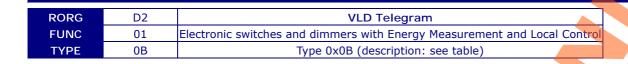
RORG	D2	_/	VLD Telegram
FUNC	01	E	lectronic switches and dimmers with Energy Measurement and Local Control
TYPE	09		Type 0x09 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control

TYPE 0A Type 0x0A (description: see table)

See profile: D2-01-00



See profile: D2-01-00

		_			
RORG	D2	VLD Telegram			
FUNC	01	Electronic switches and dimmers with Energy Measurement	t and L	ocal	Control
TYPE	0C	Type 0x0C			

Submitter: AVIDSEN

Description

Intended for heating module with Pilotwire command and Energy Measurement

Pilot wire includes 6 different modes:

- Off
- Comfort
- Eco
- Anti-freeze
- Comfort-1°C
- Comfort-2°C

Data exchange

Direction: bidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: at each state change / every 5 minutes
Trigger event: actuator status change, consumption information change

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

Supported command	Type 0x0C
0x1 – Actuator Set Output	X
0x2 - Actuator Set Local	Χ
0x3 - Actuator Status Query	Χ
0x4 - Actuator Status Response	Χ
0x5 - Actuator Set Measurement	Χ
0x6 - Actuator Measurement Query	Χ
0x7 – Actuator Measurement Response	Χ
0x8 - Actuator Set Pilot Wire Mode	Χ
0x9 - Actuator Pilot Wire Mode Query	Χ
0xA - Actuator Pilot Wire Mode Response	Χ

Telegram Definition

The telegrams corresponding to Command IDs: 0x1, 0x2, 0x3, 0x4, 0x5, 0x6 and 0x7 are already defined in EEP V2.6.2 and do not change.

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0D	Type 0x0D

Submitter: ID-RF

Description for TYPE 0x0D, 0x0E, 0x0F, 0x12

Add three commands:

- CMD 0xB Actuator Set External Interface Settings
- CMD 0xC Actuator External Interface Settings Query
- CMD 0xD Actuator External Interface Settings Response

Supported functions:

- External Switch/Push Button Control
- External Switch/Push Button Type (Bi-stable or Mono-stable / 2-state switch)
- Auto OFF Timer
- Delay OFF Timer

Add D2-01-0D profile – Micro smart plug with 1 channel, no metering capabilities

Add D2-01-0E profile - Micro smart plug with 1 channel, and metering capabilities

Add D2-01-0F profile – Slot-in module with 1 channel, no metering capabilities

Add D2-01-12 profile - Slot-in module with 2 channels, no metering capabilities

These new profiles are modifications of the existing ones, please find below a listing:

- Profile D2-01-0D is all same as D2-01-0A but with one modification
- Profile D2-01-0E is all same as D2-01-0B but with one modification
- Profiles D2-01-0F is all same as D2-01-0A but with three modifications
- Profiles D2-01-12 is all same as D2-01-0A but with four modifications

Description of new supported functions

External Switch/Push Button Control

As for "Local Control" function, it indicates if the product can be controlled using an additional physical interface, as an external push button or wall switch. This interface is not directly integrated to the product, but can be connected using wires.

External Switch/Push Button Type

• Bi-stable or Mono-stable:

External interface can be composed of bi-stable button (switch) or mono-stable button (push button). Depending of the type selected, the product will have different reactions when switch/push button actions are

- If bi-stable button type selected, each change of state (open or close) toggle the output.
- If mono-stable button type selected, first change of state (open or close) toggle the output, second change (close or open) is ignored, and output remains unchanged.

NOTE: If the product has more than one output, the external interface type is applied for all outputs.

• 2-state switch:

This parameter is effective only if external switch/push button type is set as "bi-stable". When this setting is enabled, the device will turn ON output(s) when contacts are closed and turn OFF output(s) when contacts are open. When this setting is disabled (default mode), a change of contacts state will toggle the output(s).

Auto OFF Timer

This functions turns OFF the output when time elapsed.

Use case: In corridor, when you turn ON the light, you want it to be turned OFF automatically after a certain time.

Delay OFF Timer

When the device receives a valid radio command, setting an output state to OFF, instead of setting immediately the new output state, this function set the new output state when time elapsed.

Use Case: In hotel room, when you send a radio command (removing card from card switch) to turn OFF the light, instead, turn OFF light after a certain time, to allow people to leave the room.

The addition of these functions required three new commands:

- CMD 0xB Actuator Set External Interface Settings
- CMD 0xC Actuator External Interface Settings Query
- CMD 0xD Actuator External Interface Settings Response

Data exchange

Direction: bidirectional Addressing: broadcast

Communication trigger: event triggered Communication interval: no fix interval

Trigger event: actuator status change, consumption information

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

Supported command	Type 0x0D	Type 0x0E	Type 0x0F	Type 0x12
0x1 - Actuator Set Output	X	X	X	X
0x2 - Actuator Set Local	X	X	X	X
0x3 - Actuator Status Query	X	Χ	Χ	Х
0x4 - Actuator Status Response	X	Χ	X	X
0x5 - Actuator Set Measurement	=	Χ	-	-
0x6 – Actuator Measurement Query	=	Χ	-	
0x7 – Actuator Measurement Response	=	Χ	-	-
0x8 - Actuator Set Pilot Wire Mode	=	-		-/
0x9 – Actuator Pilot Wire Mode Query	=	-	-	-
0xA – Actuator Pilot Wire Mode Response	=	-		=
0xB - Actuator Set External Interface Settings	-	-	Х	Χ
0xC – Actuator External Interface Settings Query	-	-	X	Χ
0xD – Actuator External Interface Settings Response	-	-	X	Χ

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0E	Type 0x0E (description: see table)

Submitter: ID-RF

Description see TYPE 0x0D

See profile: D2-01-00

RORG	D2		VLD Telegram
FUNC	01	Electronic s	witches and dimmers with Energy Measurement and Local Control
TYPE	0F		Type 0x0F (description: see table)

Submitter: ID-RF

Description see TYPE 0x0D

See profile: D2-01-00

RORG	47	D2	VLD Telegram
FUNC		01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE		10	Type 0x10 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	11	Type 0x11 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram			
FUNC	01	Electronic switches and dimmers with Energy Measurement and	Local C	onti	rol
TYPE	12	Type 0x12 (description: see table)			
		1,752 11122 (46561.1941.111.11)			_

Submitter: ID-RF

Description see TYPE 0x0D

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	13	Type 0x13 (description: see table)

Submitter: AWAG Elektrotechnik AG

See profile: D2-01-01

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	14	Type 0x14 (description: see table)

Submitter: AWAG Elektrotechnik AG

See profile: D2-01-01

D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke

This EEP family shall be used for bidirectional sensors that measure temperature, illumination, and detect room occupancy and smoke presence.

The EEP may be used in conjunction with the Smart Acknowledge protocol.

For teach-in and teach-out the "Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication" shall be used. Alternatively the Smart Acknowledge Teach-In Procedure is used for those sensors supporting Smart Acknowledge.

Supported function	Type 0x00	Type 0x01	Type 0x02
Temperature Sensor	X	Χ	X
Illumination Sensor	X	Χ	-
Occupancy Detector	X	=	-
Smoke Detector	Χ	Χ	Χ

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	00	Type 0x00

Submitter: MSR-Office

CMD 0x1 - Sensor Measurement

This message is sent by a sensor if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)

- Message Actuator Measurement Query has been received

Response Timing: None

Command ID 01 (CMD)

	DB_3									DB_2								DB_1							DB_0							
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
						a	MD		1	ty pe							MS	В				me	easu	ire m	nent	val	ue				L	SB

Offset	Size	Data	ShortCut	Description		Valid Range	Scale	Unit
0	4	Not Used (= 0)						
4	4	Command ID	CMD	command identifier	Enum:			
					0x01	l: ID 01		
8	3	Measurement type	type		Enum:			
					0x00:	Temperature (065 +120°C)	5535: -40 to	
					0x01:	Illumination (065	535: 0 to 204	17lx)
					0x02:	Occupancy (0: not detected)	detected; 1:	
					0x03:	Smoke The following contevalue in DB_0 and 0x00 - No smoke d 0x01 - Smoke detechamber 0x02 - Smoke detechamber 0x03 - Smoke detechambers	DB_1: etected ected via ionizected via option	ation
11	5	Not Used (= 0)						
16	16	Measurement value (2 bytes)	MV	DB_0 = LSB / DB_1 = MSB	0655	535		N/A

CMD 0x2 - Sensor Test/Trigger

This message is sent to a sensor. It causes the sensor to enter self-test mode or trigger an alarm (if supported).

Response Timing: None

Command ID 02 (CMD)

				DΒ	_1							DΒ	_0			
DB_1.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a	4D		ST	TΑ						

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0	0)				
4	4	Command ID	CMD	Command identifier	Enum:		
					0x02: ID 02	_	
8	1	Self-test	ST		Enum:		
					0b0: Self-test	mode	
					0b1: Normal	operatio	on
9	1	Trigger alarm	TA		Enum:		
					0b0: Trigger a	alarm	
					0b1: Normal	operation	n
10	6	Not Used (= 0	0)				

CMD 0x3 - Actuator Set Measurement

This message is sent to a sensor. It configures the measurement behaviour of the sensor.

Response Timing: None

Command ID 03 (CMD)

		DB_	5						DB	_4			4				DB	_3						D	B_2	2						DB,	_1							DB,	_0			
DB_5.BIT_7 ← 0	7 6 5	4	3	2 :	1	οГ.	7 6	5	4	3	2	1	0	7	6	5	4	3	2	1	ᇭ	7 [7	6 5	5 4	1 3	2	1	Т	7	6	5	4	3	2	1	o	7	6	5	4	3	2	110	Л
Bit Offset: 0 → 47	0 1 2	3	4	5 6	6	7 8	3 9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24 2	25 2	6 2	7 28	3 29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45 4	46 4	7
				GME	5	R	M								/LS	B			ī	Unit	П				MSB				m	ax.	time	Re:	spor	nce	mes	ss.	mi	in, t	time	Re	spon	ce m	iess.	П

Measurement delta to be reported

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x03: ID 03		
8	1	Report measurement	RM		Enum:		
					Report mea 0b0: only	surement: que	ery
					Report mea 0b1: auto report	surement: que	ery /
9	7	Not Used (= 0)					
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN		Enum:		
					0x00: Ter	nperature (°C)	<u> </u>
					0x01: Illu	ımination (lx)	
					0x020x07: No	t used	
24		Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A

32	_	Maximum time between two subsequent Actuator	Measurement Response messages [10s]	0255	102550	S
40	-	Minimum time between two subsequent Actuator	Measurement Response messages [s]	0255	0255	S

CMD 0x4 - Sensor Measurement Query

This message is sent to a sensor. The sensor replies with an Sensor Measurement message.

Response Timing:

A Sensor Measurement message shall be received within a maximum of 300ms from the time of transmission of this message.

In case no such response is received within this time frame the action shall be treated as completed without result.

	Co	mı	na	nd	ID	0	4	(CI	MD)						
				DΒ	_1							DΒ	_0			
DB_1.BIT_7 ← 0		6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a	ИD			qu						

Offset	Size	Data	ShortCut	Description	Valid Ran	ige	Scale	Unit
0	4	Not Used (=	0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04	4		
8	3	Query	qu		0x1: 0x2:	Query Query Query		ion
11	5	Not Used (=	0)					

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	01	Type 0x01 (description: see table)

See profile: D2-02-00

RORG	D2		7/	VLD Telegram
FUNC	02	Se	osor	s for Temperature, Illumination, Occupancy And Smoke
TYPE	02			Type 0x02 (description: see table)

See profile: D2-02-00

D2-03:/Light, Switching + Blind Control

The EEP family D2-03-xx provides different telegram types for switches, light and blind control. The purpose is to support secure communication and other functional aspects of applications extending the possibilities given by

existing profiles (1BS, RPS, 4BS). Transmitting information in the status field of a telegram is not necessary with this EEP family.

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

EEP Properties: DATA EXCHANGE Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: N/A Tx delay: N/A Rx timeout : N/A

TEACH-IN

Teach-in method: Universal teach-in (UTE) + Secure Teach-in (for secure communication)

SECURITY

Encryption supported: yes

EEP Family Table:

Supported function	Type 00
2 Rocker Switch	Χ

The encrypted telegram has the R-ORG 0x30. The payload (4 bits) is encrypted. That telegram can be repeated. After decryption and the authentication of the CMAC, the telegram turns into a non-encrypted EnOcean telegram with the R-ORG 0x32. The payload will be expanded to 8 bits (4 MSB set to zero) and can then be interpreted as described in the telegram definition table.

The decrypted telegram may not be repeated as the information is not secure anymore. The following table provides information about the conversion between the profiles D2-03-00 and F6-02-01:

D2-03-00 DATA	F6-02-01 DATA	F6-02-01 STATUS
04	-	-
5	0x17	0x30
6	0x70	0x20
7	0x37	0x30
8	0x10	0x20
9	0x15	0x30
10	0x35	0x30
11	0x50	0x30
12	0x70	0x30
13	0x10	0x30
14	0x30	0x30
15	bxxx0xxxx	0x20

Offset	Size	Data	ShortCut	Description	Val	id Range	Scale	Unit
0	4	Not Used (= 0)						
4	4	Rocker Information		(similar to RPS profiles)	6:	Reserved Button A1 + energy bow p 3 or 4 button energy bow p Button A0 + energy bow p	pressed is pressed, pressed B0 pressed	,

8: No buttons pressed, energy bow pressed
9: Button A1 + B1 pressed, energy bow pressed
10: Button A0 + B1 pressed, energy bow pressed
11: Button B1 pressed, energy bow pressed
12: Button B0 pressed, energy bow pressed
13: Button A1 pressed, energy bow pressed
14: Button A0 pressed, energy bow pressed
15: Energy bow released

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	10	Mechanical Handle

Submitter: Eltako

This document contains the description of <u>decrypted</u> mechanical handle data. The mechanical handle profile must be redefined because there is no status field in EnOcean security available.

EEP Properties: DATA EXCHANGE Direction: unidirectional

Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: rotate mechanical handle

Tx delay: N/A Rx timeout: N/A

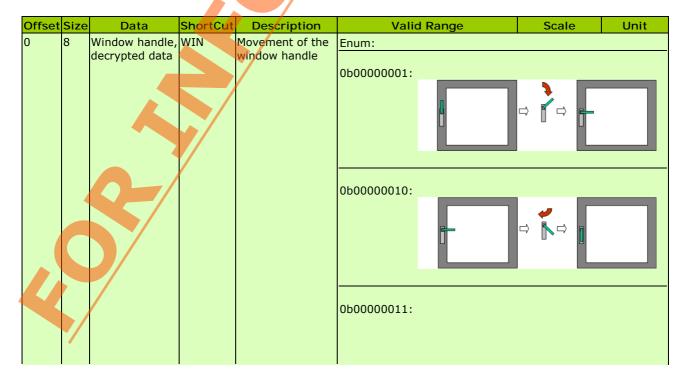
TEACH-IN

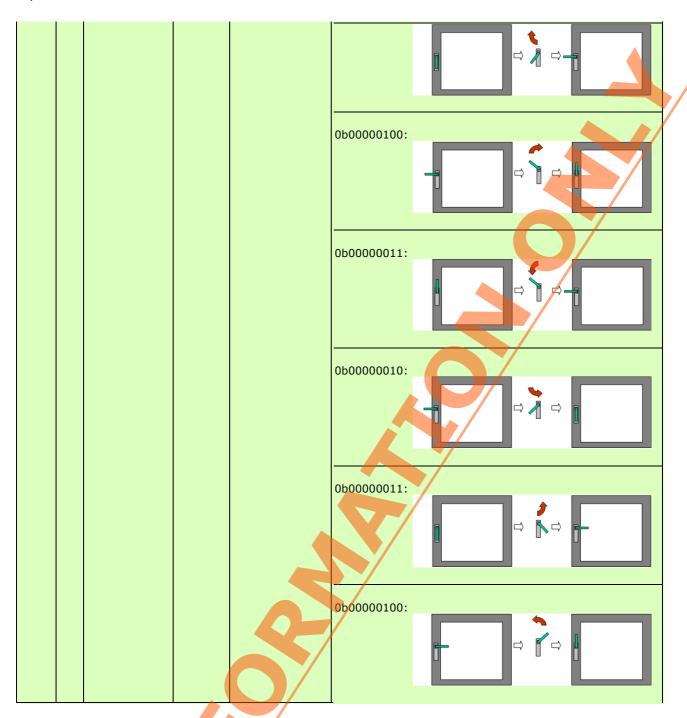
Teach-in method: Secure Teach-in, followed by special RPS teach-in sequence: Mechanical handle (closed => opened

=> closed within 2s)

SECURITY

Encryption supported: yes Security level format:





RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	20	Beacon with Vibration Detection

Submitter: Star Micronics Co., LTD.

Description

This profile is defined for the use in beacon devices. Such devices transmit if the telegram was triggered by a vibration or the timer.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: Vibration (movement), timer

Tx delay: -Rx timeout:

Teach-in

Teach-in method: N/A

Security

Encryption supported: no Security level format: -

Appendix

This beacon device can send a radio telegram at a prescribed timing. The receiver can detect the beacon device with this transmission. This device, when attached to a human body, can also be made into a wide variety of beacon-based systems, which keep people within the safe area, or keep them out of the danger zone.

This device can replace a battery with a vibration power generator. The beacon device harvests power from human walking motion and activates the radio transmitter circuit; it does not require batteries of any kind, enabling maintenance-free operation in many applications.

The product to be immediately released comes with no switches, and the future product, to follow soon, will be equipped with pushbuttons for wider application possibilities.

Offset	Size	Data	ShortCut	Description	Valid Range	e / Sca	ale	Unit
0		Energy Supply		Defines the energy source for the transmission	0: Battery: 1: Vibration supply		or	
1	7	Not Used (= 0)					

D2-04: CO2, Humidity, Temperature, Day/Night and Autonomy

CO2 sensor with 8 bits resolution (0 - 2000ppm or 0-5000ppm range) 8 bits temperature and relative humidity with Day / Night and battery autonomy.

Day / Night is based on illumination not on clock

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered

Communication interval: According to remaining autonomy and day or night

Trigger event: heartbeat, ...

Teach-in method: Universal teach-in, Smart Ack

Encryption required: no Security level format: 0

EEP Family Table

Each TYPE has to support every parameter that is marked in its column!

TYPE	Оx	00	Ox	01	0x02	Oxo	03 Ox	(04	0x05	0x06	0x07	0x08	0x09	0x10	0x1A	0x1B	0x1C	0x1D	Ox1E
CO2 Sensor 0-2000	Χ	4	Χ		X	X	Х		Χ	Χ	Χ	-	-	-	-	-	-	-	-
ppm range																			
CO2 Sensor 0-5000	F		-		7/	-	-		-	-	-	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ
ppm range																			
Humidity Sensor	Χ		Χ		-	-	-		ı	ı	-	Χ	Χ	-	-	-	-	ı	-
Temperature Sensor	Χ		Y .		Χ	Χ	Х		Χ	•	•	Χ	-	Χ	Χ	Χ	Χ	i	-
Day/Night Sensor	Χ		X		X	-	-		Χ	Χ	Χ	X	Х	X	-	-	Χ	X	Χ
Battery Autonomy	Χ	7/	Χ		X	Χ	-		-	-	Χ	X	Χ	X	Χ	-	-	_	Χ

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	00	Type 0x00

Submitter: NanoSense

The manufacturer will indicate emission rates versus battery autonomy and day night status.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	CO2		Concentration (linear), 1 LSB = 7.84 ppm Or Concentration (linear), 1 LSB = 19.6 ppm	0255	02000 (or 5000)	ppm
8	8	Humidity	HUM	Rel. Humidity (linear), 1 LSB = 0.5 %	0200	0100	%
16	8	Temperature	TMP	Temperature (linear), 1 LSB = 0.2 °C	0255	0+51	°C
24	1	Day/Night	DN		Enum: 0: Day 1: Night		
25		Battery autonomy	ВА	Battery autonomy	1: 87.5 - 6 2: 75 - 6 3: 62.5 - 4: 50 - 2 5: 37.5 -	87.5 % - 75 % 52.5 % - 50 % 57.5 % - 25 % - 2.5 %	
28	4	Not Used (= 0)					

RORG	D2	VLD Telegram							
FUNC	04 CO2, Humidity, Temperature, Day/Night and Aut								
TYPE	01	Type 0x01 (description: see table)							

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	02	Type 0x02 (description: see table)

See profile: D2-04-00

RORG	D2		VLD Telegram
FUNC	04	CO2, Humidity	y, Temperature, Day/Night and Autonomy
TYPE	03	Тур	e 0x03 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	04	Type 0x04 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	05	Type 0x05 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	06	Type 0x06 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Auto	nomy
TYPE	07	Type 0x07 (description: see table)	

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	08	Type 0x08 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	09	Type 0x09 (description: see table)

See profile: D2-04-00

RORG	D2		VLD Telegram
FUNC	04	CO2, Humidi	ty, Temperature, Day/Night and Autonomy
TYPE	10	Ту	pe 0x10 (description: see table)

See profile: D2-04-00

RORG		D2	VLD Telegram
FUNC	abla	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	4	1A	Type 0x1A (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1B	Type 0x1B (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1C	Type 0x1C (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autor	nomy
TYPE	1D	Type 0x1D (description: see table)	
		/ (

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1E	Type 0x1E (description: see table)

See profile: D2-04-00

D2-05: Blinds Control for Position and Angle

Submitter: AWAG Elektrotechnik AG

Description

The protocol is intended for commissioning as well as for operation of a blind actuator that supports control of the vertical position as well as the rotation angle of the slats.

Data exchange

Direction: bidirectional

Addressing: unicast (ADT) & broadcast

Communication trigger: event-triggered or upon query Communication interval: TYPE 00,01: heartbeat (off or 30 s or 3 min), TYPE 02: event-triggered

Trigger event TYPE 00,01:

- a) status change (alarm, blockage, deblockage)
- b) position change > 10 % of range
- c) end position reached (0% or 100%)
- d) heartbeat

Trigger event TYPE 02:

request, manual change (position, angle)

Tx delay: n/a Rx timeout: n/a

Teach-in method: Universal teach-in

Security

Encryption supported: no

Security level format: n/a

EEP Family Table

Each TYPE has to support all telegrams and parameters marked in its column.

Command Overview	Type 0x00	Type 0x01	Type 0x02
No. of output channels	1	4	1
Go to Position and Angle	X	Χ	X
Stop	Х	Χ	Х
Query Position and Angle	Х	Χ	Х
Reply Position and Angle	Х	Χ	Х
Set parameters	Χ	Χ	-

Parameter Overview	Type 0x00	Type 0x01	Type 0x02
Vertical position	Χ	Χ	X
Rotation angle	Χ	Χ	X
Repositioning	Χ	Χ	X
Blockage mode	Χ	Χ	X
Alarm mode	Χ	Χ	-
Set vertical, 5 sec 5 min	Χ	Χ	-
Set rotation, 0 2.54 sec	Χ	Χ	-
Set Alarm Action	Χ	Χ	-



RORG	D2	VLD Telegram
FUNC	05	Blinds Control for Position and Angle
TYPE	00	Type 0x00

Submitter: AWAG Elektrotechnik AG

CMD 1 - Go to Position and Angle

Once the actuator is configured either by the "Set Parameters" command or through manual configuration (using local buttons) the position of the blinds can be controlled with this command.

When the actuator is set to "blockage" mode, neither local nor central positioning and configuration commands will be executed. This mode is intended for putting the device temporarily out of service, e.g. for a maintenance operation. When the actuator is set to the "alarm" mode neither local nor central positioning and configuration commands will be executed. Before entering the "alarm" mode, the actuator will execute the "alarm action" as configured by the "Set parameter" command.

When this command is sent with the "deblockage" option, the actuator terminates the "alarm" or "blockage" mode and enters the normal mode.

Exemplary illustration of data bytes 0 ... 3:

Command ID 01 (CMD)

				DE	3_3							DB	_2							DB	_1							DB	_0			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 -> 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
					POS					ANG			R	EP	0		L	OC	K		CH	IN			CM	1D						

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0)		-		
1	7	Position	POS	Vertical position	Enum:		
					0100:	01	00 %

1					-
					127: Do not
					change
8	1	Not Used $(= 0)$			
9	7	Angle	ANG	Rotation angle	Enum:
					0100: 0100 %
					127: Do not
					change
16	1	Not Used $(= 0)$	1	<u>, </u>	
17	3	Repositioning	REPO	How to adjust the internal positioning	Enum:
				tracker before going to the new position	0: Go directly to POS/ANG
					1: Go up (0%), then to
					POS/ANG
					2: Go down (100%), then to
					POS/ANG
					3 Reserved
20	_	No. I I I I I I I I			7.
20	3	Not Used (= 0	Ĺ		
21	3	Locking modes	LOCK	Set/reset locking modes	Enum:
		inoues			0: Do not change
					1: Set blockage mode
					2: Set alarm mode
					3 6: Reserved
					7: Deblockage
24	4	Channel	CHN	Channel address	Enum:
					0: Channel 1
					1: Channel 2
					2: Channel 3
					3: Channel 4
					15: All channels
28	4	Command ID	CMD	Command identifier	Enum:
					1: Goto command

CMD 2 - Stop

This command immediately stops a running blind motor. It has no effect when the actuator is in "blockage" or "alarm" mode, i.e. it will not stop an eventual "go up" or "go down" alarm action.

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	4	Channel	CHN	Channel address	Enum			
					0:	Channe	el 1	
					1:	Channe	el 2	
					2:	Channe	el 3	
					3:	Channe	el 4	
					15:	All cha	nnels	
4	4	Command ID	CMD	Command identifier	Enum			
					2:	Stop co	omman	d

CMD 3 - Query Position and Angle

This command requests the actuator to return a "reply" command.

Offse	et S	Size		Data	ShortCut	Description	Valid	l Range	Scale	Unit
0	,	4	Ch	nnel	CHN	Channel address	Enum	:		
	7						0:	Channe	l 1	
							1:	Channe	l 2	_
							2:	Channe	I 3	_
							3:	Channe	I 4	

						15:	All channels
4	4	4	Command ID	CMD	Command identifier	Enum:	
						3:	Query command

CMD 4 - Reply Position and Angle

Either upon request ("Query" command) or after an internal trigger (see EEP Properties) the actuator sends this command to inform about its current state.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0)					
1	7	Position	POS	Current vertical position	Enum: 0100: 127: Position unknown, v		0100 %
					known after the next goto		
8		Not Used $(= 0)$					
9	7	Angle	ANG	Current rotation angle	Enum: 0100: 127: Angle unknown, wil after the next goto	l be known	.100
16	5	Not Used (= 0))				
21	3	Locking modes	LOCK	Current locking mode	Enum: 0: Normal (no lock) 1: Blockage mode 2: Alarm mode 3 7: Reserved		
24	4	Channel	CHN	Channel address	Enum. 0; Channel 1 1: Channel 2 2: Channel 3 3: Channel 4		
28	4	Command ID	CMD	Command identifier	Enum: 4: Reply command		

CMD 5 - Set parameters

This command sets one or multiple configuration parameters of the actuator. When a parameter value is set to "-> no change" this parameter will not be modified. The VERT and ROT parameters describe the duration needed by the motor for a full run of the blind, or for a complete turn of the slats, respectively. They have to be measured on site and assigned to the actuator.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (=	0)				
1	15	Set vertical			Enum:		
				run	50030000:	500030	0000 ms
					0 499: Reserved		
					32767 -> No		
					(0x7FFF): change		
16	8	Set rotation	ROT	Measured duration of rotation	Enum:		
					1254:	r	ms
						102540	
					0: No rotation		
					255: -> No change		
24	5	Not Used (=	0)				

29	3	Set alarm action	AA	Besides locking all other commands entering the alarm mode results in	Enum: 0: No action 1: Immediate stop 2: Go up (0%) 3: Go down (100%) 4 6: Reserved 7: -> No change
32	4	Channel	CHN	Channel address	Enum: 0: Channel 1 1: Channel 2 2: Channel 3 3: Channel 4 15: All channels
36	4	Command ID	CMD	Command identifier	Enum: 5: Set parameters command

RORG	D2	VLD Telegram
FUNC	05	Blinds Control for Position and Angle
TYPE	01	Type 0x01 (description: see table)

Submitter: AWAG Elektrotechnik AG

See profile: D2-05-00

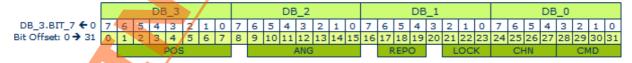
RORG	D2	VLD Telegram
FUNC	05	Blinds Control for Position and Angle
TYPE	02	Type 0x02

Submitter: ViCOS GmbH

CMD 1 - Go to Position and Angle

Exemplary illustration of data bytes 0 ... 3:

Command ID 01 (CMD)



Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	1	Not Used (= (0)					
1	7	Position	POS	Vertical position	Enum:			
					0100:		01	00 %
					127:	Do not change		
8	1, /	Not Used (= ())					
	4/		· · · · · · · · · · · · · · · · · · ·					

9	7	Angle	ANG	Rotation angle	Enum:
					0100: 0100 %
					change
16	1	Not Used (= 0	0)		-
17	3	Repositioning	REPO	How to adjust the internal positioning tracker before going to the new position	Enum: 0: Go directly to POS/ANG 1: Go up (0%), then to POS/ANG 2: Go down (100%), then to POS/ANG Reserved 37:
20	1	Not Used (= 0	0)		
21	3	Locking mode	LOCK	Set/reset locking mode	Enum: 0: Do not change 1: Set blockage mode 26: Reserved 7: Deblockage
24	4	Channel	CHN	Channel address	Enum: 0: Channel 1 26: Reserved
28	4	Command ID	CMD	Command identifier	Enum: 1: Goto command

CMD 2 - Stop

Offset	Size	Data	ShortCut	Description	Vá	alic	l R	ang	Scale	Unit
0	4	Channel	CHN	Channel address	En	um	ì:			
						0:	/(Chan	nel 1	
4	4	Command ID	CMD	Command identifier	En	ıun	ı:			
						2:	S	Stop	commar	nd

CMD 3 - Query Position and Angle

Offset	Size	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0	4	Channel	CHN	Channel address	Enum	:		
					0:	Channe	l 1	
4	4	Command ID	CMD	Command identifier	Enum	:		
					3:	Query c	ommar	nd

CMD 4 - Reply Position and Angle

Offset	Size	Data	ShortCut	Description	V	alid Range	Scale	Unit
0	1	Not Used $(= 0)$))					
1	7	Position	POS	Current vertical position	Enum:			
					0100:			%
								0100
						Position unknown, v		
						after the next goto	cmd	
8	1	Not Used (= 0))					

9	7	Angle	ANG	Current rotation angle	Enum: 0100: 0100
					127: Angle unknown, will be known after the next goto cmd
16	5	Not Used (= 0))		
21	3	Locking mode	LOCK	Set/reset locking mode	Enum: 0: Normal (no lock) 1: Blockage mode 27: Reserved
24	4	Channel	CHN	Channel address	Enum: 0: Channel 1 115: Reserved
28	4	Command ID	CMD	Command identifier	Enum: 4: Reply command

D2-06: Multisensor Window Handle

EEP Family Table

Each TYPE has to support all telegrams and parameters marked in its column.

Message	Type 01
Message Type 0x00 Sensor Values	Χ
Message Type 0x10 Configuration Report	Χ
Message Type 0x20 Log Data 01	Χ
Message Type 0x21 Log Data 02	Χ
Message Type 0x22 Log Data 03	Χ
Message Type 0x23 Log Data 04	Χ
Message Type 0x80 Control and Settings	X

The list of parameters could be structured following the features that always include a certain group of parameters.

RORG	D2	VLD Telegram
FUNC	06	Multisensor Window Handle
TYPE	01	Alarm, Position Sensor, Vacation Mode, Optional Sensors

Submitter: SODA GmbH

Data exchange

Direction: bidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: Time-Triggered: Default is 20 Minutes; Event-Triggered Trigger event: Alarm, Handle Movement, Window Movement, Button Presses

Tx delay: 500 ms Rx timeout: 100 ms

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

Product Description

The device represented by this EEP is a "Multi-Sensor Window Handle with Alarm Functionality". It is powered by two 1.5V AA batteries.

It can be equipped with the following set of features:

- Alarm Sensor
- Handle Position Sensor
- Window Position Sensor

- Two General Purpose Buttons
- Temperature Sensor
- Humidity Sensor
- Illumination Sensor
- Motion Sensor
- Vacation Mode
- Battery Level Measurement
- Buzzer
- Two LEDs

Details to all features are listed below.

For pairing the bidirectional UTE method is used.

The device transmits the actual sensor values periodically (dDefault: 20 minutes) or on an event like "Handle Movement" or "Alarm".

After each transmission of a packet the radio part of the handle is in receive mode for a certain amount of time (default: 500 ms) and accepts then messages from a paired Controller/Gateway/... . For normal operation it is not necessary to send data to the handle. It is just needed to make some configurations, get log data or control some parts of the handle.

Because it is possible to have all possible permutations of the handle features out in the market, the EEP approach presented in this document is used. The variety of handle-products with different equipped features does not fit well to the EEP family approach preferred in the EnOcean world.

Feature Description

The handle may have all or a subset of the features described here. If a feature is not available (e.g. the sensor is not equipped), then this will be marked in the radio telegram (see detailed tables below).

Burglary Alarm Sensor

The handle can detect if someone tries to commit burglary on the window the handle is mounted on. The Burglary Alarm Sensor is automatically enabled/disabled each time the window is closed/opened. If an alarm is detected, a radio packet is send with "Burglary Alarm Triggered" flag set and (if handle is equipped with a buzzer) a local alarm sound is generated by the internal buzzer for a certain amount of time (180 s). During the alarm time a repeated "Burglary Alarm On" is send every 15 seconds + Random Offset (0...7 seconds).

Protection Plus Alarm Sensor

Protection Plus is a feature, which generates an alarm every time the handle is moved. Due to security reasons, the detailed documentation about this feature is available from SODA GmbH only under NDA.

Handle Position

The position of the handle is detected and transmitted on every change.

Window Position

It is possible to detect if the window is tilted or not tilted. A packet is send on every change.

General Purpose Buttons

There are two buttons on the handle which can be used as general purpose buttons to control blinds/shutters, lights, etc.

A packet is send when a button is pressed and again when it is released.

Temperature Sensor, Humidity Sensor, Brightness Sensor

The environmental sensors are updated periodically (adjustable, default: 20 minutes) and after this a packet with the updated values is send.

Motion Sensor

The handle can be equipped with a PIR Motion sensor which triggers a packet every time a motion change is detected.

Vacation Mode

If the Vacation Mode is enabled, the red LEDs on the sides of the handle light up every few seconds. This signalizes that the alarm monitoring is active and should be daunting for potential burglars.

The Vacation Mode can be enabled/disabled by a radio command or by a button press locally on the handle. If it is activated locally, a radio packet is sent out to signalize the change to a paired gateway.

Battery Monitor

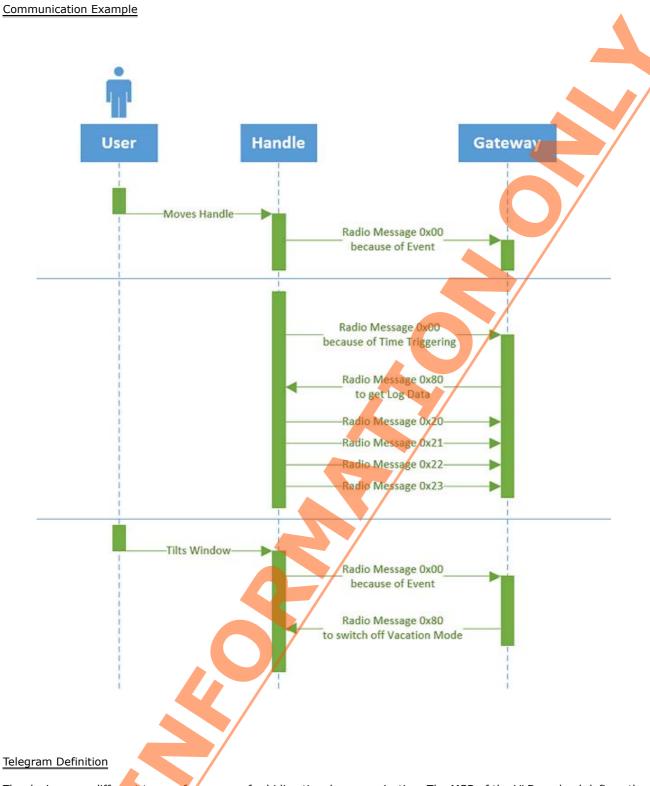
The handle monitors its battery level and transmits the state of the battery.

Battery Low Click

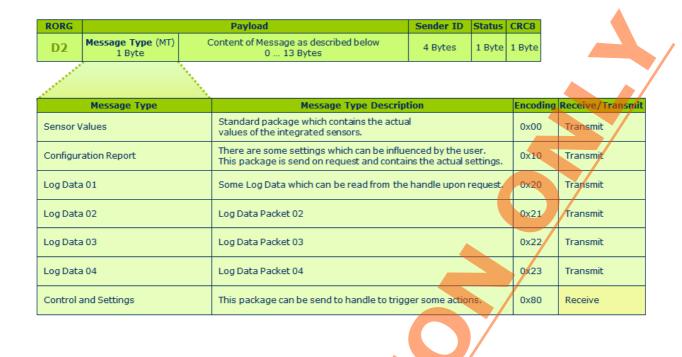
If enabled, the handle also makes some click noises when the battery level is critical.

Handle Closed Click

The handle generates a click sound every time the handle is closed (put in downward position). This signalizes the activation of the alarm monitoring and gives an acoustic feedback to the user. This click sound can be enabled or disabled by a radio command.



The device uses different types of messages for bidirectional communication. The MSB of the VLD payload defines the type of message as shown below in the first table. The different message types are listed in the second table. A detailed description of each message type is then followed in separate tables.



Message Type 0x00: Sensor Values

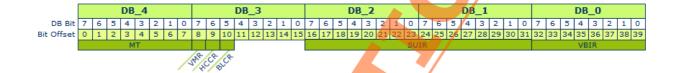
				DB_	_9							DE	3_	8							DE	3_7							D	B _	6						D	B _	5				٠.		
DB Bit	7 (6 :	5	4	3	2	1	0	7	6	5	4	3	3	2	1	0	7	6	5	4	3	2	1	0	7	6	. 5	4	1 3	3 2	2 1) 7	6	5	5 4	1 3	3	2	1	0	•	`	
Bit Offset	0 :	1 :	2	3	4	5	6	7	8	9	10	11	1	2 1	13	14	15	16	17	18	19	20	2:	1 22	23	3 24	4 2	5 2	6 2	7 2	8 2	9 3	0 3	1 3	2 3	3 3	4 3	5 3	6 3	37 3	38	39		١	
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		DB	Bit	7	_	5 5	[OB_		2	1	0	7	6	5	D	B_3	3	2	1/	-	7	6	5	- ОВ_ 4	2	2	1	0	7	6	5	 DB	_1 3	2	1	0	7	6	5	DI 4	B_0	2	1	0
		DB Off		_	60 4	5 5	5	4	3	2 45	1 46	0 47 4	7	6 49	5	D	B_:	3	2 53 5	1/14:	0 55 5	7 56 5	6	5	4	3	2 61	1 62	0	7 64	6	5	4	_1 3 68	2 69	1 70	0 71	7 72	6 73	5 74	4	3	2	1 7 78	. 0

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:			
					0x00: Mes	sage Type Ser	nsor Values	
8	4	Burglary Alarm		Burglary Alarm Trigger	Enum:			
				Signal	0x0:	Burglary Alar	m Not Trigge	ered
					0x1:	Burglary Alar	m Triggered	
					0x20xD	: Reserved		_
					0xE:	Supported +	Invalid	_
					0xF:	Not Supporte	ed .	
12	4			Protection Plus Alarm Trigger	Enum:			
		Alarm		Signal	0×0:	Protection Plu Triggered	ıs Alarm Not	
					0x1:	Protection Plu	ıs Alarm Trig	gered
					0x20xD:	Reserved		
					0xE:	Supported +	Invalid	
					0xF:	Not Supporte	d	

16	4	Handle Position	НР	Position of Handle	Enum:	
					0x0:	Handle Position Undefined
					0x1:	Handle Up
					0x2:	Handle Down
					0x3:	Handle Left
					0x4:	Handle Right
					0x50xD	: Reserved
					0xE:	Supported + Invalid
					0xF:	Not Supported
20	4	Window State	WS	State of Window	Enum:	
					0x0:	Window State Undefined
					0x1:	Window Not Tilted
					0x2:	Window Tilted
					0x30xD	: Reserved
					0xE:	Supported + Invalid
					0xF:	Not Supported
24	4	Button Right	BR	Button Right Activities	Enum:	
					0x0:	No Change
					0x1:	Button Pressed
					0x2:	Button Released
					0x30xD	: Reserved
					0xE:	Supported + Invalid
					0xF:	Not Supported
28	4	Button Left	BL	Button Left Activities	Enum:	
					0x0:	No Change
					0x1:	Button Pressed
					0x2:	Button Released
						: Reserved
					0xE:	Supported + Invalid
					0xF:	Not Supported
32	4	Motion	М	Motion sensing like typical	Enum:	
32	ľ	T TOCION		PIR sensors	0x0:	Motion Not Triggered
					0x1:	Motion Triggered
					-	: Reserved
					0xE:	Supported + Invalid
					0xF:	Not Supported
36	4	Vacation Mode	V	If Vacation Mode is active,	Enum:	
	·			the LEDs of	0x0:	No Change
				the handle light up every	OXO1	The change
				few seconds.	0x1:	Vacation Mode Locally Switched
				Vacation Mode can be		On
				activated remotely	0x2:	Vacation Mode Locally Switched
				by a radio command or		Off
				locally by a		Reserved
				button press at the handle	0x30xD:	
					0xE:	Supported + Invalid
					0xF:	Not Supported
40	8	Temperature	1	Measurement of	Enum:	
40	0	Temperature		Temperature in linear	0250:	
			/	0.32 °C steps	0250:	-20+60 °C
						Reserved
					251253:	. Coci ved
	ì				254:	Supported +
						Invalid
					255:	Not Supported
48	8	Humidity	Н	Measurement of Relative	Enum:	
				Humidity in	0200:	%
				linear 0.5 % steps		0100
					201253	: Reserved
	1				254:	Supported + Invalid
					255:	Not Supported
-						

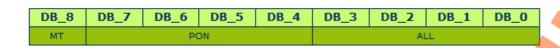
56	16	Illumination	I	Illumination linear in 1 lx	Enum:	
				steps	060000:	060000 lx
					60001:	Over Range
					6000265533:	Reserved
					65534:	Supported + Invalid
					65535:	Not Supported
72	5	Battery State	BS	State of the battery charge	Enum:	
				in 5 % steps	020:	0100
					2131: Reser	ved
77	3	Not Used (= 0)				

Message Type 0x10: Configuration Report



Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	8	Message Type	MT	Descriptor of t <mark>his message</mark>	Enum: Message Type Configuration 0x10: Report
8	1	Vacation Mode	VMR	Status of Vacation Mode	Enum: 0x0: Vacation Mode is Off 0x1: Vacation Mode is On
9		Handle Closed Click	HCCR	Status of Handle Closed Click Feature	Enum: Handle Closed Click Feature is 0x0: Disabled Handle Closed Click Feature is 0x1: Enabled
10	1	Battery Low Click	BLCR	Status of Battery Low Click Feature	Enum: Battery Low Click Feature is 0x0: Disabled Battery Low Click Feature is 0x1: Enabled
11		Not Used (= 0)			
16	16	Sensor Update Interval		Interval in seconds between the update of the environmental sensors. After each update period a Sensor Value packet (Message Type 0x00, see above) is transmitted	Enum: 0x00000x0004: Reserved 0x00050xFFFF: s 565535
32	8	Vacation Blink Interval		Interval in seconds between the LED blinks when Vacation Mode is activated	Enum: 0x000x02: Reserved 0x030xFF: s 3255

Message Type 0x20: Log Data 01



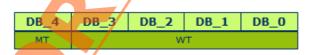
Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:		
					0x20: Message Typ	e Log Dat	a 01
8	32	Power Ons	PON	Number of Power Ons	Enum:		
					0x000000000xFl	FFFFFF:	7
40	32	Alarms	ALL	Number of Alarms	Enum:		
					0x000000000xFl	FFFFFF.	

Message Type 0x21: Log Data 02



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	Message Type	MT	Descriptor of this message	Enum:			
					Message Tyl 0x21: 02	pe Log Da	ta	
8	32	Handle Movements	НМС	Number of Handle Movements	Enum:			
		Closed		Closed	0x000000000xFFFFFFF:			
40	32	Handle Movements	НМО	Number of Handle Movements	Enum:			
		Opened		Opened	0x000000000xF	FFFFFFFF:		
72	32	Handle Movements			Enum:			
		Tilted		Tilted	0x000000000xF	FFFFFFF:		

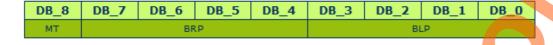
Message Type 0x22: Log Data 03



1	Off	fset	S	İΖ€	Data	ShortCut	Description	Valid Range	Scale	Unit
()		8		Message Type	MT	Descriptor of this message	Enum:		
			1	_				0x22: Message Typ	e Log Data	a 03

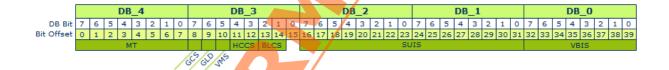
8	32	Window Tilts	WT	Number of Window Tilts	Enum:
					0x000000000xFFFFFFFF:

Message Type 0x23: Log Data 04



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:		
					0x23: Message Typ	oe Log Data	a 04
8	32	Button Right Presses	BRP	Number of Button Right Presses	Enum:		
					0x000000000xF	FFFFFFF:	,
40	32	Button Left Presses	BLP	Number of Button Left Presses	Enum:		
					0x000000000xF	FFFFFFF:	

Message Type 0x80: Control and Settings



Notes:

The following settings are stored non volatile inside the handle and only need to be send on a change request:

- Handle Closed Click Feature
- Battery Low Click Feature
- Sensor Update Interval
- Vacation Blink Interval

It is possible to trigger several of the actions in one message; e.g. if DB3.7 and DB3.6 both are set, the handle will transmit the messages with the message types: 0x10, 0x20, 0x21, 0x22 and 0x23

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	Message Type	MT	Descriptor of this message	Enum:		
					Message Type Control ox80: Settings	ontrol and	
8	1	Get Configuration	GCS		Enum:		
		Settings		Configuration Settings (Message Type 0x10, see above)	0x0: No Change		
					0x1: Start Transmissio	n	
9	1	Get Log Data	GLD	Start Transmission of the Log	Enum:		
				Data Packets	0x0: No Change		
				(Message Type 0x2x, see above)	0x1: Start Transmissio	n	
10	1	Vacation Mode	VMS	Set Vacation Mode	Enum:		
	7/				0x0: Switch Vacation N	1ode Off	_
					0x1: Switch Vacation N	1ode On	

11	2	Handle Closed Click	HCCS	Set Handle Closed Click Feature	Enum: No Change 0x0: Disable Handle Closed Click 0x1: Feature Enable Handle Closed Click 0x2: Feature
13	2	Battery Low Click	BLCS	Set Battery Low Click Feature	Reserved 0x3: Enum:
				reacure	0x0: No Change 0x1: Disable Battery Low Click Feature 0x2: Enable Battery Low Click Feature 0x3: Reserved
15	1	Not Used (= 0)	•		
16	16	Sensor Update Interval	SUIS	Set Sensor Update Interval	Enum: 0x0000: No Change Reserved 0x00010x0004: 0x00050xFFFF: 565535 s
32	8	Vacation Blink Interval	VBIS	Set Vacation Blink Interval	Enum: 0x00: No Change 0x010x02: Reserved 0x030xFF: s 3255

D2-10: Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program

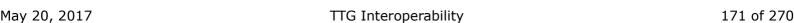
Submitter: Kieback&Peter GmbH & CO KG

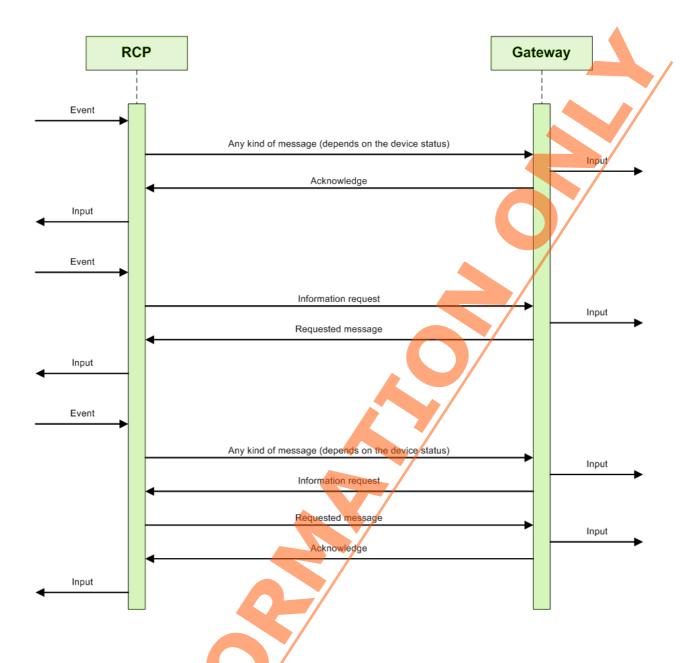
Description

This VLD family consists of several profiles for a group of different room control panels with various functions and measurements (see following table of parameters for a feature list).

The profiles are designed to establish a communication between a battery-powered room control panel and a line-powered (and therefor always receiving) gateway. It also allows a gateway-to-gateway communication.

Due to the high energy consumption while powering the receiver, the room control panel will always be the initiator of a data exchange. It cannot be triggered by the gateway as it is not in a receiving mode most of the time.





<u>Data exchange</u> <u>Direction: bidirectional</u>

Addressing: unicast (ADT) & broadcast
Communication trigger: event- & time-triggered
Communication interval: can be defined during runtime

Trigger event: device status change

Tx delay: 1 s Rx timeout: N/A

Teach-in method: UTE

Security

Encryption required: no Security level format: -

EEP Family Table:

Telegram	Type 00	Type 01	Type 02
General Message	Χ	Χ	Χ
Data Message	Χ	Χ	Χ
Configuration Message	Х	Χ	Χ
Room Control Setup	Х	Χ	Χ
Time Program Setup	Χ	Χ	-

Parameter Type 00 Type 01 Type 02

	Ì	Ī	Ī
Message Identifier	Χ	Χ	Χ
Message Continuation Flag	Χ	Χ	Χ
Information Request Classifier	Χ	Χ	Χ
Feedback Classifier	Χ	Χ	Χ
General Message Type	Χ	Χ	Χ
Humidity	Χ	-	-
Humidity Validity Flag	Χ	-	-
Fan Speed Control	Χ	-	-
Fan Speed Validity Flag	Χ	-	-
Fan Speed Mode	Χ	_	-
Custom Warning 2	Χ	Χ	Χ
Custom Warning 1	Χ	Х	Х
Mold Warning	Χ	-	-
Window Open Detection	X	Х	Х
Battery Status	X	X	X
Solar-power Status	X	_	X
PIR Status	X		X
	X	- V	X
Occupancy Button Status	X	X -	_
Cooling Operation Status		-	
Heating Operation Status	X	-	-
Room Control Mode	X	X	X
Temperature Set Point Validity	X	X	X
Temperature Validity	Χ	X	X
Temperature Set Point	Х	X	X
Room Temperature	Х	X	X
PIR Status Lock	Χ	-	X
Temperature Scale Lock	Χ	X	-
Display Content Lock	Χ	Χ	X
Date / Time Lock	X	X	X
Time Program Lock	X	X	X
Occupancy Button Lock	X	X	Χ
Temperature Set Point Lock	X	X	-
Fan Speed Lock	X	- /	-
Radio Communication Interval	X	X	Х
Key Lock	X	X	_
,	X	Х	Х
Temperature Scale	X	Х	X
	X	X	X
Time Notation	X	X	X
	X	X	X
Month	X	X	X
Year		^	^
		V	V
Minuto	X	X	X
Minute	X X	Χ	Х
Hour	X X X	X X	X X
Hour Date / Time Update Flag	X X X	X X X	Х
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode	X X X X	X X	X X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode	X X X X X	X X X X	X X X -
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode	X X X X X X X	X X X X - X	X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode	X X X X X X X	X X X X - X	X X X -
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode	X X X X X X X X	X X X X - X	X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode	X X X X X X X X X	X X X X - X X X	X X X - - X X X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode	X X X X X X X X X X	X X X X - X	X X X - - X X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode	X X X X X X X X X	X X X X - X X X	X X X - - X X X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode	X X X X X X X X X X	X X X X - X X X X	X X X - - X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode Temperature Set Point Flag Comfort Mode	X X X X X X X X X X X	X X X X - X X X X	X X X - - X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode End Time: Minute	X X X X X X X X X X X X	X X X X - X X X X X X	X X X - - X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode End Time: Minute End Time: Hour	X X X X X X X X X X X X X	X X X X - X X X X - X X	X X X - - X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode End Time: Minute End Time: Minute	X X X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X	X X X - - X X X - - X
Hour Date / Time Update Flag Temperature Set Point Building Protection Mode Temperature Set Point Pre-comfort Mode Temperature Set Point Economy Mode Temperature Set Point Comfort Mode Temperature Set Point Flag Building Protection Mode Temperature Set Point Flag Pre-comfort Mode Temperature Set Point Flag Economy Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode Temperature Set Point Flag Comfort Mode End Time: Minute End Time: Hour Start Time: Hour	X X X X X X X X X X X X X X X X	X X X X - X X X X X X X X	X X X - - X X X - - X



FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room St	tatus Information
TYPE	00	Type 0x00	
Submitter: Ki	eback&Peter	GmbH & CO KG	

General Message

exemplary illustration of data bytes 0/1:

				DB	_1				DB_0							
DB_1.BIT_7 ← 0		6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
		M	ID				M	CF				IRC	,	FE	3C	GMT

Offset	Size	Data	ShortCut	Description	Valid	Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum	
					0:	General Message
3	3	Not Used (= 0)				
6			MCF	Indicates if another telegram has to be	Enum	
		continuation flag		expected or if the message is complete	3:	Reserved
					2:	Automatic message control
						Incomplete
					0:	Complete
8		Not Used (= 0)				
10		Information request	IRC	Defines the type of information request	Enum	
		classifier			7:	Reserved
					6:	Reserved
					5:	Reserved
					4:	Time program request
					3:	Room control setup request
					2:	Configuration request
					1:	Data request
					0:	Acknowledge request
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum	
				,,	3:	Reserved
					2:	Message repetition request
					1:	Telegram repetition request
					0:	Acknowledge / heartbeat
15	1	General message		Indicates if the general message is a	Enum	
		type		feedback or an information request		Information request

0: Feedback

Data Message

Offset	Sizo	Data	ShortCut	Description	Valid Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum:
Ü		14c33age lacitation	MID	Defines the type of message	1: Data Message
2	3	Not Used (= 0)			1. Data Nessage
3 6	2	Message	MCF	Indicates if another telegram has to be	Enum
O	2	continuation flag	MCF	expected or if the message is complete	Enum: 3: Reserved
					3. Reserved
					2: Automatic message
					control
					1: Incomplete
					0: Complete
8	8	Humidity	HUM	Measured humidity	0255 0100 %
16	1	Humidity validity	HVF	Indicates if the value for humidity is valid	Enum:
		flag			1: Valid value
					0: No change
17	7	Fan speed control	FS	Fan speed	0100 0100 %
24	1	Fan speed validity	FSV	Indicates if the fan speed value is valid	Enum:
		flag			1: Valid value
					0: No change
25	1	Fan speed mode	FSM	Defines the mode the fan runs in	Enum:
					1: Individual fan speed
					control
					0: Central fan speed
26	_	Not the defeat			control
26	1	Not Used (= 0)	CMO		-
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum:
					1: True
20	_	C	CM4	El Controller de l'action de l	0: False
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum:
					1: True
			1101		0: False
29	1	Mold warning	MW	Flag for an application depending mold warning	Enum:
				waiting	1: True
					0: False
30	2	Window open	WOD	Indicates if an open window is detected	Enum:
		detection			3: Reserved
					2: Open
					1: Closed
					0: No change
32	1	Not Used (= 0)		-	
33	2	Battery status	BS	Battery status	Enum:
					3: Critical
					2: Low
					1: Good
			0.7.5		0: No change
35	II.	Solar-powered status	SPS	Indicates if the device is powered by its solar cell	Enum:
		Status		Solai Cell	1: Not solar-powered
					0: Solar-powered
36	2	PIR status	PIR	Indicates if the PIR detected a movement	Enum:
					3: Locked
	7/				2. Mayararat di tanàn
					2: Movement detected

						No mo	vement	
						No cha		
20		0	ODC	To disable if the converse we houte a sur-	<u> </u>			
38	2	Occupancy button	OBS	Indicates if the occupancy button was	Enum:			
		status		pressed and its occupancy status	3:	Reserv	ed	
						Button unoccu	pressed a	and
						Button occupie	pressed a	ind
						No cha		
40	2	Cooling	C00	Recent cooling operation status	Enum:	Automa	tic	
					2:	Off	auc	
					1:	On /		
					0:	No cha	nge	
42	2	Heating	HEA	Recent heating operation status	Enum:			
						Automa	atic	
						Off		
						On		
	_				1	No cha	nge	
44	2	Room control mode	RCM	Recent room control mode	Enum:			
							g protection	on
						Pre-cor		
					-	Econor		
46	1	Temperature set	SPV	Indicates if the temperature set point	Enum:			
40		point validity	51 V	value is valid		Valid v	alue	
		,			l	No cha		
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum:			
					1:	Valid v	alue	
					0:	No cha		
48	8	Temperature set point	TSP	Recent temperature set point	0255	5	0+40	°C
56	8	Temperature	TMP	Recent room temperature	0255	5	0+40	°C

Configuration Message

Offset	Size	Data	ShortCut	Description	Val Ran		Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum 2:		iguration sage	
3	3	Not Used (= 0)						
6		Message continuation flag		Indicates if another telegram has to be expected or if the message is complete	3: 2:	Rese	matic messa	ge
					0:		plete	
8	1	PIR status lock	PSL	Indicates if the PIR status is transmitted or	Enum	:		
				kept inside the room control panel	1:	Unlo	cked	
					0:	Lock	ed	
9		Temperature scale lock	TSL	Indicates if the temperature scale can be changed at the room control panel	Enum 1: 0:	: Unlo Lock		

10	1	Display content lock	DCL	Indicates if the display content can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
11	1	Date / time lock	DTL	Indicates if date and time can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
12	1	Time program lock	TPL	Indicates if the time program can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
13	1	Occupancy button lock	OBL	Indicates if the occupancy status can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
14	1	Temperature set point lock	SPL	Indicates if the temperature set point can be changed at the room control panel	Enum: 1. Unlocked 0: Locked
15	1	Fan speed lock	FSL	Indicates if the fan speed can be changed at the room control panel	Enum: 1: Unlocked 0: Locked
16	6	Radio communication interval	RCI	Defines the longest time between two consecutive telegrams (clock-based communication)	Enum: 63: 24 hours 62: 12 hours 61: 3 hours 160 min
					160: 0: No communication interval
22	1	Key lock	KL	Indicates if all buttons on the device are locked	Enum: 1: Unlocked 0: Locked
23	1	Not Used (= 0)	•		
24	3	Display content	DC	Defines the main display content	Enum:
					7: Humidity 6: Display off
					5: Temperature set point
			, (4: Room temperature (external)
					3: Room temperature (internal) 2: Time
					1: Default
					0: No change
27	2	Temperature scale	rs	Defines the used temperature scale for the room control panel display and menus	3: ° Fahrenheit 2: ° Celsius 1: Default
29	1	Daylight saving time flag	DST	Indicates if daylight saving time is supported	Enum: 1: Not supported
20.	2	Time notation	TN	Defines the used time notation	0: Supported
30	Z	Time notation	TN	Defines the used time notation	Enum: 3: 12 h
					2: 24 h
	1				1: Default
32	5	Day	DAY	Date format: YYYY/MM/DD	0: No change 131 131 day

4	Month	MON	Date format: YYYY/MM/DD	112	112	mon	
7	Year	YR	Date format: YYYY/MM/DD				
6	Minute	MIN	Time format: hh:mm	059	059	min	
2	Not Used (= 0)						
5	Hour	HR	Time format: hh:mm	023	023	h	
2	Not Used (= 0)						
1	Date / time update flag	DTU	Indicates if an update of date or time is provided				
	7 6 2	7 Year 6 Minute 2 Not Used (= 0) 5 Hour 2 Not Used (= 0) 1 Date / time update	7 Year YR 6 Minute MIN 2 Not Used (= 0) 5 Hour HR 2 Not Used (= 0) 1 Date / time update DTU	7 Year YR Date format: YYYY/MM/DD year = 2000 + x 6 Minute MIN Time format: hh:mm 2 Not Used (= 0) 5 Hour HR Time format: hh:mm 2 Not Used (= 0) 1 Date / time update DTU Indicates if an update of date or time is	7 Year YR Date format: YYYY/MM/DD year = 2000 + x 0127 6 Minute MIN Time format: hh:mm 059 2 Not Used (= 0) Time format: hh:mm 023 2 Not Used (= 0) Indicates if an update of date or time is provided Enum: 1: Up	7 Year YR Date format: YYYY/MM/DD year = 2000 + x 0127 20002127 6 Minute MIN Time format: hh:mm 059 059 2 Not Used (= 0) 23 023 023 2 Not Used (= 0) 23 023 023 1 Date / time update flag DTU Indicates if an update of date or time is provided Enum: 1: Update	

Room Control Setup

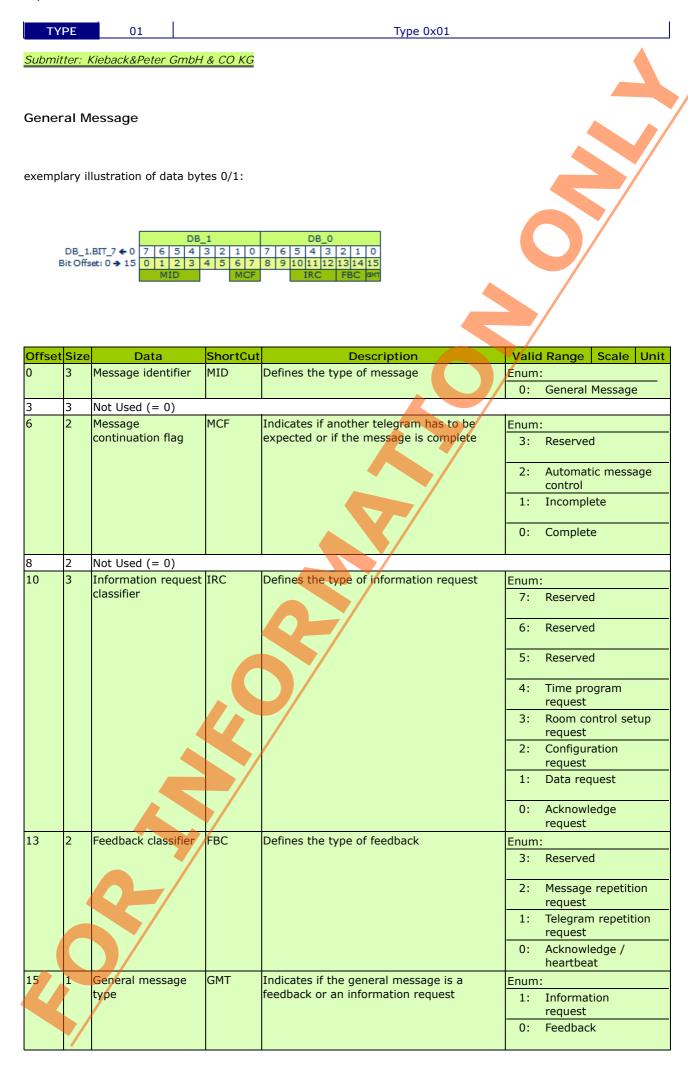
Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	3	Message identifier	MID	Defines the type of message	/			
3	3	Not Used (= 0)	•		•			
6	2	Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	2: Automatic message control 1: Incomplete 0: Complete			
8	8	Temperature set point building protection mode	SPB	Temperature set point building protection mode	0255	0+40	°C	
16	8	Temperature set point pre-comfort mode	SPP	Temperature set point pre-comfort mode	0255	0+40	°C	
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C	
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C	
40	4	Not Used (= 0)			•			
44	1	Temperature set point flag building protection mode	SFB	Indicates if a temperature set point for the building protection mode is provided	1: Valid	value hange	-	
45	1	Temperature set point flag pre-comfort mode	SFP	Indicates if a temperature set point for the pre-comfort mode is provided	1: Valid	value hange		
46	1	Temperature set point flag economy mode	SFE	Indicates if a temperature set point for the economy mode is provided	1: Valid	value hange	-	
47	1	Temperature set point flag comfort mode SFC Indicates if a temperature set point for the comfort mode is provided 0: No change 1: Valid value 0: No change						

Time Program Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum:		
					4: Time Pr	ogram	
					Setup		
3	3	Not Used (= 0)					_

6	2	Message	MCF	Indicates if another telegram has to be	Enum	
		continuation flag		expected or if the message is complete	3:	Reserved
					2:	Automatic message
						control
					1:	Incomplete
					0:	Complete
					0.	Complete
8	2	Not Used (= 0)				
10	6	End time: Minute	ETM	Time format: hh:mm	059	059/1
16	3	Not Used (= 0)	•			
19	5	End time: Hour	ETH	Time format: hh:mm	023	023 1
24	2	Not Used (= 0)	•			
26	6	Start time: Minute	STM	Time format: hh:mm	059	059 1
32	3	Not Used (= 0)				
35	5	Start time: Hour	STH	Time format: hh:mm	023	023 1
40	4	Period	PER	Assigned period of time (weekdays) for the	Enum	:/
				provided schedule time		Friday - Monday
						,,
					14:	Friday - Sunday
					13:	Thursday - Friday
					12:	Wednesday -
					44.	Friday
					11:	Tuesday - Thursday
					10.	Monday -
					10.	Wednesday
					9:	Sunday
						,
					8:	Saturday
					7:	Friday
					6:	Thursday
					0.	Titursuay
					5:	Wednesday
						,
					4:	Tuesday
					3:	Monday
						Cit to Cit
					2:	Saturday - Sunday
					1:	Monday - Friday
					1.	Pionally Triday
					0:	Monday - Sunday
						,
44	2	Room control	RCM	Assigned room control mode for the provided	Enum	
		mode		schedule time	3:	Building protection
					2:	Pre-comfort
					1:	Economy
					0:	Comfort
46	1	Not Used (= 0)				
47	1	Time program	TPD	Deletes the stored time program	Enum	
		deletion			1:	Deletion
					0:	No deletion

	/	
RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program



Data Message

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum:
					1: Data Message
3	3	Not Used (= 0)			
6	2	Message	MCF	Indicates if another telegram has to be	Enum:
		continuation flag		expected or if the message is complete	3: Reserved
					2: Automatic message control
					1: Incomplete
					0: Complete
8	8	Not Used (= 0)			
16	1	Not Used (= 0)			
17	7	Not Used (= 0)			<u> </u>
24	1	Not Used (= 0)			<u>/</u>
25	1	Not Used (= 0)			<u> </u>
26	1	Not Used (= 0)	•		
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum:
					1: True
					0: False
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum:
					1: True
					0: False
29	1	Not Used (= 0)			1
	2	Window open	WOD	Indicates if an open window is detected	Enum:
		detection			3: Reserved
					2: Open
					1: Closed
					0: No change
32	1	Not Used (= 0)			<u> </u>
33	2	Battery status	BS	Battery status	Enum:
		,			3: Critical
					2: Low
					1: Good
					0: No change
35	1	Not Used (= 0)			or the change
36	2	Not Used (= 0)		/	
38	2	Occupancy button	OBS	Indicates if the occupancy button was	Enum:
		status		pressed and its occupancy status	3: Reserved
					2: Button pressed and
					unoccupied 1: Button pressed and
					occupied
					0: No change
40	2	Not Used (= 0)			
42	2	Not Used (= 0)			
44	2	Room control mode	RCM	Recent room control mode	Enum:
		control mode			3: Building protection
					2: Pre-comfort
					1: Economy
					0: Comfort
46	1	Temperature set	SPV	Indicates if the temperature set point	
TU		point validity	31 V	value is valid	Enum: 1: Valid value
					0: No change
					J. No change

47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum:		
					1: Valid v	alue	
					0: No cha	nge	
48	8	Temperature set	TSP	Recent temperature set point	0255	0+40	°C
		point					
56	8	Temperature	TMP	Recent room temperature	0255	0+40	°C

Configuration Message

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum:		
						figuration sage	
3	3	Not Used (= 0)			-		
6	2	Message	MCF	Indicates if another telegram has to be	Enum:		
		continuation flag		expected or if the message is complete		erved	
					con		ge
						omplete	
					0: Con	nplete	
8		Not Used (= 0)	TCI	To the control of the	_		
9	1	Temperature scale lock	TSL	Indicates if the temperature scale can be changed at the room control panel	Enum:	ocked	
		, oo a			1: Unlo		
10	1	Display content lock	DCL	Indicates if the display content can be	Enum:	\cu	
				changed at the room control panel		ocked	
					0: Locl		
11	1	Date / time lock	DTL	Indicates if date and time can be changed	Enum:		
				at the room control panel	1: Unlo	ocked	
					0: Locl	ked	
12	1	Time program lock	TPL	Indicates if the time program can be changed at the room control panel	Enum:		
				changed de the room control panel	1: Unlo	ocked ved	
13	1	Occupancy button	OBL	Indicates if the occupancy status can be	Enum:	\Cu	
	_	lock		changed at the room control panel		ocked	
					0: Locl	ked	
14	1	Temperature set	SPL	Indicates if the temperature set point can	Enum:		
		point lock		be changed at the room control panel		ocked	
					0: Loci	ked	
15 16		Not Used (= 0) Radio	RCI	Defines the leagest time between two	l		
10	О	communication interval		Defines the longest time between two consecutive telegrams (clock-based communication)	Enum: 63: 24	hours	
		interval			62: 12	hours	
					61: 3 h	nours	
					160:	.60 min	
						communicati erval	on
22	1	Key lock	KL	Indicates if all buttons on the device are	Enum:		
				locked		ocked	
22	1	Not Head (O)			0: Loc	ked	
23	4/	Not Used (= 0)			-		

24	3	Display content	DC	Defines the main display content	Enum:		
					7: Hu	ımidity	
					6: Di	splay off	7
						mperature set	
						om temperatur xternal)	e
						om temperatur nternal)	e
					2: Ti	me	
						efault	
					0: No	change	
27	2	Temperature scale	TS	Defines the used temperature scale for the			
				room control panel display and menus		ahrenheit	
						Celsius efault	
						change	
29	1	Daylight saving	DST	Indicates if daylight saving time is	Enum:		
		time flag		supported	1: No	t supported	-
					0: St	ipported	_
30	2	Time notation	TN	Defines the used time notation	Enum:		
					3: 12	! h	
					2: 24	h	
					-	efault	
						change	
32	5	Day	DAY	Date format: YYYY/MM/DD	131	131	day
37 41	4 7	Month	MON	Date format: YYYY/MM/DD	112	112	mon
41		Year	YR	Date format: YYYY/MM/DD year = 2000 + x	0127	20002127	year
48	6	Minute	MIN	Time format: hh:mm	059	059	min
54	2	Not Used (= 0)	1		1		
56	5	Hour	HR	Time format: hh:mm	023	023	h
61	2	Not Used (= 0)					
63	1	Date / time update	DTU	Indicates if an update of date or time is	Enum:		
		flag		provided		odate	
					0: No	update	

Room Control Setup

Offset	Size	Data	ShortCut	Description	Va Rar	lid nge	Scale	Unit	
0	3	Message identifier	MID	Defines the type of message	Enum 3:		n Control p		
3	3 Not Used (= 0)								
6	2	Message continuation flag		Indicates if another telegram has to be expected or if the message is complete		Rese	rved		
4					1:	mess	age contr	ol	
8	8	Temperature set point building protection mode	SPB	Temperature set point building protection mode	025	5	0+40	°C	

16	8	Not Used (= 0)					
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40 °C	;
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40 °C	
40	4	Not Used (= 0)					
44	1	Temperature set point flag building protection mode	SFB	Indicates if a temperature set point for the building protection mode is provided	1: Valid	value hange	
45	1	Not Used (= 0)					
46	1	Temperature set point flag economy mode	SFE	Indicates if a temperature set point for the economy mode is provided	1: Valid	value hange	
47	1	Temperature set point flag comfort mode	SFC	Indicates if a temperature set point for the comfort mode is provided	1: Valid	value hange	

Time Program Setup

				_				
Offset			ShortCut			Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum			
					4:	Time Pro	gram	
2	_	Mat Hand (O)				Setup		
3		Not Used (= 0)	MCE	To the last of another than the	_			
6	2	Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	Enum			
		continuation hag		expected of it the message is complete	3:	Reserve	3	
					2:	Automat	ic mess	age
						control		J
					1:	Incompl	ete	
					0:	Complet	e	
0	2	Not Used (- 0)						
8 10	6	Not Used (= 0) End time: Minute	ETM	Time format: bh:mm	059		059	1
16	+	Not Used (= 0)	E114	printe formac. William	039		039	T
19		End time: Hour	ETH	Time format: hh:mm	023		023	1
24		Not Used (= 0)	- 111	Time format: minim	025		025	-
26		Start time: Minute	STM	Time format: hh:mm	059		059	1
32	_	Not Used (= 0)	311	Time to make the time time.	055		055	-
35		Start time: Hour	STH	Time format: hh:mm	023		023	1
40		Period	PER	Assigned period of time (weekdays) for the	Enum		011123	-
	•			provided schedule time		Friday -	Monday	,
						,	,	
					14:	Friday -	Sunday	
					13:	Thursda	y - Frida	ау
					12:	Wedneso Friday	day -	
					11.	Tuesday	_	
	4					Thursda		
					10:	Monday	-	
						Wedneso	day	
					9:	Sunday		
					0,	Caturday		
					8:	Saturday	/	
					7:	Friday		
					6:	Thursda	У	

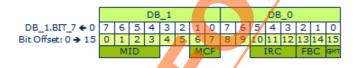
					5:	Wednesday
					4:	Tuesday
					3:	Monday
					2:	Saturday - Sunday
					1:	Monday - Friday
					0:	Monday - Sunday
44	2	Room control	RCM	Assigned room control mode for the provided	Enum	
		mode		schedule time	3:	Building protection
					2:	Pre-comfort
					1:	Economy
					0:	Comfort
46	1	Not Used (= 0)				
47	1	Time program	TPD	Deletes the stored time program	Enum	
		deletion			1:/	Deletion
					0:	No deletion

RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	02	Type 0x02

Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum			
					0:	General	Message	9
3	3	Not Used (= 0)						
6				Indicates if another telegram has to be	Enum			
		continuation flag		expected or if the message is complete	3:	Reserved	t	
					2:	Automat control	ic messa	age
					1:	Incomple	ete	
					0:	Complet	е	
8	2	Not Used (= 0)						
10		Information request	IRC	Defines the type of information request	Enum			
		classifier			7:	Reserved	d	

					6:	Reserved
					5:	Reserved
					4:	Time program request
					3:	Room control setup request
					2:	Configuration request
					1:	Data request
					0:	Acknowledge request
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum	
					3:	Reserved
					2:	Message repetition
						request
					1:	Telegram repetition request
					Ø:	Acknowledge / heartbeat
15	1	General message	GMT	Indicates if the general message is a	Enum	:
		type		feedback or an information request	1:	Information
						request
					0:	Feedback

Data Message

Offset	Size		ShortCut		Valid Range Scale Unit						
0	3	Message identifier	MID	Defines the type of message	Enum:						
					1: Data Message						
3	3	Not Used (= 0)									
6	2	Message	MCF	Indicates if another telegram has to be	Enum:						
		continuation flag		expected or if the message is complete	3: Reserved						
					2: Automatic message control						
					1: Incomplete						
					0: Complete						
8	8	Not Used (= 0)									
16	1	Not Used (= 0)	t Used (= 0)								
17	7	Not Used (= 0)									
24	1	Not Used (= 0)	7/								
25	1	Not Used (= 0)									
26	1	Not Used (= 0)									
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum:						
					1: True						
	4				0: False						
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum:						
					1: True						
					0: False						
29	1	Not Used (= 0)			•						
30	2	Window open	WOD	Indicates if an open window is detected	Enum:						
		detection			3: Reserved						
	1				2: Open						
					1: Closed						
					0: No change						

32	1	Not Used (= 0)					
33	2	Battery status	BS	Battery status	Enum: 3: Critical 2: Low 1: Good 0: No cha		1
35	1	Solar-powered status	SPS	Indicates if the device is powered by its solar cell	Enum: 1: Not so	ar-powered	ed
36	2	PIR status	PIR	Indicates if the PIR detected a movement	Enum: 3: Locked 2: Movem	ent detectivement	ted
38	2	Occupancy button status	OBS	Indicates if the occupancy button was pressed and its occupancy status	unoccu	pressed a pied pressed a ed	
40	2	Not Used (= 0)			L.		
42	2	Not Used (= 0)					
44	2		RCM	Recent room control mode	Enum: 3: Buildin 2: Pre-coi 1: Econor 0: Comfoi	ny	on
46	1	Temperature set point validity	SPV	Indicates if the temperature set point value is valid	Enum: 1: Valid v 0: No cha		
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum: 1: Valid v 0: No cha	alue	
48	8	Temperature set point	TSP	Recent temperature set point	0255	0+40	°C
56	8	Temperature	TMP	Recent room temperature	0255	0+40	°C

Configuration Message

Offset	Size	Data	ShortCut	Description	Val Ran		Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum			
					2:		figuration sage	
3	3	Not Used (= 0)	•					
6				3	Enum	:		
		continuation flag		expected or if the message is complete	3:	Rese	erved	
					2:	Auto	matic messa rol	ge
					1:	Inco	mplete	
					0:	Com	plete	

8	1	PIR status lock	PSL	Indicates if the PIR status is transmitted or	Enum:
	-	TIN Status Tock	l SL	kept inside the room control panel	1: Unlocked
					0: Locked
0	1	Not Used (= 0)			U. LUCKEU
9	1	Display content lock	DCI	Indicates if the display content can be	Faure
10	1	Display Content lock	DCL	changed at the room control panel	Enum:
				landinged at the room control panel	1: Unlocked
					0: Locked
11	1	Date / time lock	DTL	Indicates if date and time can be changed	Enum:
				at the room control panel	1: Unlocked
					0: Locked
12	1	Time program lock	TPL	Indicates if the time program can be	Enum:
				changed at the room control panel	1: Unlocked
					0: Locked
13	1	Occupancy button	OBL	Indicates if the occupancy status can be	Enum:
	-	lock	ODL	changed at the room control panel	1: Unlocked
					0: Locked
1.4	1.	Not the difference of			U. Locked
14	1	Not Used (= 0)			
15	1	Not Used (= 0)			
16	6	Radio	RCI	Defines the longest time between two	Enum:
		communication		consecutive telegrams (clock-based	63: 24 hours
		interval		communication)	
					62: 12 hours
					61: 3 hours
					160 min
					160:
					0: No communication
					interval
22	1	Not Used (= 0)			
23	1	Not Used (= 0)			
24	3	Display content	DC	Defines the main display content	Enum:
					7: Humidity
					6: Display off
					5: Temperature set
					point
					4: Room temperature
					(external)
					(external) 3: Room temperature
					(external) 3: Room temperature (internal)
					(external) 3: Room temperature
					(external) 3: Room temperature (internal) 2: Time
					(external) 3: Room temperature (internal)
					(external) 3: Room temperature (internal) 2: Time 1: Default
					(external) 3: Room temperature (internal) 2: Time
27	2				(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change
27	2	Temperature scale	TS	Defines the used temperature scale for the	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum:
27	2	Temperature scale	TS	Defines the used temperature scale for the room control panel display and menus	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit
27	2	Temperature scale	TS		(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum:
27	2	Temperature scale	TS		(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit
27	2	Temperature scale	TS		(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius
27	2		TS	room control panel display and menus	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change
		Temperature scale Daylight saving time flag			(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum:
		Daylight saving		room control panel display and menus Indicates if daylight saving time is	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported
29		Daylight saving time flag	DST	room control panel display and menus Indicates if daylight saving time is supported	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported
		Daylight saving		room control panel display and menus Indicates if daylight saving time is	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum:
29		Daylight saving time flag	DST	room control panel display and menus Indicates if daylight saving time is supported	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h
29		Daylight saving time flag	DST	room control panel display and menus Indicates if daylight saving time is supported	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h 2: 24 h
29		Daylight saving time flag	DST	room control panel display and menus Indicates if daylight saving time is supported	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h 2: 24 h 1: Default
29		Daylight saving time flag Time notation	DST	room control panel display and menus Indicates if daylight saving time is supported	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h 2: 24 h 1: Default 0: No change
29		Daylight saving time flag	DST	room control panel display and menus Indicates if daylight saving time is supported	(external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h 2: 24 h 1: Default

41	7	Year	YR	Date format: YYYY/MM/DD year = 2000 + x	0127	20002127	year
48	6	Minute	MIN	Time format: hh:mm	059	059	min
54	2	Not Used (= 0)					
56	5	Hour	HR	Time format: hh:mm	023	023	h
61	2	Not Used (= 0)					
63		Date / time update flag	DTU	Indicates if an update of date or time is provided	1: Upd 0: No	late update	

Room Control Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	7	om Control tup	
3		Not Used (= 0)	ı				
6	2	Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	3: Re	served	
					me	tomatic essage contro	ollc
						complete	
					0: Co	mplete	
8	8	Not Used (= 0)					
16	8	Not Used (= 0)					
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C
40	4	Not Used (= 0)					
44	1	Not Used (= 0)					
45	1	Not Used (= 0)			-		
46	1	Temperature set point flag economy mode		Indicates if a temperature set point for the economy mode is provided		lid value change	
47	1	Temperature set point flag comfort mode	SFC	Indicates if a temperature set point for the comfort mode is provided		lid value change	

D2-11: Bidirectional Room Operating Panel

Submitter: Thermokon Sensortechnik GmbH

Data exchange

Direction: bidirectional (Smart-Ack) Addressing: broadcast and addressed

Communication trigger: event- & time-triggered

Communication interval: time-triggered (configurable at the device) & event-triggered

Trigger event: keypress

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Smart-Ack teach-in without repeater

Security

Encryption required: no Security level format: -

Product Description

The device represented by this EEP is a "Bidirectional Room Operating Panel with Display". It is powered by solar cell.

It may be equipped with the following features (for details please see the EEP-Family table below):

- Temperature Sensor
- Humidity Sensor
- Temperature Setpoint Adjustment
- Fan Speed Adjustment
- Occupancy-State Adjustment

For pairing the bidirectional "Smart Ack Teach-In without repeater" method is used.

The device transmits the actual sensor values periodically (default: 1000 s) or on the event keypress.

Temperature Sensor, Humidity Sensor

The environmental sensors are updated periodically (adjustable, default: 100 s) and, if there is a change, the updated values will be send immediately.

The Smart Ack functionality will be used for setting display symbols like "window open, heating/cooling, occupancy state" or for overwriting parameters like setpoint, fan speed or occupancy state which are stored at the device.

EEP Family Table:

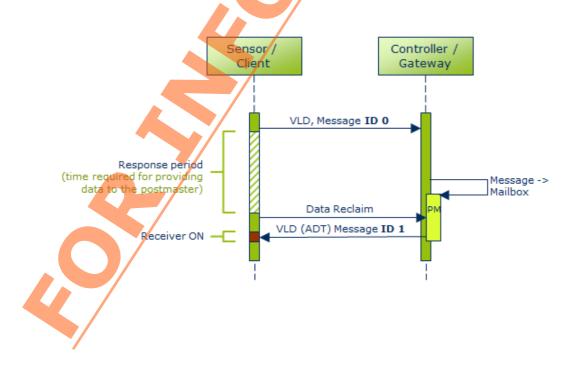
Type	01	02	03	04	05	06	07	08
Temperature Measurement	Х	Χ	Χ	Χ	Χ	Χ	X	Χ
Setpoint	Х	Χ	Χ	Χ	Χ	Χ	Χ	Χ
Humidity Measurement	-	Χ	-	Χ	-	Χ	-	Χ
Fan Speed	-	-	Χ	Χ	Χ	Χ	-	-
Occupancy	-	-	-	-	Χ	Χ	Χ	Χ

For the types 0x01, 0x03, 0x05, 0x07 the value of DB3 at message type C will be 0 = not available.

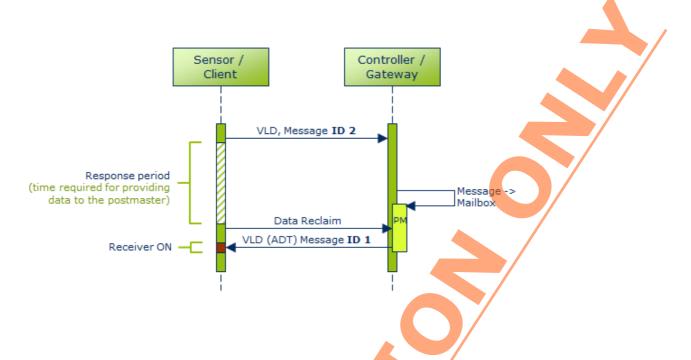
For the types 0x01, 0x02, 0x07, 0x08 the value of DB0.3 ... DB0.1 at message type B and C will be 7 = not available.

For the types 0x01, 0x02, 0x03, 0x04 the value of DB0.0 at message type C has to be 0 = not used.

Communication flow, triggered by a keystroke (first keystroke within inactive state, display state is off):



Communication flow, triggered by an event like temperature- and or humidity change or heartbeat:

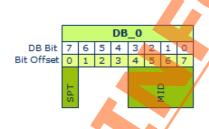


RORG	D2	VLD Telegram
FUNC	11	Bidirectional Room Operating Panel
TYPE	01	Type 0x01

Message type A / ID 0 (First switch press after sleep-mode, request new data)

Direction: Sensor -> Gateway

Bit 0.7 indicates which setpoint type is actual used at the device. The difference is made at the visualization of the setpoint (real temperature setpoint (24.5°C) or setpoint shift (+ 3.0°C)) and this information is needed for interpreting the value of DB2 at Message Type C (ID2).



Offset	Size	Data	ShortCut	Description	Valid	d Range	Scale	Unit
0	1	Setpoint		Setpoint type actual used by the device	Enum:			
		type		(temperature correction / temperature setpoint)		Temperatur correction	re	
					1:	Temperatur	e setpoir	nt
1	3	Not Used (=	0)					
4	4	Message ID	MID	Message Type A, ID-0	Enum:			
					0:	ID-0		
					1:	ID-1		
					2:	ID-2		

3...15: Reserved

Message type B / ID 1 (Override device parameter, reply to data request)

Direction: Gateway -> Sensor

Bit 3.7 may be used for setting new setpoint type at the device. If no change is needed mirroring Bit 0.7 of the last received Message Type A is required.

Byte 2 may be used for overwriting the actual setpoint shift at the device (i.e. for resetting the setpoint shift at the evening to default value). If no change is needed mirroring Byte 2 of the last received Message-Type C is required.

Byte 1 may be used for setting new basesetpoint at the device. If no change is needed mirroring Byte 1 of the last received Message-Type C is required.

Bit 0.7 ... 0.4 may be used for setting new valid setpoint shift at the device. If no change is needed mirroring Bit0.7 ... 0.4 of the last received Message-Type C is required.

				DB	_3							DB	_2							DB	_1							DB	_0			
DB Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	SPT	DHS	DCS	MSS		9	OI E					0	0 0							200	200	7				c c	¥00			OFS		500

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Set Setpoint type	SPT	Set setpoint type to be used by the device		erature correctio erature setpoint	n
1	1	Display heating symbol	DHS	Set/Clear heating symbol at the display		ng symbol off ng symbol on	-
2	1	Display cooling symbol	DCS	Set/Clear cooling symbol at the display	-	ng symbol off ng symbol on	-
3	1	Display "window open" symbol	SSW	Set/Clear "window open" symbol at the display	off	dow open" symbo	
4	4	Message ID	MID	Message Type B, ID-1	Enum: 0: ID- 1: ID- 2: ID- 315: Res	2	
8	8	Temperature correction	OSO	Override Setpoint offset (linear, min. max. +) (valid temperature correction)		according to COA	K
16	8	Basesetpoint	BSP	Set basesetpoint for visualization of the temperature setpoint	1530:	Reserved 1530 Reserved) °C
24	4	Valid temperature correction	COA	Set valid temperature correction	Enum: 0: Re 1:	eserved -11	K

			1		
					2: K
					-22
					3: K
					4: K
					-44
					5: K
					6: K
					7: K
					8: K
					9: K
					10: K
					1115: Reserved
28	3	Fan Speed	OFS	Override actual Fan Speed	Enum:
					0: Auto
					1: Speed 0
					2: Speed 1
					3: Speed 2
					4: Speed 3
					56: Reserved
					7: Not available
31	1	Occupancy State	00S	Override actual Occupancy State	Enum:
					0: State Unoccupied
					1: State Occupied

Message type C / ID 2 (Transmit actual data)

Direction: Sensor -> Gateway

Offset Size

Data

Bit 5.7 indicates which setpoint type is actual used at the device. The difference is made at the visualization of the setpoint (real temperature setpoint (24.5 °C) or setpoint shift (+ 3.0 °C)) and this information is needed for interpreting the value of DB2.

Byte 4 transmits the actual measured temperature.

Byte 2 transmits the actual setpoint shift. How to interpret this value is a combination of Bit 5.7, Byte 1 and Bit 0.7 ... 0.4.

If the actual setpoint type is setpoint shift, then the value of Byte 2 only represents the scaled valid setpoint shift at Bit 0.7 ... 0.4.

If the setpoint type is temperature setpoint, then the temperature setpoint is calculated as sum of the internal basesetpoint at Byte 1 and the scaled valid setpoint shift at Bit 0.7 ... 0.4, transmitted at Byte 2.

Byte 1 transmits the actual, at the device stored, basesetpoint.

Bit 0.7 ... 0.4 transmits the actual valid, at the device stored, setpoint shift.

ShortCut

		DE	_5					DI	3_4						DE	3_3						DB	3_2			П			D	В_	1						DB_	_0		
DB Bit	7 6 3	5 4	3 2	1	0	7	6 5	5 4	3	2	1 (0 7	7 6	5	4	3	2	1	0	7 E	5 5	4	3	2	1	0	7 (6	5 4	1 3	3 2	1	0	7	6	5	4	3	2 1	0
Bit Offset	0 1 2	2 3	4 5	6	7	8	9 1	0 11	12	13	14 1	5 1	6 17	7 18	3 19	20	21	22 2	23	24 2	5 26	27	28	29	30	31	32 3	33	34 3	5 3	6 37	7 38	3 39	40	41 4	42	43	44	45 4	6 47
	E E			MID					TEMP							HOMI							dS d							IBS					BSP	i i			ES.	SO
4																																								

Description

Valid Range

Unit

Scale

EEP 2.6.7 Specification © EnOcean Alliance

0	1	Setpoint type	SPT	Satnaint type actual used by the	Enum
U	1	Serpoint type	SF I	Setpoint type actual used by the device	Enum: 0: Temperature correction
				(temperature correction /	1: Temperature setpoint
				temperature setpoint)	
1	2	Telegram Type	π	Telegram Trigger	Enum:
					0: Heartbeat
					1: Change of temperature- or
					humidity value 2: User caused parameter
					change
3	1	Not Used (= 0)	1		
4	4	Message ID	MID	Message Type C, ID-2	Enum:
					0: ID-0
					1: ID-1
					2: ID-2 315: Reserved
8	0	Tomporaturo	TEMP	Tomporature	
16	8	Temperature Humidity	HUMI	Temperature Humidity	0255 0+40 °C 0250 0+100 %rH
24	8	Setpoint offset	SP	Setpoint shift, linear	0255 according to BSB K
2.7		occpoint onset	31	(refers to valid setpoint shift at	decording to B3B
				DB0.7 DB0.4)	
32	8	Basesetpoint	IBS	Internal basesetpoint, required for	
				setpoint type "temperature setpoint"	014: Reserved
				Seeponie	1530: °C
					1530
40	4	Valid tomporature	BSB	Valid temperature correction	31255: Reserved
40	4	Valid temperature correction	DSD	Valid temperature correction	Enum: 0: Reserved
					1: K
					-11
					2: K
					-22
					3: K
					-33
					4: K
					-44 5: K
					-55
					6: K
					-66
					7: K
					-77
					8: K
			X		-88
					9: K -99
					10: K
					-1010
					1115: Reserved
44	3	Fan Speed	FS	Fan Speed	Enum:
					0: Auto
					1: Speed 0
					2: Speed 1
	4				3: Speed 2
					4: Speed 3
					56: Reserved
47	1		00	0	7: Not available
47	T	Occupancy State	os	Occupancy State	Enum:
					0: State Unoccupied 1: State Occupied
					1. State Occupied

RORG	D2	VLD Telegram
FUNC	11	Bidirectional Room Operating Panel
TYPE	02	Type 0x02 (description: see table)

See profile: D2-11-01

RORG	D2	VLD Telegram		
FUNC	11	Bidirectional Room Operating Panel		
TYPE	03	Type 0x03 (description: see table)		

See profile: D2-11-01

RORG	D2	VLD Telegram
FUNC	11	Bidirectional Room Operating Panel
TYPE	04	Type 0x04 (description: see table)

See profile: D2-11-01

RORG	D2	VLD Telegram
FUNC	11	Bidirectional Room Operating Panel
TYPE	05	Type 0x05 (description: see table)

See profile: D2-11-01

RORG	D2	VLD Telegram
FUNC	11	Bidirectional Room Operating Panel
TYPE	06	Type 0x06 (description: see table)

See profile: D2-11-01

RORG	D2 /	VLD Telegram	
FUNC	11	Bidirectional Room Operating Panel	
TYPE	07	Type 0x07 (description: see table)	

See profile: D2-11-01

RORG	D2	VLD Telegram	
FUNC	1/1	Bidirectional Room Operating Panel	
TYPE	08	Type 0x08 (description: see table)	

See profile: D2-11-01

D2-20: Fan Control

The EEP family D2-20-xx provides different telegram types for fan control and fan supervision messages using various parameters and variables.

Devices using this EEP family may include a master-slave function (for further description see subheading 'Master-slave function').

EEP Properties:

DATA EXCHANGE Direction: bidirectional

Addressing: unicast (ADT) + broadcast Communication trigger: event-triggered

Communication interval: N/A Trigger event: query / polling

Tx delay: N/A Rx timeout : N/A

TEACH-IN

Teach-in method: Universal teach-in (UTE)

SECURITY

Encryption supported: no Security level: none

EEP Family Table:

LLI Tulling Tubio.			
Supported function	Type 00	Type 01	Type 02
Fan Speed	Χ	Χ	Χ
Fan Speed Status	Χ	Χ	Χ
Humidity	Χ	-	-
Humidity Control	Χ	-	-
Humidity Control Status	Χ	-	Χ
Humidity Threshold	Χ	-	-
Message Type	Χ	Χ	X
Operating Mode	Χ	-	-
Operating Mode Status	Χ	Χ	-
Room Size	Χ	Χ	X
Room Size Reference	Χ	Χ	X
Room Size Reference Status	Χ	X	X
Room Size Status	Χ	Х	X
Service Information	Χ	-	
Temperature Level	Χ	-	
•			

Each TYPE has to support every parameter that is marked in its column!

Master-slave function:

A device using this EEP may be able to work as a master or a slave fan. Master fans control slave fans. Slave fans are controlled by master fans. These roles are defined during the teach-in process. A slave fan will always be taught-in to a master. A master fan will accept teach in requests from slave fans. A fan that is taught-in to another device will from now on work as a slave. A fan that accepted the teach-in of another device will go on working as a master. Combining master fans is not possible. Not every device is able to work as a master and a slave. Certain fans might only be able to be used as slaves.

RORG	D2	VLD Telegram
FUNC <	20	Fan Control
TYPE	00	Type 0x00

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

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^{*} Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly

and match values beside those discrete levels to the next lower fan speed level.

Offset			ShortCut	vels to the next lower fan speed level. Description	Valid Range Scale Unit
0	4	Operating Mode	ОМ	Sets the operating mode	Enum:
					0: Disabled
					1: Standard
					compliant
					Reserved
					214:
					15: No change
4	1	Not Used (= 0)			
5	2	Temperature Level	TL	Status of the temperature supervision	Enum:
					0: Too low
					1: Normal
					2: Too high
_		_			3: No change
7	1	Message Type	MT	Defines the message type	Enum:
_	_				0: Fan control
8	2	Humidity Control	HC	Activates the humidity control	Enum:
					0: Disabled
					1: Enabled
					2: Default
1.0	2	Doom Cine	DCD	Defines if the provided was give has to be	3: No change
10	2	Room Size Reference	RSR	Defines if the provided room size has to be considered	Enum:
		Reference		considered	0: Used 1: Not used
					2: Default
					3: No change
12	4	Room Size	RS	Defines the room size	, and the second
12	7	Room Size	N.S	Defines the room size	Enum: 0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
1.0	0	11	UT	Color than he wild the color th	15: No change
16	8	Humidity Threshold	HT	Sets the humidity threshold	Enum:
		Threshold			0100: 0100%
					101252: Reserved 253: Auto
					254: Auto 254: Default
		4/			255: No change
24	8	Fan Speed *	FS	Sets the fan speed	Enum:
<u>_</u>		di Speed	. 5	Jets the full speed	0100: 0100%
					101252: Reserved
					253: Auto
					254: Default
					255: No change

Telegram Definition : 'Fan Status Message'

Oms Status Operating Mode Status Oms Status It: Standard compliant Reserved 214: 15: Not supported Enum: O: Nothing to report I: Air filter error 2: Hardware error 36: Reserved 7: Not supported Oms Status Oms Status Oms Status Enum: Oms Oms Nothing to report I: Air filter error I: Air filter error I: Fan status Enum: Oms	Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
Status	0				•	
1: Standard	J.			00	. To video and receive operating mode	
Compliant Reserved						o. Disabled
Compliant Reserved						1: Standard
Reserved 2Hs						
15: Not supported						
Service Information SI Si Service information Si Si Service information Si Si Si Si Si Si Si S						
Service Information SI Service information						15: Not supported
Message Type						
1	4	3	Service Information	SI	Service information	Enum:
1						0: Nothing to report
A						
Nessage Type						
7						
Status	7	1	Message Type	МТ	Defines the message type	
Status	,	-	inessage type	111	Defines the message type	
Status	0		II with Control	1166	Chalan if the Land III and all in a state	
1: Enabled 2: Reserved 3: Not supported Enum:	δ	2		ITCS	States if the numidity control is active	
10 2 Room Size RSR States if the provided room size has to be considered			Status			/
10 2 Room Size RSR RSR States if the provided room size has to be considered						
Room Size Reference RSR States if the provided room size has to be considered						-
Reference Considered						3: Not supported
1: Not used	10	2		RSR	States if the provided room size has to be	Enum:
2: Reserved 3: Not supported			Reference		considered	0: Used
Room Size Status						1: Not used
Room Size Status RSS Room size status						2: Reserved
Room Size Status RSS Room size status						3: Not supported
0: < 25 m ² 1: 2550 m ² 2: 5075 m ² 3: 75100 m ² 4: 100125 m ² 5: 125150 m ² 6: 150175 m ² 7: 175200 m ² 8: 200225 m ² 9: 225250 m ² 10: 250275 m ² 11: 275300 m ² 12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 14: > 350 m ² 15: Not supported 16	12	4	Room Size Status	RSS	Room size status	
1: 2550 m² 2: 5075 m² 3: 75100 m² 4: 100125 m² 5: 125150 m² 6: 150175 m² 7: 175200 m² 8: 200225 m² 9: 225250 m² 10: 250275 m² 11: 275300 m² 12: 300325 m² 13: 325350 m² 14: > 350 m² 15: Not supported 16						
2: 5075 m²						
3: 75100 m²						
Humidity Hum Humidity measurement Hum:						
S: 125150 m²						
6: 150175 m² 7: 175200 m² 8: 200225 m² 9: 225250 m² 10: 250275 m² 11: 275300 m² 12: 300325 m² 14: > 350 m² 14: > 350 m² 15: Not supported 15: Not supported 16						
T: 175200 m²						
8: 200225 m² 9: 225250 m² 10: 250275 m² 11: 275300 m² 12: 300325 m² 13: 325350 m² 14: > 350 m² 15: Not supported 16						
9: 225250 m²						,
10: 250275 m ² 11: 275300 m ² 12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 15: Not supported						
11: 275300 m ² 12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 15: Not supported						
12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 15: Not supported						,
13: 325350 m ² 14: > 350 m ² 15: Not supported						
14: > 350 m ² 15: Not supported						
15: Not supported 16 8 Humidity Humidity measurement Enum:						
Humidity						
0100: 0100% Reserved 101254: 255: Not supported						
Reserved 101254: 255: Not supported	16	8	Humidity	HUM	Humidity measurement	
101254: 255: Not supported						0100: 0100%
101254: 255: Not supported						
24 8 Fan Speed Status FSS Fan speed Enum: 0100: 0100% Reserved 101254: 255: Not						
Supported Supp						
24 8 Fan Speed Status FSS Fan speed Enum: 0100: 0100% Reserved 101254: 255: Not						
0100: 0100% Reserved 101254: 255: Not	24	Q	Fan Speed Status	ECC	Fan spood	
Reserved 101254: 255: Not	24	δ	rail Speed Status	F35	ran speed	
101254: 255: Not						0100: 0100%
101254: 255: Not						Docomicad
255: Not						
Зарропси						
						Supported

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	01	Type 0x01

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

				vels to the next lower fan speed level.		
Offset	Size	Data	ShortCut	Description	Valid Rang	ge Scale Unit
0	7	Not Used (= 0)				
7	1	Message Type	MT	Defines the message type	Enum:	
					0: / Fan d	control
8	2	Not Used (= 0)				
10	2	Room Size	RSR	Defines if the provided room size has to be	Enum:	
		Reference		considered	0: Used	
					1: Not	used
					2: Defa	ult
					3: No c	hange
12	4	Room Size	RS	Defines the room size	Enum:	
					0: < 25	m²
					1: 25	50 m²
					2: 50	75 m²
					3: 75	100 m²
						125 m²
						150 m²
						175 m²
						200 m²
						225 m²
						250 m²
					10: 250.	
					11: 275.	
					12: 300.	
					13: 325.	
					14: > 35	
16	0	National (O)			15: No c	nange
24	8	Not Used (= 0) Fan Speed *	FS	Sets the fan speed	Enum:	
24	O	l all Speed		Sets the fair speed	0100:	0100%
					0100.	0100%
						Reserved
					101252:	
					253:	Auto
					254:	Default
					255:	No
					233.	change

Telegram Definition: 'Fan Status Message'

Offs	Size	Data	ShortCut	Description	Valid I	Range	Scale	Unit
0		Operating Mode Status	OMS	Provides the recent operating mode	Enum: 0:	Disable	d	
					0.	Disable	u	

					r
					1: Standard
					compliant
					Reserved
					214:
					15: Not supported
4	3	Not Used (= 0)	1	I	
7	1	Message Type	MT	Defines the message type	Enum:
					1: Fan status
8	2	Not Used (= 0)	1	T	
10	2	Room Size	RSR	States if the provided room size has to be	Enum:
		Reference		considered	0: Used
					1; Not used
					2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum:
				A STATE OF S	0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3; 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
					15: Not supported
16	8	Not Used (= 0)			
24	8	Fan Speed Status	FSS	Fan speed	Enum:
27		Tan Speca Status	1 33	Turi Specu	0100: 0100%
					0100. 0100%
					Reserved
					101254:
					255: Not
					supported
					5 app 5. to a

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	02	Type 0x02

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	7	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum: 0: Fan control
8	2	Not Used (= 0)			
10		Room Size Reference		Defines if the provided room size has to be considered	Enum: 0: Used 1: Not used

						<u> </u>
						fault
					3: No	change
12	4	Room Size	RS	Defines the room size	Enum:	
					0: <	25 m ²
					1: 25	50 m²
					2: 50	75 m²
					3: 75	100 m ²
					4: 10	0125 m ²
					5: 12	5150 m ²
					6: 15	0175 m ²
					7: 17	5200 m ²
					8: 20	0225 m ²
					9: 22	5250 m ²
					10: 25	0275 m ²
					11: 27	5300 m ²
					12: 30	0325 m ²
					13:/32	5350 m ²
					14: >	350 m²
					15: No	change
16	8	Not Used (= 0)				
24	8	Fan Speed *	FS	Sets the fan speed	Enum:	
					0100	: 0100%
						Reserved
					101252) • • •
					253:	Auto
					254:	Default
					255:	No
						change

Telegram Definition: 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	7	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum: 1: Fan status
8		Humidity Control Status	HCS	States if the humidity control is active	Enum: 0: Disabled 1: Enabled 2: Reserved 3: Not supported
10		Room Size Reference	RSR	States if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Reserved 3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum: 0: < 25 m² 1: 2550 m² 2: 5075 m² 3: 75100 m² 4: 100125 m² 5: 125150 m² 6: 150175 m² 7: 175200 m² 8: 200225 m² 9: 225250 m² 10: 250275 m²

					11: 275300 m ² 12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 15: Not supported
16	8	Not Used (= 0)			
24	8	Fan Speed Status	FSS	Fan speed	Enum: 0100: 0100% Reserved 101254: 255: Not supported

D2-30: Floor Heating Controls and Automated Meter Reading

Floor heating controls and automated meter reading gateway may appear combined in one device, but the metering functionality can also be absent.

The floor heating control unit controls a number of valves for separate heating circuits (e.g. for separate heating of single rooms). It measures the common hot water supply temperature as well as the return water temperatures of each single circuit.

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered

Communication interval: minimum 1-1000 s, maximum 1000 s

Trigger event: heartbeat 1000 s, value change in "Position", "Return Temperature", "Status/Error", "Supply

Temperature", "Meter Reading" while respecting the minimum reporting interval

Tx delay: 500 ms (maximum response time, first telegram)

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: Universal teach-in (outbound)

Encryption required : no Security level format : 0

EEP Family Table

Туре	0x00	0x01	0x02	0x03	0x04	0x05	0x06
Number of heating channels/valves	4	8	8	8	8	6	12
Channel return temperature	X	Χ	Χ	Χ	Χ	Ī	ı
Global return temperature	X	Χ	Χ	Χ	Χ	-	-
Global supply temperature	X	Χ	Χ	Χ	Χ	-	-
Number of supported MBUS meters	0	0	8	10	10	0	0
Number of supported S0 meters	0	0	0	0	1	0	0
Number of supported D0 meters	0	0	0	0	0	0	0

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

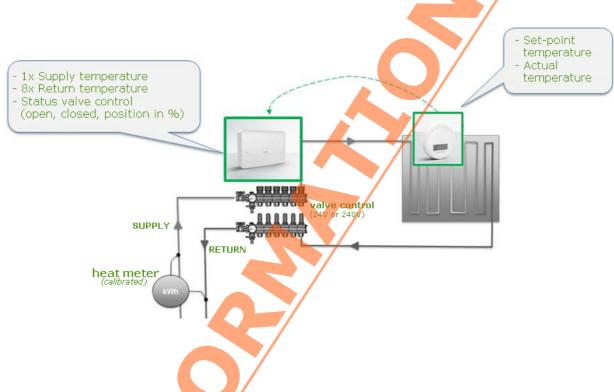
D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

Application example for floor heating controls



References:

M-Bus documentation: www.m-bus.com

SML specification: www.vde.com/de/fnn/arbeitsgebiete/messwesen/Sym2/Seiten/default.aspx

DLMS User Association: www.dlms.com

RORG	D2		VLD Telegram
FUNC	30	Floor He	ating Controls and Automated Meter Reading
TYPE	00		Type 0x00

Submitter: MSR-Solutions

CMD 0x1 - Set heating controls output

This message is sent to a floor heating actuator. It controls the valve position of one channel or of all channels of the floor heating controls.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit
-------------	------	----------	-------------	-------------	-------	------

(T valve open + T valve closed) change 1: 1 s 2: 2 s 3: 5 s	default / no ge			
1: 1 s 2: 2 s 3: 5 s				
3: 5 s				
4: 10 s				
5: 20 s				
6: 50 s				
7: 100 \$				
8: 200 s				
9: 500 s				
10: 1000				
1115:	rved			
4 Command ID CMD Command identifier Enum: 0x01: ID 01				
8 2 Not Used (= 0)				
10 1 Valve type VTYP Type of connected valve Enum:				
0: Valve no (N.C.)	ormally closed			
(N.O.)	ormally open			
11 5 Heating channel HCH The heating channel that should Enum:				
be set 015: A val				
Resel 1630:	rved			
31: All va	alid channels			
16 1 Run init sequence RIN Measure and store the valve zero Enum:				
point 0: No action				
1: Run init				
7 Valve position set point POS Valve set point 0100% (0=closed, 100=open)	0100 %			

CMD 0x2 - Heating controls status query

This message is sent to a floor heating actuator. It requests the status of one channel or the status of the global control unit of an actuator.

Sender: controller; send type; broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit				
0	4	Not Used (= 0)									
4	4	Command ID	CMD	Command identifier	Enum:						
					0x02: ID 02						
8	3	Not Used (= 0)								
11		Heating channel		The heating channel that should be reported	Enum: 015: A valid channe Reserved 1628:	el number					

		29:	All valid channels
		30:	All valid channels and global device status
		31:	Global device status only

CMD 0x3 - Heating controls status response / CH = 0...15

This message is sent by a floor heating controls if one of the following events occurs:

- Message 'status query' has been received (CMD 0x2).
- Status of one channel or temperature has changed.

Sender: actuator; send type: broadcast; maximum send delay 1 s.

If the response is for single channel data (CH = 0...15):

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x03; ID 03		
8	3	Status / Error	STATUS	Status / Error indication of given channel	5: Valve error	ce running t available re sensor en	
11	5	Heating channel	НСН	The heating channel that is reported	Enum: 015: A valid number Reserve 1631:		
16	1	Not Used (= 0)		/			_
17	7	Valve position	POS	Actual valve position 0100% (0=closed, 100=open)	0100	0100	%
24	8	Return temperature	TEMPRET	The current return temperature of the channel	0180	090	°C

CMD 0x3 - Heating controls status response / CH = 31

If the response is for global floor heating controls unit data (CH = 31):

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	4	Not Used (= 0)						
4	4	Command ID	CMD	Command identifier	Enum:			
					0x03: ID 03			
8	3	Status / Error	STATUS	Global unit status	Enum:			
						0: No fault		
					1:	General er	ror	

					2: Supply temperature error
					3: Return temperature error
					4: Error on both sensors
					Reserved 57:
11	5	Heating channel	НСН	The heating channel that is reported (=global unit)	Enum: 31: Unit status only
16		Supply temperature	TSUP	The current supply temperature of the unit	0180 090 °C
24	_	Return temperature	TRET	The current common return temperature	090 °C

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting	Enum:		
		measurement		interval	0: No auto re	porting	
					1: Min. 1 s int	terval	
					2: Min. 3 s int	terval	
					3: Min. 10 s ir	nterval	
					4: Min. 30 s ir	nterval	
					5: Min. 100 s	interval	
					6: Min. 300 s	interval	
					7: Min. 1000	s interval	
					815: Reserved		
4	4	Command ID	CMD	Command identifier	Enum:		
					0x06: ID 06		
8	1	Not Used (= 0)					
9	2	Meter bus type	BUS	The meter bus that should be	Enum:		
				configured	0: Reserved		
					1: MBUS		
					2: S0		
					3: D0		
11	5	Meter channel index	MCH	The meter bus that should be configured	030	030	1
16	2	Not Used (= 0)				•	
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:		
				quantity (imported value)	0: No reading (ι	unconfigured)	
			-/		1: Current value value kWh	e W, accumula	ted
					2: Current value value Wh	e W, accumula	ted
					3: Accumulated	value kWh or	nly
	4				4: Current value value m3	e m3/h, accun	nulated
					5: Current value value dm3	dm3/h, accu	mulated
					6: Accumulated	value m3 onl	У
					7: Digital counte	er	
21	3, /	Meter 2 units	UNIT2	Physical units of second	Enum:		
				measured quantity (exported value)	0: No reading (ι	unconfigured)	

					1:	Current value W, accumulated value kWh
					2:	Current value W, accumulated value Wh
					3:	Accumulated value kWh only
					4:	Current value m3/h, accumulated value m3
					5:	Current value dm3/h, accumulated value dm3
					6:	Accumulated value m3 only
					7:	Digital counter
24	8	Primary Address	ADDR	The primary MBUS address of the meter	125	50 1250 1
32	40	Not Used (= 0)				

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:		
		measurement			0: No auto re	porting	
					1: Min. 1 s int	erval	_
					2: Min. 3 s int	erval	_
					3: Min. 10 s ii	nterval	_
					4: Min. 30 s ii	nterval	_
					5: Min. 100 s	interval	_
					6: Min. 300 s	interval	_
					7: Min. 1000	s interval	_
					815: Reserved		_
4	4	Command ID	CMD	Command identifier	Enum:		
					0x06: ID 06		
8	1	Not Used (= 0)			1 100122 00		
9	2	Meter bus type	BUS	The meter bus that should be	Enum:		
_				configured	0: Reserved		
					1: MBUS		
					2: S0		
					3: D0		
11	5	Meter channel	MCH	The meter number of given bus	030	030	1
		index		that should be configured	050	050	_
16	2	Not Used (= 0)			•		1
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:		
				quantity (imported value)	0: No reading (ι	ınconfigure	t)
				(,,	1: Current value	W accumu	latod
					value kWh	: vv, accumu	iateu
					2: Current value	W. accumu	lated
					value Wh	, acca	
					3: Accumulated	value kWh	only
					4: Current value	m3/h.	
					accumulated		
					5: Current value	dm3/h,	
					accumulated	value dm3	
					6: Accumulated	value m3 o	nly
					7: Digital counte	er	
21	3 /	Meter 2 units	UNIT2	Physical units of second	Enum:		
				measured quantity (exported value)	0: No reading (u	ınconfigured	d)

					1: Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
					3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
24	2	Factor of number of pulses	FACP	The factor for the number of pulses	Enum:
		puises	per value in UNIT1	0: 1 1: 0.1	
					2: 0.01
26	14	Number of pulses	NOP	The number of pulses per value	Enum:
		·		in UNIT1* FACP	0: Do not change the current setting of NOP
					Number of pulses per unit 116383: (EEP 2.6.5: 1 16383 ±
					 65535)
40	32	Preset value	RST	Preset the accumulated value to	Enum:
				this value	New preset value 0,4294967294:
					0xFFFFFFFF: Do not change the
					current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report measurement	RM	Minimum auto reporting interval	Enum: 0: No auto report 1: Min. 1 s inter 2: Min. 3 s inter 3: Min. 10 s inter 4: Min. 30 s inter 5: Min. 100 s inter 6: Min. 300 s inter 7: Min. 1000 s inter 815: Reserved	val val erval erval erval	
4	4	Command ID	CMD	Command identifier	Enum: 0x06: ID 06		
8	1	Not Used (= 0)					
9	2	Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0		
11	5	Meter channel index	МСН	The meter number of given bus that should be configured	030	030	1
16	2	Not Used (= 0)					
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity (imported value)	Enum: 0: No reading (und 1: Current value W value kWh		

						rrent value W, accumulated ue Wh
					3: Ac	cumulated value kWh only
						rrent value m3/h, cumulated value m3
						rrent value dm3/h, cumulated value dm3
					6: Ac	cumulated value m3 only
					7: Dig	gital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum:	
				quantity (exported value)	0: No	reading (unconfigured)
						rrent value W, accumulated lue kWh
						rrent value W, accumulated ue Wh
					3: Ac	cumulated value kWh only
					acc	rrent value m3/h, cumulated value m3
						rrent value dm3/h,
						cumulated value dm3
						cumulated value m3 only
					7: Dig	gital counter
24	8	D0 Protocol	PROT	The D0 protocol that should be	Enum:	
				used for that meter	0:	Auto detect
						SML (Smart Message Language)
						DLMS (Device Language Message Specification)
					3255:	Reserved
32	40	Not Used (= 0)				

CMD 0x7 - Meter Status Query

This message is sent to a metering device gateway to query the status of a meter. Sender: controller; send type: broadcast or addressed; expected response: CMD 0x8.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum:
					0x07: ID 07
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum:
					0: Reserved
					1: MBUS
					2: S0
					3: D0
11	5	Meter channel	MCH	The meter channel of given bus that status is	Enum:
		index		queried	Meter channel
					030:
					31: All valid
					channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message 'meter status query' has been received (CMD 0x7)
- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Not Used (= 0)			<u> </u>		
1		Meter status / error		Meter channel status	3: Bus un 4: Bus sho 5: Commo	ll error configured connected	
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08	-/	
8	1	Not Used (= 0))				
9		Meter bus type	BUS	The used bus of the meter status response	Enum: 0: Reserv 1: MBUS 2: S0 3: D0	ed	
11		Meter channel index	MCH	The meter number of given bus that status is reported	030	030	1
16	3	Not Used (= 0))		7/	•	-
19	2	Value selection	VSEL	The selection of the reported value	1: Meter 2 2: Meter 2	1 Current value 1 Accumulated val 2 Current value 2 Accumulated val	
21	3	Value unit	VUNIT	The unit of the reported value		cal counter)	
24	32	Meter reading value	VAL	The reported value	0429496729	95 0429496729!	According to VUNIT

RORG	D2		VLD Telegram
FUNC	30	Floo	r Heating Controls and Automated Meter Reading
TYPE	01		Type 0x01 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	02	Type 0x02 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	03	Type 0x03 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	04	Type 0x04 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	05	Type 0x05 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	06	Type 0x06 (description: see table)

See profile: D2-30-00

D2-31: Automated Meter Reading Gateway

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered

Communication interval: minimum 1-1000 s (configuration item), maximum 1000 s

Trigger event: heartbeat 1000 s, value change in "Status/Error", "Meter Reading" while respecting the minimum

reporting interval

Tx delay: 500 ms (maximum response time, first telegram)

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: Universal teach-in (outbound)

Encryption required : no Security level format : 0

Telegram Definition

The telegram definition is inherited from profile D2-30-xx and thus identical to the definition there.

EEP Family Table

Supported function	Type 0x00	Type 0x01
Number of supported MBUS meters	10	16
Number of supported S0 meters	2	0
Number of supported D0 meters	2	0

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

References:

M-Bus documentation: www.m-bus.com

SML specification: www.vde.com/de/fnn/arbeitsgebiete/messwesen/Sym2/Seiten/default.aspx

DLMS User Association: www.dlms.com

RORG	D2	VLD Telegram
FUNC	31	Automated Meter Reading Gateway
TYPE	00	Type 0x00

Submitter: MSR-Solutions

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data	ShortCut	Description	Valid	d Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:			
		measurement			0:	No auto rep	orting	
					1:	Min. 1 s int	erval	-
					2:	Min. 3 s int	erval	-
					3:	Min. 10 s ir	nterval	-
					4:	Min. 30 s ir	nterval	-
					5:	Min. 100 s	interval	
					6:	Min. 300 s	interval	
					7:	Min. 1000 s	interval	
					815	: Reserved		
4	4	Command ID	CMD	Command identifier	Enum:			•
					0x06:	ID 06		
8	1	Not Used (= 0)			0			

index that should be configured 16 2 Not Used (= 0) 18 3 Meter 1 units UNIT1 Physical units of first measured quantity Physical units of first measured quantity O: No reading (unconfigured)	1
1: MBUS 2: S0 3: D0 11	
2: S0 3: D0 11	1
3: D0 11 5 Meter channel MCH The meter number of given bus index 030 030 16 2 Not Used (= 0) 18 3 Meter 1 units UNIT1 Physical units of first measured quantity	1
11 5 Meter channel index The meter number of given bus that should be configured 16 2 Not Used (= 0) 18 3 Meter 1 units UNIT1 Physical units of first measured quantity Physical units of first measured quantity O: No reading (unconfigured)	1
16 2 Not Used (= 0) 18 3 Meter 1 units UNIT1 Physical units of first measured quantity Enum: O: No reading (unconfigured)	1//
18 3 Meter 1 units UNIT1 Physical units of first measured quantity Enum: O: No reading (unconfigured)	
quantity 0: No reading (unconfigured)	
or ito reading (uncomigated)	
(imported value)	
1: Current value W, accumula value kWh	ted
2: Current value W, accumula value Wh	ted
3: Accumulated value kWh or	nly
4: Current value m3/h,	
accumulated value m3	
5: Current value dm3/h,	
accumulated value dm3	
6: Accumulated value m3 only	У
7: Digital counter	
21 3 Meter 2 units UNIT2 Physical units of second measured Enum:	
quantity (exported value) 0: No reading (unconfigured)	
1: Current value W, accumula value kWh	ted
2: Current value W, accumula value Wh	ted
3: Accumulated value kWh or	nly
4: Current value m3/h, accumulated value m3	
5: Current value dm3/h, accumulated value dm3	
6: Accumulated value m3 only	у
7: Digital counter	
24 8 Primary Address ADDR The primary MBUS address of the 1250 1250	1
32 40 Not Used (= 0)	

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

Offs	set Size	Data	ShortCut	Description	Vali	d Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:			
		measurement			0:	No auto repo	rting	
					1:	Min. 1 s inter	val	
					2:	Min. 3 s inter	val	
					3:	Min. 10 s inte	erval	
					4:	Min. 30 s inte	erval	
					5:	Min. 100 s in	terval	
					6:	Min. 300 s in	terval	_
					7:	Min. 1000 s i	nterval	_
					815	: Reserved		
4	4	Command ID	CMD	Command identifier	Enum:			
					0x06:	ID 06		
8	1	Not Used (= 0)			•			

9	2	Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11	5	Meter channel index	MCH	The meter number of given bus that should be configured	030 030 1
16	2	Not Used (= 0)			
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity (imported value)	Enum: 0: No reading (unconfigured) 1: Current value W, accumulated value kWh 2: Current value W, accumulated value Wh 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h, accumulated value dm3 6: Accumulated value m3 only
					7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured quantity (exported value)	Enum: 0: No reading (unconfigured) 1: Current value W, accumulated value kWh 2: Current value W, accumulated value Wh 3: Accumulated value kWh only 4: Current value m3/h, accumulated value m3 5: Current value dm3/h, accumulated value dm3 6: Accumulated value m3 only 7: Digital counter
24	2	Factor of number of pulses	FACP	The factor for the number of pulses per value in UNIT1	Enum: 0: 1 1: 0.1 2: 0.01 3: 0.001
26	14	Number of pulses	NOP	The number of pulses per value in UNIT1* FACP	Enum: 0: Do not change the current setting of NOP Number of pulses per unit 116383: (EEP 2.6.5: 1 16383 ± 65535)
40	32	Preset value	RST	Preset the accumulated value to this value	Enum: New preset value 04294967294: 0xFFFFFFFF: Do not change the current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

onset[size] Data [shortcut] Description Valid Range Scale Onit	Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit
--	-------------	------	----------	-------------	-------------	-------	------

0	4	Report measurement	RM	Minimum auto reporting interval	Enum: 0: No auto reporting 1: Min. 1 s interval 2: Min. 3 s interval
					3: Min. 10 s interval 4: Min. 30 s interval 5: Min. 100 s interval 6: Min. 300 s interval 7: Min. 1000 s interval 815: Reserved
4	4	Command ID	CMD	Command identifier	Enum: 0x06: ID 06
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11	5	Meter channel index	МСН	The meter number of given bus that should be configured	030 1
16	2	Not Used (= 0)	LINITE	Dhuniani u il u C C	
18	3	Meter 1 units	UNIT1	Physical units of first measured quantity (imported value)	0: No reading (unconfigured) 1: Current value W, accumulated
					value kWh 2: Current value W, accumulated value Wh 3: Accumulated value kWh only
					4: Current value m3/h,
					accumulated value m3 5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured	
				quantity (exported value)	0: No reading (unconfigured)
					Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
		4			3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
		A -/			7: Digital counter
24	8	D0 Protocol	PROT	The D0 protocol that should be	Enum:
				used for that meter	0: Auto detect
					1: SML (Smart Message Language)
					2: DLMS (Device Language Message Specification)
	-/				Reserved 3255:
32	40	Not Used (= 0)			

CMD 0x7 - Meter Status Query

This message is sent to a metering device gateway to query the status of a meter. Sender: controller; send type: broadcast or addressed; expected response: CMD 0x8.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11	_	Meter channel index		The meter channel of given bus that status is queried	Meter channel 030: 31: All valid channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message 'meter status query' has been received (CMD 0x7)
- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Siza	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0				Description	Valle	ritarige	Scale	Offic
1		Not Used (= 0) Meter status / error		Meter channel status	Enum: 0: 1: 2: 3: 4: 5: 6:	No fault General e Bus unco Bus unco Bus short Commun Unknown configura	nfigured nnected	
4	4	Command ID	CMD	Command identifier	Enum: 0x08	3: ID 08	_	
8	1	Not Used $(= 0)$			_			
9		Meter bus type	BUS.	The used bus of the meter status response	Enum: 0: 1: 2: 3:	Reserved MBUS S0 D0		
11	5	Meter channel index		The meter number of given bus that status is reported	030		030	1
16	3	Not Used $(= 0)$	1					
19	2	Value selection	VSEL	The selection of the reported value	Enum: 0: 1: 2: 3:	Meter 1 A Meter 1 A Meter 2 (Current value Accumulated valu Current value Accumulated valu	

١	21	3	Value unit	VUNIT	The unit of the reported value	Enum:
			value unic	VOIVE	The unit of the reported value	0: W
						1: Wh
						2: kWh
						3: m3/h
						4: dm3/h
						5: m3
						6: dm3
						7: 1 (digital counter)
	24	32	Meter reading value	VAL	The reported value	04294967295 04294967295 According to VUNIT

RORG	D2	VLD Telegram
FUNC	31	Automated Meter Reading Gateway
TYPE	01	Type 0x01 (description: see table)

See profile: D2-31-00

D2-32: A.C. Current Clamp

Description

A family of EEP's based on a central unit where up to three a.c. Current Clamps can be connected. Each one capable of energy harvesting sufficiently to enable readings of current values to be taken in amps and transmitted every 30 seconds.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered Communication interval: 30 seconds

Trigger event: Threshold Voltage for Power Fail transmission bit

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table:

Supported function	Type 00	Type 01	Type 02
Channel 1	X	X	Χ
Channel 2	-	X	Χ
Channel 3	-	/	Χ

Each TYPE has to support every parameter that is marked in its column!

The list of parameters could be structured following the features that always include a certain group of parameters.

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	00	Type 0x00

Submitter: Pressac Communications Ltd

Type 00

				DB	_2							DB	_1							DB	_0			
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🗲 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
	PF	DIV												CH	11									

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
					1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	4	Not Used ((= 0)	<u>-</u>		

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	01	Type 0x01

Submitter: Pressac Communications Ltd

Type 01

				DB	_3						> /	DB	_2							DB	_1							DB	_0			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 -> 31	it Offset: 0 -> 31 0 1 2 3 4 5 6								8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	PF	DIV												CH	11											CH	12					

- Notes
 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
					1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	12	Channel 2	CH2	Current value	00xFFF	04095 (409,5) A

RORG	D2	VLD Telegram

FUNC	32	A.C. Current Clamp
TYPE	02	Type 0x02

Submitter: Pressac Communications Ltd

Type 02

				DB	_5						- 1	DB_	4							DB.	_3							DB	_2							DB_	_1							DI	B_C	5			
DB_5.BIT_7 ← 0 Bit Offset: 0 → 47	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	. 0	
Bit Offset: 0 🗲 47	0	1	2	3	4	5	6	7	8	9	10 11 12 13 14 15 16 17 1								18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	2 43	3 44	4 45	5 46	5 4	7
							СН	1											CI	12											CH							V				_							

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
					1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	0409 5 (409,5) A
20	12	Channel 2	CH2	Current value	00xFFF	04095 (409,5) A
32	12	Channel 3	CH3	Current value	00xFFF	0 <mark>.4</mark> 095 (409,5) A
44	4	Not Used ((= 0)			

D2-33: Intelligent, Bi-directional Heaters and Controllers

Submitter: WATTS Electronics

Description

This profile is used for all ADEO electric heaters (replacing pilot wire control) in scope of global comfort management in the home through a central processing unit. This includes temperature setpoint control based on a series of embedded sensors on the heater. Temperature management can also be tuned by an external temperature sensor input.

Data exchange

Direction: bidirectional Addressing: addressed

Communication trigger: time-triggered (10 min +/- 3 min) and event based

Communication interval: 10 min +/- 5 min

Trigger event: defined in section 2. Typical emitter/receiver rules

Tx delay: 200 ms Rx timeout: 1 s

Teach-in

UTE Bidirectional Teach-In / Teach-Out is used.

The device is set in pairing mode via manual on-screen set-up, then the gateway send unicast pairing message to the device with known unique ID of the heater.

Security

Encryption supported: yes

Security level format: RLC, CMAC, VAES

VLD Family Table:

Supported function	Type 00
Program (command: MID = 2)	Χ
Time and date (command: MID = 3)	Χ

Pilot wire flag	X
Window open detection	X
PIR detection	X
Reference temperature	X
Derogation	X
COV Sensor	-
CO sensor	-
CO2 sensor	-
Particles 1 sensor	-
Particles 2.5 sensor	-
Particles 10 sensor	-
Radio activity sensor	-
Sound sensor	-
Hydrometry sensor	-
Air moving sensor	-
Pressure sensor	-
Temperature scale status	X
Time notation status	X
Display content status	X
Display content status	X



This shows the different commands and data fields which can be supported by different profiles of this VLD family. If a field is not supported, it's value shall always be transmitted as 0.

Rules for the communications

1) ACKNOWLEDGE mechanism

The gateway can request information from the heater via the "Request" message (MID = 0) but it can also send pure information to the heater based on gateway/user events without any request for status (MID = 0 to 3). Conversely, the heater can request information from the gateway via the "request and status" message (MID = 8) but also send pure information based on heater/user events (MID = 8 to $\frac{12}{12}$).

The below table describes the expected ACKNOWLEDGE frames for each type of initiated message:

Message type		ator eway	hea	get ster wledge
	MID	REQ	MID	REQ
Request status	0	8	8	15/
Request param	0	9	9	N.A.
Request sensor1	0	10	10	N.A.
Request sensor2	0	11	11	N.A.
Request sensor3	0	12	12	N.A.
Event DATA	0	13	8	15
Reserved	0	14	N.A.	N.A.
N.A.	0	15	N.A.	N.A.
Event DATA	1→3	N.A.	8	15

Message type		ator ater	Target gateway acknowledge		
	MID	REQ	MID	REQ	
Request external temp	8	0	0	15	
Request sensor param	8	1	1	N.A.	
Request program	8	2	2	N.A.	
Request time & date	8	3	3	N.A.	
Event DATA	8	4	0	15	
Reserved	8	5 → 14	N.A.	N.A.	
N.A.	8	15	N.A.	N.A.	
Event DATA	9 → 13	N.A.	0	15	

2) Typical emitter/receiver rules

Emitter	Message Type	Receiver	Message sent by the receiver
Gateway	Request	Heater	Answers Request
Gateway	Data	Heater	Answer Acknowledge

Emitter	Message Type	Receiver	Message sent by the receiver
Heater	Request	Gateway	Answers Request
Heater	Data	Gateway	Answer Acknowledge

Device send Heater message when:

- Heater has to respond to gateway
- Heater is entering Derogation Mode (manual entry on the device's screen)
- All 30 min +/- 10% (random value)
- Key lock user (KLU) function is activated on the device
- Any sensor is triggered:
 - Windows detection triggered
 - PIR sensor triggered
 - CO2 limit reached => 1000ppm
 - CO limit reached
 - => 9 ppm (CO Max prolonged exposure ASHRAE std)
 - =>< 1.0 ppm = Good, or "Green"
 - 1.0 to 10 ppm = Marginal, or "Yellow
 - 10 ppm and higher = Poor, or "Red"
 - Particles Limit reached:
 - P1V => 10µg/m3
 - P2V => $25\mu g/m3$ (EU regulation)
 - P10V => $40\mu g/m3$ (EU regulation)
 - Radioactivity Limit reached => 16 mSv
 - Hygrometry Limit reached => >75%
 - Temperature Variation: significant changes thresholds for slope detection with 10% random:
 - 0,5°C/3min +- 10%
 - 0,4°C/5min +- 10%
 - 0,3°C/8min +- 10%
 - 0,2°C/15min +- 10%
 - 0,1°C/30min +- 10%
 - Sound level Limit reached => 20 dB
 - Pressure level Limit reached =
 - >< 980hPa = cyclonic weather
 - 1030hPa = anticyclonic weather
 - Air moving Limit reached
 - > 0,15 m/s @ 19°C
 - > 0,16 m/s @ 20°C
 - > 0,17 m/s @ 21°C
 - > 0,18 m/s @ 22°C
 - > 0,21 m/s @ 24°C
- > 0,25 m/s @ 26°C
- Error flag triggered
- Pilot wire change

Gateway sends message when:

- It's needed regarding applications and functionalities. (e.g. gateway start-up)
- When Gateway receives Heater message from a device.
- In case of Program request, Gateway has to send all programs to heaters.

RORG	D2	VLD Telegram
FUNC	33	Intelligent, Bi-directional Heaters and Controllers
TYPE	00	Type 0x00

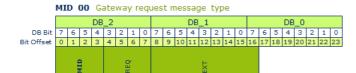
Submitter: WATTS Electronics

1) Gateway messages

There are four different messages which can be used to transmit data to heaters:

1a) Gateway request message type

Used to send external temperatures to heaters and ask for special requests.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Message Identifier	MID	Defines the type of message	Enum: 0: Gateway request	message type	
4	4	Request Frame		Request information to the heater	Enum: Reserved 07: 8: Question: status 9: Question: parame 10: Question: sensor 11: Question: sensor	and flags eters heaters CO/HYGRO/Sound particle/radioactivit air flow, hygrometr perature eater	
8	9	External Temperature		Recent external temperature: Temp(°C) = value / 10	1500	0.150.0	°C
17	7	Not Used (= 0)					

1b) Sensor parameters

This command is transmitted by the gateway controller to enable/disable a sensor. If a sensor is disabled, no measurement will be taken and the corresponding data field will be set to 0 to indicate that the sensor is disabled. For any fields that are not supported, as indicated in the VLD family table above, 0 shall be transmitted in the corresponding field of the sensor parameters message. Only the supported fields are valid for each EEP and the rest should be ignored on the heater side.



	١.			la c	I
0	4	Message Identifier	MID	Defines the type of message	Enum: 1: Sensor parameters
4	1	Window Open	wos	Indicates if the open window detection is	Enum:
•	-	Detection Status		active	0: Disabled
					1: Enabled
5	1	PIR Detection Status	PIS	Indicates if the PIR function is active	Enum:
					0: Disabled
					1: Enabled
6	1	Reference	RTS	Indicates which temperature has to be	Enum:
		Temperature Status		used	0: Dîsabled
					1: Enabled
7	1	COV Sensor	CVS	Indicate if COV sensor is active	Enum:
					0: Disabled
					1: Enabled
8	1	CO Sensor	cos	Indicate if CO sensor is active	Enum:
					0: Disabled
					1: Enabled
9	1	CO2 Sensor	C2S	Indicate if CO2 sensor is active	Enum:
					0; Disabled
					1: Enabled
10	1	Particles 1 Sensor	P1S	Indicate if particles 1 sensor is active	Enum:
					0: Disabled
					1: Enabled
11	1	Particles 2.5 Sensor	P2S	Indicate if particles 2.5 sensor is active	Enum:
					0: Disabled
					1: Enabled
12	1	Particles 10 Sensor	P10S	Indicate if particles 10 sensor is active	Enum:
					0: Disabled
					1: Enabled
13	1	Radio Activity	RAS	Indicate if radio activity sensor is active	Enum:
		Sensor			0: Disabled
					1: Enabled
14	1	Sound Sensor	SOS	Indicate if sound sensor is active	Enum:
					0: Disabled
					1: Enabled
15	1	Hygrometry Sensor	HYS	Indicate if hygrometry sensor is active	Enum:
					0: Disabled
					1: Enabled
16	1	Air Moving Sensor	AMS	Indicate if air moving sensor is active	Enum:
					0: Disabled
					1: Enabled
17	1	Pressure Sensor	PRS	Indicate if pressure sensor is active	Enum:
					0: Disabled
					1: Enabled
18	2	Temperature Scale	TSS	Defines the used temperature scale for the	Enum:
		Status		room control panel display and menus	0: No change
					1: Default
					2: °Celsius
20	2	Time No. 11	TNC	D. C	3: °Fahrenheit
20	2	Time Notation Status	TNS	Defines the used time notation	Enum:
		Stotus			0: No change
					1: Default
					2: 24 h 3: 12 h
22	3	Display Content	DCS	Defines the main display content	-
22	3	Status	DCS	Defines the main display content	Enum:
					0: No change
					1: Default
	7/				2: Time

		1				
					3:	Room temperature (internal)
					4:	Room temperature (external)
					5:	Temperature setpoint
					6:	Display off
					7:	Reserved
25	1	Derogation Status	DGS	Indicates if the derogation is allowed	Enum	:
					0:	Derogation is not
						allowed
					1:/	Derogation is
						allowed
26	6	Not Used (= 0)				

1c) Program

Use to define scheduling (timeslot + setpoint temperature) for all week.

To set a continuous loop over several weeks with the same setpoint temperature (Non timed mode), the gateway must send the following configuration: (as Comfort/Reduce)

- Send in One time mode
- Monday 00:00 to Monday 00:00 (Start = Stop)
- Set point: in Celcius

If start time = stop time, the stop time isn't taken into account and in this case the One time timeslot is a "forever" loop.

To send a full new weekly schedule, the gateway must sequentially send all timeslots with the desired setpoint temperature.

Priority: On Time information has higher priority than weekly information. In case of non-information for one time and weekly, the heater is in stop mode.

Warning: When both the CSC and TPT fields are set to 1, all scheduling programs (one time and weekly) of the heater are cleared.



Offset	Size	Data	ShortCut	Description	Val Ran		Scale	Unit
0	4	Message Identifier	MID	Defines the type of message	Enum	:		
					2:	Prog	ram	
4	1	Scheduled Order	TPT	Type of provided schedule order	Enum	:		
		Туре			0:	One	time	
					1:	Weel	kly	
5	3	End Time Day	ETD	The end day to apply the provided scheduled	Enum	:		_
				order	0:	Mond	day	
					1:	Tues	day	_
					2:	Wedi	nesday	_
				3:	Thur	sday	_	
					4:	Frida	ıy	_
					5:	Satu	rday	_
					6:	Sund	lay	_
					7:	Rese	rved	

8	6	End Time Minute	ETM	The end time (minute) to apply the provided scheduled order	059	059	Min
14	5	End Time Hour	ETH	The end time (hour) to apply the provided scheduled order	023	023	Hour
19	3	Start Time Day	STD	The start day to apply the provided scheduled order	3: Thui 4: Frida 5: Satu 6: Sun	nesday rsday ay urday	//
22	6	Start Time Minute	STM	The start time (minute) to apply the provided scheduled order	059	059	Min
28	5	Start Time Hour	STH	The start time (hour) to apply the provided scheduled order	023	023	Hour
33	9	Temperature Setpoint	TSP	The temperature setpoint to apply the provided scheduled order: Setpoint(°C) = value / 10	1500	0.150.0	°C
42	1	Clear Schedule	CSC	Allow to clear Weekly or one time	Enum: 0: Set 1: Clea		
43	5	Not Used (= 0)				•	

1d) Time and date

Use to define Time and date for heaters.

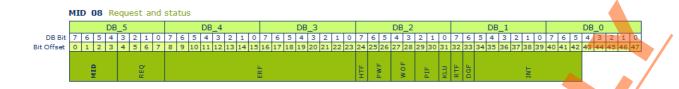


Size	Data	ShortCut	Description	Valid Range	Scale	Unit
4	Message Identifier	MID	Defines the type of message	Enum:		
				3: Time a	nd date	
5	Day	DAY	Date format: YYYY/MM/DD	131	131	Day
4	Month	MON	Date format: YYYY/MM/DD	112	112	Mon
12	Year	YR	Date format: YYYY/MM/DD	04095	04095	Year
5	Minute	MIN	Time format: hh:mm	059	059	Min
5	Hour	HR	Time format: hh:mm	023	023	Hour
3	Day Week	DAYW	Day of week	Enum:		
				0: Monda	У	
				1: Tuesda	ау	
				2: Wedne	esday	
				3: Thurso	lay	
				4: Friday		
				5: Saturd	lay	
				6: Sunda	У	
				7: Reserv	ed ed	
1	Not Used (= 0)			•		
1	5 1 2 5 5 5 3	Day Month Year Minute Hour	Day DAY Month MON Very Year Minute MIN MIN Day Week DAYW	Message Identifier MID Defines the type of message Day Date format: YYYY/MM/DD Date format: YYYY/MM/DD Date format: YYYY/MM/DD Date format: YYYY/MM/DD Minute MIN Time format: hh:mm HR Day Week Day Date format: YYYY/MM/DD Message Identifier MID Defines the type of message Enum: 3: Time a 4: Friday 5: Saturd 6: Sunda 7: Reserv	Message Identifier MID Defines the type of message Enum: 3: Time and date 3: Time and date 1:31 Month MON Date format: YYYY/MM/DD 1:12 1:12 Year YR Date format: YYYY/MM/DD 04095 Minute MIN Time format: hh:mm 059 059 Hour HR Time format: hh:mm 023 023 Day Week Day of week Enum: 0: Monday 1: Tuesday 2: Wednesday 3: Thursday 4: Friday 5: Saturday 6: Sunday 7: Reserved	

2) Heater message 5 different messages to communicate data to Gateway:

2a) Request and status

Ask for special data from gateway and send actual status of product.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	4	Message Identifier		Defines the type of	Enum:	
				message	8: Request ar	nd status
4	4	Request Frame	_	Ask information from heater	Enum:	
				lieatei		n External Temp.
						Sensor parameters
						Program
						Time and date
						tion to gateway
					57: Reserve	
						d for gateway frame edge frame
0	16	Error Flag	ERF	Indicates the errors		euge frame
8	10	Error Flag		occurred	Enum:	
				occurred	0: Temperatu	re sensor is open
						re sensor is Short circuit
					than 50°C	re measured is greater
						een internal temp and emp is greater than 4°C
					4: Reserved	
					5: Reserved	
					6: Reserved	
					7: Reserved	
					8: Reserved	
					9: Reserved	
					10: Reserved	
					11: Reserved	
					12: Reserved	
			/		13: Reserved	
					14: Reserved	
					15: Reserved	
24	1	Heating Flag		Indicates if the heater is	Enum:	
				heating the room	0: No heating	ı up
					1: Heating up)
25	2	Pilot Wire Flag	PWF	Indicates the status of the	Enum:	
				pilot wire	0: No pilot wi	re
					1: Pilot wire a	active
					2: Pilot wire -	1
					3: Pilot wire -	-2
	7/			<u> </u>	<u> </u>	

27	2	Window Open Detection Flag	WOF	Indicates if an open window is detected	Enum: 0: Disabled 1: Close 2: Open 3: Reserved
29	2	PIR Flag	PIF	Indicates if the PIR detected a movement	Enum: 0: Disabled 1: No movement detected 2: Movement detected 3: Reserved
31	1	Key Lock User Status	KLU	Indicates if the children protection is active or not	Enum: 0: Key Lock is disabled 1: Key Lock is enabled
32	1	Reference Temperature Flag	RTF	Indicates which temperature is used	Enum: 0: Internal 1: External
33	1	Derogation Flag	DGF	Indicates the status of the derogation	Enum: 0: No derogation 1: Derogation active
34	9	Internal Temperature	INT	Recent internal temperature: Temp(°C) = value / 10	1500 +0.1+50.0 °C
43	5	Not Used (= 0)			

2b) Heater parameters

Use by gateway to know Energy, Setpoint in derogation mode and firmware version.

Offset	Size	Data	ShortCut		Description	Valid Range	Scale	Unit
0	4	Message Identifier	MID	Defines	the type of message	Enum:		
						9: Heater	parameters	
4	24	Energy Measurement			nount of energy consumed KWh) = value / 10	016777215	01677721	kWh
28		Derogation Temperature Setpoint		the dero	perature setpoint set with gation: :(°C) = value / 10	1500	+0.1+50.0	°C
37	10	Firmware Version	FWV	Give the	version of the firmware	01024	01024	-
47	1	Not Used (= 0)						

2c) Value of CO, COV, CO2 and sound level

Use by gateway to know value of CO, COV, CO2 and sound level.

Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit
		•				

0		Message Identifier	MID	Defines the type of message	Enum: 10: Value of CO, CO level	OV, CO2 and soun	d
4	16	COV Value	CVV	COV value in ppb	165535	165535	ppb
20	8	CO Value	VOCT	CO value in ppm	1255	1255	ppm
28	8	CO2 Value	C2V	CO2 value in ppm	1255	102550	ppm
36	7	Sound Value	SOV	Sound value in dB	1127	1127	dB 🍆
43	5	Not Used (= 0)					

2d) Value of particles and radioactivity sensors

Use by gateway to know value of particle and radioactivity.

MID 11	Value	of of	f particle	and	radioac	tivit	y
--------	-------	-------	------------	-----	---------	-------	---

				DB	_5							DB_	_4						- [DB_	3						[DB_	_2							DB	_1							DB.	_0			
DB Bit Bit Offset	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19 2	20 2	21 2	22 2	23 2	24 2	25 2	26 2	27	28 2	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46 4	47
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			Ē						Ξ									Ξ									Ξ												Ž									
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Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Message Identifier		Defines the type of message	Enum: 11: Value of par sensors	ticles and radioactivit	ty
4	9	Particle 1 Value	PM1	Particle 1 value in µg/m3	1511	1511	μg/m3
13	9	Particle 2 Value	PM2	Particle 2 value in µg/m3	1511	1511	μg/m3
22	9	Particle 10 Value	_	Particle 10 value in µg/m3	1511	1511	μg/m3
31		Radioactivity Value		Radioactivity value In µSv/h	116383	0.01163.83	μSv/h
45	3	Not Used (= 0)					

2e) Value of air flow, hygrometry, pressure and temperature
Use by gateway to know value of air flow, hygrometry, pressure and temperature.

MID 12 Value of of air flow, hygrometry, pressure and temperature

				DB	_5						- 1	DB_{-}	4			М			D	B_3	3						DB	_2							DB.	_1							DB	_0			
DB Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5 4	1 3	3 2	2 1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset	0	1	2	3	4	5	6	7	8	9	10:	11	12	13 1	4	15	16 1	7 1	8 1	9 2	0 2	1 22	23	3 24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
			MID			2000	> E (PRV								3) } !									LNI									

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Message Identifier	MID	Defines the type of	Enum:		
				message	12: Value of air, temp.	hygro., pressure and	i
4	4	Air Moving	AMV	Air moving value in m/s	115	115	m/s
8	7	Not Used (= 0)					
15	10	Pressure Value	PRV	Pressure value in hPa	11023	5001150	hPa
25	8	Hygrometry Value	HYV	Hygrometry value in %	1200	1100	%
33		Internal Temperature		Recent internal temperature: Temp(°C) = value / 10	1500	+0.1+50.0	°C
44	4	Not Used (= 0)			•	•	

D2-34: Heating Actuator

Submitter: AWAG Elektrotechnik AG

Description

The profile is used to monitor and control a simple heating actuator. The actuator compares the current room temperature with a target temperature (set point) and accordingly switches on and off the heating.

The set point is either taken from a room operating panel (see A5-10-xx profiles) or can be configured by a radio command. A specific set point can be set as well as a relative shift to the panel value. The override can be temporary or permanent.

Data exchange

1. Status update on heartbeat or opmode change:

Direction: unidirectional Addressing: broadcast

Communication trigger: heartbeat or operation mode change Communication interval: heartbeat configurable: off / 30 sec / 3 min

Trigger event: opmode change or heartbeat

Tx delay: n/a Rx timeout: n/a

2. Status response and set point response are replies to the corresponding requests. A request for all channels results in a separate reply for each channel:

Direction: bidirectional Addressing: unicast (ADT) Communication trigger: request Communication interval: n/a

Trigger event: n/a Tx delay: 500 ms Rx timeout: 500 ms

3. Set point configuration is a unconfirmed request (per channel). Success can be determined by a set point query:

Direction: unidirectional Addressing: unicast (ADT) Communication trigger: request Communication interval: n/a

Trigger event: n/a Tx delay: n/a Rx timeout: n/a

Teach-in

Teach-in method: Universal teach-in (UTE)

Encryption supported: no Security level format: -

VLD Family Table:

Each TYPE has to support every command / parameter that is marked in its column!

Supported command	Type 00	Type 01	Type 02
No. of output channels	1	2	8
Status broadcast	X	X	Χ
Query/Reply status	X	X	Χ
Configure set point	X	X	Χ
Query/Reply set point	X	X	Χ

Supported parameter	Type 00	Type 01	Type 02
Current room temperature	Х	Χ	Χ
Currently active set point	Χ	Χ	Χ
Panel set point	Χ	Χ	Χ
Operation mode	Χ	Χ	Χ
Set point configuration	Χ	Χ	Χ
Set point override value	Χ	Χ	Χ
Set point shift value	Χ	Χ	Χ
Set point override duration	Χ	Χ	Χ

The list of parameters could be structured following the features that always include a certain group of parameters.

Appendix:

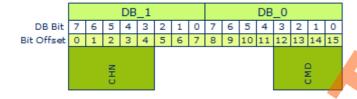
Depending on the value of CFG, the set point is evaluated differently:

- 0: Current set point = room panel value
- ... SHF, OVR and DUR are ignored
- 1: Current set point = OVR
- \dots SHF is ignored, fallback to room panel value after DUR
- 2: Current set point = room panel value + SHF
- \dots OVR is ignored, fallback to room panel value after DUR
- 3: Current set point = room panel value SHF
- ... OVR is ignored, fallback to room panel value after DUR

RORG	D2	VLD Telegram
FUNC	34	Heating Actuator
TYPE	00	1 Output Channel

Submitter: AWAG Elektrotechnik AG

CMD 0x3 - Actuator Status Query



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	5	Channel	CHN	Channel address	Enum:		
				4	0x000x1D:		130 CHN
					0x1E: All channels suppo device	rted by the	
					0x1F: Not used		
5	7	Not Used (=	0)				
12	4	Command	CMD		Enum:		
		ID		identifier	3: Status query command		

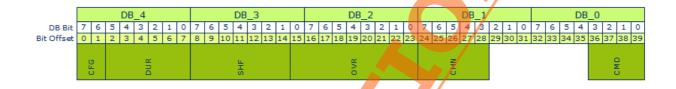
CMD 0x4 – Actuator Status Response

						_																										
			4	DB	_3							DB	_2							DB	_1							DB	_0			
DB Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	d W F										SP							E				CHN					0) D				

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	9	Temperature	TMP	Current room	Enum:		
				temperature	0400:	°C	
					0+4	0	
					0x1FF: Unknown		
9	9	Set point	SP	Currently active set point	0400	0+40	°C
	7/		,		,		

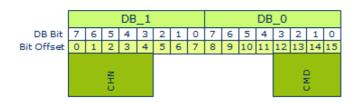
18	4	Operation Mode	ОРМ	Current mode valid for the channel	Enum: 0x0: Off (deactivated) 0x1: Temperature unknown 0x2: No heating required 0x3: Heating required 0x40xF: Not used
22	5	Channel	CHN	Channel address	Enum: 0x000x1D: 130 CHN 0x1E: All channels supported by the device
					0x1F: Not used
27	1	Not Used (= 0)		
28	4	Command ID	CMD	Command identifier	Enum: 4: Status response command

CMD 0x5 – Actuator Set Point Configuration



Offset	Sizo	Data	ShortCut	Description	Valid Range	Scale Unit
						ocale Utill
0	2	Configuration	CFG	How set point is evaluated	Epum:	
				(see appendix)	0: Room panel value	
					1: Override with OVR	
					2: Add SHF to panel value	<u> </u>
					3: Subtract SHF from pane	el value
2	6	Duration	DUR	Duration of the override until	Enum:	
				fallback to room panel value	0: Endless	
					163: h	
					163	
8	7	Set point	SHF	Set point shift value	0100 01	0 K
15	9	Set point	OVR	Set point override value	0400 0+	40 °C
24	5	Channel	CHN	Channel address	Enum:	
					0x000x1D:	130 CHN
					0x1E: All channels	
					supported by th	ie
					device	
					0x1F: Not used	
29	7	Not Used (= (0)	/		
36	4	Command ID	CMD	Command identifier	Enum:	
					5: Set point configuration	command

CMD 0x6 - Actuator Set Point Query



Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	5	Channel	CHN	Channel address	Enum:
					0x000x1D: 130 CHN
					0x1E: All channels supported by the device
					0x1F: Not used
5	7	Not Used (=	0)		
12		Command ID	_	Command identifier	Enum:
		טו		luentiner	6: Set point query command

CMD 0x7 - Actuator Set Point Response

				DE	B_5	5			Т				DB	_4							DE	3_3			7				DE	_2							B_	1			T				B_(0		
DB Bit	7	6	5	4	3	2	2 1	L	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5 4	1 :	3 2	2 :	L (7	7 6	5	5 4	4 3	3 2	1	0
Bit Offset	0	1	2	3	4	5	5 6	5 7	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32 3	33 3	34 3	5 3	6 3	7 3	8 3	9 4	0 4	1 4	2 4	3 4	4 45	46	47
	1	อหว				DUR								PNL							<u> </u>	SHF		7				7		OVR							Z L J									<u> </u>	CMD	

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	2	Configuration		How set point is evaluated	Enum:		
				(see appendix)	0: Room panel value)	
					1: Override with OVI	R	
					2: Add SHF to panel	value	
					3: Subtract SHF from	n panel valu	е
2	6	Duration		Remaining override time until	Enum:		
				fallback to room panel value	0: Expired (CFG =	: 0)	
					163:		h
						163	
8	9	Set point	PNL	Set point provided by room panel	0400	0+40	°C
17	7	Set point	SHF	Set point shift value	0100	010	K
	9	Set point	OVR	Set point override value	0400	0+40	°C
33	5	Channel	CHN	Channel address	Enum:		
			1/		0x000x1D:		130 CHN
		<u></u>			0x1E: All channe supported device		
					0x1F: Not used		
38	6	Not Used (= (0)				
44	4	Command ID	CMD	Command identifier	Enum:		
					7: Set point respons	e command	

RORG	D2	VLD Telegram
FUNC	34	Heating Actuator

TYPE 01 2 Output Channels

Submitter: AWAG Elektrotechnik AG

See profile: D2-34-00

RORG	D2	VLD Telegram
FUNC	34	Heating Actuator
TYPE	02	8 Output Channels

Submitter: AWAG Elektrotechnik AG

See profile: D2-34-00



Description

This family of EEP's is used for sending handling a LED controller device. The status is send periodically, or after product specific event occurred e.g. when one of the parameters from the status message has changed. It allows other devices to monitor LED controller and react to its actions.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: configurable

Trigger event: heartbeat, change of one of the parameters from the status message

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table:

Supported function	Type	00	Type	01
MsgId	X		X	
LED output enabled	X		X	7
"Demand Response" mode Active	X	•	X	
Daylight Harvesting	X		X	
Occupancy state	X		X	
Status Tx reason	X		Χ	
Current Dim Level	X		1	
Current Dim Level LED R	1		Χ	
Current Dim Level LED G	-		Χ	
Current Dim Level LED B	-		Χ	

Each TYPE has to support every parameter that is marked in its column!

"LED output enabled" parameter is correlated with dimming level – it is set to ENABLE if dimming level is above 0%. 0% dimming level means that the light is completely OFF.

LED controller has a "Demand Response" feature. When DR mode is triggered by external device, "Demand Response" mode Active will be set to TRUE.

Daylight Harvesting feature of the LED controller is also triggered by the external sensor.

Occupancy state is change by occupancy sensor taught in to the LED controller.

DR, Daylight Harvesting, and Occupancy will influence dimming levels, with an algorithm specific to the device that sends the status message.

RORG	D2	VLD Telegram
FUNC	40	LED Controller Status
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

MsgId 0x00:Status of monocolor LED controller

MsgId 0x00

DB_1.BIT_7

O 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

DB_1.BIT_7

O 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

monocolor LED

Offset	Size	Data	ShortCut	Description	Valid Range S	cale Unit	
0		LED output enabled	OUTEN	Driving LED enabled	Enum: 0: Disabled 1: Enabled		
1		"Demand Response" mode Active		Controller is in the DR mode. It had received a DR command from DR controller, and it is executing it.	Enum: 0: False 1: True		
2		Daylight Harvesting Active		Daylight harvesting feature is turned on. Readings from photo sensor are influencing the dimming level.	Enum: 0: False 1: True		
3	2	Occupancy State		Room which controller is in charge of is considered occupied.	Enum: 0: Not occupie 1: Occupied 2: Unknown	ed	
5	1	Status Tx reason	SREAS	Reason for sending this status message	Enum: 0: Other 1: Heartbeat	_	
6	2	MsgId	MI	Message Id; 0x00	Enum: 0: LED Status monocolor	3	
8	8	Current Dim Level	DLVL	Current dim level for the monocolor LED	Enum: 0200: 0xFF: If not used	0100 %	

RORG	D2	VLD Telegram
FUNC	40	LED Controller Status
TYPE	01	Type 0x01

Submitter: EnOcean GmbH

MsgId 0x01:Status of RGB LED controller

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0		LED output	OUTEN	Driving LED enabled	Enum:
		enabled			0: Disabled
					1: Enabled
1	1	"Demand	DRA	Controller is in the DR mode. It had received	Enum:
		Response" mode Active		a DR command from DR controller, and it is executing it.	0: False
				J. Control of the con	1: True
2		Daylight Harvesting Active	DHAR	Daylight harvesting feature is turned on. Readings from photo sensor are influencing	Enum:
		narvesting Active		the dimming level.	0: False
-	_	0 0 1	0.00		1: True
3	2	Occupancy State	occ	Room which controller is in charge of is considered occupied.	Enum:
				considered occupied.	0: Not occupied 1: Occupied
					2: Unknown
5	1	Status Tx reason	SREAS	Reason for sending this status message	Enum:
3	_	Status 1x reason	SILLING	incusor for seriality this status thessage	0: Other
					1: Heartbeat
6	2	MsgId	MI	Message Id; 0x01	Enum:
					1: LED Status RGB
8	8	Current Dim Level	DLVLR	Current dim level for the red LED	Enum:
		LED R			
					0200: 0100 %
					0xFF: If not
1.0	0	C	DIV# C		used _
16		Current Dim Level LED G	DLVLG	Current dim level for the green LED	Enum:
					0200: 0100 %
					0xFF: If not
					used
24		Current Dim Level	DLVLB	Current dim level for the blue LED	Enum:
		LED B			
					0200: 0100 %
					0xFF: If not
					used

D2-50: Heat Recovery Ventilation

Submitter: Glen Dimplex

Description

The EEP family D2-50-XX provides different telegram types for heat-recovery ventilation control and status messages using various parameters and variables.

There are 4 types of messages:

- Ventilation Remote Transmission Request Message
- Ventilation Control Message
- Ventilation Basic Status Message

- Ventilation Extended Status Information Message

Data exchange

Direction: bidirectional

Addressing: unicast (ADT) + broadcast

Communication trigger: event- & time-triggered

Communication interval: min. 1s (not more than once per second on events), max. 5s (heartbeat)

Trigger event:

heartbeat 5s

on reception of 'Ventilation Control Message'

query / polling by 'Ventilation Remote Transmission Request Message'

on value change at ...

- "Operating Mode Status"
- "Digital Input 0...15 Status"
- "Digital Output 0...15 Status"
- "Info Message 0...15 Status"
- "Fault 0...31 Status"

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table

TYPE 00: single room ventilation unit

TYPE 01: single room ventilation unit with pre-heater TYPE 02...09: reserved for future single room variants TYPE 10: multi room ventilation unit without bypass TYPE 11: multi room ventilation unit with bypass

TYPE 12...xx: reserved for future multi room variants

Supported function	Type 00	Type 01	Type 10	Type 11
Message Type	Х	Х	X	X
Requested Message Type	Х	Х	X	Х
Direct Operation Mode Control	Х	X	X	Х
Operation Mode Control	X	X	X	Х
Timer Operation Mode Control	X	X	X	Χ
CO2 Threshold	X	X	X	Χ
Heat Exchanger Bypass Control	-	-	-	Χ
Humidity Threshold	X	X	Χ	Χ
Air Quality Threshold	X	X	Χ	Χ
Room Temperature Threshold	-	-/	X	Χ
Operation Mode Status	X	X	Χ	Χ
Safety Mode Status		-	-	Χ
Heat Exchanger Bypass Status	- 7/	-	-	Χ
Supply Air Flap Position	X /	Х	-	-
Exhaust Air Flap Position	Х	Χ	-	-
Defrost Mode Status	Х	Х	Х	Х
Cooling Protection Status	Х	Х	Х	Х
Outdoor Air Heater Status	-	Х	Х	Х
Supply Air Heater Status	-	-	Х	Х
Drain Heater Status	Х	Х	-	-
Timer Operation Mode Status	Х	Х	Х	X
Filter Maintenance Status	Х	Х	Х	X
Weekly Timer Program Status	-	-	Х	Х
Room Temperature Control Status	-	-	Х	X
Air Quality Sensor 1	Х	Х	Х	Х
Master/Slave Status	X	Х	-	-
Air Quality Sensor 2	-	-	Х	Х
Outdoor Air Temperature	X	Х	Х	Х
Supply Air Temperature	Х	Х	Х	Χ

Indoor Air Temperature	 -	_	X	X
Exhaust Air Temperature	-	-	Χ	X
Supply Air Fan Air Flow Rate	Х	Χ	Χ	X
Exhaust Air Fan Air Flow Rate	Χ	Χ	Χ	Χ
Supply Fan Speed	Χ	Χ	Χ	Χ
Exhaust Fan Speed	Χ	Χ	Χ	Χ
Software Version Info	Χ	Χ	Χ	Χ
Operation Hours Counter	Χ	Χ	Χ	Χ
Digital Input 015 Status	-	-	Χ	Χ
Digital Output 015 Status	-	-	Χ	Χ
Info Message 015 Status	Χ	Χ	Χ	Χ
Fault 031 Status	Χ	X	X	X



The list of parameters could be structured following the features that always include a certain group of parameters.

Each TYPE has to support every parameter that is marked in its column!

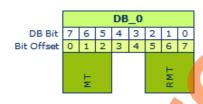
RORG	D2	VLD Telegram
FUNC	50	Heat Recovery Ventilation
TYPE	00	Type 0x00

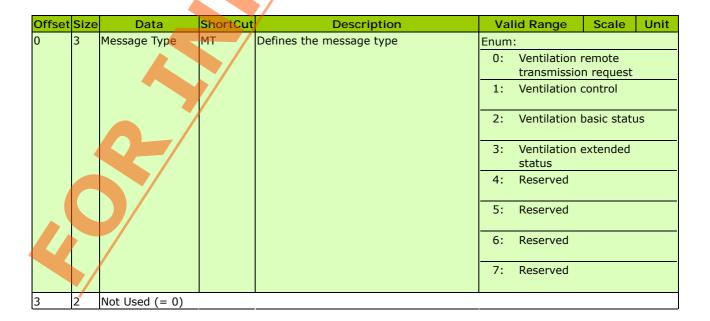
Submitter: Glen Dimplex

Telegram Definition: 'Ventilation Remote Transmission Request Message'

The 'Ventilation Remote Transmission Request Message' queries a particular status message from the heat-recovery ventilation unit. Thus status messages can be obtained at any time or at a higher update rate than the heartbeat rate, e.g. during commissioning.

Direction: Gateway --> Heat-recovery ventilation unit





5	3	Requested	RMT	Defines the message type, which is	Enum	:
		Message Type		requested by the remote device	0:	Ventilation basic status
			1:	Ventilation extended status		
					2:	Reserved
					3:	Reserved
					4:	Reserved
					5:	Reserved
					6:	Reserved
					7:	Reserved

Telegram Definition: 'Ventilation Control Message'

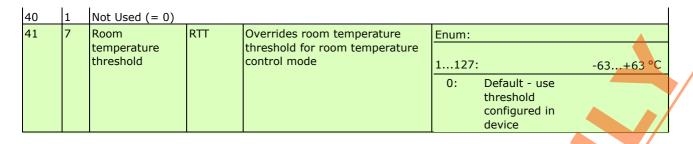
The 'Ventilation Control Message' changes the operating mode, the state of several actuators and a subset of control parameters.

Direction: Gateway --> Heat-recovery ventilation unit



Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	3	Message Type	МТ	Defines the message type	Enum:	c status
3 4		Not Used (= 0) Direct Operation Mode Control	DOMC	Selects ventilation mode/level	Enum: 0: Off 1: Level 1 2: Level 2 3: Level 3	

					4: Level 4
					5: Reserved
					6: Reserved
					7: Reserved
					8: Reserved
					9: Reserved
					10: Reserved
					11: Automatic
					12: Automatic on demand
					13: Supply air only
					14: Exhaust air only
					15: No action (keep current ventilation mode/level)
8	2	Operation Mode Control	ОМС	Selects the next resp. previous available ventilation mode/level	Enum: 0: No action
					1: Select next operation mode
					(edge-trigger) 2: Select previous operation mode
					(edge-trigger) 3: Reserved
10	2	Heat Exchanger	НВС	Manual override of automatic	Enum:
		Bypass Control		heat exchanger bypass control	0: No action
					1: Close bypass (edge-trigger)
					2: Open bypass (edge-trigger)
					3: Reserved
12	4	Not Used (= 0)			
16	1	Timer Operation	TOMC	Enables Timer Operation Mode,	Enum:
		Mode Control		i.e. a particular ventilation mode is activated for a defined time	0: No action
					1: Start timer operation mode (edge-trigger)
17	7	CO2 Threshold	COT	Overrides CO2 threshold for CO2	Enum:
				control in automatic mode	0100: 0100 %
					Reserved 101126:
					127: Default (use threshold configured in device)
24	1	Not Used (= 0)	. 7/		
25	7	Humidity	HT	Overrides humidity threshold for	Enum:
		Threshold		humidity control in automatic mode	0100: 0100 %
					Reserved 101126:
					127: Default (use threshold configured in device)
32	1	Not Used (= 0)			
33	7		AQT	Overrides air quality threshold for	Enum:
		Threshold		air quality control in automatic mode	0100: 0100 %
Y				mode	Reserved
					101126: 127: Default (use threshold
					configured in device)

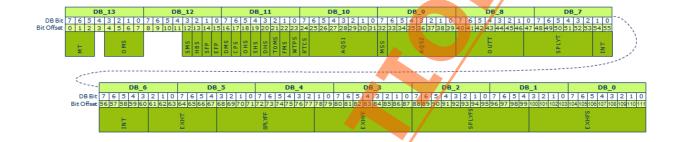


Telegram Definition: 'Ventilation Basic Status Message'

The 'Ventilation Basic Status Message' provides current sensor values and internal control status information. It is triggered once at power-on and on particular value changes.

Additionally this message is available on request.

Direction: Heat-recovery ventilation unit --> Gateway



Offset	Size	Data	ShortCut	Description	Valid	Range	Scale Unit
0	3	Message Type	MT	Defines the message type	Enum	:	
					0:		ion remote ssion request
					1:	Ventilat	ion control
					2:	Ventilat	ion basic status
					3:	Ventilat status	ion extended
					4:	Reserve	d
					5:	Reserve	d
					6:	Reserve	d
					7:	Reserve	d
3	1	Not Used (= 0)					
4	4	Operation Mode	OMS	Shows current Operation Mode Status	Enum	:	
		Status			0:	Off	
					1:	Level 1	
	4				2:	Level 2	
					3:	Level 3	
					4:	Level 4	
					5:	Reserve	d
					6:	Reserve	<u>d</u>
					7:	Reserve	
					8:	Reserve	
	/				9:	Reserve	
					-	Reserve	
					11:	Automa	tic

					-10	
						Automatic on demand
						Supply air only
					-	Exhaust air only
_					15:	Reserved
8	4	Not Used (= 0)				
12	1	Safety Mode Status	SMS	Indicates if device is running in	Enum:	
				fireplace safety mode	0:	Fireplace safety mode
						disabled
					1:	Fireplace safety mode enabled
4.0	_		LUDG	- 1:		
13	1	Heat Exchanger Bypass Status	HBS	Indicates heat exchanger bypass status	Enum:	
		Dypass Status		Status	0:	Bypass closed (heat-
						recovery active)
					1:	Bypass opened (heat- recovery inactive)
14	1	Supply Air Flap	SFP	Supply Air Flap Position	Enum:	
14	1	Position	31 F	Supply All Trap Fosition	_	
					0:	Supply air flap closed
4.5	_	E 1 . A. El		5 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1:	Supply air flap opened
15	1	Exhaust Air Flap Position	EFP	Exhaust Air Flap Position	Enum:	
		Position			0:	Exhaust air flap closed
					1:	Exhaust air flap opened
16	1	Defrost Mode	DMS	Indicates if device is running in defrost		
		Status		mode, i.e. automatic defrosting of heat	0:	Defrost mode inactive
				exchanger is active	1:	Defrost mode active
17	1	Cooling Protection	CPS	Indicates if device is running in cooling	Enum:	
		Status		protection	0:	Cooling protection mode
						inactive
					1:	Cooling protection mode
						active
18	1	Outdoor Air Heater	OHS	Outdoor Air Heater Status	Enum:	<u> </u>
		Status			0:	Inactive
					1:	Active
19	1	Supply Air Heater	SHS	Supply Air Heater Status	Enum:	
		Status			0:	Inactive
					1:	Active
20	1	Drain Heater	DHS	Drain Heater Status	Enum:	
		Status			0:	Inactive
					1:	Active
21	1	Timer Operation	TOMS	Indicates timer operation mode status	Enum:	
	_	Mode Status	10110	and the special section of the secti	0:	timer operation mode
					0.	inactive
					1:	timer operation mode
						active
22	1	Filter Maintenance	FMS	Filter Maintenance Status	Enum:	
		Status			0:	Maintenance not
						required
					1:	Maintenance required
23	1	Weekly Timer	WTPS	Indicates if weekly timer program is	Enum:	
		Program Status		active (i.e. if device is running	0:	Weekly timer program
				according to configured program)		disabled or not
		/			-	configured
					1:	Weekly timer program
						active
24	1	Room Temperature	RTCS	Indicates room temperature control	Enum:	
		Control Status		status	0:	Room temperature
						control inactive
					1:	Room temperature
25	-	Air Our III C	1001	Command aire and lit	_	control active
25		Air Quality Sensor	AQS1	Current air quality sensor 1 measurement value	Enum:	
		7		measurement value	01	
	7/				-	126: Reserved
					127	: Not available

32	1	Master/Slave	MSS	Indicates whether device is configured	Enum:		
		Configuration		as master or slave unit	0: Master		
		Status			1: Slave		
33	7	Air Quality Sensor	AQS2	Current air quality sensor 2	Enum:		
		2		measurement value	0100: ()100 %	
					101126: I	Reserved	
					127:	Not available	
40	7	Outdoor Air Temperature	OUTT	Current outdoor air temperature	0127	-64+63	°C
47	7	Supply Air Temperature	SPLYT	Current supply air temperature	0127	-64+63	°C
54	7	Indoor Air Temperature	INT	Current indoor air temperature	0127	-64+63	°C
61	7	Exhaust Air Temperature	EXHT	Current exhaust air temperature	0127	-64+63	°C
68	10	Supply Air Fan Air Flow Rate	SPLYFF	Current supply air fan air flow rate setpoint	01023	01023	m3/h
78	10	Exhaust Air Fan Air Flow Rate	EXHFF	Current exhaust air fan air flow rate setpoint	01023	01023	m3/h
88	12	Supply Fan Speed	SPLYFS	Current supply air fan speed	04095	04095	1/min
100	12	Exhaust Fan Speed	EXHFS	Current exhaust air fan speed	04095	04095	1/min

Telegram Definition: 'Ventilation Extended Status Message'

The 'Ventilation Extended Status Message' provides additional information, e.g. active failure information. It is triggered once at power-on and on particular value changes.

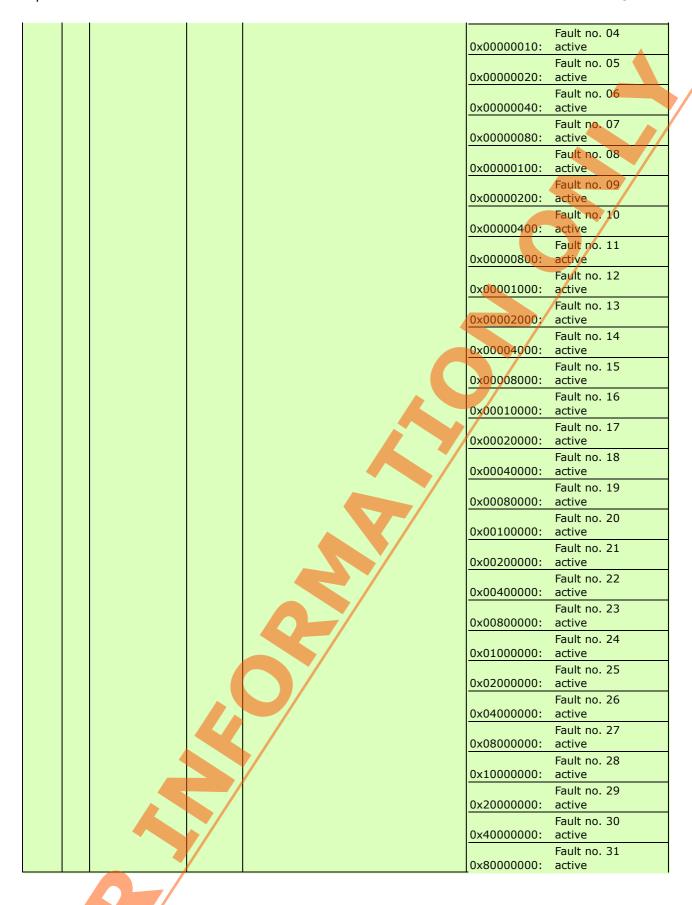
Additionally, this message is available on request.

Direction: Heat-recovery ventilation unit --> Gateway

DB_13	DB_12	DB_11	DB	_10 C)B_9	DB_8	DB_7
DB Bit 7 6 5 4 3 2 1 0	7 6 5 4 3 2 1	7 6 5 4 3 2	1 0 7 6 5 4	3 2 1 0 7 6 5	4 3 2 1 0 7 6 5	4 3 2 1 0	7 6 5 4 3 2 1 0
Bit Offset 0 1 2 3 4 5 6 7	8 9 10 11 12 13 14 1	5 16 17 18 19 20 21	22 23 24 25 26 27	28 29 30 31 32 33 34 3	5 36 37 38 39 40 41 42	43 44 45 46 47 4	18 49 50 51 52 53 54 55
MT	SVT		OHC		DIS		DOS
<55.77 <u></u>							
DB	_6 DB	_5	DB_4	DB_3	DB_2	DB_1	. DB_0
DB Bit 7 6 5 4	_6 DB	_5 3 2 1 0 7 6 5	DB_4	DB_3	DB_2	DB_1	DB_0
DB_	_6 DB 3 2 1 0 7 6 5 4 50 61 62 63 64 65 66 67	3 2 1 0 7 6 5	DB_4 5 4 3 2 1 0 7 4757677787980	DB_3 6 5 4 3 2 1 0 0 81 82 83 84 85 86 87	7 6 5 4 3 2 1	DB_1 0 7 6 5 4 3 5 96 97 98 99 100	DB_0 2 1 0 7 6 5 4 3 2 1 0 0101102103104105106107108109110111
DB Bit 7 6 5 4	3 2 1 0 7 6 5 4 50 61 62 63 64 65 66 67	3 2 1 0 7 6 5	DB_4 5 4 3 2 4 0 7 4757677 787980	6 5 4 3 2 1 0	7 6 5 4 3 2 1	7 6 5 4 3	DB_0 2 1 0 7 6 5 4 3 2 1 0 0101102103104105108107108109110111

Offset	Size	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	3	Message Type	MT	Defines the message type	Enum	:		
					0:		on remote ssion request	
					1:	Ventilati	on control	
					2:	Ventilati	on basic status	
					3:	Ventilati status	on extended	
					4:	Reserve	d	
					5:	Reserve	d	
					6:	Reserve	d	
					7:	Reserve	d	
3	1	Not Used (= 0)						
4		Software Version Info	SVI	Shows Software Version Information	040	95	04095	-

16	16	Operation Hours Counter	ОНС	Indicates device operation hours	065535	0196605 h				
32	16	Digital Input	DIS	Indicates the current state of digital	Enum:					
32		015 Status	D10	inputs 015 of the device		ut no. 00 active				
						ut no. 01 active				
				input assignment depends on device						
				variant and configuration		0x0004: Input no. 02 active 0x0008: Input no. 03 active				
							7/			
						ut no. 04 active	/ /			
						ut no. 05 active	_			
						ut no. 06 active	_			
						ut no. 07 active	_			
						ut no. 08 active	_			
						ut no. 09 active	_			
					0x0400: Inp	ut no. 10 active	_			
					0x0800: Inp	ut no. 11 active	<u>_</u>			
					0x1000: Inp	ut no. 12 active				
					0x2000: Inp	ut no. 13 active				
						ut no. 14 active	_			
						ut no. 15 active	_			
48	16	Digital Output	DOS	Indicates the current state of digital	Enum:					
70	10	015 Status	003	outputs 015 of the device		tout no 00 active	_			
	July Status		3.000		tput no. 00 active					
				output assignment depends on device		tput no. 01 active				
				variant and configuration		tput no. 02 active				
						tput no. 03 active	<u> </u>			
						tput no. 04 active				
					0x0020: Out	tput no. 05 active				
					0x0040: Out	tput no. 06 active				
					0x0080: Out	tput no. 07 active				
					0x0100: Out	tput no. 08 active				
					0x0200: Out	tput no. 09 active	_			
					-	tput no. 10 active	_			
						tput no. 11 active	—			
					-	tput no. 12 active	—			
						tput no. 13 active	—			
						tput no. 14 active				
						tput no. 15 active	—			
C 4	1.0	Info Massage	TMC	Indicates the current state of info		tput no. 13 active				
64	16	Info Message 015 Status	IMS	message no. 015 generated by the	Enum:	00 !				
		o15 Status		device		o no. 00 active				
						o no. 01 active				
						o no. 02 active				
						o no. 03 active				
						o no. 04 active				
					0x0020: Inf	o no. 05 active	_			
					0x0040: Inf	o no. 06 active				
					0x0080: Inf	o no. 07 active				
					0x0100: Inf	o no. 08 active				
					0x0200: Inf	o no. 09 active				
						o no. 10 active				
						o no. 11 active				
					-	o no. 12 active				
					-	o no. 13 active				
					-	o no. 14 active				
					-	o no. 14 active				
00	22	F-14 0 21	FC	T		o iio. 15 active				
80	32	Fault 031 Status	FS	Indicates the current state of fault no. 031 generated by the device	Enum:	FII CO				
		Status		Single generated by the device	0x00000001:	Fault no. 00 active				
					0.00000001:	Fault no. 01				
					0x00000002:	active				
					0.00000002:	Fault no. 02				
	7				0x00000004:	active				
					. JACCUCUUT.	G C C V C				
						Fault no 03				
					0x00000008:	Fault no. 03 active				
	//									



RORG	D2	VLD Telegram
FUNC	50	Heat Recovery Ventilation
TYPE	01	Type 0x01 (description: see table)

See profile: D2-50-00

RORG	D2	VLD Telegram
FUNC	50	Heat Recovery Ventilation
TYPE	10	Type 0x10 (description: see table)

See profile: D2-50-00

RORG	D2	VLD Telegram
FUNC	50	Heat Recovery Ventilation
TYPE	11	Type 0x11 (description: see table)

See profile: D2-50-00

D2-A0: Standard Valve

RORG	D2	VLD Telegram
FUNC	Α0	Standard Valve
TYPE	01	Valve Control (BI-DIR)

Submitter: Afriso / EnOcean

Description

Radio operated valve control with feedback message. Valve is controlled through the air interface to be opened or closed. The valve reports the actual status after finishing the determined operation.

Data exchange

Direction: bidirectional

Addressing: addressed (inbound) and broadcast (outbound)

Communication trigger: event- & time-triggered Trigger event: position of valve has changed

Teach-in method: UTE

DIRECTION-1 = Outbound (water valve to the controller)

Description: Valve reports its status. Report is sent after operation was executed or as a heartbeat.

DIRECTION-2 = Inbound (controller to the water valve)

Description: Operational command to the valve. After this request a feedback response will be transmitted, once the operation is finished.

A "no change"-command will also be followed by a feedback response. Therefore, it can be used as a status request.

DIRECTION-1

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	6	Not Used	(= 0)			
6	2	Feedback	FDB	Return	Enum:	
		4			0b00: Not o	defined
					0b01: Close	ed
					0b10: Open	ned
					0b11: Not o	defined

DIRECTION-2

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	6	Not Use	ed (= 0)				
6	2	Request	REQ	Request to operate the valve	Enum:		
					0b00: No change (requ	est of feed	back)
					0b01: Request to close	valve	
					0b10: Request to oper	valve	
	1/				0b11: Request to close	valve	

D2-B0: Liquid Leakage Sensor

RORG	D2	VLD Telegram
FUNC	В0	Liquid Leakage Sensor
TYPE	51	Mechanic Harvester

Submitter: Afriso / EnOcean

Description

This device is used to detect water. It is commonly placed on ground where a water leakage causes damage. The principle is that "paper rings" swell in water and trigger an ECO 200 (generator) based transmitter. This version is done for USA 902 MHz.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A Trigger event: (water detected)

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: UTE teach-in

Security

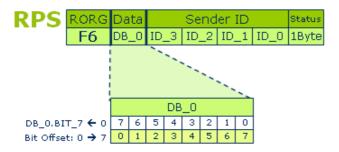
Encryption supported: no Security level format: -

	Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit				
	0	8	Water	WA	Alert signal that the sensor detected	Enum:						
			sensor		water leakage.	No water det	ected / retu	ırn				
						0x00: position	0: position					
						Water detecte	ed					
Į						0x11:						

EEP 2.6.7 Specification © EnOcean Alliance

3) Appendix

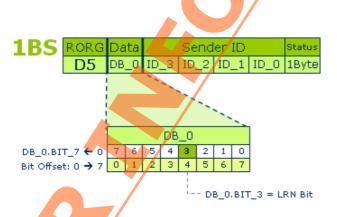
3.1) RPS Teach-in



The RPS telegram can only send data and has no special telegram modification to teach-in the device. Therefore, the teach-in procedure takes place manually on the actuator/controller through a normal data telegram. The EEP profile must be manually supplied to the controller per sender ID.

In learn mode, the receiving actuator reduces the input sensitivity in order to fade out weakly received data telegrams. This helps avoid inadvertently teaching-in sensors.





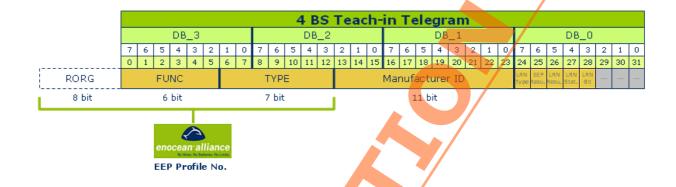
The 1BS telegram has its own teach-in telegram, which can signal the teach-in command through the DB_0.BIT_3 data bit.

Offset Size Bitrange Data Valid Range Scale Unit

4	1	DB0.3	LRN Bit	Enum:	
				0:	Teach-in telegram
				1:	Data telegram

Here, an EEP profile must also be manually allocated per sender ID.

3.3) 4BS Teach-in



The 4BS telegram also has its own teach-in telegram, however with more teach-in variations:

Variation 1

The profile-less unidirectional teach-in procedure functions according to the same principle as the 1BS telegram: if the data bit is DB_0.BIT_3 = 0, then a teach-in telegram is sent. This includes the 'LRN TYPE' DB_0.BIT_7 = 0 data bit. Then no EEP profile identifier and no manufacturer ID are transferred.

Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum:			
				0:	telegram without EEP	and Manufact	urer ID
28	1	DB0.3	LRN Bit	Enum:			
				0:	Teach-in telegram		
				1:	Data telegram		

Variation 2

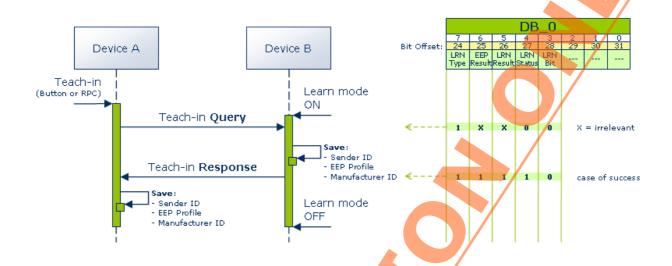
For the unidirectional profile teach-in procedure, it is preferred in opposite to variation 1), as the teach-in telegram contains both the complete EEP number and the manufacturer ID. The device is therefore clearly identifiable as ready-to-use and can be securely executed in a complex system environment or by foreign systems. In this case, the 'LRN TYPE' data bit is $DB_0.BIT_7 = 1$.

O	ffse	t S	Size	Bitrange	Data		Valid Range Scale Unit									
2	4	1		DB0.7	LRN Type	Enum	:									
						1:	telegram with EEP nun	nber and Manufac	turer ID							
2	8//	1		DB0.3	LRN Bit	Enum	:									
		4				0:	Teach-in telegram									
						1:	Data telegram									

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Variation 3

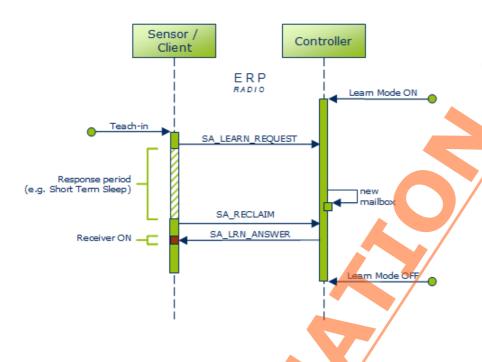
During the bidirectional teach-in procedure, further bits are required from the DB_0, in order to develop the mutual teach-in between two communication partners. For this, the procedure is made up of 2 teach-in telegrams, which are exchanged on both sides. The following UML diagram is used to illustrate this:



Offset	Size	Bitrange	Data	Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum:		
				0: telegram without EEP a	nd Manufacturer	ID
				1: telegram with EEP num	ber and Manufac	turer ID
25	1	DB0.6	EEP Result	Enum:		
				0: EEP not supported	V /	
				1: EEP supported		
26	1	DB0.5	LRN Result	Enum:		
				0: Sender ID deleted/not s	stored	
				1: Sender ID stored		
27	1	DB0.4	LRN Status	Enum:		
				0: Query		
				1: Response		
28	1	DB0.3	LRN Bit	Enum:		
				0: Teach-in telegram		
				1. Data telegram		

3.4) Smart Ack Teach-in (without repeater)

Under Smart Ack (SA), the teach-in procedure is more complex as, alongside the SA client and SA controller, a Postmaster must also be established to prepare a mailbox for each taught-in SA client. The Postmaster is normally found in the controller. If a repeater is installed, then a postmaster is set up there.

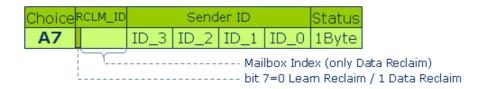


After the learn mode is activated on the controller, the teach-in procedure can be started on the client. The client sends an SA_LEARN_REQUEST telegram:

RC	RG	Req.	Manuf.ID	D EEP (3 byte)			RSSI		Repea	iter ID		Sender ID				Status	CHCK
	6	5 bit	it 11 bit RORG FUNC TYPE		TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte	
	Request Code							/									

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0x00	0 = Without repeater
Repeater ID	0x00000000	0 = Without repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

During the 'response period' in the SA client, which is always 550 ms during the teach-in, the controller creates a new mailbox in its postmaster and leaves its first message there with an OK receipt. This entry is requested from the postmaster by the SA client with an SA_RECLAIM 'Learn' telegram:



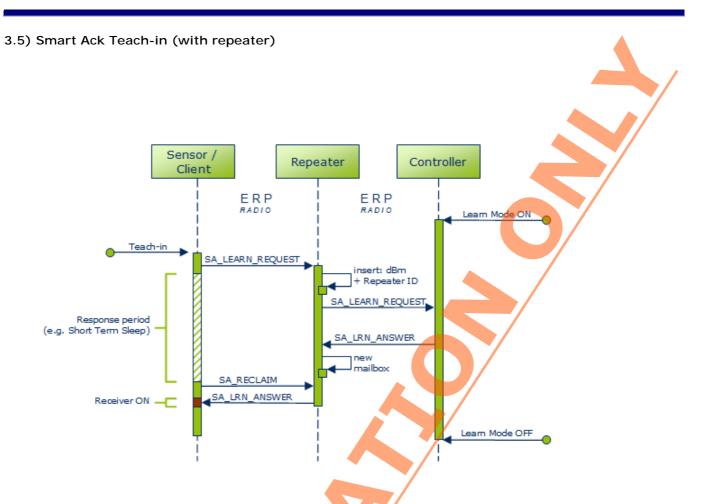
Data	Value	Description					
Message Index	0b0	Bit 7: 0 = Learn Reclaim					
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-i					
Status	0x0F	0F = no repeating desired					
CHCK	0xnn	Checksum					

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

ROF	RG F	RORG-EN	Index	Respor	nse time	Ack C.	Mailbox		not used	ı	Postmaster ID					Contro	Status	CHCK		
- 0		1	2	3	4	5	- 6	7	7 8 9		10	11	12	13	14	15	16	17	18	19
Αđ	5	C7	02					-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time	0xnnnn	Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value 550 ms = 0x0226)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	OF = no repeating permitted
CHCK	0xnn	Checksum



If a repeater comes into operation, the SA_LEARN_REQUEST telegram sent by the SA client (with an EEP No., Manufacturer ID, Sender ID) is completed on the repeater with the RSSI value (in dBm) and the Repeater ID, and sent to the controller.

	RORG	Req.	Manuf.ID	Manuf.ID EEP (3 byte)				П		7	Repea	ter ID			Send	er ID		Status	снск
ľ		<u> </u>		dBm	ID_:					ID_0	ID_3 ID_2 ID_1 ID_0					1 Byte			
ľ	Request Code																		

Data	Value	Description					
Request Code	0b11111	Default value – send by sensor					
Manufacturer ID	0bnnnnnnnnnnn	Corresponding to the teach-in sensor					
EEP No.	0xnnnnn	RORG, FUNC, TYPE					
RSSI	0xnn	Value added from repeater					
Repeater ID	0xnnnnnnn	Device ID repeater					
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in					
Status	0x0F	0F = no repeating permitted					
CHCK	0xnn	Checksum					

From the reception strength of the RSSI, the controller can recognise which repeater is best for the task of postmaster. In the meantime, the SA client will be in its 'response period'.

The sent addressed telegram SA_LRN_ANSWER with the message 'Learn Reply' by the controller to the repeater ensures that the postmaster is activated and a mailbox is created.

4	RORG	RG Req. Manuf.ID EEP (3 byte)		RSSI	Repeater ID			Sender ID				Status	CHCK				
	C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
		Reques Code	t														

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x01	Message Index; 01 = Learn Reply
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value 550 ms = 0x0226)
Acknowledge code	0x00	First Learn In successful
Sender ID	0xnnnnnnn	Chip ID of sensor to be teach-in
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

Also, a mailbox is created for the SA client, where an initial entry with an OK message is left. This information is requested by the SA client from the repeater's postmaster with the SA_RECLAIM 'Learn' telegram.

Choice	RCLM_ID		Send	ler ID	Status		-	
A7		ID_3	ID_2	ID_1	ID_0	1Byte		
						ex (only C m Reclain	V Comment	

Data	Value	Description
Message Index	0b0	Bit 7: 0 = Learn Reclaim
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating desired
CHCK	0xnn	Checksum

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

RORG	RORG-EN	Index	Respon	ise time	Ack C.	Mailbo:	KI .	not used			Postmaster ID			Controller ID				Status	CHCK		
0	1	2	3	4	5	6		7	8		9	10	11	12	13	14	15	16	17	18	19
A6	C7	02						-	V 7		-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

<u> </u>		
Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value 550 ms = 0x0226)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

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3.6) UTE - Universal Uni- and Bidirectional Teach-in

General

Up to now there are teach-in procedures available for:

- RPS communication (EnOcean ID + rocker/channel information, unidirectional)
- 1BS communication (LRN telegram, w/o EEP and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, bidirectional)
- SmartACK communication (self powered devices, bidirectional)

For uni- and bidirectional EEP communication that does not fit into SmartACK communication principles but is based on e.g. MSC and VLD messages no teach-in procedure is defined so far.

Therefore, this document proposes a universal teach-in procedure that allows handling of teach-in and teach-out requirements for EEP based communication of all different RORG. This proposal shall be understood as an alternative to SmartACK teach-in for devices where SmartACK is not applicable.

RORG to be used: OxD4 Universal Teach-in, EEP based (UTE)

FUNC and TYPE shall be represented as 8bit parameters, both with a value range from 0x00 ... 0xFF. This aligns UTE with the EEP representation defined for SmartACK teach-in.

REMARK 1:

Even though the proposed Universal Tech-In Procedure is able to cover EEPs based on RPS, 1BS and 4BS messages as well, it is not intended to replace the existing RPS, 1BS and 4BS teach-in / teach-out procedures for unidirectional and the existing 4BS teach-in / teach-out procedures for bidirectional communication.

However, it is recommended that with the acceptance of the proposed Universal Tech-In Procedure all new bidirectional 4BS applications shall use it for teach-in and teach-out as well.

REMARK 2:

The proposed Universal Tech-In Procedure is dedicated to EEP based EnOcean communication. It does neither compete with nor shall it interfere with the tech-in process of the Generic EnOcean Communication.

Communication - Principles and Definitions

BIDIRECTIONAL EEP-BASED COMMUNICATION

Bidirectional EnOcean communication means a point-to-point communication relationship between two enabled EnOcean devices. It requires all parties involved to know the unique EnOcean ID of their partners. Such point-to-point communication relationship is established with the completion of a successful teach-in process and it is deleted with the completion of a successful teach-out process.

To get a maximum reliable teach-in process with a minimum consumption of energy and resources, a simple query response mechanism is used: the device that is intended to be taught-in broadcasts a query message and gets back an addresses response message, containing its own EnOcean ID as the transmission target address.

In case there is more than one device ready to accept teach-in query messages at the same time and within the same radio range, the device with the quickest response time will be accepted by the device to be taught-in. Second and further devices will respond as well but they will not be accepted by the device to be taught-in. This will result in a configuration situation that is common to today's EEP based unidirectional teach-in processes.

UNIDIRECTIONAL EEP-BASED COMMUNICATION

Unidirectional EnOcean communication means a point-to-multipoint communication relationship between enabled EnOcean devices. In this case of broadcasting the device to be taught-in to other devices does not know the unique EnOcean ID of those communication partners.

The proposed Universal Teach-In Procedure supports unidirectional EnOcean communication thru related configuration bits in the query message.

However, for specific applications – e.g. configuration feedback - it is also possible to combine a bidirectional teach-in process with a unidirectional EEP based communication during the regular operation of a device.

EEP Teach-In Query - UTE Message (Broadcast / CMD: 0x0)

This message is sent by the EEP based EnOcean device that is intended to be taught-in to another device (which has been set into LRN-mode before either manually or thru a ReMan command).

Response Timing:

If a response is expected it shall be received within a maximum of 700ms from the time of transmission of this message. In case no such response is received within this time frame the query action shall be treated as completed with negative result. If no response is expected, each query action has to be treated as completed with positive result.

		UTE Teach-in Query													
	DB_6	DB_5	DB_4	DB_3	DB_2	DB_1	DB_0								
DB_6.BIT_7 ← 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0	7 6 5 4 3 2 1	0 7 6 5 4 3 2 1 0								
Bit Offset: 0 → 55	0 1 2 3 4 5 6 7					40 41 42 43 44 45 46 4	17 48 49 50 51 52 53 54 55								
		No. of individual channel Manufacturer-ID Manuf-:ID TYPE FUNC to be taught in LSB MSB													
	to be taught in Lise Miss Command Identifier (CMD): EEP Teach-In Query Teach-in request EEP Teach-In-Response message expected y/n														

TABLE OF 7 BYTE PAYLOAD:

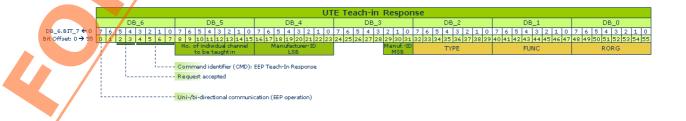
Offset	Size	Bitrange	Value	Description
0	1	DB6.7	0b0	Unidirectional communication (EEP operation)
" "	" "	" "	0b1	Bidirectional communication (EEP operation)
1	1	DB6.6	0b0	EEP Teach-In-Response message expected
" "	11 11	" "	0b1	No EEP Teach-In-Response message expected
2	2	DB6.5 DB6.4	0b00	Teach-in request
" "	=	" "	0b01	Teach-in deletion request
" "	11 11	" "	0b10	Teach-in or deletion of teach-in, not specified
" "	=	" "	0b11	Not used
4	4	DB6.3 DB6.0	0x0	Command identifier (CMD) / 0x0: EEP Teach-In Query
8	8	DB5.7 DB5.0	0x00 0xFE	Number of individual channel to be taught in
" "	=	" "	0xFF	Teach-in of all channels supported by the device
16	8	DB4.7 DB4.0	MID (8LSB)	Manufacturer-ID (8LSB)
24	5	DB3.7 DB3.3	-	Do not use
29	3	DB3.2 DB3.0	MID (3MSB)	Manufacturer-ID (3MSB)
32	8	DB2.7 DB2.0	TYPE	TYPE of EEP [0x00 0xFF]
40	8	DB1.7 DB1.0	FUNC	FUNC of EEP [0x00 0xFF]
48	8	DB0.7 DB0.0	RORG	RORG of EEP [0x00 0xFF]

EEP Teach-In Response - UTE Message (Addressed / CMD: 0x1)

This message is the reply to an EEP Teach-In Query message. It is sent by the EEP based EnOcean device that has been set into LRN-mode before (either manually by HMI or thru a ReMan command).

Response Timing:

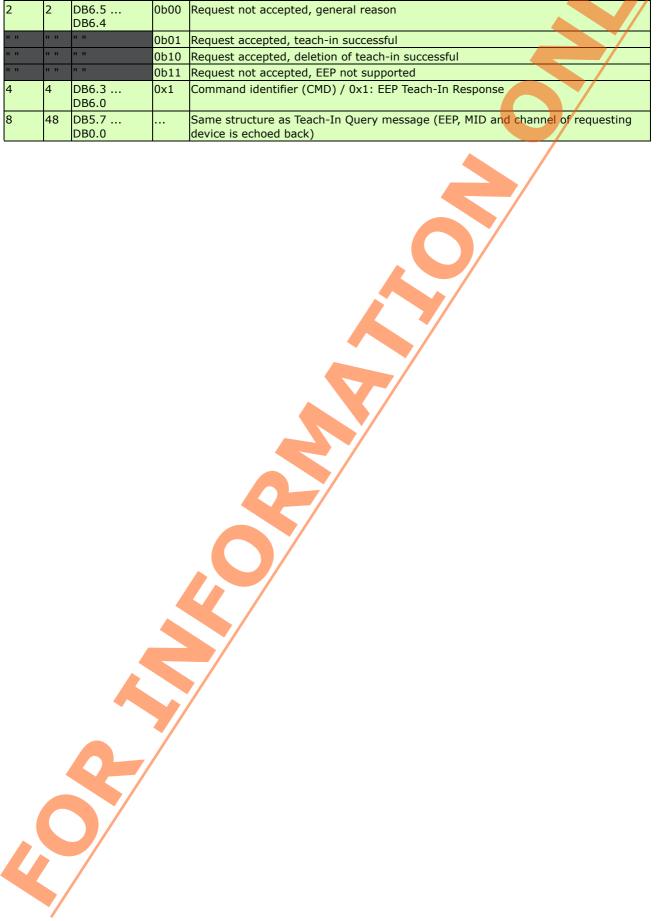
If a response is requested this message shall be sent within a maximum of 500ms from the time of reception of the EEP Teach-In Query message. This limit shall give sufficient time to decide on the teach-in request and answer accordingly (e.g. when requests need to be processes by data base systems connected asynchronously).



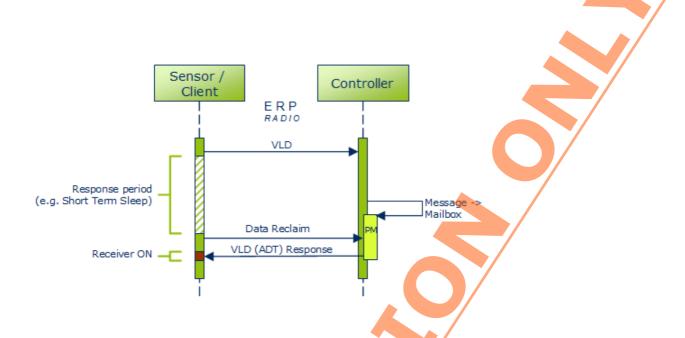
EEP 2.6.7 Specification © EnOcean Alliance

TABLE OF 7 BYTE PAYLOAD:

Offset	Size	Bitrange	Value	Description
0		DB6.7		Unidirectional communication (EEP operation)
11 11	11 11	" "	0b1	Bidirectional communication (EEP operation)
1	1	DB6.6	-	Not used
2		DB6.5 DB6.4	0b00	Request not accepted, general reason
" "		п п	0b01	Request accepted, teach-in successful
" "	" "	п п	0b10	Request accepted, deletion of teach-in successful
" "	11 11	" "	0b11	Request not accepted, EEP not supported
4		DB6.3 DB6.0	0x1	Command identifier (CMD) / 0x1: EEP Teach-In Response
8	_	DB5.7 DB0.0		Same structure as Teach-In Query message (EEP, MID and channel of requesting device is echoed back)



3.7) Smart Ack: functional principle (without repeater)



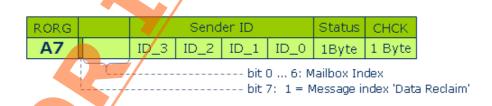
Smart Ack is a bidirectional communication protocol between a self-powered device and a line-powered controller. Data transmission in both directions is controlled by the sensor/client, as the limited energy budget requires an exact synchronization of the sent and the received messages. This pre-defined time interval allows a very short activation of the energy-intensive receiver electronics on the client.

If the teach-in procedure has already taken place as in Chapter 'Smart Ack Teach-in procedure' and the two devices already 'know each other', communication always takes place as following under Smart Ack:

The client sends its message over a VLD telegram to the controller (Manufacturer ID = optional).

VLD								
RORG	Manufacturer ID	Variable data		Send	er ID		Status	CRC8
D2	1,5 byte	1 12,5 bytes	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

Finally, the message is processed in the controller, or forwarded to an external micro-controller over the serial interface for each use case. During the intervening period, the client is in the 'response period', which is frequently connected to an energy saving measure (like 'Short Term Sleep'). The length of this time period is agreed during the teach-in procedure between the devices as 'response time'. The feedback defined for the client is deposited in the mailbox of the postmaster (PM). When the client is active again, it requests this message containing the Smart Ack telegram DATA_RECLAIM from the responsible postmaster.

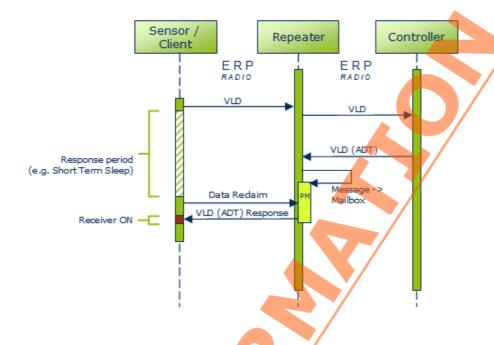


Finally, the receiver part of the client is activated and the message sent by the postmaster is accepted. In this case the VLD telegram is sent encapsulated as ADT telegram (= addressed).

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RORG	RORG-EN	Manufacturer ID	Variable data	ariable data Destination ID				Sender ID					us	CRC8
A6	D2	1,5 byte	1 7,5 bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 6	yte	1 byte

3.8) Smart Ack: functional principle (with repeater)



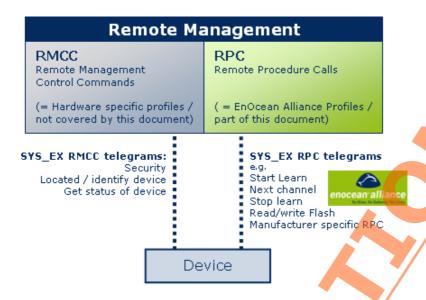
If a repeater is used, it takes over the task of the postmaster after the teach-in procedure. Hence, the client cannot view under operating conditions whether it is communicating directly with a controller or with a repeater.

The VLD telegram of the client is forwarded by the repeater 1:1 in the direction of the controller. The feedback is transferred in the form of an addressed telegram (containing Repeater ID) to the postmaster of the repeater and stored in the mailbox.

The client then turns to the repeater with its 'Data Reclaim', instead of turning to the controller, and requests the response message from the postmaster.

3.9) Remote Management / RPC

Remote Management allows EnOcean devices to be configured and maintained over the air or via a serial interface. For instance sensor or switch IDs can be stored or deleted from already installed actuators or gateways that are hard to access. There is a remote management library available for Dolphin based products.



Remote management is divided into two function groups:

RMCCs are mandatory features; they are permanently defined and they have overlapping tasks. They cannot be modified devicespecifically and are therefore, not an integral part of this description.

RPCs cover optional and manufacturer-specific features, and they have a flexible number of functionalities that can be used for numerous devices. If new device properties are mapped, RPCs can be extended correspondingly. To keep the RPCs interoperable, it is in the interest of the EnOcean Alliance to standardize these procedures.

The RPCs available today with their SYS_EX structures do not have any data-technical commonalities with EEP, but are to be handled the same way in future within the framework of coordination measures.

Structure of SYS_EX for RPC

SYS_EX telegrams for RPCs are generally encapsulated in an ADT telegram (RORG = A6) and are sent addressed as such.

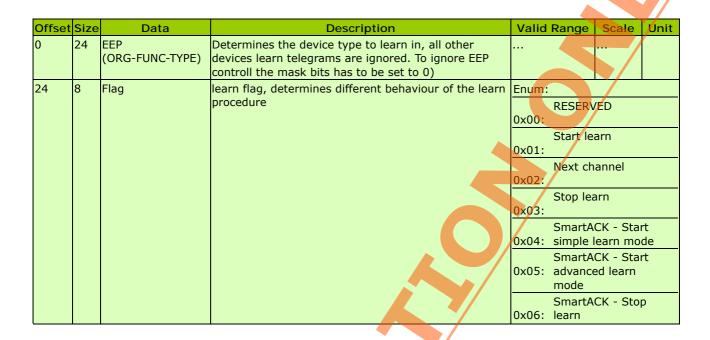
ADT / 8	SYS_EX	/ RF	C											
RORG	RORG-EN			SYS-EX data		Destination ID				Send	Status	CRC8		
A6	C5			x bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

In the following section the SYS_EX data is described in detail. Note that Remote Management RPC commands are composed of several telegrams. That means SYS_EX data is than merged in one data block. The next section describes this datablock in detail.

For further details refer to the specification Remote Management, V1.7, Dec 16, 2010, released by EnOcean GmbH www.enocean.com/fileadmin/redaktion/pdf/tec_docs/RemoteManagement.pdf, please.

Title	RPC - Remote learn
Function code	0x201

Manufacturerid	0x7FF
Datalength	0x04
Broadcast	YES
Addressable	YES
Answer	NO



Title	RPC - Remote flash write
Function code	0x203
Manufacturerid	0x7FF
Datalength	0x04 + N
Broadcast	YES
Addressable	YES
Answer	NO

Using this command the flash of a device can be written.

Offset	Size	Data				Description
0	16	Flash Memory Address	De	stinatio	n v	here the data should be stored
16	16	Number of Bytes	Nu	mber c	f by	ytes to be transfered and written to the flash
32	N*8	Data	dat	a to b	tra	ansfered and written to the flash

Title	RPC - Remote flash read
Function code	0x204
Manufacturerid	0x7FF
Datalength	0×04
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the flash can be read from the application. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash

Title	RPC - Remote flash read answer
Function code	0x804
Manufacturerid	0x7FF
Datalength	N
Broadcast	NO
Addressable	YES
Answer	NO

Offset	Size	Data	Description
0	N*8	Data	data read from flash

Title	RPC - SmartACK read settings
Function code	0x205
Manufacturerid	0x7FF
Datalength	1
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the SmartACK settings and learn tables can be read from the device. The Setting type filled determines what type of data is requested. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description	Valid Range	Scale	Unit
0		_	read	Enum: RESERVED 0x00: Mailbox settings 0x01: Learned sensor - read the ID 0x02: Controller	table of sensors i	n the

Title	RPC - SmartACK read settings - Mailbox settings answer
Function code	0x805
Manufacturerid	0x7FF
Datalength	4
Broadcast	NO
Addressable	YES
Answer	NO

Offset	Size	Data	Description
0	16	SmartACK flash address	Address where the SmartACK settings are stored
16	16	SmartACK mailbox count	number of mailboxes stored in flash

Title	RPC - SmartACK read settings - Learned sensor answer
Function code	0x806
Manufacturerid	0x7FF
Datalength	N*9
Broadcast	NO
Addressable	YES
Answer	NO

N - is the number of entries: SensorID, ControllerID, LearnCount

Offset	Size	Data
N*0	32	SensorID
N*32	32	ControllerID
N*64	8	Learned Count

Title	RPC - SmartACK write settings
Function code	0x206
Manufacturerid	0x7FF
Datalength	10
Broadcast	NO
Addressable	YES
Answer	YES

Using this command different type of data can be transmitted to the SmartACK devices. This command is useful when the SmartACK device has to be configured remotely. The structure of the data transmitted is depends on the Operation Type field.

Operation Type = 0x01: Add mailbox (only controller)

Offset	Size	Data	Value	Description
0	8	Operatian Type	0x01	Add mailbox (only controller)
8	8	Mailbox Index		
16	32	SensorID		
48	32	PostmasterID		

Operation Type = 0x02: Delete mailbox

Offset	Size	Data	Value	Description
0	8	Operation Type	0x02	Delete mailbox
8	8	Mailbox Index		
16	64	Not Used (= 0)		

Operation Type = 0x03: LearnIn - only controller

Offset Size Data Value Description	on
0 8 Operation Type 0x03 LearnIn - only co	ontroller
8 8 Learn Count	
16 32 SensorID	
48 32 ControllerID	

Operation Type = 0x04: LearnOut - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x04	LearnOut - only controller
8	8	Learn Count		
16	32	SensorID		
48	32/	ControllerID		
	7/	•		

3.10) Interoperability with Security of EnOcean Networks

The Specification "Security of EnOcean Networks" defines two new telegram types for secure EnOcean telegrams in operational mode:

- R-ORG = 0x30 = SEC <u>Secure telegram</u>
- R-ORG = 0x31 = SEC_ENCAPS Secure telegram with R-ORG encapsulation

To make sure that interoperability is warranted, both telegrams may used for telegram transmission with existing EEP's. Because the profile of the device is known, the data of the SEC or SEC_ENCAPS telegram contains the same information as described in the profile, but it may be encrypted defined by the SLF (Security level format) of the device. When the device uses more than one R-ORG's in operational mode, the SEC_ENCAPS telegram has to be applied to ensure the correct original R-ORG after converting from secure to unsecure telegram. At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

Example for converting a telegram from unsecure to secure and back:

Unsecure:	4BS	Data of profile	TX-I	D Sta	atus Ch	k/	
Secure:	SEC	Encrypted Data of profile	RLC	CMAC	TX-ID	Status	Chk
Unsecure:	NON SEC	Data of profile	TX-I	D Sta	atus Ch	k	

The data of the known profile will be applied in the unsecure telegram after the conversion from secure to unsecure telegram.

Example for converting a telegram from unsecure to secure and back with encapsulated R-ORG:



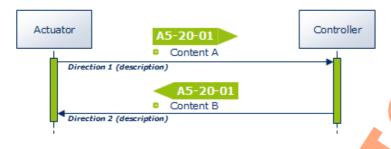
After conversion from secure to unsecure telegram, the encapsulated R-ORG will be applied in the telegram. The data of the profile of the encapsulated R-ORG will be applied.

3.11) Existing 'bidirectional' profile structures

At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

The original terminology 'transmit mode / receive mode' was not taken over, as no unique assignment to device type and hence to transmission direction can be derived there from. A neutral number (Direction 1 / 2) or the state of a bit should allow the required free space to the individual application.

Variant 1:



In Variant 1, there is no data-technical differentiation option in the 4BS telegram between Direction 1 and Direction 2, but only a documentation-related direction specification. No transmission direction can be detected if the telegrams are monitored on the radio stretch.

Variant 2:



In Variant 2, 3 bits are provided in the 4BS telegram, which allow up to 8 different data interpretations of the same EEP Profile No. through bit combination. 1 bit is used for direction (with the instruction text 'message source') and 2 bits for the Message ID.

Variant 3:



In Variant 3, the Smart Ack technology normally offers multiple use options of bidirectional data transmission. Smart Ack clients can therefore be energy self-sufficient devices. The used VLD telegrams allow a payload of up to 14 bytes (12.5 bytes with Manufacturer ID). Contents can thus be structured more individually.



3.12) MSC telegram - Manufacturer Specific Communication

Communication over MSC telegrams can always be used when bigger data volumes are to be transmitted, and at the same time, a closed system structure is to be created. This can be the case if e.g., the controller system backbone is expanded to include radio components, or if safety-related controls require proprietary data structures.

Such communication must not affect any interoperable EEP-based communication and should be identifiable as MSC by any Dolphin-based hardware.

Interoperability Conditions:

A device using MSC in addition to other EEPs may be marked with the EnOcean ingredient logo, as long as it complies with the rules defined by the EnOcean alliance for such markings. A device using MSC may be marked with the EnOcean ingredient logo even though the manufacturer does not disclose any or all information regarding the MSC payload. However, all other functionality of such a device shall comply with the latest EEP specification and such a device shall support at least one additional EEP. The manufacturer must clearly state which EEP(s) the device complies with. To safeguard interoperability, if there is sufficient justified doubt within the EnOcean Alliance TWG, a specific unit using MSC can be assessed by the TWG and if found to breach the interoperability intentions, the TWG may then decide (majority vote) to adapt the rules for the usage of the interoperability logo.

The MSC telegram has the same structure as a VLD telegram. The only difference is that the RORG Number is different and the payload specification is missing.

15	180									
	RORG	Manufacturer ID	Variable data			Send	er ID		Status	CRC8
	D1	1,5 byte	1 12,5 bytes		ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

The following points are to be noted:

- 1. The usage of the Multi User Manufacturer ID (0x7FF) shall not be allowed.
- 2. Each user may send MSC telegrams under his own Manufacturer ID. The Manufacturer ID should not be left out.



3.13) Manufacturer ID's

This chapter was transferred into a separate document entitled EnOcean Manufacturer Identification (ManID). This document will be updated as soon as a new ManID will be allocated to a member of the EnOcean Alliance. The document EnOcean Manufacturer Identification (ManID) is stored in the webspace of the TWG on http://portal.enocean-alliance.org/MyWorkGroups/Documents.aspx (access only for registered members of the TWG).

3.14) XML + DOC Maintenance process

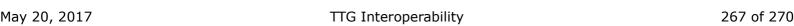
3.14.1) General

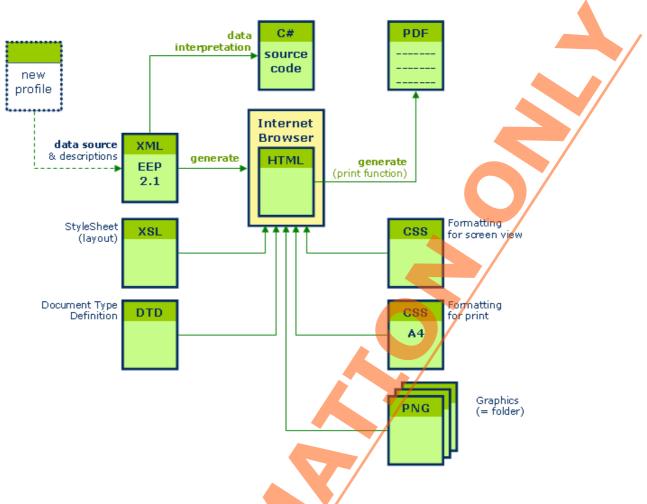
The maintenance process is descripted separately in the document: EEP2x Maintenance Process.pdf.

3.14.2) XML file

With EEP 2.1, a new type of documentation is introduced, which can also display logical structures next to the described contents. These can be adapted by developers into their programming environment.

XML is fully compatible with applications like C# or JAVA, and it can be combined with any application which is capable of processing XML irrespective of the platform it is being used on. If the application can work alongside XML, then XML can work on any platform and has no boundaries. It is also vendor independent and system independent.





Only the XML data is edited and released in defined time intervals as a total release under a new version. A styles sheet file (XSL) and formatting specifications (CSS) ensure that an attractive HTML representation is possible in an internet browser. The author of the new version also creates a final PDF file.

This method ensures that the document view, as well as the software environment, remain synchronized. Errors are strongly reduced and data maintenance is optimized.



3.15) Revision

Rev.	Date	Editor	Major Changes
0.10		GT	Initial EnOcean Alliance Version created, based on the EnOcean GmbH document 'Standardization EnOcean Communication Profiles_v1.04'
0.90			EEP for ORG = 0x05 added EEP for ORG = 0x06 added Headlines and Text formatted
0.91			FUNC = 11 "Controller Status" added Proposals added: EEP 07-11-01 "Lightning Controller" (EchoFlex) EEP 07-02-0C "Temp.Sensor, Window Contact" (EchoFlex) EEP 07-10-0A "Temp. Sensor, Set-Point Adj., Window Contact" (EchoFlex) EEP 07-30-02 "Window Contact, Single Input" (EchoFlex)
0.92			Manufacturer ID: Guidelines added. Definitions updated Revision History moved to a separate document chapter INPUT document for Berlin Meeting April 2009
2.0R			EEP 07-02-0C shifted to Room Operating Panels -> EEP 07-10-0B EEP 06-00-00 renamed to 06-00-01 EEP 05-xx-xx (PRS telegram / PTM200) updated with results of latest discussions EEP 05-04-01 (Key Card Activated Switch) updated Proposals Added: EEP 07-10-0C "Temp. Sensor, Occupancy Control" (Termokon) EEP 07-10-0D "Temp. Sensor, Day/Night Control" (Termokon) Ratification info and period added
	July 2009		Creation of final Version V2.0 EEP 05-03-02 added EEP 05-04-01 corrected EEP 06-00-01 renamed Single Input Contact EEP 07-10-0A and EEP 07-10-0B updated Single Input Contact EEP 07-30-01 and EEP 07-30-02 updated Single Input Contact 4BS teach in Telegram updated FUNC /TYPE Editorial corrections
R1	Nov 12, 2010		The EEP 2.0 document as well as all 2.1 single documents were transferred to an XML data structure and standardized. The following chapters were re-written: Introduction, Teach-in, Bi-directional profiles, Smart Ack, RPC and MSC. Profiles that are still being coordinated were also accepted. These are characterized as 'Not approved' in the document. Bidirectional profiles are labeled with 'BI-DIR'. RPS ORG 05 = RORG F6; 1BS ORG 06 = RORG D5; 4BS ORG 07 = RORG A5
R2	Dec 31, 2010		2th review
2.1	Jan 20, 2011	Ор	Final version V2.1
R1	May 20, 2012		Review version 1 Added profiles: - 1 RPS: F6-02-03 - 16 4BS: A5-07-02, A5-09-02, A5-09-05, A5-09-06, A5-09-07, A5-10-1F, A5-11-03, A5-11-04, A5-14-01, A5-14-02, A5-14-03, A5-14-04, A5-14-05, A5-14-06, A5-38-08 CMD 0x07, A5-38-09 - 15 VLD: D2-01-0011, D2-01-0002 Updated profiles: A5-07-01, A5-09-01, A5-09-04 Further: - Description: UTE - Universal Uni- and Bidirectional Teach-in - RPC function no. added - Manufacturer ID's added
R2	Nov 08, 2012	Op	Review version 2 Significant changes: - Chapter 1.3 - Add new profiles: A5-06-03, A5-07-03, A5-13-07
	Feb 03, 2013	Ор	- Update of profiles: A5-10-15, A5-10-16, A5-10-17, A5-13-01, A5-13-05 Significant changes: - Add new profiles: D2-03-00, D2-20-00, D2-20-01, D2-20-02 - Update of profiles: A5-07-02, A5-13-02, D2-01-00 - Deleted Chapter 'Manufacturer ID's'

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	March 04, 2013	Ор	FINAL version 2.5
-	Nov 26, 2013	Ор	Review version
	Dec 17, 2013	Ор	FINAL version 2.6
	Apr 15, 2014	Ор	Review version
	Apr 27, 2014	Ор	2nd review version / contains EnOcean checking
	Jun 04, 2014	Ор	FINAL version 2.6.1
	Oct 15, 2014	Ор	Review version
2.6.2	Nov 19, 2014	Ор	FINAL version 2.6.2
2.6.3 R1	May 03, 2015	Ор	Review version
2.6.3 R2	May 19, 2015	Ор	2nd Review version: - New: A5-09-0A, A5-09-0B - Modified: A5-30-06 (previous A5-0B-01) submitter, encryption, security, graphic of case 2 - Modified: D2-32-xx Enum structur
2.6.3	Jun 08, 2015	Ор	FINAL version 2.6.3 - Removed: A5-30-06 (withdrawn profile)
	Oct 13, 2015	Ор	Review version
2.6.4	Dec 17, 2015	Ор	FINAL version 2.6.4
	Apr 07, 2016	Ор	Review version
2.6.5	May 02, 2016	Ор	FINAL version 2.6.5
	Oct 16, 2016	Ор	Review version
2.6.6 R2	Nov 09, 2016	Ор	2nd review version
2.6.6		Ор	3th version
2.6.6		Ор	FINAL version 2.6.6
		Ор	Review version
2.6.7		Ор	FINAL version 2.6.7