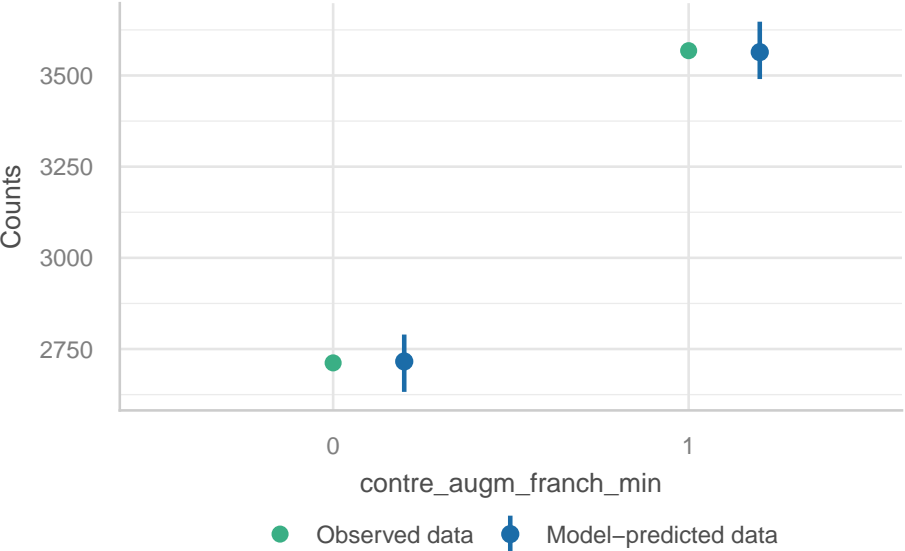
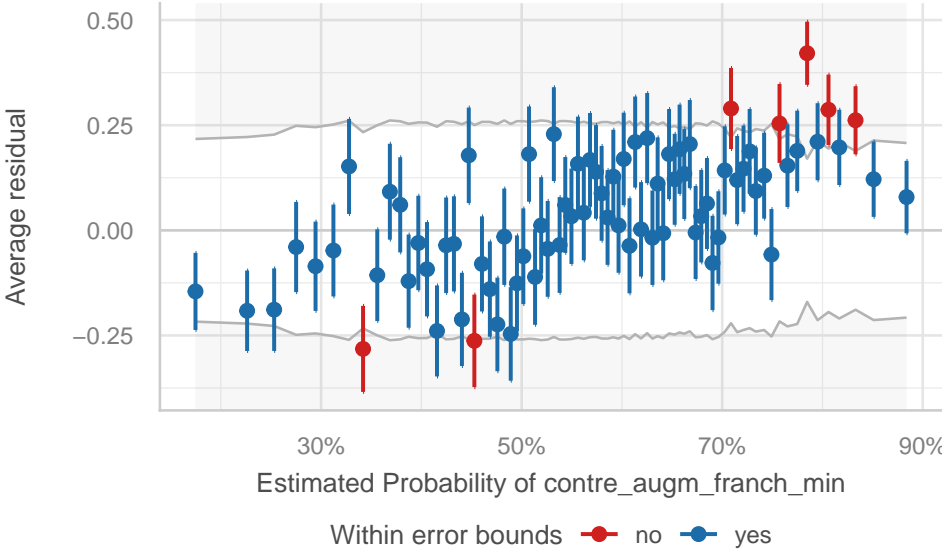


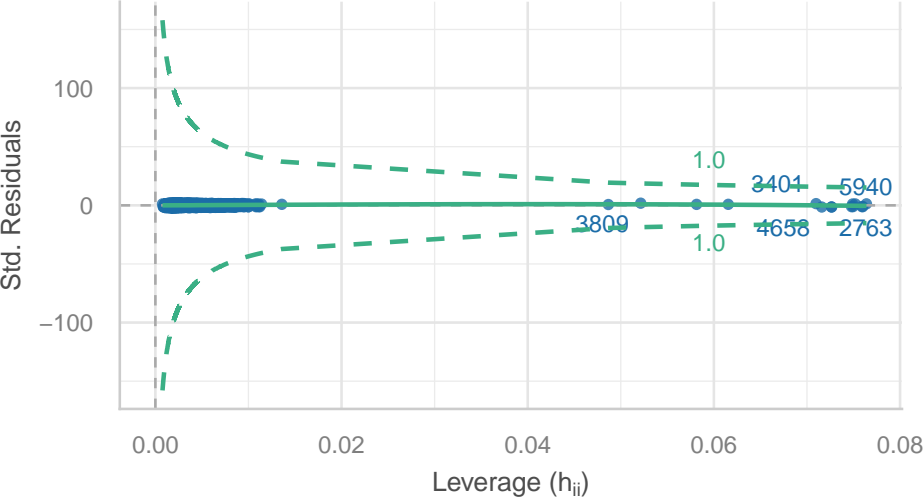
Posterior Predictive Check  
Model-predicted intervals should include observed data points



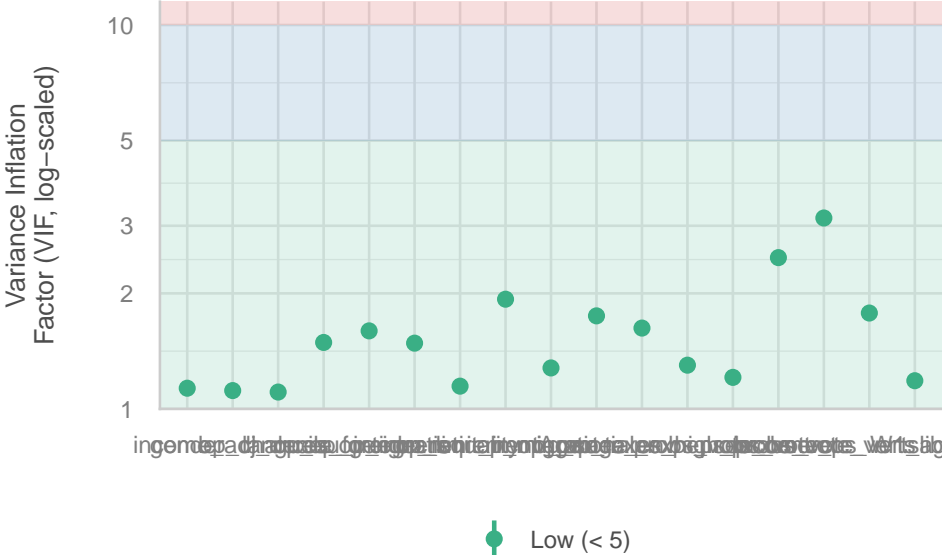
Binned Residuals  
Points should be within error bounds



Influential Observations  
Points should be inside the contour lines



Collinearity  
High collinearity (VIF) may inflate parameter uncertainty



Distribution of Quantile Residuals  
Dots should fall along the line

