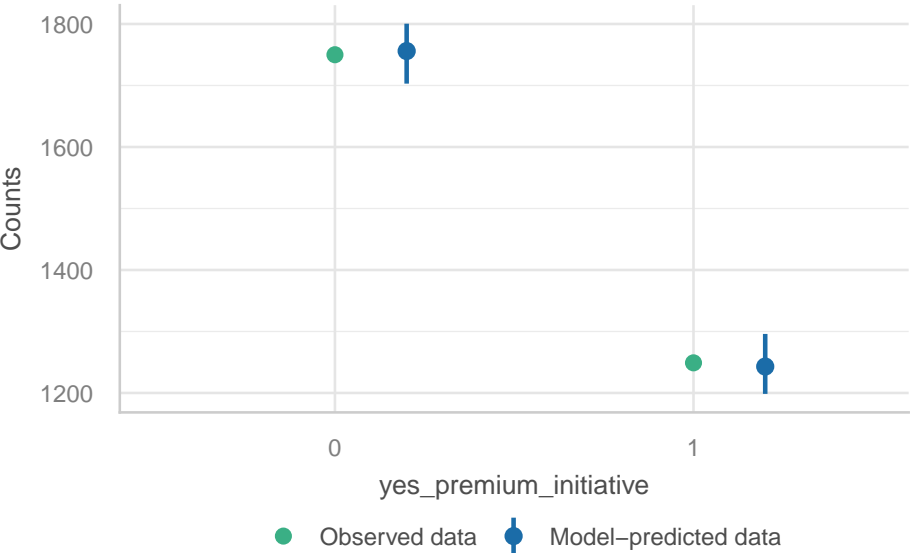
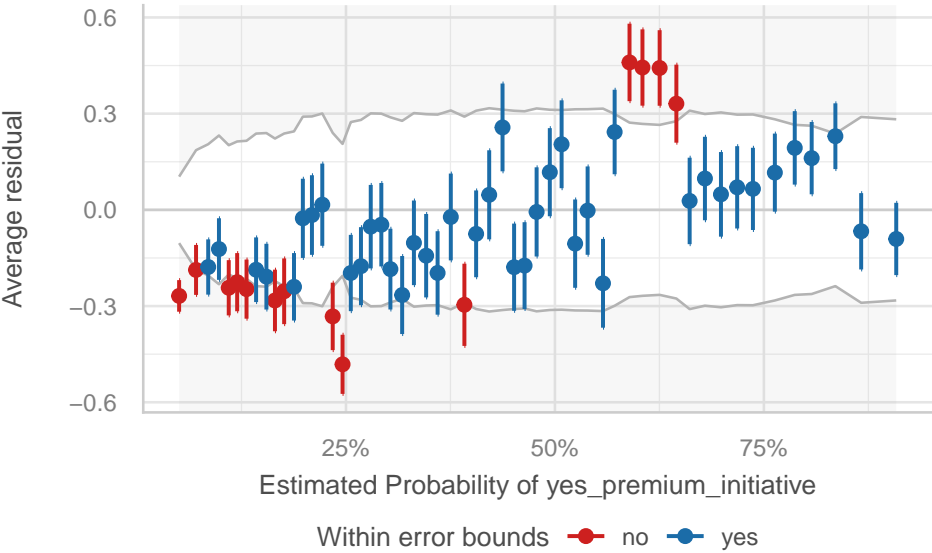


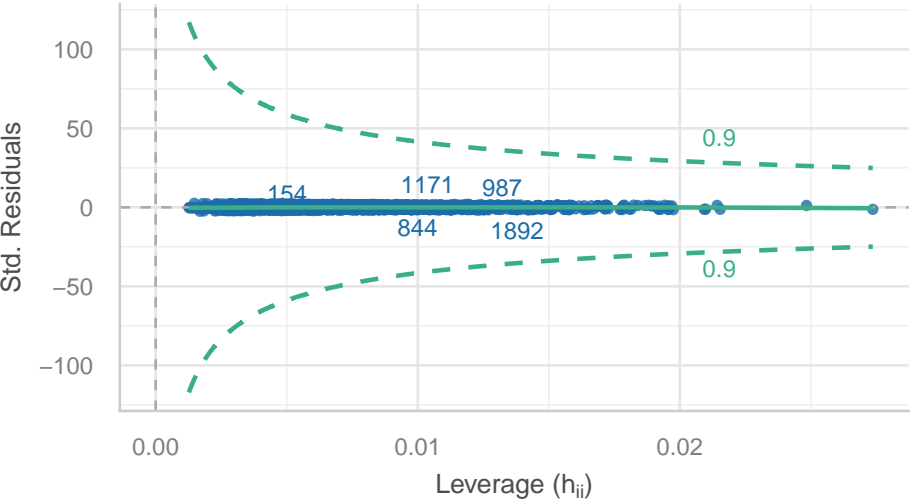
Posterior Predictive Check
Model-predicted intervals should include observed data points



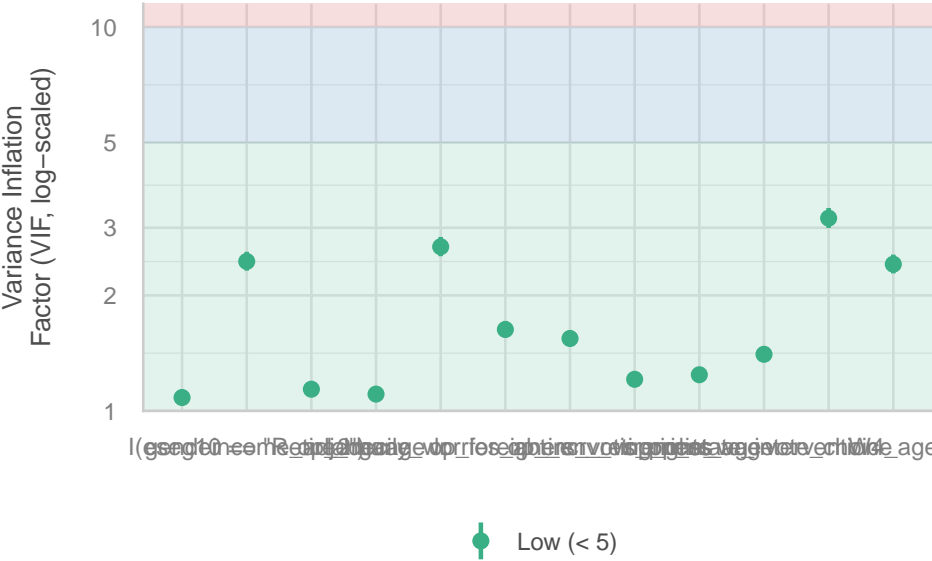
Binned Residuals
Points should be within error bounds



Influential Observations
Points should be inside the contour lines



Collinearity
High collinearity (VIF) may inflate parameter uncertainty



Distribution of Quantile Residuals
Dots should fall along the line

