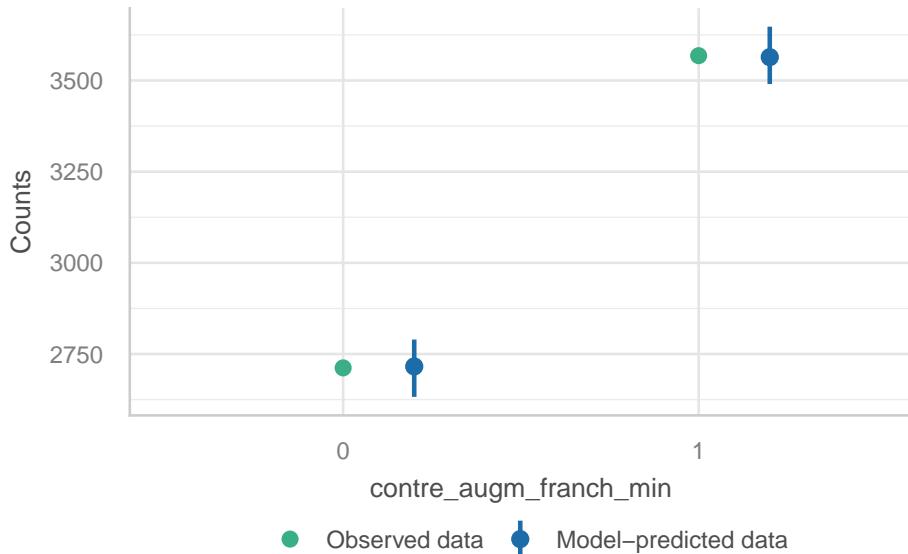


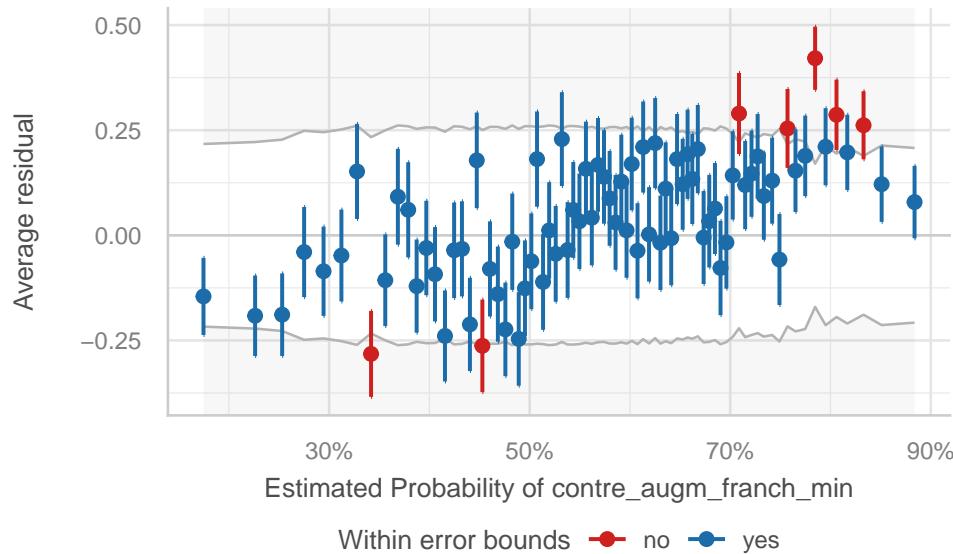
Posterior Predictive Check

Model-predicted intervals should include observed data points



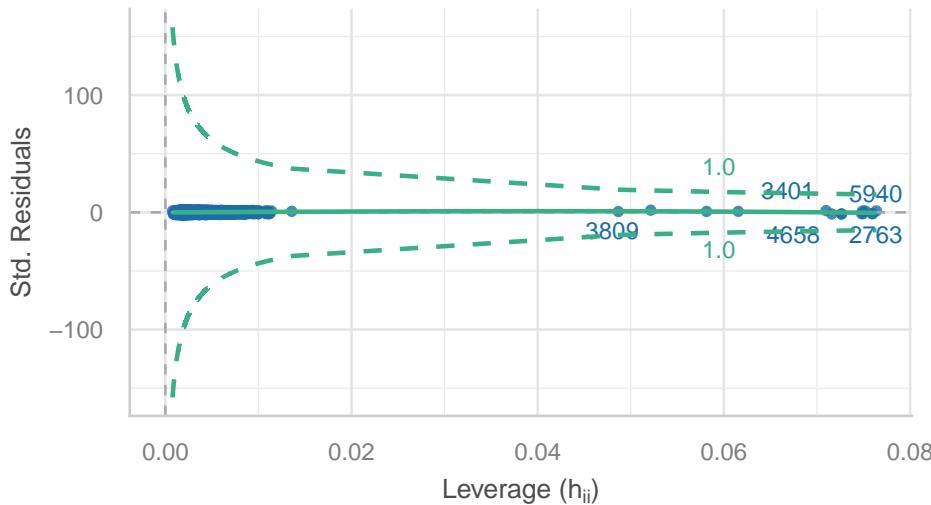
Binned Residuals

Points should be within error bounds



Influential Observations

Points should be inside the contour lines



Collinearity

High collinearity (VIF) may inflate parameter uncertainty

