

[SWE2015-41] Introduction to Data Structures (자료구조개론)

Heap

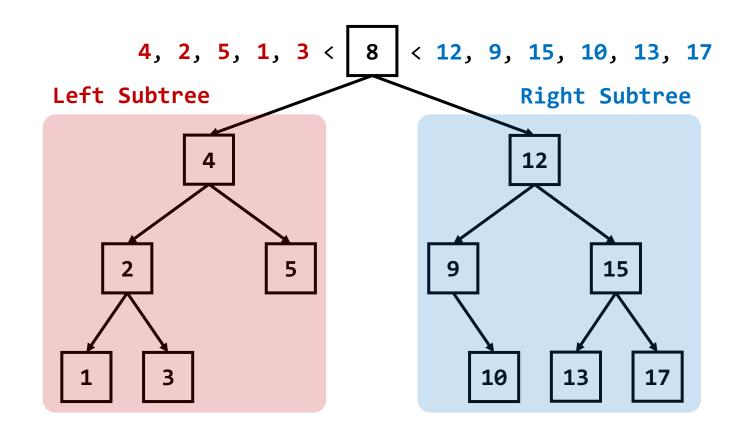
Department of Computer Science and Engineering

Instructor: Hankook Lee (이한국)

(Recap) Binary Search Trees (BSTs)



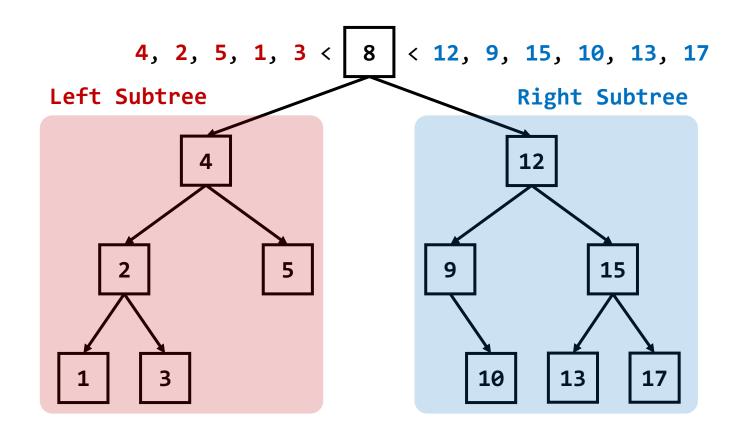
- Binary Search Trees (BSTs) are efficient for search, insertion, deletion, ...
 - Due to the relationship between root, left subtree, and right subtree



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 - But its implementation is complicated ... (e.g., AVL & Red-Black trees)



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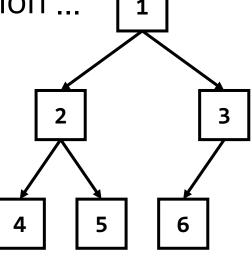
There are other options when you don't need search operation ...

• Based on **complete binary trees** which supports ...

- Easy representation (with array)
- 2. Easy access between parent and children (with numbering)

You can use ...

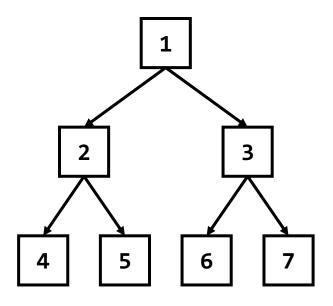
- **Heap** if interested in only the minimum or maximum element
- Segment Tree if interested in statistics (e.g., sum, avg) of segments (intervals)

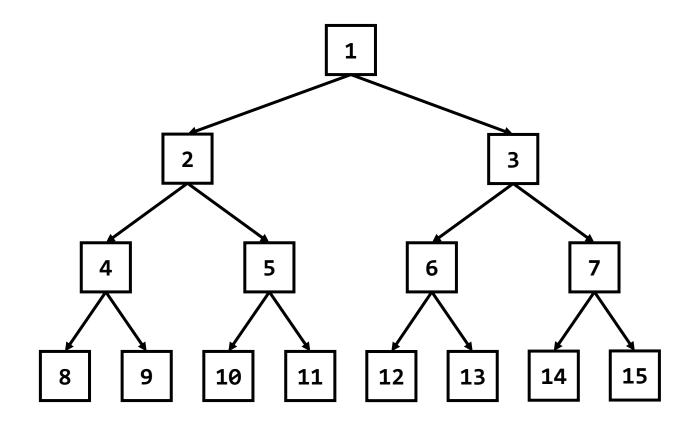


(Recap) Full & Complete Binary Trees



- Full Binary Tree is a BT of height H has $2^H 1$ nodes
 - Node numbering from lower to higher levels, from left to right

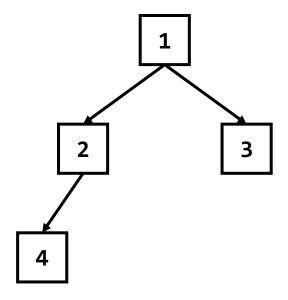


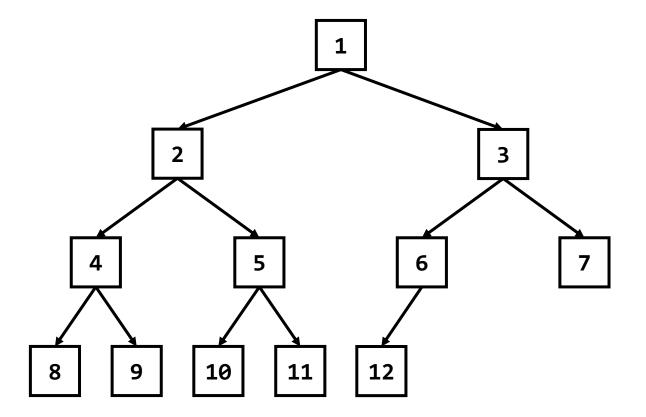


(Recap) Full & Complete Binary Trees



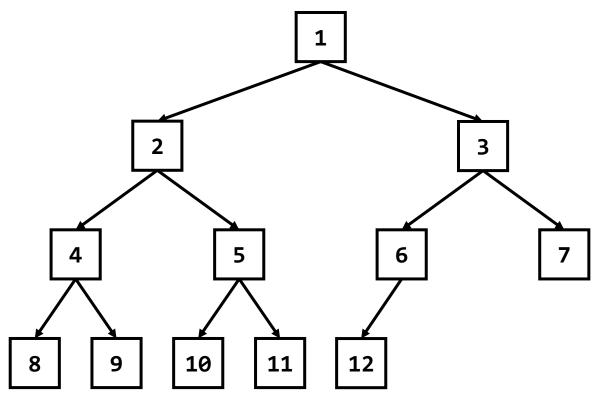
- Complete Binary Tree is a BT satisfying ...
 - All nodes are sequentially filled from lower to higher levels, from left to right
 - The same node numbering to the full binary tree







- The nodes in a complete binary tree are sequentially filled
 - There exists the unique node numbering
 - You can efficiently implement a complete BT using the array structure

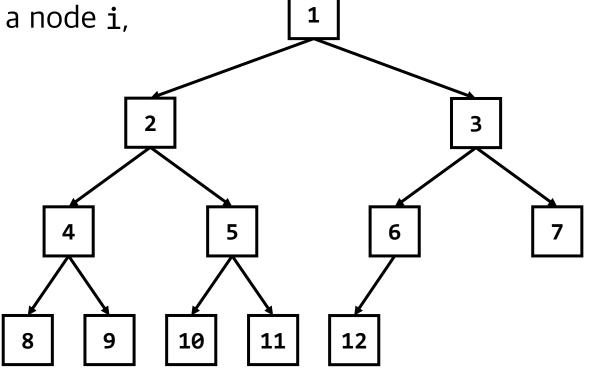




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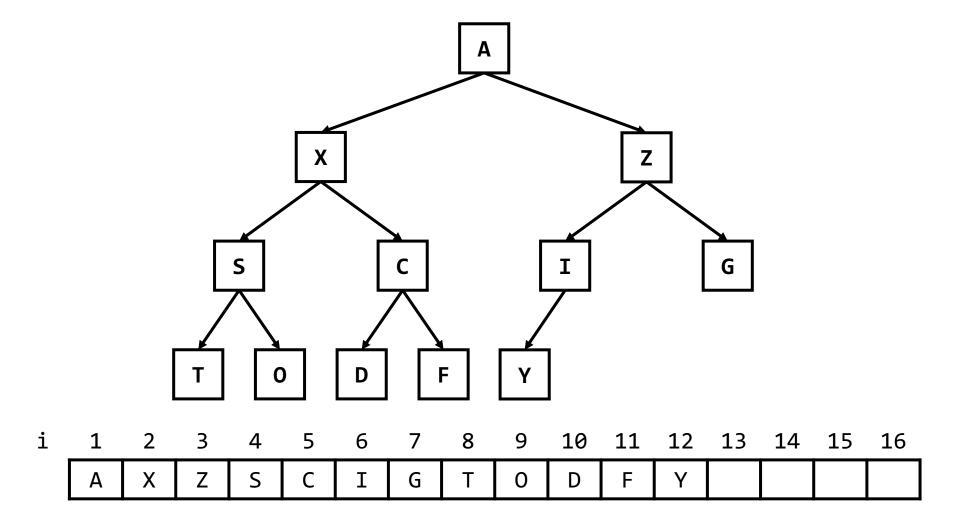
Interesting property of the numbering: for a node i,

- its parent is i/2
- its left child is i*2
- its right child is i*2+1
- You can traverse nodes much easier



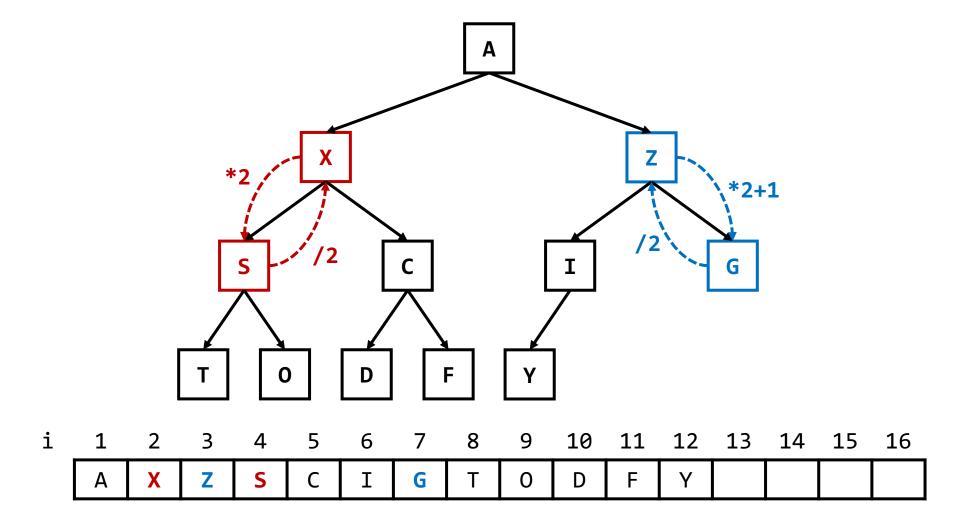


• A complete tree can be represented by an array structure





• A complete tree can be represented by an array structure





- Heap is a complete binary tree satisfying ...
 - Each node has its own **priority** (like key in BSTs)
 - Any node has a higher priority than its children:

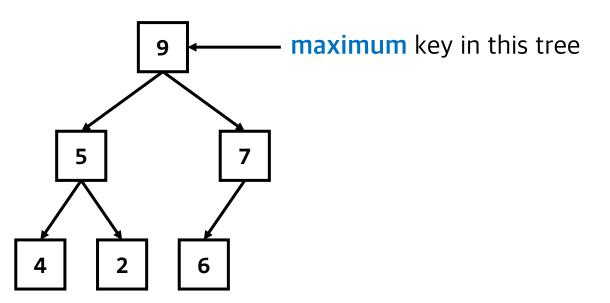
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priority(parent) >= priority(child)
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If a larger key means a higher priority ... (MAX heap)

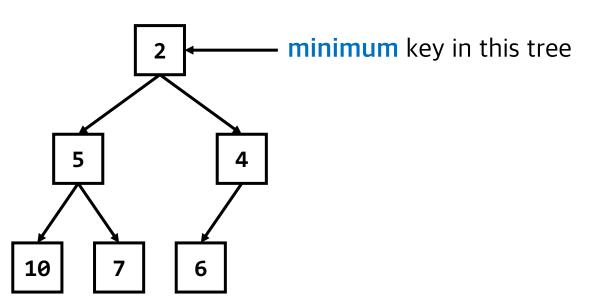




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• If a smaller key means a higher priority ... (MIN heap)





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 - Each node has its own **priority** (like key in BSTs)
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Properties

- The height is $O(\log N)$ where N is the number of nodes
- The root node has the highest priority
 - You can find the most important node in O(1)



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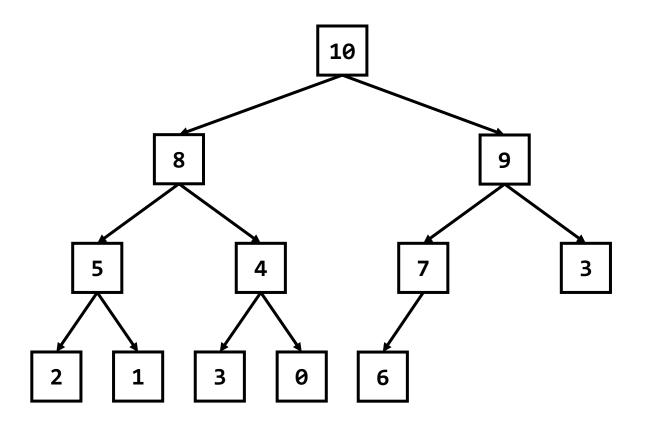
Properties

- The height is $O(\log N)$ where N is the number of nodes
- The root node has the highest priority
 - You can find the most important node in O(1)
- Insertion of a new node has $O(\log N)$ time complexity
- Deletion of the root node has $O(\log N)$ time complexity
- Note. Heap does not support efficient search operation

Examples



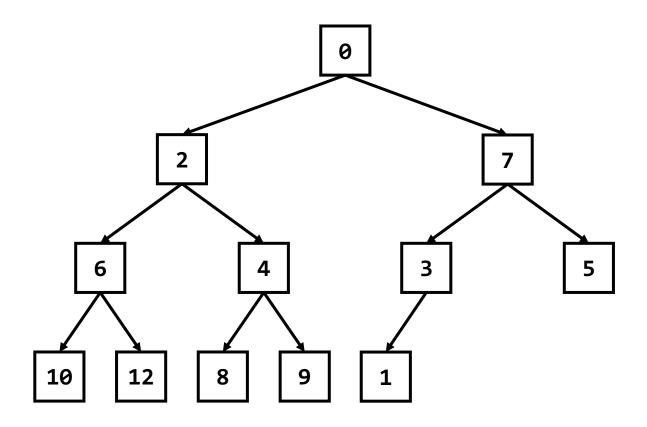
Max heap



Examples



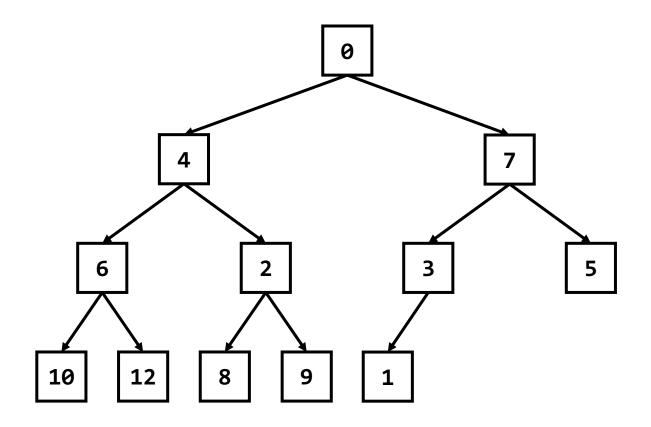
• Min heap



Examples



NOT heap



Heap Operations



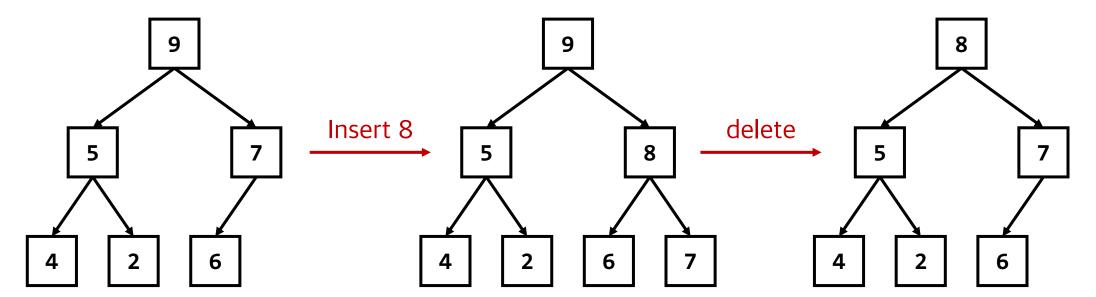
- getFirst find the first (i.e., the most important) element
 - The element is always the root node
 - This is similar to the peek() operation in queue and stack

The most important element

Heap Operations



- getFirst find the first (i.e., the most important) element
 - The element is always the root node
 - This is similar to the peek() operation in queue and stack
- insert insert an element without violating the priority condition
- delete delete the root node without violating the priority condition



Heap Operations

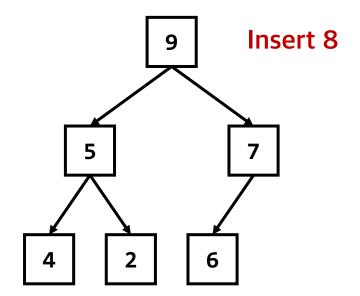


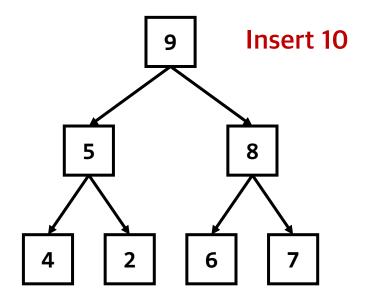
- Recommend using the array-based representation for the heap structure
 - In this lecture, we'll focus on max heap. Min heap implementation is very similar

```
typedef struct MaxHeap {
    int items[MAX_SIZE+1];
    int size;
} MaxHeap;
int getFirst(MaxHeap *heap);
void insert(MaxHeap *heap, int item);
void delete(MaxHeap *heap);
int getFirst(MaxHeap *heap) {
    return heap->items[1]; // node numbering starts from 1
```



• How to insert a new node into the heap?

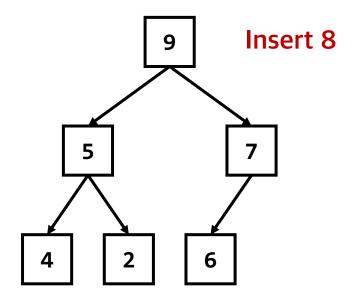


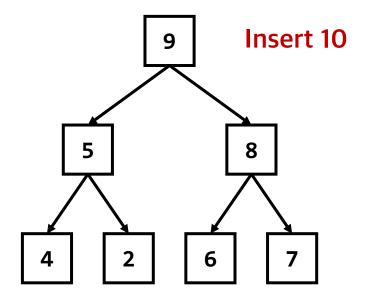




How to insert a new node into the heap?

(Step 1) Insert the node at the last position (i.e., bottom-rightmost)

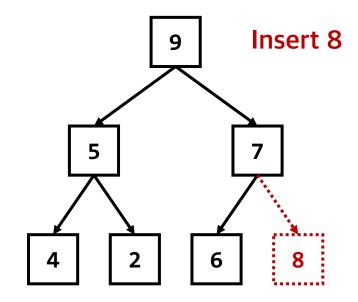


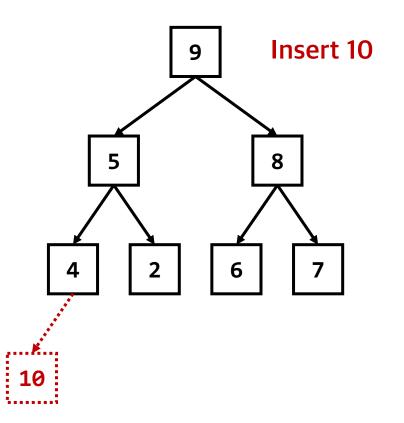




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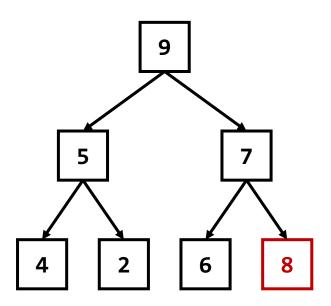






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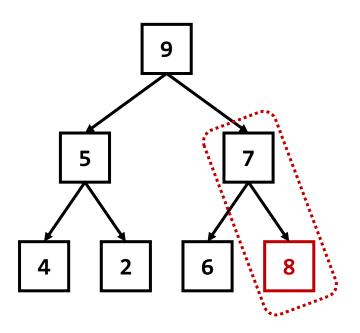
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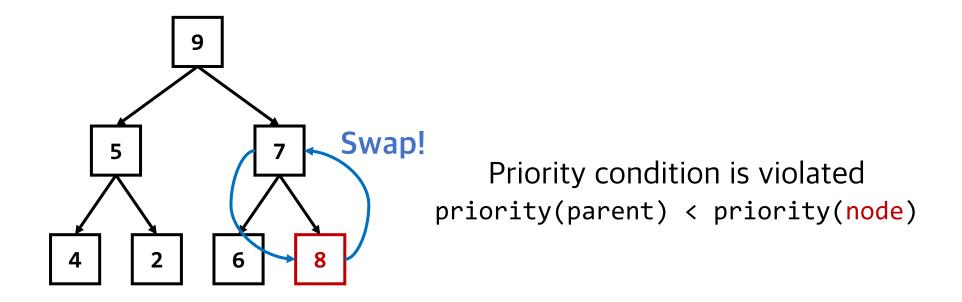


Priority condition is violated
priority(parent) < priority(node)</pre>



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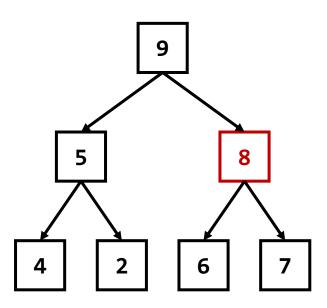
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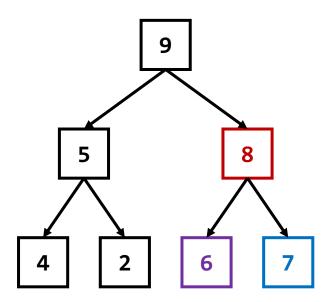
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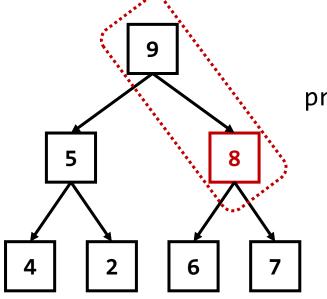
You don't need to compare the **new node** with **another child** (in this case, 6) because the **original parent** (in this case, 7) has a higher priority than **the child**



• How to insert a new node into the heap?

(Step 2) If the new node and its parent violate the priority condition, swap them

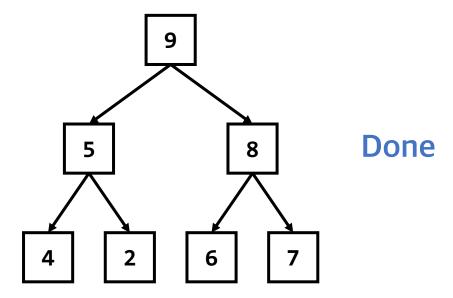
Repeat this step until not violated



Priority condition is not violated
priority(parent) > priority(node)

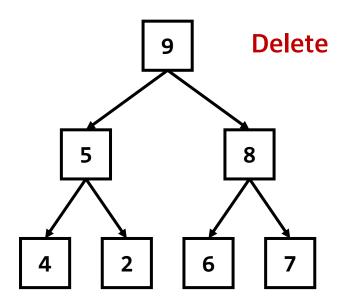


- How to insert a new node into the heap?
 - (Step 2) If the new node and its parent violate the priority condition, swap them
 - Repeat this step until not violated



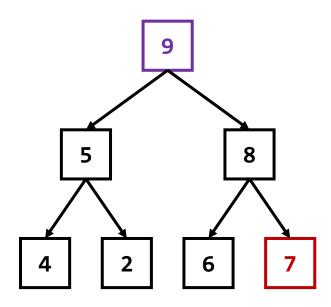


• How to delete the root node?



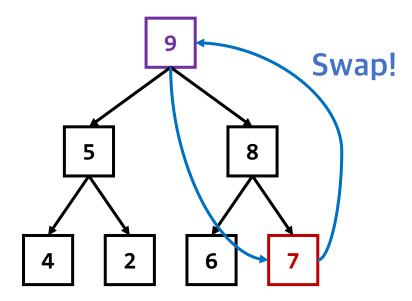


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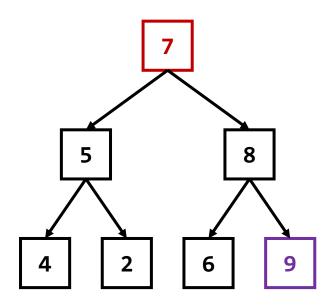


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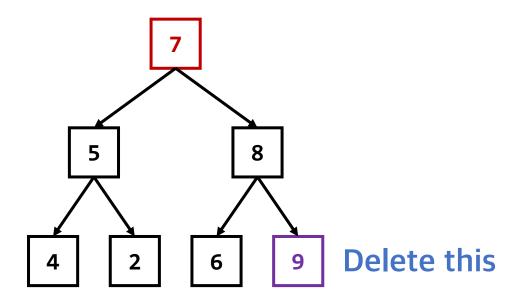


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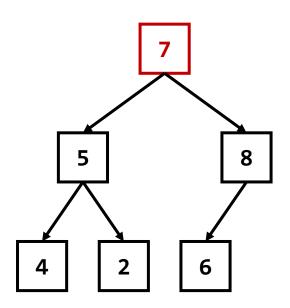
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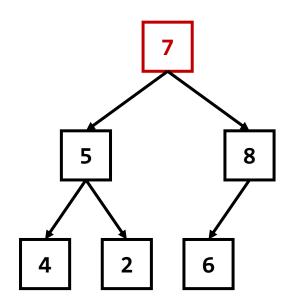
(Step 1) Swap the root node and the last node & delete the root node





How to delete the root node?

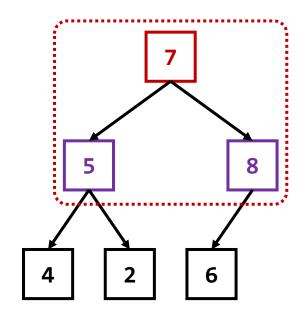
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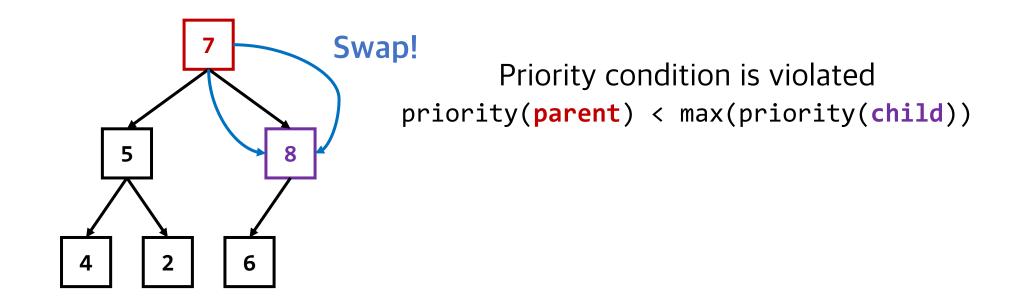
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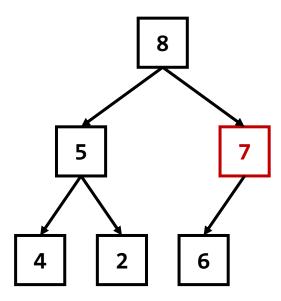
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Swap the last node and the child of the highest priority



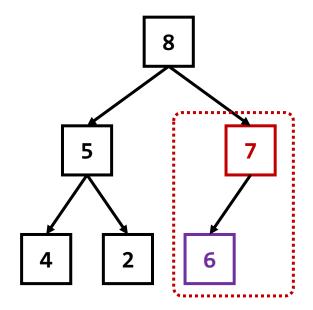


- How to delete the root node?
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 - Swap the last node and the child of the highest priority
 - Repeat this step until not violated





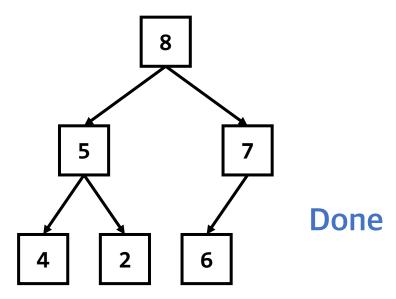
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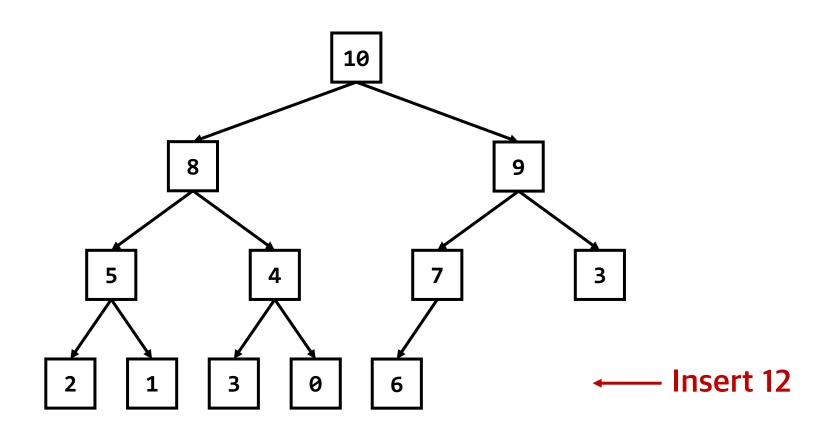
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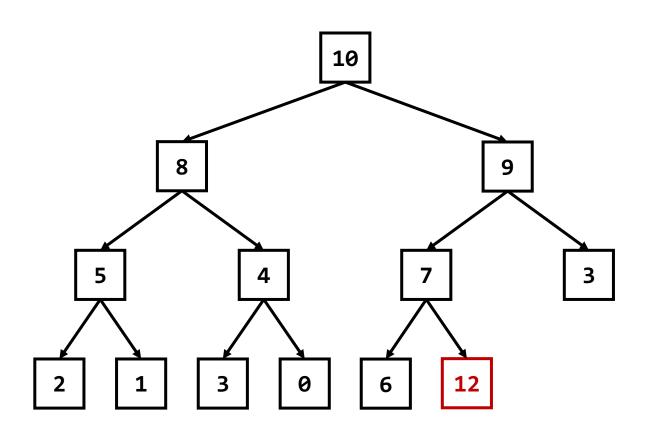
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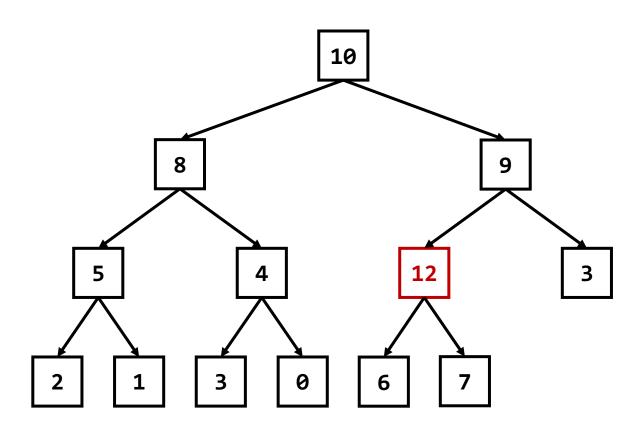




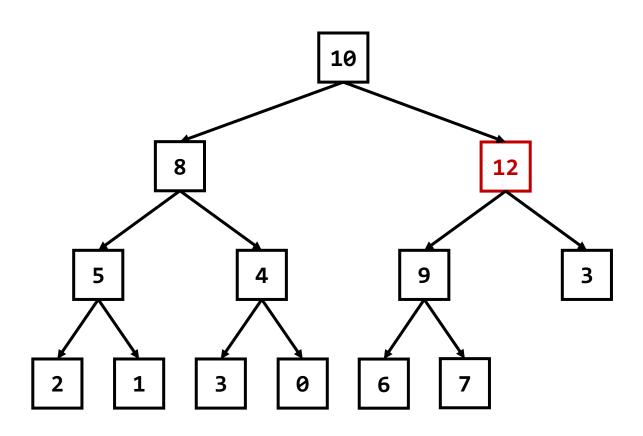




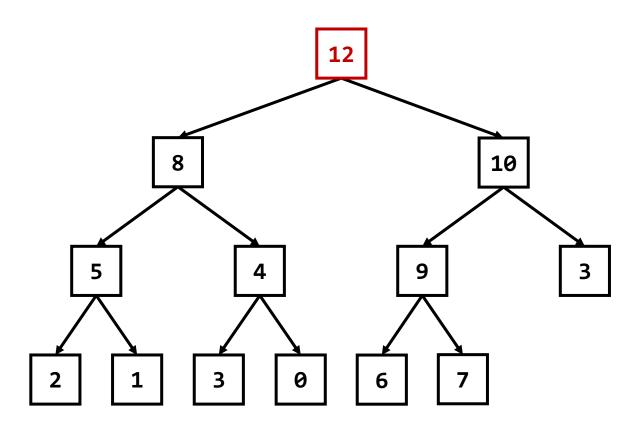




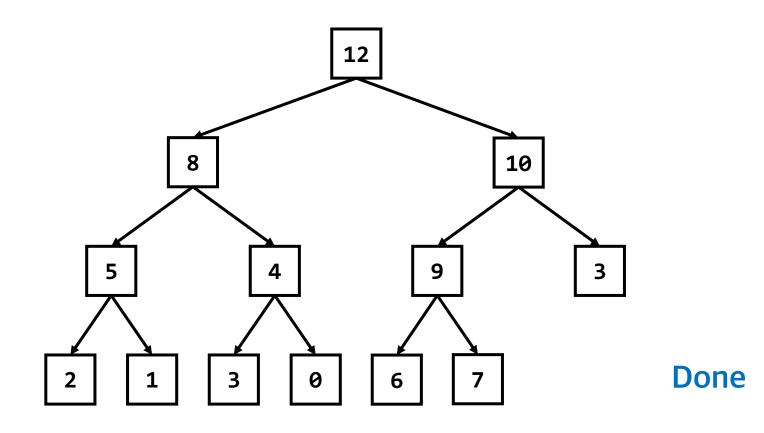




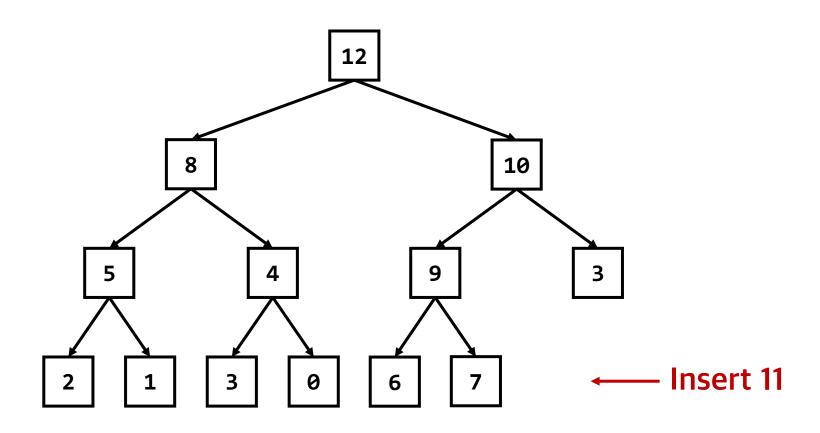




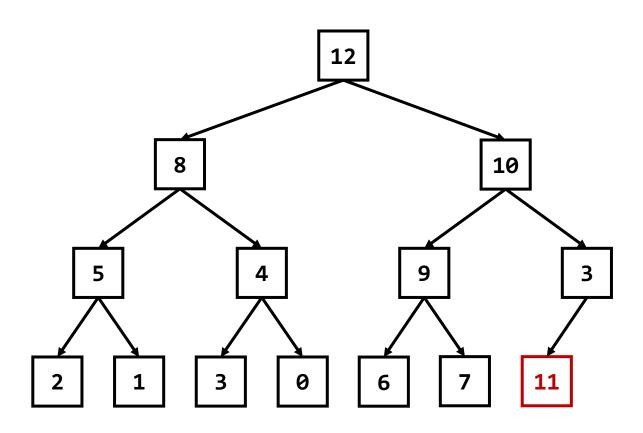




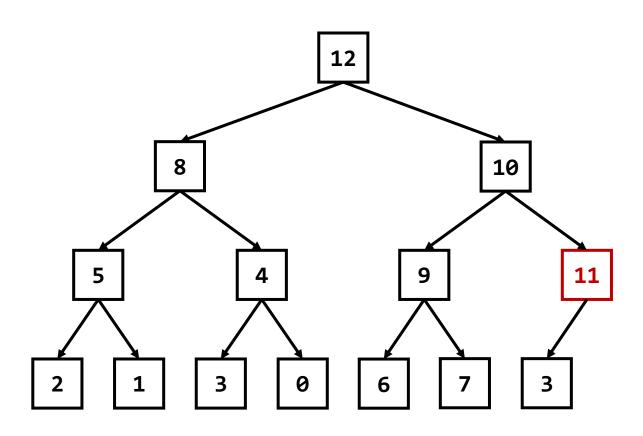




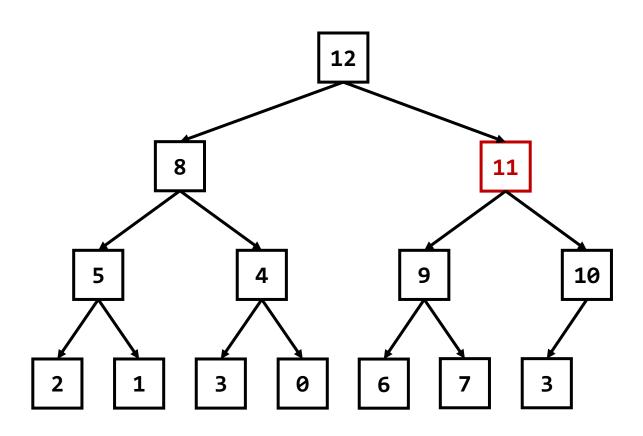




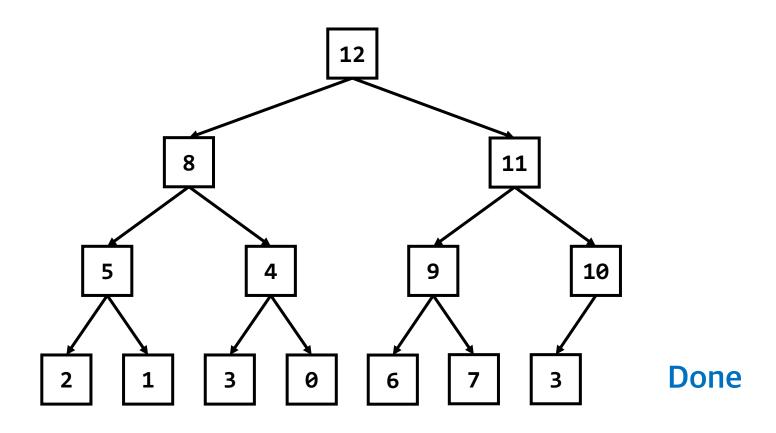




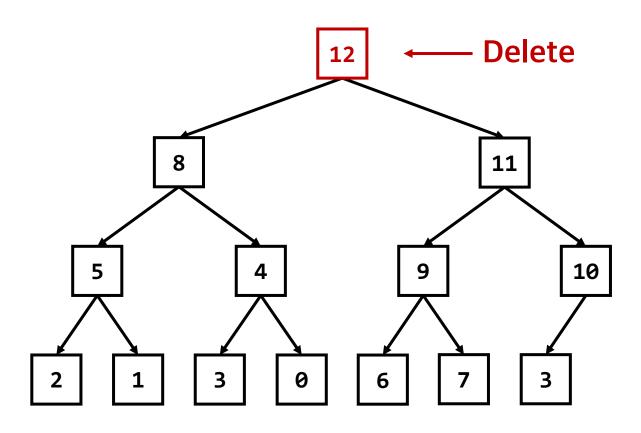




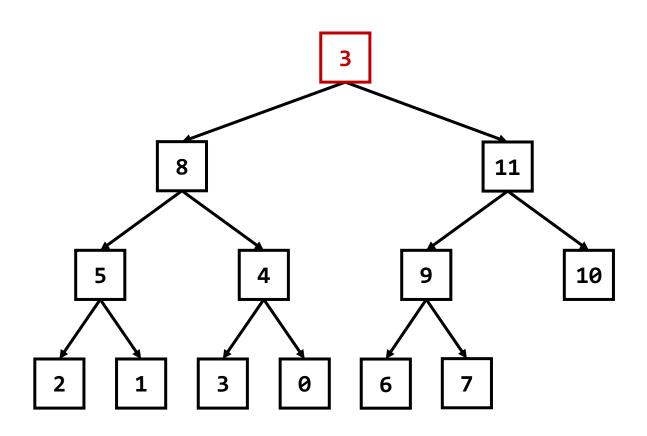




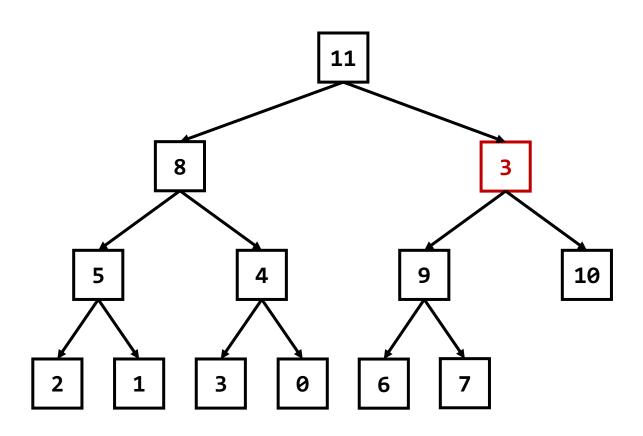




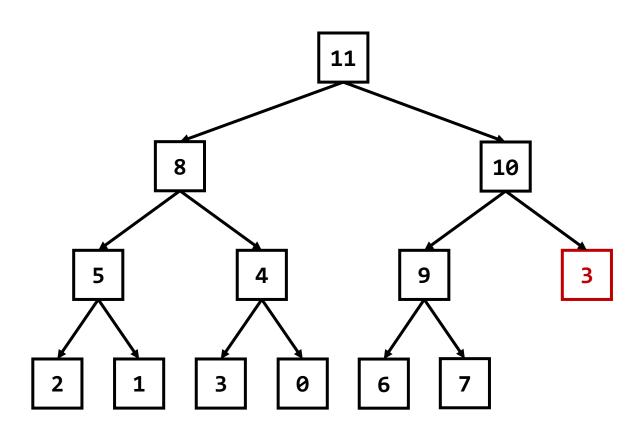




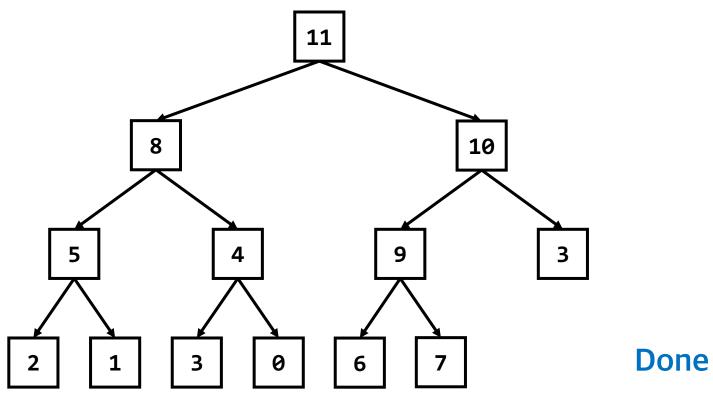












Applications: Priority Queue

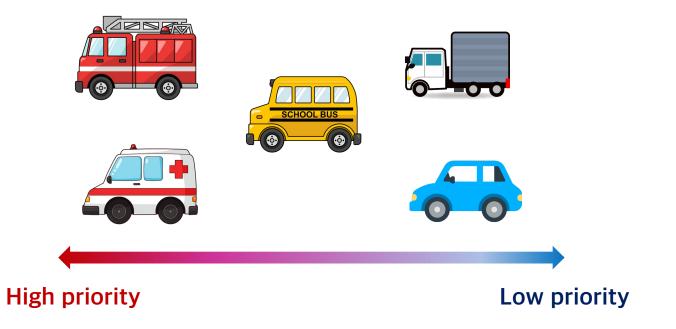


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Applications: Priority Queue



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Applications: Priority Queue

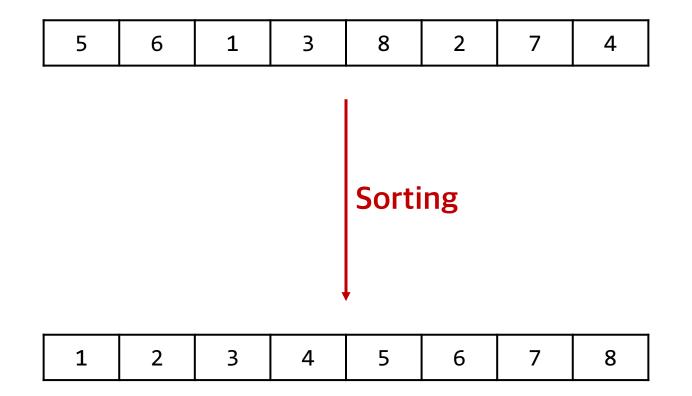


- What is the priority queue?
 - This queue does not follow the first-in first-out (FIFO) principle
 - Each element in the queue has its own priority
 - The most important element (i.e., highest priority) should come out first
- Priority queue operations
 - enqueue() insert an element into the queue
 - dequeue() delete the most important element from the queue
 - peek() return the value of the most important element
 - These functions can be easily implemented using heap

Applications: Heap Sort



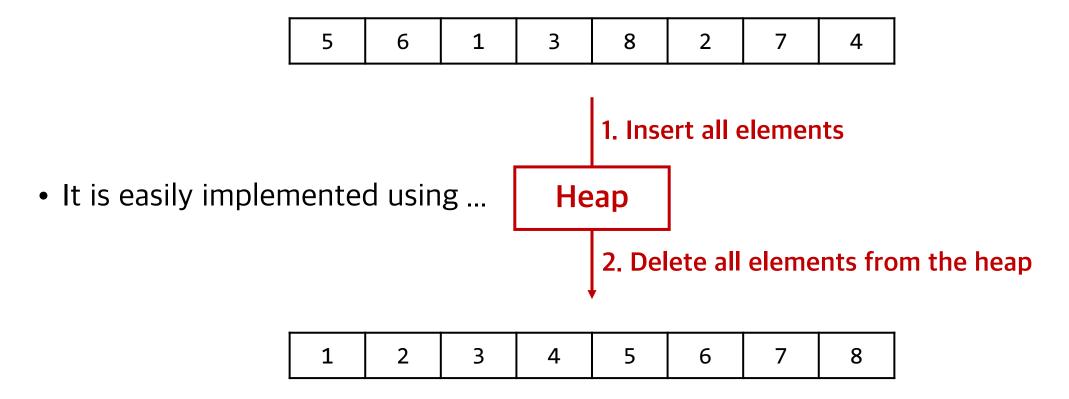
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 - Example: Sort below numbers in the increasing order



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Time Complexities



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- In the priority queue,
 - Enqueue (\approx insertion) has $O(\log N)$ time complexity
 - Dequeue (\approx deletion) has $O(\log N)$ time complexity
- In heap sort,
 - Sorting N elements requires $c \cdot (\log 1 + \log 2 + \dots + \log N) = O(N \log N)$

Any Questions?

