

# Assignment 5 FTS

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1.  $y_t = \varepsilon_t - \theta_1 \varepsilon_{t-1} - \theta_2 \varepsilon_{t-2}$

(a)

$$\mu = E(y_t) = 0$$

$$\text{Var}(E_t) = \gamma_0 = (1 + \theta_1^2 + \theta_2^2)\sigma^2$$

(b)

$$\gamma_1 = E[(\varepsilon_t - \mu)(\varepsilon_{t-1} - \mu)] = (1 + \theta_1^2 + \theta_2^2)\sigma^2$$

$$\rho_1 = \frac{\gamma_1}{\gamma_0} = (1 + \theta_1^2 + \theta_2^2)^{-1}(1 + \theta_1^2 + \theta_2^2) \quad (1)$$

$$\gamma_2 = E[(\varepsilon_t - \mu)(\varepsilon_{t-2} - \mu)] = -\theta_2\sigma^2$$

$$\rho_2 = \frac{\gamma_2}{\gamma_0} = (1 + \theta_1^2 + \theta_2^2)^{-1}(-\theta_2) \quad (2)$$

For  $i > 2$

$$\gamma_i = E[(\varepsilon_t - \mu)(\varepsilon_{t-i} - \mu)] = 0$$

$$\rho_i = \frac{\gamma_i}{\gamma_0} = 0 \quad (3)$$

(c) Since it is a MA process, the stationarity always holds. The necessary and sufficient condition for invertibility is that all roots of the eigenequation are in the unit circle.

2.  $y_t = c + \alpha_1 y_{t-1} + \dots + \alpha_p y_{t-p} + e_t$ ,  $e_t = \phi_1 e_{t-1} + \dots + \phi_m e_{t-m} + \varepsilon_t$ . Prove that  $y_t \sim AR(m + p)$ .

Pf. Denote  $1 - \alpha_1 L - \dots - \alpha_p L^p$  as  $\alpha(L)$ , and  $1 - \phi_1 L - \dots - \phi_m L^m$  as  $\phi(L)$ .

$\varepsilon_t = \phi(L)e_t$ , and  $e_t = \varepsilon_t \phi(L)^{-1}$ , then  $\alpha(L)y_t = c + \varepsilon_t \phi(L)^{-1}$ ,  $\alpha(L)\phi(L)y_t = \phi(L)c + \varepsilon_t$ , conforming to the expression of AR model.

$\alpha(L)\phi(L) = \alpha_p L^p \phi_m L^m + \dots = \alpha_p \phi_m L^{p+m} + \dots$ , and thus  $y_t \sim AR(m + p)$ .

3.  $y_t = c + \alpha_1 y_{t-1} + \varepsilon_t - \theta_1 \varepsilon_t - 1$

(a) Converting to MA form.

We rewrite the equation.

$$(1 - \alpha_1 L)y_t = c + (1 - \theta_1 L)\varepsilon_t$$

$$y_t = (1 - \alpha_1 L)^{-1}c + (1 - \alpha_1 L)^{-1}(1 - \theta_1 L)\varepsilon_t$$

$$= (1 - \alpha_1 L)^{-1}c + (1 + \alpha_1 L + \alpha_1^2 L^2 + \dots)(1 - \theta_1 L - \theta_1^2 L^2 - \dots)\varepsilon_t$$

$$= (1 - \alpha_1 L)^{-1}c + \varepsilon_t - [(\theta_1 - \alpha_1)\varepsilon_{t-1} + \alpha_1(\theta_1 - \alpha_1)\varepsilon_{t-2} + \dots] \quad (4)$$

- (b) Converting to AR form.  
rewrite the equation.

$$\begin{aligned}
 (1 - \alpha_1 L)y_t &= c + (1 - \theta_1 L)\varepsilon_t \\
 (1 - \alpha_1 L)(1 + \theta_1 L + \theta_1^2 L^2 + \dots)y_t &= (1 - \theta_1 L)^{-1}c + \varepsilon_t \\
 (1 - \alpha_1 L)(1 - \theta_1 L)y_t &= (1 - \theta_1 L)^{-1}c + \varepsilon_t \\
 y_t + (\theta_1 - \alpha_1)y_{t-1} + \theta_1(\theta_1 - \alpha_1)y_{t-2} + \dots &= (1 - \theta_1 L)^{-1}c + \varepsilon_t
 \end{aligned}$$

So

$$y_t = (\alpha_1 - \theta_1)y_{t-1} + \theta_1(\alpha_1 - \theta_1)y_{t-2} + \dots + (1 - \theta_1 L)^{-1}c + \varepsilon_t \quad (5)$$

- (c) If  $\alpha_1 = \theta_1$ .

Then (4) turns into  $y_t = (1 - \alpha_1 L)^{-1}c + \varepsilon_t$ , and (5) turns into  $y_t = (1 - \theta_1 L)^{-1}c + \varepsilon_t$ .