



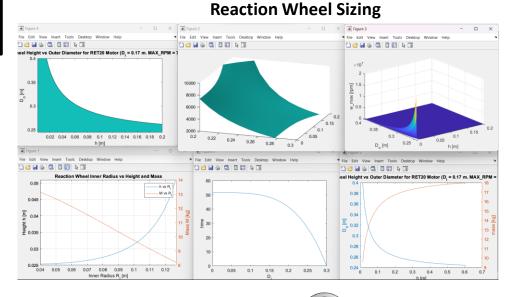
## Spin-Stabilization System for Hoisted Payloads (SpinStop) | Engineering Capstone

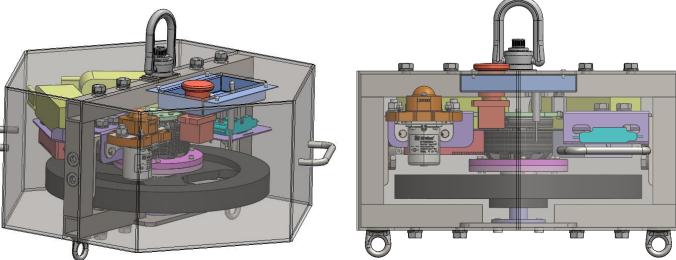
**Controls Scheme** 

**Goal:** Build a system to stabilize uncontrolled spinning of helicopter-hoisted payloads during rescue operations (and applicable to other cases).

#### Remote E-STOP Remote Controller ESP32, Physical Buttor Remote start, stop, DAQ Heartbeat Signal Battery Gyro Sensors 2x 6s LiPo DC Regulator Microcontroller LV Switch (>2500mAh and ~200A (2+ for redundancy and ESP32 continuous discharge better state estimation) Remote E-STOP Activation Control Signal Normally Open Relay Motor Controller Flycolor X Cross HV3 Motor Torque (should have regen/resistor Reaction Wheel Neumotor network braking feature) 6521/4.5/281 BLDC Inertia baby (should have current sensing Onboard (rigidly fixed to housing) feature to estimate battery E-STOP Housing With upper cable attachments to helicopter hoist and lower cable attachments to payload (maybe aluminum or plastic sheet with keylar coating)

Bothery + electronics







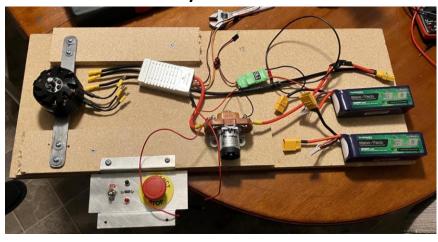


# Cont'd: Spin-Stabilization System for Hoisted Payloads (SpinStop) | Engineering Capstone

Enough designing, let's machine some parts!



And test the electrical system!



Reaction wheel – motor adaptor shrink fit using liquid nitrogen!



Shoutout to Brent's Welding for making our system housing!



Initial mechanical assembly check, it looks beautiful! (To be continued)





# Jerry Lu | Engineering Portfolio





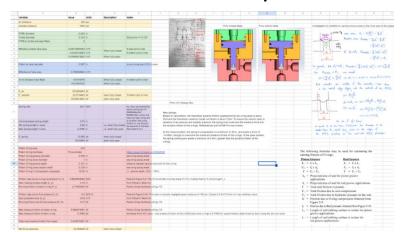
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### 2<sup>nd</sup>-Gen Oxidizer Vent Valve for 2023 Hybrid Rocket | Waterloo Rocketry

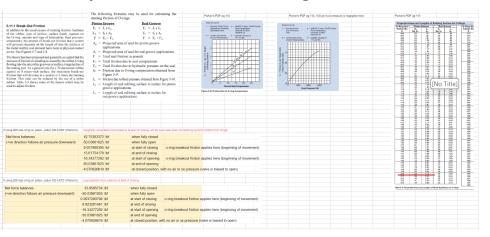
**Goal:** Build a pneumatically-actuated, normally-open, light & compact valve to control oxidizer venting from the launch vehicle.

#### First, lots of design calcs:

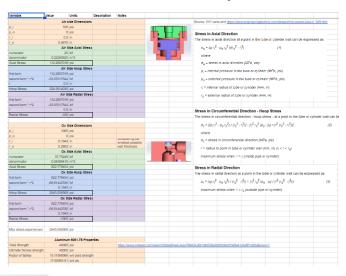
#### Force balance on valve piston



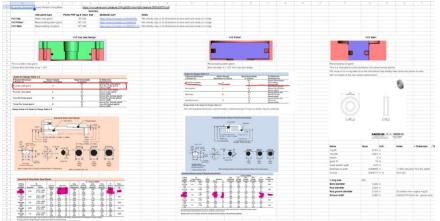
#### **Dynamic friction due to O-ring seals**



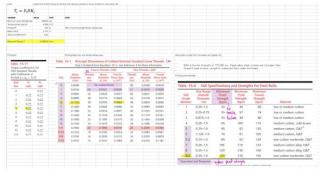
#### **Stresses on valve components**



### O-ring groove sizing (Shoutout to Parker's Handbook)

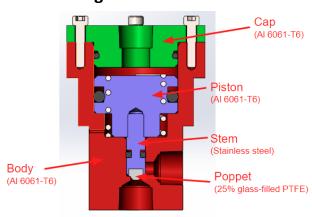


### Torque spec for fasteners





#### Initial design!

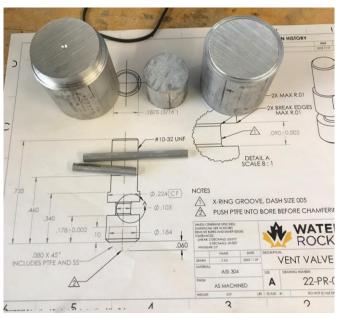




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### Cont'd: 2<sup>nd</sup>-Gen Oxidizer Vent Valve for 2023 Hybrid Rocket | Waterloo Rocketry

It's machining time!



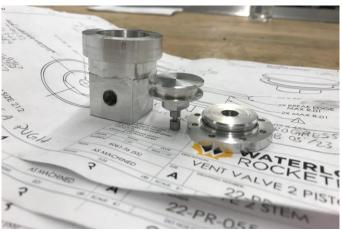


**Hydrostatically** tested to spec and now strapped atop the engine testing container prior to static fire test.













Assembled, tested, sanitized, and ready to fly!

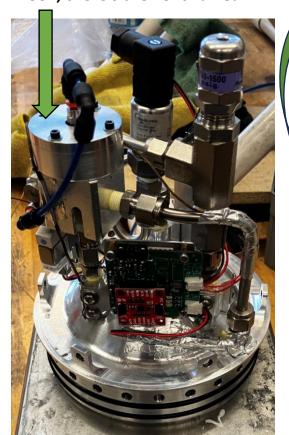
**New and prettier** body for easier integration of pilot solenoid valve and thermistor.

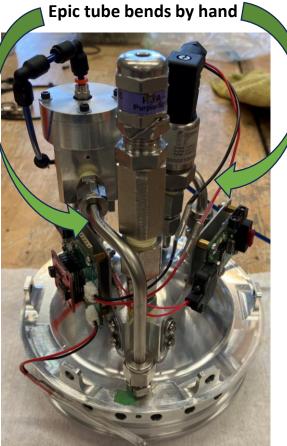


### High Pressure Oxidizer Venting System for 2023 Hybrid Rocket | Waterloo Rocketry

**Goal:** Integrate the oxidizer vent valve, pilot solenoid valve, pressure-relief valve, pressure transducer, actuator control board, sensor measurement board, and two Raspberry Pi cameras into a 5.5" by 10" cylindrical space atop the oxidizer tank.

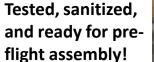
#### Look, there's the vent valve!







Awaiting systems test in front of a beautiful sunset.





Post-launch and -recovery in the New Mexico desert!
Welcome back ©

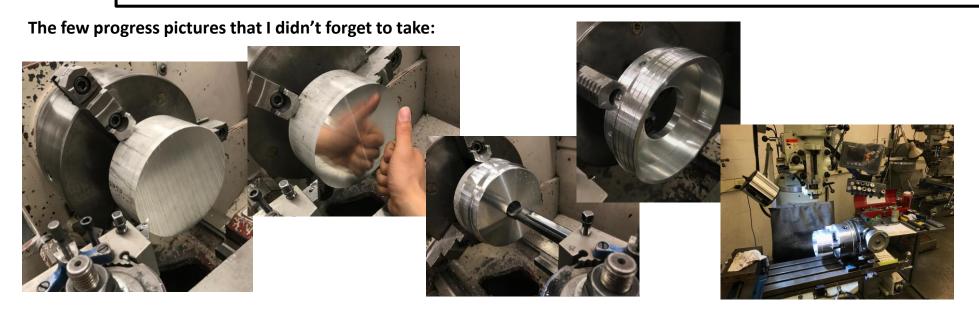




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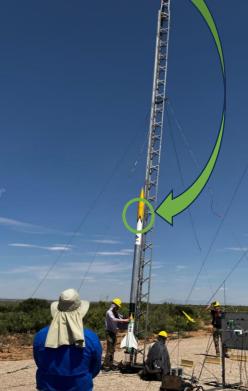
## Airframe Couplers for 2023 Hybrid Rocket | Waterloo Rocketry | May – June 2023

**Goal:** Machine three critical airframe couplers to ensure timely assembly of the launch vehicle airframe.



rocket together:

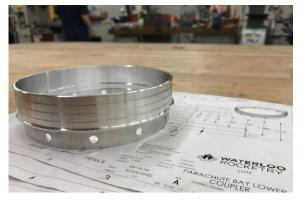
The couplers holding the



**Recovery bay coupler:** 



Parachute bay coupler:

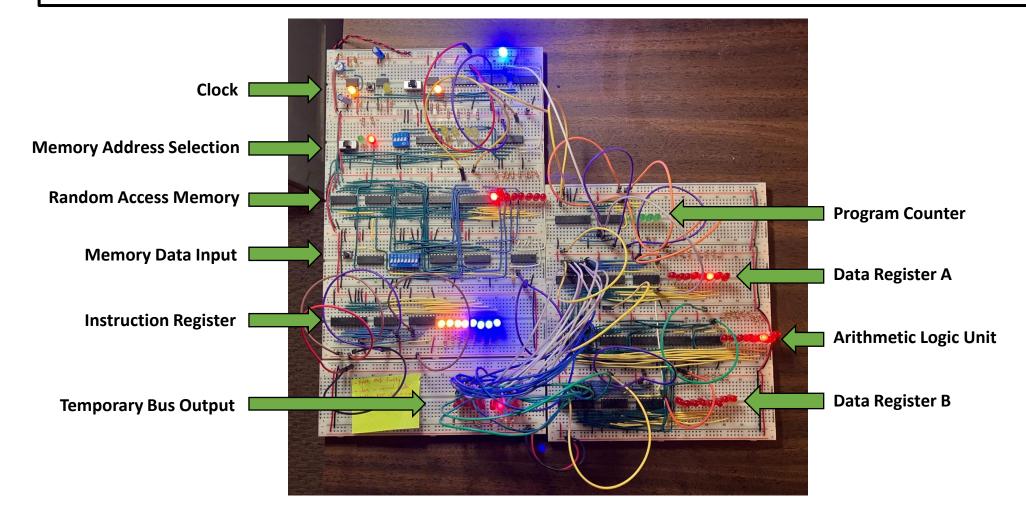


Nose cone coupler:



### 8-bit Breadboard Computer | Personal Project | July 2023 – On Hold for Now

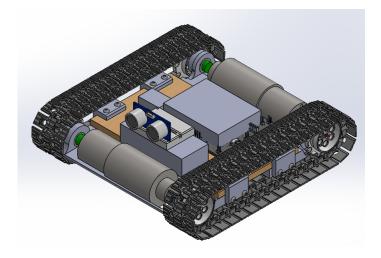
**Goal/Motivation:** Computers are very cool and I want to learn something out of my comfort zone, so I'm following online tutorials to build a first-principles digital computer from low-level IC components.



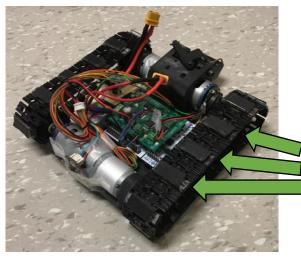


## **Autonomous Wall-Climbing Robot (Wall-e) | 3rd Year Course Project**

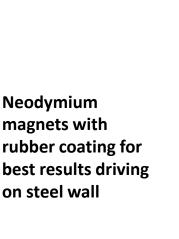
**Goal:** Build a system capable of autonomously getting over a steel wall and locating a target on the other side.







Reality

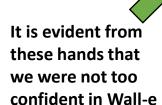


**Neodymium** 

on steel wall



Wall-e in action:







Wall-e needed some human help to get over the top of the wall. This project taught me the importance of rapidly testing drastically different proofs-ofconcepts before making minuscule improvements to a particular design (we only did the latter).

Wall-e in retirement:

