DUSIC IFY Programming Techniques Python application for Projectile Motion Simulation Jia Xiu Sai

Date: 2019-04-30

1 Python application for projectile motion simulation

1.1 Introduction

Simulation programs are used in engineering and science to investigate how complex systems will react to changing variables without doing the experiment in real-life. This saves time, cost and most importantly, it provides a safe environment as the engineers and scientist do not need to carry out the experiments in real life. In this project, the simulation will focus on a sphere object that is fired out of an air cannon at different speeds. It will show the changing speed and distance with both a spreadsheet and animated graphics from the variable parameters input by the user. This simulation will show how the initial angle, initial speed and weight of the projectile object affect the responding variables using physics equations taking gravitational force and air resistance into consideration.

1.1.1 Specifications

The minimum specification for this program was as follows:

The application must ...

- be written using the Python programming language
- use at least three relevant physics equations
- use the import function
- use a range of data types, including lists
- have a basic menu system with at least three subroutines to allow the user to:
 - have parsed input
 - enter system parameters and simulation properties
 - calculate and display some simulation data in tabular format
 - plot at least one graph of the data
 - optionally save to file in CSV format
 - optionally show a real-time animation of the simulation data using basic 2D graphics
 - exit the program in a controlled fashion

1.1.2 Projectile Motion Theory

In this program, the cannonball is calculated as a 2-dimensional projectile where the total velocity can be split into two individual forces, X and Y. X velocity only acts horizontally while the Y velocity only acts vertically. The object is supposed to continue moving in a straight line because of inertia but there are forces opposing it namely, air resistance and gravity. Air resistance that opposes the velocity is also a 2-dimensional force which acts in opposite directions to the horizontal and vertical velocity moving forward regardless of which direction the velocity is moving.[1] Furthermore, the gravity of Earth is also considered in this simulation which always pulls the cannonball downwards.[2] Figure 1 below shows the forces acting on the cannonball when it is moving in a parabolic path.

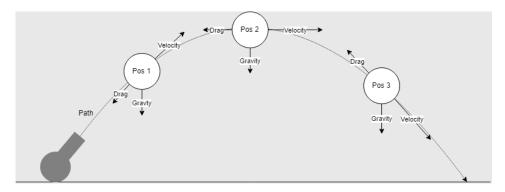


Figure 1: Illustration of a cannon and the forces acting on the cannonball

1.2 Design

The program is designed so that the program is both user-friendly and efficient. The following section will explain some of the design decision made in this project.

1.2.1 System Parameters

[682–691] The program uses the following system parameters and their units:

Variable	Parameter	Default Value	Unit
mass	Mass of the projectile	5.5	(Kilograms)
height	Height of initial projection	0.0	(Meters)
speed	The initial speed of projectile	100	(Meter per second)
area	The surface area of projectile	0.0154	$(Meters^2).$
step	Step size	0.01	(Seconds)
ang_in_deg	Initial angle	45	(Degrees)
ang_in_rad	Initial angle	0.79	(Radians)

The default values are determined by real-life examples. A cannonball with a mass of 5.5kg has a radius of 7.7cm. Thus, the frontal area is calculated to be 0.0154 meters².[3] Furthermore, The initial speed is the average speed of real-life cannon launch speed.[4] The step size is a value that can be adjusted to be more accurate but slower simulation by having a smaller step size or a faster but more inaccurate simulation with a larger step size. The step size greatly affects the smoothness of the simulation. There are 2 system variables to hold data for the angle because angle in degrees are used for user related display and input while the angle in radians is used for the program to run its calculations. The angle in radians is calculated when the user first inputs the value for angle in degrees.

1.2.2 Equations

The simulation is modelled using the following equations:

$$F_q = -mass \times gravity \ on \ Earth \tag{1}$$

$$F_d = 0.5 \times v \mid v \mid k_d \times area \times \rho \tag{2}$$

$$a = \frac{F_g - F_d}{m} \tag{3}$$

$$\frac{dv}{dt} = a \tag{4}$$

$$\frac{dx}{dt} = v \tag{5}$$

$$Z^2 = X^2 + Y^2 \tag{6}$$

The simulation algorithm uses the method of finite differences, or Euler's method, to determine approximate solutions to the differential equations of the system. After setting initial conditions, the algorithm iterates, calculating the forces acting on the cannonball and therefore the acceleration of the cannonball over small steps in time. At each point, the next values of velocity, distance and time are determined from current values. Errors are reduced and accuracy improved by using very small increments in time. However, a small increment may dramatically increase the time required for the calculation to be completed.

$$\frac{dv}{dt} \approx \frac{v_{i+1} - v_i}{h} \tag{7}$$

$$\frac{dx}{dt} \approx \frac{x_{i+1} - x_i}{h} \tag{8}$$

$$v_{i+1} = v_i - (a_i \times h) \tag{9}$$

$$x_{i+1} = x_i + (v_i \times h) \tag{10}$$

$$t_{i+1} = t_i + h \tag{11}$$

The basic steps of the calculate function:

- 1. The initial time set to zero.
- 2. The initial X displacement and Y displacement set to zero.
- 3. The initial X velocity and Y velocity are calculated using trigonometry.
- 4. The total velocity is set to the value input by the user.
- 5. Initial values are stored in their respective lists.
- 6. This loop runs until Y displacement reaches 0 again (Cannonball reaches ground level):
 - (a) Force of gravity is calculated using equation (1).
 - (b) Current X air resistance is calculated using equation (2).
 - (c) Current X acceleration is calculates using equation (3).
 - (d) Next X velocity is calculated using equation (9).
 - (e) Next X distance is calculated using equation (10).
 - (f) Current Y air resistance is calculated using equation (2).
 - (g) Current Y acceleration is calculates using equation (3).
 - (h) Next Y velocity is calculated using equation (9).
 - (i) Next Y distance is calculated using equation (10).
 - (j) Total velocity is calculated using the Pythagoras theorem (6).
 - (k) Next time value is calculated using equation (11).
 - (l) Results are added to their respective lists.

The values for X and Y velocity are calculated separately because the air resistance and gravity acting on them are different. The X velocity is only opposed by air resistance but the Y velocity is opposed by both air resistance and gravity (when ascending). The gravity increases of the acceleration when the cannonball is descending in altitude thus, increasing its speed. The air resistance is always the opposing the Y velocity regardless when the cannonball is increasing or decreasing in altitude. The equation (2) drag uses an absolute value for the current velocity in its equation because it will ensure that when used in the equation (3), the value will be added to the force of gravity when the cannonball is ascending in altitude and cancel out by the gravity when descending.

1.2.3 Problem Decomposition

The program is designed around the main menu which allows the user to run functions by inputting commands. Figure 2 below shows the structure diagram of the program with the main components.

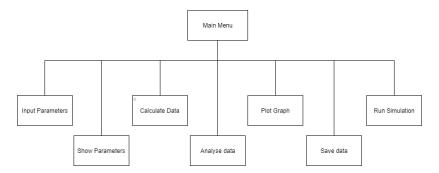


Figure 2: Program Structure

1.2.4 Test Plan

The following test plans templates in Figures 3, 4 and 5 are to be filled by doing manual testing with running the code. The test plans aim to find any errors in the program.

1.3 Implementation

The program was implemented by creating a menu system with functions defined for each of the commands listed on the menu. The menu allows the user to input commands to start different functions. This program uses Python 3 and referred to [5] where required.

1.3.1 Main program loop

Figure 6 shows the general flowchart of the main program. The code listing can be found in Appendix A.

[682–691] The program begins by defining and initialising the system parameters:

mass	Mass of the projectile	(Kilograms)
height	Height of initial projection	(Meters)
speed	The initial speed of the projectile	(Meter per second)
area	The surface area of projectile	$(Meters^2).$
step	Step size	(Seconds)
ang_in_deg	Initial angle	(Degrees)
ang_in_rad	Initial angle	(Radians)

[697–703] Data lists are then created for holding the simulation data:

t[]	$_{ m time}$	(Seconds)
x[]	X displacement	(Meters)
у[]	Y displacement	(Meters)
xv[]	X velocity	(Meter per second)
yv[]	Y velocity	(Meter per second)
v[]	Velocity	(Meter per second)

[760-842] The main program loop is a while loop. This loop repeats until the user enters the required input to quit the program, which in this case is the character quit.

[760–725] First, the menu is displayed on the console with the commands and functions.

[728–841] A basic if-elif structure is used to invoke a specific function depending on the menu choice entered by the user.

1.3.2 Function: input parameters

[59-84] Figure 7 shows the flowchart for the function input_parameters that allows the user to input parameters to run calculations for the projectile. The function checks every value input by the user by running the value through function get_float. The value input is then recorded if it passes all requirements.

1.3.3 Function: get float

[21–53] Figure 8 shows the flowchart for function get_float. Although the user is given the ability to input any values, this function checks the value input for three requirements:

- 1. must be smaller than maximum value.
- 2. must be larger than the minimum value.
- 3. must be a float.

If all three requirement are meet, the value input is recorded. However, if one of the requirements are not met, the pre-set default value will be recorded instead.

1.3.4 Function: show parameters

[90–104] Figure 9 shows the flowchart for this simple function that displays the parameters input by the user that have been checked by the function get_float. A basic if-elif structure checks if parameters are entered to prevent the function from crashing.

1.3.5 Function: calculate data

Figure 10 shows the general flowchart of the function calculate_data used to calculate the projectile motion simulation data. A basic if-elif structure checks if parameters are entered to prevent the function from crashing. The system parameters are passed to the function when it is called.

[120–144] Firstly, variables for both current and next are declared for holding the calculations. Furthermore, the fixed parameters are declared:

```
g Gravity on Earth 9.807 (Meters per second<sup>2</sup>)) [6]
a_d Air density at sea-level 1.225 (Kilogram per meter<sup>3</sup>) [7]
drag Drag coefficient 0.47
```

[147–152] Next, lists are declared for holding the calculation results, and initial values are appended to the lists to create the first set of results i.e. t[0], x[0], y[0], xv[0], yv[0] and v[0].

[177–231] A while loop is used with an incremental index i. During each execution of the loop, the next output value is calculated using Equation (11) and appended to the list of output values. The time value is incremented by the step size and appended to the list of time values.

[236] Once the time value reaches the total simulation time required, the loop is exited and the lists of data i,t,xv,yv,x,y,v are returned to the main program.

1.3.6 Function: analyse data

[242–295] Figure 11 shows the flowchart for the function that displays additional information (Furthest distance and highest altitude) from the data set calculated using the calculate data function. A basic if-elif structure to check if the user entered the parameters and if the data is calculated to prevent the function from having errors.

[249–254] The console output present the user with a option to exit the function to the main menu or proceed to display the analysis for the data.

1.3.7 Function: plot graph

[301–404] Figure 12 shows the flowchart for the function that presents the option to display one of two graphs using the data set calculated. A basic if-elif structure to check if the user entered the parameters and if the data is calculated to prevent the function from having errors. A second menu with commands for 2 different graphs with appear and it allows the user to choose which graph to display first.

1.3.8 Function: save data

[414–461] Figure 13 shows the flowchart for the function that saves the data set in an external CSV file. A basic if-elif structure to check if the user entered the parameters and if the data is calculated to prevent the function from having errors.

1.3.9 Function: run simulation

[467–668] Figure 13 shows the flowchart for the function that runs an animation using the current data set to provide the user with a better visualisation of the projectile motion in real time. A basic if-elif structure to check if the user entered the parameters and if the data is calculated to prevent the function from running and encountering errors.

[487–496] The function determines the scale for the visuals to ensure the cannonball to always be within the screen. The scale adjusts the change in movement of the cannonball on the screen.

1.4 Testing

Code testing is an important part of programming as by testing code, the developers are able:

- 1. To identify errors
- 2. To ensure code meets the specification (fit for purpose)
- 3. To ensure code is efficient
- 4. To ensure code is maintainable

By testing a program, companies are able to prevent financial losses and delayed deadlines due to faulty programs. It ensures the code to be properly functioning and is able to process the tasks properly.

1.4.1 Completed Test Tables

The following completed test tables in Figures 15, 16 and 17 are filled in after doing testing with the templates provided.

1.4.2 Testing evidence for Test table 1

When first running the program, the system menu and system information can be seen in the following console output:

```
6 | Save data
7 | Run visuals
quit | Quit program
```

Enter command:

The following console output was displayed when Test 1 in Test table 1 (15) was carried out:

```
Projectile Motion Simulator
Jia Xiu Sai-2427165
12:32 24/5/2019
Function: Change parameters
Enter the mass of the cannonball in kg (1-20): 10
Value recorded.
Enter the initial height (0-10): 5
Value recorded.
Enter the initial speed of the cannonball in m/s (10-200): 100
Value recorded.
Enter the frontal area of cannonball in meters2 (0.005-1): 0.02
Value recorded.
Enter the step size in seconds (0.001-1): 0.005
Value recorded.
Enter the initial angle in degrees (10-90): 30
Value recorded.
```

The following console output was displayed when Test 2 in Test table 1 (15) was carried out:

```
Projectile Motion Simulator
Jia Xiu Sai-2427165
12: 6 24/5/2019
Function: Change parameters
Enter the mass of the cannonball in kg (1-20): 0
Oops! The value of the number is too small. Using default value.
Enter the initial height (0-10): -10
Oops! The value of the number is too small. Using default value.
Enter the initial speed of the cannonball in \mbox{m/s} (10-200): -5
      The value of the number is too small. Using default value.
Enter the frontal area of cannonball in meters2 (0.005-1): 0.00001
Oops! The value of the number is too small. Using default value.
Enter the step size in seconds (0.001-1): 0.0001
Oops! The value of the number is too small. Using default value.
Enter the initial angle in degrees (10-90): 0
Oops! The value of the number is too small. Using default value.
```

The following console output was displayed when Test 3 in Test table 1 (15) was carried out:

```
DUISC
Projectile Motion Simulator
Jia Xiu Sai - 2427165
12:12 24/5/2019
Function: Change parameters
Enter the mass of the cannonball in kg (1-20): 50
Oops! The value of the number is too big. Using default value.
Enter the initial height (0-10): 50
Oops! The value of the number is too big. Using default value.
Enter the initial speed of the cannonball in m/s (10-200): 300
      The value of the number is too big. Using default value.
Enter the frontal area of cannonball in meters2 (0.005-1): 5
Oops! The value of the number is too big. Using default value.
Enter the step size in seconds (0.001-1): 10
Oops! The value of the number is too big. Using default value.
Enter the initial angle in degrees (10-90): 180
Oops! The value of the number is too big. Using default value
```

The following console output was displayed when Test 4 in Test table 1 (15) was carried out:

```
Projectile Motion Simulator
Jia Xiu Sai-2427165
12:19 24/5/2019
Function: Change parameters
Enter the mass of the cannonball in kg (1-20): heavy
Oops! That was not a valid number. Using default value.
Enter the initial height (0-10): high
Oops! That was not a valid number. Using default value.
Enter the initial speed of the cannonball in m/s (10-200): fast
Oops! That was not a valid number. Using default value.
Enter the frontal area of cannonball in meters2 (0.005-1): average
      That was not a valid number. Using default value.
Enter the step size in seconds (0.001-1): daily
Oops! That was not a valid number. Using default value.
Enter the initial angle in degrees (10-90): fish
Oops! That was not a valid number. Using default value.
```

The following console output was displayed when Test 5 in Test table 1 (15) was carried out:

```
DUISC
Projectile Motion Simulator
Jia Xiu Sai - 2427165
12:21 24/5/2019
Function: Change parameters
Enter the mass of the cannonball in kg (1-20): !
Oops! That was not a valid number. Using default value.
Enter the initial height (0-10): @
Oops! That was not a valid number. Using default value.
Enter the initial speed of the cannonball in m/s (10-200): #
      That was not a valid number. Using default value.
Enter the frontal area of cannonball in meters2 (0.005-1): $
Oops! That was not a valid number. Using default value.
Enter the step size in seconds (0.001-1): %
Oops! That was not a valid number. Using default value.
Enter the initial angle in degrees (10-90):
     That was not a valid number. Using default value.
```

The following console output was displayed when Test 6 in Test table 1 (15) was carried out:

```
Projectile Motion Simulator
Jia Xiu Sai-2427165
11:56 24/5/2019
Function: Change parameters
Enter the mass of the cannonball in kg (1-20):
Oops! That was not a valid number. Using default value.
Enter the initial height (0-10):
Oops! That was not a valid number. Using default value.
Enter the initial speed of the cannonball in m/s (10-200):
Oops! That was not a valid number. Using default value.
Enter the frontal area of cannonball in meters2 (0.005-1):
Oops! That was not a valid number. Using default value.
Enter the step size in seconds (0.001-1):
Oops! That was not a valid number. Using default value.
Enter the initial angle in degrees (10-90):
Oops! That was not a valid number. Using default value.
```

1.4.3 Testing evidence for Test table 2

The following console output was displayed when Test 1 in Test table 2 (16) was carried out:

```
Projectile Motion Simulator
Jia Xiu Sai-2427165
22:27 21/5/2019
Function: Show current parameters
 -----
Current parameters of projectile object:
Mass = 5.50 kg
Height = 0.0 meters
Speed = 100.00 meters per seconds
Surface area = 0.1540 meters2
Step size = 0.01 seconds
Initial angle = 45.00 degrees (0.79 radians)
Would you like to run calculations?
1: Yes
Press any key to go back to main menu.
Enter command:
The following console output was displayed when Test 2 in Test table 2 (16) was carried out:
Projectile Motion Simulator
Jia Xiu Sai - 2427165
22:27 21/5/2019
Function: Calculate and show current data set
Data table:
                                        Velocity | X_Distance |
Step | Time | X_Velocity | Y_Velocity |
                                                                  Y_Distance
 0 |
      0.00
               70.670
                             70.572 |
                                         100.000 |
                                                    0.000
                                                                    0.000
       0.01
                 70.630
                             70.434
                                      -
                                          99.874 |
                                                      0.707
                                                                    0.707
 1
    1
            - 1
                         - 1
                                                               1
                                     - 1
                                                 - 1
 2
    - 1
       0.02
            1
                 70.590
                         - 1
                             70.296
                                          99.748
                                                     1.414
                                                               1.413
 3
       0.03
                70.550
                            70.158
                                          99.622 |
                                                     2.120
                                                                   2.117
                        1
                                     | |
       0.04
                 70.510
                             70.020
                                          99.496
            - 1
                                                      2.826
                                                                    2.820
 4
    - 1
                                                               - 1
 5
       0.05
            - 1
                 70.470
                         69.883
                                          99.370
                                                 - 1
                                                      3.532
                                                                    3.522
    - 1
      0.06 |
                70.430
                        69.745
                                          99.245
                                                     4.237
                                                                   4.222
                                          99.120 |
                                     0.07
            -
                 70.390
                            69.608
 7
    - 1
                        - 1
                                                      4.941
                                                               - 1
                                                                   4.921
 8
    -
      0.08
            70.350
                         69.471
                                          98.995
                                                 - 1
                                                     5.646
                                                               -
                                                                   5.618
                                     - 1
                        | 69.334
      0.09 |
                70.310
                                          98.870
                                                     6.349
    6.314
 10 | 0.10 |
                                         98.745
                 70.270
                        69.197
                                     - 1
                                                      7.053
                                                               7.009
1312 | 13.12 | 40.437 | -59.051 | 71.519 |
                                                     692.778 I
                                                                   5.289
1313 | 13.13 |
                40.423
                             -59.121
                                     71.569
                                                      693.182
                                                                   4.700
                        |
1314|
      13.14 |
                 40.410
                             -59.191
                                          71.620
                                                 - 1
                                                      693.587
                                                               - 1
                                                                    4.109
1315 | 13.15 |
                40.397
                            -59.261
                                          71.670
                                                 693.991
                                                                   3.518
                                                               - 1
                           -59.331
1316 | 13.16 | 40.384
                                         71.720 |
                                                      694.395
                                                                   2.926
                                          71.771 |
71.821 |
                        | |
1317|
      13.17 |
                 40.371
                             -59.401
                                      - 1
                                                      694.799
                                                                    2.333
                                                               i
                                                              Ì
1318 | 13.18 |
                 40.358
                             -59.470
                                                      695.203
                                                                    1.740
1319 | 13.19 |
                 40.345
                             -59.540
                                          71.871
                                                      695.606 |
                                                                    1.146
1320 | 13.20 |
1321 | 13.21 |
                                     40.331
                        |
                             -59.609
                                          71.921
                                                696.010
                                                             |
                                                                    0.551
                40.318
                             -59.679
                                          71.971
                                                      696.413
                                                                    -0.044
Number of data points for:
Time - 1322
Velocity - 1322
X - 1322
Y - 1322
    ______
Would you like to display analysis?
Press any key to go back to main menu.
Enter command:
```

DUICS/IFY/PT/Project 2019

As shown above, the last line of calculation showed that the Y displacement to be a negative value which is not supposed to happen as the while loop is supposed to stop at when Y displacement reaches 0. The value for Y distance 0 and jumps from 0.551 to -0.044. This is because the simulation uses Euler's method to determine approximate solutions to the differential equations of the system and inaccuracy can be reduced by using a smaller step value but the calculation will take longer as more steps need to be calculated for the same amount of distance.

The following console output was displayed when Test 3 in Test table 2 (16) was carried out:

```
Projectile Motion Simulator
Jia Xiu Sai - 2427165
22:27 21/5/2019
Function: Analyse data
Data analysis:
Furthest distance achieved at:
X-coordinate - 226.571 meters
Y-coordinate - -0.607 meters
Speed - 33.337 meter per seconds
Time - 9.15 seconds
Highest distance achieved at:
X-coordinate - 146.289 meters
Y-coordinate - 101.214 meters
Speed - 21.703 meter per seconds
Time - 3.95 seconds
Press any key to go back to main menu.
```

The following console output was displayed when Test 4 and 5 in Test table 2 (16) was carried out:

When on of the command is selected, the console output becomes:

```
DUISC
Projectile Motion Simulator
Jia Xiu Sai-2427165
22:27 21/5/2019
Function: Plot graph

Plotting graph......
Press any key to go back.
```

Test 4 will create Graph 1: Displacement Y against displacement X as shown in Figure 18. The highest height achieved by the cannonball is marked [8] and labelled [9]. This extra feature was later added to the program.

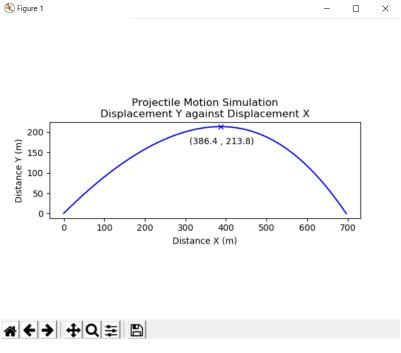


Figure 18: Graph 1

Test 5 will create Graph 2: Velocity against time as shown in Figure 19

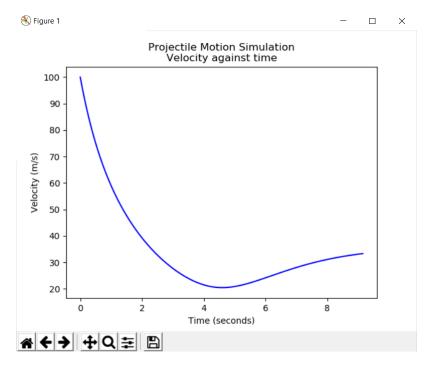


Figure 19: Graph 2

As shown above, the velocity of the cannonball rapidly decreases but at no point it reaches 0 because it is still moving forward. However, the Y velocity at the lowest point is 0 as the cannonball is starting it's descend towards the ground.

The following console output and Figure 20 was displayed when Test 6 in Test table 2 (16) was carried out:

	Α	В	С	D	Е	F	G
1							
2	Step	Time(Seconds)	X_Velocity(m/s)	Y_Velocity(m/s)	Velocity(m/s)	X_Distance(m)	Y_Distance(m)
3	0	0.00	7.071	7.071	10.000	0.000	0.000
4	1	0.00	6.985	6.975	9.871	0.007	0.007
5	2	0.00	6.900	6.881	9.745	0.014	0.014
6	3	0.00	6.818	6.789	9.622	0.021	0.021
7	4	0.00	6.738	6.700	9.502	0.028	0.028
8	5	0.01	6.659	6.613	9.385	0.035	0.034
9	6	0.01	6.583	6.527	9.270	0.041	0.041
10	7	0.01	6.508	6.444	9.159	0.048	0.048
11	8	0.01	6.435	6.362	9.049	0.054	0.054
12	9	0.01	6.363	6.283	8.942	0.061	0.060
13	10	0.01	6.293	6.205	8.838	0.067	0.067

Figure 20: Data is now save in csv.file "Projectile Motion"

The following console output and Figure 21 and 22 was displayed when Test 7 in Test table 2 (16) was carried out:

DUISC
Projectile Motion Simulator
Jia Xiu Sai-2427165
22:41 21/5/2019
Function: Run simulation
Running simulation.....

In Figure 21, the simulation has just started and is waiting for the user to press any key to start the visualisation. The animation provide real-time information like iteration, velocity and time. A real-time indicator is added to inform the user if the program in real-time.

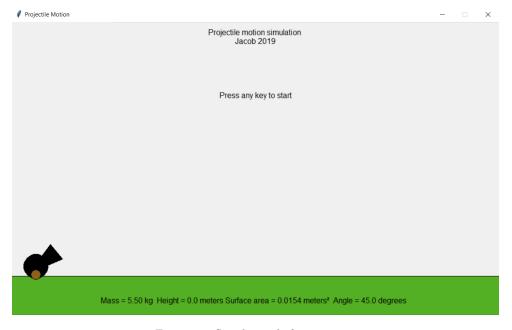


Figure 21: Simulation before starting

In Figure 22, the simulation has been started and stopped by the user by pressing any key again. The additional data showing the highest and furthest distance achieved are added to provide the user with more information.

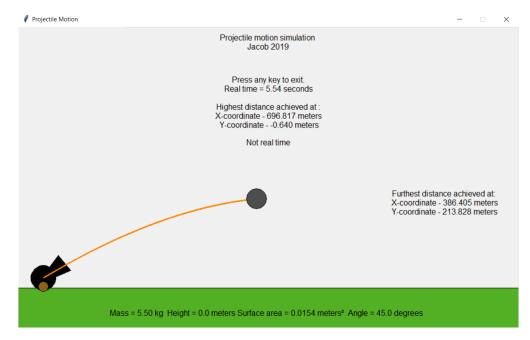


Figure 22: When the simulation is running

1.4.4 Testing evidence for Test table 3

The following console output was displayed when Test 1,2,3,4,5 and 6 in Test table 3 (17) was carried out:

```
DUISC
Projectile Motion Simulator
Jia Xiu Sai-2427165
22:47 21/5/2019
Function: Analyse data
No parameters enter yet.
Press any key to go back to main menu.
```

This function is to prevent the user from crashing the program by not inputting any parameters.

The following console output was displayed when Test 7,8,9 and 10 in Test table 3 (17) was carried out:

```
DUISC
Projectile Motion Simulator
Jia Xiu Sai-2427165
22:47 21/5/2019
Function: Run simulation
No data calculated yet.

Press any key to go back to main menu.
```

This function is to prevent the user from crashing the program by not calculating the data set.

The following console output was displayed when Test 11 in Test table 3 (17) was carried out:

```
Quitting...
Program has ended
Bye

-----
(program exited with code: 0)

Press any key to continue . . .
```

1.4.5 Dry run

Figure 23 shows the dry run of function calculate_data by manually inputting functions into an excel document and calculating the values for the first 10 iteration using default parameters by going through all the steps as shown in Section 1.2.2.

The results from the dry run matches with the calculation from the program, this shows that the program has no calculation error.

1.5 Conclusion

1.5.1 Key findings

The program has been able to use loops and functions to create a menu to simulate the projectile motion of a cannonball with the parameters input from a user. Furthermore, it give an idea of how a cannonball will react in a similar experiment in real-life but it is slightly inaccurate as other factors like wind are not considered in this simulation. This simulation should be used as a reference and should not replace real-life data collected from experiments. The data calculated is an estimation using the limited information used in the calculations.

1.5.2 Future improvements

Future improvement that can be implemented include:

- Calculation
 - Take into consideration other forces like wind.
 - * This feature has been tested but the results were not always consistent as the vector can only either be more with or against the velocity in the calculations thus, causing the wind to be only working in on direction. Furthermore, if the wind is moving the projectile further or faster, the calculation will have to continue for a longer period of time. It has been decided that it will be more realistic to exclude this feature until a more optimal solution can be implemented.
 - Ability to change the projectile to other objects like a Frisbee.
 - * This has not been tested as wind and lift will play a major part in the simulation as shown in Figure 24 and the reason stated in the previous point, it is more realistic to exclude this feature until a more optimal solution can be implemented.

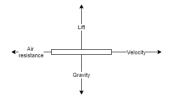


Figure 24: Force diagram of a Frisbee

• Animation

- A changing scale is calculated using the furthest distance divided by the margin size.
 - * This has been tested and the object will always land at the same spot in the animation thus, fully utilising the margin. However, if the angle is changed to a border value (5 or 85 degrees), the scale will be too small/big making the projectile move out of the margin.
- A ruler that shows how far or high the projectile travelled that changes according to the maximum distance or height.
- A vector with a label or colour code which changes with the magnitude and direction of the force acting on the projectile object.
- A pause and play option.

• Graphs

An option to change the axis of the graph to other data calculated like acceleration or air resistance.

1.6 Evaluation

1.6.1 Appraisal

All the requirements are met for this project include:

- The code to be written in Python language. The code is shown in Appendix A.
- Using 12 Physic and Math equation. The equations used are shown in Section 1.2.1.
- Using the import function
- Using lists to store data. The function of this feature is shown in Section 1.3.1.
- User input required to run the program. The function of this feature is shown in Test 1 in Test Table 2 shown in Section 1.4.3.
- Allow user to change system parameters. The function of this feature is shown in all the Tests done in Test table 1 shown in Section 1.4.2.
- Allow user to plot 2 different graphs. The function of this feature is shown in Test 4 and 5 in Test table 2 shown in Section 1.4.3.
- Allow user to save data in a CSV file. The function of this feature is shown in Test 6 in Test table 2 shown in Section 1.4.3.
- Allow user to run a real-time animation. The function of this feature is shown in Test 7 in Test table 2 shown in Section 1.4.3.
- Allow user to exit program properly as shown in Test 11 in Test table 3 shown in Section 1.4.4.

1.6.2 Limitations

Although all specifications are met, there are some limitations in this program. The limitations include:

- Unable to calculate data at a specific point in the program. Without calculating the whole simulation. This is because of the lack of time to research a more advanced way to calculate the data required in the data set instead of using the Euler's method where it is an estimation.
- Unable to reliably compare the results in simulation as there is no recourse or time available to fire a cannon in real life and record the real-time statistics. Furthermore, cannons are no longer used in modern times as more advanced alternatives are available.
- Unable to create a better representative of a cannon in the animation because the module graphics doesn't allow shapes to be placed diagonally.

2 References

- [1] N. Hall. Drag of a Sphere. [Online]. Available: https://www.grc.nasa.gov/www/k-12/airplane/dragsphere.html
- [2] —. Ballistic Flight Equation. [Online]. Available: https://www.grc.nasa.gov/www/k-12/airplane/ballflght.html
- [3] D. A. Collins. British Cannonball Sizes. [Online]. Available: https://www.arc.id.au/Cannonballs.html
- [4] R. Allain. CANNONBALLS: SIZE MATTERS. [Online]. Available: https://www.wired.com/2011/12/cannon-balls-size-matters/
- [5] P. S. Foundation. Python 3.7.3rc1 documentation. [Online]. Available: https://docs.python.org/3/
- [6] M. Williams. How strong is the force of gravity on Earth? [Online]. Available: https://phys.org/news/2016-12-strong-gravity-earth.html
- [7] A. M. Helmenstine. What Is the Density of Air at STP? [Online]. Available: https://www.thoughtco.com/density-of-air-at-stp-607546
- [8] M. development team. Markevery Demo. [Online]. Available: https://matplotlib.org/gallery/lines_bars and markers/markevery demo.html
- [9] —. matplotlib.pyplot.annotate. [Online]. Available: https://matplotlib.org/api/_as_gen/matplotlib.pyplot.annotate.html

Test Plan 1

No.	Test Description	Test Data		Expected outcome	Actual outcome	Improvements
-	Test if parameters within range are recorded properly.	Mass – 10kg Speed – 100 m/s Step – 0.005 s	Height – 5 meters Area – 0.02 m² Angle – 30 degrees	All values should be recorded and displayed in show current parameters console display.		
2	Test if parameters below range are rejected and default value is used.	Mass – 0kg Speed – 5 m/s Step – 0.0001 s	Height – -10 meters Area – 0.00001 m² Angle – 0 degrees	All values should be rejected and the default values are displayed in show current parameters console display.		
c	Test if parameters above range are rejected and default value is used.	Mass – 50 kg Height – 50 Speed – 300 m/s Area – 5 m² Step – 10 s Angle – 180	Height – 50 meters Area – 5 m² Angle – 180 degrees	All values should be rejected and the default values are displayed in show current parameters console display.		
4	Test if letters are input for parameters.	Mass – heavy Speed – fast Step – daily	Height – high Area – average Angle – fish	All values should be rejected and the default values are displayed in show current parameters console display.		
5	Test if symbols are input for parameters.	Mass – ! Speed – # Step – %	Height – @ Area – \$ Angle – ^	All values should be rejected and the default values are displayed in show current parameters console display.		
9	Test if no values are input for parameters.	Mass – Speed – Step –	Height – Area – Angle –	All values should be rejected and the default values are displayed in show current parameters console display.		

Figure 3: Test-1 template

Test Plan 2

No.	Test Description	Test Data	Expected outcome	Actual outcome	Improvements
П	Try command 2 (show parameters) with default parameter.	Command 2	Console output will proceed to display parameters when command 2 is selected.		
2	Try command 3 (calculate data) with default parameter.	Command 3	Console output will proceed to calculate data when command 3 is selected.		
3	Try command 4 (analyse data) with default parameter and data set calculated.	Command 4	Console output will proceed to display analysis of the data calculated when command 4 is selected then		
4	Try command 5 (plot graph) to display graph 1 with default parameter and data set calculated.	Command 5,	Console output will proceed to display another menu for a selection of graphs and graph 1 will be displayed when selected.		
5	Try command 5 (plot graph) to display graph 2 with default parameter and data set calculated.	Command 5, Command 2	Console output will proceed to display another menu for a selection of graphs and graph 2 will be displayed when selected.		
9	Try command 6 (save data) with default parameter and data set calculated.	Command 6	The data set will be save in a csv file named "Projectile_Motion".		
7	Try command 7 (run simulation) with default parameter and data set calculated.	Command 7	Simulation will run when the user press any key and stop either when the user presses any key again or when the cannonball reaches the ground again.		

Figure 4: Test-2 template

est Plan 3

No.	Test Description	Test Data	Expected outcome	Actual outcome	Improvements
1	Try command 2 (show parameters) without input parameters	Command 2	Console output will inform user that no parameters have been input.		
2	Try command 3 (calculate data) without input parameters	Command 3	Console output will inform user that no parameters have been input.		
ო	Try command 4 (analyse data) without input parameters	Command 4	Console output will inform user that no parameters have been input.		
4	Try command 5 (plot graph) without input parameters	Command 5	Console output will inform user that no parameters have been input.		
5	Try command 6 (save data) without input parameters	Command 6	Console output will inform user that no parameters have been input.		
9	Try command 7 (run simulation) without parameters	Command 7	Console output will inform user that no parameters have been input.		
7	Try command 4 (analyse data) with parameters but without calculating data set	Command 4	Console output will inform user that data has not been calculated.		
oo oo	Try command 5 (plot graph) with parameters but without calculating data set	Command 5	Console output will inform user that data has not been calculated.		
6	Try command 6 (save data) with parameters but without calculating data set	Command 6	Console output will inform user that data has not been calculated.		
10	Try command 7 (run simulation) with parameters but without calculating data set	Command 7	Console output will inform user that data has not been calculated.		
11	Try command quit (quit program)	Command quit	Console output will inform user that program is quitting		

Figure 5: Test-3 template

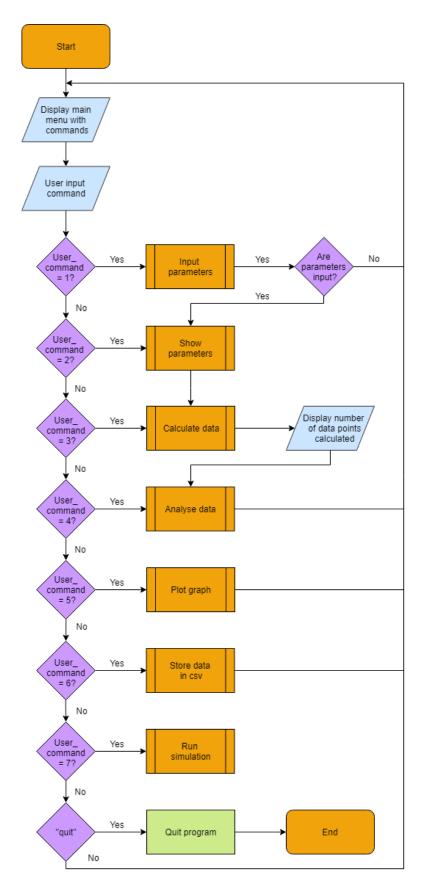


Figure 6: Flowchart: main program

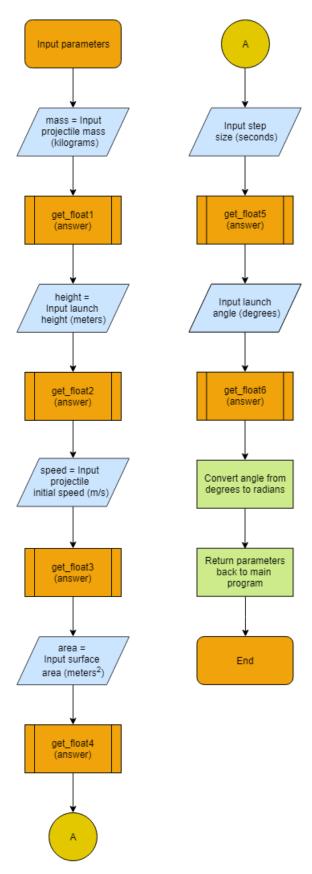


Figure 7: Flowchart: function to input parameters projectile motion simulation data

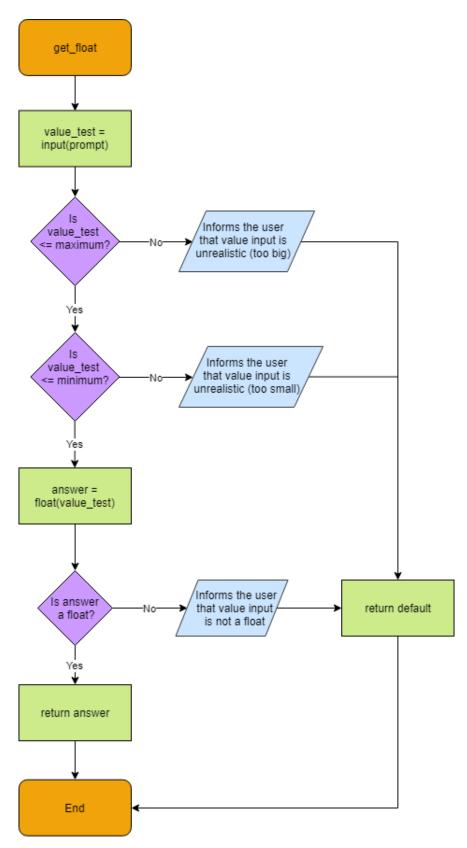


Figure 8: Flowchart: function to ensure user input realistic parameters

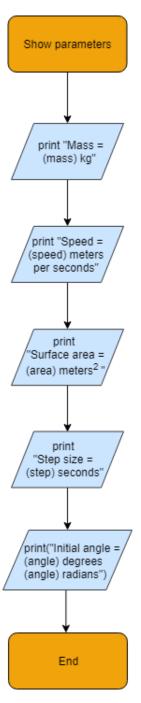


Figure 9: Flowchart: function to show current parameters

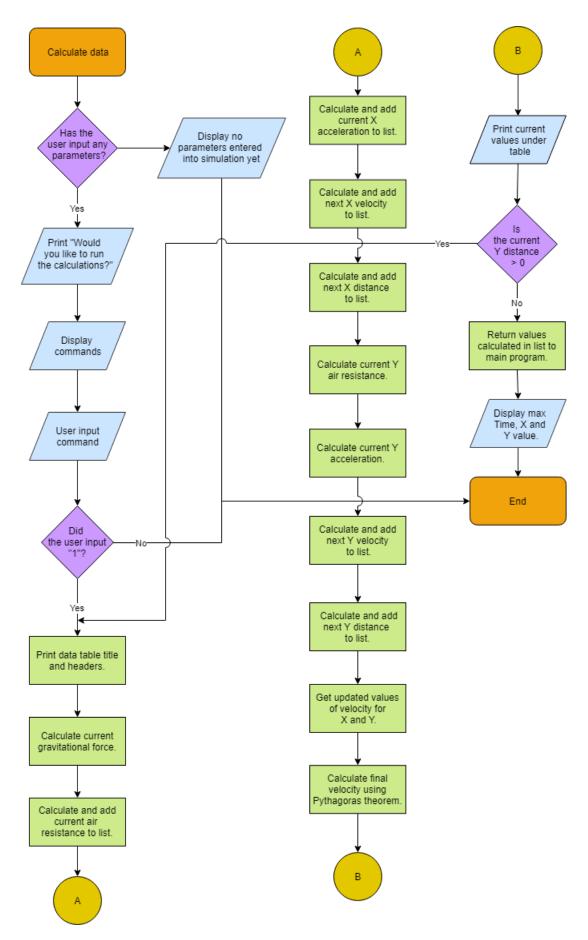


Figure 10: Flowchart: function to calculate projectile motion simulation data

DUICS/IFY/PT/Project 2019

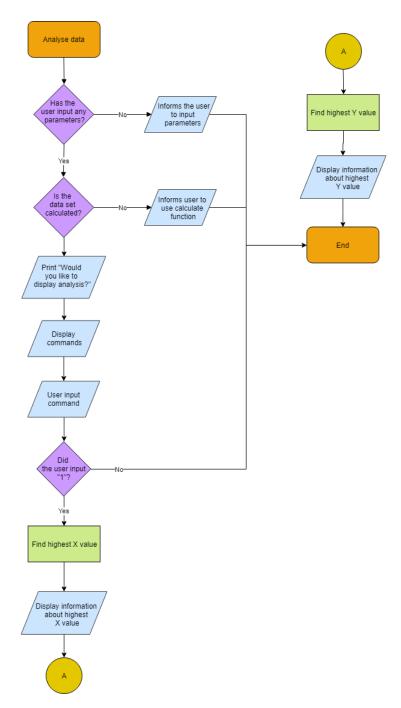


Figure 11: Flowchart: function to display analysis for the data calculated

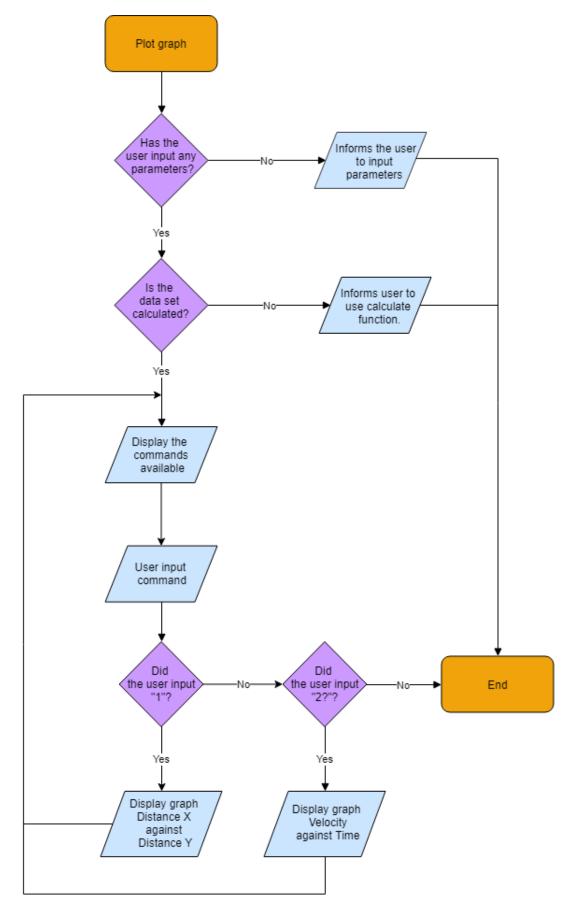


Figure 12: Flowchart: function to display graphs

DUICS/IFY/PT/Project 2019

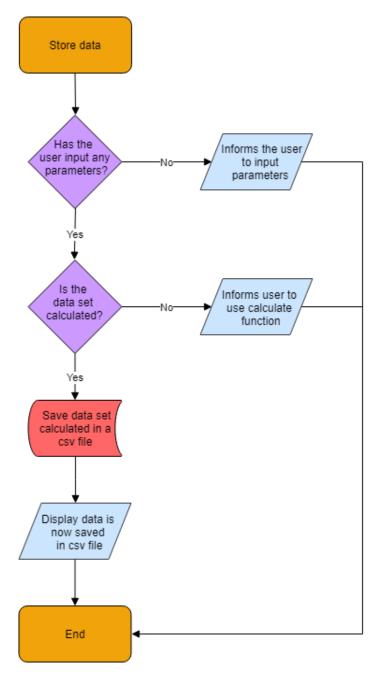


Figure 13: Flowchart: function to display graphs

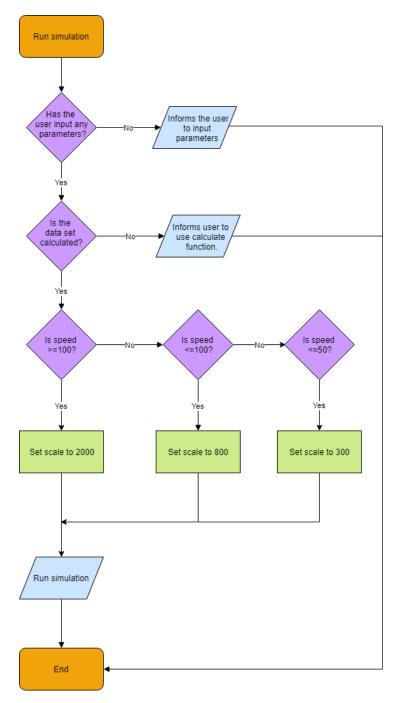


Figure 14: Flowchart: function to run simulation

Test Plan 1

No.	Test Description	Test Data		Expected outcome	Actual outcome	Improvements
П	Test if parameters within range are recorded properly.	Mass – 10kg Speed – 100 m/s Step – 0.005 s	Height – 5 meters Area – 0.02 m² Angle – 30 degrees	All values should be recorded and displayed in show current parameters console display.	The actual outcome is as expected.	N/A
2	Test if parameters below range are rejected and default value is used.	Mass – Okg Speed – 5 m/s Step – 0.0001 s	Height – -10 meters Area – 0.00001 m² Angle – 0 degrees	All values should be rejected and the default values are displayed in show current parameters console display.	The actual outcome is as expected.	More details (default value) can be stated when user input is rejected.
m	Test if parameters above range are rejected and default value is used.	Mass – 50 kg Height – 50 Speed – 300 m/s Area – 5 m² Step – 10 s Angle – 180	Height – 50 meters Area – 5 m² Angle – 180 degrees	All values should be rejected and the default values are displayed in show current parameters console display.	The actual outcome is as expected.	More details (default value) can be stated when user input is rejected.
4	Test if letters are input for parameters.	Mass – heavy Speed – fast Step – daily	Height – high Area – average Angle – fish	All values should be rejected and the default values are displayed in show current parameters console display.	The actual outcome is as expected.	More details (default value) can be stated when user input is rejected.
2	Test if symbols are input for parameters.	Mass – ! Speed – # Step – %	Height – @ Area – \$ Angle – ^	All values should be rejected and the default values are displayed in show current parameters console display.	The actual outcome is as expected.	More details (default value) can be stated when user input is rejected.
9	Test if no values are input for parameters.	Mass – Speed – Step –	Height – Area – Angle –	All values should be rejected and the default values are displayed in show current parameters console display.	The actual outcome is as expected.	More details (default value) can be stated when user input is rejected.

Figure 15: Test-1 Completed

7
Ę
吕
بز
es

No.	Test Description	Test Data	Expected outcome	Actual outcome	Improvements
₽	Try command 2 (show parameters) with default parameter.	Command 2	Console output will proceed to display parameters when command 2 is selected.	The actual outcome is as expected.	N/A
7	Try command 3 (calculate data) with default parameter.	Command 3	Console output will proceed to calculate data when command 3 is selected.	The actual outcome is as expected.	N/A
m	Try command 4 (analyse data) with default parameter and data set calculated.	Command 4	Console output will proceed to display analysis of the data calculated when command 4 is selected then	The actual outcome is as expected.	N/A
4	Try command 5 (plot graph) to display graph 1 with default parameter and data set calculated.	Command 5,	Console output will proceed to display another menu for a selection of graphs and graph 1 will be displayed when selected.	The actual outcome is as expected.	N/A
5	Try command 5 (plot graph) to display graph 2 with default parameter and data set calculated.	Command 5,	Console output will proceed to display another menu for a selection of graphs and graph 2 will be displayed when selected.	The actual outcome is as expected.	N/A
9	Try command 6 (save data) with default parameter and data set calculated.	Command 6	The data set will be save in a csv file named "Projectile_Motion".	The actual outcome is as expected.	Allow the csv to open when the data has been saved successfully.
7	Try command 7 (run simulation) with default parameter and data set calculated.	Command 7	Simulation will run when the user press any key and stop either when the user presses any key again or when the cannonball reaches the ground again.	The actual outcome is as expected.	Better visualisation of the cannon in graphics module.

Figure 16: Test-2 Completed

Test Plan 3

7	Try command 2 (show	Command 2	Console output will inform user that no	The actual	Allow use to skip to input
	parameters) without		parameters have been input.	outcome is as	parameters after displaying no
	input parameters			expected.	מושווברבו אושאב מבבוו ווומתר
2	Try command 3 (calculate	Command 3	Console output will inform user that no	The actual	Allow use to skip to input
	data) without input parameters		parameters mave been input.	expected.	parameters arter displaying no parameters have been input
3	Try command 4 (analyse data) without input	Command 4	Console output will inform user that no parameters have been input.	The actual outcome is as	Allow use to skip to input parameters after displaying no
	parameters			expected.	parameters have been input
4	Try command 5 (plot	Command 5	Console output will inform user that no	The actual	Allow use to skip to input
	graph) without input parameters		parameters have been input.	outcome is as expected.	parameters after displaying no parameters have been input
5	Try command 6 (save	Command 6	Console output will inform user that no	The actual	Allow use to skip to input
)	data) without input		parameters have been input.	outcome is as	parameters after displaying no
	parameters			expected.	parameters have been input
9	Try command 7 (run	Command 7	Console output will inform user that no	The actual	Allow use to skip to input
	simulation) without		parameters have been input.	outcome is as	parameters after displaying no
	parameters			expected.	parameters have been input
7	Try command 4 (analyse	Command 4	Console output will inform user that	The actual	Allow use to skip to calculate data
	data) with parameters but		data has not been calculated.	outcome is as	after data has not been calculated.
	without calculating data			expected.	
	set				
oo	Try command 5 (plot	Command 5	Console output will inform user that	The actual	Allow use to skip to calculate data
	graph) with parameters		data has not been calculated.	outcome is as	after data has not been calculated.
	data set				
6	Try command 6 (save	Command 6	Console output will inform user that	The actual	Allow use to skip to calculate data
	data) with parameters but		data has not been calculated.	outcome is as	after data has not been calculated.
	without calculating data			expected.	
,)	-	3-11	1	All
10	Iry command / (run simulation) with	Command /	Console output will inform user that data has not been calculated.	The actual outcome is as	Allow use to skip to calculate data after data has not been calculated.
	parameters but without			expected.	
	calculating data set				
11	Try command quit (quit	Command quit	Console output will inform user that	The actual	N/A
	program)		program is quitting	outcome is as expected.	

Figure 17: Test-3 Completed

O		Displacement	0.706561184	1.412719966	2.118476802	2.82383215	3.528786468	4.23334021	4.937493832	5.641247789	6.344602534	7.047558519		Displacement	0.705866099	1.410350386	2.113454432	2.815179803	3.51552806	4.21450076	4.912099453	5.608325687	6.303181004	6.99666694
Ь		Velocity (m/s)	70.65611844	70.61587811	70.57568361	70.53553484	70.49543175	70.45537424	70.41536224	70.37539568	70.33547447	70.29559854		Velocity (m/s)	70.58660991	70.44842872	70.31040461	70.1725371	70.03482571	69.89726995	69.75986934	69.6226234	69.48553166	69.34859364
0	X Current	Acceleration (m/s**2) Velocity (m/s)	4.028623096	4.024032996	4.019450737	4.014876302	4.010309674	4.005750833	4.001199764	3.996656447	3.992120866	3.987593003	Y Current	Air resistance (m/s**2) Acceleration (m/s**2) Velocity (m/s)	13.8338769	13.81811954	13.80241092	13.78675089	13.77113929	13.75557595	13.74006073	13.72459345	13.70917398	13.69380214
Z		Air resistance (m/s**2)	22.15742703	22.13218148	22.10697905	22.08181966	22.05670321	22.03162958	22.0065987	21.98161046	21.95666476	21.93176151		Air resistance (m/s**2)	22.17532297	22.08865747	22.00226007	21.91612991	21.83026609	21.74466775	21.65933401	21.574264	21.48945686	21.40491174
Σ		Gravitational force	53.911	53.911	53.911	53.911	53.911	53.911	53.911	53.911	53.911	53.911												
٦		٨	70.72494868	70.58660991	70.44842872	70.31040461	70.1725371	70.03482571	69.89726995	69.75986934	69.6226234	69.48553166												
¥	Velocity(m/s)	×	70.69640468	70.65611844	70.61587811	70.57568361	70.53553484	70.49543175	70.45537424	70.41536224	70.37539568	70.33547447												
ſ		Total	100	99.87370311	99.74759822	99.62168495	99.49596293	99.37043176	99.24509109	99.11994053	98.9949797	98.87020825												
_		Time(Seconds)	0	0.01	0.02	0.03	0.04	0.05	90.0	0.07	0.08	0.09												
I		Step	1	2	3	4	2	9	7	∞	6	10												
g																								
ш	Equations	1. Initial X Velocity	1. Initial Y Velocity	2. Gravitational force	3. X Air resistance	4. X Acceleration	5 X Velocity	6. X Distance	7. Y Air resistance	8. Y Acceleration	9. Y Velocity	10. Y Distance	10. Velocity from X and Y											

Figure 23: Dry run done in excel manually

Appendix

A Code: Projectile Motion Simulator

Listing 1: Python Code

```
1 # Jia Xiu Sai
2 # 2427165
3 # 07/04/2019
4 # Project - Projectile motion simulation
7 # Import modules.
9 import os
10 import datetime
11 import math
12 import matplotlib.pyplot as plt
13 import csv
14 import time
15 from graphics import *
17
18 # Functions
20 # Checks if value input by user is resonable/float.
21 def get_float(prompt, default, minimum, maximum):
22
    value_test = input(prompt)
23
24
    # Test if the value input is a float.
25
26
    try:
27
28
      # Test if the value input is reasonable.
      if(float(value_test) <= maximum):</pre>
29
30
        if(float(value_test)>=minimum):
31
32
          # Test if the value input is a float.
33
          answer = float(value_test)
34
35
          print(" Value recorded.")
36
          # If the value input is a float, the value is returned back to the main program.
37
39
        # If the value input is unrealistic, the default value that was set beforehand is
40
      returned to the main program.
        else:
41
          print(" Oops! The value of the number is too small. Using default value.")
42
          return default
43
44
      # If the value input is unrealistic, the default value that was set beforehand is
      returned to the main program.
46
      else:
        print(" Oops! The value of the number is too big. Using default value.")
47
        return default
48
49
    # If the value input is not a float, a ValueError will appear and the default value that
50
      was set beforehand is returned to the main program.
    except ValueError:
      print(" Oops! That was not a valid number. Using default value.")
return default
52
53
54
55 # End of function get_float
58 # Lets the user change the current parameters.
59 def change_para():
60
61
   os.system('cls')
   print (program_info)
```

```
print(" Function: Change parameters")
63
     print (line*30)
64
65
     # The parameters are input by user:
66
67
     # Mass of projectile object (kilograms).
     # Height of initial projection (meters).
69
70
     # Initial speed of projectile (meter per second).
     # Frontal area of object (meters square).
71
     # The step size (seconds).
72
    # Initial angle (degrees).
73
     mass = get_float(" Enter the mass of the cannonball in kg (1-20): ",5.5,1,20)
74
     height = get_float(" Enter the initial height (0-10): ",0,0,10)
75
     speed = get_float(" Enter the initial speed of the cannonball in m/s (10-200): "
       ,100,10,200)
     area = get_float(" Enter the frontal area of cannonball in meters\u00b2 (0.005-1): "
77
       ,0.0154,0.005,1)
     step = get_float(" Enter the step size in seconds (0.001-1): ",0.01,0.001,1)
     ang_in_deg = get_float(" Enter the initial angle in degrees (10-90): ",45,10,90)
79
     # The angle is converted from degrees into radians.
80
     ang_in_rad = math.radians(ang_in_deg)
81
     # Parameters are returned back to the main program.
83
84
    return mass,height,speed,area,step,ang_in_deg,ang_in_rad
86 # End of function change_para
87 #----
89\ \mbox{\#} Show current parameters input by user.
90 def show_current_para(mass,height,speed,area,step,ang_in_deg,ang_in_rad):
91
     os.svstem('cls')
92
93
    print (program_info)
    print(" Function: Show current parameters")
94
    print (line*30)
95
    print(" Current parameters of projectile object:")
96
97
    # Prints the parameters input by user.
    print(" Mass = %.2f kg" %(mass))
print(" Height = %.1f meters" %(height))
99
100
    print(" Speed = %.2f meters per seconds" %(speed))
101
    print(" Surface area = %.4f meters\u00b2" %(area))
102
     print(" Step size = %s seconds" %(step))
103
    print(" Initial angle = %.2f degrees (%0.2f radians)" %(ang_in_deg,ang_in_rad))
104
105
106 # End of function show_current_para
107 #-----
108
_{109} # Calculates the data set using the parameters input by user.
def calculate_data(mass, height, speed, area, step, ang_in_deg, ang_in_rad):
111
112
     # Ask if user wants to calculate data.
    print("\n Would you like to run calculations?")
113
    print("\n 1: Yes\n Press any key to go back to main menu.")
114
     user_command = input("\n Enter command: ")
115
116
     # When '1' is input, continue to run function calculate_data.
117
    if (user_command == '1'):
118
119
                         # Iteration (i.e. step)
120
      i = int(0)
      t_current = float(0) # Current time value (seconds)
121
       t_next = float(0)  # Next time value (seconds)
122
       fd_current = float(0) # Current air resistance (newtons)
123
       fd_next = float(0)
                             # Next air resistance (newtons)
124
      # Values for X-coordinates:
126
      x_current = float(0) # Current distance (meters)
127
       x_next = float(0) # Next distance (meters)
128
       xv_current = float(0) # Current velocity (meters/seconds)
129
       xv_next = float(0)
                             # Next velocity (meters/seconds)
130
131
       # Values for Y-coordinates:
132
       y_current = float(0) # Current distance (meters)
```

```
y_next = float(0)
                           # Next distance (meters)
134
       yv_current = float(0) # Current velocity (meters/seconds)
135
136
       yv_next = float(0)
                              # Next velocity (meters/seconds)
137
       v_current = float(0) # Current velocity (meters/seconds)
138
       v_next = float(0)
                           # Next velocity (meters/seconds)
139
140
       # Fixed parameters:
141
       g = 9.807  # Gravity on Earth (meters/second square)
142
                     # Drag coefficient of a ciruclar smooth surface
       drag = 0.47
143
       a_d = 1.225 # Air density at sea-level (kg/m**3)
144
145
       # Lists:
146
147
       t = []
                  # Holds time data
       x = []
                  # Holds distance data for X axis
148
       y = []
                 # Holds distance data for Y axis
149
       xv = []
                 # Holds velocity data for X axis
150
       yv = []
                 # Holds velocity data for Y axis
       v = []
152
                 # Holds total velocity data
       t_sim_run = float(0)
                                # Current simulation run time (seconds)
154
155
       # Set the initial values and add to data lists.
156
       t.append(0.0)
       x.append(0.0)
158
       y.append(height)
159
       xv.append(speed*math.cos(ang_in_rad))
160
       yv.append(speed*math.sin(ang_in_rad))
161
       v.append(speed)
162
163
       os.system('cls')
164
       print (program_info)
165
166
       print(" Function: Calculate and show current data set")
       print (line*30)
167
168
       # Title and header of the table.
169
       print("\n Data table:\n")
       print(" Step| Time | X_Velocity | Y_Velocity | Velocity | X_Distance |
171
       Y_Distance")
       # Loop to create data points.
173
174
175
       # Makes this function run until object lands on the ground.
176
       while (y_current >= 0):
177
178
         # Get current values
179
         t_current = t[i]
180
         x_current = x[i]
181
         y_current = y[i]
182
         xv_current = xv[i]
183
184
         yv_current = yv[i]
         v_current = v[i]
185
186
         # Calculate current gravitational force.
187
         fg_current = (mass*g)
188
         # Calculate and add current X air resistance to list.
190
         xfd_current = 0.5*xv_current*abs(xv_current)*drag*area*a_d
191
192
         \mbox{\tt\#} Calculate and add current X acceleration to list.
193
         xa_current = (xfd_current)/mass
194
195
         # Calculate and add next X velocity to list.
196
         xv.append(xv_current - (xa_current*step))
197
198
199
         \mbox{\tt\#} Calculate and add next X distance to list.
         x.append(x_current + (xv_current*step))
200
201
         # Calculate current Y air resistance.
202
203
         yfd_current = 0.5*yv_current*abs(yv_current)*drag*area*a_d
204
205
         # Calculate current Y acceleration.
```

```
ya_current = (fg_current + yfd_current)/mass
206
207
                 # Calculate and add next Y velocity to list.
208
                yv.append(yv_current - (ya_current*step))
209
210
                 # Calculate and add next Y distance to list.
                y.append(y_current + (yv_current*step))
212
213
                 # Get updated values of X velocity and Y velocity.
214
                 xv_current = xv[i+1]
215
216
                 yv_current = yv[i+1]
217
                 # Calculate final velocity using pythagoras theorem.
218
                 v.append(math.sqrt((xv_current*xv_current)+(yv_current*yv_current)))
220
221
                 # Calculate and next time to list.
                t.append(t_current + step)
222
223
                 # Update the simulation run time.
224
                 t_sim_run = t_sim_run + step
225
226
                # Data table
                print(" %d | %.2f | %.3f | %.3
228
              ,t_current,xv_current,yv_current,v_current,x_current,y_current))
                 # Update the iteration / step.
230
231
                i = i + 1
232
233
             print (line*30)
234
             # Values in data lists are returned back to main program.
235
236
            return i,t,xv,yv,x,y,v
237
238 # End of function calculate_data
239 #-----
                                                                  _____
240
_{241} # Analyse the data calculated.
242 def analyse_data(mass,i,t,xv,yv,x,y,v):
243
         \mbox{\tt\#} Checks if any parameters is input by user.
244
         if (0 < (mass)):</pre>
245
246
             # Checks if data set is calculated.
247
            num_x = len(x)
248
            if (0 < num_x):</pre>
249
250
                 # Ask if the user wants to analyses data.
251
               print("\n Would you like to display analysis?")
252
                 print("\n 1: Yes\n Press any key to go back to main menu.")
                user_command = input("\n Enter command: ")
254
255
256
                 # When '1' is input, continue to run function calculate_data.
                if (user_command == '1'):
257
258
                     os.system('cls')
259
                     print (program_info)
260
                     print(" Function: Analyse data")
                    print (line*30)
262
263
                    print(" Data analysis:\n")
264
265
                    # Highest height achieved.
266
                    mx = max(x)
267
                     max_x = x.index(mx)
268
                     print(" Furthest distance achieved at:\n X-coordinate - %0.3f meters\n Y-coordinate
269
             - %0.3f meters\n Speed - %0.3f meter per seconds \n Time - %0.2f seconds \n" %(mx,y[
             max_x],v[max_x],t[max_x]))
                    # Furthest distance achieved.
271
                    my = max(y)
272
273
                     max_y = y.index(my)
                     print(" Highest distance achieved at:\n X-coordinate - %0.3f meters\n Y-coordinate -
274
               %0.3f meters\n Speed - %0.3f meter per seconds \n Time - %0.2f seconds " %(x[max_y],my,
```

```
v[max_y],t[max_y]))
275
            input ("\n Press any key to go back to main menu.")
276
277
         return i,t,xv,yv,x,y,v
278
279
       else:
280
         os.system('cls')
281
         print (program_info)
282
         print(" Function: Analyse data")
283
         print (line*30)
284
         print(" No data calculated yet.")
285
         input ("\nPress any key to go back to main menu.")
286
287
     # Informs the user to input parameters.
288
289
     else:
       os.system('cls')
290
       print (program_info)
291
       print(" Function: Analyse data")
292
293
       print (line*30)
       print(" No parameters enter yet.")
294
       input ("\n Press any key to go back to main menu.")
295
296
297 # End of function analysis_data
299
300 # Plots a graph using data set calculated.
301 def plot_graph(mass,i,t,xv,yv,x,y,v):
302
303
     # Checks if any parameters is input by user.
     if (0 < (mass)):</pre>
304
305
306
       # Checks if data set is calculated.
       num_x = len(x)
307
       if (0 < num_x):</pre>
308
309
         os.system('cls')
310
         print (program_info)
311
         print(" Function: Plot graph")
312
         print (line*30)
313
314
         # Show commands for different graphs.
315
         print("\n Commands| Graph:")
316
         print("
                    1 | Displacement Y against Displacement X")
317
         print("
                    2
                          | Velocity against Time")
318
         print("\n Input any key to go back to main menu.")
319
320
         user_command = input("\n Enter command: ")
321
         os.system('cls')
         print (program_info)
323
324
         print(" Function: Plot graph")
325
         print (line*30)
         print (" Plotting graph.....")
326
327
         # When '1' is input, display graph: Displacement Y against Displacement X.
328
         if (user_command == '1'):
329
           my = max(y)
331
            max_y = y.index(my)
332
           maxpoint = [max_y]
333
334
335
            # Plot graph with (x-axis,y-axis and line type).
            plt.plot(x,y,'b-x', ms=6, markevery=maxpoint)
336
337
            # Annotate the highest point on graph.
            my = max(y)
339
340
            max_y = y.index(my)
            x = (0,0), x = (0,0)
341
       *0.8))
342
343
            # Scale graph.
            plt.axis('scaled')
344
345
```

```
# X-axis label.
346
           plt.xlabel('Distance X (m)')
347
348
           # Y-axis label.
349
           plt.ylabel('Distance Y (m)')
350
351
           # Graph title.
352
353
           plt.title('Projectile Motion Simulation\nDisplacement Y against Displacement X')
354
           plt.ion()
355
           # Show graph created.
356
           plt.show()
357
           input ("\n Press any key to go back.")
358
359
           plt.close()
360
           # Return to function plot_graph.
361
           plot_graph(mass,i,t,xv,yv,x,y,v)
362
363
         # When '2' is input, display graph: Velocity against Time.
364
         if (user_command == '2'):
365
366
           \# Plot graph with (x-axis,y-axis and line type).
367
           plt.plot(t,v,'b-')
368
369
           # X-axis label
370
           plt.xlabel('Time (seconds)')
371
372
           # Y-axis label
373
           plt.ylabel('Velocity (m/s)')
374
375
           # Graph title
376
           plt.title('Projectile Motion Simulation\nVelocity against time')
377
           plt.ion()
378
379
380
           # Show graph created
           plt.show()
381
           input ("\n Press any key to go back.")
382
           plt.close()
383
384
           # Return to function plot_graph.
385
           plot_graph(mass,i,t,xv,yv,x,y,v)
386
387
       # Informs the user to use calculate function.
388
389
       else:
        os.system('cls')
390
391
         print (program_info)
         print(" Function: Plot graph")
392
        print (line*30)
393
         print(" No data calculated yet.")
394
         input ("\n Press any key to go back to main menu.")
395
396
397
     # Informs the user to input parameters.
398
     else:
       os.system('cls')
399
       print (program_info)
400
       print(" Function: Analyse data")
401
      print (line*30)
       print(" No parameters enter yet.")
403
       input ("\n Press any key to go back to main menu.")
404
405
406 # End of function plot_graph
407 #-----
408
409 # Save data set calculated in a csv file.
410 def save_data(mass,i,t,xv,yv,x,y,v):
411
412
     # Checks if any parameters is input by user.
     if (0 < (mass)):</pre>
413
414
415
       # Checks if data set is calculated.
       num_x = len(x)
416
       if (0 < num_x):</pre>
417
418
```

```
os.system('cls')
419
                 print (program_info)
420
421
                  print(" Function: Save data")
                 print (line*30)
422
423
                  # Open/create csv filed named "Projectile_Motion.csv' and enable write mode.
424
                 Projectile_Motion_csv = open("Projectile_Motion.csv", "w")
425
426
427
                  # Write column titles
                  Projectile_Motion_csv.write("Step, Time(Seconds), X_Velocity(m/s), Y_Velocity(m/s),
428
              Velocity(m/s), X_Distance(m), Y_Distance(m)")
429
                  num t = len(t)
430
431
                  # Runs this function for all data calculated stored in list/arrays.
432
                 for i in range(0,num_t):
433
434
                      # Record data calculated in different coloumns.
435
                     Projectile\_Motion\_csv.write("\n\d,\%.2f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,\%.3f,
436
              ],v[i],x[i],y[i]))
437
                  # Close csv file.
438
                 Projectile_Motion_csv.close()
439
440
                  # Informs user data is saved in file.
441
                  print(" Data is now saved in file name: 'Projectile_Motion.csv'.")
442
                  input ("\n Press any key to go back to main menu.")
443
444
              # Informs the user to use calculate function.
445
446
                 os.system('cls')
447
                print (program_info)
448
449
                 print(" Function: Save data")
                 print (line*30)
450
451
                 print(" No data calculated yet.")
                 input ("\n Press any key to go back to main menu.")
452
453
454
         # Informs the user to input parameters.
455
         else:
            os.system('cls')
456
             print (program_info)
457
             print(" Function: Save data")
458
              print (line*30)
459
             print(" No parameters enter yet.")
460
              input ("\n Press any key to go back to main menu.")
461
462
463 # End of function save data
464 #----
_{466} # Runs simulation with parameters input by user and the data calculated.
467 def run_simu(mass,height,speed,area,step,ang_in_deg,ang_in_rad,i,t,xv,yv,x,y,v):
468
         # Checks if any parameters is input by user.
469
         if (0 < (mass)):
470
471
             # Checks if data set is calculated.
472
            num_x=len(t)
473
             if (0 < num_x):</pre>
474
475
                  # Determine whether values are possible to display.
476
                if (0 >= (height)):
477
478
                     try:
479
                         os.system('cls')
480
                         print (program_info)
                         print(" Function: Run simulation")
482
483
                         print (line*30)
                         print (" Running simulation....")
484
485
                         # Run this simulation for speed above speed of 100.
486
                         if (100 < (speed)):</pre>
487
                             scale = 2000
488
489
```

```
# Run this simulation for speed under speed of 100.
490
              if (100 >= (speed)):
491
                scale = 800
492
493
              # Run this simulation for speed under speed of 50.
494
             if (50 >= (speed)):
                scale = 300
496
497
              # Set margin size.
498
              width_x = 1000
499
              length_y = 600
500
              centre_x = width_x/2
501
              centre_y = length_y/2
502
              start_x = height+50
503
              start_y = 500
504
505
              # Set projectile size.
506
             radius = 20
507
             radius_dot = 1
508
509
              # Print blank margin.
510
             win = GraphWin("Projectile Motion", width_x, length_y)
511
512
             # Path of projectile object.
513
             path = Circle(Point(start_x,start_y), radius_dot)
514
              path.setFill("#FF8500")
515
516
              path.setOutline("#FF8500")
             path.draw(win)
517
518
519
              # Projectile object.
              ball = Circle(Point(start_x, start_y), radius)
520
              ball.setFill("#4D4D4D")
521
522
              ball.draw(win)
523
524
              # Ground.
              ground= Rectangle(Point(0,start_y+radius), Point(width_x,length_y))
525
              ground.setFill("#53AF23")
526
              ground.draw(win)
527
528
              # Cannon 1.
529
              cannnon_1= Circle(Point(start_x,start_y), radius+5)
530
              cannnon_1.setFill("#000000")
531
532
              cannnon_1.draw(win)
533
534
              # Cannon 2.
              cannnon_2= Polygon(Point(start_x-15, start_y+15), Point(start_x+30, start_y-45),
       Point(start_x+55, start_y-15))
              cannnon_2.setFill("#000000")
536
              path.setOutline("#000000")
537
              cannnon_2.draw(win)
538
539
540
             cannnon_3= Circle(Point(start_x,start_y+17),10)
541
              cannnon_3.setFill("#8C611A")
542
              path.setOutline("#8C611A")
543
              cannnon_3.draw(win)
544
              # Create text area.
546
             message = Text(Point(centre_x,centre_y-150), 'Press any key to start')
547
             message.draw(win)
548
549
              # Create text area 2.
550
             message_2 = Text(Point(centre_x,centre_y-70), '')
551
             message_2.draw(win)
552
              # Create text area 3.
554
              message_3 = Text(Point(centre_x,570),"Mass = %.2f kg Height = %.1f meters Surface
555
                                   Angle = %.1f degrees " %(mass,height,area,ang_in_deg,))
        area = \%.4f meters\u00b2
             message_3.draw(win)
556
557
558
              # Create text area 4.
              message_4 = Text(Point(centre_x,30),"Projectile motion simulation \nJacob 2019")
559
              message_4.draw(win)
```

```
561
             # Create text area 5.
562
              message_5 = Text(Point(centre_x+350,centre_y+50)," ")
563
564
             message_5.draw(win)
565
             win.getKey()
566
567
             num_t = len(t)
568
569
             for i in range(1,num_t):
571
                # Start timing current time.
572
                start_time = time.time()
573
574
                # Change text area 1 to show changing parameters of running simulation.
575
                message.setText("Step=%d Time=%0.2f seconds Velocity=%0.2f m/s\nPress any key
576
       to stop" %(i,t[i],v[i]))
577
578
                # Calculate next position for object.
579
                next_delta_x = x[i]*(width_x/scale)
                next_delta_y = y[i]*(length_y/scale)
580
                next_x = start_x + next_delta_x
581
                next_y = start_y - next_delta_y
582
583
                # Draw path of projectile object.
584
                new_path = Circle(Point(next_x,next_y), radius_dot)
585
                new_path.setFill("#FF8500")
586
                new_path.setOutline("#FF8500")
587
588
               new_path.draw(win)
589
                # Draw projectile object.
590
                new_ball = Circle(Point(next_x,next_y), radius)
591
592
                new_ball.setFill("#4D4D4D")
594
                # Print new object position.
                new_ball.draw(win)
595
596
                # Calculate running time for simulation.
597
                elapsed_time = time.time() - start_time
598
599
                h = t[i]-t[i-1]
600
601
                \# Test if simulation is running same speed/ faster than real time.
602
                if (elapsed_time < h):</pre>
603
604
                  # Slow down simulation if simulation is running too fast.
605
                  time.sleep(h - elapsed_time)
606
                  message_2.setText("Real-time")
607
608
                # If simulation is too slow, continue running the simulation.
609
610
                else:
611
                  # Inform the user that simulation is not in real time.
612
                  message_2.setText("Not real time")
613
614
                # Undraw starting/current object.
615
                ball.undraw()
617
                # Make new object the current object.
618
                ball = new_ball
619
620
               path = new_path
621
                # End simulation when user press any key.
622
                keypress = win.checkKey()
623
                if (keypress !=""):
624
                  break
625
626
              # Show how long the simulation ran and the highest height achieved.
              mx = max(x)
628
              max_x = x.index(mx)
629
              message.setText("Press any key to exit.\nReal time = %0.2f seconds\n\nHighest
630
       distance achieved at :\n X-coordinate - %0.3f meters \n Y-coordinate - %0.3f meters" %(t
       [i],mx,y[max_x],))
```

```
631
             # Show the furthest distance achieved.
632
633
             my = max(y)
             max_y = y.index(my)
634
             message_5.setText("Furthest distance achieved at:\n X-coordinate - %0.3f meters\n
635
      Y-coordinate - %0.3f meters" %(x[max_y],my))
            win.getKey()
636
637
             win.close()
             return()
638
639
640
          except:
641
            print()
642
        # Informs that values are not able to simulate due to height.
        else:
644
           os.system('cls')
645
           print (program_info)
646
           print(" Function: Run simulation")
647
          print (line*30)
648
           print(" Unable to run simulation")
649
           input ("\n Press any key to go back to main menu.")
650
      # Informs the user to use calculate function.
652
653
      else:
        os.system('cls')
654
        print (program_info)
655
        print(" Function: Run simulation")
656
        print (line*30)
657
        print(" No data calculated yet.")
658
659
         input ("\n Press any key to go back to main menu.")
660
     # Informs the user to input parameters.
661
662
     else:
      os.system('cls')
663
664
      print (program_info)
      print(" Function: Run simulation")
665
      print (line*30)
666
      print(" No parameters enter yet.")
667
       input ("\n Press any key to go back to main menu.")
668
669
670 # End of function run simu.
671 #-----
672
673 # MAIN PROGRAM
674 now = datetime.datetime.now()
675 program_info = (" DUISC\n Projectile Motion Simulator\n Jia Xiu Sai-2427165\n %s:%2.f %s/%s
      /%s" %(now.hour, now.minute, now.day, now.month, now.year))
676 menu_options = {}
677 user_command = "nothing"
678
679 # Line used in program.
680 line ="-"
681
682 # Projectile parameters.
683 \text{ mass} = 0.0
684 height = 0.0
685 speed = 0.0
686 area = 0.0
687
688 # Sim parameters.
689 \text{ step} = 0.0
690 ang_in_rad = 0.0
691 ang_in_deg = 0.0
692
693 # Other variables.
694 t_0 = 0.0
695 i = 0.0
697 # Data list.
698 t = []
699 x = []
700 y = []
_{701} xv = []
```

```
702 yv = []
703 v = []
704
705 # Main menu function.
706 while (user_command != 'quit'):
707
     os.system('cls')
708
709
     print (program_info)
     print(" Main menu")
710
     print (line*30)
711
712
     # Print main menu and commands available.
713
     print (" Commands| Functions")
714
715
     print (line*30)
     print("
                       | Change parameters")
716
               1
     print("
                      | Show current parameters")
717
                 2
     print("
                      | Calculate and show current data set")
718
                 3
     print("
                      | Analyse data")
                 4
719
     print("
720
                5
                      | Plot graph")
721
     print("
                 6
                      | Save data")
     print("
                       | Run visuals")
                7
722
     print("
                quit | Quit program")
723
724
     user_command = input("\nEnter command: ")
725
726
     # When '1' is input, run function calculate_data.
727
     if (user_command == '1'):
728
729
       mass,height,speed,area,step,ang_in_deg,ang_in_rad = change_para()
730
731
       # Checks if any parameters is input by user.
       if (0 < (mass)):</pre>
732
733
734
          trv:
           show_current_para(mass,height,speed,area,step,ang_in_deg,ang_in_rad)
735
736
           i,t,xv,yv,x,y,v = calculate_data(mass,height,speed,area,step,ang_in_deg,ang_in_rad)
           print(" Number of data points for:")
737
           print(" Time - %d" %(len(t)-1))
738
           print(" Velocity - %d" %(len(v)-1))
print(" X - %d" %(len(x)-1))
739
740
           print(" Y - %d" %(len(y)-1))
741
           print (line*30)
742
           analyse_data(mass,i,t,xv,yv,x,y,v)
743
744
745
         except:
           print()
746
747
       # If no parameters are input by user yet, no parameters can be displayed.
748
749
       else:
         os.system('cls')
750
         print (program_info)
751
         print(" Function: Change parameters")
752
753
         print (line*30)
754
755
         # Informs the user to input parameters.
         print("No parameters enter yet.")
756
757
         # Stop the function to let the user choose when to exit to main menu.
758
         input ("\nPress any key to go back to main menu.")
759
760
     # When '2' is input, run function show current parameters.
761
     if (user_command == '2'):
762
763
       show_current_para(mass,height,speed,area,step,ang_in_deg,ang_in_rad)
764
       # Checks if any parameters is input by user.
765
       if (0 < (mass)):</pre>
766
767
768
         try:
            i,t,xv,yv,x,y,v = calculate_data(mass,height,speed,area,step,ang_in_deg,ang_in_rad)
769
            print(" Number of data points for:")
            print(" Time - %d" %(len(t)-2))
771
772
            print(" Velocity - %d" %(len(v)-2))
            print(" X - %d" %(len(x)-2))
773
            print(" Y - %d" %(len(y)-2))
774
```

```
print (line*30)
775
           analyse_data(mass,i,t,xv,yv,x,y,v)
776
777
778
           print()
779
780
       # If no parameters are input by user yet, no parameters can be displayed.
781
782
       else:
         os.system('cls')
783
         print (program_info)
784
         print(" Function: Show current parameters")
785
         print (line*30)
786
787
         # Informs the user to input parameters.
         print(" No parameters enter yet.")
789
790
         # Stop the function to let the user choose when to exit to main menu.
791
         input ("\n Press any key to go back to main menu.")
792
793
794
     # When '3' is input, run function calculate data.
     if (user_command == '3'):
795
796
       # Checks if any parameters is input by user.
797
       if (0 < (mass)):</pre>
798
799
800
         trv:
           i,t,xv,yv,x,y,v = calculate_data(mass,height,speed,area,step,ang_in_deg,ang_in_rad)
801
           print(" Number of data points for:")
802
           print(" Time - %d" %(len(t)-2))
803
            print(" Velocity - %d" %(len(v)-2))
804
           print(" X - %d" %(len(x)-2))
805
           print(" Y - %d" %(len(y)-2))
806
            print (line*30)
807
           analyse_data(mass,i,t,xv,yv,x,y,v)
808
809
         except:
810
           print()
811
       # If no parameters are input by user yet, no parameters can be displayed.
813
814
       else:
         os.system('cls')
815
         print (program_info)
816
         print(" Function: Calculate and show current data set")
817
         print (line*30)
818
819
820
         # Informs the user to input parameters.
         print(" No parameters enter yet.")
821
         input ("\n Press any key to go back to main menu")
822
823
     # When '4' is input, run function plot graph.
824
     if (user_command == '4'):
825
826
       analyse_data(mass,i,t,xv,yv,x,y,v)
827
     # When '5' is input, run function plot graph.
828
     if (user_command == '5'):
829
       plot_graph(mass,i,t,xv,yv,x,y,v)
830
831
     # When '6' is input, run function save data.
832
     if (user_command == '6'):
833
       save_data(mass,i,t,xv,yv,x,y,v)
834
835
     \mbox{\tt\#} When '7' is input, run function run simulation.
836
     if (user_command == '7'):
837
       run_simu(mass, height, speed, area, step, ang_in_deg, ang_in_rad,i,t,xv,yv,x,y,v)
838
     # When 'quit' is input, exit main menu function.
840
841
     if (user_command =='quit'):
       print ()
842
843
844\ \mbox{\#} End of main menu function.
845 print(" Quitting...");
846 print(" Program has ended");
847 print(" Bye");
```

```
848
849 # End of main program.
850 #-----
```