

CS49n – Using bits to control atoms

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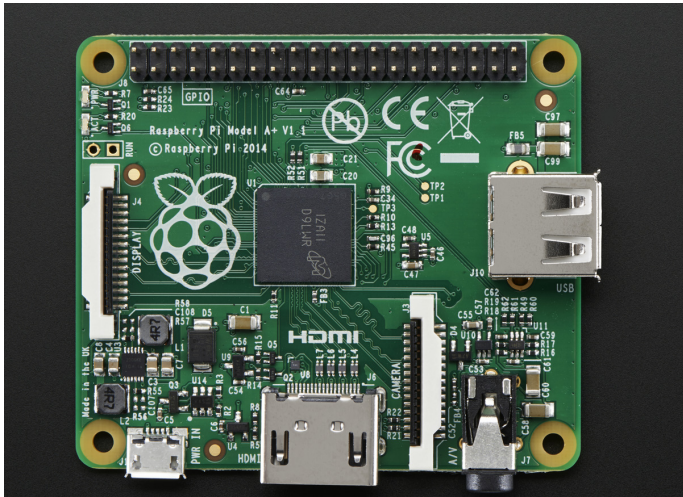
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Outline

1 What, Why

What

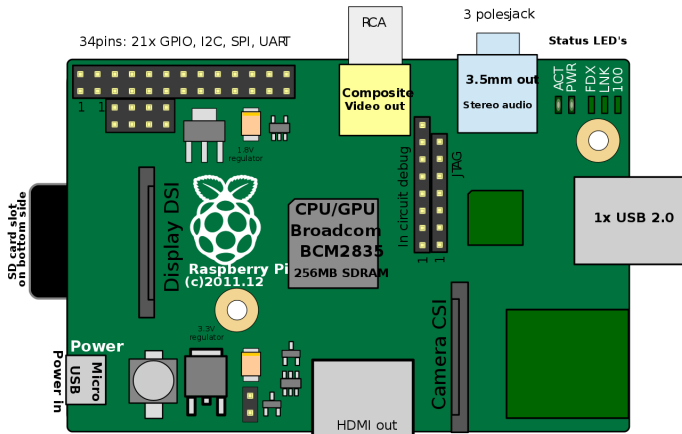
- Write small, clean pieces of code to control sensors and do interesting tricks on the raspberry pi A+.
 - https://en.wikipedia.org/wiki/Raspberry_Pi



What

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What you will build

- Sonar, IR, hall-effect, accelerometer, microphone.
- Interrupts.
- Network.
- I2C, SPI.
- Bootloader.
- Modern bug finding tricks.
- Final project: open ended. Expense account at [sparkfun](#)/[adafruit](#).

Why

- If you can write this kind of code, you can write pretty much anything.
- **No abstractions: will understand (a) reality.**
 - Once you get this, easy to delta to other examples.
- **The real world is not a clean, textbook chapter.**
 - Difficult to understand documents.
 - Wrong.
 - Incomplete.
 - Not written to be used.
 - You will learn how to orientate and operate in such a world, without a lot of drama.
 - We chose r/pi A+ because lots of useful blog posts for how to do things. (Later pi's are less helpful).

Why R/pi

- **Most OS classes (cs140) use a fake simulator.**
 - A lot of work. Not that cool at the end.
- **r/pi = real computer for about \$20.**
 - HDMI, SD card, memory: can put mouse, display, keyboard, have a lot of control.
- **Unlike most machines: Makes interacting with the real world very easy.**
 - Can build many interesting systems because can use weird hardware.
 - motion sensor, ir sensor, accelerometer, gyroscope, light sensor, etc.
- **Since bare metal: Very easy to build cool tools that are hard otherwise (gprof, eraser).**

You will develop two super-powers

- **Differential debugging.** You write code, it doesn't work. Error could be:
 - The code you wrote;
 - Hardware fault (smoked something);
 - Wiring mistake;
 - Subtle cache issue;
 - Compiler problem;
 - ...
 - You will get good at breaking down problems to isolate.
- **Epsilon-steps.**
 - Engler's theorem: Given a working system W_k and a change c , then as $c \rightarrow \epsilon$ then the time T it takes to figure out why $W_n + C$ doesn't work goes to 0 ($T \rightarrow 0$).
 - For a fixed amount of IQ, the smaller the step you can take from a working system, the faster you can debug when it doesn't work.