



Recap on Subtyping

Subsumption

Some types *are better* than others, in the sense that a value of one can *always safely be used* where a value of the other is expected.

Which can be formalized as by introducing:

1. a *subtyping* relation between types, written $S <: T$
2. a *rule of subsumption* stating that, if $S <: T$, then any value of type S can also be regarded as having type T

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Principle of safe substitution

Subtype Relation



$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\{1_i : T_i \mid i \in 1..n+k\} <: \{1_i : T_i \mid i \in 1..n\} \quad (\text{S-RCDWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\{1_i : S_i \mid i \in 1..n\} <: \{1_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDDEPTH})$$

$$\frac{\{k_j : S_j \mid j \in 1..n\} \text{ is a permutation of } \{1_i : T_i \mid i \in 1..n\}}{\{k_j : S_j \mid j \in 1..n\} <: \{1_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDPERM})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$

Syntax

$t ::=$

- x *terms:*
variable
- $\lambda x:T. t$ *abstraction*
- $t t$ *application*

$v ::=$

- $\lambda x:T. t$ *values:*
abstraction value

$T ::=$

- Top** *types:*
maximum type
- $T \rightarrow T$ *type of functions*

$\Gamma ::=$

- \emptyset *contexts:*
empty context
- $\Gamma, x:T$ *term variable binding*

Evaluation

 $t \rightarrow t'$

$$\frac{t_1 \rightarrow t'_1}{t_1 t_2 \rightarrow t'_1 t_2} \quad (\text{E-APP1})$$

$$\frac{t_2 \rightarrow t'_2}{v_1 t_2 \rightarrow v_1 t'_2} \quad (\text{E-APP2})$$

$$(\lambda x:T_{11}. t_{12}) v_2 \rightarrow [x \mapsto v_2] t_{12} \quad (\text{E-APPABS})$$

Subtyping

 $S <: T$ $S <: S$

(S-REFL)

$$\frac{S <: U \quad U <: T}{S <: T}$$

(S-TRANS)

 $S <: \text{Top}$

(S-TOP)

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

(S-ARROW)

Typing

 $\Gamma \vdash t : T$

$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T}$$

(T-VAR)

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2}$$

(T-ABS)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T}$$

(T-SUB)

Records



$\rightarrow \{\}$

Extends λ_{\rightarrow} (9-1)

New syntactic forms

$t ::= \dots$
 $\{l_i = t_i \mid i \in 1..n\}$
 $t.l$

terms:
record
projection

$v ::= \dots$
 $\{l_i = v_i \mid i \in 1..n\}$

values:
record value

$T ::= \dots$
 $\{l_i : T_i \mid i \in 1..n\}$

types:
type of records

New evaluation rules

$\{l_i = v_i \mid i \in 1..n\}.l_j \rightarrow v_j$

(E-PROJRCD)

$t \rightarrow t'$

$$\frac{t_1 \rightarrow t'_1}{t_1.l \rightarrow t'_1.l}$$

(E-PROJ)

$$t_j \rightarrow t'_j$$

(E-RCD)

$$\frac{\{l_i = v_i \mid i \in 1..j-1, l_j = t_j, l_k = t_k \mid k \in j+1..n\}}{\rightarrow \{l_i = v_i \mid i \in 1..j-1, l_j = t'_j, l_k = t_k \mid k \in j+1..n\}}$$

New typing rules

$\boxed{\Gamma \vdash t : T}$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_i = t_i \mid i \in 1..n\} : \{l_i : T_i \mid i \in 1..n\}}$$

(T-RCD)

$$\frac{\Gamma \vdash t_1 : \{l_i : T_i \mid i \in 1..n\}}{\Gamma \vdash t_1.l_j : T_j}$$

(T-PROJ)

Records & Subtyping



$\rightarrow \{\}$ $<:$

Extends $\lambda_{<}$ (15-1) and simple record rules (15-2)

New subtyping rules

$S <: T$

$\{\tau_i : T_i^{i \in 1..n+k}\} <: \{\tau_i : T_i^{i \in 1..n}\}$ (S-RCDWIDTH)

$$\frac{\text{for each } i \quad S_i <: T_i}{\{\tau_i : S_i^{i \in 1..n}\} <: \{\tau_i : T_i^{i \in 1..n}\}} \text{ (S-RCDDEPTH)}$$

$\{k_j : S_j^{j \in 1..n}\}$ is a permutation of $\{\tau_i : T_i^{i \in 1..n}\}$

$\{k_j : S_j^{j \in 1..n}\} <: \{\tau_i : T_i^{i \in 1..n}\}$

(S-RCDPERM)



Properties of Subtyping

Safety



Do the Statements of progress and preservation theorems need change?

Statements of progress and preservation theorems are unchanged from λ_{\rightarrow} .

Safety



Statements of **progress** and **preservation** theorems are unchanged from λ_{\rightarrow} .

However, Proofs become a bit *more involved*, because the typing relation is no longer *syntax directed*.

Given a derivation, *we don't always know what rule was used* in the last step.

e.g., the rule **T-SUB** could appear anywhere.

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Syntax-directed rules



When we say a set of rules is syntax-directed we mean two things:

1. There is *exactly one rule* in the set that applies to each syntactic form. (We can tell by the syntax of a term which rule to use.)
 - In order to derive a type for $t_1 t_2$, we must use **T-App**.
2. We don't have to “*guess*” an input (or output) for any rule.
 - To derive a type for $t_1 t_2$, we need to derive a type for t_1 and a type for t_2 .

Preservation



Theorem: If $\Gamma \vdash t : T$ and $t \rightarrow t'$, then $\Gamma \vdash t' : T$.

*Proof: By induction on **typing derivations**.*

Which cases are likely to be **hard**?

Subsumption case



Case T-Sub: $t : S \quad S <: T$

By the induction hypothesis, $\Gamma \vdash t' : S$.

By T-Sub, $\Gamma \vdash t' : T$.

Not hard!



Application case

Case **T-App**:

$$t = t_1 \ t_2 \quad \Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

By the inversion lemma for evaluation, there are *three rules* by which $t \rightarrow t'$ can be derived:

E-App1, E-App2, and E-AppAbs.

Proceed by cases.

Application case

Case **T-App** :

$$t = t_1 \ t_2 \quad \Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

By the evaluation rules in Figure 15-1 and 15-2, there are *three rules* by which $t \rightarrow t'$ can be derived:

E-App1, E-App2, and E-AppAbs.

Proceed by cases.

Subcase **E-App1**: $t_1 \rightarrow t'_1 \quad t' = t'_1 \ t_2$

The result follows from the induction hypothesis and **T-App**.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$

Application case

Case **T-App** :

$$t = t_1 t_2 \quad \Gamma \vdash t_1 : T_{11} \longrightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

Subcase **E-App2** : $t_1 = v_1 \quad t_2 \longrightarrow t'_2 \quad t' = v_1 t'_2$

Similar.

$$\frac{\Gamma \vdash t_1 : T_{11} \longrightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

$$\frac{t_2 \longrightarrow t'_2}{v_1 t_2 \longrightarrow v_1 t'_2} \quad (\text{E-APP2})$$

Application case

Case **T-App**:

$$t = t_1 \ t_2 \quad \Gamma \vdash t_1 : T_{11} \longrightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

Subcase **E-AppAbs**:

$$t_1 = \lambda x : S_{11}. t_{12} \quad t_2 = v_2 \quad t' = [x \mapsto v_2] t_{12}$$

by the *inversion lemma* for the typing relation ...

$$T_{11} <: S_{11} \quad \text{and} \quad \Gamma, x : S_{11} \vdash t_{12} : T_{12}.$$

By using **T-Sub**, $\Gamma \vdash t_2 : S_{11}$.

by the *substitution lemma*, $\Gamma \vdash t' : T_{12}$.

$$\frac{\Gamma \vdash t_1 : T_{11} \longrightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$

$$(\lambda x : T_{11}. t_{12}) \ v_2 \longrightarrow [x \mapsto v_2] t_{12} \quad (\text{E-APPABS})$$



Inversion Lemma for Typing

Lemma(15.3.3): If $\Gamma \vdash \lambda x: S_1. s_2: T_1 \rightarrow T_2$, then
 $T_1 <: S_1$ and $\Gamma, x: S_1 \vdash s_2: T_2$.

Proof: *Induction on typing derivations.*

Case T-Sub: $\lambda x: S_1. s_2: U$ $U: T_1 \rightarrow T_2$

We want to say “By the induction hypothesis...”, but the IH does not apply (since we do not know that U is an arrow type).

Need another lemma...

Lemma (15.3.2): If $U <: T_1 \rightarrow T_2$, then U has the form of
 $U_1 \rightarrow U_2$,

with $T_1 <: U_1$ and $U_2 <: T_2$.

(*Proof:* by *induction on subtyping derivations.*)



Inversion Lemma for Typing

By **this lemma**, we know

$U = U_1 \rightarrow U_2$, with $T_1 <: U_1$ and $U_2 <: T_2$.

The **IH** now applies, yielding

$U_1 <: S_1$ and $\Gamma, x: S_1 \vdash s_2: U_2$.

From $U_1 <: S_1$ and $T_1 <: U_1$, rule **S-Trans** gives

$T_1 <: S_1$.

From $\Gamma, x: S_1 \vdash s_2: U_2$ and $U_2 <: T_2$, rule **T-Sub** gives

$\Gamma, x: S_1 \vdash s_2: T_2$,

and we are done.

Progress



Theorem: If t is a closed, well-typed term, then either t is a value or else there is some t' , with and $t \rightarrow t'$

*Proof: By induction on **typing derivations**.*

Which cases are likely to be **hard**?

case T-APP

case T-RCD

case T-PROJ

case T-SUB



Subtyping with Other Features

Ascription and Casting



Ordinary ascription:

$$\frac{\Gamma \vdash t_1 : T}{\Gamma \vdash t_1 \text{ as } T : T} \quad (\text{T-ASCRIIBE})$$

$$v_1 \text{ as } T \longrightarrow v_1 \quad (\text{E-ASCRIIBE})$$

Ascription and Casting



Ordinary ascription:

$$\frac{\Gamma \vdash t_1 : T}{\Gamma \vdash t_1 \text{ as } T : T} \quad (\text{T-ASCRIIBE})$$

$$v_1 \text{ as } T \longrightarrow v_1 \quad (\text{E-ASCRIIBE})$$

Casting (cf. Java):

$$\frac{\Gamma \vdash t_1 : S}{\Gamma \vdash t_1 \text{ as } T : T} \quad (\text{T-CAST})$$

$$\frac{\vdash v_1 : T}{v_1 \text{ as } T \longrightarrow v_1} \quad (\text{E-CAST})$$

Subtyping and Variants



$$\langle l_i : T_i \rangle_{i \in 1..n} <: \langle l_i : T_i \rangle_{i \in 1..n+k} \quad (\text{S-VARIANTWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\langle l_i : S_i \rangle_{i \in 1..n} <: \langle l_i : T_i \rangle_{i \in 1..n}} \quad (\text{S-VARIANTDEPTH})$$

$$\frac{\langle k_j : S_j \rangle_{j \in 1..n} \text{ is a permutation of } \langle l_i : T_i \rangle_{i \in 1..n}}{\langle k_j : S_j \rangle_{j \in 1..n} <: \langle l_i : T_i \rangle_{i \in 1..n}} \quad (\text{S-VARIANTPERM})$$

$$\frac{\Gamma \vdash t_1 : T_1}{\Gamma \vdash \langle l_1 = t_1 \rangle : \langle l_1 : T_1 \rangle} \quad (\text{T-VARIANT})$$

Subtyping and Lists



$$\frac{S_1 <: T_1}{\text{List } S_1 <: \text{List } T_1} \quad (\text{S-LIST})$$

i.e., List is a covariant type constructor.

Subtyping and References



$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Ref } S_1 <: \text{Ref } T_1} \quad (\text{S-REF})$$

i.e., **Ref** is not a *covariant* (nor a *contravariant*) type constructor.

Subtyping and References



$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Ref } S_1 <: \text{Ref } T_1} \quad (\text{S-REF})$$

i.e., **Ref** is not a *covariant* (nor a *contravariant*) type constructor.

Why?

- When a reference is *read*, the context expects a T_1 , so if $S_1 <: T_1$ then an S_1 is ok.

Subtyping and References



$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Ref } S_1 <: \text{Ref } T_1} \quad (\text{S-REF})$$

i.e., **Ref** is not a *covariant* (nor a *contravariant*) type constructor.

Why?

- When a reference is *read*, the context expects a T_1 , so if $S_1 <: T_1$ then an S_1 is ok.
- When a reference is *written*, the context provides a T_1 and if the actual type of the reference is $\text{Ref } S_1$, someone else may use the T_1 as an S_1 . So we need $T_1 <: S_1$.

References again



Observation: a value of type **Ref T** can be used in two different ways: as a *source* for values of type **T** and as a *sink* for values of type **T**.

Idea: Split **Ref T** into three parts:

- **Source T**: reference cell with “read capability”
- **Sink T**: reference cell with “write capability”
- **Ref T**: cell with both capabilities

Subtyping and Arrays



Similarly...

$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Array } S_1 <: \text{Array } T_1} \quad (\text{S-ARRAY})$$

$$\frac{S_1 <: T_1}{\text{Array } S_1 <: \text{Array } T_1} \quad (\text{S-ARRAYJAVA})$$

This is regarded (even by the Java designers) as a mistake in the design.

References again



Observation: a value of type *Ref* T can be used in two different ways:

- as a *source* for values of type T , and
- as a *sink* for values of type T .

References again



Observation: a value of type *Ref T* can be used in two different ways:

- as a *source* for values of type *T*, and
- as a *sink* for values of type *T*.

Idea: Split *Ref T* into three parts:

- *Source T*: reference cell with “read capability”
- *Sink T*: reference cell with “write capability”
- *Ref T*: cell with both capabilities

Modified Typing Rules



$$\frac{\Gamma \mid \Sigma \vdash t_1 : \text{Source } T_{11}}{\Gamma \mid \Sigma \vdash !t_1 : T_{11}} \quad (\text{T-DEREF})$$

$$\frac{\Gamma \mid \Sigma \vdash t_1 : \text{Sink } T_{11} \quad \Gamma \mid \Sigma \vdash t_2 : T_{11}}{\Gamma \mid \Sigma \vdash t_1 := t_2 : \text{Unit}} \quad (\text{T-ASSIGN})$$

Subtyping rules



$$\frac{S_1 <: T_1}{\text{Source } S_1 <: \text{Source } T_1} \quad (\text{S-SOURCE})$$

$$\frac{T_1 <: S_1}{\text{Sink } S_1 <: \text{Sink } T_1} \quad (\text{S-SINK})$$

$$\text{Ref } T_1 <: \text{Source } T_1 \quad (\text{S-REFSOURCE})$$

$$\text{Ref } T_1 <: \text{Sink } T_1 \quad (\text{S-REFSINK})$$

Capabilities



- Other kinds of capabilities can be treated similarly, e.g.,
- send and receive capabilities on communication channels,
 - encrypt/decrypt capabilities of cryptographic keys,
 - ...



Intersection and Union Types

Intersection Types

The inhabitants of $T_1 \wedge T_2$ are terms belonging to *both* S and T —i.e., $T_1 \wedge T_2$ is an order-theoretic meet (greatest lower bound) of T_1 and T_2 .

$$T_1 \wedge T_2 <: T_1$$

(S-INTER1)

$$T_1 \wedge T_2 <: T_2$$

(S-INTER2)

$$\frac{S <: T_1 \quad S <: T_2}{S <: T_1 \wedge T_2}$$

(S-INTER3)

$$S \rightarrow T_1 \wedge S \rightarrow T_2 <: S \rightarrow (T_1 \wedge T_2)$$

(S-INTER4)

Intersection Types

Intersection types permit a very *flexible form* of *finitary overloading*.

$+ : (\text{Nat} \rightarrow \text{Nat} \rightarrow \text{Nat}) \wedge (\text{Float} \rightarrow \text{Float} \rightarrow \text{Float})$

This form of overloading is extremely powerful.

Every strongly normalizing untyped lambda-term can be typed in the simply typed lambda-calculus with intersection types.

type reconstruction problem is undecidable

Intersection types *have not been used much* in language designs (too powerful!), but are being *intensively investigated* as type systems for *intermediate languages* in highly optimizing compilers (cf. Church project).

Union types

Union types are also useful.

$T_1 \vee T_2$ is an **untagged** (non-disjoint) union of T_1 and T_2 .

No tags : no *case* construct. The only operations we can safely perform on elements of $T_1 \vee T_2$ are ones *that make sense for both* T_1 and T_2 .

N. B: untagged union types in C are a source of *type safety violations* precisely because they ignores this restriction, allowing any operation on an element of $T_1 \vee T_2$ that makes sense for *either* T_1 or T_2 .

Union types are being used recently in type systems for XML processing languages (cf. Xduce, Xtatic).

Varieties of Polymorphism



- Parametric polymorphism (ML-style)
- Subtype polymorphism (OO-style)
- Ad-hoc polymorphism (overloading)



Chap 16

Metatheory of Subtyping

Algorithmic Subtyping

Algorithmic Typing

Joins and Meets



Developing an algorithmic subtyping relation

Subtype Relation



$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\{l_i : T_i \mid i \in 1..n+k\} <: \{l_i : T_i \mid i \in 1..n\} \quad (\text{S-RCDWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\{l_i : S_i \mid i \in 1..n\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDDEPTH})$$

$$\frac{\{k_j : S_j \mid j \in 1..n\} \text{ is a permutation of } \{l_i : T_i \mid i \in 1..n\}}{\{k_j : S_j \mid j \in 1..n\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDPERM})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$

Issues in Subtyping



For a *given subtyping statement*, there are *multiple rules* that could be used in a derivation.

1. The conclusions of **S-RcdWidth**, **S-RcdDepth**, and **S-RcdPerm** *overlap with each other*.
2. **S-REFL** and **S-TRANS** overlap with every other rule.

What to do?



We'll turn the *declarative version* of subtyping into the *algorithmic version*.

The **problem** was that we don't have an algorithm to decide when $S <: T$ or $\Gamma \vdash t : T$.

Both sets of rules are not *syntax-directed*.

Syntax-directed rules



In the simply typed lambda-calculus (without subtyping), each rule can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$

Syntax-directed rules



In the simply typed lambda-calculus (without subtyping), each rule can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$

If we are given some Γ and some t of the form $t_1 \ t_2$, we can try to *find a type* for t by

1. finding (recursively) a type for t_1
2. checking that it has the form $T_{11} \rightarrow T_{12}$
3. finding (recursively) a type for t_2
4. checking that it is the same as T_{11}

Syntax-directed rules

Technically, the reason this works is that we can *divide the “positions”* of the typing relation into *input positions* (i.e., Γ and t) and *output positions* (T).

- For the input positions, all metavariables appearing in the *premises* also appear in the *conclusion* (so we can calculate inputs to the “subgoals” from the subexpressions of inputs to the main goal)
- For the output positions, all metavariables appearing in the *conclusions* also appear in the *premises* (so we can calculate outputs from the main goal from the outputs of the subgoals)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$

Syntax-directed sets of rules



The *second important point* about the simply typed lambda-calculus is that *the set of typing rules is syntax-directed*, in the sense that, for every “*input*” Γ and t , there is *one rule* that can be used to derive typing statements involving t .

E.g., if t is an *application*, then we must proceed by trying to use **T-App**. If we succeed, then we have found a type (indeed, the *unique type*) for t . If it *fails*, then we know that t is *not typable*.

⇒ no backtracking!

Non-syntax-directedness of typing



When we extend the system with *subtyping*, both aspects of syntax-directedness get broken.

1. The set of typing rules now includes *two* rules that can be used to give a type to terms of a given shape (the old one plus T-SUB)

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

2. Worse yet, the new rule T-SUB itself is not syntax directed: the *inputs* to the left-hand subgoal are exactly the same as the *inputs* to the main goal!

(Hence, if we translated the typing rules naively into a typechecking function, the case corresponding to T-SUB would cause divergence.)

Non-syntax-directedness of subtyping



Moreover, the *subtyping relation* is *not syntax directed* either.

1. There are *lots* of ways to derive a given subtyping statement.
2. The transitivity rule

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

is *badly non-syntax-directed*: the premises contain a *metavariable* (in an “*input position*”) that does *not appear at all in the conclusion*.

To implement this rule naively, we have to *guess* a value for **U**!

What to do?

1. *Observation*: We don't *need* lots of ways to prove a given typing or subtyping statement — *one is enough*.
→ Think more carefully about the *typing and subtyping* systems to see where we can get rid of excess flexibility.
2. Use the resulting intuitions to formulate new “*algorithmic*” (i.e., syntax-directed) typing and subtyping relations.
3. Prove that the algorithmic relations are “*the same as*” the original ones in an appropriate sense.



Algorithmic Subtyping

What to do



How do we change the rules deriving $S <: T$ to be *syntax-directed*?

There are lots of ways to derive a given subtyping statement $S <: T$.

The general idea is to *change this system* so that there is *only one way* to derive it.

Step 1: simplify record subtyping



Idea: combine all three record subtyping rules into one “*macro rule*” that captures all of their effects

$$\frac{\{1_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = 1_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{1_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

Simpler subtype relation



$$S <: S$$

(S-REFL)

$$\frac{S <: U \quad U <: T}{S <: T}$$

(S-TRANS)

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}}$$

(S-RCD)

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

(S-ARROW)

$$S <: \text{Top}$$

(S-TOP)

Step 2: Get rid of reflexivity



Observation: S-REFL is unnecessary.

Lemma: $S <: S$ can be derived for every type S without using S-REFL.

Even simpler subtype relation



$$\frac{S <: U \quad U <: T}{S <: T}$$

(S-TRANS)

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}}$$

(S-RCD)

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

(S-ARROW)

$$S <: \text{Top}$$

(S-TOP)

Step 3: Get rid of transitivity



Observation: S-Trans is unnecessary.

Lemma: If $S <: T$ can be derived, then it can be derived without using S-Trans .

“Algorithmic” subtype relation



$$\boxed{\vdash} S <: \text{Top}$$

$$(\boxed{\text{SA}}\text{-TOP})$$

$$\frac{\vdash T_1 <: S_1 \quad \vdash S_2 <: T_2}{\vdash S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

$$(\text{SA-ARROW})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad \text{for each } k_j = l_i, \vdash S_j <: T_i}{\vdash \{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{SA-RCD})$$

Soundness and completeness



Theorem: $S <: T$ iff $\mapsto S <: T$

Terminology:

- The algorithmic presentation of subtyping is *sound* with respect to the original if $\mapsto S <: T$ implies $S <: T$. (Everything validated by the algorithm is actually true.)
- The algorithmic presentation of subtyping is *complete* with respect to the original if $S <: T$ implies $\mapsto S <: T$. (Everything true is validated by the algorithm.)

Decision Procedures



A *decision procedure* for a relation $R \subseteq U$ is a *total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Decision Procedures



Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Is our *subtype* function a decision procedure?

Decision Procedures



Recall: A decision procedure for a relation $R \subseteq U$ is a *total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Is our *subtype* function a decision procedure?

Since *subtype* is just an implementation of the algorithmic subtyping rules, we have

1. if $subtype(S, T) = true$, then $\mapsto S <: T$ (hence, by *soundness* of the algorithmic rules, $S <: T$)
2. if $subtype(S, T) = false$, then not $\mapsto S <: T$ (hence, by *completeness* of the algorithmic rules, not $S <: T$)

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Q: What's missing?

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Q: What's missing?

A: How do we know that *subtype* is a **total function**?

Decision Procedures



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2. if $subtype(S, T) = false$, then not $\mapsto S <: T$ (hence, by **completeness** of the algorithmic rules, not $S <: T$)

Q: What's missing?

A: How do we know that *subtype* is a *total function*?

Prove it!

Decision Procedures



Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

Note that, we are saying nothing about *computability*.

Decision Procedures



Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function p whose graph is

$$\begin{aligned} &\{ ((1, 2), true), ((2, 3), true), \\ &\quad ((1, 1), false), ((1, 3), false), \\ &\quad ((2, 1), false), ((2, 2), false), \\ &\quad ((3, 1), false), ((3, 2), false), ((3, 3), false) \} \end{aligned}$$

is a decision function for R .

Decision Procedures



Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function p' whose graph is

$$\{((1, 2), true), ((2, 3), true)\}$$

is not a decision function for R .

Decision Procedures



Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function p'' whose graph is

$$\{((1, 2), true), ((2, 3), true), ((1, 3), false)\}$$

is *also not* a decision function for R .

Decision Procedures (take 2)



We want a decision procedure to be a *procedure*.

A *decision procedure* for a relation $R \subseteq U$ is a *computable total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example



$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function

$$p(x, y) = \begin{array}{l} \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ \text{else false} \end{array}$$

whose graph is

$$\begin{array}{l} \{ ((1, 2), \text{true}), ((2, 3), \text{true}), \\ ((1, 1), \text{false}), ((1, 3), \text{false}), \\ ((2, 1), \text{false}), ((2, 2), \text{false}), \\ ((3, 1), \text{false}), ((3, 2), \text{false}), ((3, 3), \text{false}) \} \end{array}$$

is a decision procedure for R .

Example



$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$p(x, y) =$ if $x = 2$ and $y = 3$ then true
else if $x = 1$ and $y = 2$ then true
else if $x = 1$ and $y = 3$ then false
else $p(x, y)$

Example



$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$$\begin{aligned} p(x, y) = & \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ & \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ & \text{else if } x = 1 \text{ and } y = 3 \text{ then false} \\ & \text{else } p(x, y) \end{aligned}$$

whose graph is

$$\{((1, 2), \text{true}), ((2, 3), \text{true}), ((1, 3), \text{false})\}$$

is *not* a decision procedure for R .

Subtyping Algorithm



This *recursively defined total function* is a decision procedure for the subtype relation:

$subtype(S, T) =$

if $T = \text{Top}$, then *true*

else if $S = S_1 \rightarrow S_2$ and $T = T_1 \rightarrow T_2$

then $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$

else if $S = \{k_j: S_j^{j \in 1..m}\}$ and $T = \{l_i: T_i^{i \in 1..n}\}$

then $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$

\wedge for all $i \in 1..n$ there is some $j \in 1..m$ with $k_j = l_i$

and $subtype(S_j, T_i)$

else *false*.

Subtyping Algorithm



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if $T = \text{Top}$, then *true*

else if $S = S_1 \rightarrow S_2$ and $T = T_1 \rightarrow T_2$
then $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$

else if $S = \{k_j: S_j^{j \in 1..m}\}$ and $T = \{l_i: T_i^{i \in 1..n}\}$

then $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$

\wedge for all $i \in 1..n$ there is some $j \in 1..m$ with $k_j = l_i$
and $subtype(S_j, T_i)$

else *false*.

To show this, we need to prove:

1. that it returns *true* whenever $S <: T$, and
2. that it returns either *true* or *false* on all inputs.



Algorithmic Typing

Algorithmic typing



How do we implement a *type checker* for the lambda-calculus *with subtyping*?

Given a context Γ and a term t , how do we determine its type T , such that $\Gamma \vdash t : T$?

Issue



For the typing relation, we have *just one problematic rule* to deal with: subsumption rule

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Q: where is this rule really needed?

Issue



For the typing relation, we have *just one problematic rule* to deal with: subsumption

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Q: where is this rule really needed?

For applications, e.g., the term

$(\lambda r: \{x: \text{Nat}\}. r. x) \{x = 0, y = 1\}$

is *not typable* without using subsumption.

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Where else??

Issue



For the typing relation, we have *just one problematic rule* to deal with: subsumption

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Q: where is this rule really needed?

For *applications*, e.g., the term

$(\lambda r: \{x: \text{Nat}\}. r. x) \{x = 0, y = 1\}$

is *not typable* without using subsumption.

Where else??

Nowhere else!

Uses of subsumption to help typecheck *applications* are the only interesting ones.

Plan



1. Investigate *how subsumption is used in typing derivations* by *looking at examples* of how it can be “pushed through” other rules
2. Use the intuitions gained from this exercise to design a new, algorithmic typing relation that
 - *Omits subsumption*
 - Compensates for its absence by *enriching the application rule*
3. *Show that* the algorithmic typing relation is essentially *equivalent* to the original, declarative one

Example (T-ABS)



$$\frac{\frac{\vdots}{\Gamma, x:S_1 \vdash s_2 : S_2} \quad \frac{\vdots}{S_2 <: T_2}}{\Gamma, x:S_1 \vdash s_2 : T_2} \text{ (T-SUB)}$$
$$\frac{\Gamma, x:S_1 \vdash s_2 : T_2}{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2} \text{ (T-ABS)}$$

Example (T-ABS)



$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2 \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : T_2 \quad (\text{T-SUB}) \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \quad (\text{T-ABS})
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_1 <: S_1 \quad (\text{S-REFL}) \qquad S_2 <: T_2 \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow S_2 \quad (\text{T-ABS}) \qquad S_1 \rightarrow S_2 <: S_1 \rightarrow T_2 \quad (\text{S-ARROW}) \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \quad (\text{T-SUB})
 \end{array}$$

Intuitions



These examples show that we do not need **T-SUB** to “enable” **T-ABS** : given any typing derivation, we can construct a derivation *with the same conclusion* in which **T-SUB** is never used immediately before **T-ABS**.

What about **T-APP**?

We’ve already observed that **T-SUB** is required for typechecking some *applications*. So we expect to find that we *cannot* play the same game with **T-APP** as we’ve done with **T-ABS**.

Let’s see why.

Example (T-Sub with T-APP on the left)



$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \vdots \qquad \qquad \qquad \frac{T_{11} <: S_{11} \quad S_{12} <: T_{12}}{(S\text{-ARROW})} \\
 \hline
 \frac{\Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \quad S_{11} \rightarrow S_{12} <: T_{11} \rightarrow T_{12}}{(T\text{-SUB})} \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \qquad \qquad \qquad \frac{\Gamma \vdash s_2 : T_{11}}{(T\text{-APP})} \\
 \hline
 \Gamma \vdash s_1 \ s_2 : T_{12}
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \vdots \qquad \qquad \qquad \frac{\Gamma \vdash s_2 : T_{11} \quad T_{11} <: S_{11}}{(T\text{-SUB})} \\
 \hline
 \frac{\Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \quad \Gamma \vdash s_2 : S_{11}}{(T\text{-APP})} \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma \vdash s_1 \ s_2 : S_{12} \qquad \qquad \qquad \frac{S_{12} <: T_{12}}{(T\text{-SUB})} \\
 \hline
 \Gamma \vdash s_1 \ s_2 : T_{12}
 \end{array}$$

Example (T-Sub with T-APP on the right)



$$\begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_1 : T_{11} \rightarrow T_{12}
 \end{array}
 \quad
 \begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_2 : T_2
 \end{array}
 \quad
 \begin{array}{c}
 \vdots \\
 \hline
 T_2 <: T_{11}
 \end{array}
 \quad
 \begin{array}{c}
 \hline
 \Gamma \vdash s_2 : T_{11}
 \end{array}
 \quad
 \begin{array}{c}
 \hline
 \Gamma \vdash s_1 \ s_2 : T_{12}
 \end{array}
 \quad
 \begin{array}{c}
 \text{(T-SUB)} \\
 \text{(T-APP)}
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_1 : T_{11} \rightarrow T_{12}
 \end{array}
 \quad
 \begin{array}{c}
 \vdots \\
 \hline
 T_2 <: T_{11}
 \end{array}
 \quad
 \begin{array}{c}
 \hline
 T_{12} <: T_{12}
 \end{array}
 \quad
 \begin{array}{c}
 \hline
 T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}
 \end{array}
 \quad
 \begin{array}{c}
 \hline
 \Gamma \vdash s_2 : T_2
 \end{array}
 \quad
 \begin{array}{c}
 \hline
 \Gamma \vdash s_1 \ s_2 : T_{12}
 \end{array}
 \quad
 \begin{array}{c}
 \text{(S-REFL)} \\
 \text{(S-ARROW)} \\
 \text{(T-SUB)} \\
 \text{(T-APP)}
 \end{array}$$

Observations



So we've seen that uses of subsumption can be “*pushed*” from one of immediately before **T-APP**'s premises to the other, but *cannot be completely eliminated*.

Example (nested uses of T-Sub)



$$\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\vdots}{S <: U}}{\Gamma \vdash s : U} \text{ (T-SUB)} \quad \frac{\vdots}{U <: T}$$
$$\frac{\Gamma \vdash s : U \quad U <: T}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

Example (nested uses of T-Sub)



$$\begin{array}{c}
 \begin{array}{c} \vdots \\ \hline \Gamma \vdash s : S \end{array} \quad \begin{array}{c} \vdots \\ \hline S <: U \end{array} \\
 \hline \Gamma \vdash s : U \quad (T\text{-SUB})
 \end{array}
 \quad
 \begin{array}{c} \vdots \\ \hline U <: T \end{array}$$

$$\hline \Gamma \vdash s : T \quad (T\text{-SUB})$$

becomes

$$\begin{array}{c} \vdots \\ \hline \Gamma \vdash s : S \end{array}
 \quad
 \begin{array}{c} \vdots \quad \vdots \\ \hline S <: U \quad U <: T \\ \hline S <: T \end{array} \quad (S\text{-TRANS})$$

$$\hline \Gamma \vdash s : T \quad (T\text{-SUB})$$

Summary



What we've learned:

- Uses of the **T-Sub** rule can be “*pushed down*” through typing derivations until they encounter either
 1. a use of **T-App** or
 2. the root of the derivation tree.
- In both cases, multiple uses of **T-Sub** can be coalesced into a single one.

Summary



What we've learned:

- Uses of the T-Sub rule can be “pushed down” through typing derivations until they encounter either
 1. a use of T-App or
 2. the root of the derivation tree.
- In both cases, multiple uses of T-Sub can be collapsed into a single one.

This suggests a notion of “normal form” for typing derivations, in which there is

- exactly one use of T-Sub before each use of T-App
- one use of T-Sub at the very end of the derivation
- no uses of T T-Sub anywhere else.

Algorithmic Typing



The next step is to “build in” the use of subsumption in application rules, by changing the **T-App** rule to incorporate a subtyping premise.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}}$$

Given any typing derivation, we can now

1. **normalize** it, to move all uses of subsumption to either just before applications (in the right-hand premise) or at the very end
2. **replace** uses of **T-App** with **T-SUB** in the right-hand premise by uses of the extended rule above

This yields a derivation in which there is just *one* use of subsumption, at the very end!

Minimal Types



But... if subsumption is only used at the very end of derivations, then it is actually *not needed* in order to show that *any term is typable*!

It is just used to give *more* types to terms that have already been shown to have a type.

In other words, if we dropped subsumption completely (after refining the application rule), we would still be able to give types to exactly the same set of terms — we just would not be able to give as many types to some of them.

If we drop subsumption, then the remaining rules will assign a *unique, minimal* type to each typable term.

For purposes of building a typechecking algorithm, this is enough.

Final Algorithmic Typing Rules



$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T} \quad (\text{TA-VAR})$$

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2} \quad (\text{TA-ABS})$$

$$\frac{\Gamma \vdash t_1 : T_1 \quad T_1 = T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{TA-APP})$$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_1=t_1 \dots l_n=t_n\} : \{l_1:T_1 \dots l_n:T_n\}} \quad (\text{TA-RCD})$$

$$\frac{\Gamma \vdash t_1 : R_1 \quad R_1 = \{l_1:T_1 \dots l_n:T_n\}}{\Gamma \vdash t_1.l_i : T_i} \quad (\text{TA-PROJ})$$

Completeness of the algorithmic rules



Theorem [Minimal Typing]: If $\Gamma \vdash t : T$, then $\Gamma \mapsto t : S$ for some $S <: T$.

Completeness of the algorithmic rules



Theorem [Minimal Typing]: If $\Gamma \vdash t : T$, then $\Gamma \mapsto t : S$ for some $S <: T$.

Proof: Induction on *typing derivation*.

(N.b.: All the messing around with transforming derivations was just to build intuitions and *decide what algorithmic rules* to write down and *what property* to prove: the proof itself is a straightforward induction on typing derivations.)



Meets and Joins

Adding Booleans



Suppose we want to add *booleans* and *conditionals* to the language we have been discussing.

For the declarative presentation of the system, we just add in the appropriate syntactic forms, evaluation rules, and typing rules.

$$\begin{array}{lcl} \Gamma \vdash \text{true} : \text{Bool} & & (\text{T-TRUE}) \\ \Gamma \vdash \text{false} : \text{Bool} & & (\text{T-FALSE}) \\ \hline \Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T \quad \Gamma \vdash t_3 : T & & (\text{T-IF}) \\ \Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T & & \end{array}$$

A Problem with Conditional Expressions



For the algorithmic presentation of the system, however, we encounter a little difficulty.

What is the minimal type of

if true then $\{x = \text{true}, y = \text{false}\}$ else $\{x = \text{true}, z = \text{ture}\}$

?

The Algorithmic Conditional Rule



More generally, we can use subsumption to give an expression

if t_1 then t_2 else t_3

any type that is a possible type of both t_2 and t_3 .

So the *minimal* type of the conditional is the *least common supertype* (or *join*) of the minimal type of t_2 and the minimal type of t_3 .

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

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So the *minimal* type of the conditional is the *least common supertype* (or *join*) of the minimal type of t_2 and the minimal type of t_3 .

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

Q: Does such a type exist for every T_2 and T_3 ??

Existence of Joins



Theorem: For every pair of types S and T , there is a type J such that

1. $S <: J$
2. $T <: J$
3. If K is a type such that $S <: K$ and $T <: K$, then $J <: K$.

i.e., J is the smallest type that is a supertype of both S and T .

How to prove it?

Examples



What are the joins of the following pairs of types?

1. $\{x: \text{Bool}, y: \text{Bool}\}$ and $\{y: \text{Bool}, z: \text{Bool}\}$?
2. $\{x: \text{Bool}\}$ and $\{y: \text{Bool}\}$?
3. $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$ and $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$?
4. $\{\}$ and Bool ?
5. $\{x: \{\}\}$ and $\{x: \text{Bool}\}$?
6. $\text{Top} \rightarrow \{x: \text{Bool}\}$ and $\text{Top} \rightarrow \{y: \text{Bool}\}$?
7. $\{x: \text{Bool}\} \rightarrow \text{Top}$ and $\{y: \text{Bool}\} \rightarrow \text{Top}$?

Meets



To calculate joins of arrow types, we also need to be able to calculate meets (greatest lower bounds)!

Unlike joins, meets do not necessarily exist.

E.g., $\text{Bool} \rightarrow \text{Bool}$ and $\{\}$ have no common subtypes, so they certainly don't have a greatest one!

However...

Existence of Meets



Theorem: For every pair of types S and T , if there is any type N such that $N <: S$ and $N <: T$, then there is a type M such that

1. $M <: S$
2. $M <: T$
3. If O is a type such that $O <: S$ and $O <: T$, then $O <: M$.

i.e., M (when it exists) is the largest type that is a subtype of both S and T .

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Jargon: In the simply typed lambda calculus with subtyping, records, and booleans...

- The subtype relation *has joins*
- The subtype relation *has bounded meets*

Examples



What are the meets of the following pairs of types?

1. $\{x: \text{Bool}, y: \text{Bool}\}$ and $\{y: \text{Bool}, z: \text{Bool}\}$?
2. $\{x: \text{Bool}\}$ and $\{y: \text{Bool}\}$?
3. $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$ and $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$?
4. $\{\}$ and Bool ?
5. $\{x: \{\}\}$ and $\{x: \text{Bool}\}$?
6. $\text{Top} \rightarrow \{x: \text{Bool}\}$ and $\text{Top} \rightarrow \{y: \text{Bool}\}$?
7. $\{x: \text{Bool}\} \rightarrow \text{Top}$ and $\{y: \text{Bool}\} \rightarrow \text{Top}$?

Calculating Joins



$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \wedge T_1 = M_1 \quad S_2 \vee T_2 = J_2 \\ \{j_l : J_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{j_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & S_j \vee T_i = J_l \quad \text{for each } j_l = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$

Calculating Meets



$S \wedge T =$

S	if $T = \text{Top}$
T	if $S = \text{Top}$
Bool	if $S = T = \text{Bool}$
$J_1 \rightarrow M_2$	if $S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2$ $S_1 \vee T_1 = J_1 \quad S_2 \wedge T_2 = M_2$
$\{m_l : M_l \mid l \in 1..q\}$	if $S = \{k_j : S_j \mid j \in 1..m\}$ $T = \{l_i : T_i \mid i \in 1..n\}$ $\{m_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cup \{l_i \mid i \in 1..n\}$ $S_j \wedge T_i = M_l$ for each $m_l = k_j = l_i$ $M_l = S_j$ if $m_l = k_j$ occurs only in S $M_l = T_i$ if $m_l = l_i$ occurs only in T
<i>fail</i>	otherwise

Homework😊



- Read and digest chapter 16 & 17
- HW#1: 16.2.5
- HW#2: 16.2.6