

# AVRDUDE on Windows with WSL

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This guide to test and program the chip on Windows using WSL (Windows Subsystem for Windows) for embedded systems courses at UC Riverside.

If you are using a Windows machine, using WSL with VS Code is a good way to test your code and program your chip without using a virtual machine.

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## Prerequisites

On your Windows machine, it should have these intalled:

1. WSL installed and initialized
  - Follow [this link](#) to install WSL on your machine, and [this link](#) to initialize it.
    - I recomment you use your name as the UNIX username, because the username will appear as the author in your lab files.
  - You can intall any distro you like, but this guide uses Ubuntu.
2. MinGW-x64
  - Download [here](#) via SourceForge;
3. VS Code
  - Download [here](#);

You should also have a GitHub account. You can signup [here](#).

**Now, open Linux Bash.**

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## Setup the Basics in WSL

## Working Directory

1. In Windows, create a folder for your CS120B labs as your working directory, it should have **no space** in its directory;
  - Good example: "E:\Desktop\CS\_120B\Labs", this directory will be used in all examples below.
2. To access this folder in WSL, do `

```
# Command:
$ cd /mnt/DRIVE_FLAG/FOLDER_DIR

# For example:
$ cd /mnt/e/Desktop/CS_120B/Labs
```

3. (Optional) To quickly access this folder, you can add an alias entry.

```
# Command:
$ alias alias_name="command_to_run"

# For example:
$ alias cs120blab="cd /mnt/e/Desktop/CS_120B/Labs"
```

To make the alias entry permanent, add the command in `~/.bash_aliases` file (`~/.bashrc` if you are on other distros).

## Git

1. Setting your username and email in Git

```
$ git config --global user.name "Your Name"
$ git config --global user.email "your_email@example.com"
```

2. (Optional) Connecting to GitHub with SSH You don't have to use a SSH key to access GitHub, but I think it's easier this way. You can also skip this step if you have already done so.

1. Check if you have ssh key or not

```
$ ls -al ~/.ssh
```

If prompt

```
> ls: cannot access '/home/you/.ssh': No such file or directory
```

continue to the next step;

if prompt

```
> total 8  
...
```

Go to step 4.

2. Create a SSH key in WSL. Replace `your_email@example.com` with your email used in GitHub.

```
$ ssh-keygen -t rsa -b 4096 -C "your_email@example.com"  
  
> Enter a file in which to save the key (/home/you/.ssh/id_rsa):  
[Press enter]  
  
> Enter passphrase (empty for no passphrase): [Type a passphrase]  
> Enter same passphrase again: [Type passphrase again]
```

3. Add SSH key to the ssh-agent.

```
$ eval $(ssh-agent -s)  
> Agent pid 59566  
  
$ ssh-add ~/.ssh/id_rsa
```

4. Add SSH key to GitHub account.

```
$ vim ~/.ssh/id_rsa.pub
> ssh-rsa AAAAB3NzaC1yc2
...
your_email@example.com
```

Copy the printout.

Follow [this guide](#) from step 2.

## VS Code

### 1. Install VS Code Server for x64

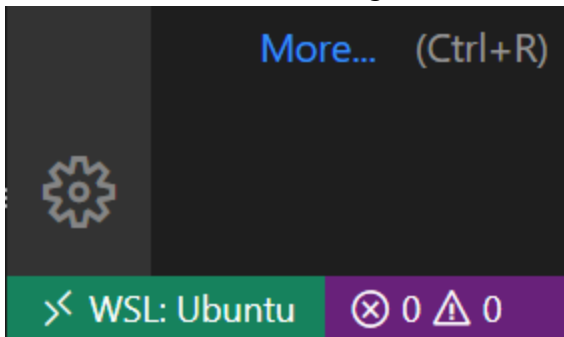
```
# In any directory
$ code .
> Installing VS Code Server for x64 (...)
```

### 2. Allow firewall connection

### 3. Install VS Code "Remote - WSL" extension

- Should install automatically.

### 4. On the bottom-left corner, a green icon should appear saying **WSL: your distro**.



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## Get AVR-ToolChain working on WSL

### 1. Install basic components

```
$ sudo apt-get make zlib1g zlib1g-dev zip
```

## 2. Install simAVR

### 1. Install by `apt-get`:

```
$ sudo apt-get install simavr
```

### 2. Install by `git clone`

```
# Clone it to your home directory
$ cd ~
$ git clone git@github.com:buserror/simavr.git

# If you are using https, do this instead
$ git clone https://github.com/buserror/simavr.git
```

- Note: You need to install simAVR in both ways.
  - `apt-get` gives you access to bash command `simavr`,
  - `git clone` gives the MakeFile access to the installation directory which we will use later.

## 3. Install AVR-GCC Toolchain

```
$ sudo apt-get install gcc-avr binutils-avr avr-libc gdb-avr
```

- If you are following the AVR-GCC Toolchain [installation guide](#) linked in UCRCS120B\_AVRTools' GitHub page, you can skip step 3 and onward since we are using avrdude in Windows instead of WSL.

## 4. Clone UCRCS120B\_AVRTools to your working directory;

```
$ git clone git@github.com:jmcda001/UCRCS120B_AVRTools.git

# If you are using https, do this instead
$ git clone https://github.com/jmcda001/UCRCS120B_AVRTools.git
```

5. Edit the MakefileTemplate In `UCRCS120B_AVRTools/templates/MakefileTemplate` file, edit line 14 to be the path to your SimAVR installation.

```
# Edit this
SIMAVRDIR=SET YOUR SIMAVR DIRECTORY HERE

# To this
# If simavr is in your home directory like we showed above
SIMAVRDIR=/home/$(USER)/simavr/simavr/
```

6. Edit createProject.sh In `UCRCS120B_AVRTools/createProject.sh` file, edit line 76 to be the relative path from your SIMAVRDIR to the `avr_mcu_section.h` file.

```
// Edit this
#include "include/simavr/avr/avr_mcu_section.h"

// To this
// If simavr is in your home directory like we showed above
#include "/home/${USER}/simavr/simavr/sim/avr/avr_mcu_section.h"
```

7. Customize createProject.sh (optional) Replace line 114 to 121 with the following code to initialize and push the directory to a GitHub repo automatically.

```
echo -e "Initialize the directory to a GitHub repo."
read -p 'git repo link [press ENTER to skip]: ' link

if [ -n "$link" ]
then
    echo -e 'Initializing repo...'
    cd "$name"
    git init
    git add .
    git commit -m 'Initializing repository'

    echo -e 'Adding repo to GitHub...'
    git remote add origin "$link"
    git remote -v

    echo -e 'Pushing changes to GitHub...'
```

```
git push -u origin master

echo
echo -e "\e[42mProject Pushed.\033[0m You can change your
directory and continue working."
else
echo -e "\e[104mProject not initialized.\033[0m You can change
your directory and continue working."
fi
```

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## Get AvrDude Working in WSL

**In WSL:** You need to use avrdude.exe in Windows to program your chip, since WSL does not support libusb devices (such as the Atmel board when using avrdude).

1. Download avrdude on [official website](#);
  - Download area click [here](#).
  - Select mingw32 version, file name should look like `avrdude-*. *-mingw32.zip`.
2. Unzip and put it in a folder which directory has **no space**;
3. Change `UCRCS120B_AVRTools/templates/MakeFileTemplate` line 37 to `avrdude.exe`'s directory; If `avrdude.exe` is in `E:\Desktop\CS_120B\avrdude-6.3`:

```
# Edit this
PROGRAM=avrdude

# To this
PROGRAM=/mnt/e/Desktop/CS_120B/avrdude-6.3/avrdude.exe
```

4. If you are having error (and you most likely are) `avrdude.exe: jtag3_open_common(): Did not find any device matching VID 0x03eb and PID list: 0x2141`, go to [this section](#).

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## Install Driver for Atmel Programming board

If you are having error in **Windows**, `avrdude.exe: jtag3_open_common(): Did not find any device matching VID 0x03eb and PID list: 0x2141` in `avrdude(ss)`, follow steps below.

If you are having a similar error in **WSL**, `avrdude: jtag3_open_common(): Did not find any device matching VID 0x03eb and PID list: 0x2141`, you should go to [this part](#).

1. Download Zadig from its [official website](#);
2. Connect the board to your computer;
3. Open `zadig.exe`;
4. In the dropdown list, select "Atmel-IEC \*\*\*\*";
  - Might be 2-3 devices start with "Atmel-IEC", repeat step 4-7 on all of them.
  - If you don't see it, select "List All Devices" in "Option" menu.
5. Check USB ID, should be `03EB 2141` (might have `01` or `02` in the third box);
6. Select "libusb-win32" as the driver to be installed;
7. Click "Install Driver" or "Replace Driver";
8. In Device Manager, the board should be under "libusb-win32 Devices".