

State Sequence

Let's write a test to see if we can go from 'waitA0' to 'pressA1'

```
# Test sequence from waitA0: A0, !A0, A1 => PORTB: 1
test "PINA: 0x01, 0x00, 0x02 => PORTB: 1, state: pressA1"
set state = waitA0
setPINA 0x01
continue 2
setPINA 0x00
continue 2
setPINA 0x02
continue 2
expectPORTB 0xF0
checkResult
```

Notice how we continue several times in between each change to `PINA`. When you program the hardware next week, the clock is ticking so fast that each button press will last for several runs through the program, we want to test to make sure our state machines work in those situations.

Since 'pressA1' has an output, we are able to inspect `PORTB` to see if we're in the right state, but we should inspect the `state` variable as well. We can add this line under `expectPORTB 0xF0` to check that the state is in fact in 'pressA1'.

```
expect state pressA1
```

Starting State

Each test we write should:

1. Initialize the context to some known starting state
(gdb) set state = waitA0
2. Apply stimulus (input)
(gdb) setPINA 0x01
...
3. Observe output
(gdb) expectPORTB 0xF0
(gdb) expect state pressA1

Let's write a test to see if we can get `PORTB` output to be `0x0F` when our `cntA0` is greater than

100.

```
test "cntA0 > 100 => PORTB: 0x0F"  
set exampleTick::cntA0 = 101  
set state = pressA1  
setPINA 0x02  
continue 2  
expectPORTB 0x0F  
expect state pressA1  
checkResult
```

Let's look at a couple specific lines in this test:

- "set exampleTick::cntA0 = 101" will set the cntA0 variable that is locally scoped in the exampleTick() function to the value of 101. Whenever you are setting or inspecting a variable that is local to a function (except main) you must scope it.
- "set state = pressA1" will set the current state to pressA1
- "setPINA 0x02" sets A1 so we will stay in state pressA1

We then continue several times and verify that the state doesn't change and the output on PORTB is correct (0x0F).

Exercises

Note: Drawing state machines is a helpful and powerful way to debug your own code. If you are running into a problem in your logic, drawing out the SM will help both you, and your TA, to analyze your logic.

Write C programs for the following exercises targeting an ATmega1284 following the PES *standard technique*. For any behavior response caused by a button press, the response should occur almost immediately upon the press, not waiting for the button release (unless otherwise stated). Be sure to count each button press only once, no matter the duration the button is pressed. In addition to demoing your programs, you should show that your code adheres entirely to the technique in PES for capturing SMs in C, with no variations.

Note: As you are using the standard model, you should `display` the `state` variable to ensure you are transitioning properly between states. When demoing be sure to have this ready for the TA.

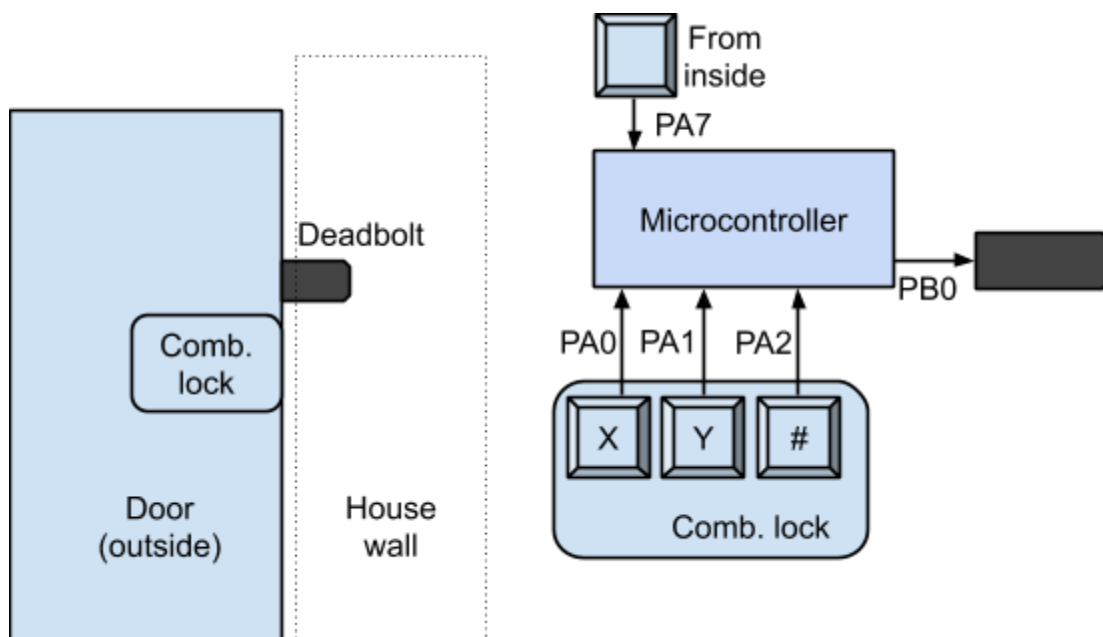
Note: When developing, you want to save your work every so often so that you don't lose your work if your machine dies (or, in the case of the lab machines, you accidentally log out or get disconnected). You especially want to save when you are about to implement a new feature so if you break anything you can *revert* back to an older, working, copy. **This will be the last lab we remind you to do this!**

If feasible, demonstrate parts 1 and 2 to a TA before moving on.

1. PB0 and PB1 each connect to an LED, and PB0's LED is initially on. Pressing a button connected to PA0 turns off PB0's LED and turns on PB1's LED, staying that way after button release. Pressing the button again turns off PB1's LED and turns on PB0's LED.

```
$ cp source/main.c turnin/[cslogin]_lab4_part1.c
$ cp test/tests.gdb turnin/[cslogin]_lab4_part1_tests.gdb
$ git commit -m "Completed part 1"
```
2. Buttons are connected to PA0 and PA1. Output for PORTC is initially 7. Pressing PA0 increments PORTC once (stopping at 9). Pressing PA1 decrements PORTC once (stopping at 0). If both buttons are depressed (even if not initially simultaneously), PORTC resets to 0.

```
$ cp source/main.c turnin/[cslogin]_lab4_part2.c
$ cp test/tests.gdb turnin/[cslogin]_lab4_part2_tests.gdb
$ git commit -m "Completed part 2"
```
3. A household has a digital combination deadbolt lock system on the doorway. The system has buttons on a keypad. Button 'X' connects to PA0, 'Y' to PA1, and '#' to PA2. Pressing and releasing '#', then pressing 'Y', should unlock the door by setting PB0 to 1. Any other sequence fails to unlock. Pressing a button from inside the house (PA7) locks the door (PB0=0). For debugging purposes, give each state a number, and always write the current state to PORTC (consider using the [enum](#) state variable). Also, be sure to check that only one button is pressed at a time.



```
$ cp source/main.c turnin/[cslogin]_lab4_part3.c
$ cp test/tests.gdb turnin/[cslogin]_lab4_part3_tests.gdb
$ git commit -m "Completed part 3"
```

4. **(Challenge)** Extend the above door so that it can also be *locked* by entering the earlier

code.

```
$ cp source/main.c turnin/[cslogin]_lab4_part4.c
$ cp test/tests.gdb turnin/[cslogin]_lab4_part4_tests.gdb
$ git commit -m "Completed part 4"
```

5. **(Challenge)** Extend the above door to require the 4-button sequence **#-X-Y-X** rather than the earlier 2-button sequence. To avoid excessive states, store the correct button sequence in an array, and use a looping SM.

```
$ cp source/main.c turnin/[cslogin]_lab4_part5.c
$ cp test/tests.gdb turnin/[cslogin]_lab4_part5_tests.gdb
$ git commit -m "Completed part 5"
```

Submission

Each student must submit their source files (.c) and test files (.gdb) through Gradescope according to instructions in the [lab submission guidelines](#).

Don't forget to commit and push to Github before you logout!