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1. (1%) 請使用不同的 Autoencoder model,以及不同的降維方式(降到不同維度), 討論其 reconstruction loss & public / private accuracy。(因此模型需要兩種,降維 方法也需要兩種,但 clustrering 不用兩種。)

第一種降維方式我採用和助教手把手類似辦法,降到 16*8*8

結果: reconstruction loss: 0.0038

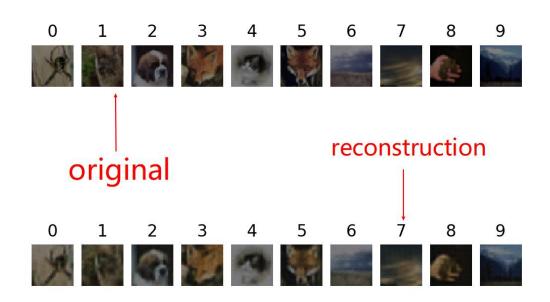
Public accuracy: 0.74185 Private accuracy: 0.74000

第二種降維方式我採用相同的結構,但使用 VAE.

結果: total loss: 0.0124 (reconstruction loss + KL loss)

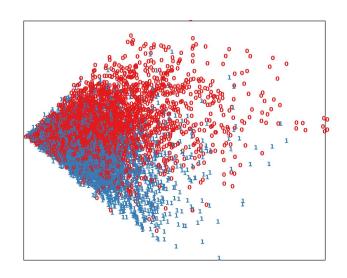
Public accuracy: 0.82407 Private accuracy: 0.82650

2. (1%) 從 dataset 選出 2 張圖,並貼上原圖以及經過 autoencoder 後 reconstruct 的圖片。

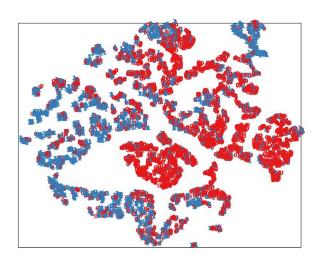


上圖為選出的前十組圖片,可以看出 reconstruction 的結果基本還比較好,部分像素點有些模糊,整體還比價完整。

3. (1%) 在之後我們會給你 dataset 的 label。請在二維平面上視覺化 label 的分佈。 取前兩維的結果:



做 TSNE:



可以看出,只取 PCA 的前兩維時,結果會混在一起,但做了 TSNE 後,結果會分的比較開。

4. (3%)Refer to math problem

1.(a) Cov_mat:

$$(0V = \frac{1}{m-1} (X - \overline{X})^{T} (X - \overline{x}) = \begin{cases} 13.38 & 0.555 & 3.644 \\ 0.555 & 13.555 & 3.222 \\ 3.644 & 3.222 & 9.067 \end{cases}$$

eigen value:

16.997

12.923

6.08

ergen rector:

(b). (1, 2, 3)
$$\rightarrow$$
 (7.19, 1.37, -2.25)

$$(4, 8, 5)$$
 \rightarrow $(0.76, -0.94, -a.73)$

$$(3, 12, 9)$$
 \rightarrow $(-3.07, -4.45, -3.19)$

$$(1, 8, 5)$$
 -7 $(2.11, -2.98, -1.93)$

$$(7, 4, 1)$$
 -7 $(3.35, 3.92, 2.53)$

$$(9, 8, 9) \rightarrow (-4.41, 2.56, -2.14)$$

$$(3, 8, 1) \rightarrow (3.47, -1.73, 2.28)$$

$$(11, 5, 6) \rightarrow (-2.31, (1.03, 0.20)$$

(6).

$$\chi_{20} \cdot A = \chi_{30}$$
 (reconstruction)

error: $\frac{1}{10} \frac{1}{3} ||X_i - X_{50}i||_2 = 11.026$ 2. (a) AER MXN $(AA^T)^T = AA^T$, $(A^TA)^T = A^TA$ symmetric YXERM $X^T A A^T X = (A^T X)^T A^T X > 0$ thus: AAT is positive semi-definite Yx&R^ $X^T (A^T A)X = (AX)^T AX 7 0$ thus: AAT is positive semi-definite assume: $\lambda \neq 0$ is an eigenvalue of $A^{T}A$ $= A^T A x = \lambda x$ $f_{0}r_{x}\neq 0$ $A\cdot A^{T}A_{x}=A_{\lambda}x$ \vec{A} \vec{A} \vec{A} \vec{A} \vec{A} \vec{A} \vec{A} \vec{A} thus $\Lambda \neq 0$ is also an eigenvalue of AA^{T} as same, we can prove that: if A is an eigenvalue of AAT, is also an eigenvalue of ATA (b). 7

(c)
$$L = Trace(\Phi^T Z \Phi) + \lambda (\Phi^T \Phi - I_k)$$

$$\frac{\partial L}{\partial \Phi} = \frac{\partial \operatorname{Trace} \left(\mathbf{Z}^{T} \mathbf{Z} \mathbf{\Phi} \right)}{\partial \mathbf{\Phi}} + 2\lambda \mathbf{\Phi}$$

$$\frac{\int \operatorname{Trace}(\mathbf{E}^{T} \mathbf{2}\mathbf{E})}{\int \mathbf{E}} = \mathbf{E}^{T} \mathbf{2} + \mathbf{E}^{T} \mathbf{2}^{T}$$

$$= 2\mathbf{E}^{T} \mathbf{3}$$

thus
$$\mathbf{Z}^{\mathsf{T}}\mathbf{Z} + \mathbf{\Lambda}\mathbf{Z}^{\mathsf{T}} = \mathbf{0}$$

$$\frac{\partial L}{\partial \lambda} = \mathcal{Z}^T \mathcal{Z} - I_m = 0 \qquad \qquad I_k \mathcal{Z} + \mathcal{I} \mathcal{Z}^2 =$$

thus
$$\mathbf{Z}^{\mathsf{T}}\mathbf{Z} = \mathbf{I}\mathbf{m}$$
 0

3. rorry, no idea!