執行：

因為兩個任務合併時出現了一些 error 沒有被查出來，所以提交了兩份 code，分別對應任務 1 和任務 2。

目錄：

```
t08902109_Nachos2/
|_ nachos-4.0-1/
|_ nachos-4.0-2/
|_ report.pdf
```

System Call：

```
~ $cd ./t08902109_Nachos2/nachos-4.0-1/code
~/code $ make
~/code cd userprog
~/userprog $./nachos -e ./../test/test
```

CPU Scheduling:

```
~ $cd ./t08902109_Nachos2/nachos-4.0-2/code
~/code $ make
~/code cd threads
~/thread $./nachos FCFS
~/thread $./nachos SJF
~/thread $ ./nachos PRIORITY
~/thread $ ./nachos RR
```

一． System Call

1. Motivation

目標：撰寫 Sleep function，將 Thread 進入休眠。

計劃：

一方面，當程序呼叫 Sleep() 時，會呼叫 WaitUntil()，然後將其丟入 Bedroom 安眠。實現休眠。

另一方面，kernel 存有 alarm，每隔固定一段時間，就會呼叫 Alarm::CallBack()，因此，對於這個鬧鐘來個累加器_current_interrupt，全局去記數，每加一次就相當於過了 1 毫秒 (ms)。然後在 CallBlack() 被呼叫時，來去檢查誰該醒來。

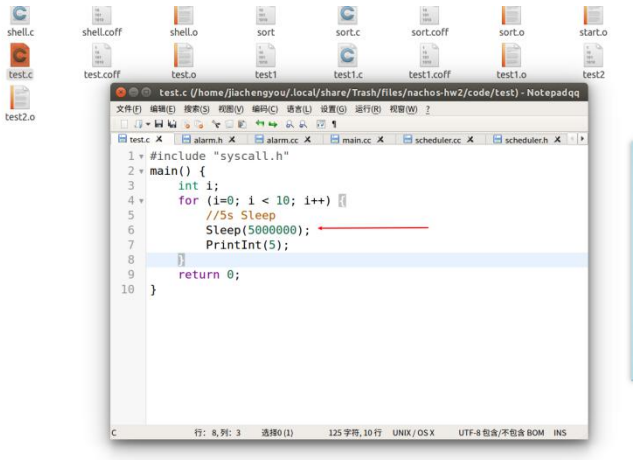
2. Implementation

執行 ：make

./nachos -e ./../test/test

可以看到休眠結果。

（1）Test function



每五秒輸出一個整數 5

（2）準備 call code，宣告函數。

```
31  #define SC_ThreadYield  10
32  #define SC_PrintInt 11
33  #define SC_Sleep 12
```

```
131
132  void PrintInt(int number);  //my System Call
133  void Sleep(int number); //add
134  #endif /* IN_ASM */
```

（3）呼叫 WaitUntil()

```
        return;
    case SC_Sleep:
        val=kernel->machine->ReadRegister(4);
        cout << "Sleep time:" << val << "(ms)" << endl;
        kernel->alarm->WaitUntil(val);
        return;
```

（3）書寫 bedroom，全局計數

```
class Bedroom {
    public:
        Bedroom():_current_interrupt(0) {};
        void PutToBed(Thread *t, int x);
    bool MorningCall();
    bool IsEmpty();
    private:
        class Bed {
            public:
                Bed(Thread* t, int x):
                    sleeper(t), when(x) {};
                Thread* sleeper;
                int when;
        };
```

（4）Callback 檢測何時喚醒

```
Alarm::CallBack()
{
    Interrupt *interrupt = kernel->interrupt;
    MachineStatus status = interrupt->getStatus();
    bool woken = _bedroom.MorningCall();
    kernel->currentThread->setPriority(kernel->currentThread->getPriority() - 1);
    if (status == IdleMode && !woken && _bedroom.IsEmpty()) {
        if (!interrupt->AnyFutureInterrupts()) {
        timer->Disable();
    }
    } else {
```

（5） WaitUntil()，將 thread 丟入 Bedroom 安眠。

```
74
75 void Alarm::WaitUntil(int x) {
76     IntStatus oldLevel = kernel->interrupt->SetLevel(IntOff);
77     Thread* t = kernel->currentThread;
78
79
80
81     cout << "Alarm::WaitUntil go sleep" << endl;
82     _bedroom.PutToBed(t, x);
83     kernel->interrupt->SetLevel(oldLevel);
84 }
```

（6）bedroom 進入休眠，和喚醒休眠。

```
88 void Bedroom::PutToBed(Thread*t, int x) {
89     ASSERT(kernel->interrupt->getLevel() == IntOff);
90     _beds.push_back(Bed(t, _current_interrupt + x));
91     t->Sleep(false);
92 }
93 bool Bedroom::MorningCall() {
94     bool woken = false;
95     _current_interrupt ++;
96     for(std::list<Bed>::iterator it = _beds.begin();
97         it != _beds.end(); ) {
98         if(_current_interrupt >= it->when) {
99             woken = true;
00             cout << "Bedroom::MorningCall Thread woken" << endl;
01             kernel->scheduler->ReadyToRun(it->sleeper);
02             it = _beds.erase(it);
```

3. Result

運行結果：

```
jiachengyou@jiachengyou-virtual-machine: ~/t08902109_Nachos1/nachos-4.0/code/userprog
jiachengyou@jiachengyou-virtual-machine:~/t08902109_Nachos1/nachos-4.0/code$ cd
./userprog/
jiachengyou@jiachengyou-virtual-machine:~/t08902109_Nachos1/nachos-4.0/code/user
prog$ ./nachos -e ./../test/test
Total threads number is 1
Thread ./../test/test is executing.
Sleep Time :5000000(ms)
Alarm::WaitUntil go sleep
Bedroom::MorningCall Thread woken
Print integer:5
Sleep Time :5000000(ms)
Alarm::WaitUntil go sleep
Bedroom::MorningCall Thread woken
Print integer:5
Sleep Time :5000000(ms)
Alarm::WaitUntil go sleep
Bedroom::MorningCall Thread woken
Print integer:5
Sleep Time :5000000(ms)
Alarm::WaitUntil go sleep
Bedroom::MorningCall Thread woken
Print integer:5
Sleep Time :5000000(ms)
Alarm::WaitUntil go sleep
```

二． CPU Scheduling

1. Motivation

目標：決定程式的執行次序。

有如下幾種方式：

FIFO (FCFS) 先來先服務

SJF 最短工作優先

Priority 最小優先權優先

RR (Round-robin)

2. Implementation

cd code/threads

$ ./nachos FCFS

$ ./nachos SJF

$ ./nachos Priority

$ ./nachos RR

計劃：

撰寫 self::test 函數，通過宣告不同的 compare function，實現不同類型的排程。

（1）書寫 test 測試

```
Thread::SchedulingTest()
{
    const int thread_num = 4;
    char *name[thread_num] = {"A", "B", "C", "D"};
    int thread_priority[thread_num] = {5, 1, 3, 2};
    int thread_burst[thread_num] = {3, 9, 7, 3};

    Thread *t;
    for (int i = 0; i < thread_num; i ++) {
        t = new Thread(name[i]);
        t->setPriority(thread_priority[i]);
        t->setBurstTime(thread_burst[i]);
        t->Fork((VoidFunctionPtr) threadBody, (void *)NULL);
    }
    kernel->currentThread->Yield();
}
```

（2）修改讀入參數

```
//add
SchedulerType type = RR;
if(strcmp(argv[1], "FCFS") == 0) {
    type = FIFO;
} else if (strcmp(argv[1], "SJF") == 0) {
    type = SJF;
} else if (strcmp(argv[1], "PRIORITY") == 0) {
    type = Priority;
} else if (strcmp(argv[1], "RR") == 0) {
    type = RR;
}

//add

kernel = new KernelType(argc, argv);
kernel->Initialize(type);
```

（3）定義 schedule type 和相關函數

```
enum SchedulerType {
        RR,     // Round Robin
        SJF,
        Priority,
        FIFO
};

class Scheduler {
  public:
    Scheduler();        // Initialize list of ready threads
    Scheduler(SchedulerType type);
    ~Scheduler();
```

```
// SelfTest for scheduler is implemented in class Thread
SchedulerType getSchedulerType() {return schedulerType;}
void setSchedulerType(SchedulerType t) {schedulerType = t;}
private:
SchedulerType schedulerType;
List<Thread *> *readyList;  // queue of threads that are ready to run,
                // but not running
```

（4）不同類型的排程，宣告相對應的 compare function.

```
int SJFCompare(Thread *a, Thread *b) {
    if(a->getBurstTime() == b->getBurstTime())
        return 0;
    return a->getBurstTime() > b->getBurstTime() ? 1 : -1;
}
int PriorityCompare(Thread *a, Thread *b) {
    if(a->getPriority() == b->getPriority())
        return 0;
    return a->getPriority() > b->getPriority() ? 1 : -1;
}
int FIFOCompare(Thread *a, Thread *b) {
    return 1;
}
```

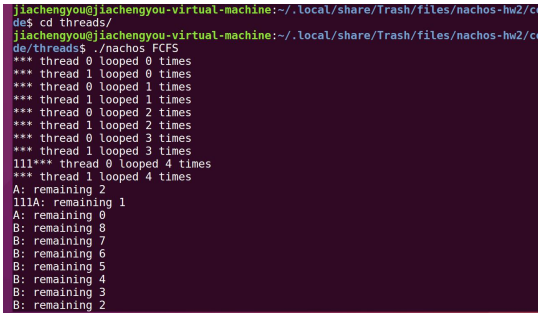
```
Scheduler::Scheduler() {
    Scheduler(RR);
}

Scheduler::Scheduler(SchedulerType type)
{
    schedulerType = type;
    switch(schedulerType) {
    case RR:
        readyList = new List<Thread *>;
        break;
    case SJF:
        readyList = new SortedList<Thread *>(SJFCompare);
        break;
    case Priority:
        readyList = new SortedList<Thread *>(PriorityCompare);
        break;
    case FIFO:
        readyList = new SortedList<Thread *>(FIFOCompare);
    }
    toBeDestroyed = NULL;
}
```

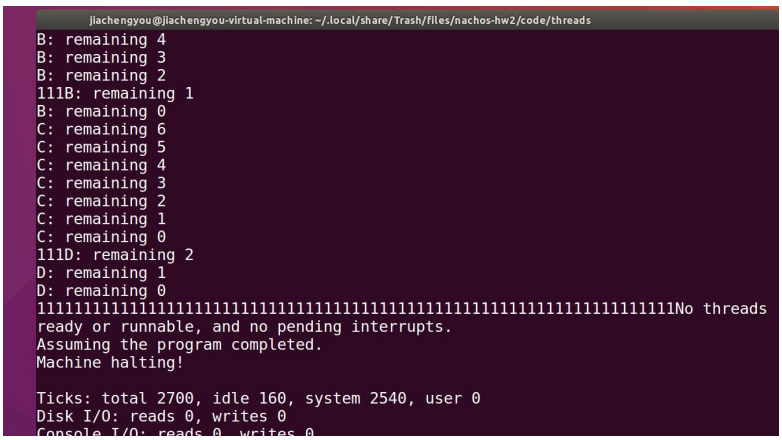
（5）修改到對應的 callback 和 waitUntil

```
50  Alarm::CallBack()
51  {
52      Interrupt *interrupt = kernel->interrupt;
53      MachineStatus status = interrupt->getStatus();
54      bool woken = _bedroom.MorningCall();
55      printf("111");
56      kernel->currentThread->setPriority(kernel->currentThread->getPriority() - 1
57      if (status == IdleMode && !woken && _bedroom.IsEmpty()) {
58          if (!interrupt->AnyFutureInterrupts()) {
59          timer->Disable();
60      }
61      } else {
62          if(kernel->scheduler->getSchedulerType() == RR ||
63              kernel->scheduler->getSchedulerType() == Priority ) {
64              cout << "=== interrupt->YieldOnReturn ===" << endl;
65              interrupt->YieldOnReturn();
66          }
67      }
68  }
69
70
71
72
73  void Alarm::WaitUntil(int x) {
74      IntStatus oldLevel = kernel->interrupt->SetLevel(IntOff);
75      Thread* t = kernel->currentThread;
76      printf("222");
77           // burst time
78      int worktime = kernel->stats->userTicks - t->getStartTime();
79      t->setBurstTime(t->getBurstTime() + worktime);
80      t->setStartTime(kernel->stats->userTicks);
```

3. Result

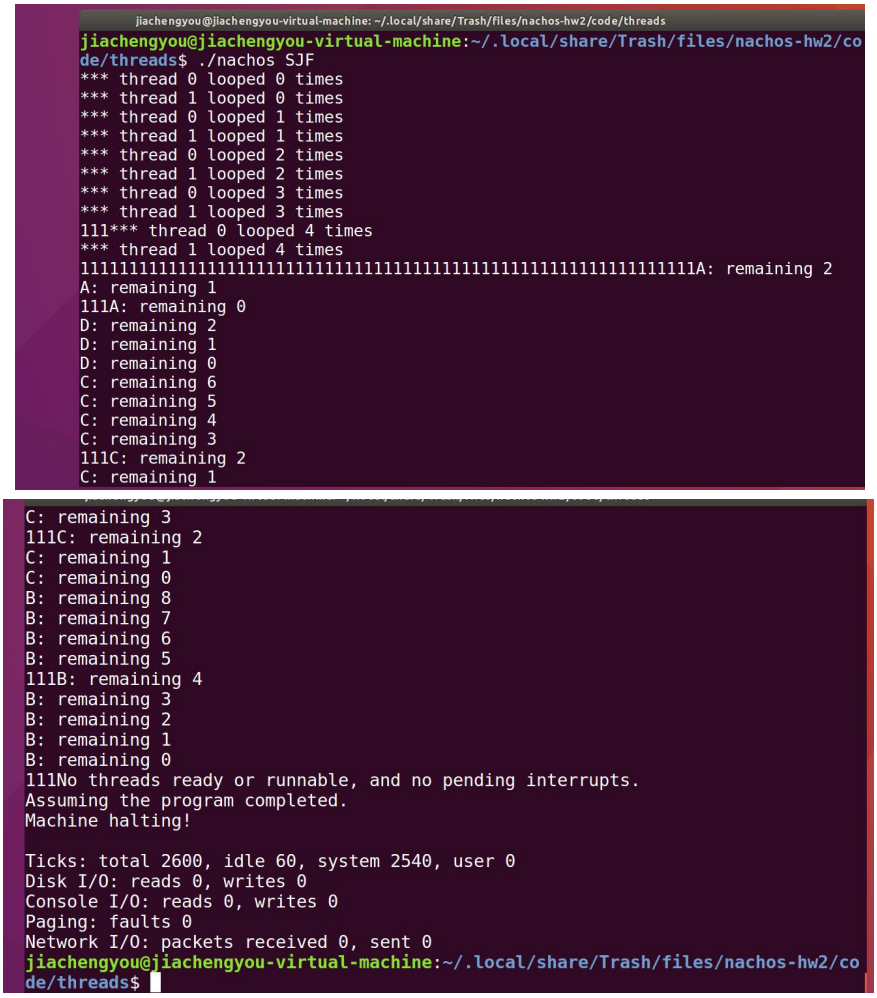
（1） (./threads) $ ./nachos FCFS





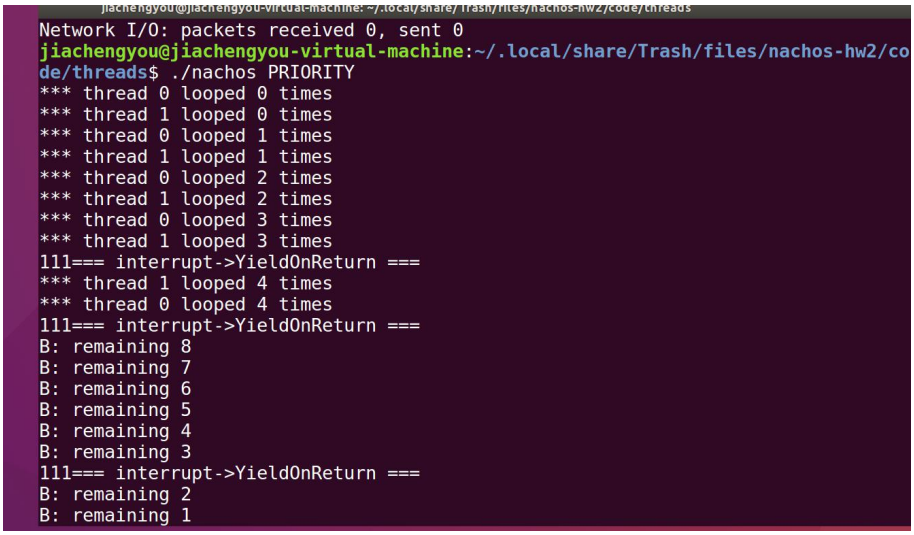
可以看出執行順序為 A,B,C,D，即先來先服務。

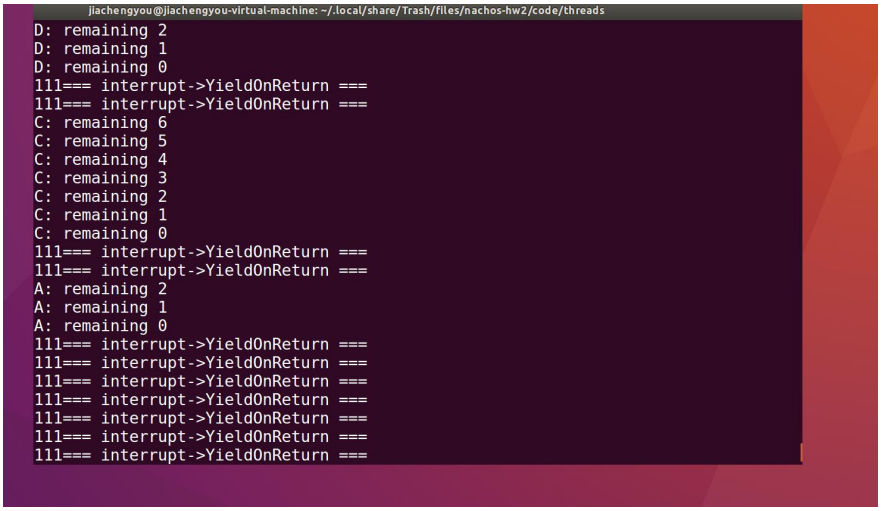
（2） (./threads) $ ./nachos SJF



執行結果為 A,D,C,B，即最短工作優先，thread_burst 越小越先執行。

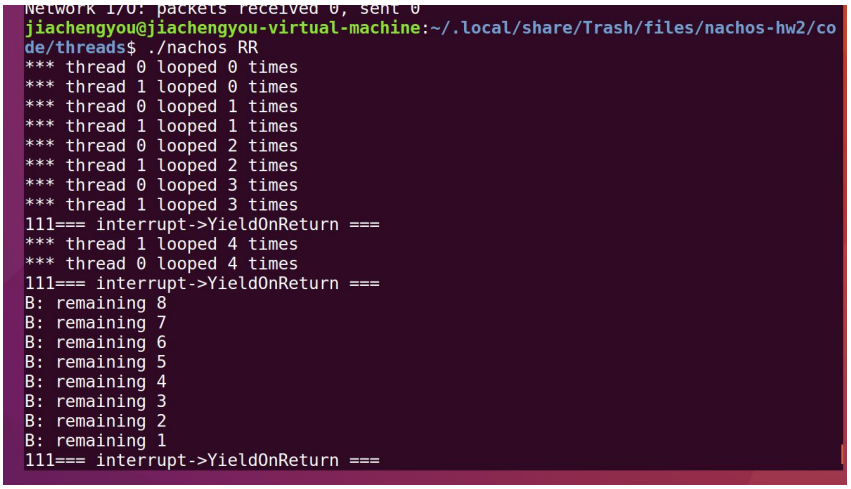
（3） (./threads) $ ./nachos　PRIORITY

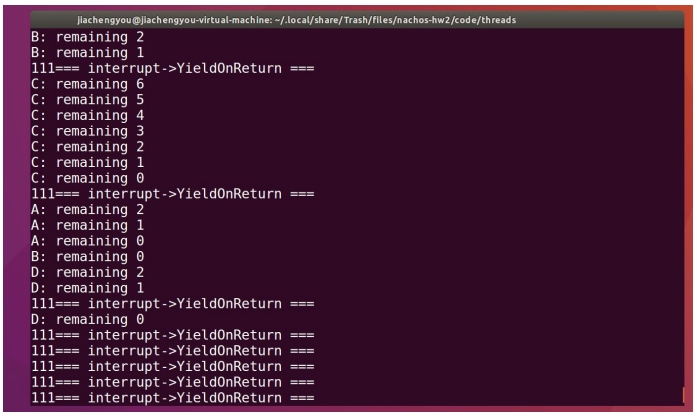




執行結果為 B,D,C,A，按照 priority 順序執行。

（4）(./threads) $ ./nachos　RR





一些問題：

寫完 CPU schedule 時，如果執行原來的命令（如下），會出現段錯誤

可能因為在寫第二個命令時修改到了不對的地方，因為時間關係，這個問題本次沒有解決。