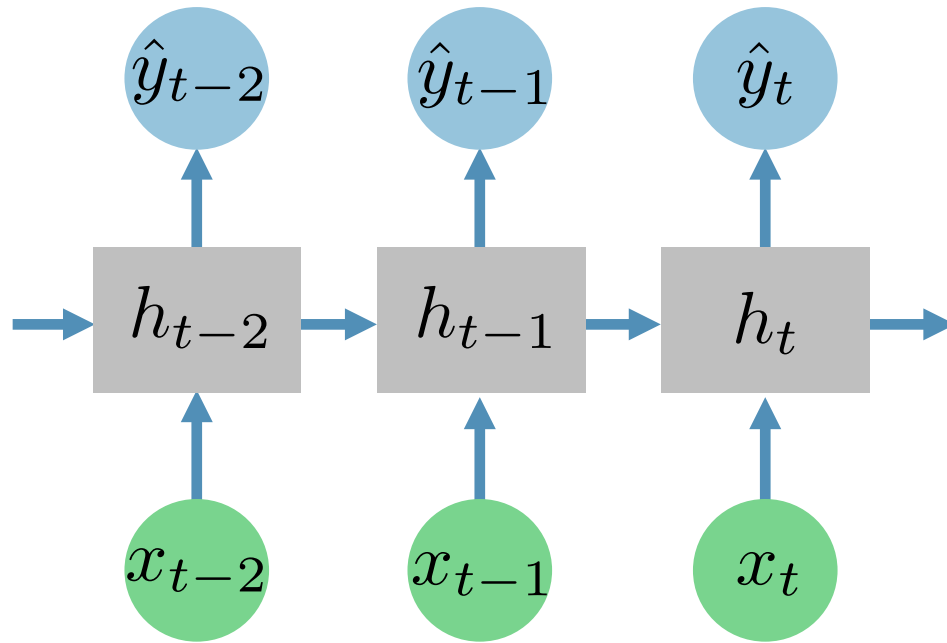


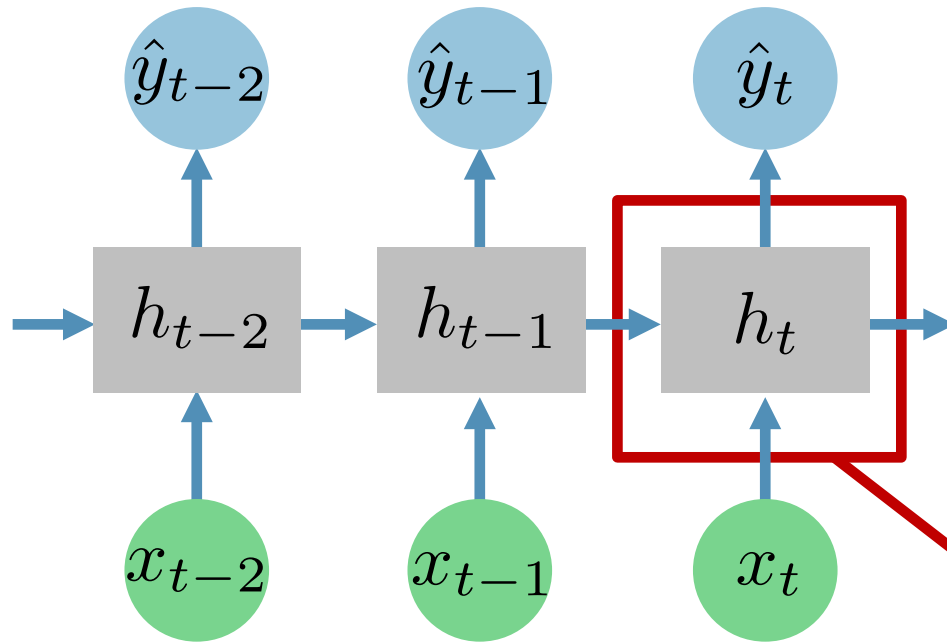
LSTM and GRU

Previously on this week: Simple RNN



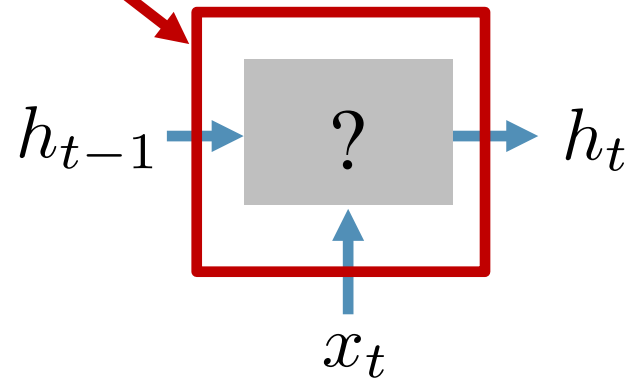
$$h_t = f_h(Vx_t + Wh_{t-1} + b_h)$$

Previously on this week: Simple RNN

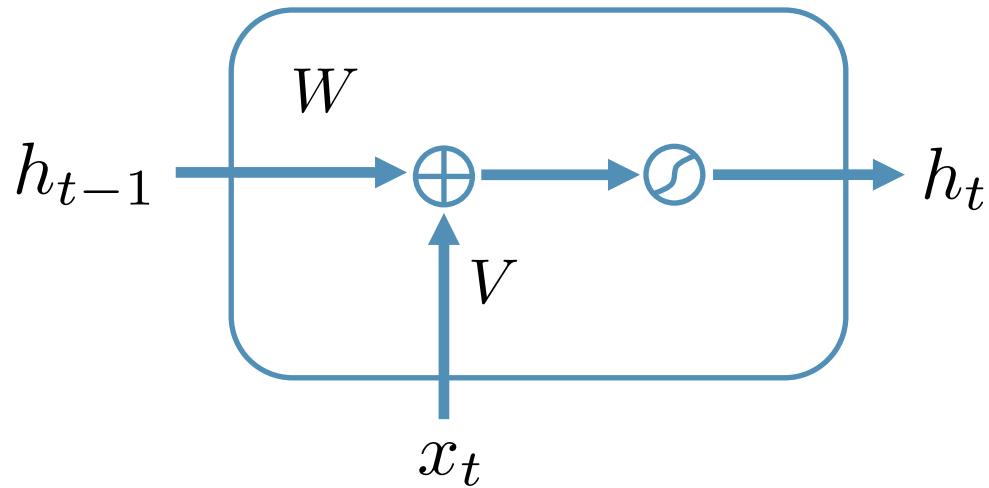


$$h_t = f_h(Vx_t + Wh_{t-1} + b_h)$$

More sophisticated
function

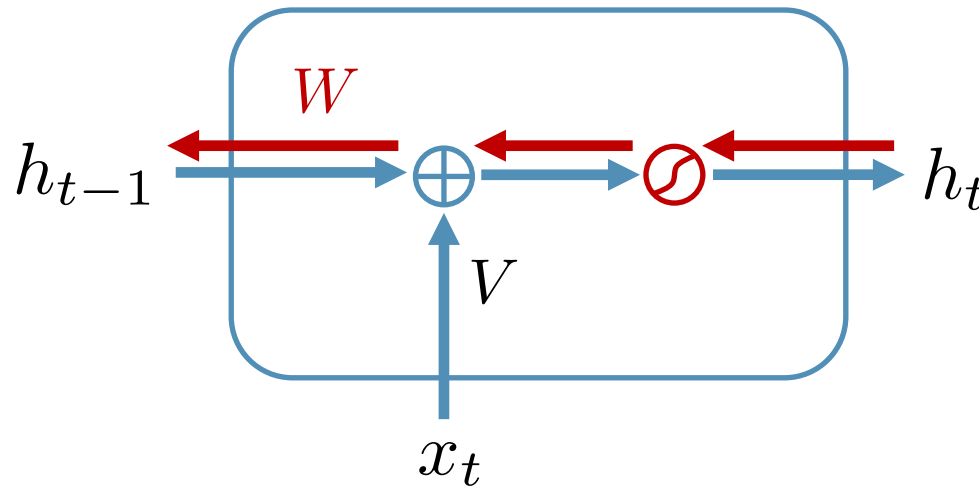


Simple RNN



$$h_t = \tilde{f}(Vx_t + Wh_{t-1} + b_h)$$

Simple RNN



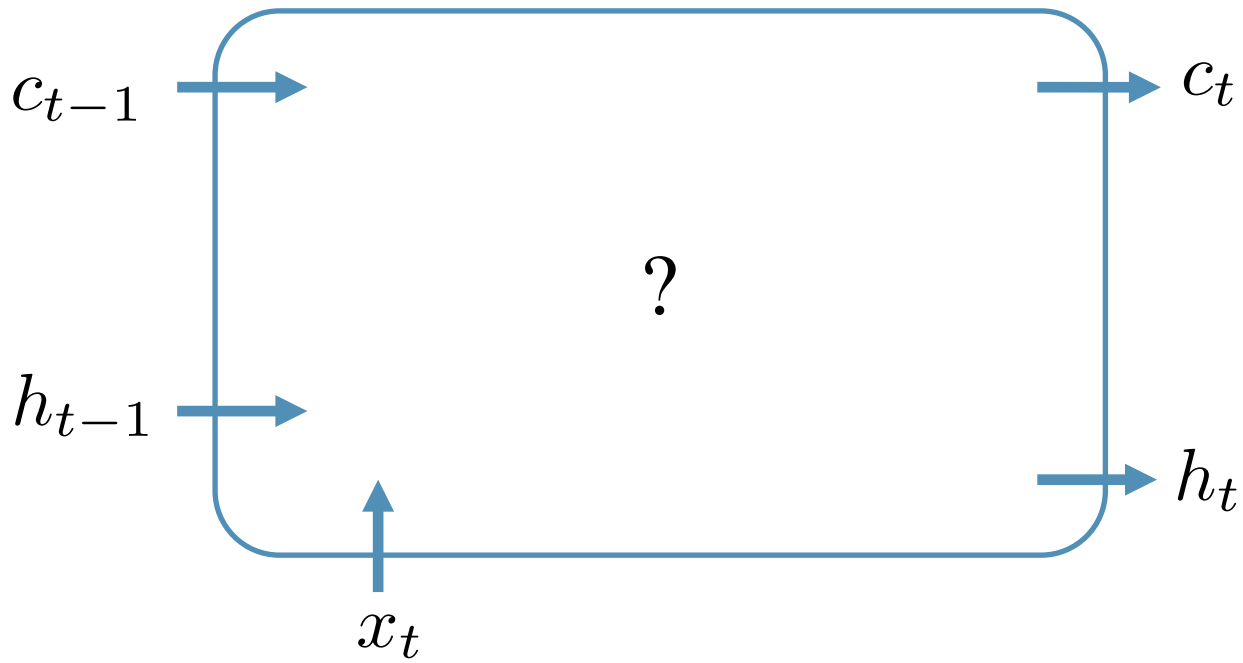
$$h_t = \tilde{f}(Vx_t + Wh_{t-1} + b_h)$$

Backward pass

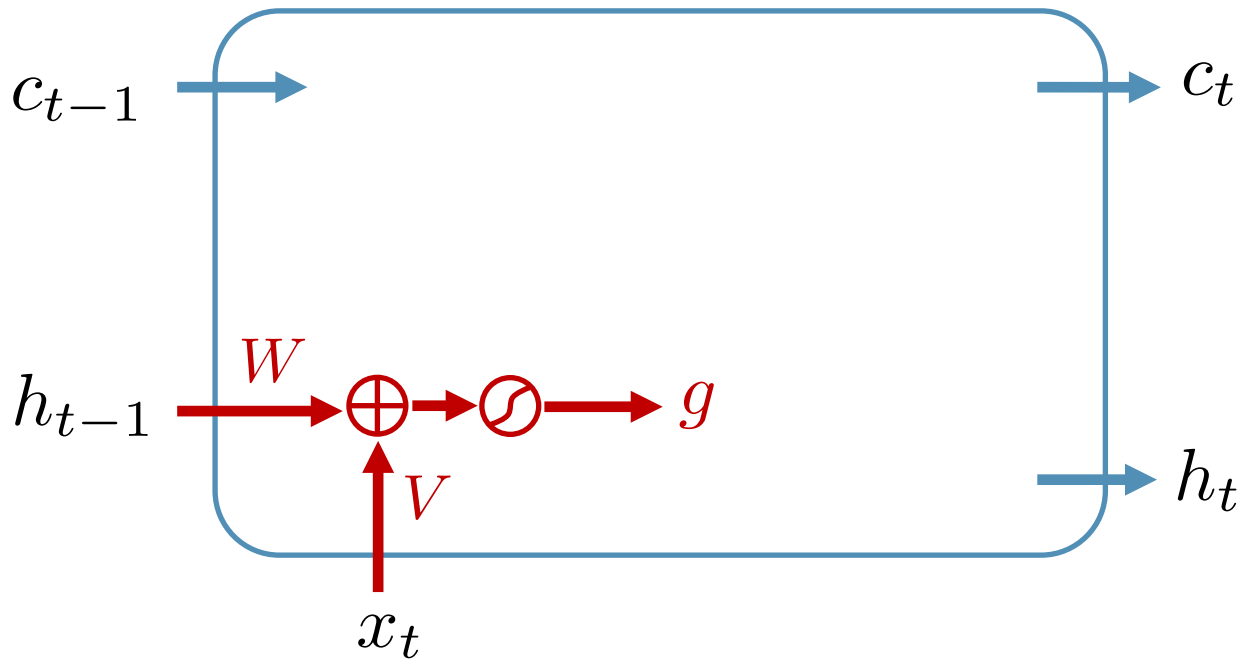
W and nonlinearity \longrightarrow vanishing gradients

We need a short way for the gradients!

LSTM: version 0

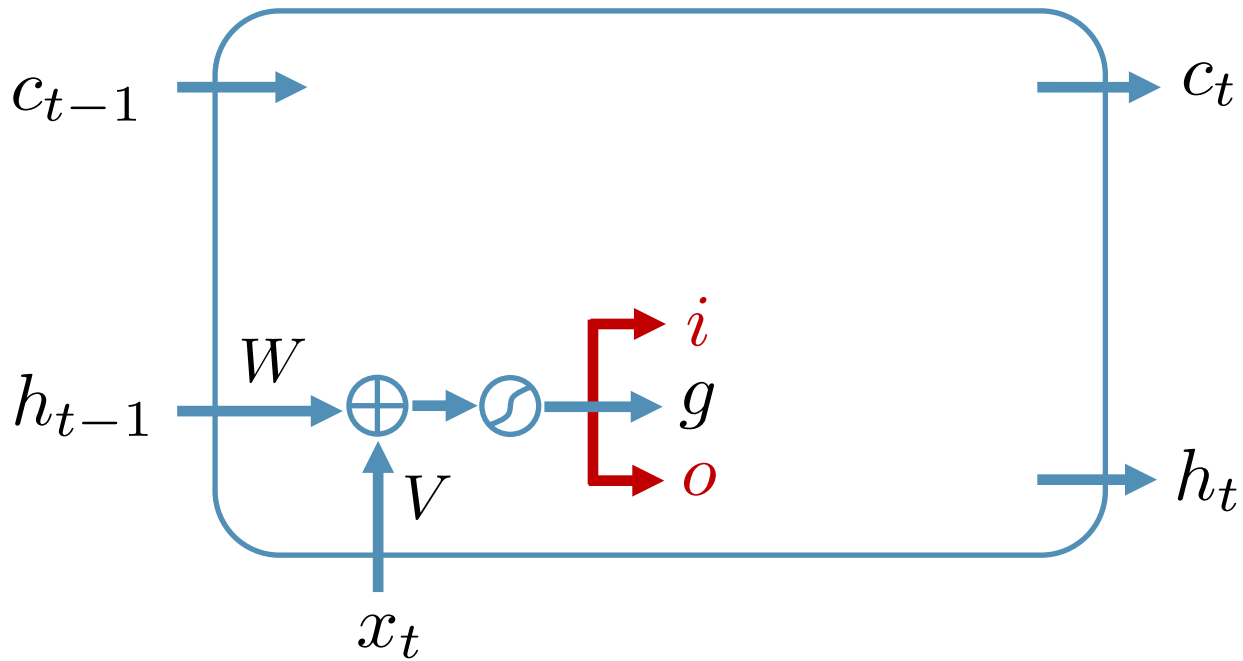


LSTM: version 0



$$g_t = \tilde{f}(V_g x_t + W_g h_{t-1} + b_g)$$

LSTM: version 0

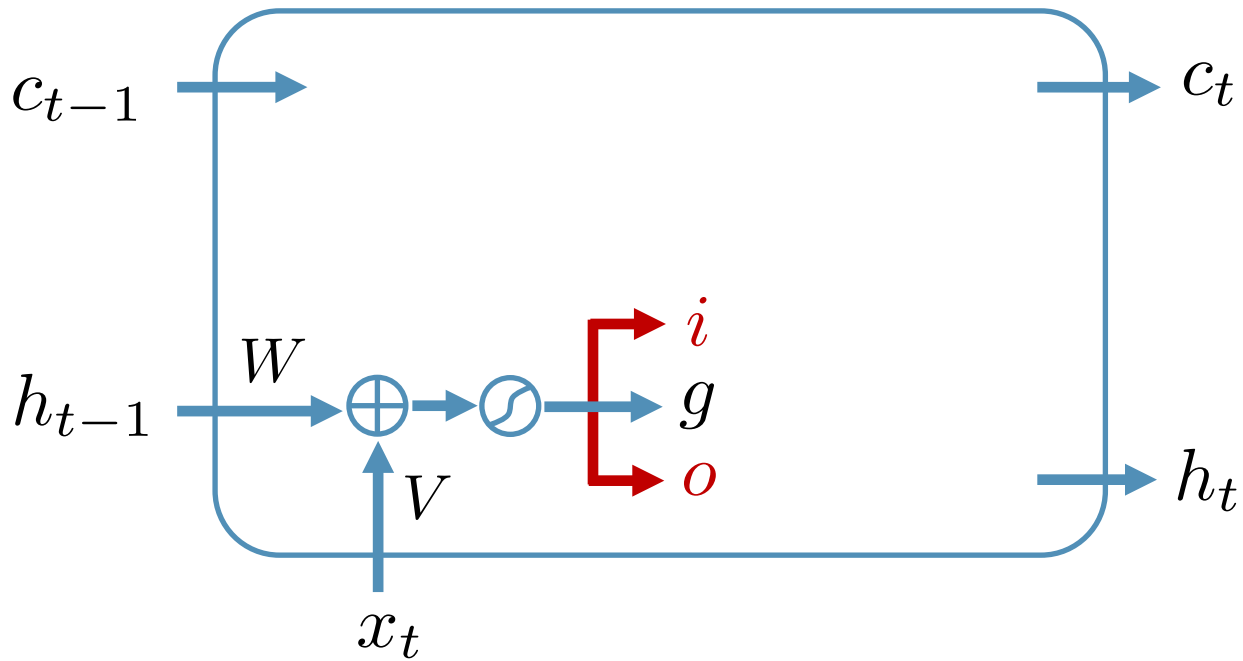


$$g_t = \tilde{f}(V_g x_t + W_g h_{t-1} + b_g)$$

$$i_t = \sigma(V_i x_t + W_i h_{t-1} + b_i)$$

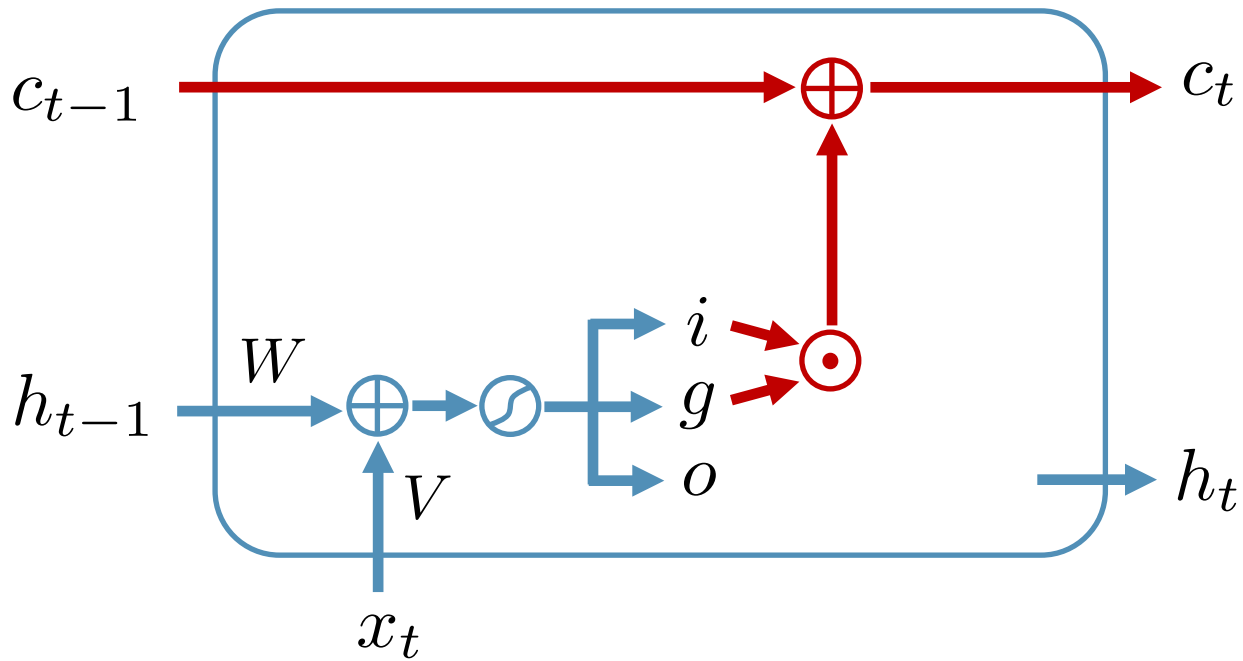
$$o_t = \sigma(V_o x_t + W_o h_{t-1} + b_o)$$

LSTM: version 0



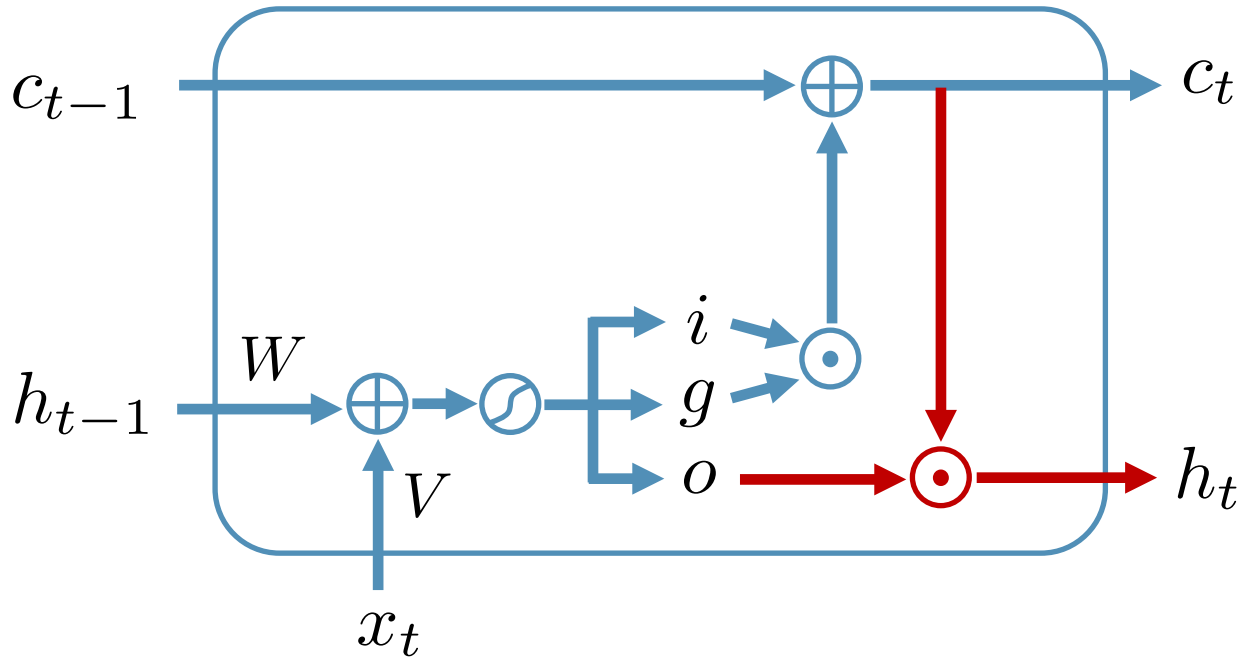
$$\begin{pmatrix} g_t \\ i_t \\ o_t \end{pmatrix} = \begin{pmatrix} \tilde{f} \\ \sigma \\ \sigma \end{pmatrix} (V x_t + W h_{t-1} + b)$$

LSTM: version 0



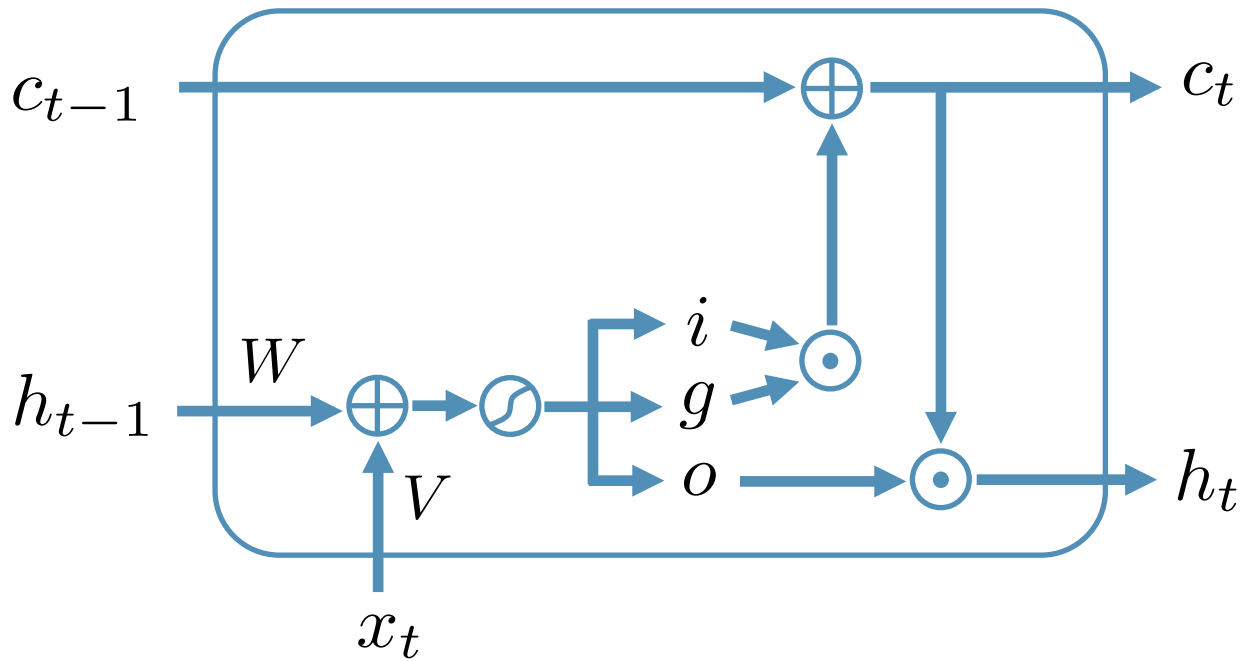
$$\begin{pmatrix} g_t \\ i_t \\ o_t \end{pmatrix} = \begin{pmatrix} \tilde{f} \\ \sigma \\ \sigma \end{pmatrix} (Vx_t + Wh_{t-1} + b) \quad c_t = c_{t-1} + i_t \cdot g_t$$

LSTM: version 0

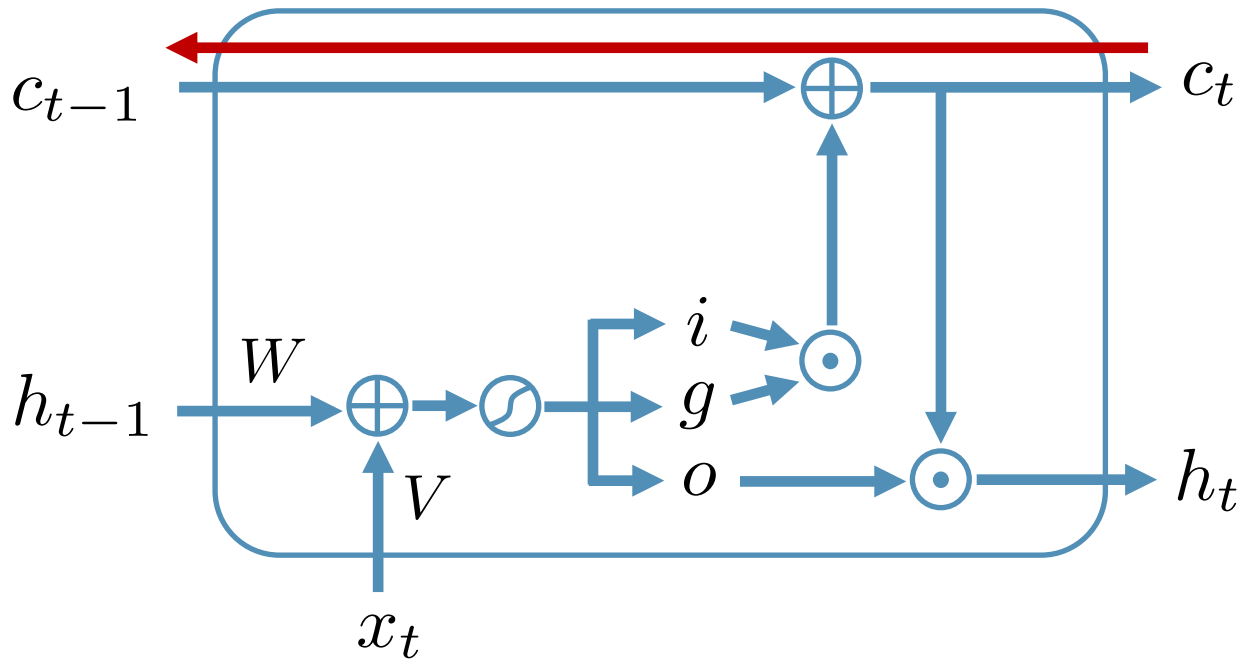


$$\begin{pmatrix} g_t \\ i_t \\ o_t \end{pmatrix} = \begin{pmatrix} \tilde{f} \\ \sigma \\ \sigma \end{pmatrix} (Vx_t + Wh_{t-1} + b) \quad \begin{aligned} c_t &= c_{t-1} + i_t \cdot g_t \\ h_t &= o_t \cdot \tilde{f}(c_t) \end{aligned}$$

LSTM: vanishing gradients



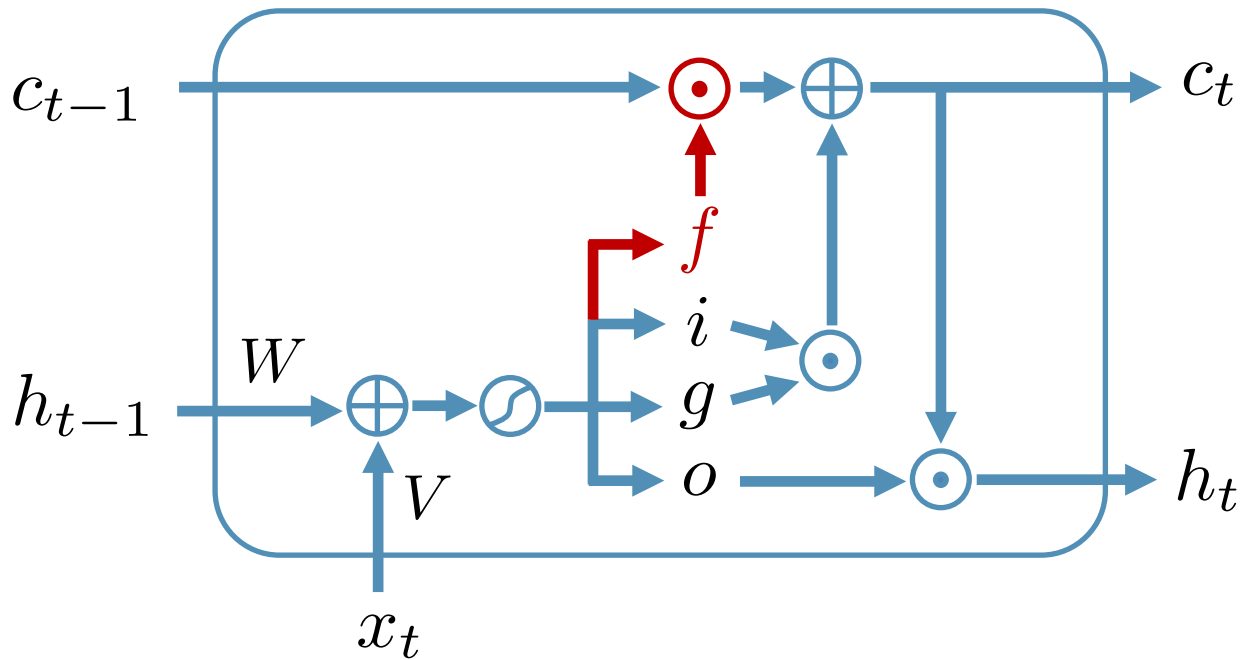
LSTM: vanishing gradients



$$c_t = c_{t-1} + i_t \cdot g_t \quad \frac{\partial h_t}{\partial h_{t-1}} \Rightarrow \frac{\partial c_t}{\partial c_{t-1}} = \text{diag}(1)$$

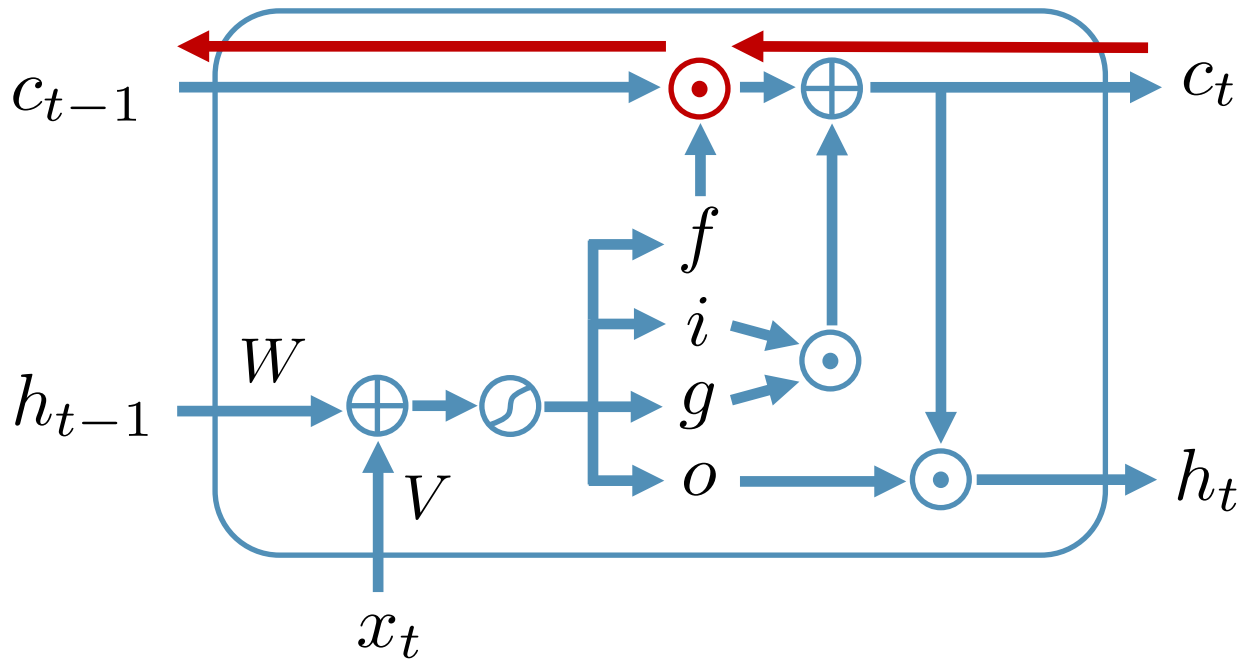
Gradients do not vanish!

LSTM: forget sometimes



$$\begin{pmatrix} g_t \\ i_t \\ o_t \\ \textcolor{red}{f}_t \end{pmatrix} = \begin{pmatrix} \tilde{f} \\ \sigma \\ \sigma \\ \sigma \end{pmatrix} (Vx_t + Wh_{t-1} + b) \quad \begin{aligned} c_t &= \textcolor{red}{f}_t \cdot c_{t-1} + i_t \cdot g_t \\ h_t &= o_t \cdot \tilde{f}(c_t) \end{aligned}$$

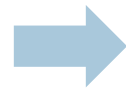
LSTM: forget sometimes



$$f_t = \sigma(V_f x_t + W_f h_{t-1} + b_f)$$

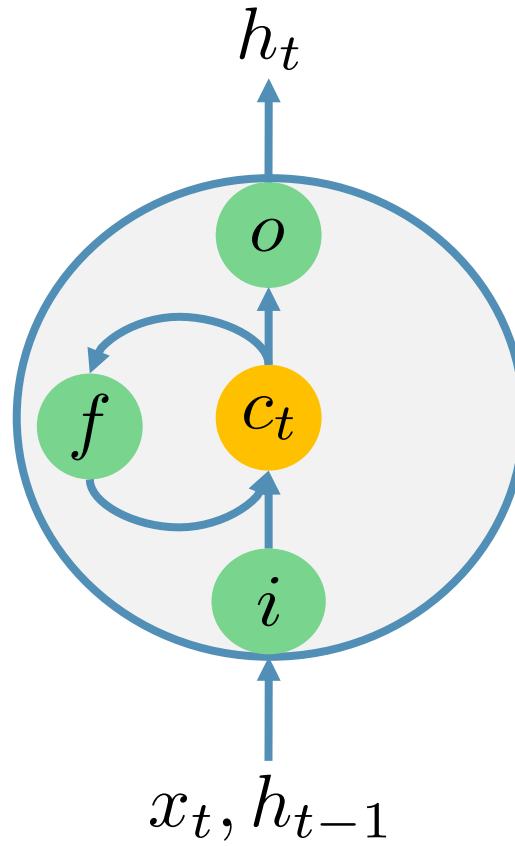
$$c_t = f_t \cdot c_{t-1} + i_t \cdot g_t$$

$$\frac{\partial c_t}{\partial c_{t-1}} = \text{diag}(f_t)$$



High initial b_f

LSTM: extreme regimes

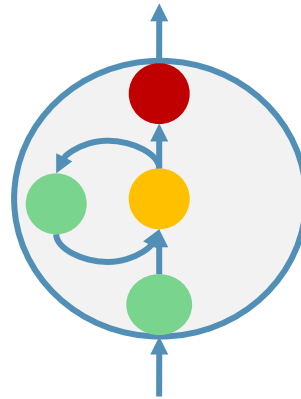


LSTM: extreme regimes

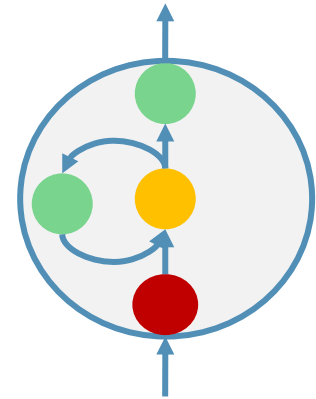
● - gate is close

● - gate is open

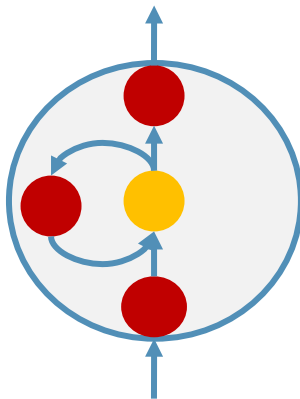
Captures info



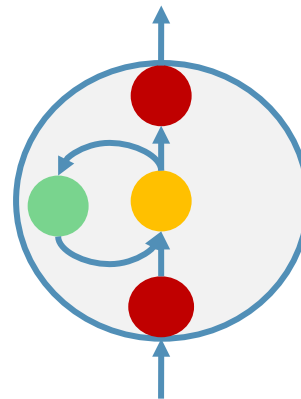
Releases info



Erases info



Keeps info



= RNN

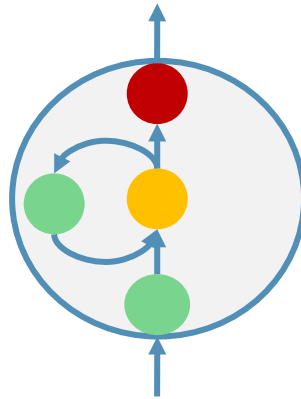
?

LSTM: extreme regimes

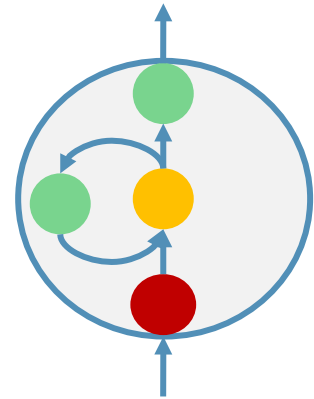
● - gate is close

● - gate is open

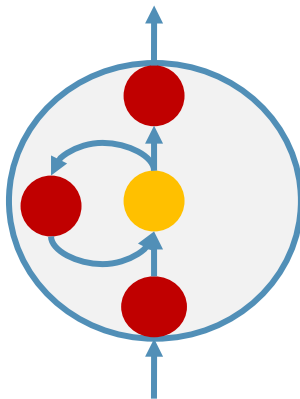
Captures info



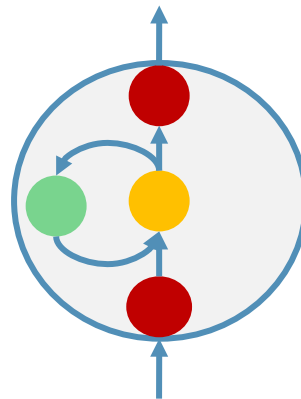
Releases info



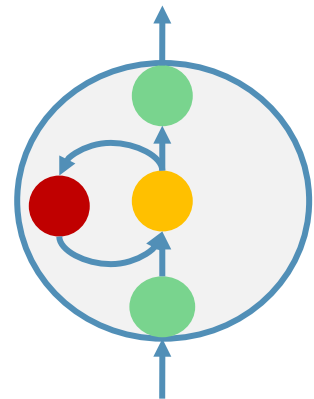
Erases info



Keeps info

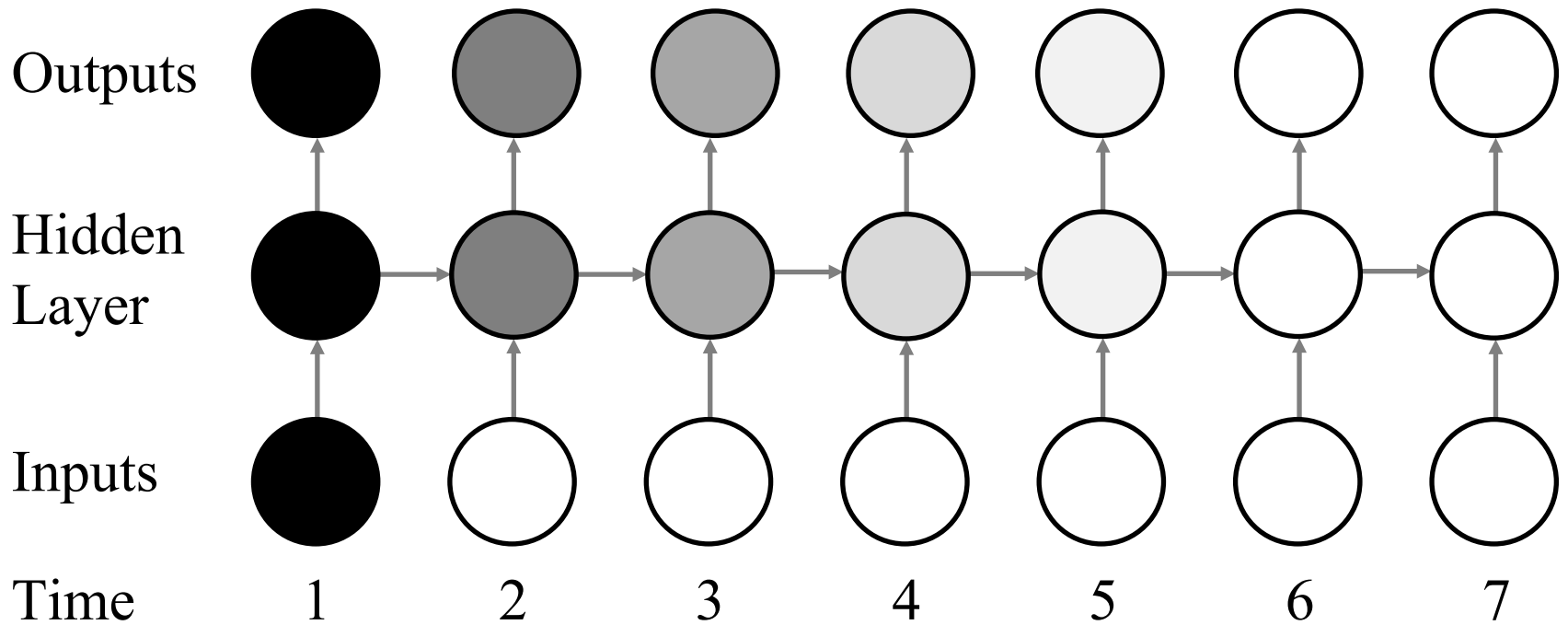


= RNN



LSTM: information flow

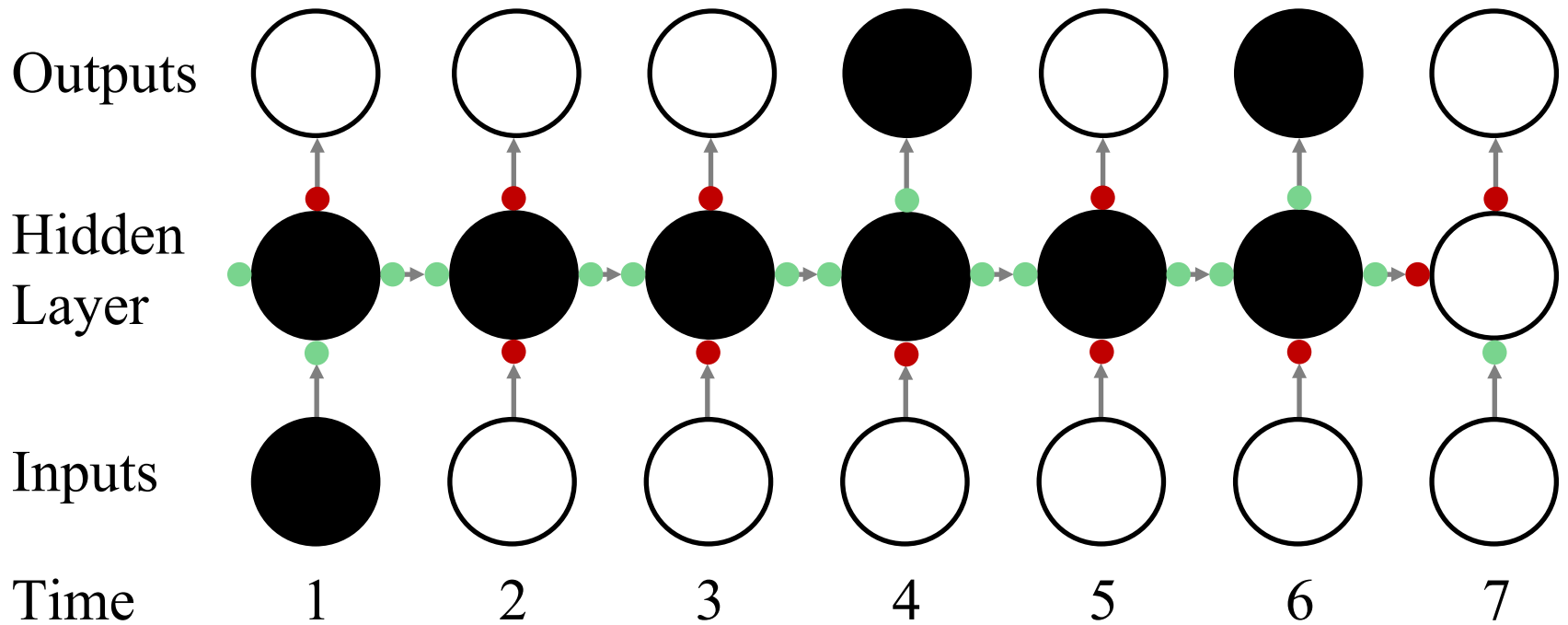
RNN



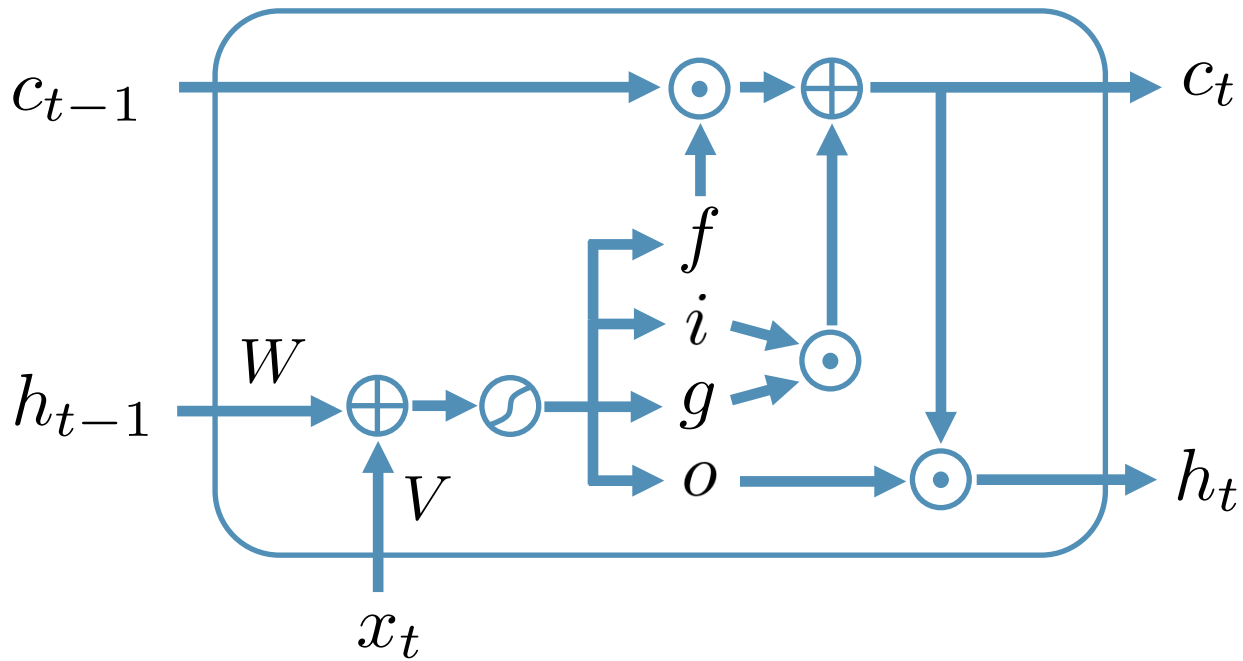
LSTM: information flow

LSTM

- - gate is close
- - gate is open

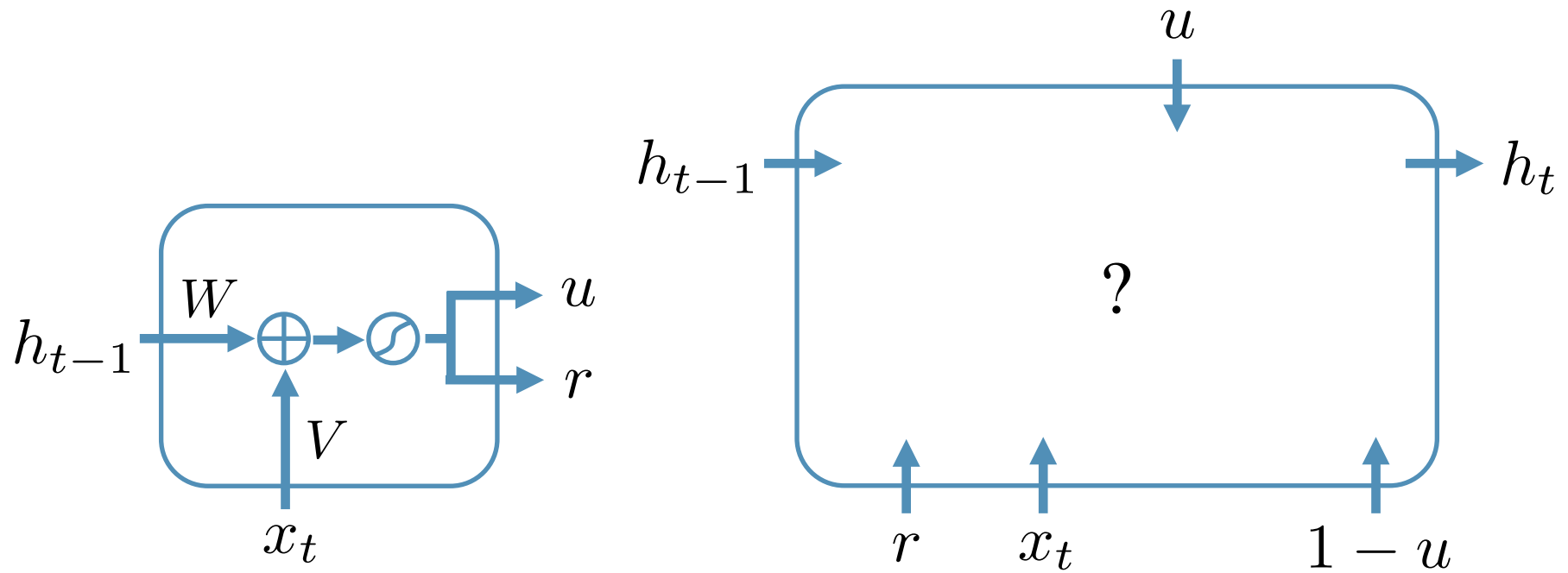


LSTM



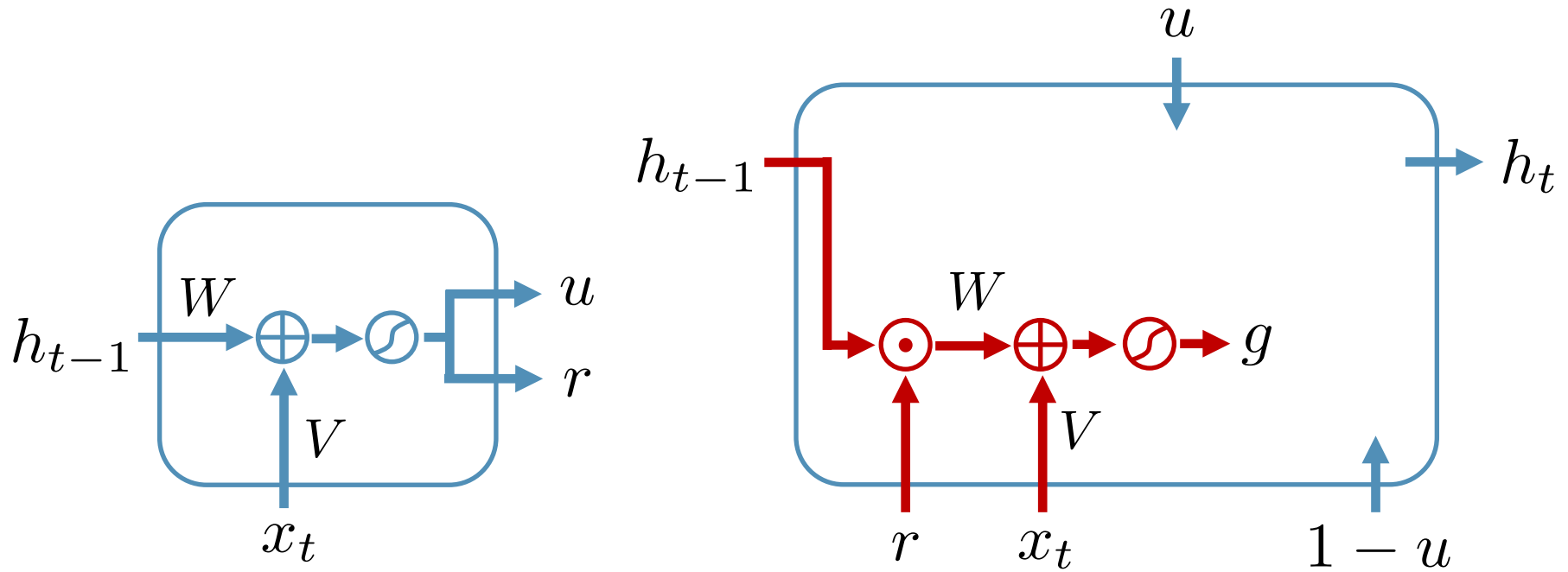
$$\begin{pmatrix} g_t \\ i_t \\ o_t \\ f_t \end{pmatrix} = \begin{pmatrix} \tilde{f} \\ \sigma \\ \sigma \\ \sigma \end{pmatrix} (Vx_t + Wh_{t-1} + b) \quad \begin{aligned} c_t &= f_t \cdot c_{t-1} + i_t \cdot g_t \\ h_t &= o_t \cdot \tilde{f}(c_t) \end{aligned}$$

GRU



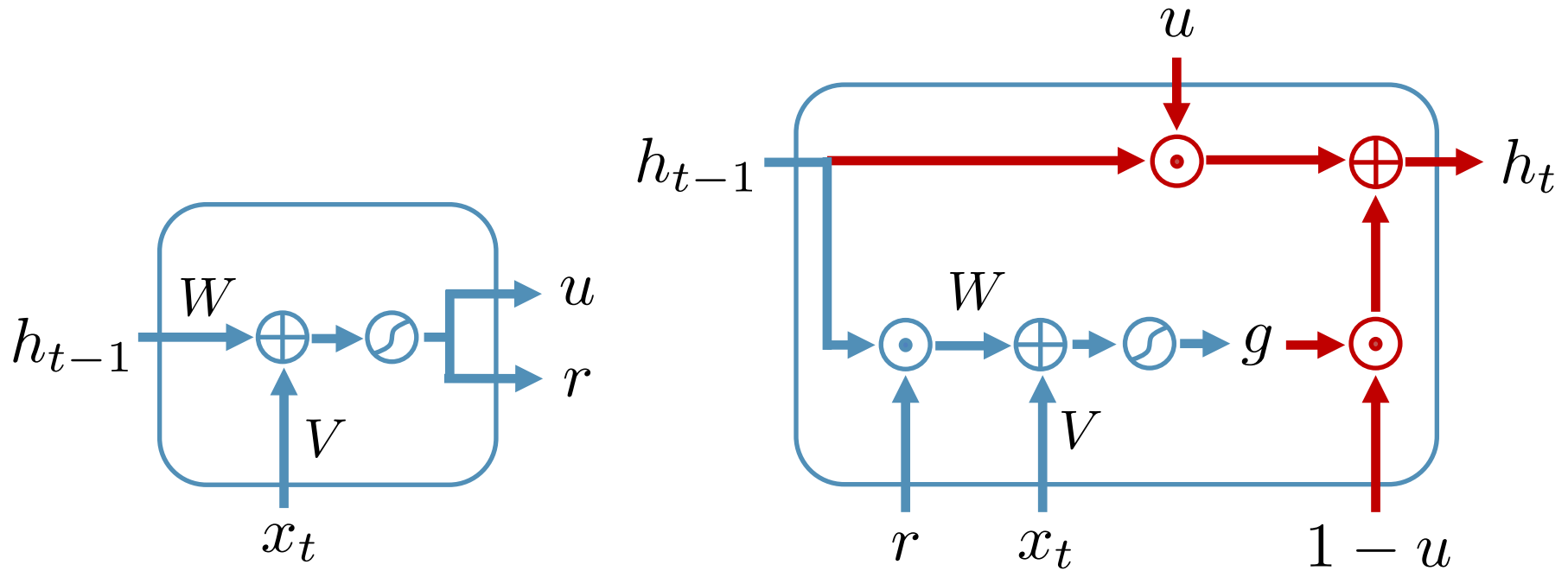
$$\begin{pmatrix} r_t \\ u_t \end{pmatrix} = \sigma(Vx_t + Wh_{t-1} + b)$$

GRU



$$\begin{pmatrix} r_t \\ u_t \end{pmatrix} = \sigma(Vx_t + Wh_{t-1} + b) \quad g_t = \tilde{f}(V_g x_t + W_g(h_{t-1} \cdot r_t) + b_g)$$

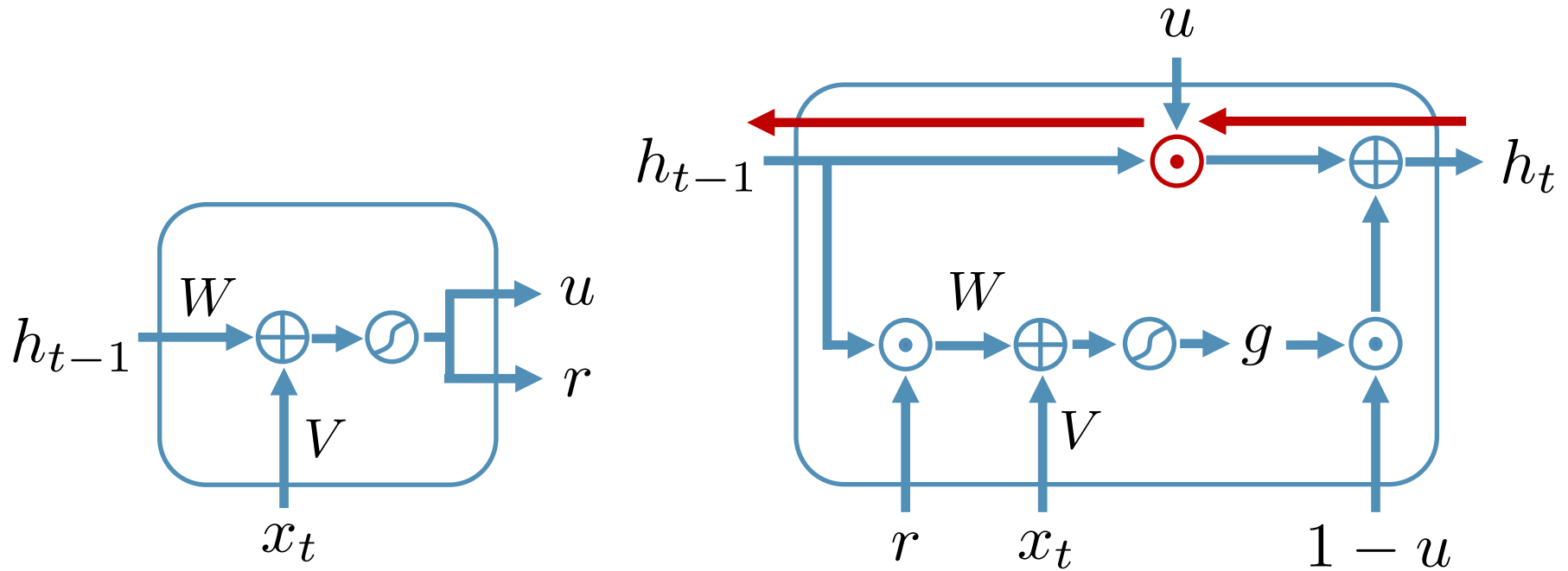
GRU



$$\begin{pmatrix} r_t \\ u_t \end{pmatrix} = \sigma(Vx_t + Wh_{t-1} + b) \quad g_t = \tilde{f}(V_g x_t + W_g(h_{t-1} \cdot r_t) + b_g)$$

$$h_t = (1 - u_t) \cdot g_t + u_t \cdot h_{t-1}$$

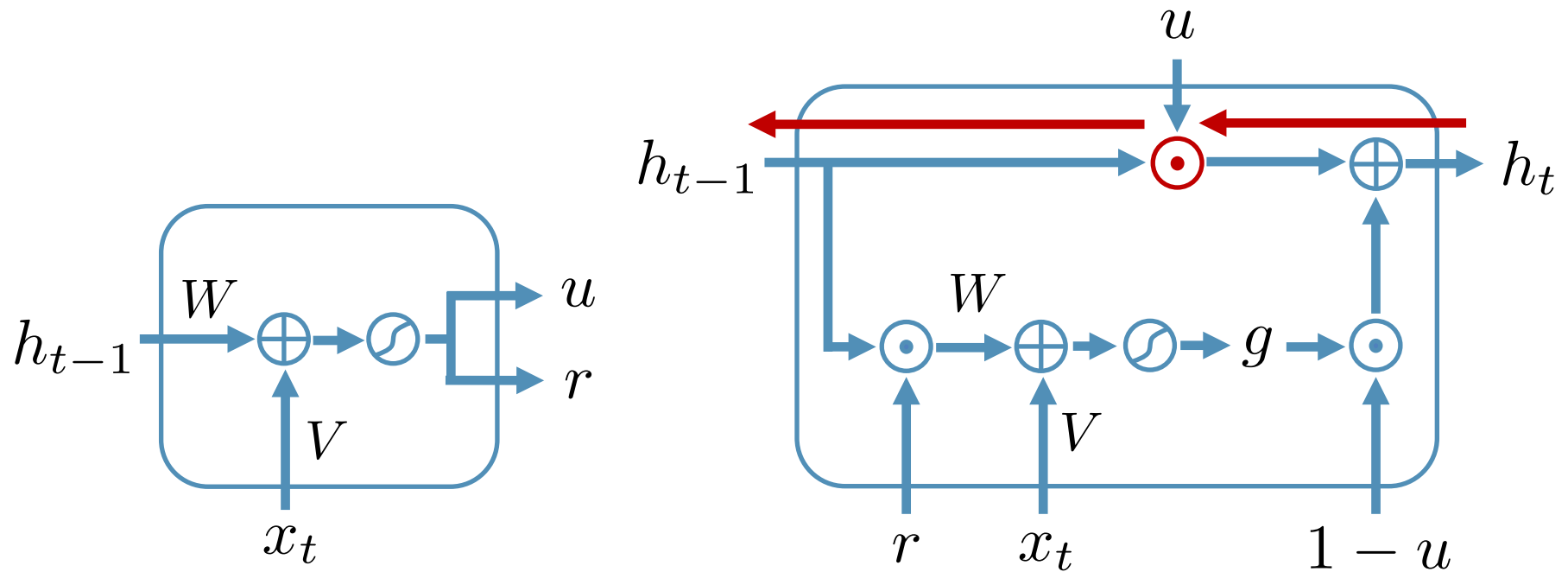
GRU: vanishing gradients



$$u_t = \sigma(V_u x_t + W_u h_{t-1} + b_u)$$

$$h_t = (1 - u_t) \cdot g_t + u_t \cdot h_{t-1}$$

GRU: vanishing gradients



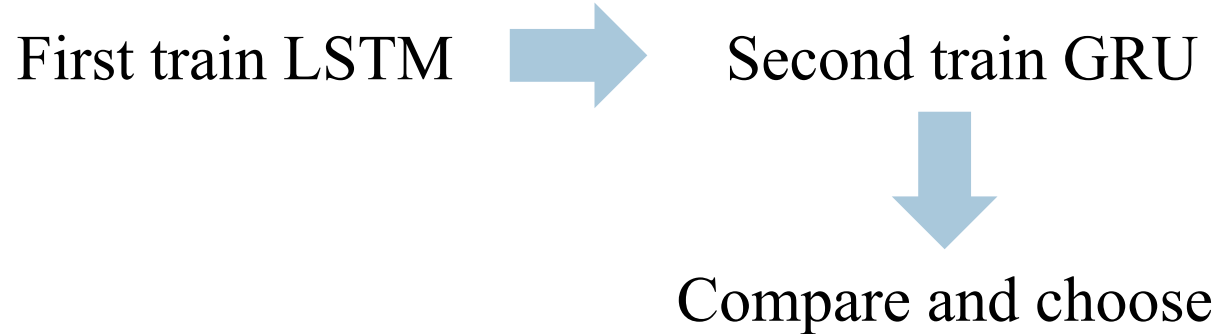
$$u_t = \sigma(V_u x_t + W_u h_{t-1} + b_u) \quad h_t = (1 - u_t) \cdot g_t + u_t \cdot h_{t-1}$$

$$\frac{\partial h_t}{\partial h_{t-1}} = \text{diag}(1 - u_h) \cdot \frac{\partial g_h}{\partial h_{h-1}} + \text{diag}(u_h) \Rightarrow \text{High initial } b_u$$

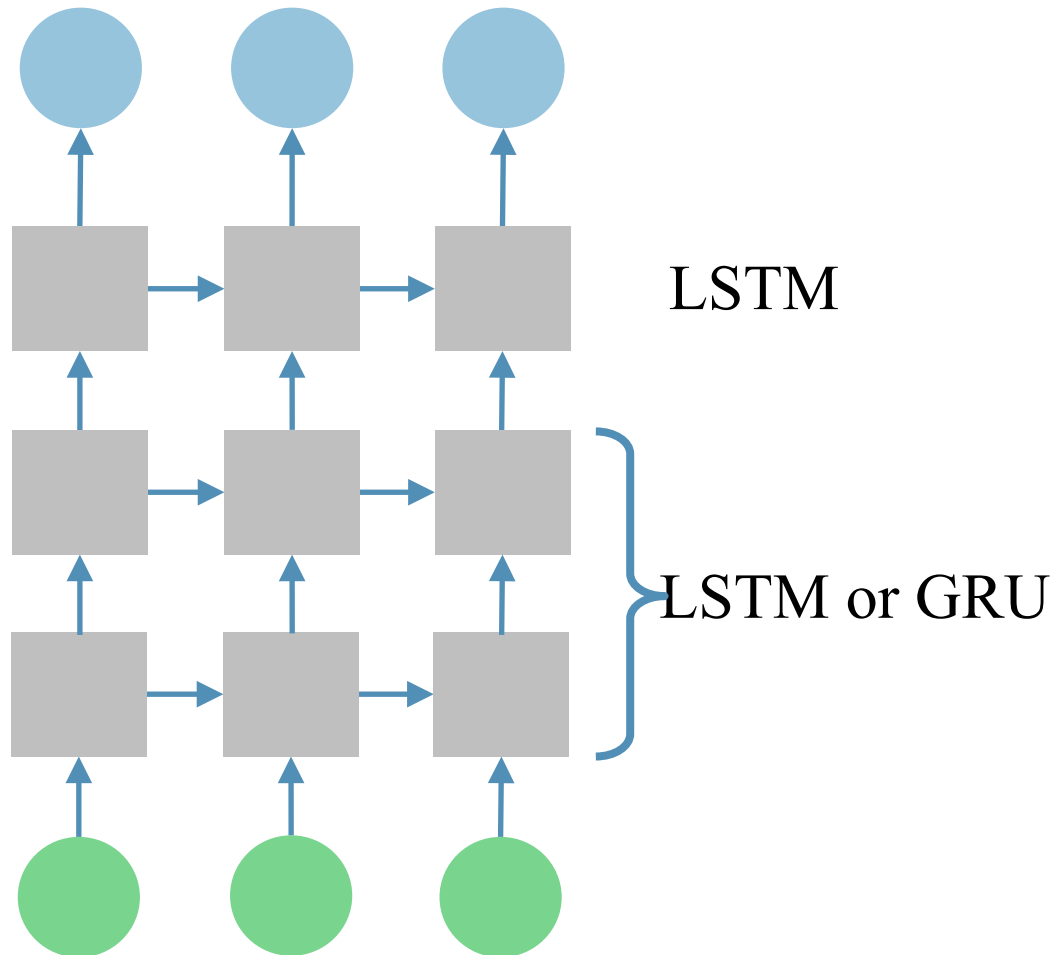
LSTM or GRU?

LSTM → more flexible

GRU → less parameters



LSTM or GRU: stack more layers



Summary

- Gated recurrent architectures: LSTM and GRU.
- They do not suffer from vanishing gradients that much because there is an additional short way for the gradients through them

In the next video:

How to use RNNs to solve different
practical tasks