# Week 12

## P1: Barriers

**A barrier** is a synchronization point at which a certain number of threads must arrive before any participating thread can continue

```
pthread_barrier_t mybarrier;

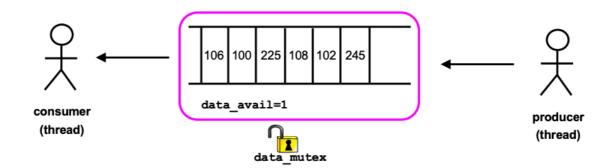
/*
    [a pointer to a barrier variable], [a pointer to barrier attributes], [number of threads]
    */
pthread_barrier_init(&mybarrier, NULL, number_of_threads);

/*
    block until specific number of threads reach this line
    */
pthread_barrier_wait(&mybarrier);

int pthread_barrier_destroy(pthread_barrier_t *barrier);
```

```
pthread_t thr[3];
 pthread_barrier_t mybarrier;
                                                                                                   1
void * tfunc (void * arg) {
                                                                                              T3 T2
   int i;
   int 1;
for (i=1; i<Max_GENERATIONS; i++) {
    // participate computing generation i from generation i-1:</pre>
                                                                                                    1
      pthread_barrier_wait(&mybarrier); // wait until all 3
                                                                                          T3 T2 T1
                                                     // threads arrive at the
// barrier.
                                                                                                    \mathbb{1}
int main() {
  int i, j;
  pthread_barrier_init(&mybarrier, NULL, 3);
  for (j=0; j<3; j++) {
    pthread_create(&thr[j], NULL, tfunc, (void *)j);
}</pre>
                                                                                          T3 T2 T1
                                                                Here we set up a
                                                                barrier for 3 threads.
                                                                                                11
  pthread_exit(NULL);// Exit the main thread.
```

## P2: Condition variables



Global variable data\_avail is used to tell the consumer that data is available.

- data\_avail = 1 means "data is available".
- data\_avail = 0 means "queue is empty".

To avoid race conditions we use mutex "data\_mutex" to synchronize access

# Why we need condition var

-- Busy waiting

## Without Condition Variables (cont.)

```
void *consumer(void *)
2
  {
      int GotItem = 0;
3
      while ( GotItem == 0 )
4
5
6
         pthread_mutex_lock(&data_mutex);
7
         if ( data avail == 1 ) {
             Fetch data item from queue();
8
9
             if ( queue is empty )
10
              data avail = 0;
             GotItem = 1;
11
12
13
         pthread mutex unlock(&data mutex);
14
15
      consume_data();
16 }
```

Note: Spinning means to circle in the loop from lines 4-14 until a data item was fetched from the queue.

- Problem: the consumer must spin until data becomes available.
  - aquire data mutex
  - check data\_avail
  - release data mutex
- Once data\_avail set to 1 by producer, consumer can extract data item from queue.
  - set GotItem=1 to exit spin loop.
- We would like a solution were the consumer <u>blocks</u> until data becomes available.
  - Better then consuming CPU cycles through busy waiting!

9

### How to use condition var

Some functions

```
/*
For waiting/sleeping, until the specific condition is signaled

The most important function !!!!!!!!

During waiting time, mutex is unlocked. When return, mutex locks again.

So, before this function, we need lock the mutex. After this, we need unlock the mutex

*/
```

```
lock(mutex)
pthread_cond_wait(condition, mutex);
// wait until some condition is sat
/*
 For waking up other threads
*/
/*
 Wake up (at least) one thread waiting on the condition variable.
 Must be called after mutex is locked, and must unlock mutex
thereafter.
*/
pthread_cond_signal(condition);
/*
  Used when multiple threads blocked at the condition.
  Wake up all threads blocked at the condition.
*/
pthread_cond_broadcast(condition);
```

#### **Producer**

- Variable data\_cond is a condition variable.
- Producer uses data\_cond to signal consumer that new
   data is available.
- Will unblock a blocking consumer.
- Has no effect if no consumer is blocking.
  - The signal is 'lost' (which is ok if nobody is waiting).

#### Consumer

```
void *consumer(void *)
{
   pthread_mutex_lock(&data_mutex);

while( data_avail == 0 ) {
     // sleep on condition variable:
     pthread_cond_wait(&data_cond, &data_mutex);
}

// woken up, execute critical section:
Extract data from queue;
if (queue is empty)
     data_avail = 0;

pthread_mutex_unlock(&data_mutex);

consume_data();
}
```

- Consumer acquires lock.
- Checks data\_avail for available data.
- If no data is available, the consumer blocks using pthread\_cond\_wait().
  - will relinquish the mutex!
  - otherwise producer could not produce!
- Once the producer signals
   data\_cond and relinquishes
   the mutex, the consumer will
   be unblocked.
  - Holds the mutex again!

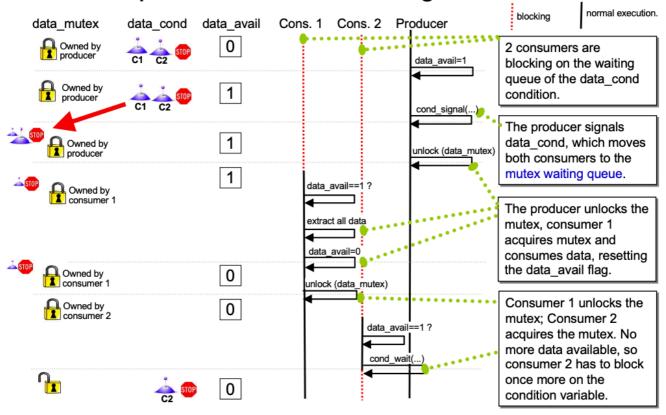
### Question: Why need while loop?

• case: many threads are waiting

```
void *consumer(void *)
{
 pthread mutex lock(&data mutex);
 while( data avail == 0 ) {
    // sleep on condition variable:
   pthread cond wait(&data cond, &data mutex);
      1. Assume T1 is waiting => data mutex unlock (why?)
          So T2 can get the data mutex and wait as well. ==> at this
stage data mutex is unlocked (Both threads block at wait, haven't
return yet)
          T1, T2 => blocking => data mutex freed
      2. Producer only enqueue 1 element, send signal. Two consumers
are put in the mutex wait queue
      3. Only 1 consumer can get the lock. Assume T1 get the
data mutex, T2 still waits, but it is waiting for data mutex to be
available.
      4. T1 Extract data from queue and unlock, it will set
data avaiable 0
      5. So T2 `wait` return and lock it again,
          but data avail == 0, so it can not break the loop
          execute pthread cond wait(&data cond, &data mutex); again,
blocking and unlock mutex
    */
  }
// woken up, execute critical section:
// Extract data from queue;
if (queue is empty)
  data avail = 0;
pthread mutex unlock(&data mutex);
```

```
consume_data();
}
```





Some Problem: Alice bob email example

# Thread pool

Most Web servers need to deal with a lot of requests in a short time. These requests need a little time to execute.

The normal way is when receiving a request, create a thread, do something, join/destroy the thread. Since the high frequency requesting, we have to spend a lot of time on creating and join threads.

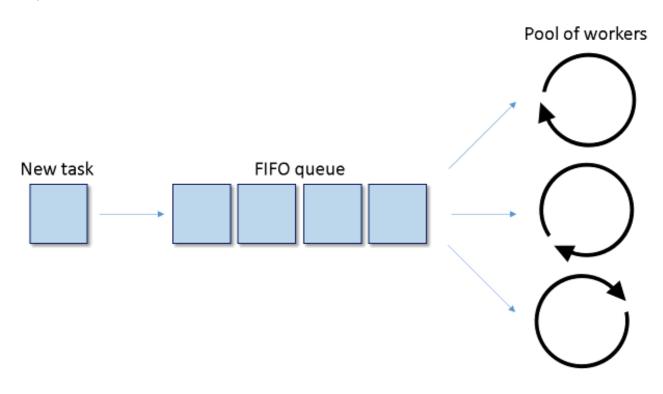
### Thread pool can fix that:

After the program start,

we create some threads and make them blocked/waiting.

When there is a request, thread pool will choose a free one to do work. After finishing,

we do not destroy that thread, however, we make it blocked again and put back to thread pool



# Strict aliasing, restrict

Two pointers are said to alias when they are used to access the same underlying region of memory.

```
int i = 0;
int *a = &i;
int *b = &i;
```

type punning is when you have two pointers of different type, both pointing at the same location

```
// BAD CODE
uint32_t data;
uint32_t* u32 = &data;
uint16_t* u16 = (uint16_t*)&data; // undefined behavior
```

However, union is fine.

"Strict aliasing is an assumption, made by the C (or C++) compiler, that dereferencing pointers to objects of different types will <u>never</u> refer to the same memory location (i.e. alias each other.)"

# **Example**

```
int foo(int *a, int *b)
{
    *a = 5;
    *b = 6;
    return *a + *b;
}

/*
    1. 11
    2. 12 => a is changed into 6
*/
```

```
foo:
    movl $5, (%rdi)  # 5 to *a
    movl $6, (%rsi)  # 6 to *b
    movl (%rdi), %eax  # reload *a, since last line may change the
value
    addl $6, %eax  # add 6
```

After restrict

```
int rfoo(int *restrict a, int *restrict b)
{
    *a = 5;
    *b = 6;
    return *a + *b;
}
```

```
foo:

movl $11, %eax  # During compliation,

movl $5, (%rdi)  # 5 to *a

movl $6, (%rsi)  # 6 to *b
```

####### Week12/Q3 #########

# **Casting and promotion**

#### Promotion

- If an integer type is used in an operation with another integer type of greater size (sizeof), the original type is promoted (casted) to the larger type
- If a signed integer type is used in an operation with an unsigned integer type, the unsigned integer type "wins" and the signed type is promoted (casted) to the unsigned type.

```
#include <stdio.h>
int main(){
  unsigned int a = 1;
  signed int b = -3;
  int c;
  (a + b > 0) ? (c = 1): (c = 0);
  printf("%d\n", c);
  // a + b => unsigned, big/small(overflow)
}
```

```
const char c = 'A';

void foo(const char** ptr)
{
    *ptr = &c; // Perfectly legal.
    // Here *ptr is const char* => legal
    // But at the same time, the ptr in main scope will pointes to c as well
}
int main()
{
    char* ptr = nullptr;
```

```
foo(&ptr); // When the function returns, ptr points to c, which is
a const object.
  *ptr = 'B'; // We have now modified c, which was meant to be a
const object.
}
```

