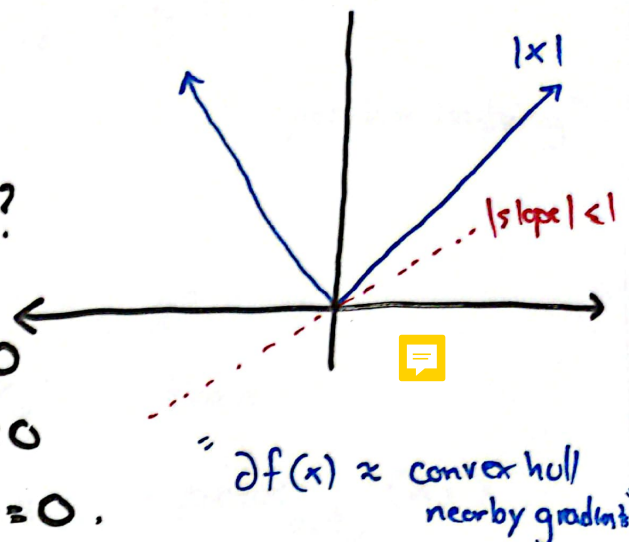


Starting 9/30

Example $f(x) = |x|$

What is $\partial f(x)$ and $\text{prox}_{\alpha f}(x)$?

$$\text{Claim: } \partial f(x) = \begin{cases} \{1\} & \text{if } x > 0 \\ \{-1\} & \text{if } x < 0 \\ [-1, 1] & \text{if } x = 0. \end{cases}$$



Proof. At $x \neq 0$, the gradient is the unique vector w w/

$$\lim_{y \rightarrow x} \frac{f(y) - f(x) + g^T(y-x)}{\|y-x\|} = 0.$$

$$\Rightarrow \partial f(x) = \{ \nabla f(x) \}.$$

At $x=0$, check! Proof by picture.

$$\text{Claim: } \text{prox}_{\alpha f}(\bar{x}) = \begin{cases} 0 & \text{if } \bar{x} \in (-\alpha, \alpha) \\ \bar{x} - \alpha & \text{if } \bar{x} \geq \alpha \\ \bar{x} + \alpha & \text{if } \bar{x} \leq -\alpha. \end{cases}$$

Proof. Let $\bar{x}^* = \text{prox}_{\alpha f}(\bar{x})$, then $\frac{1}{\alpha}(\bar{x} - \bar{x}^*) \in \partial f(\bar{x}^*)$.
 (by HW2, Q2)

$$\text{If } \bar{x}^* > 0, \frac{1}{\alpha}(\bar{x} - \bar{x}^*) = 1 \Leftrightarrow \bar{x}^* = \bar{x} - \alpha$$

(Further, $\bar{x} > \alpha$)

$$\text{If } \bar{x}^* < 0, \frac{1}{\alpha}(\bar{x} - \bar{x}^*) = -1 \Leftrightarrow \bar{x}^* = \bar{x} + \alpha$$

(Further $\bar{x} < -\alpha$)

$$\text{If } \bar{x}^* = 0, \frac{1}{\alpha}(\bar{x} - \bar{x}^*) \in [-1, 1], \Leftrightarrow \bar{x} \in \bar{x}^* + [-\alpha, \alpha] = [-\alpha, \alpha] \dots$$

(Recall LASSO, $\min \|Ax - b\|_2^2 + \gamma \|x\|_1$) ^{$= \sum |x_i|$}
 \uparrow "sparsity inducing"

Lemma (Seperable Prox Functions)

$f: \mathbb{R}^d \rightarrow \mathbb{R}$

Suppose $f(x) = \sum_{i=1}^d f_i(x_i)$, then

$$\text{prox}_{\alpha f}(\bar{x}) = \text{prox}_{\alpha f_1}(\bar{x}_1) \times \dots \times \text{prox}_{\alpha f_d}(\bar{x}_d).$$

Proof.

$$\begin{aligned} & \min_x \left\{ f(x) + \frac{1}{2\alpha} \|x - \bar{x}\|_2^2 \right\} \\ &= \min_x \left\{ \sum_{i=1}^d f_i(x_i) + \frac{1}{2\alpha} \sum_{i=1}^d (x_i - \bar{x}_i)^2 \right\} \\ &= \min_x \left\{ \sum (f_i(x_i) + \frac{1}{2\alpha} (x_i - \bar{x}_i)^2) \right\} \\ &= \sum \min_{x_i} \left\{ f_i(x_i) + \frac{1}{2\alpha} (x_i - \bar{x}_i)^2 \right\}. \end{aligned}$$

\Rightarrow Minimize separately over each x_i . \square

$$\Rightarrow \left[\text{prox}_{\alpha \|\cdot\|_1}(x) \right]_i = \begin{cases} 0 & \text{if } x_i \in [-\alpha, \alpha] \\ x_i - \alpha & \text{if } x_i > \alpha \\ x_i + \alpha & \text{if } x_i < -\alpha \end{cases}.$$

"Soft Thresholding".

Iterating the prox operation, you get
"the Proximal Point Method"

$$x_{k+1} = \text{prox}_{\alpha_k f}(x_k)$$

By HW2, Q2, $\frac{1}{\alpha_k} (x_k - x_{k+1}) \in \partial f(x_{k+1})$

$$\Leftrightarrow x_k - x_{k+1} \in \alpha_k \cdot \partial f(x_{k+1})$$

$$\Leftrightarrow x_{k+1} \in x_k - \alpha_k \partial f(x_{k+1})$$

Looks like gradient descent

(i) Gradient \rightarrow Subgradient

(ii) using 1st-order object at $k+1$
instead of k .

(for ODE background, Backward Euler Step)

Lemma Every strongly convex function f has a
unique minimizer.

Proof. HW 3

Then for convex f , $f(x) + \frac{1}{2\alpha} \|x - \bar{x}\|_2^2$ is $0 + \frac{1}{2\alpha}$ -strongly

by lemma

$\Rightarrow \text{prox}_{\alpha f}$ is well-defined and a singleton.

Abuse notation, $x_{k+1} = \text{prox}_{\alpha f}(x_k)$

2. Constraints via Proximal Operator

Suppose we want to minimize $f(x)$ over $x \in S$.

We will use the extended reals $\mathbb{R} \cup \{\pm\infty\}$ to write this as a single objective function.

Define indicator function

$$\delta_S(x) = \begin{cases} +\infty & \text{if } x \notin S \\ 0 & \text{if } x \in S. \end{cases}$$

Then we consider

$$\min_{x \in \mathbb{R}^d} f(x) + \delta_S(x) = \min_{x \in S} f(x).$$

We can handle f via gradients if it's smooth, need prox to handle δ_S .

Lemma $\text{prox}_{\alpha\delta_S}(\bar{x}) = \text{proj}_S(\bar{x})$

$$:= \arg\min \{ \|x - \bar{x}\|_2 \mid x \in S \}$$

"orthogonal projection"
moving to nearest feasible point.

Proof. $\text{prox}_{\alpha\delta_S}(\bar{x}) = \arg\min \{ \delta_S(x) + \frac{1}{2\alpha} \|x - \bar{x}\|_2^2 \}$

$$= \arg\min \{ \|x - \bar{x}\|_2^2 \mid x \in S \}.$$

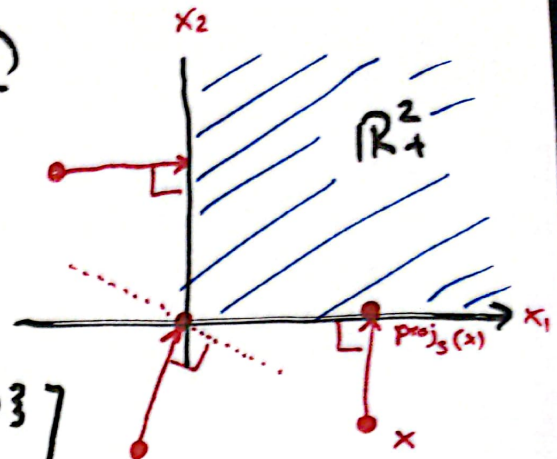
□

Example (Nonnegativity Constraints)

$$S = \{x \text{ s.t. } x_i \geq 0\} = \mathbb{R}_+^d$$

Claim: $\text{proj}_S(x) = [x]_+$

$$\hat{=} \begin{bmatrix} \max\{x_1, 0\} \\ \vdots \\ \max\{x_d, 0\} \end{bmatrix}$$



Proof. $\text{proj}_S(x) = \text{prox}_{\delta_S}(x)$

$$= \text{prox}_{\delta_{\mathbb{R}_+^d}}(x)$$

$$= \text{prox}_{\delta_{\mathbb{R}_+}}(x_1) \times \dots \times \text{prox}_{\delta_{\mathbb{R}_+}}(x_d)$$

$$\delta_{\mathbb{R}_+^d}(x) = \sum_{i=1}^d \delta_{\mathbb{R}_+}(x_i)$$

" $\begin{cases} +\infty & \text{if any } x_i < 0 \\ 0 & \text{otherwise} \end{cases}$

Check $\text{proj}_{\mathbb{R}_+}(x) = \max\{x, 0\}$. \square

Example (Grading Polyhedra)

$$S = \{(H, M, F) \mid Ax \leq b\}$$

\hookrightarrow 7 inequalities in syllabus.

$$\text{proj}_S(\bar{x}) = \underset{x \in S}{\text{argmin}} \ \|x - \bar{x}\|_2^2$$

Quadratic Programming