Proof. Suppose to the control, some
$$\|g\|_2 > M$$
, $g \in \mathcal{A}(n)$

Look at $y = x + g$,

$$f(y) \ge f(x) + g^{\top}(y - x)$$

$$= f(x) + \|g\|_2^2$$

$$> f(x) + \|g\|_2^2 > f(x)$$

2 2 de

Want 10

minif(xi)-f(x)} Weighted Average of 15x

$$\frac{||x_0 - x^*||^2 + M^2 \sum_{i=0}^{k} \alpha_i^2}{2 \sum_{i=0}^{k} \alpha_i}$$
Lemma)

$$\rightarrow$$
 0 whenever $\sum_{i=0}^{\infty} \alpha_{i}^{2} \leq C$

Finite - Time Guarantees.

Constant dx = d.

$$\Rightarrow \min_{i \leq K} \{f(x_i) - f(x_i)\} \leq \frac{\|x_0 - x_i\|^2 + M^2 \alpha^2 \cdot K}{2\alpha K}$$

$$= \frac{\|x_0 - x_i\|^2}{2\alpha K} + \frac{M^2 \alpha^2}{2} \cdot K$$

Wort LHS
$$\leq E$$
, need
$$\frac{||x_0 - x^*||^2}{||x_0 - x^*||^2} + \frac{M^2 \alpha}{||x_0 - x^*||^2} = E$$

$$\frac{M^2 ||x_0 - x^*||^2}{||x_0 - x^*||^2} = \frac{E}{2}$$
For comparison, $GD: f(x_0) - f(x_0^*) \leq f($

Accel: => K = V %

Sadly this is as good as possible.

"Theorem" there exists a bad function f; and subgradient oracle $g(x) \in \partial f(x)$ s.t.

Using |(+)| = d, after K = teps $f(x_K) - f(x^*) \ge \frac{M ||x_0 - x^*||}{Z(1 + \sqrt{K + 1})}$

Proof. Nesterov's Convex OPT book.

The subgradient method is optimal (but still slow).

Extra Directions

Speedquader Strong Convexity: O(1/K)

Nonconvex Guarantees [Devis, 2018] O(KIM)

Cadviser

Overview So For

- 1. Necessary + Sufficient Optimality Cond
- 7. First-Order Methods

Smooth OPT

(linesearchs

GD-

Accel)

Equiv Characterizations for Smooth, Conver, Strongly Comm

Proximal First-Order Methods (Mirrors smooth setting)

Nonsmooth OPT more generally

Subgradients

Subgrad Method is optimal.

W: grann

Stochastic OPT

3. Second-Order Methods

Newton

"Quasi-Netwon"