

# EN.530.663: Robot Motion Planning

## Homework 5 Solution

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problem 1.

$$X = \{0, 1, 2, 3, 4\}$$

$$\mathcal{T}_1 = \{X, \emptyset, \{0\}, \{2, 3\}, \{0, 2, 3\}, \{1, 2, 3, 4\}\}$$

①  $X$  and  $\emptyset$  belong to  $\mathcal{T}_1$  ✓.

② Union check:

$$\rightarrow X \cup \text{any other elements in } \mathcal{T}_1 = X \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow \emptyset \cup \text{any other elements in } \mathcal{T}_1 = \text{any other elements in } \mathcal{T}_1 \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow \{0\} \cup \{2, 3\} = \{0\} \cup \{0, 2, 3\} = \{0, 2, 3\} \in \mathcal{T}_1 \quad \text{✓}$$

$$\{0\} \cup \{1, 2, 3, 4\} = X \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow \{0, 2, 3\} \cup \{1, 2, 3, 4\} = X \in \mathcal{T}_1 \quad \text{✓}$$

[Passed] ✓

③ Intersection check:

$$\rightarrow \emptyset \cap \text{any other elements in } \mathcal{T}_1 = \emptyset \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow X \cap \text{any other elements in } \mathcal{T}_1 = \text{any other elements in } \mathcal{T}_1 \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow \{0\} \cap \{2, 3\} = \emptyset \in \mathcal{T}_1 \quad \text{✓}. \quad \{0\} \cap \{0, 2, 3\} = \{0\} \quad \text{✓}.$$

$$\{0\} \cap \{1, 2, 3, 4\} = \emptyset \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow \{2, 3\} \cap \{0, 2, 3\} = \{2, 3\} \cap \{1, 2, 3, 4\} = \{2, 3\} \in \mathcal{T}_1 \quad \text{✓}$$

$$\rightarrow \{0, 2, 3\} \cap \{1, 2, 3, 4\} = \{2, 3\} \in \mathcal{T}_1 \quad \text{✓}$$

[Passed] ✓

∴  $\mathcal{T}_1$  is a topology.

$$\mathcal{T}_2 = \{X, \emptyset, \{0\}, \{2, 3\}, \{0, 2, 3\}, \{1, 2, 3\}\}$$

①  $X$  and  $\emptyset$  belong to  $\mathcal{T}_2$  ✓.

② Union check:

$\rightarrow X$  and  $\emptyset$  follow the same results as in  $\mathcal{T}_1$  ✓.

$\rightarrow \{0\} \cup \{1, 2, 3\} = \{0, 1, 2, 3\} \notin \mathcal{T}_2$  ✗ counter-example.

Therefore  $\mathcal{T}_2$  is not a topology.

$$\mathcal{T}_3 = \{X, \emptyset, \{0\}, \{2, 3\}, \{0, 2, 3\}, \{0, 1, 3, 4\}\}$$

$\emptyset$  and  $X$  belong to  $\mathcal{T}_3$ .

② Union check:

$\rightarrow X$  and  $\emptyset$  follow the same results as in  $\mathcal{T}_1$ .

$$\rightarrow \{0\} \cup \{2, 3\} = \{0\} \cup \{0, 2, 3\} = \{0, 2, 3\} \in \mathcal{T}_3.$$

$$\{0\} \cup \{0, 1, 3, 4\} = \{0, 1, 3, 4\}$$

$$\rightarrow \{2, 3\} \cup \{0, 2, 3\} = \{0, 2, 3\} \in \mathcal{T}_3.$$

$$\{2, 3\} \cup \{0, 1, 3, 4\} = \{0, 1, 2, 3, 4\}$$

$$\rightarrow \{0, 2, 3\} \cup \{0, 1, 3, 4\} = \{0, 1, 2, 3, 4\}$$

③ Intersection check:

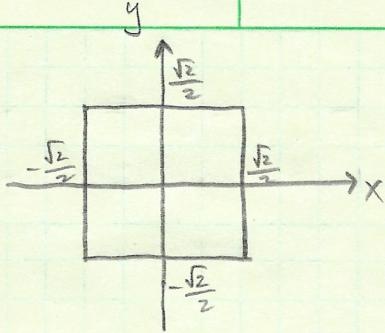
$\rightarrow \emptyset$  and  $X$  follow the same results as in  $\mathcal{T}_1$ .

$$\rightarrow \{2, 3\} \cap \{0, 1, 3, 4\} = \{3\} \notin \mathcal{T}_3 \text{ counter-example}$$

$\therefore \mathcal{T}_3$  is not a topology.

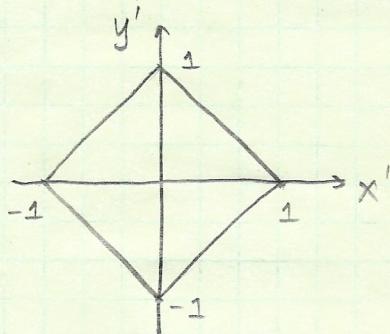
problem 2.

a)  $T$ :



Homeomorphic transform  $T$   
by rotating  $45^\circ$  ccw.

$T'$ :



$$f: \begin{bmatrix} y' \\ x' \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

where  $\theta = 45^\circ$ .

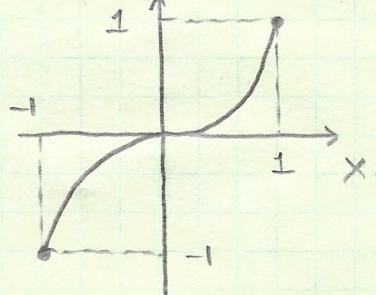
it's bijective and continuous.

$T'$  can be represented by line functions also:

$$T' = \{(x, y) \in \mathbb{R}^2 \mid |x| + |y| = 1\}$$

$$\text{also, } S^1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1\}$$

Define a function:  $f: [-1, 1] \mapsto [-1, 1]$ :  $\begin{cases} x = \text{sign}(x)|x|^2 \\ y = \text{sign}(y)|y|^2 \end{cases}$



$$\text{where } \text{sign}(a) = \begin{cases} 1, & a > 0 \\ 0, & a = 0 \\ -1, & a < 0 \end{cases}$$

it's continuous and bijective.

$\therefore f^{-1}$  exists.

Therefore,  $S^1$  and  $T'$  are homeomorphic to each other, or equivalently  $S^1$  and  $T$  are also homeomorphic to each other.

$$b) A = \{(x,y) \in \mathbb{R}^2 \mid 1 \leq 4x^2 + y^2 \leq 4\}$$

$$B = \{(x,y) \in \mathbb{R}^3 \mid x^2 + y^2 = 1, 0 \leq z \leq 1\}$$

Homeomorphic transform of A first.

$$A' = \{(\theta, \rho) \in \mathbb{R}^2 \mid 0 < \theta \leq 2\pi, 1 \leq \rho \leq 2\} \quad \textcircled{1}$$

$$f_1 = \begin{cases} x = (\rho \cdot \cos \theta)/2 \\ y = \rho \cdot \sin \theta \end{cases} \quad \text{it's bijective and continuous.}$$

∴ A' and A are equivalent.

Homeomorphic transform of B:

$$B' = \{(\theta, z) \in \mathbb{R}^2 \mid 0 \leq \theta \leq 2\pi, 0 < z \leq 1\} \quad \textcircled{2}$$

$$f_2 = \begin{cases} x = \cos \theta \\ y = \sin \theta \end{cases} \quad \text{it's bijective and continuous.}$$

∴ B' and B are equivalent.

Show \textcircled{1} & \textcircled{2} are homeomorphic:

$$f_3: \begin{aligned} \theta &\mapsto \theta : \theta = \theta \\ \rho &\mapsto z : \rho = z+1 \end{aligned}$$

it's bijective and continuous.

Therefore, A and B are homeomorphic to each other.

problem 3.

a) Check if  $f$  is bijective:

Define  $\begin{cases} x_1' = e^{x_1} & \text{where } x_1 \in \mathbb{R}, x_1' \in (0, \infty) \\ x_2' = 3x_2 + 1 & \text{where } x_2 \in \mathbb{R}, x_2' \in \mathbb{R} \end{cases}$

$\hookrightarrow \begin{cases} x_1 = \ln(x_1') \\ x_2 = (x_2' - 1)/3 \end{cases}$  is  $f^{-1}$  with domain  $\begin{cases} x_1' \in (0, \infty) \\ x_2' \in \mathbb{R} \end{cases}$  codomain  $\begin{cases} x_1 \in \mathbb{R} \\ x_2 \in \mathbb{R} \end{cases}$ .

so  $f$  is surjective.

Check injective?

If  $\exists (a, b) \neq (a', b')$  s.t.  $f(a', b') = f(a, b)$ , then it's not injective

$\hookrightarrow$  Let  $\begin{cases} e^a = e^{a'} \\ 3b + 1 = 3b' + 1 \end{cases} \Leftrightarrow \begin{cases} a = a' \\ b = b' \end{cases}$  ↑ this does not hold

**note that in the current definition  $f: \mathbb{R} \rightarrow \mathbb{R}$ ,  $f$  is not bijective.  
But once you change the domain from  $\mathbb{R}$  to  $\mathbb{R} \geq 0$ , then  $f$  is bijective.**

Check if  $f$  is  $C^\infty$  differentiable:

$$\text{1st: } \frac{\partial f_1}{\partial x_1} = e^{x_1}; \frac{\partial f_1}{\partial x_2} = 0; \quad \frac{\partial f_2}{\partial x_1} = 0; \quad \frac{\partial f_2}{\partial x_2} = 3.$$

$$\text{2nd: } \frac{\partial^2 f_1}{\partial x_1^2} = e^{x_1}; \frac{\partial^2 f_1}{\partial x_2^2} = 0; \quad \frac{\partial^2 f_2}{\partial x_1^2} = 0; \quad \frac{\partial^2 f_2}{\partial x_2^2} = 0.$$

$$\frac{\partial^2 f_1}{\partial x_1 \partial x_2} = 0; \quad \frac{\partial^2 f_2}{\partial x_1 \partial x_2} = 0.$$

⋮

$$\therefore \frac{\partial^{n+m} f_1}{\partial x_1^n \partial x_2^m} = \begin{cases} e^{x_1}, & m=0 \\ 0, & m \neq 0 \end{cases} \quad \frac{\partial^{n+m} f_2}{\partial x_1^n \partial x_2^m} = \begin{cases} 3, & m=1 \\ 0, & m \neq 1 \end{cases}$$

where  $m, n$  are non-negative integers.

| From above, we see  $f$  is  $C^\infty$  differentiable. |

Check if  $f$  is diffeomorphism with Inverse Function Theorem.

$$\forall (x_1, x_2) \in \mathbb{R}^2, J = \begin{bmatrix} e^{x_1} & 0 \\ 0 & 3 \end{bmatrix}$$

$$\det(J) = 3e^{x_1} > 0 \quad \forall x_1 \in \mathbb{R}$$

According to inverse function theorem,  $f$  is a diffeomorphism.  
again, if you use the different codomain of  $f$ .

$$b). f: (0, \infty) \times (0, 2\pi) \rightarrow \mathbb{R}^2 \setminus \{(x, 0) | x \geq 0\} = (r, \theta) \mapsto (x, y)$$

Find the mapping first:

$\mathbb{R}^2 \setminus \{(x, 0) | x \geq 0\}$  is visualized as:

re-represent as:

$$\{(r, \theta) | r > 0, 0 < \theta < 2\pi\}$$

$$f: \begin{cases} x = r \cdot \cos \theta \\ y = r \cdot \sin \theta \end{cases}$$

$$f^{-1}: \begin{cases} r = \sqrt{x^2 + y^2} \\ \theta = \operatorname{atanz}(y, x) \end{cases}$$

$\hookrightarrow$  it's surjective.

check injective?

Let  $(r', \theta') \in (0, \infty), (0, 2\pi)$

$$\hookrightarrow \text{set } \begin{cases} r \cdot \cos \theta = r' \cos \theta' \\ r \cdot \sin \theta = r' \sin \theta' \end{cases} \Leftrightarrow \begin{cases} \theta = \theta' \text{ due to atan2 property.} \\ r = r' \end{cases}$$

$\hookrightarrow$  it's injective.

$\therefore [f \text{ is bijective}]$

Check  $f$  is  $C^\infty$  differentiable,

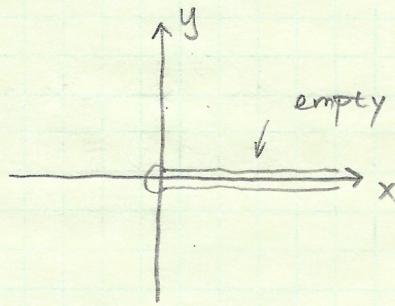
$$\text{1st: } \frac{\partial f_1}{\partial r} = \cos \theta, \quad \frac{\partial f_1}{\partial \theta} = -r \sin \theta, \quad \frac{\partial f_2}{\partial r} = \sin \theta, \quad \frac{\partial f_2}{\partial \theta} = r \cos \theta.$$

$$\begin{array}{lll} \text{2nd: } \frac{\partial^2 f_1}{\partial r^2} = 0, & \frac{\partial^2 f_1}{\partial \theta^2} = -r \cos \theta, & \frac{\partial^2 f_2}{\partial r^2} = 0, \quad \frac{\partial^2 f_2}{\partial \theta^2} = r \sin \theta. \\ \frac{\partial^2 f_1}{\partial r \partial \theta} = -\sin \theta, & & \frac{\partial^2 f_1}{\partial \theta \partial r} = \cos \theta. \end{array}$$

$\boxed{\text{From above, we can see } f \text{ is } C^\infty \text{ differentiable.}}$

$$J = \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \quad \begin{array}{l} r \in (0, \infty) \\ \theta \in (0, 2\pi) \end{array} \quad \det(J) = r \in (0, \infty) \neq 0$$

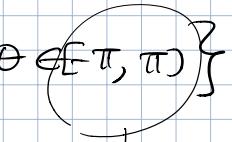
$\boxed{\text{Therefore, } f \text{ is a diffomorphism according to Inverse Function Thm}}$



Problem 4

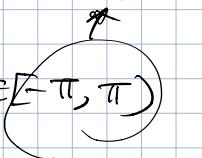
$$(a) D = \{ (r, \theta) \in \underbrace{\mathbb{R}_{\geq 0} \times [0, 2\pi] \setminus \{(0, 0)\}}_{\text{It can be } \mathbb{R}_{\geq 0} \times S^1} \mid r \in (1, 2), \theta \in [-\pi, \pi) \}$$

It can be  
 $\mathbb{R}_{\geq 0} \times S^1$



It can be  
 $[0, 2\pi), \dots$

$$(b) f(r, \theta) = \begin{pmatrix} r \cos \theta \\ r \sin \theta \end{pmatrix}, \quad r \in (1, 2), \theta \in [-\pi, \pi)$$



(c) Let

$$\gamma(t) = \begin{cases} (r_1 \cos \theta_1, r_1 \sin \theta_1)^T, & 0 \leq t \leq 1/2 \\ (r_2 t \cos \theta_2, r_2 t \sin \theta_2)^T, & 1/2 < t \leq 1 \end{cases}$$

$$\text{with } \theta(t) = \theta_1 + 2(\theta_2 - \theta_1)t$$

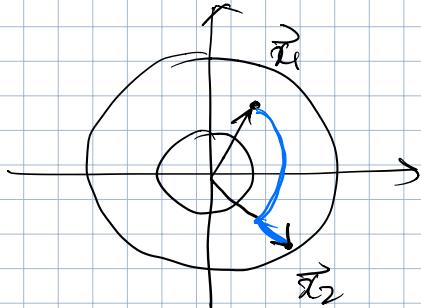
$$r(t) = r_1 + 2(r_2 - r_1)(t - \frac{1}{2})$$

$$\text{and } \vec{x}_1 = \begin{pmatrix} r_1 \cos \theta_1 \\ r_1 \sin \theta_1 \end{pmatrix}, \quad \vec{x}_2 = \begin{pmatrix} r_2 \cos \theta_2 \\ r_2 \sin \theta_2 \end{pmatrix}$$

$\forall \vec{x}_1, \vec{x}_2 \in S$

$\gamma(t)$  exists such that  $\gamma(0) = \vec{x}_1$  and  $\gamma(1) = \vec{x}_2$

$\Rightarrow$  path-connected!



### Problem 5

(a)  $\phi_1(x, y) = (x, y)$

$$\phi_2(x, y) = (\sqrt{x^2 + y^2}, \operatorname{atan} 2(y, x))$$

(b)  $\phi_1(U_1 \cap U_2) = \mathbb{R}^2 \setminus \{(x, 0) \mid x \leq 0\}$

$$\phi_2(U_1 \cap U_2) = \{(r, \theta) \mid r > 0, \theta \in (-\pi, \pi)\}$$

$$\phi_2(r, \theta) = (r \cos \theta, r \sin \theta)$$

(c)  $\phi_2(x, y) = (\phi_2 \circ \phi_1^{-1})(x, y) \text{ in } U_1 \cap U_2$

$$= (\sqrt{x^2 + y^2}, \operatorname{atan} 2(y, x))$$

$$\underline{J} = \begin{pmatrix} \frac{x}{\sqrt{x^2 + y^2}} & \frac{y}{\sqrt{x^2 + y^2}} \\ -\frac{y}{x^2 + y^2} & \frac{x}{x^2 + y^2} \end{pmatrix}$$

$$\det(\underline{J}) = \frac{1}{\sqrt{x^2 + y^2}}$$

Since  $(x, y) \in U_1 \cap U_2 \rightarrow (0, 0) \notin U_1 \cap U_2$

$$\therefore \det(\underline{J}) \neq 0$$

$\therefore$  locally diffeomorphism, Since  $\phi_{12}(x, y)$   
is bijective, it is globally diffeomorphism