

## 5 1D seismic wave propagation

Until now, we dealt with equations that had a first order time derivative (e.g., the diffusion equation) which are called *parabolic equations* or which had no time derivative at all (e.g., steady-state thermal diffusion) called *elliptic equations*. Yet, a third type of partial differential equations exist that have a second order time derivative. These types of equations are called *hyperbolic equations*. In geophysics, the most common equation is the wave equation which governs how seismic waves propagate through an elastic Earth.

In 1-D the governing equation is

$$\rho \frac{\partial^2 u}{\partial t^2} = \frac{\partial}{\partial x} (\sigma) \quad (1)$$

where  $u$  is the elastic displacement [m],  $\rho$  rock density (between 2500-3300 kg/m<sup>3</sup>) and  $\sigma$  is stress.

In a linear elastic body, stress depends on strain as follows

$$\sigma = E \frac{\partial u}{\partial x} \quad (2)$$

where  $E$  is the Young's module (typical values are between 10<sup>10</sup> – 10<sup>11</sup> Pa).

Equations (1) and (2) can be solved for  $u$ , with a usual finite difference discretization. One of the nice things of solving elastic wave equations is that it can often be done with explicit methods, which makes the code efficient.

Equation 2 is discretized in a staggered manner as:

$$\sigma_{i+1/2}^n = E \frac{u_{i+1}^n - u_i^n}{\Delta x} \quad (3)$$

And equation 1 in a discretized manner is:

$$\rho \frac{u_i^{n+1} - 2u_i^n + u_i^{n-1}}{(\Delta t)^2} = \frac{\sigma_{i+1/2}^n - \sigma_{i-1/2}^n}{\Delta x} \quad (4)$$

where  $i$  indicates spatial discretization and  $n$  the temporal discretization.

In order to solve for  $u_i^{n+1}$ , we thus need to know both  $u_i^n$  and  $u_i^{n-1}$  (so the displacement of the current timestep and that of the timestep before). That sounds more difficult than it is in practice, as during the first timestep we simply set  $u^{n-1}$  to zero everywhere.

The way wave propagation codes are often written is by (1) defining a displacement field, (2) computing stresses from that displacement field using eq. (3) and (3) computing a new displacement field from equation (4).

### 5.1 Exercises

1. Write a 1D code that solves the wave equation in the upper 100 km of the Earth, using a timestep of 0.1 seconds, a Young's module of 5e10 Pa and a rock density of 3000 kg/m<sup>3</sup>. To initiate the wave, apply the following function in the middle of the domain for 5 seconds:  $u = 10^{-3} \sin(t\pi/5)^2$ , where  $t$  is time. The lower boundary condition is motion-free ( $u(-L) = 0$ ), whereas the upper boundary is stress free ( $\sigma(0) = 0$ ). If you do things correctly, the code should be less than a single page including plotting and you should see a wave that propagates and is deflected.
2. Compute a synthetic seismogram at the surface of your model, which records the vertical displacement there as a function of time.
3. Measure the velocity of the propagating wave. How does this velocity change if we change  $E$  and  $\rho$ ?
4. Implement a layer with a different Young's module and density at the bottom of the model. What changes?