# Jiahui Zhang

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### Education

#### **University of Southern California**

Los Angeles, US

Master of Science

Jan 2020 - Dec 2021

Ming Hsieh Department of Electrical and Computer Engineering

#### **Beijing University of Technology**

Beijing, China

Bachelor of Engineering

Sept 2015 - Jul 2019

Fan Gongxiu Honors College

### **Publication**

- 1. Jesse Zhang, Karl Pertsch, **Jiahui Zhang**, Taewook Nam, Sung Ju Hwang, Xiang Ren, and Joseph J Lim. SPRINT: Scalable semantic policy pre-training via language instruction relabeling. In *Submitted to The Eleventh International Conference on Learning Representations (ICLR)*, 2023. under review
- 2. Xiaoqing Zhu, Dengyu Ran, Chentong Xiang, **Jiahui Zhang**, Ge Li, Zhicheng Chen, and Yuwen Fang. Design, analysis and experiments of bionic hexapod robot with multilayer c-shape legs for unstructured terrain. In 2018 13th World Congress on Intelligent Control and Automation (WCICA), pages 438–443, 2018

# **Research Experience**

#### **Cognitive Learning for Vision and Robotics Lab**

Los Angeles, US

Advisor: Prof. Joseph J. Lim

Aug 2021 - Current

- Working on Language-guided offline reinforcement pre-training for long-horizon skills.
- · Proposed a new composition behavior learning paradigm by generating language-conditioned priors to guide the agent policy.
- Built an interface to enable humans to collect Minecraft demonstrations.

#### **USC Media Communications Lab**

Los Angeles, US

Advisor: Prof. C.-C. Jay Kuo

Jan 2021 - May 2021

- · Applied image multi-layer spectrum decomposition for image denoising by coarse-to-fine layer-wise batch filtering in each spectrum range.
- · Achieved comparable performance with state-of-art deep learning methods with minimum computation resources.

### Fan Gongxiu Honors College Capstone Project

Beijing, China

Advisor: Prof. Luheng Jia

Jul 2018 - May 2019

- · Built a video rate controller by detecting inter-frame salient regions via motion cues and intra-frame salient regions via visual cues.
- Using detected saliency to control the quantization parameters of HEVC encoder.

## Beijing University of Technology Artificial Intelligence and Robotics Research Center

Beijing, China

Advisor: Prof. Xiaoqing Zhu

Dec 2016 - Mar 2018

- $\bullet \ \ \text{Design, assembly, control a bionic hexapod real robot to adapt to different terrains.}$
- Work accepted at World Congress on Intelligent Control and Automation (WCICA).

# **Course Project**

#### **Policy Adaption on Human Language Generated Environment**

Los Angeles, US

Advisor: Prof. Stefanos Nikolaidis

Feb 2021 - May 2021

- Enabled a well-trained policy to adapt to any human language-described environment.
- Narrow the gap between the training environment and human described environment.
- Our method required fewer environment steps than training from scratch to solve tasks in the new environment.

#### **Super Resolution GAN**

Advisor: Dr. Jiali Duan

Los Angeles, US Mar 2020 - May 2020

• We formulated super resolution for image generation via GAN network.

- We purposed a novel loss function to improve image perceptual quality.
- Our method preserved the image texture, reducing MSE loss on average by 20+ compared with the SRCNN baseline on the BSD100 dataset.

# Award and Scholarship

Principle's scholarship, Beijing University of Technology

Beijing, China

2017 **Outstanding Research Achievement Award**, Beijing University of Technology, Fan Gongxiu Honors College

Beijing, China