

Q1.1

$$\frac{\partial l}{\partial u_i} = \frac{\partial l}{\partial h_i} \frac{\partial h_i}{\partial u_i}$$

So

$$\begin{aligned} \frac{\partial l}{\partial \mathbf{u}} &= \frac{\partial l}{\partial \mathbf{h}} \cdot * \frac{\partial \mathbf{h}}{\partial \mathbf{u}} \\ &= \frac{\partial l}{\partial \mathbf{a}} * \frac{\partial \mathbf{a}}{\partial \mathbf{u}} \cdot * \mathbf{H}(\mathbf{u})^T \\ &= \frac{\partial l}{\partial \mathbf{a}} * \frac{\partial(\mathbf{W}^{(2)}\mathbf{h} + \mathbf{b}^{(2)})}{\partial \mathbf{h}} \cdot * \mathbf{H}(\mathbf{u})^T \\ &= \frac{\partial l}{\partial \mathbf{a}} * \mathbf{W}^{(2)} \cdot * \mathbf{H}(\mathbf{u})^T \end{aligned}$$

$$\begin{aligned} \frac{\partial l}{\partial a_i} &= \frac{\partial l}{\partial z_i} * \frac{\partial z_i}{\partial a_i} \\ &= -(y_i == k) * \frac{1}{z_i} * (z_i * (1 - z_i)) \\ &= -(y_i == k) * (1 - z_i) \\ \frac{\partial l}{\partial \mathbf{a}} &= \mathbf{y}^T \mathbf{z} - \mathbf{y}^T \end{aligned}$$

$$\frac{\partial l}{w_{ji}^{(1)}} = \frac{\partial l}{\partial u_j} \frac{\partial u_j}{\partial w_{ji}^{(1)}} = \frac{\partial l}{\partial u_j} * x_i$$

$$\frac{\partial l}{\partial \mathbf{W}^{(1)}} = \left( \frac{\partial l}{\partial \mathbf{u}} \right)^T * \mathbf{x}^T$$

$$\frac{\partial l}{\partial \mathbf{b}^{(1)}} = \frac{\partial l}{\partial \mathbf{u}} \frac{\partial \mathbf{u}}{\partial \mathbf{b}} = \frac{\partial l}{\partial \mathbf{u}}$$

$$\frac{\partial l}{w_{ji}^{(2)}} = \frac{\partial l}{\partial a_j} \frac{\partial a_j}{\partial w_{ji}^{(2)}} = \frac{\partial l}{\partial u_j} * h_i$$

$$\frac{\partial l}{\partial \mathbf{W}^{(2)}} = \left(\frac{\partial l}{\partial \mathbf{a}}\right)^T * \mathbf{h}^T$$

Q1.2 Because  $\mathbf{W}^{(1)}, \mathbf{W}^{(2)}, \mathbf{b}^{(1)}$  are all initialed to zero and from the above derivation, the gradient  $\frac{\partial l}{\partial \mathbf{W}^{(1)}}, \frac{\partial l}{\partial \mathbf{W}^{(2)}}, \frac{\partial l}{\partial \mathbf{b}^{(1)}}$  are all 0.

Q 1.3

$$\begin{aligned}\mathbf{a} &= \mathbf{W}^{(2)}\mathbf{u} + \mathbf{b}^{(2)} \\ &= \mathbf{W}^{(2)}(\mathbf{W}^{(1)}\mathbf{x} + \mathbf{b}^{(1)}) + \mathbf{b}^{(2)} \\ &= \mathbf{W}^{(2)}\mathbf{W}^{(1)}\mathbf{x} + \mathbf{W}^{(2)}\mathbf{b}^{(1)} + \mathbf{b}^{(2)} \\ \mathbf{U} &= \mathbf{W}^{(2)}\mathbf{W}^{(1)} \\ \mathbf{v} &= \mathbf{W}^{(2)}\mathbf{b}^{(1)} + \mathbf{b}^{(2)}\end{aligned}$$

Q2.1

$$\begin{aligned}\frac{\partial l}{\partial \mathbf{w}} &= \sum_n \frac{\partial l(s, y_n)}{\partial s} \frac{\partial s}{\partial \mathbf{w}} + \lambda \mathbf{w} \\ \sum_n \frac{\partial l(s, y_n)}{\partial s} \phi(\mathbf{x}_n) + \lambda \mathbf{w}^* &= 0 \\ \mathbf{w}^* &= -\frac{\sum_n \frac{\partial l(s, y_n)}{\partial s} \phi(\mathbf{x}_n)}{\lambda}\end{aligned}$$

Q2.2

$$\begin{aligned}\mathbf{w}^* &= \Phi^T \boldsymbol{\alpha} \\ \sum_n l(\mathbf{w}^T \phi(\mathbf{x}_n), y_n) + \frac{\lambda}{2} \|\mathbf{w}\|_2^2 \\ &= \sum_n l(\boldsymbol{\alpha}^T \Phi(\mathbf{x}) \phi(\mathbf{x}_n), y_n) + \frac{\lambda}{2} \|\mathbf{w}\|_2^2 \\ &= \sum_n l(\boldsymbol{\alpha}^T [K_{1n}, K_{2n}, \dots, K_{nn}]^T, y_n) + \frac{\lambda}{2} \|\mathbf{w}\|_2^2\end{aligned}$$