

Homework

Determine the acceleration^a of the 150-lb^G cabinet and the normal reaction under the legs *A* and *B* if $P = 35$ lb. The coefficients of static and kinetic friction between the cabinet and the plane are $\mu_s = 0.2$ and $\mu_k = 0.15$, respectively. The cabinet's center of gravity is located at *G*.

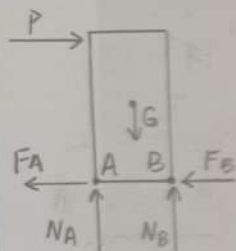
解:

$$(F_A + F_B)_{\text{static}} = G \cdot \mu_s = 30 \text{ lb} < P = 35 \text{ lb}$$

the cabinet will move.

$$(F_A + F_B)_k = G \cdot \mu_k < P, \text{ it will accelerate.}$$

FBD



$$\rightarrow \Sigma F_x = P - F_A - F_B = m a_{Gx}$$

$$\uparrow \Sigma F_y = N_A + N_B - G = 0$$

$$\curvearrowright \Sigma M_A = -P \cdot d_1 - G \cdot d_2 + N_B \cdot d_3 = -m a_{Gx} d_4$$

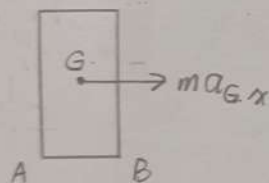
$$N_A \cdot \mu_k = F_A, N_B \cdot \mu_k = F_B$$

$$\Rightarrow N_A = 26.875 \text{ lb} \quad \boxed{\text{ANS}}$$

$$N_B = 123.125 \text{ lb}$$

$$a_{Gx} = 2.6828 \text{ ft/s}^2 \quad \boxed{\text{ANS}}$$

KD



$$d_1 = 4 \text{ ft}$$

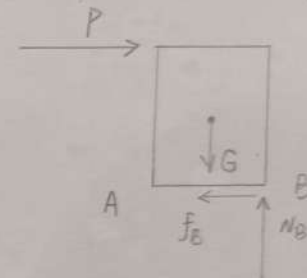
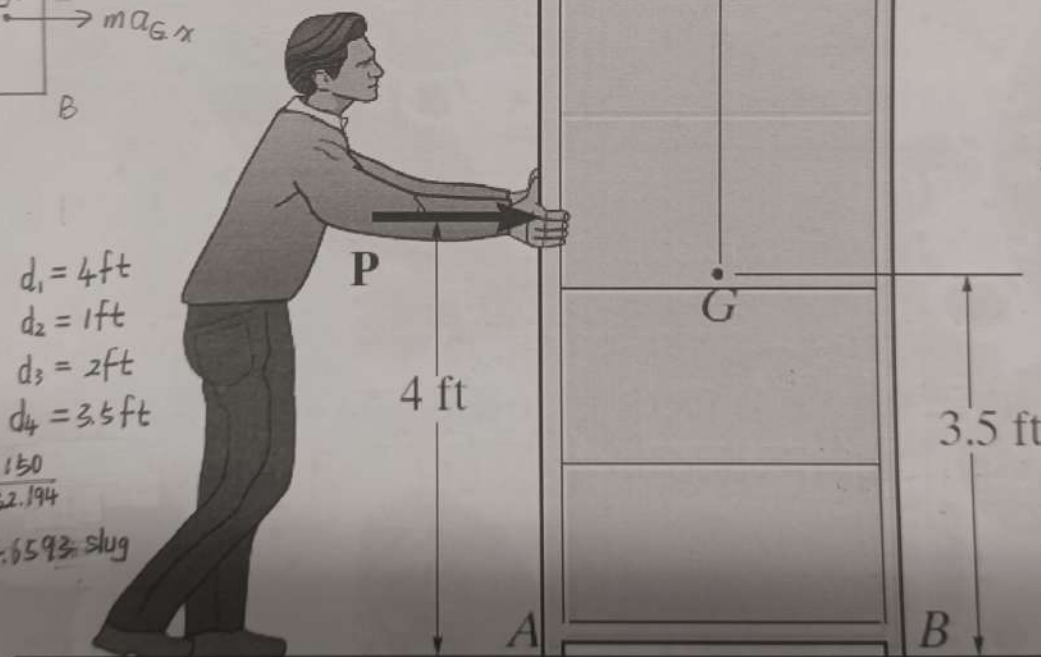
$$d_2 = 1 \text{ ft}$$

$$d_3 = 2 \text{ ft}$$

$$d_4 = 3.5 \text{ ft}$$

$$m = \frac{150}{32.174}$$

$$= 4.6593 \text{ slug}$$



$$N_B = 150 \text{ lb}$$

$$\curvearrowright \Sigma M_B = +G \cdot d_1 - P \cdot d_2 = 150 \times 1 - 35 \times 4 = 10 \neq 0$$

会发生倾翻

∴ A点不可能悬空

FBD 如左图所示

Homework

Motor M exerts a constant force of $P = 750 \text{ N}$ on the rope. If the 100-kg post is at rest when $\theta = 0^\circ$, determine the angular velocity of the post at the instant $\theta = 60^\circ$. Neglect the mass of the pulley and its size and consider the post as a slender rod.

解:

At $\theta = 0^\circ$, post rest

$$T_1 = 0$$

At $\theta = 60^\circ$,

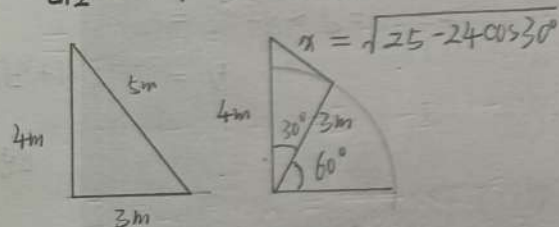
$$T_2 = \frac{1}{2} m v_G^2 + \frac{1}{2} I_G \omega^2 = I_B \omega^2 \cdot \frac{1}{2}$$

$$I_B = I_G + m \left(\frac{L_{AB}}{2} \right)^2 = 300 \text{ kg} \cdot \text{m}^2$$

$$I_G = \frac{1}{12} m L_{AB}^2 = 75 \text{ kg} \cdot \text{m}^2$$

From $\theta = 0^\circ$ to $\theta = 60^\circ$:

$$U_{1-2} = + P \cdot s - G \cdot h$$

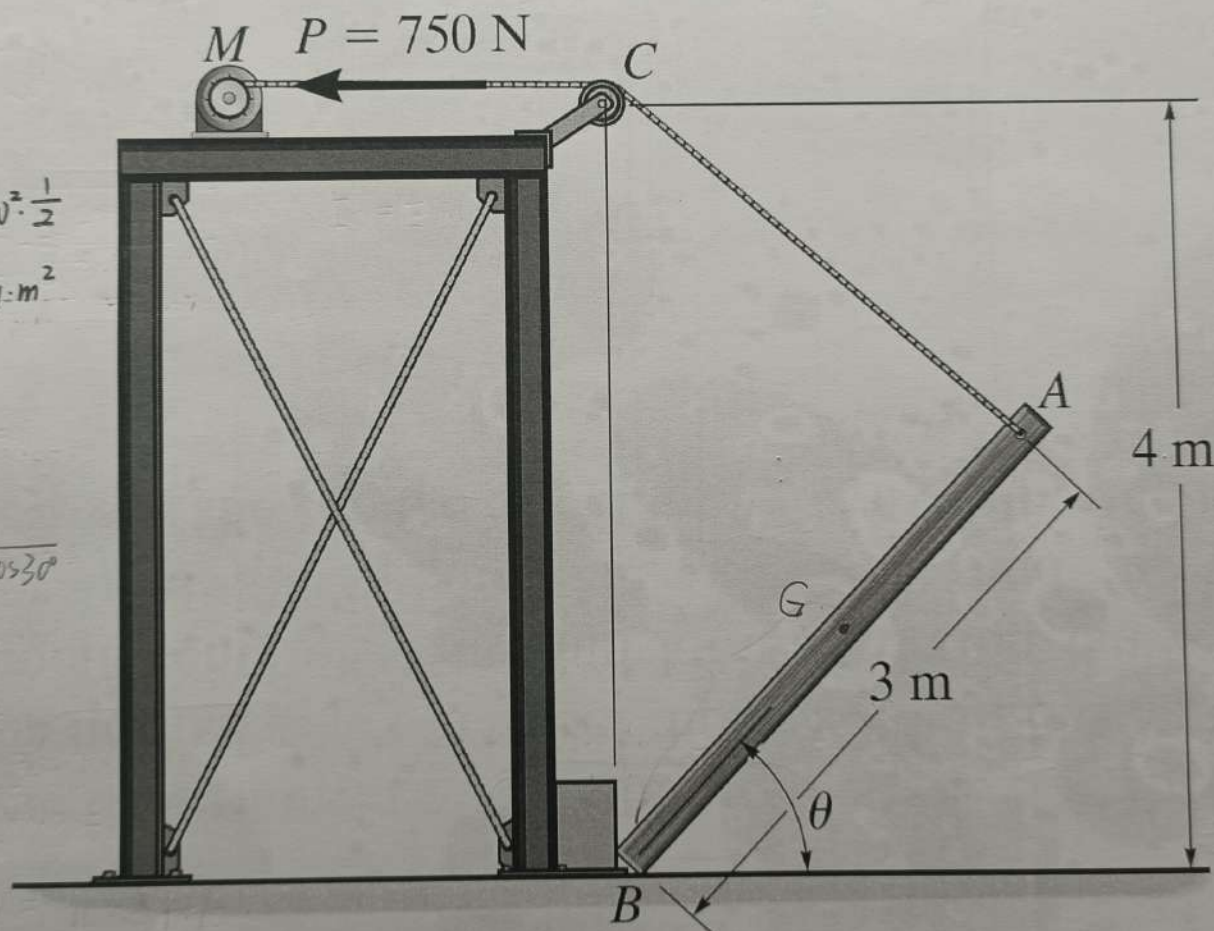


$$s = 5 - \sqrt{25 - 24 \cos 30^\circ} \text{ m}$$

$$h = 0.75 \sqrt{3} \text{ m}$$

$$\therefore T_1 + U_{1-2} = T_2$$

$$0 + P \cdot s - G \cdot h = \frac{1}{2} I_B \omega^2 \Rightarrow \omega = 2.498 \text{ rad/s} \quad \boxed{\text{ANS}}$$



Homework

The frame of a tandem drum roller has a weight of 4000 lb excluding the two rollers. Each roller has a weight of 1500 lb and a radius of gyration about its axle of 1.25 ft. If a torque of $M = 300 \text{ lb}\cdot\text{ft}$ is supplied to the rear roller A, determine the speed of the drum roller 10 s later, starting from rest.

解:

FBD: For roller A:

$$H_{A,1} + \sum \int_{t_1}^{t_2} M_A dt = H_{A,2}$$

starting from rest: $H_{A,1} = 0$

$$\rightarrow M_A = M + A_x \cdot r$$

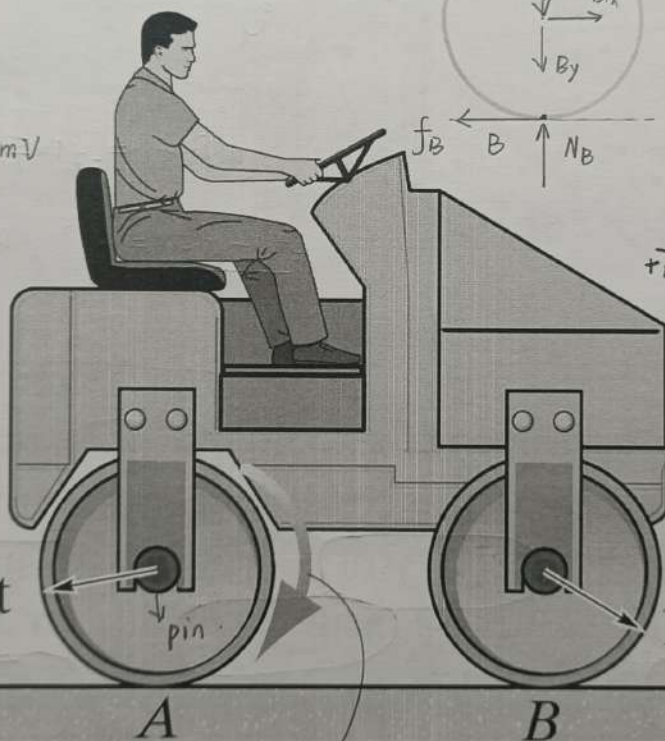
$$H_{A,2} = I\omega + mv \cdot r$$

$$\Rightarrow 0 + \int_0^{10} (M + A_x \cdot r) dt = I\omega + mv \cdot r \quad (1)$$

$$(300 + A_x \cdot 1.5)10 = I \cdot \frac{v}{r} + mv \cdot r$$

$$= 72.8 \times \frac{v}{1.5} + \frac{1500}{32.174} \times v \times 1.5 = 118.42V$$

$$300 + 1.5 A_x = 118.42V \quad (2)$$



$M = 300 \text{ lb}\cdot\text{ft}$

FBD: For roller B: KD: $I\omega$

$$H_{B,1} + \sum \int_{t_1}^{t_2} M_B dt = H_{B,2}$$

$$H_{B,1} = 0$$

$$\rightarrow M_B = B_x \cdot r$$

$$H_{B,2} = mv \cdot r + I\omega$$

$$\Rightarrow 0 + \int_0^{10} B_x r dt = I\omega + mv \cdot r \quad (2)$$

$$I = mk^2 = \frac{1500}{32.174} \times 1.25^2 = 72.8 \text{ slug}\cdot\text{ft}^2$$

without slipping: $v = \omega \cdot r \quad (3)$

For the frame:

FBD: KD: $m_0 v$

$$\sum \int_0^{10} (-A_x - B_x) dt = m_0 v \quad (4)$$

由(1)(2)(3)(4): $v = 7.0899 \text{ ft/s}$ **ANS**

Homework

The 10-g ^{0.01 kg} bullet having a velocity of 800 m/s is fired into the edge of the 5-kg disk as shown. Determine the angular velocity of the disk just after the bullet becomes embedded into its edge. Also, calculate the angle θ the disk will swing when it stops. The disk is originally at rest. Neglect the mass of the rod AB .

解:

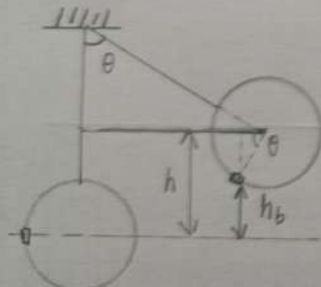
$$H_{A,1} = H_{A,2}$$

$$m_b v_b (r+l) = m_b v_{b,2} r_b + I_A \omega, \quad r_b = \sqrt{2.4^2 + 0.4^2}$$

$$I_A = I_G + m_d (r+l)^2, \quad I_G = \frac{1}{2} m_d r^2 = 0.4 \text{ kg} \cdot \text{m}^2$$

$$v_{b,2} = \omega \cdot r_b$$

$$\Rightarrow \omega = 0.6562 \text{ rad/s} \quad \boxed{\text{ANS}}$$

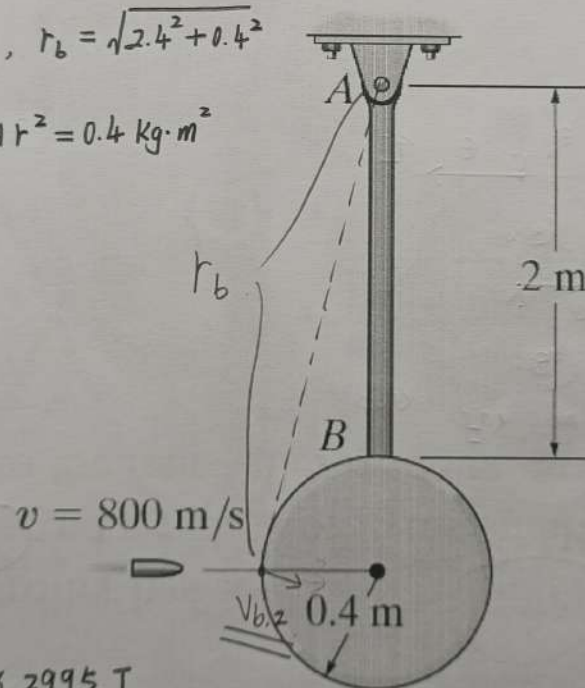


$$h = (l+r)(1-\cos\theta), \quad h_b = h - r \sin\theta$$

$$T_2 = 0, \quad T_1 = \frac{1}{2} m_b v_{b,2}^2 + \frac{1}{2} I_A \omega^2 = 6.2995 \text{ J}$$

$$U_{1-2} = -m_d g h - m_b g h_b$$

$$T_1 + U_{1-2} = T_2 \Rightarrow \theta = 18.9^\circ \quad \boxed{\text{ANS}}$$



$$h = 2.4(1-\cos\theta) = 2.4 - 2.4\cos\theta$$

$$h_b = 2.4 - 2.4\cos\theta - 0.4\sin\theta$$