

LEC 303. 2022/23.

a) i)  $X(z) = \sum_n x(n) z^{-n}$ .

$$y(k) = \{1, 0, 0, -0.1, 1, 0, \dots\}.$$

$$Y(z) = 1 - 0.1 z^{-3} + z^{-4}.$$

ii)  $\omega = 100\pi$ .  $f = \frac{\omega}{2\pi} = 50 \text{ Hz}$ .  $f_s \geq 2f = 100 \text{ Hz}$ .

$100 \text{ Hz} > 60 \text{ Hz}$  unsuitable.

iii).  $\frac{F(z)}{z} = \frac{z+1}{z(z+0.1)(z+0.2)}$   $\frac{F(z)}{z} = \frac{z+1}{z(z+0.1)(z+0.2)} = \frac{A}{z} + \frac{B}{z+0.1} + \frac{C}{z+0.2}$

①  $z=0$ .  $0+1 = A \cdot 0 \cdot 1 \cdot 0.2 + 0 + 0 \Rightarrow A = 50$ .

②  $z=-0.1$   $0.9 = 0 + B(-0.1) 0.1 + 0 \Rightarrow B = \frac{0.9}{0.01} = 90$

③  $z=-0.2$   $0.8 = 0 + 0 + C(-0.2)(-0.1) \Rightarrow C = \frac{0.8}{0.02} = 40$ .

$\therefore F(z) \therefore f(x) = 50\delta(x) - 90(-0.1)^x u(x) + 40(-0.2)^x u(x)$ .

b)  $f(k) = \begin{cases} 4 & k=2, 3, \dots \\ 0 & \text{otherwise.} \end{cases} \therefore x(n-k) \xrightarrow{Z} z^{-k} X(z)$   
 $\therefore f(k-2) \xrightarrow{Z} z^{-2} F(z)$ .

$$\therefore \{f(k-2)\} \xrightarrow{Z} \sum_{k=2}^{\infty} f(k-2) z^{-(k-2)}.$$

$$= \sum_{k=2}^{\infty} 4 z^{-(k-2)}.$$

$$\therefore \sum_{k=0}^{\infty} ar^k = \frac{a}{1-r}$$

$$\therefore \sum_{k=2}^{\infty} 4 z^{-(k-2)} = \frac{4}{1-z^{-1}}.$$

$$\therefore F(z) = z^2 \cdot \{f(k-2)\} = \frac{4z^2}{1-z^{-1}}$$

$$\therefore \{f(k)\} = z^2 \{f(k-2)\}.$$

c)  $x(k) - \alpha x(k-1) = u(k)$ .

i)  $\{x(k) - \alpha x(k-1)\} = \{u(k)\}$

$$X(z) - \alpha z^{-1} X(z) = \frac{z}{z-1}$$

$$X(z)(1-\alpha z^{-1}) = \frac{z}{z-1}$$

$$X(z) = \frac{z}{z-1} \cdot \frac{1}{1-\alpha z^{-1}} = \frac{z}{(z-1)(1-\alpha z^{-1})} = \frac{z^2}{(z-1)(z-\alpha)}$$

(1)

$$\begin{aligned} X(z) &= \frac{z^2}{(z-1)(z-a)} \quad \frac{X(z)}{z} = \frac{z^2}{z(z-1)(z-a)} = \frac{A}{z} + \frac{B}{z-1} + \frac{C}{z-a} \end{aligned}$$

$$\textcircled{1} z=0 \quad z^2=0 = A \cdot (-1) \cdot (-a) \Rightarrow A=0.$$

$$\textcircled{2} z=1 \quad z^2=1 = 0 + B \cdot 1 \cdot (1-a) \Rightarrow B=\frac{1}{1-a}$$

$$\textcircled{3} z=a \quad z^2=a^2=0+0+C \cdot a \cdot (a-1) \Rightarrow C=\frac{a^2}{a(a-1)}=\frac{a}{a-1}$$

$$\therefore X(z) = \frac{1}{1-a} \frac{z}{z-1} + \frac{a}{a-1} \frac{z}{z-a}$$

$$x(k) = \frac{1}{1-a}(1)^k u(k) + \frac{a}{a-1}(a)^k u(k) = \frac{1}{1-a} u(k) + \frac{a}{a-1} \cdot a^k u(k)$$

iii) final value theorem:  $x_{\text{final}} = \lim_{z \rightarrow 1} (z-1) X(z).$

$$x(k)_{\text{final}} = \lim_{z \rightarrow 1} (z-1) X(z) = \lim_{z \rightarrow 1} (z-1) \cdot \frac{z^2}{(z-1)(z-a)} = \frac{1}{1-a}$$

2. a) characteristic equation:  $z^2 - z + 0.25 + k = 0.$

$$b^2 - 4ac = 1 - 4(0.25+k) \quad z = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$

$$\textcircled{1} k=0 \quad z^2 - z + 0.25 = 0. \quad z = \frac{1}{2} = 0.5.$$

$$\textcircled{2} k=0.25 \quad z^2 - z + 0.5 = 0 \quad z_1 = \frac{1}{2} + \frac{1}{2}i \quad z_2 = \frac{1}{2} - \frac{1}{2}i$$

$$\textcircled{3} k=0.5 \quad z^2 - z + 0.75 = 0. \quad z_1 = \frac{1}{2} + \frac{\sqrt{3}}{2}i \quad z_2 = \frac{1}{2} - \frac{\sqrt{3}}{2}i. \quad |z| = \frac{\sqrt{3}}{2} = 0.866 < 1$$

$$\textcircled{4} k=0.75 \quad z^2 - z + 1 = 0. \quad z_1 = \frac{1}{2} + \frac{\sqrt{3}}{2}i \quad z_2 = \frac{1}{2} - \frac{\sqrt{3}}{2}i. \quad |z| = 1.$$

$$\textcircled{5} k=1 \quad z^2 - z + 1.25 = 0. \quad z_1 = \frac{1}{2} + i \quad z_2 = \frac{1}{2} - i. \quad |z| = \frac{\sqrt{5}}{2} > 1$$

between 0.75 and 1.

$$\text{b) } ZOH = \frac{1-e^{-Ts}}{s} \quad ZOH(s) = \frac{1-e^{-st}}{s} \quad T=1 \text{ second} \quad ZOH(s) = \frac{1-e^{-s}}{s}$$

$$P(z) = Z \left\{ \frac{1-e^{-s}}{s} \cdot P(s) \right\} = (1-z^{-1}) \cdot Z \left\{ \frac{P(s)}{s} \right\} = (1-z^{-1}) Z \left\{ \frac{e^{-2s}}{s(2s+1)} \right\}$$

$$Z \left\{ \frac{e^{-2s}}{s(2s+1)} \right\} = Z \left\{ \frac{e^{-2s}}{2s^2+s} \right\} = \frac{1}{2} Z \left\{ \frac{e^{-2s}}{s^2+\frac{1}{2}s} \right\} = \frac{1}{2} \cdot z^{-2} Z \left\{ \frac{1}{s+\frac{1}{2}z^{-1}} \right\}$$

$$= z^{-2} Z \left\{ \frac{\frac{1}{2}}{s(\frac{1}{2}z^{-1})} \right\} = z^{-2} \cdot \frac{z(1-e^{-\frac{1}{2}})}{(z-1)(z-e^{-\frac{1}{2}})} \quad s(\frac{1}{2}z^{-1})$$

$$\therefore P(z) = (1-z^{-1}) \cdot z^{-2} \cdot \frac{z(1-e^{-\frac{1}{2}})}{(z-1)(z-e^{-\frac{1}{2}})} = \frac{z-1}{z} \cdot z^{-2} \cdot \frac{z(1-e^{-\frac{1}{2}})}{(z-1)(z-e^{-\frac{1}{2}})}$$

$$\text{c) } A = \begin{bmatrix} -\frac{1}{R_1 C} & 0 \\ 0 & -\frac{R_2}{L} \end{bmatrix} \quad B = \begin{bmatrix} \frac{1}{R_1 C} \\ \frac{1}{L} \end{bmatrix} \quad \text{uncontrollable: } |Q_M| = |[B \ AB]| = 0.$$

$$\overline{AB} = \begin{bmatrix} -\frac{1}{R_1^2 C^2} \\ -\frac{R_2}{L^2} \end{bmatrix} \quad |Q_M| = |[B \ AB]| = \begin{vmatrix} \frac{1}{R_1 C} & -\frac{1}{R_1^2 C^2} \\ \frac{1}{L} & -\frac{R_2}{L^2} \end{vmatrix} = \frac{-R_2}{R_1 C L^2} + \frac{1}{R_1^2 C^2 L} = 0. \quad \text{②}$$

$$\therefore R_1 R_2 = \frac{1}{C}$$

$$f(x, y, z) = \frac{1}{2}(x^2 + y^2 + z^2)$$

$$\begin{cases} f(x, y, z) = \frac{1}{2}(x^2 + y^2 + z^2) \\ Lf(x, y, z, \lambda_1, \lambda_2) = \frac{1}{2}(x^2 + y^2 + z^2) + \lambda_1(x-y) + \lambda_2(x+y+z-1) \end{cases}$$

$$\therefore \frac{\partial L}{\partial x} = x + \lambda_1 + \lambda_2 = 0. \quad \text{①} \quad \text{①} \Rightarrow \begin{cases} x+y+2\lambda_2=0 \\ x-y+2\lambda_1=0 \end{cases}$$

$$\frac{\partial L}{\partial y} = y - \lambda_1 + \lambda_2 = 0. \quad \text{②} \quad \text{②} \Rightarrow \begin{cases} 2x+2\lambda_2=0 \\ 2\lambda_1=0 \end{cases} \Rightarrow \begin{cases} x=-\lambda_2 \\ \lambda_1=0 \end{cases}$$

$$\frac{\partial L}{\partial z} = z + \lambda_2 = 0. \quad \text{③} \quad \because \text{③} \Rightarrow z = -\lambda_2 \therefore x = z = y.$$

$$\frac{\partial L}{\partial \lambda_1} = x-y=0. \quad \text{④} \quad \text{in ④} \Rightarrow 3x-1=0 \therefore x=y=z=\frac{1}{3}$$

$$\frac{\partial L}{\partial \lambda_2} = x+y+z-1=0. \quad \text{⑤} \quad \therefore \lambda_2 = \frac{1}{3}$$

$$3. \quad \text{TF: } \frac{Y(z)}{R(z)} = T(z) = \frac{(C(z) \cdot P(z))}{1 + C(z) \cdot P(z)} \quad C(z) = k \frac{z}{z-1} \quad P(z) = z \{ZOH(s) \cdot P(s)\}.$$

$$\begin{aligned} P(z) &= \frac{\{1-e^{-st}\}}{z} \cdot P(s) = (1-z) \frac{\{P(s)\}}{z} = (1-z^{-1}) \frac{\{1\}}{z^{-1}(s+1)} = \frac{(-z^{-1})}{(z-1)(s+1)} \\ &= (1-z^{-1}) \left( \frac{z^{-1}[e^{-1}z + 1 - e^{-1} - e^{-1}]}{(z-1)^2(z-e^{-1})} \right) = \frac{z-1}{z} \frac{z \cdot (e^{-1}z - 2e^{-1} + 1)}{(z-1)^2(z-e^{-1})} \end{aligned}$$

$$\therefore \frac{1}{(z-1)(z-e^{-1})} = \frac{1}{z^2 - (1+e^{-1})z + e^{-1}} \quad \frac{e^{-1}(z-2)+1}{(z-1)(z-e^{-1})} = \frac{e^{-1}(z-2)+1}{z^2 - (1+e^{-1})z + e^{-1}}$$

$$\therefore \frac{(C(z)P(z))}{(z-1)(z-e^{-1})} = \frac{kz}{(z-1)(z-e^{-1})} = \frac{k(z)}{(z-1)^2(z-e^{-1})}$$

$$\therefore T(z) = \frac{kz}{(z-1)^2(z-e^{-1})} \cdot \frac{(z-1)^2(z-e^{-1})}{(z-1)^2(z-e^{-1}) + kz} = \frac{kz}{(z-1)^2(z-e^{-1}) + kz} = \frac{kz}{z^2 - (1+e^{-1})z + e^{-1} + kz}$$

$$e^{-1} = 0.3679 \Rightarrow 1+e^{-1} = 1.3679 \quad \therefore \frac{kz}{(z-1)^2(z-e^{-1}) + kz} = \frac{kz}{(z-1)^2(z-e^{-1}) + kz} = \frac{kz}{z^2 - 2z^2 + z - e^{-1}z^2 - 2e^{-1}z^2 - e^{-1}z + kz}$$

$$\therefore T(z) = \frac{kz}{z^2 - 2z^2 + z - e^{-1}z^2 - 2e^{-1}z^2 - e^{-1}z + kz} = \frac{kz}{z^2 - z^2 + z - e^{-1}z^2 - 2e^{-1}z^2 - e^{-1}z + kz} = \frac{kz}{kz} = 1$$

$$T(z) = \frac{(C(z)P(z))}{1 + C(z)P(z)} = \frac{ke^{-1}(z-2)}{z^2 - (1+e^{-1})z + e^{-1}} \cdot \frac{z^2 - (1+e^{-1})z + e^{-1}}{z^2 - (1+e^{-1})z + e^{-1} + ke^{-1}(z-2) + 1} = \frac{ke^{-1}(z-2)}{z^2 - z^2 + z - e^{-1}z^2 - 2e^{-1}z^2 - e^{-1}z + kz + 1 - ke^{-1}z + ke^{-1}z - 2 + 1} = \frac{ke^{-1}(z-2)}{kz} = \frac{ke^{-1}(z-2)}{kz} = 1$$

$$\therefore \text{Ch eq: } z^2 + z(ke^{-1} - 1 - e^{-1}) + e^{-1}k + e^{-1} = 0. \quad \therefore ke^{-1} = 0.3679. \quad 1+e^{-1} = 1.3679. \quad 1-e^{-1} = 0.26424$$

$$\therefore z^2 + z(0.3679k - 1.3679) + 0.26424k + 0.3679 = 0.$$

$$b) \text{ Jury test: } P(z) = a_n z^n + a_{n-1} z^{n-1} + \dots + a_1 z + a_0, \quad a_n > 0.$$

$$\text{①} |a_0| < a_n. \quad a_0 = 0.26424k + 0.3679 \quad a_n = 0.3679k - 1.3679 \Rightarrow |0.26424k + 0.3679| < 0.3679k - 1.3679.$$

$$\text{② } P(z)|_{z=1} > 0. \quad P(z)|_{z=1} = 1 + 0.3679k - 1.3679 + 0.26424k + 0.3679 = 0.6321k > 0 \Rightarrow k > 0.$$

$$\text{③ } (-1)^n P(z)|_{z=-1} > 0. \quad (-1)^n P(z)|_{z=-1} > 0 \Rightarrow P(z)|_{z=-1} > 0.$$

③

$$\begin{aligned} \textcircled{4} \quad |b_0| &> |b_{n-1}| \\ |c_0| &> |c_{n-2}| \\ \vdots \\ |q_0| &> |q_2| \end{aligned}$$

$$\begin{array}{cccc} \text{Row} & z^0 & \cancel{z^1} & z^1 & z^2 \\ 1 & 0.2642k+0.3679 & 0.3679k-1.3679 & 1. & \\ 2. & 1. & 0.3679k-1.3679 & 0.2642k+0.3679. & \\ 3. & (0.2642k+0.3679)^2-1 & (0.2642k+0.3679) \\ & \times(0.3679k-1.3679) & - (0.3679k-1.3679) \\ & \times (0.2642k+0.3679) & = 0. \\ 4. & \vdots & (0.2642k+0.3679)^2-1 & \end{array}$$

$$b_0 = a_0 \times a_0 - a_n \times a_n$$

$$b_1 = a_0 \times a_1 - a_n \times a_{n-1}$$

$$C_0 = b_0 \times b_0 - b_{n-1} \times b_{n-1}$$

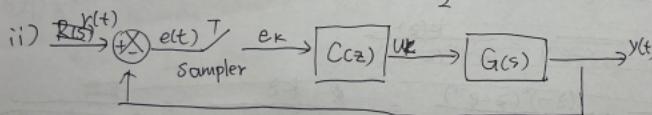
$$3. \left[ (0.2642k+0.3679)^2-1 \right]^2$$

$$|b_0| > |b_{n-1}| = 0. \Rightarrow (0.2642k+0.3679)^2-1 > 0.$$

$$\text{c) i) } G(s) = \frac{k}{s(s+1)} \quad \text{TF: } \mathcal{J}_s \cdot T(s) = \frac{k}{s(s+1)} \cdot \frac{s(s+1)}{s(s+1)+k} = \frac{k}{s(s+1)+k}$$

$$\therefore \text{poles: } s(s+1)+k=0. \quad s^2+s+k=0. \quad b^2-4ac=1-4k$$

$$\therefore s = \frac{-1 \pm \sqrt{1-4k}}{2}$$



The continuous-time system is converted into a discrete-time system.

If the sampling is too low, aliasing can occur, leading to instability or degraded performance. The process of sampling and quantization can introduce noise and errors.

Introducing a sample and hold process can offer benefits such as easier implementation of digital controllers.

$$\text{d) steepest descent: } X^{k+1} = X^k - \lambda \nabla f(X^k)$$

$$\nabla f(x_1, x_2) = \begin{bmatrix} 1+4x_1+2x_2 \\ -1+2x_1+2x_2 \end{bmatrix}, \quad X_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \nabla f(0,0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad (\lambda)^* = \frac{(P^k)^T \cdot P^k}{(P^k)^T A \cdot P^k}.$$

$$\therefore X^1 = X^0 - \lambda \nabla f(X^0), \quad (\lambda^0)^* = \frac{\begin{bmatrix} 1 \\ -1 \end{bmatrix}}{\begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 4 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}} = \frac{1+1}{2 \cdot 2} = \frac{2}{2} = 1$$

$$\therefore X^1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 1 \cdot \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \frac{1+1}{2 \cdot 2} \begin{bmatrix} 4 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{2}{2} = 1$$

$$X^2 = X^1 - \lambda \nabla f(X^1) = \begin{bmatrix} -1 \\ 1 \end{bmatrix} - 1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

(4)

4. (a) i)  $\nabla f(x) = \begin{cases} x_1^2 - 4 \\ x_2^2 - 4 \end{cases}$  let  $\nabla f(x) = 0 \Rightarrow x_1 = \pm 2, x_2 = \pm 2$   
 stationary point  $x = \begin{bmatrix} \pm 2 \\ \pm 2 \end{bmatrix}$   $(2, 2), (2, -2), (-2, 2), (-2, -2)$ .

ii).  $f(x) = \frac{1}{2} x^T Q x + b^T x + c$ .

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, Q = \begin{bmatrix} 12 & 6 & -4 \\ 6 & -4 & 0 \\ -4 & 0 & 2 \end{bmatrix}, b^T = 0, c = 0.$$

$$\therefore f(x) = \frac{1}{2} x^T \begin{bmatrix} 12 & 6 & -4 \\ 6 & -4 & 0 \\ -4 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

iii)  $A = \begin{bmatrix} 10 & 4 & -8 \\ 4 & 2 & -4 \\ -8 & -4 & 10 \end{bmatrix}, A_{11} = 10 > 0.$

$$|A| = 10(20-16) - 4(40-32) - 8(-16+16) = 40 - 32 - 0 = 8 > 0. \quad \text{positive definiteness.}$$

iv) minimum. necessary.  $f'(x) = 0$ . sufficient  $f''(x) > 0$ .

b) i)  $x^{k+1} = x^k - A_k^{-1} \nabla f(x^k), A_k^{-1} = [\nabla^2 f(x^k)]^{-1}$

$$\nabla J(u) = J'(u) = 2du, J''(u) = 2d.$$

$$d=1, J'(u) = 2u, J''(u) = 2.$$

$$u_1 = u_0 - \frac{J'(u_0)}{J''(u_0)} = u_0 - \frac{2u_0}{2} = 0.$$

$$x^{k+1} = x^k - \frac{\nabla f(x^k)}{\nabla^2 f(x^k)}$$

$$x^{k+1} = x^k - \frac{f'(x^k)}{f''(x^k)}$$

ii) The Newton method requires the calculation of the Hessian matrix.

For high-dimensional systems, this can be computationally expensive.

It requires second-order derivative information (the Hessian).