# Jialian Wu

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## **Education**

#### Ph.D. Candidate, State University of New York at Buffalo

08/2019-Present

- ➤ Computer Science and Engineering
- Advisor: Dr. Junsong Yuan

#### Graduate Study, Tianjin University

09/2018-07/2019

- M.Eng. in Electronic Information Engineering
- Advisor: Dr. <u>Yanwei Pang</u>

(Left for University at Buffalo in July 2019 before finishing my degree)

## Bachelor of Engineering, Tianjin University

09/2014-07/2018

- ➤ Electronic Information Engineering
- ➤ GPA: 3.85/4.0 (90.94/100)
- Rank: 5/84
- Thesis: Multi-level Feature Fusion Network for Object Detection. (Outstanding Bachelor Thesis)

  Research Interest: Object-centric video analysis including detection, segmentation, and tracking. I am also open to explore other interesting research topics in computer vision field.

#### **Publications**

- > *Multi-Object Tracking*: We propose a TraDeS tracker that exploits tracking cues estimated from a cost volume map to temporally propagate object features for enhancing current object recognition.
  - Jialian Wu, Jiale Cao, Liangchen Song, Yu Wang, Ming Yang, and Junsong Yuan, "Track to Detect and Segment: An Online Multi-Object Tracker", in *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition* (CVPR), 2021. [Project Page] [PDF] [Code]
- > Occluded Pedestrian Detection in Videos: We propose to exploit less-occluded pedestrians from adjacent spatial-temporal space to aid the detection of heavily occluded pedestrians in current frame.
  - Jialian Wu, Chunluan Zhou, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, "Temporal-Context Enhanced Detection of Heavily Occluded Pedestrians", in *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition* (CVPR), 2020. [PDF]
- Large-Vocabulary and Long-tailed Object Detection: We propose to build a forest classifier based on object relations, which can suppress the noisy logits existed in a fine-grained classifier.
  - Jialian Wu, Liangchen Song, Tiancai Wang, Qian Zhang, and Junsong Yuan, "Forest R-CNN: Large-Vocabulary Long-Tailed Object Detection and Instance Segmentation", in *Proceedings of the ACM International Conference on Multimedia* (ACM MM), 2020. [PDF] [Code]
- > Small-scale Pedestrian Detection: We propose to utilize the features of large-scale pedestrians from the same neural network to help the feature learning of the small-scale pedestrians.
  - Jialian Wu, Chunluan Zhou, Qian Zhang, Ming Yang, and Junsong Yuan, "Self-Mimic Learning for Small-scale Pedestrian Detection", in *Proceedings of the ACM International Conference on Multimedia* (ACM MM), 2020. [PDF]
- Multi-label image classification
  - Liangchen Song, **Jialian Wu**, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, "Handling Difficult Labels for Multi-label Image Classification via Uncertainty Distillation", in *Proceedings of the ACM International Conference on Multimedia* (ACM MM), 2021.
- **Knowledge Transferring**: We propose a hybrid network forwarding scheme to transfer the

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knowledge encoded in a teacher network to a student network.

• Liangchen Song, **Jialian Wu**, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, "Robust Knowledge Transfer via Hybrid Forward on the Teacher-Student Model", in *Proceedings of the AAAI Conference on Artificial Intelligence* (AAAI), 2021. [PDF]

## **Industry Research Experience**

### Applied Scientist Intern, Amazon, Seattle, WA, USA

May - August, 2021

Amazon Go Team, Mentor: Dr. Tian Lan

#### Research Intern, Horizon Robotics, Silicon Valley, CA, USA

May – August, 2020

Autonomous Driving Perception Team, Mentor: Dr. Yu Wang

Propose a multi-object tracker, referred as TraDeS. TraDeS is able to perform 2D box tracking, 3D box tracking, and instance segmentation tracking in real-time. TraDeS achieves state-of-the-art tracking performance on various benchmarks, including Nuscenes (3Dbox tracking), MOT (2Dbox tracking), MOTS and Youtube-VIS (instance segmentation tracking).

#### Research Intern, Horizon Robotics, Beijing, China

May – September, 2018

Mentor: Dr. Oian Zhang

➤ Propose a Self-Mimic Learning (SML) method for detecting small-scale pedestrians. SML achieves the top-1 result on the CityPersons dataset and is accepted to ACM MM 2020.

#### **Other Projects**

#### Alibaba Cloud Tianchi Competition

April - May, 2019

- Rank 30th / 2157 teams in China and 1st / 44 teams in Tianjin City.
- Achieve object detection and segmentation in X-ray images.

# Object Detection for Autonomous Driving Ship, TJU Vision Intelligence Lab March – May, 2018

> Complete dataset building (images & annotations), algorithm implementation, and interface design.

#### **National Innovation Project for Undergraduate Students**

March – May, 2017

Achieve pedestrian detection in foggy weather by using the traditional hog+svm detector with a hard example mining scheme.

#### Awards

- Best CSE First Year Achiever Award, State University of New York at Buffalo, 2020.
- Outstanding Bachelor Thesis, Tianjin University, 2018.
- First-class Entrance Fellowship, Tianjin University, 2018.
- Tianjin City Fellowship, 2016.
- Merit Student Fellowship, Tianjin University, 2017, 2016, 2015.

#### **Professional Services**

#### Reviewer:

- Conferences: CVPR 2021 (<u>outstanding reviewer</u>), ICCV 2021, AAAI 2021, IJCAI 2021, WACV 2021, ICASSP 2021, CVPR 2020, ACCV 2020
- > Journals: IEEE Transactions on Image Processing, IEEE Transactions on Circuits and Systems for Video Technology

# **Teaching Assistant:**

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- ➤ CSE573: Computer Vision and Image Processing, Fall 2019.
- > CSE191: Discrete Structures, Spring 2020.

# **Computer Skills**

> Python, MXNET, PyTorch, LaTex, Linux, etc