

Education

Ph.D. Candidate, State University of New York at Buffalo

08/2019–Present

- Computer Science and Engineering
- Advisor: Dr. [Junsong Yuan](#)

M.Eng. Study, Tianjin University

09/2018–07/2019

- Electronic Information Engineering
- Advisor: Dr. [Yanwei Pang](#)

(Left for University at Buffalo in July 2019 before finishing my degree)

Bachelor of Engineering, Tianjin University

09/2014–07/2018

- Electrical Information Engineering
- GPA: 3.85/4.0 (90.94/100)
- Rank: 5/84
- Thesis: Multi-level Feature Fusion Network for Object Detection. (Outstanding Bachelor Thesis)

Research Interest: Object-centric video analysis including detection, segmentation, and tracking. I am also open to explore other interesting research topics in computer vision field.

Publications

- **Multi-Object Tracking:** We propose a TraDeS tracker that exploits tracking cues estimated from a cost volume map to temporally propagate object features for enhancing current object recognition.
 - **Jialian Wu**, Jiale Cao, Liangchen Song, Yu Wang, Ming Yang, and Junsong Yuan, “Track to Detect and Segment: An Online Multi-Object Tracker”, in *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2021.
- **Occluded Pedestrian Detection in Videos:** We propose to exploit less-occluded pedestrians from adjacent spatial-temporal space to aid the detection of heavily occluded pedestrians in current frame.
 - **Jialian Wu**, Chunluan Zhou, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, “Temporal-Context Enhanced Detection of Heavily Occluded Pedestrians”, in *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2020. [\[PDF\]](#)
- **Large-Vocabulary and Long-tailed Object Detection:** We propose to build a forest classifier based on object relations, which can suppress the noisy logits existed in a fine-grained classifier.
 - **Jialian Wu**, Liangchen Song, Tiancai Wang, Qian Zhang, and Junsong Yuan, “Forest R-CNN: Large-Vocabulary Long-Tailed Object Detection and Instance Segmentation”, in *Proceedings of the ACM International Conference on Multimedia (ACM MM)*, 2020. [\[PDF\]](#) [\[Code\]](#)
- **Small-scale Pedestrian Detection:** We propose to utilize the features of large-scale pedestrians from the same neural network to help the feature learning of the small-scale pedestrians.
 - **Jialian Wu**, Chunluan Zhou, Qian Zhang, Ming Yang, and Junsong Yuan, “Self-Mimic Learning for Small-scale Pedestrian Detection”, in *Proceedings of the ACM International Conference on Multimedia (ACM MM)*, 2020. [\[PDF\]](#)
- **Knowledge Transferring:** We propose a hybrid network forwarding scheme to transfer the knowledge encoded in a teacher network to a student network.
 - Liangchen Song, **Jialian Wu**, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, “Robust Knowledge Transfer via Hybrid Forward on the Teacher-Student Model”, in *Proceedings of the AAAI Conference on Artificial Intelligence (AAAI)*, 2021. [\[PDF\]](#)

Jialian Wu

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Submissions

- **Jialian Wu**, Liangchen Song, Qian Zhang, Ming Yang, and Junsong Yuan, “Forest DetSeg: Large-Vocabulary Long-Tailed Object Detection and Instance Segmentation”, IEEE Transactions on Multimedia, under review.

Industry Research Experience

Research Intern, Horizon Robotics, Silicon Valley, CA, USA

May – August, 2020

Autonomous Driving Perception Team, Mentor: Dr. [Yu Wang](#)

- Propose a multi-object tracker, referred as TraDeS. TraDeS is able to perform 2D box tracking, 3D box tracking, and instance segmentation tracking in real-time. TraDeS achieves state-of-the-art tracking performance on various benchmarks, including Nuscenes (3D box tracking), MOT (2D box tracking), MOTS and Youtube-VIS (instance segmentation tracking).

Research Intern, Horizon Robotics, Beijing, China

May – September, 2018

Mentor: Dr. [Qian Zhang](#)

- Propose a Self-Mimic Learning method for detecting small-scale pedestrians. The proposed method achieves the top-1 result on the testing set of CityPersons dataset and is accepted to ACM MM 2020.

Other Projects

Alibaba Cloud Tianchi Competition

April – May, 2019

- Rank 30th / 2157 teams in China and 1st / 44 teams in Tianjin City.
- Achieve object detection and segmentation in X-ray images.

Object Detection for Autonomous Driving Ship, TJU Vision Intelligence Lab

March – May, 2018

- Complete dataset building (images & annotations), algorithm implementation, and interface design.

National Innovation Project for Undergraduate Students

March – May, 2017

- Achieve pedestrian detection in foggy weather by using the traditional hog+svm detector with a hard example mining scheme.

Awards

- [Best CSE First Year Achiever Award](#), State University of New York at Buffalo, 2020.
- Outstanding Bachelor Thesis, Tianjin University, 2018.
- First-class Entrance Fellowship, Tianjin University, 2018.
- Tianjin City Fellowship, 2016.
- Merit Student Fellowship, Tianjin University, 2017, 2016, 2015.

Professional Services

Reviewer:

- Conferences: CVPR'21'20, ICCV'21, AAAI'21, IJCAI'21, ACCV'20, WACV'21, ICASSP'21
- Journals: IEEE Transactions on Image Processing, IEEE Transactions on Circuits and Systems for Video Technology

Teaching Assistant:

- CSE573: Computer Vision and Image Processing, Fall 2019.
- CSE191: Discrete Structures, Spring 2020.

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Computer Skills

- Python, MXNET, PyTorch, LaTeX, Linux, etc