**Education**

**Ph.D. Candidate, State University of New York at Buffalo** 08/2019–Present

* Major: Computer Science and Engineering
* Current GPA: 4.0/4.0
* Supervisor: Dr. [Junsong Yuan](https://cse.buffalo.edu/~jsyuan/index.html)

**Graduate Study, Tianjin University** 09/2018–07/2019

* Major: Electronic Information Engineering
* Supervisor: Dr. [Yanwei Pang](https://scholar.google.com.hk/citations?user=dE-2UtsAAAAJ&hl=zh-CN)

(Left for University at Buffalo in July 2019 before finishing my degree)

**Bachelor of Engineering, Tianjin University** 09/2014–07/2018

* Major: Electronic Information Engineering
* GPA: 3.85/4.0 (90.94/100)
* Rank: 5th/84
* Thesis: Multi-level Feature Fusion Network for Object Detection. (Outstanding Undergraduate Thesis)

**Research Interest**: Pedestrian Detection and Object Detection in Still-Images and Videos; Joint Multi-Object Detection and Tracking; 3D Monocular Object Detection and Tracking

**Publication**

* *Heavily Occluded Pedestrian Detection*: Our solution is to exploit less-occluded pedestrians from adjacent spatial-temporal space to aid the detection of heavily occluded pedestrians in current frame.

● **Jialian Wu**, Chunluan Zhou, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, “Temporal-Context Enhanced Detection of Heavily Occluded Pedestrians”, in *Proc. IEEE Conference on Computer Vision and Pattern Recognition* (CVPR), 2020.

* *Large-Vocabulary and Long-tailed Object Detection*: Our solution is to explore relations among object categories to build a classification forest so as to suppress the noisy logits existed in a fine-grained classifier.

● **Jialian Wu**, Liangchen Song, Tiancai Wang, Qian Zhang, and Junsong Yuan, “Forest R-CNN: Large-Vocabulary Long-Tailed Object Detection and Instance Segmentation”, in *Proc. ACM International Conference on Multimedia* (ACM MM), 2020.

* *Small-scale Pedestrian Detection*: Our solution is to utilize the features of large-scale pedestrians from the same neural network to help the feature learning of the small-scale pedestrians.

● **Jialian Wu**, Chunluan Zhou, Qian Zhang, Ming Yang, and Junsong Yuan, “Self-Mimic Learning for Small-scale Pedestrian Detection”, in *Proc. ACM International Conference on Multimedia* (ACM MM), 2020.

**Submission**

* Liangchen Song, **Jialian Wu**, Ming Yang, Qian Zhang, Yuan Li, and Junsong Yuan, “Robust Knowledge Transfer via Hybrid Forward on the Teacher-Student Model”, AAAI 2021, submission.
* Liangchen Song, Ming Yang, **Jialian Wu**, Qian Zhang, Yuan Li, and Junsong Yuan, “Handling Difficult Labels for Multi-label Image Classification via Uncertainty Distillation”, IEEE Transactions on Image Processing, under review.

**Research Experience**

**Research Intern, Horizon Robotics, San Francisco Bay Area, CA, USA** May – August, 2020

Autonomous Driving Perception Team, Mentor: Dr. [Yu Wang](https://scholar.google.com/citations?user=uNj2w9gAAAAJ&hl=en)

* Improving state-of-the-art joint detection and tracking system based on anchor-free one-shot fashion.
* 3D monocular object detection system.

**Research Intern, Horizon Robotics, Beijing, China** May – September, 2018

Mentor: Dr. [Qian Zhang](https://scholar.google.com/citations?user=pCY-bikAAAAJ&hl=zh-CN)

* Implemented "Repulsion Loss: Detecting Pedestrians in a Crowd" with the FPN backbone network and achieved miss rate of 13.6% on the Cityperson dataset.
* Designed a multi-pedestrian aware network as well as a self-mimic learning technique, achieving the top-1 result on the test subset of Cityperson dataset.

**Project Experience**

**Alibaba Cloud Tianchi Competition** April – May, 2019

* Ranked 30th / 2157 teams in China and 1st / 44 teams in Tianjin City.
* Achieved restricted object detection and segmentation in X-ray images.

**Object Detection for Autonomous Driving Ship, TJU Vision Intelligence Lab** March – May, 2018

* This project includes: 10,000 images and annotations collection, object detector implementation, interface and SDK design.

**National Innovation Project for Undergraduate Students** March – May, 2017

* Achieved pedestrian detection in foggy weather by using the traditional hog+svm detector with a hard example mining scheme.

**Professional Services**

* **Teaching Assistant:**
* CSE573: Computer Vision and Image Processing, Fall 2019.
* CSE191: Discrete Structures, Spring 2020.
* **Reviewer**:
* Conferences: CVPR2020, IJICAI2021, WACV2021, ACCV2020
* Journals: IEEE Transactions on Image Processing

**Awards**

* 2015-2016, Tianjin City Scholarship.
* 2014-2015, 2015-2016, 2016-2017, Tianjin University Merit Student Scholarship.

**Computer Skills**

* Python, MXNET, PyTorch, LaTex, Linux