



# Systems Thinking

Seamless Transition-1:  
**The four principles of seamless transition**  
无缝衔接的四个原理

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# 指令周期

- 每个指令周期包含三个操作阶段（步骤）
  - 例如，指令MOV R1, M[R0]执行三步骤如下：
    - 取指操作：  $IR \leftarrow M(PC)$ ;  $PC \leftarrow PC+1$
    - 译码操作： Signals = Decode(IR)
    - 执行操作：  $M[R0] \leftarrow R1$

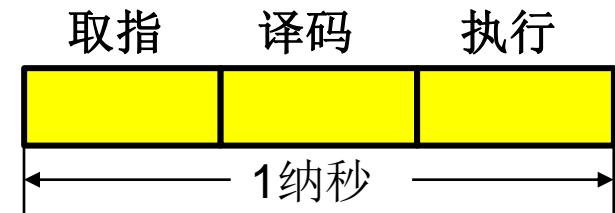


# 指令流水线

- 假设指令流水线总延时是1纳秒，流水线各阶段没有重叠（No overlap）

- 执行完当前指令，再执行下一条指令**

- 处理器时钟周期 = 1纳秒
- 处理器主频 (frequency) =  $1/(1\text{ 纳秒}) = 1 \text{ GHz}$
- 峰值速度为1 GIPS  
(Giga Instructions Per Second)  
即每秒十亿条指令



# 指令流水线

- 假设指令流水线总延时是1纳秒，流水线各阶段没有重叠（No overlap）

- 执行完当前指令，再执行下一条指令**

- 处理器时钟周期 = (1/3)纳秒
- 处理器主频 (frequency) =  $1/(1/3) = 3 \text{ GHz}$
- 执行一条指令需要三个时钟周期
- 峰值速度为1 GIPS (Giga Instructions Per Second)  
即每秒十亿条指令



# 指令流水线机制总是利用重叠 (overlap)

处理器主频= 3 GHz, 指令流水线同时执行三条指令, 平均每个时钟周期执行完毕一条指令

峰值速度: 3 Giga Instructions Per Second (GIPS), 即每秒执行30亿条指令

- 假设  $K$  级指令流水线总延时是 1 纳秒, 则有

- 处理器时钟周期是每级延时 =  $1/K$  纳秒
- 处理器主频 =  $K$  GHz
- 指令流水线同时执行  $K$  条指令, 平均每个时钟周期执行完毕一条指令
- 处理器峰值速度:  $K$  GIPS



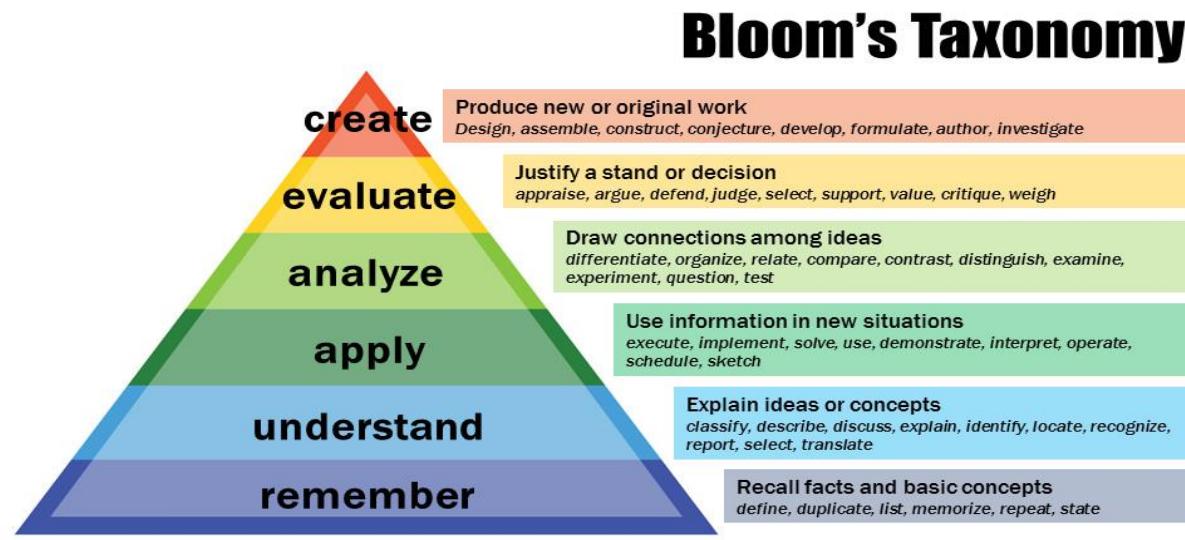
	取指	译码	执行
时钟0:	指令4	指令3	指令2
	指令1		
时钟1:	指令5	指令4	指令3
	指令2	指令1	
时钟2:	指令6	指令5	指令4
	指令3	指令2	指令1
时钟3:	指令7	指令6	指令5
	指令4	指令3	指令2
时钟4:	指令8	指令7	指令6
	指令5	指令4	指令3
时钟5:	指令9	指令8	指令7
	指令6	指令5	指令4
			指令3

# 回答同学们的若干问题

- 四个时间点（前三个是截止日期，可以提前提交）
  - 7月7日：提交个人作品的动态网页代码
  - 7月11日：提交最后一次作业
  - 7月14日：提交个人作品报告（可以完善动态网页代码）
    - 如改了代码，请注明完善了什么
  - 7月16日上午10-12点：期末考试
- 期末考试相关
  - 7月9日上课：期末复习
  - 期末考试内容范围
    - 整个课程，1-6章
    - 上课讲过的内容，也是期末复习重温的内容（注意：举一反三）
    - 中英文教科书都有的内容（少数例外）
    - 不会考个人作品涉及的编程内容
  - 教学团队周末值班

# 布鲁姆教学目标分类法应用到本课程

- 知道：能够区分概念
  - 组合电路、时序电路
- 了解：能够解决一个实例问题
- 掌握：学到了原理，能够举一反三
  - 时序电路做加法、做减法



# 无缝衔接

- 自动执行高阶：无缝衔接
    - 确保正确性的计算过程归纳法
      - 正确地确定第一步
      - 针对每个单一步骤，保证该步骤正确执行
      - 每一步骤执行完毕，  
    正确地确定并衔接到底一步骤
    - 应对计算过程的瓶颈
  - 自动执行难题尚未完全解决
    - 基本解决了单机自动执行难题
    - 在多台计算机上执行的计算过程如何自动执行？
    - 在人机物三元计算的万物互联网时代如何自动执行？
      - 网络思维（名字空间、拓扑、协议栈）
      - IEEE CS 2022报告：无缝智能
- Yang's cycle principle  
扬雄周期原理
  - Postel's robustness principle  
波斯特尔鲁棒原理
  - von Neumann's exhaustiveness principle  
冯诺依曼穷举原理
  - Amdahl's law  
阿姆达尔定律

# 无缝智能尚未实现

- 不只是简单的数值计算，而是智能计算
  - 计算机能够：理解、感知、认知，甚至呈现情感、美感、意识
- 无缝：用户体验流畅

案例：执行“请开灯”命令（2017.4.13实验）

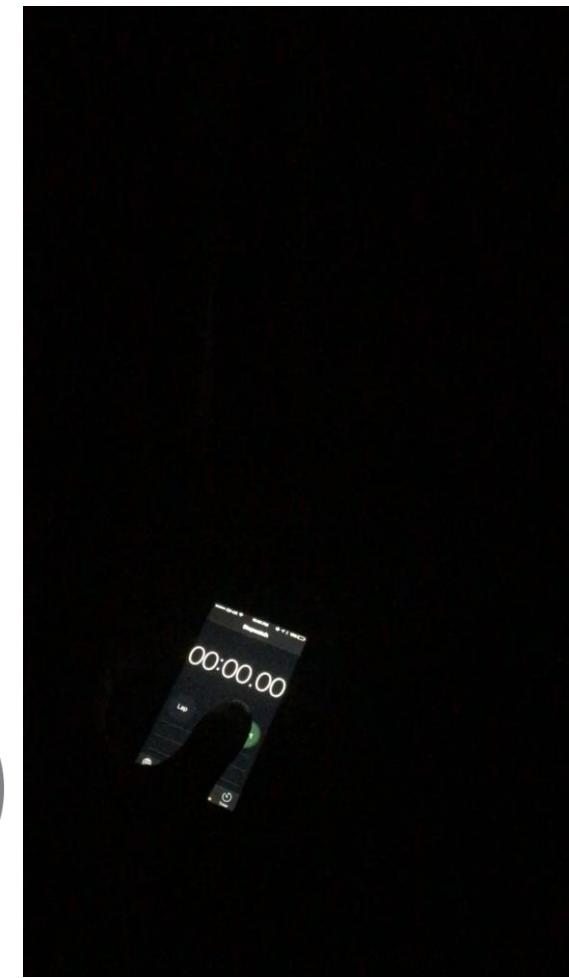
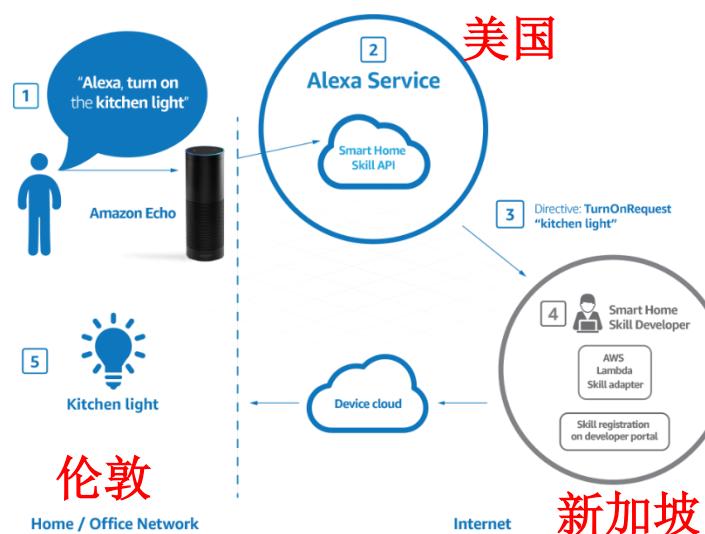
世界领先的Amazon Echo 物端系统

响应延迟：3-5秒

心理学准则：

用户体验到无缝智能  
→响应延迟<0.12秒

中科院计算所  
物端系统研究目标  
响应延迟 < 0.1秒



# 扬雄周期原理

优于尼采的永恒轮回： die ewige Wiederkunft

- 汉代扬雄所著的《太玄经》
  - 《太玄经•周首》：“阳气周神而反乎始，物继其汇”
    - 宋代司马光诠释道：“岁功既毕，神化既周”
- 扬雄周期原理体现组合性（composability）方法
  - 执行完一个XX周期，周而复始执行下一个XX周期
    - 计算过程由程序周期组合而成
    - 程序周期由指令周期组合而成
    - 指令周期由时钟周期组合而成
  - 一个时钟周期的操作对应于一个自动机的变换
  - XX周期具备可数个类别
    - 例如，指令周期有内部周期、总线周期

# Outline

- What is systems thinking?
- Three objectives of systems thinking
- Abstraction
- Modularization
- Seamless transition
  - The symphony of four principles 无缝衔接的四条原理
  - Yang's cycle principle 扬雄周期原理
  - Postel's robustness principle 波斯特尔鲁棒性原理
  - von Neumann's exhaustiveness principle 冯诺依曼穷举原理（穷尽原理）
  - Amdahl's law 阿姆达尔定律
  - Landscape of computing systems

*These slides acknowledge sources for additional data not cited in the textbook*

# 5.1 The symphony of four principles

- 1-minute quiz
  - Q: Why can two students in San Jose and Shenzhen conduct a video talk online correctly? Please give a specific principle.
    - Why trillions of instructions can be automatically executed in a fraction of a second, across the globe, to produce correct computational results?
    - 为什么两位学生，位于硅谷和深圳，可以完成一个协同计算任务，例如视频对话？
    - 为什么他们相隔几千里，却可以在一秒之内完成协同计算任务，例如传递一个视频表情（笑容）？
    - 原理上是如何做到的？
    - 先不管速度，正确性是如何保证的？（功能实现）
    - 速度是如何保证的？（性能实现）

## 5.1 The symphony of four principles

### 四条无缝衔接原理的交响乐

- 1-minute quiz

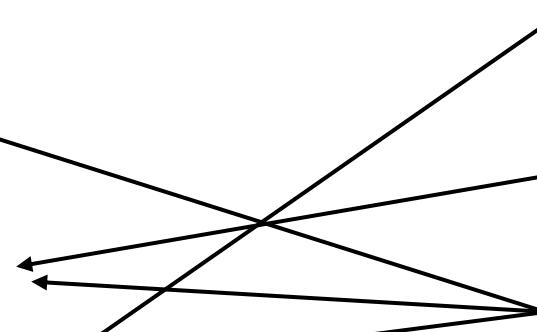
- A. The computers involved in the video talk execute their computational processes correctly and smoothly  
多个计算机正确且无缝地执行计算过程
- More concretely, for each computational process involved, do a computational induction (similar to mathematic induction)
  - Ensure that the first step is correctly identified
  - Ensure that any identified step (i.e., any single step) is correctly executed
  - For each step just finishing execution, ensure that the correct next step is identified and the current step correctly transition to the next step
- 计算归纳法（只考虑一个串行计算过程）
  - 正确地确定第一步
  - 针对每个单一步骤（一个确定的步骤），保证该步骤正确执行
  - 每一步骤执行完毕，正确地确定并衔接到底下一步骤
- A step could be a program, an instruction, a gate, etc.
  - 步骤 = 程序、指令、逻辑门等（各种粒度）

# 5.1 The symphony of four principles

## ● 1-minute quiz

- Q: Why and how can two students in San Jose and Shenzhen conduct an online video talk correctly? Please give a specific principle.
  - Why trillions of instructions can be automatically executed in a fraction of a second, across the globe, to produce **correct** computational results?
- A. The computers involved in the video talk execute their computational processes correctly and smoothly
- More concretely, for each computational process involved, do a computational induction (similar to mathematic induction), to ensure **correctness**

- Identify first step ←  
确定第一步
- Execute single step ←  
正确执行每一步
- Identify and transition to next step ←  
确定并过渡到下一步

- 
- Yang's cycle principle  
扬雄周期原理
  - Postel's robustness principle  
波斯特尔鲁棒原理
  - von Neumann's exhaustiveness principle  
冯诺依曼穷举原理

# 5.1 The symphony of four principles

- 1-minute quiz

- Q: Why and how can two students in San Jose and Shenzhen conduct an online video talk correctly? Please give a specific principle.
  - Why trillions of instructions can be automatically executed **in a fraction of a second**, across the globe, to produce **correct** computational results?
- A. The computers involved in the video talk execute their computational processes correctly and smoothly
- More concretely, for each computational process involved, do a computational induction (similar to mathematic induction), to ensure **correctness**

- Identify first step
- Execute single step
- Identify and transition to next step
- Also need to consider **smoothly**  
功能和性能的无缝衔接

- Yang's cycle principle
- Postel's robustness principle
- von Neumann's exhaustiveness principle
- **Amdahl's law**  
阿姆达尔定律

## 5.2 Yang's cycle principle

- In a multi-step computational process, how to ensure the seamless transition from one step to the next step?
- Yang's cycle principle
  - A system executes a computational process in a sequence of cycles. 系统按照周期执行计算过程
  - The system finishes one cycle and automatically returns to the beginning (of the next cycle),  
系统执行完一个周期，自动地返回到下一个周期的开始
  - So that different computational processes preserve their respective kinds.  
不同计算过程保持它们各自的特色
  - Examples of different kinds, when step=instruction
    - MOV to register instruction, MOV to memory instruction
    - ADD instruction, INC instruction
    - CMP instruction, JL instruction

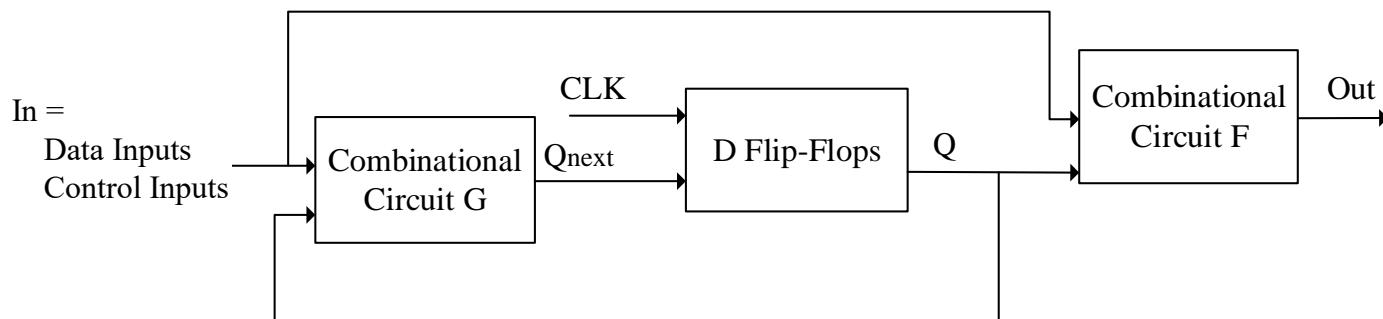
《太玄经·周首》☰：  
阳气周神而反乎始，  
物继其汇。

**Head Full Circle** ☰:  
Yang qi comes full circle. Divinely, it returns to the beginning. Things go on to preserve their kinds.

扬雄，公元前2年  
Yang Xiong, 2 BCE

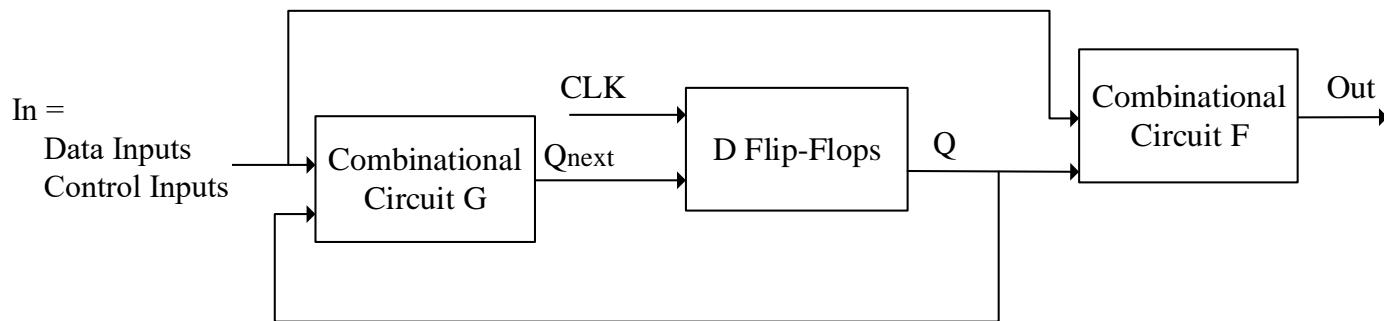
# Crucial details 使用自动机的状态变量是关键

- Automatically return to the beginning of next cycle
- 怎样实现“周而复始”？
  - Sequential circuit uses current state to generate next state  
**第k步的 $Q_{next}$ , 自动变成第k+1步的Q**
    - At step  $k$ , the system is in state  $Q$ , = output of the D flip-flops
    - Functionality of step  $k$ 
      - Use  $Q$  and current input  $In$  to generate  $Q_{next}$  and current output  $Out$
    - When step  $k$  finishes, i.e., when CLK switches to the next clock cycle
      - $Q_{next}$  replaces  $Q$  to become the current state via the D flip-flops, and the system returns to the beginning of step  $k + 1$



# Crucial details

- Automatically return to the beginning of next cycle
  - Sequential circuit uses current state to generate next state
    - At step  $k$ , the system is in state  $Q$ , = output of the D flip-flops
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      - $Q_{next}$  replaces  $Q$  to become the current state via the D flip-flops, and the system returns to the beginning of step  $k + 1$



- Use the same cycle mechanism to support diversity
  - By utilizing different control signals (control inputs)

# Cycles have different granularities

## 周期有不同粒度

- The task of sending a WeChat message involves the executions of several programs, and consists of a sequence of **program cycles** 程序周期
- Execution of a program cycle consists of the executions of a sequence **of instruction cycles** 指令周期
- Execution of a instruction cycle consists of the executions of a sequence of **clock cycles** 时钟周期
- A 1-GHz processor has a clock cycle of 1 ns
- At each clock cycle, the processor performs a state transition of one or more sequential circuits

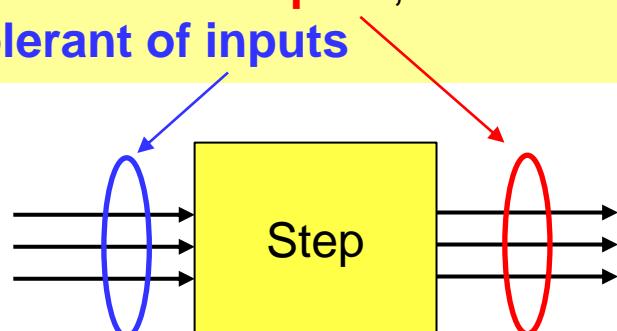
## 5.3 Postel's robustness principle 宽进严出原理

- Originally proposed by Jon Postel for the Internet
- Has become a systems principle
- When design, implement, and use a system, for every step,
  - Be tolerant of inputs and strict on outputs (宽进严出)
  - Be tolerant of inputs
    - System should still work when inputs deviate somewhat from “correct” values
  - Be strict on outputs
    - System should generate only “correct” outputs, not deviating from “correct” values
- Implication
  - Accumulation of errors, drifts, and distortions can often be avoided 误差、漂移、失真不会积累

TCP implementations should follow a general principle of robustness: be conservative in what you do, be liberal in what you accept from others.

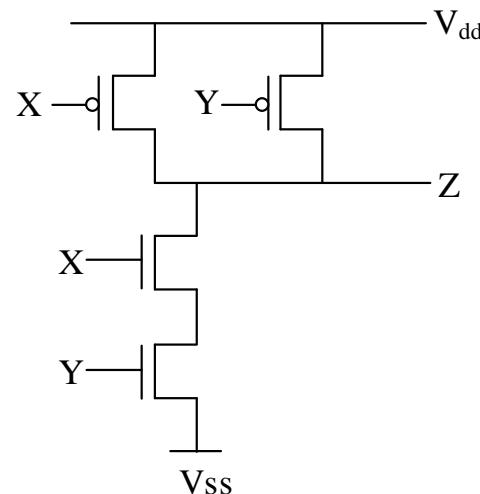
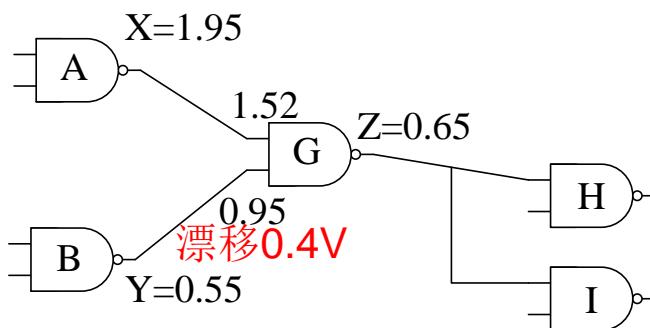
Jon Postel, 1980

Be **strict in outputs**, and be **tolerant of inputs**



# An example

- Consider gate G in the circuit of 5 NAND gates
  - It receives inputs from A, B, and outputs to H, I
    - All NAND gate have the same behavior and been implemented by a CMOS circuit
  - Naïve Design of the CMOS circuit without following Postel's robustness principle **违反波斯特尔鲁棒原理的糟糕设计**
    - There is **gap** near the threshold voltage  $V_{th} = 0.7$  Volt
      - When  $A=HIGH=1.95$  and  $B=LOW=0.55$  Volt, Z should be  $HIGH>0.7$  Volt
      - However, after B drifts +0.4 to reach 0.95 Volt, Z becomes LOW, an **error**

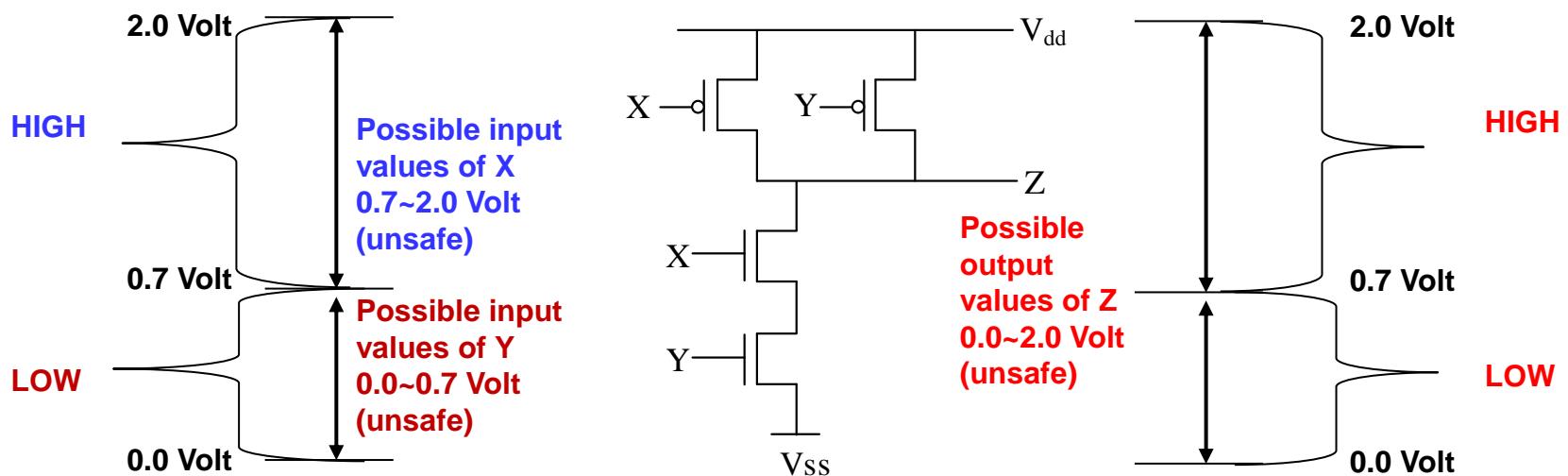


$V_{dd} = 2$  Volt 高电压  
 $V_{ss} = 0$  Volt 低电压  
 $V_{th} = 0.7$  Volt 阈值电压

Naïve Design  
Logic 1:  $> 0.7$  Volt  
Logic 0:  $< 0.7$  Volt

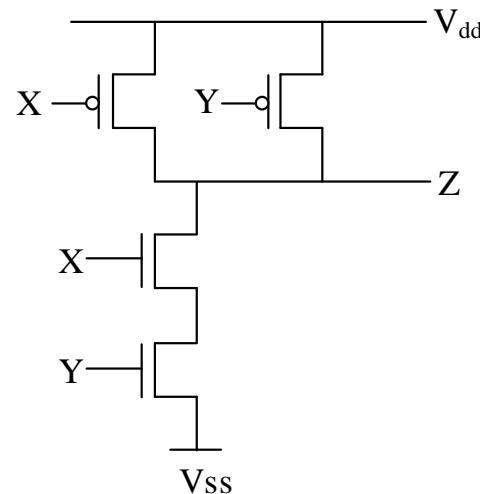
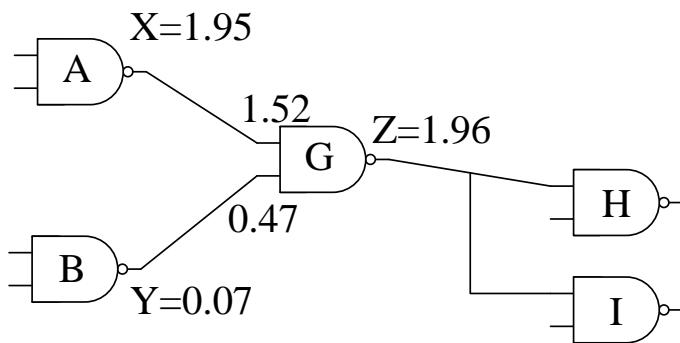
# Summary of Naïve Design

- Assume **X=HIGH** and **Y=LOW**. Then **Z should be HIGH**
  - But, could easily get the wrong result of Z = LOW
- Why?
- Treat inputs and outputs equally, and in a bad way 宽进宽出
  - Both the input side and the output side
    - have **0 minimal gap** between HIGH and LOW
    - have **unsafe margins** of 0.7 Volt for LOW and 1.3 Volt for HIGH



# A better design 遵循波斯特尔鲁棒原理

- The better design following Postel's robustness principle
  - A minimal **gap of 1.0 volt at the input side**
  - A minimal **gap of 1.8 volt at the output side**
  - Note that the output of B cannot be 0.55 Volt. It has to be  $< 0.1$  Volt
  - Let  $B=LOW=0.07 < 0.1$  Volt. Even after a drifting value of +0.4 Volt, G still sees a LOW value, since  $B=0.47$  Volt.
  - Thus, Z is HIGH with  $Z > 1.9$  Volt



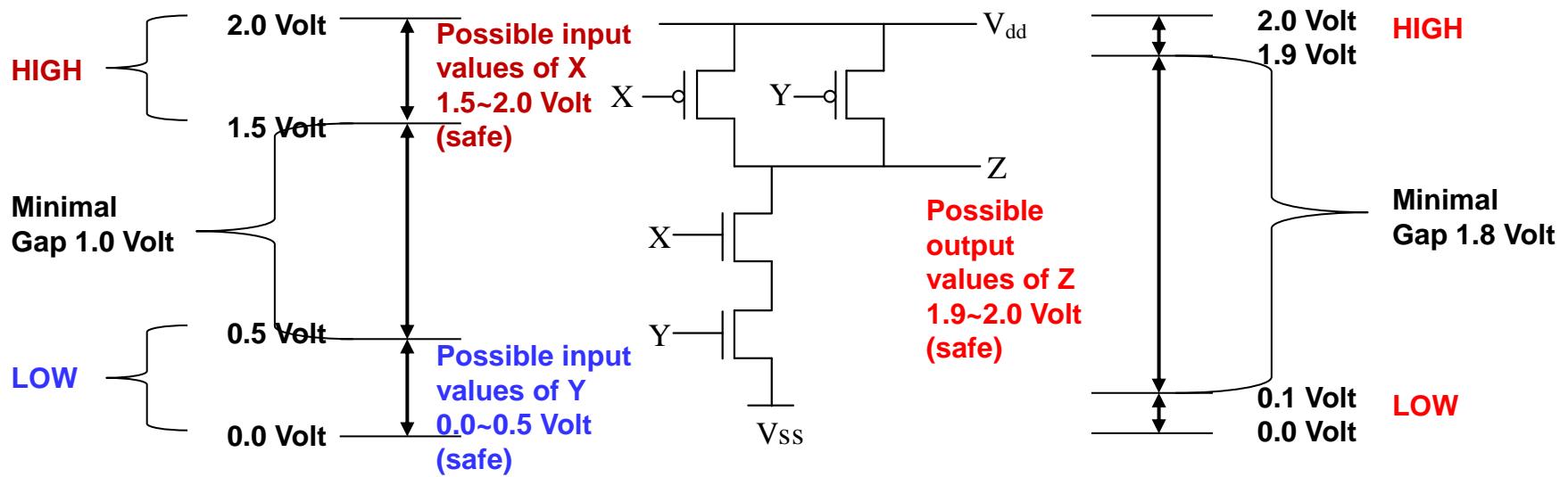
## Better Design

For Input Voltages  
Logic 1:  $> 1.5$  Volt  
Logic 0:  $< 0.5$  Volt

For Output Voltages  
Logic 1:  $> 1.9$  Volt  
Logic 0:  $< 0.1$  Volt

# Summary of Better Design

- Assume **X=HIGH** and **Y=LOW**. Then **Z will be HIGH**
- **Tolerance on inputs 宽进**
  - Input to a gate has a 0.5 Volt safe margin and a minimal gap of 1 Volt
    - Naïve Design: 0.7 and 1.3 unsafe margins and 0 minimal gap
- **Strictness on outputs 严出**
  - Output from a gate has a 0.1 Volt safe margin and a minimal gap of 1.8 Volt
    - Naïve Design: 0.7 and 1.3 unsafe margins and 0 minimal gap



## 5.4 von Neumann's exhaustiveness principle 冯诺依曼穷尽原理

- Computer must be given instructions **in absolutely exhaustive detail** when automatically solving a problem  
当自动解决问题时，必须给计算机指令，穷尽所有细节
- In the quote, two terms have specific meanings
  - *Operation* = Problem-solving Task
    - E.g., solving a non-linear partial differential equation
  - *Device* = Computer
    - An automatic computing system

The instructions which govern this *operation* must be given to the *device* in absolutely exhaustive detail. ...

Once these instructions are given to the device, it must be able to carry them out completely and without any need for further intelligent human intervention.

John von Neumann, 1945

## 5.4 von Neumann's exhaustiveness principle

- Computer must be given instructions in absolutely exhaustive detail when automatically solving a problem

- 1-minute quiz

- Q: How to cover “absolutely exhaustive detail”? 怎么可能穷尽所有细节?
- 可能有无穷多种细节，如何穷尽?
- 使用前述**计算归纳法**
  - Identify first step  
确定第一步
  - Execute single step  
正确执行每一步（当前步骤）  
**应对异常**
  - Identify and transition  
to next step 确定并过渡到下一步

The instructions which govern this operation must be given to the device in absolutely exhaustive detail. ...

Once these instructions are given to the device, it must be able to carry them out completely and without any need for further intelligent human intervention.

John von Neumann, 1945

## 5.4 von Neumann's exhaustiveness principle

- Computer must be given instructions in absolutely exhaustive detail when automatically solving a problem
- 1-minute quiz
  - Q: How to achieve “in absolutely exhaustive detail”? List the types of instructions, and give an example for each type
  - A: Answers to more fundamental questions 必须考虑正常执行和异常执行
    - Where and what is the first instruction, when the computer power is turned on? 开机之后执行的**第一条指令**在哪里？是什么？
    - How to determine the next instruction to execute? 如何确定**下一条指令**？
    - What types of exceptions are there, to normal execution of programs? 如何保证**当前指令**正确执行？  
没有正确执行，只有两种可能：（1）没有正确设计实现；（2）出现**异常**有哪些异常类别？如何应对？

# The first instruction to execute

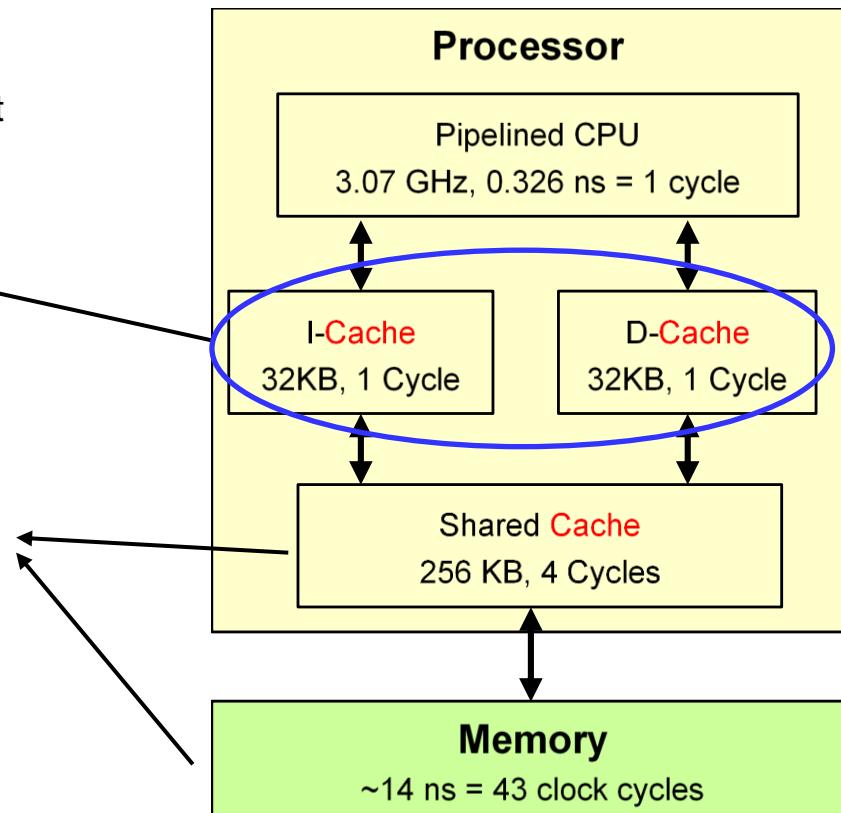
when the computer power turns on

开机后执行的第一条指令：在哪里？是什么？

- Example with an x86 processor **x86处理器例子**
  - Where: the first instruction to execute is at memory address 0xFFFFFFFF0 **在哪里？处理器规定的地址空间的某个高位地址**
  - What: a jump instruction, e.g., JUMP 000F0000 **是什么**
    - Address 000F0000 contains the entry instruction for the BIOS code **跳转指令：跳转到BIOS（最底层系统软件）的入口地址**
- Why? **什么道理？**
  - Computer starts by executing the BIOS firmware code
    - To initialize the computer and to load the operating system **计算机开机后先执行固件，做初始化工作（如自检），然后载入系统软件**
  - Using a jump instruction upfront increases flexibility **跳转指令增加灵活性**
    - E.g., if we want the computer to start by executing another firmware code BIOS-2 at entry address 000FA000, then change
    - Address 0xFFFFFFFF0 to hold JUMP 000FA000

# Three ways to determine 确定下一条指令的方法1 the next instruction to execute

- The earliest method is **linear sequencing** in Harvard Mark I computer, the *Automatic Sequence Controlled Calculator*
  - Instructions are linearly sequenced  
**下一条指令紧跟当前指令**
    - There is no jump. Next instruction is located right after current instruction on the instruction tape
  - Storing data and code separately  
**(This is called Harvard architecture)**  
**哈佛体系结构**
    - Still widely used in the cache units of modern computers. A processor has separate instruction cache and data cache
  - In contrast, the **Princeton architecture**  
**普林斯顿体系结构**  
uses a single cache or memory to store both data and instructions
- Modern computers use both



# Three ways to determine the next instruction to execute

确定下一条指令的方法2、3

- The ENIAC method

ENIAC方法

- Every instruction holds the address of the next instruction

当前指令指明下一条指令的地址

- Used by the revised version of the ENIAC computer

Opcode and operands of current instruction

Address of next instruction

- Modern computers mostly use the PC mechanism: the address of the next instruction to execute is stored in the program counter (PC)

当代计算机采用“程序计数器机制”

PC存放下一条指令的地址

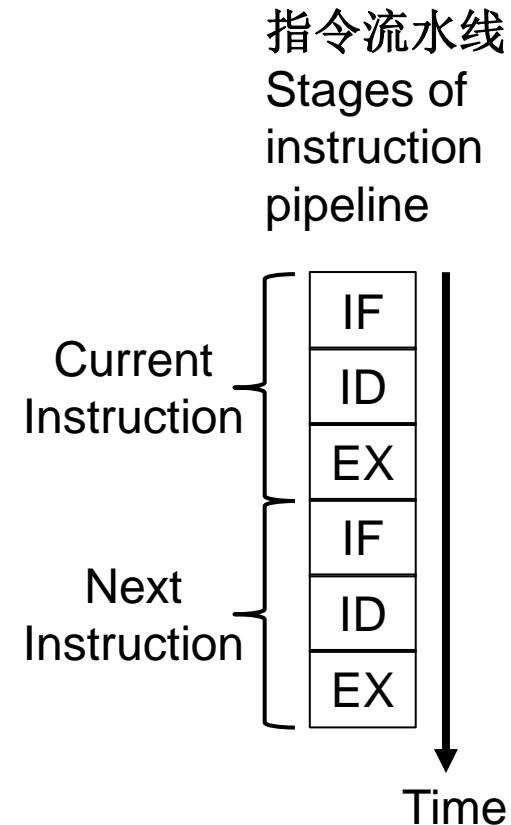
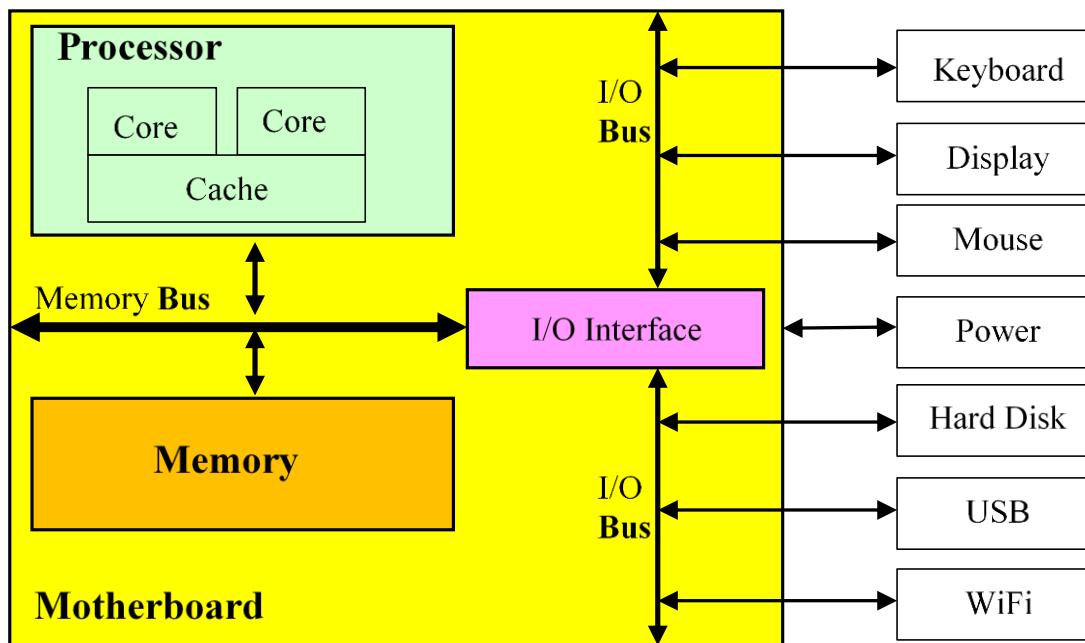
# Deal with exceptions to normal execution

## 应对异常

- 同学们已经体验过了Go语言编程中的异常
  - 读文件可能出错
- We have seen exceptions in programming, e.g., in the Text Hider project, the statement
  - `p, _ := ioutil.ReadFile("./Autumn.bmp")` 例如，文件不存在  
should really be
  - `p, error := ioutil.ReadFile("./Autumn.bmp")`  
`if error != nil {`  
    `...// put exception-handling code here` 出错了，执行异常处理代码  
`}`  
`... // no error; continue normal execution` 无错，继续正常执行

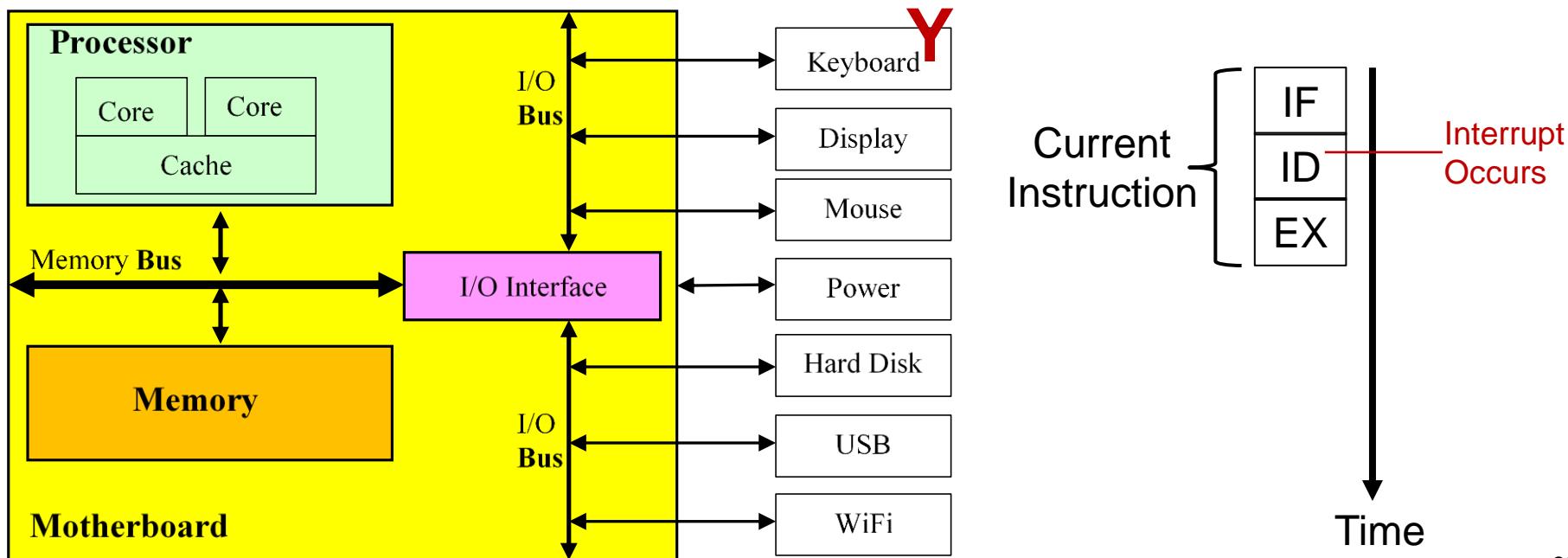
# Three types of exceptions are supported by computer hardware 三种异常

- In normal execution (without exception), the current instruction finishes and continue to execute the next instruction  
正常情况：执行完当前指令，继续执行下一条指令
- 异常情况： (1) 不执行完当前指令； (2) 不执行下一条指令；
  - Interrupt 中断
  - Hardware error 硬件出错
  - Machine check 保底异常



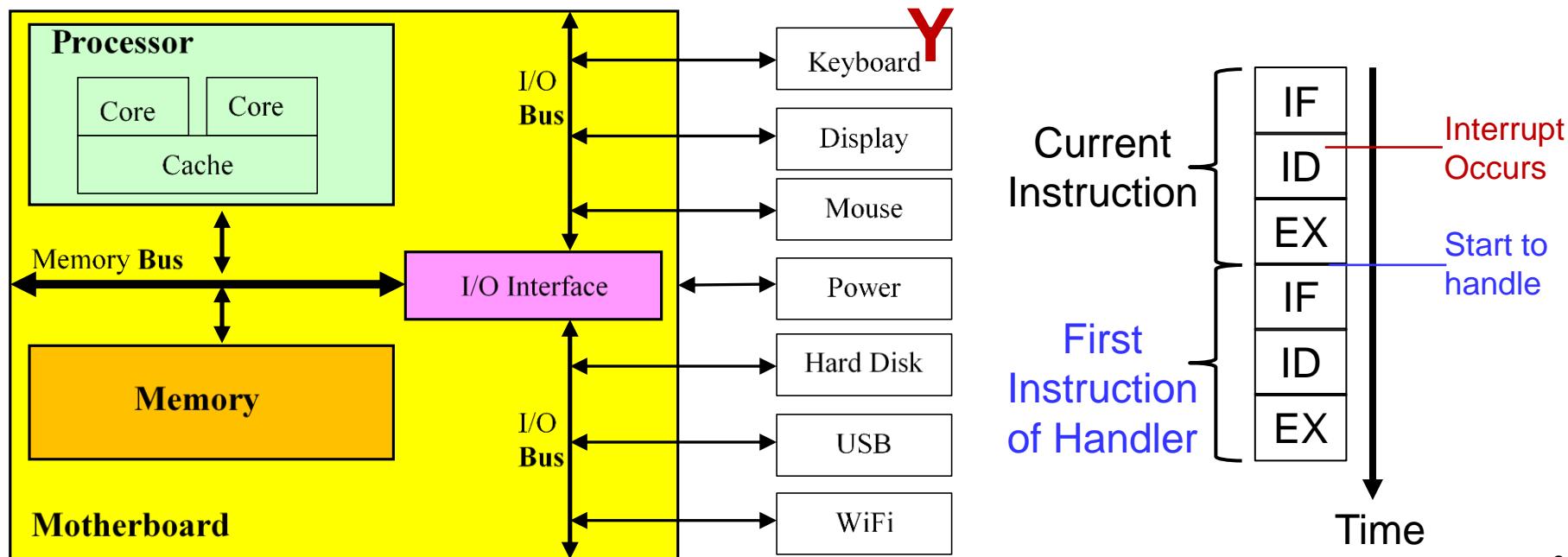
## 5.4.1 Interrupt handling 中断处理

- When an **interrupt** occurs, e.g.,
  - When the user punches key 'Y' on the keyboard 用户敲了'Y'键 while the processor is executing the instruction decode stage
- What should the processor do?
  - Should it immediately take an exception-handling action?
  - Should it finish the current instruction first?



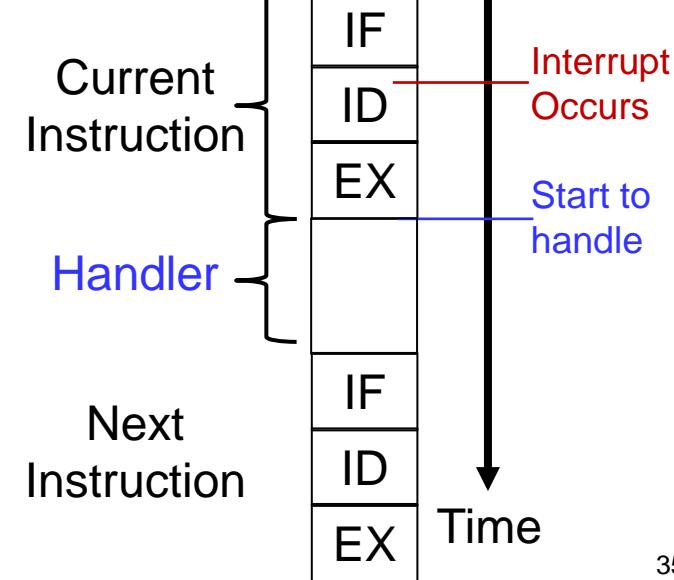
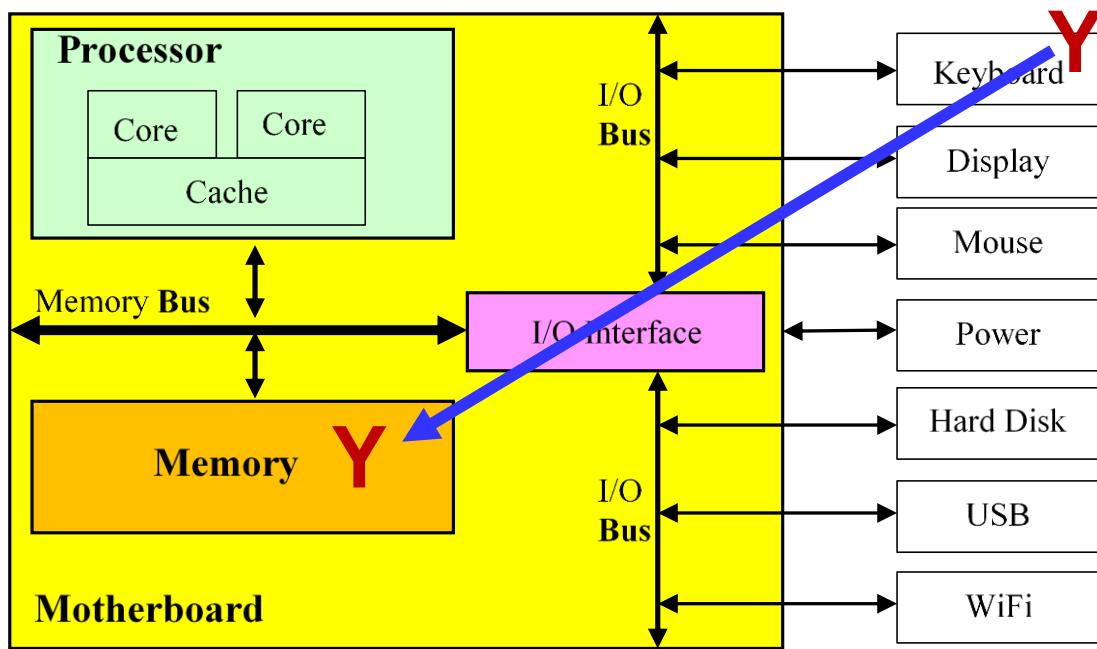
# Interrupt handling

- 继续执行完毕当前指令，然后跳转到中断处理程序的入口
- The processor finishes the current instruction and jumps to an interrupt handling subprogram to handle the interrupt
  - 中断处理程序称为 **interrupt handler**



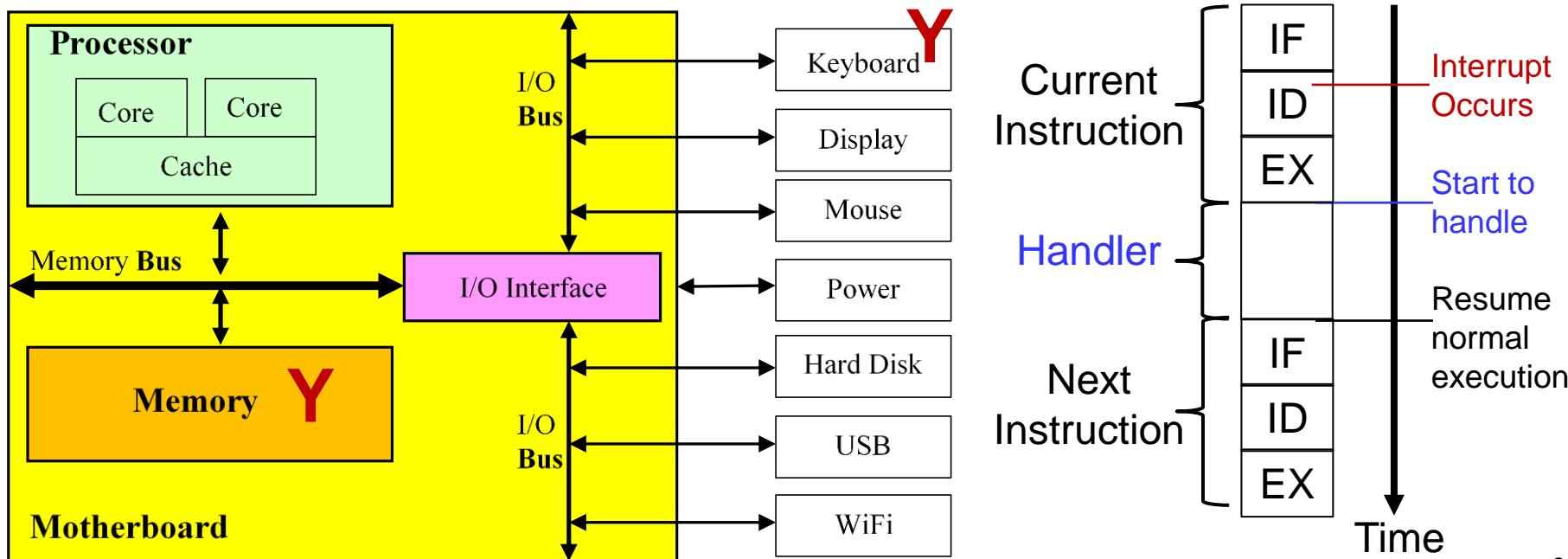
# Interrupt handling

- The processor finishes the current instruction and jumps to an interrupt handling subprogram to handle the interrupt
  - such as **copying the punched key value to memory**  
执行中断处理程序，包括将敲入的键值'Y'拷贝到内存



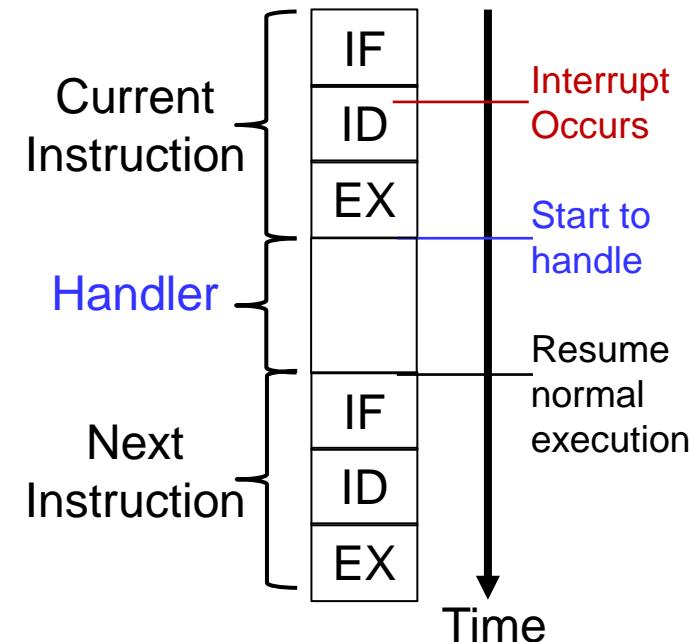
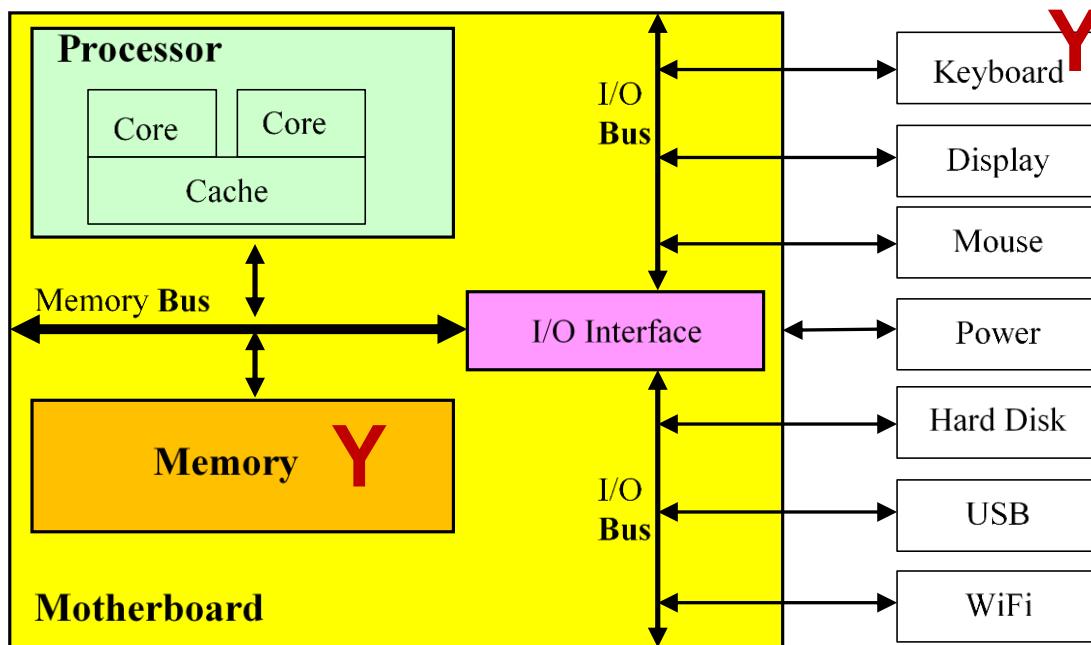
# Interrupt handling

- When an **interrupt** occurs, the processor finishes the current instruction and jumps to an interrupt handling subprogram to handle the interrupt
  - such as **copying the punched key value to memory**
- Then, the processor resumes normal execution
  - by executing the original next instruction  
退出中断处理程序，恢复正常执行原来程序的下一条指令



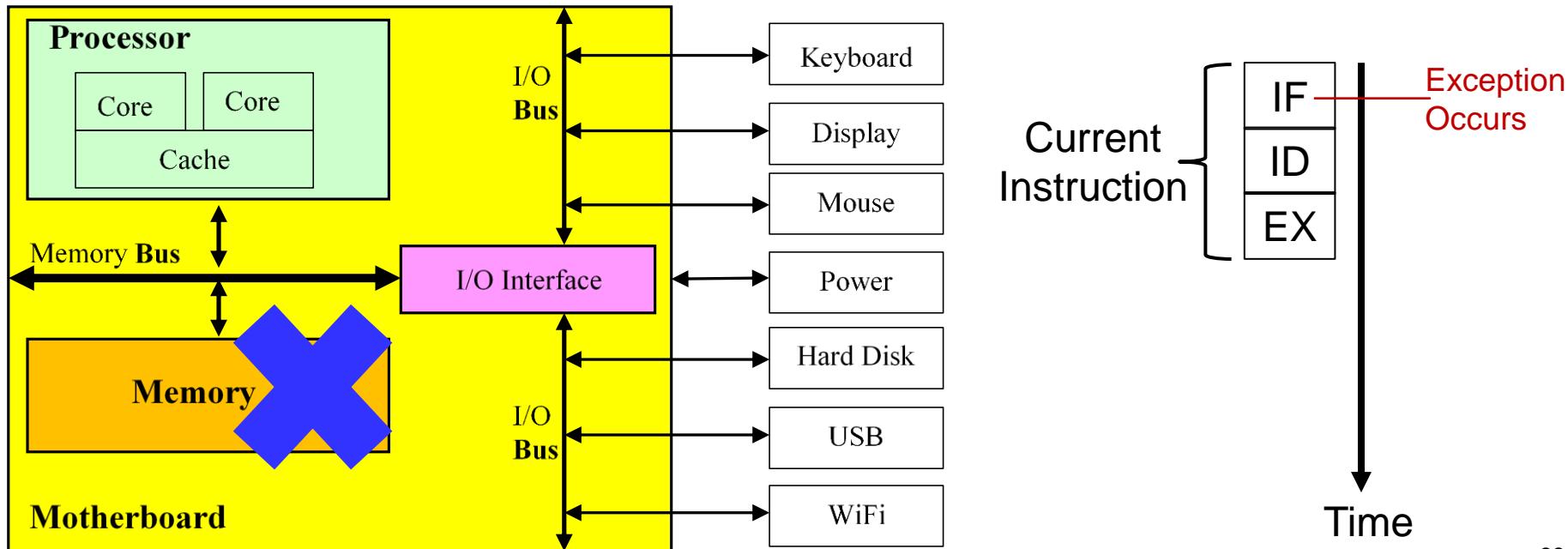
# Interrupt handling

- When an **interrupt** occurs, the processor finishes the current instruction and jumps to an interrupt handling subprogram to handle the interrupt
  - such as **copying the punched key value to memory**
- Then, the processor resumes executing the next instruction
  - Q: how does the processor know the address of the next instruction?
  - A: need to **save context** before executing handler  
进入中断处理程序前，必须保存上下文，知道返回后该执行哪条指令



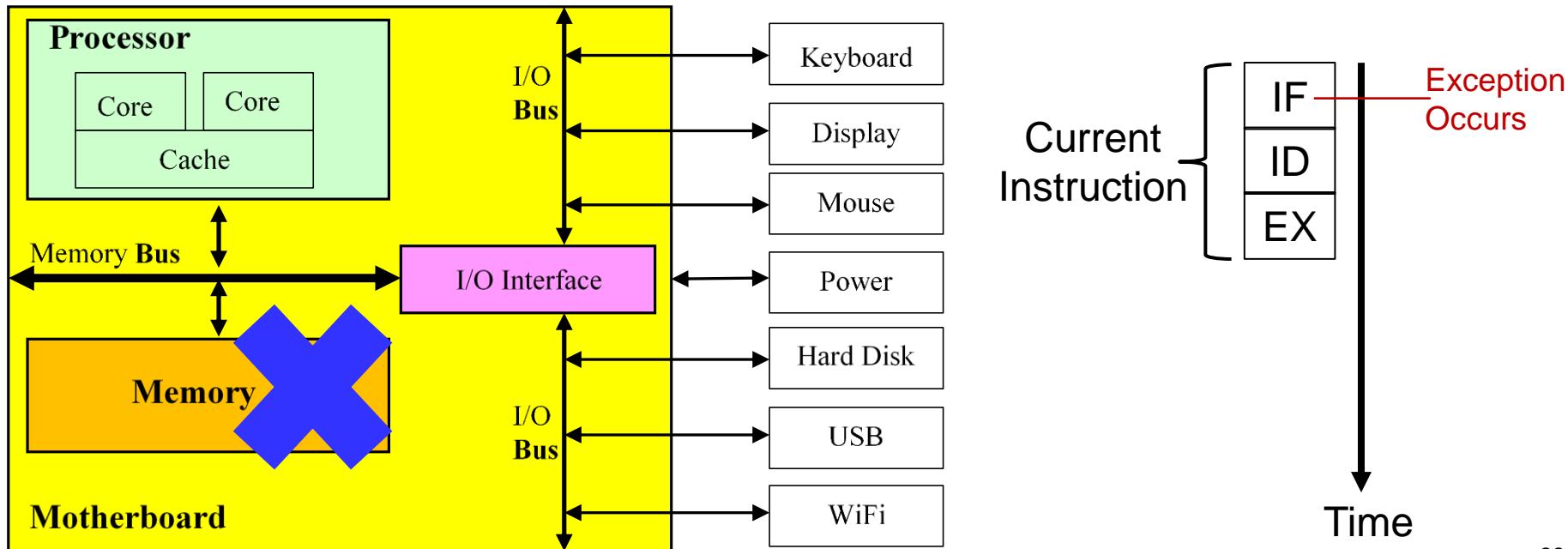
## 5.4.2 Hardware error handling 硬件出错

- When a hardware error occurs, e.g.,
  - When the memory becomes faulty and generates a hardware error exception 例如, 内存条坏了
- What should the processor do?
  - Should it immediately take an exception-handling action?
  - Should it finish the current instruction first?



# Hardware error

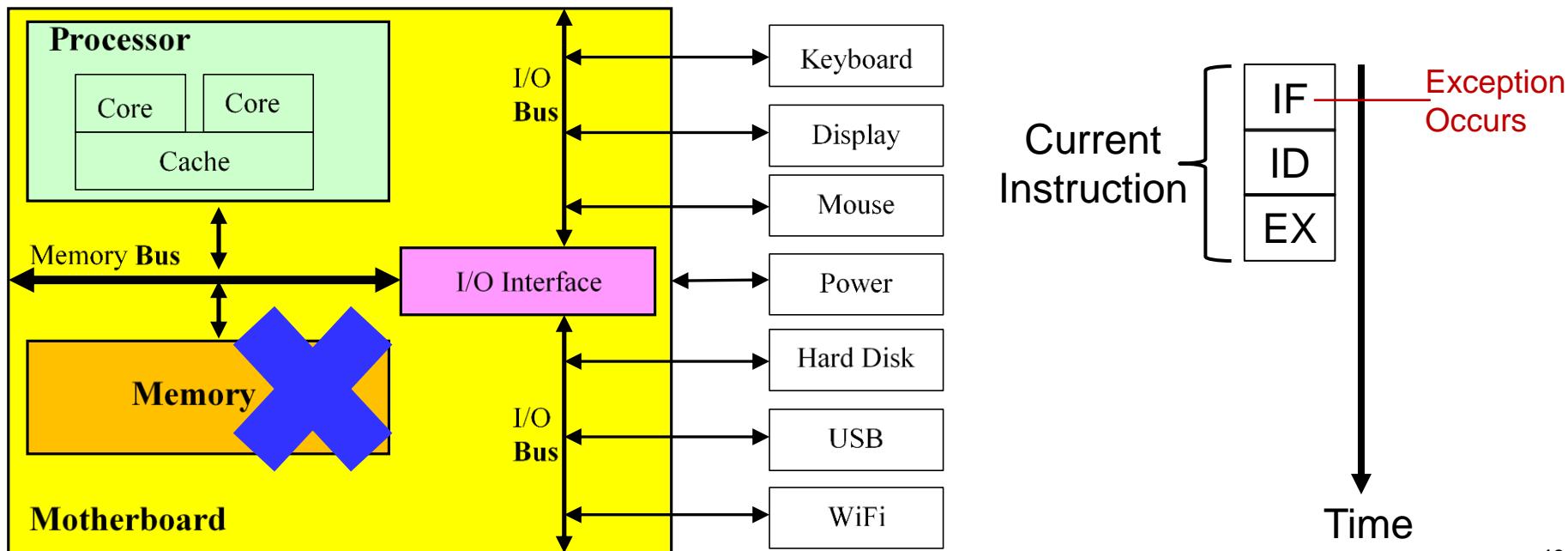
- When the memory becomes faulty and generates a hardware error exception  
内存条坏了
  - Should the processor finish the current instruction first?  
还能够先完成当前指令再“中断”吗?
  - No, because the IF stage cannot be finished
    - The instruction cannot be fetched from memory  
不行！指令都取不回来  
完不成取指（IF）操作



# Hardware error

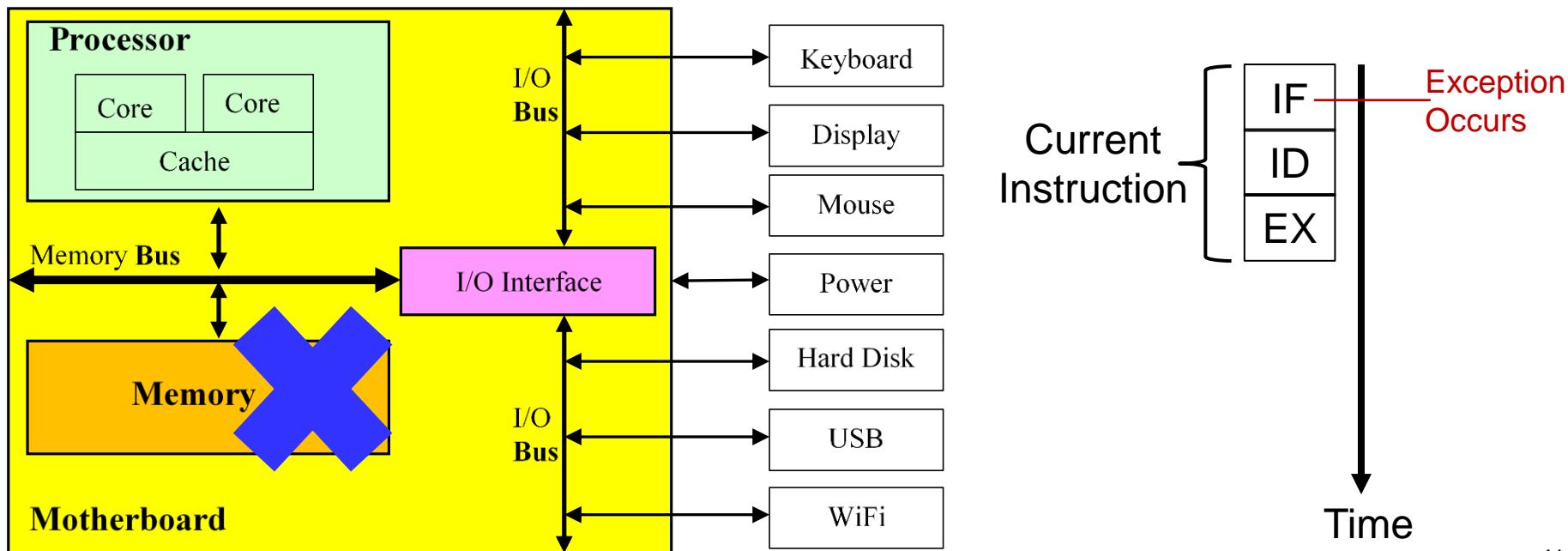
- When the memory becomes faulty and generates a hardware error exception
  - Should the processor immediately take an exception-handling action?
  - Yes, it executes an exception-handling sequence of steps without depending on the memory

立即执行异常处理程序，无需访问内存

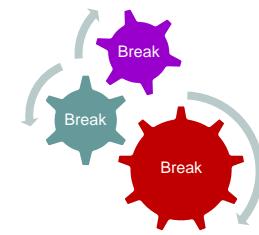


## 5.4.3 Machine check 保底异常

- This is the "all other" exception, for exhaustiveness
  - Typically, an unrecoverable hardware error
- Example
  - While executing an exception-handling sequence of steps for the memory fault, the sequence experiences another error
  - The system generates minimal diagnostic information and crashes  
输出最基本的诊断信息, 宕机



# Take-Home Messages



- Seamless transition of within a computational process is achieved by solving three problems
  - via the symphony of four principles
- Yang's cycle principle, types of cycles
  - The system finishes one cycle and automatically returns to the beginning of the next cycle, so that steps of the computational process preserve their respective kinds
- Postel's robustness principle
  - Each step should be tolerant of inputs and strict on outputs
- von Neumann's exhaustiveness principle
  - Computer must be given instructions in absolutely exhaustive detail when automatically solving a problem
  - To be exhaustive, the system designer must consider first step, next step, normal (correct) execution of current step, and exceptions
  - Exceptions include interrupts, hardware errors, machine checks