1. Study Group Tialiang Tang (myself), SID: 3039758308 Yeanzhe Wang, SID: 3039749520 4. (2) f(1,m) = 1 Because we only need to drop an egg on first floor to decide the ℓ .

f(0,m)=0 Because we don't need to drop any egg.

f(n,1) = n Because we need to drop egg on 1-st.2-nd.

3-rd. , n-th floor successively to determine 1.

f(n,o)=0 Because we have no egg to drop, we can never determine ℓ ! So we define f(n,o) as 0.

If egg breaks, we need to consider floor 1, 2, ..., X-1 and we have m-1 eggs remained to drop.

So we need f(X-1, m-1)

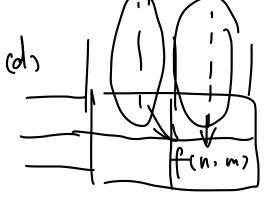
If egg deesn't break, we need to consider floor X+1, X+2, ..., n and we have m eggs still.

So we need f(n-x, m)

(C)
$$f(n,m) = m\bar{n} \left(max \left(f(\bar{i}-1, m-1), f(n-i, m) + 1 \right) \right)$$
 $|sish$

"i means we choose i-th floor to drop

So we need to choose the minimum among floors in worst cases. That's where "min-max" comes from.



To compute f(n,m), we need to f(n,m) compute all f(i-1,m-1) and f(n-i,m).

So the order is: f(2,2), f(3,2),..., f(n,2),

f(2,3), f(3,3),..., f(n,3), ..., f(2,m), f(1,m),...,f(n,m)

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(We already have f(i,i) and f(i,j)i and f(k,o) $= f(\bullet o, w)$

(e) O(mn) subproblems

Each needs O(n) to find value

Total rutine is O(n2m)

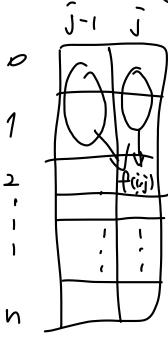
(f) Need a inx m mortrix to Stove results. Total

Space complexity is O(nm)

(9) Possible.

Modification: When running dp, we only need to store the neavest 2 lines of f(i,j) in dp matrix to compute it.

So we only need O(2n) = O(n) space.



5.(2) After any arbitrary cut, we have 2 pieces left and subproblem is to find the smallest cuts on each pieces.

(b) dp[X][y][&][w]: The minimum cut of matrix with left-upper grid (x,y) and right-bottom grid (Z, W).

 $dp[x][y][s][w] = min \left(min \left(dp[x][y][k][w] + dp[k+|][y][s][w] \right) \right)$ $x \le k \le z - 1$ $y \le p < w + 1$ + 1 (z, w) Base cases: dp[x][y][s][w] = 0 for all matrix having all 0 < or 1s.

(C) Firstly every |x| grid is in base cases.

Then we solve every 1x2 and 2x1 rectangles

Then 1x3, 3x1, 2x2 reetangles.

(Each step, we solve cases with 1 more column or 1 more row, but ensure columns <m, rows < n). Then mxn rectangle (which we want to solve)

(d) Subproblems: $O(m^2n^2)$ (The number of possible rectangles is $C_n \cdot C_n^2 = O(m^2n^2)$)

For each subproblem, we need O(m+n) to determine the dp value. But still need O(mn) to judge whether it's a base case.

Total Runtime: $O(m^2n^2, mn) = O(m^3n^3)$.

(e) All we need is a 4-dim matrix to store the result.

Space complexity is O(m2n2)

2 (a) Algorithm Description:

DSubproblems

Assume J(s): True if s is possible to be interpreted.

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Subproblem is to judge whether sub-string Si and Sz are able to be interpreted.

2 Recorrence

$$J(s) = \left(\bigvee_{S=S_1 \circ S_2} J(S_2) \right) \vee False \quad \text{(when } s \neq base \ case \text{)}$$

$$S_1 \in d[1]$$

Base cases: J(s)=True iff sedCD. (Can be directly interpreted)

3 Ordering: For Isisn, judge J(s[n-i:n-1])

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Proof or correctness:

If s is interpretable, then $S = S_1 \circ S_2 \circ \cdots \circ S_K$, $S_i \in d[i]$. So $J(S_K) = T_{ne}$, then we have $J(S_{K-1} \circ S_K) = (S_{K+1} \in d[i]) \land J(S_1) = T_{ne}$, then $J(S_1) = J(S_1 \circ \cdots \circ S_K) = (S_1 \in d[i]) \land J(S_2 \circ \cdots \circ S_K)$ = True, so ne'll always return Ime.

If s isn't interpretable. Assume by contradiction that we return True on S. Then J(s) = True. s is never a base case. So $J(s) = (S_1 \in dI_1) \wedge J(S_2) = (S_1 \in dI_1) \wedge ... \wedge (for some s_1) \qquad (for some s_1, ..., s_k)$ (Sk $\in dI_1J) = True \cdot S_0 \cdot S = S_1 \circ S_2 \circ ... \circ S_k \cdot each \cdot S_i \in dI_1J \cdot S_0 \cdot S_i \cdot s_i \cdot s_i \cdot s_i \cdot s_i$ Contradiction!

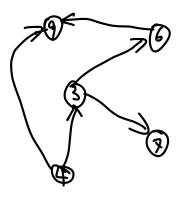
So our algorithm returns True iff s is interpretable.

Runtime Analysis: We have O(n) subproblems.

In each subproblem, we make O(k) compartisons of all elements in dti) and the prefix of current string. Each comparison takes U(1) time.

So total rantime is O(nkd).

Space Analysis: Duly need a n-length space to store our results. So total space complexity is O(n). 3.



Algorithm Description: Topological sort the graph.

Compute every T[v] in tenerse order of \$000-sort.



(T[v]: target of v)

OSnbproblem: When we consider a vertex V, it only has targets behind it in the topo-order. So we use the nodes behind it as subproblems to compute it sprecisely, nodes behind it and have edges with it)

@ Recumence

Use an array M[v] to store s[T[v]].

T[v] = $\begin{cases} argmax \\ M(u) \end{cases}$, if max(M(n)) > s[v] $(v,u) \in E$ and there exists $(v,u) \in E$ v, otherwise

T[u] = u. (Bose Case) (uis the last vertex in top-order) B Ordering: Compute T[v] by the reverse topo-order.

Runtime Analysis: Topological Sort: O(n+m)

Subproblems: ()(n)

Each subproblem we take () (out-degree (v)) time

So total runtime is O(n+m), which is linear.

(n=|V|, m=|E|).