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# An Introduction to Matlab

## Fall 2018

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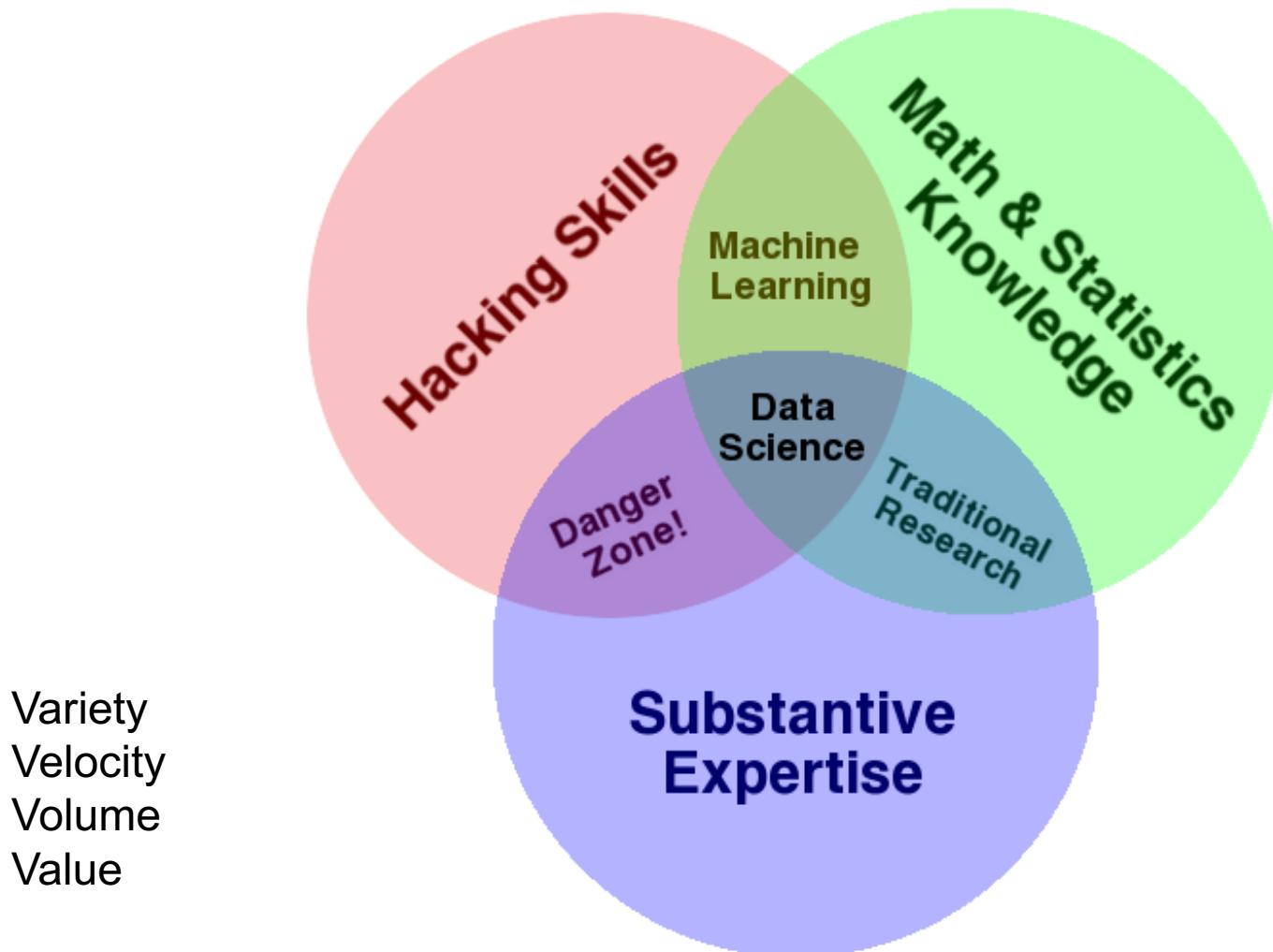
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San Diego State University

# THE DATA SCIENCE VENN DIAGRAM

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<http://drewconway.com/zia/2013/3/26/the-data-science-venn-diagram>

# A 10 minutes Introduction to Matlab

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- MatLab is a powerful software created by MathWorks, which is used extensively in mathematics, engineering, and the sciences.
- MatLab stands for Matrix Laboratory.

Three key capabilities are

1. Computing
  2. Visualizations (or Graphics)
  3. Symbolic computation (or computer algebra)
- Symbolic plotting (to get plots for symbolic functions)

References:

- <http://www-rohan.sdsu.edu/~jmahaffy/courses/f15/math337/Lectures.html>
- [http://www-rohan.sdsu.edu/~jmahaffy/courses/f15/math337/beamer/matlab/basic\\_matlab.pdf](http://www-rohan.sdsu.edu/~jmahaffy/courses/f15/math337/beamer/matlab/basic_matlab.pdf)
- [http://www.mathworks.com/help/pdf\\_doc/matlab/getstart.pdf](http://www.mathworks.com/help/pdf_doc/matlab/getstart.pdf)
- <http://www.maths.dundee.ac.uk/ftp/na-reports/MatlabNotes.pdf>
- [http://www.mathworks.com/academia/student\\_center/tutorials/launchpad.html](http://www.mathworks.com/academia/student_center/tutorials/launchpad.html)

# Matlab and Mathematical Software

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- Many forms of general-purpose numerical software are available commercially and in the public domain. Most of the early software was written for mainframe computers. Now that personal computers are sufficiently powerful, standard numerical software is available for them. **Most of this numerical software is written in FORTRAN, although some packages are written in C, C++, and FORTRAN90.**
- ALGOL procedures were presented for matrix computations in 1971 in [WR]. A package of **FORTRAN** subroutines based mainly on the ALGOL procedures was then developed into the **EISPACK** routines.
- **LINPACK** is a package of **FORTRAN** subroutines for analyzing and solving systems of linear equations and solving linear least squares problems.
- **MATLAB** was originally written to provide easy access to matrix software developed in the LINPACK and EISPACK projects. The first version was written in the late 1970s for use in courses in matrix theory, linear algebra, and numerical analysis. There are currently more than 500,000 users of MATLAB in more than 100 countries.
- In addition to Matlab, Maple (developed in 1980) and Mathematica (released in 1988) are equally popular.

## *References:*

*Burden, R., D. Faires and A. Burden, 2015: Numerical Analysis. Cengage Learning. 912pp. 10<sup>th</sup> ed. Jan. 2015.*

# Symbolic Computation: Differential and Integral Calculus

---

```
syms x
```

%In Symbolic Math Toolbox™, symbolic variables are complex variables by default.

```
y=x^5
```

```
diff (y, x)
```

```
→ 5*x^4
```

  
=====

```
syms x n real
```

#assumption

```
y=x^n
```

```
diff (y, x)
```

```
→ ans =
```

```
n*x^(n - 1)
```

  
=====

```
assume (n>0)
```

```
int(y,x)
```

```
→ ans =
```

```
x^(n + 1)/(n + 1)
```



## Symbolic Computation: the Inner Product (Section 12.3)

---

```
syms x y z
```

#In Symbolic Math Toolbox™, symbolic variables are complex variables by default.

```
r=[x, y, z]
```

```
syms x0 y0 z0
```

```
r0=[x0, y0, z0]
```

```
syms a b c real
```

#assumption

```
n=[a, b, c]
```

```
dot (n, r-r0)
```

```
→ a*(x - x0) + b*(y - y0) + c*(z - z0)
```

## Symbolic Computation: the Cross Product (Section 12.4)

---

```
syms p1 p2 p3 real
```

%In Symbolic Math Toolbox™, symbolic variables are complex variables by default.

```
P=[p1, p2, p3]
```

```
syms q1 q2 q3 real
```

```
Q =[q1, q2, q3]
```

```
syms r1 r2 r3 real
```

```
R =[r1, r2, r3]
```

```
n=cross(Q-P, R-P) %PQ x PR
```

```
dot (n, r-r0)
```

```
→((p2 - q2)*(p3 - r3) - (p3 - q3)*(p2 - r2))*(x - x0) - ((p1 - q1)*(p3 - r3) - (p3 - q3)*(p1 - r1))*(y - y0) + ((p1 - q1)*(p2 - r2) - (p2 - q2)*(p1 - r1))*(z - z0)
```

```
syms x y z real
```

```
X=[x, y, z]
```

```
planefunction = dot (n, X-P) %PX*n
```

## Section 12.6: Cylinders and Quadric Surface using ezsurf of MatLab

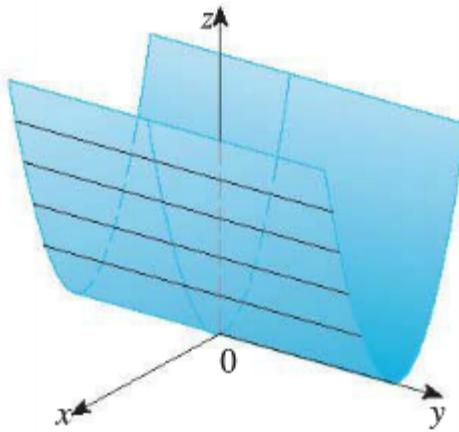
- A **cylinder** is a surface that consists of all lines (called rulings) that are parallel to a given line and pass through a given plane curve.
- A **quadric surface** is the graph of a second-degree equation in three variables (x, y, z).

$$Ax^2 + Bx^2 + Cx^2 + Dxy + Eyz + Fxz + Gx + Hy + Iz + J = 0$$

Easy-to-use 3-D colored surface plotter

- `ezsurf(fun)`
- `ezsurf(funx,funy,funz)`
- `ezsurf(...,'circ')`

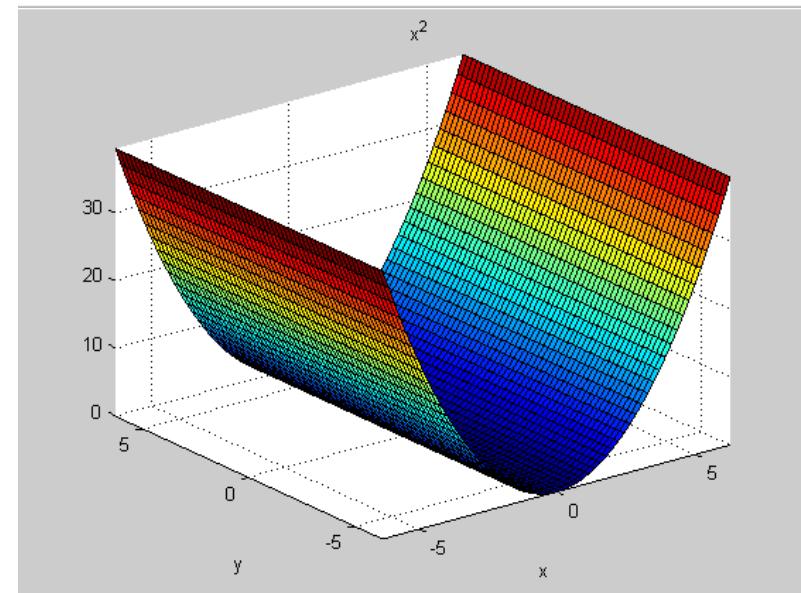
**EXAMPLE 1** Sketch the graph of the surface  $z = x^2$ .



The rulings of the cylinder are parallel to the y-axis.

**FIGURE 1**

The surface  $z = x^2$  is a parabolic cylinder.



## Section 12.6: Cylinders and Quadric Surface using ezsurf of MatLab

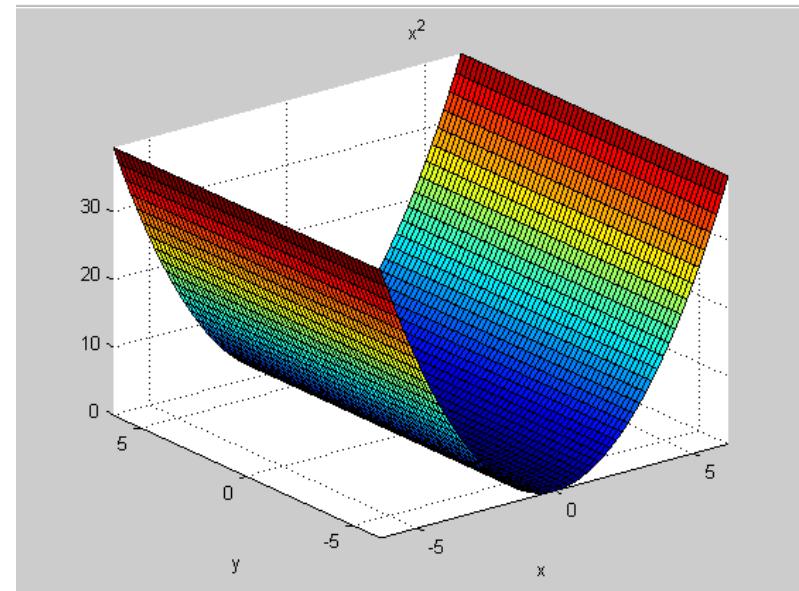
Easy-to-use 3-D colored surface plotter

- `ezsurf(fun)`
- `ezsurf(funx,funy,funz)`
- `ezsurf(...,'circ')`

```
syms x y z  
ezsurf(x^2)
```

**EXAMPLE 1** Sketch the graph of the surface  $z = x^2$ .

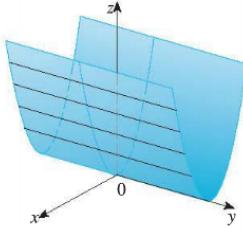
- The rulings of the cylinder are parallel to the y-axis.



# Section 12.6: Surface plots

```
syms x y z  
ezsurf(x^2)
```

**EXAMPLE 1** Sketch the graph of the surface  $z = x^2$ .



parabolic cylinder

rulings: parallel to the y-axis

```
syms t  
x=cos(t)  
y=sin(t)  
ezsurf(x,y,z)
```

**EXAMPLE 2** Identify and sketch

(a)  $x^2 + y^2 = 1$

axis: the z-axis

rulings: vertical lines  
given curve: the circle

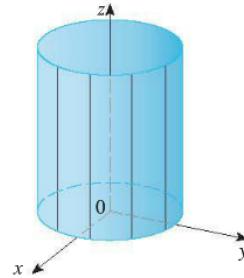


FIGURE 2  $x^2 + y^2 = 1$

```
syms t x y z  
y=cos(t)  
z=sin(t)  
ezsurf(x,y,z)
```

(b)  $y^2 + z^2 = 1$

axis: the x-axis

rulings: parallel to the axis

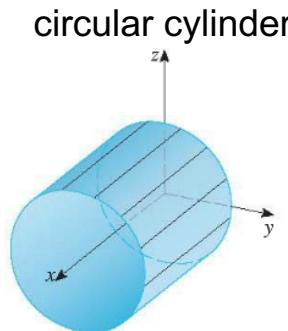
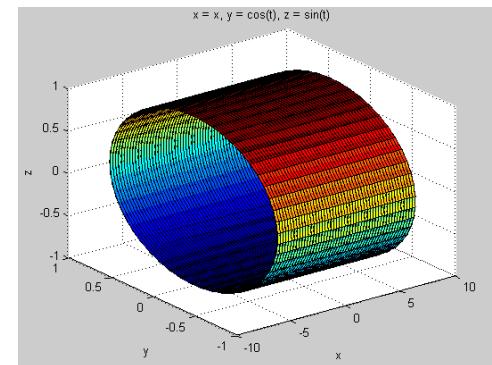
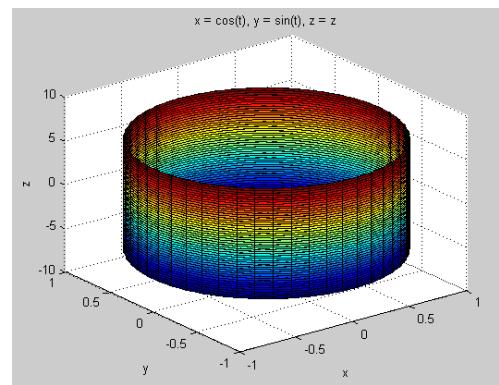
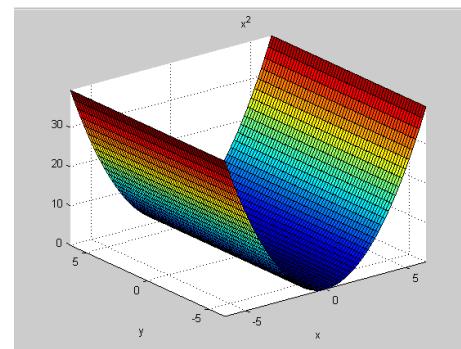


FIGURE 3  $y^2 + z^2 = 1$



## Section 12.6: Surface plots

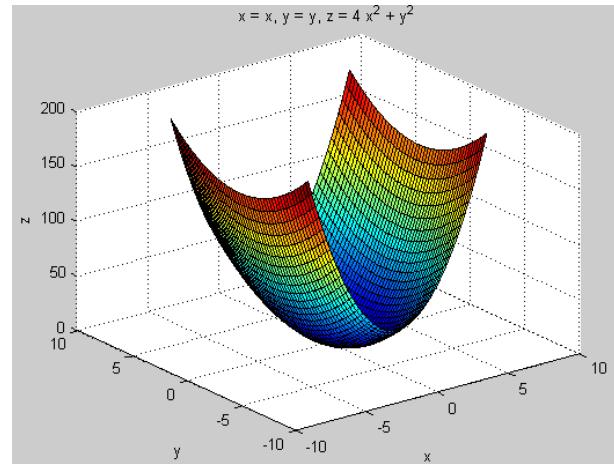
**EXAMPLE 4** Use traces to sketch the surface  $z = 4x^2 + y^2$ .

```
syms x y z
```

$$z=4*x^2 + y^2$$

```
ezsurf(x, y, z)
```

elliptic paraboloid

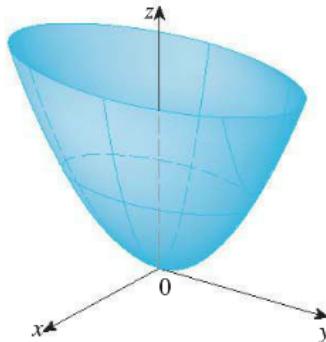


```
syms x y z t
```

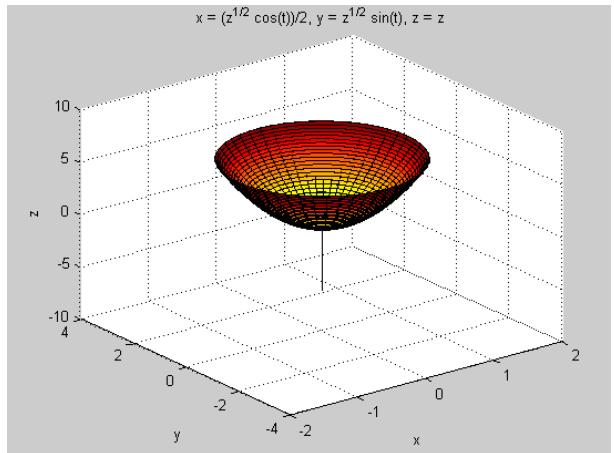
$$x=\sqrt{z}/2*\cos(t)$$

$$y=\sqrt{z}*\sin(t)$$

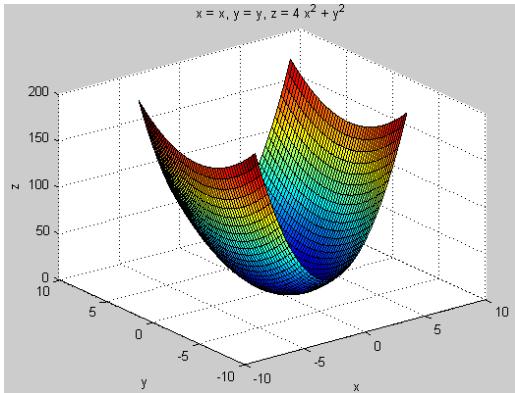
```
ezsurf(x,y,z)
```



**FIGURE 5**  
The surface  $z = 4x^2 + y^2$  is an elliptic paraboloid. Horizontal traces are ellipses; vertical traces are parabolas.

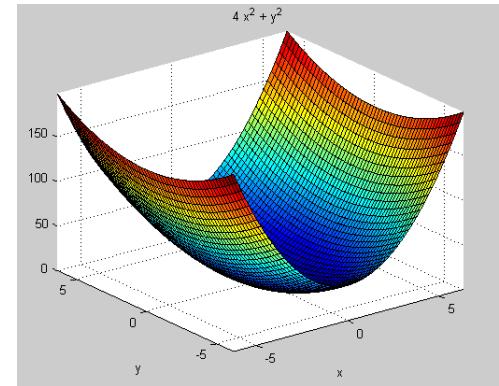


# Section 12.6: Surface plots



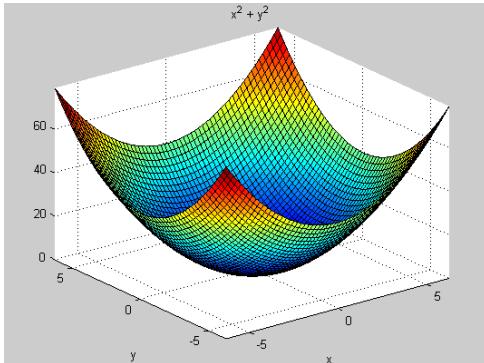
$$z = 4x^2 + y^2.$$

(left, top)  
syms x y z  
 $z=4*x^2 + y^2$   
ezsurf(x, y, z)

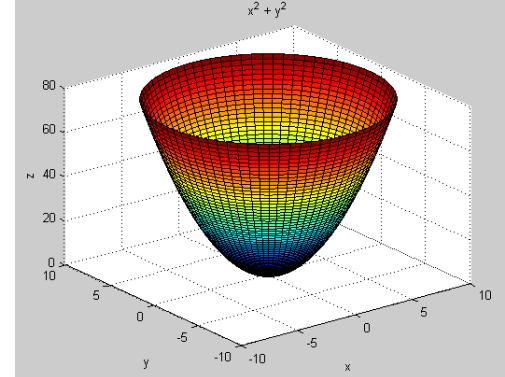


$$x^2 + y^2 = 1$$

(left, bottom)  
syms x y z  
ezsurf(x^2 + y^2)



(right, bottom)  
syms x y z  
ezsurf(x^2+y^2, 'circ')



%ezsurf(...,'circ') plots fun ("function") over a disk centered on the domain.

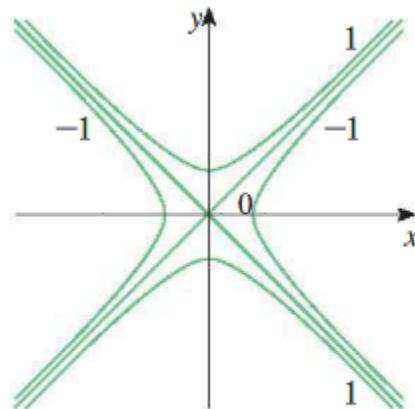
## Section 12.6: Surface plots

**EXAMPLE 5** Sketch the surface  $z = y^2 - x^2$ .

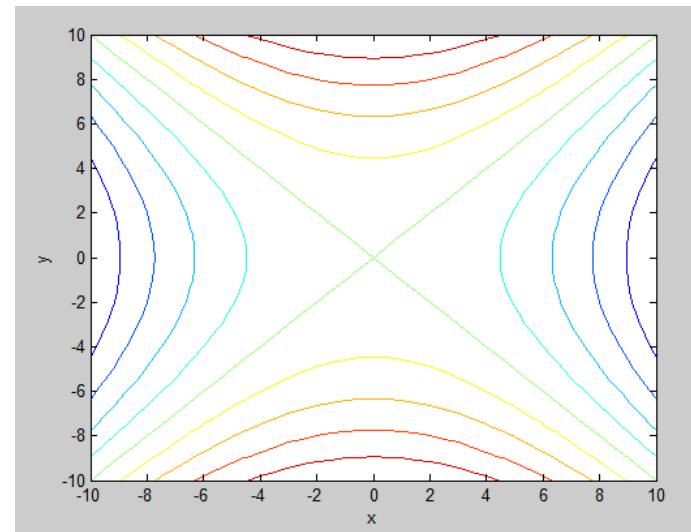
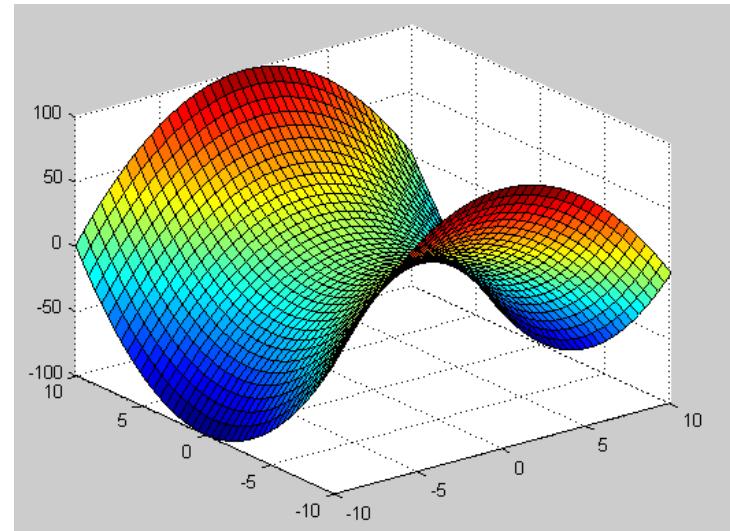
```
syms x y z  
ezsurf(y^2-x^2)
```

hyperbolic paraboloid

```
%Hyperbolic paraboloid  
x = [-10:.5:10]; y=[-10:.5:10];  
[X, Y] = meshgrid(x,y);  
Z = Y.^2-X.^2;  
surf(X,Y,Z)  
contour(X,Y,Z)  
xlabel x  
ylabel y  
zlabel z
```



Traces in  $z = k$  are  $y^2 - x^2 = k$



## Section 12.6: Surface plots

**EXAMPLE 3** Use traces to sketch the quadric surface with equation

$$x^2 + \frac{y^2}{9} + \frac{z^2}{4} = 1$$

syms x y z phi theta real

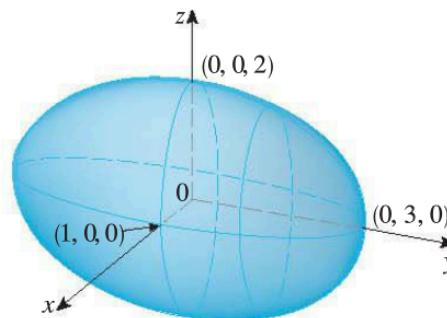
$$x=\sin(\phi)\cos(\theta)$$

$$y=1/3\sin(\phi)\sin(\theta)$$

$$z=1/2\cos(\phi)$$

ezsurf(x, y, z)

ellipsoid



**FIGURE 4**

The ellipsoid  $x^2 + \frac{y^2}{9} + \frac{z^2}{4} = 1$

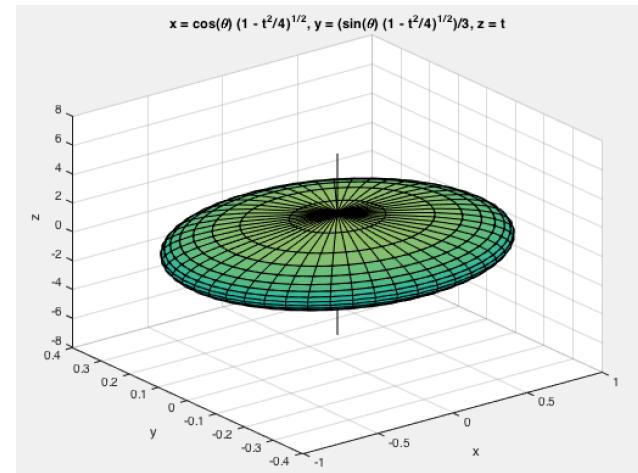
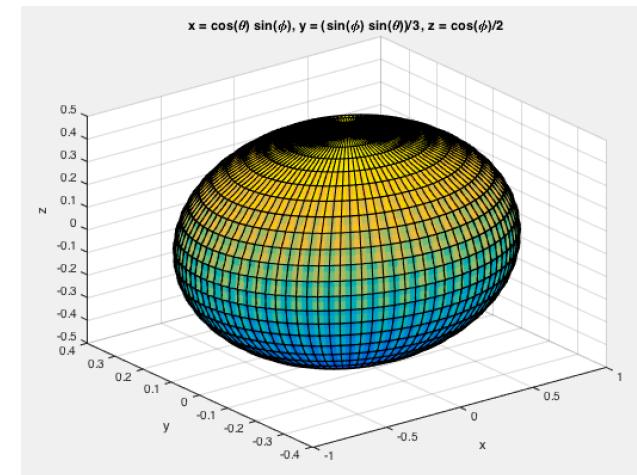
syms x y z t theta

$$z=t$$

$$x=\sqrt{1-t^2/4}\cos(\theta)$$

$$y=1/3\sqrt{1-t^2/4}\sin(\theta)$$

ezsurf(x, y, z)



## Section 12.6: Surface plots

**EXAMPLE 6** Sketch the surface  $\frac{x^2}{4} + y^2 - \frac{z^2}{4} = 1$ .

```
syms x y z t theta
```

```
z=t
```

```
x=2*sqrt(1+t^2/4)*cos(theta)
```

```
y=sqrt(1+t^2/4)*sin(theta)
```

```
ezsurf(x, y, z)
```

Hyperboloid of One Sheet

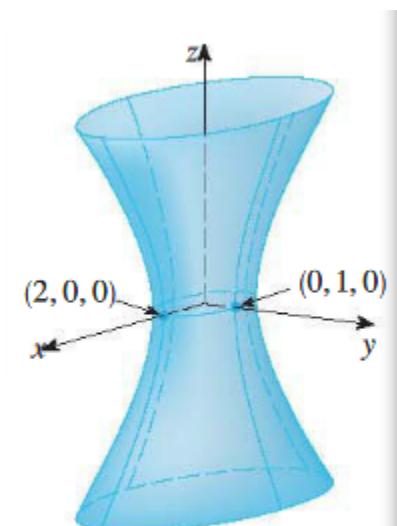
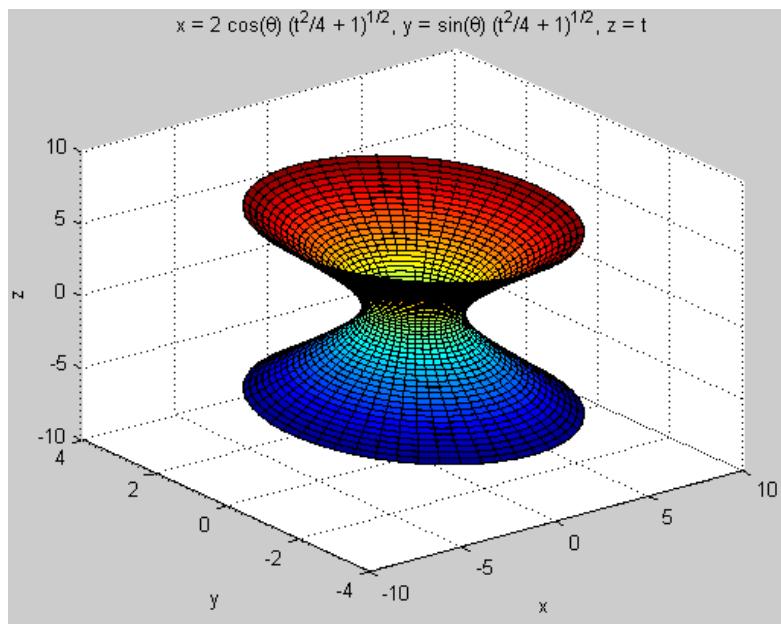


FIGURE 9

# The Top Programming Languages 2016

IEEE  
Spectrum  
  
Enterprise

Language Types (click to hide)



Web



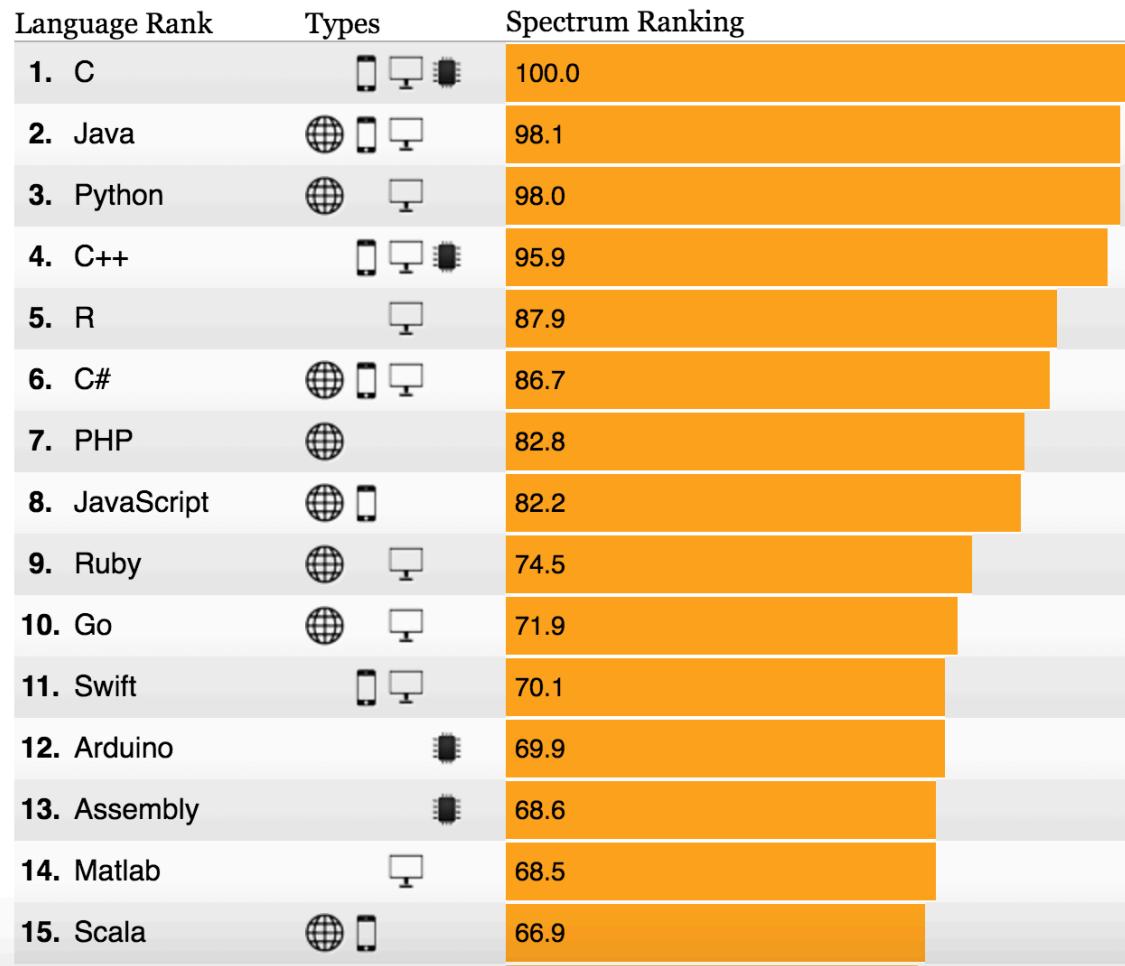
Mobile



Enterprise



Embedded



# Python Facts

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- Python is an open-source, high-level, OOP scripting languages;
- Python Is a widely used, general-purpose, interpreted language;
- Python is similar to MATLAB;
- Python is recommended by the Raspberry Pi Foundation

# The Top Programming Languages 2017

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So what are the Top Ten Languages for the typical *Spectrum* reader?

Language Rank	Types	Spectrum Ranking
1. Python	🌐💻	100.0
2. C	📱💻⚙️	99.7
3. Java	🌐📱💻	99.5
4. C++	📱💻⚙️	97.1
5. C#	🌐📱💻	87.7
6. R	💻	87.7
7. JavaScript	🌐📱	85.6
8. PHP	🌐	81.2
9. Go	🌐💻	75.1
10. Swift	📱💻	73.7

# Python Facts

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Python is often used for

- symbolic computation,
- scientific computing and plotting,
- multi-tasking (i.e., fork),
- multi-threading,
- network programming (TCP/IP, IPC),
- MPI parallel computing,
- web development, and
- game programming.

# Symbolic Computation in Python

---

```
from sympy import *
x,y,z=symbols("x y z")
y=x**6
#y=x^5, error
ans1=diff(y,x)
print(ans1)
```

→  $6x^5$

```
#  
#
ans2=integrate(y,x)
print(ans2)
```

→  $x^7/7$

```
#  
#
simplify(ans2)
#
```

```
from sympy import *
x,y,z, n=symbols("x y z n")
y=x**n
#y=x^5, error
ans1=diff(y,x)
print(ans1)
```

→  $n x^{n-1}$

```
#  
#
ans2=integrate(y,x)
print(ans2)
```

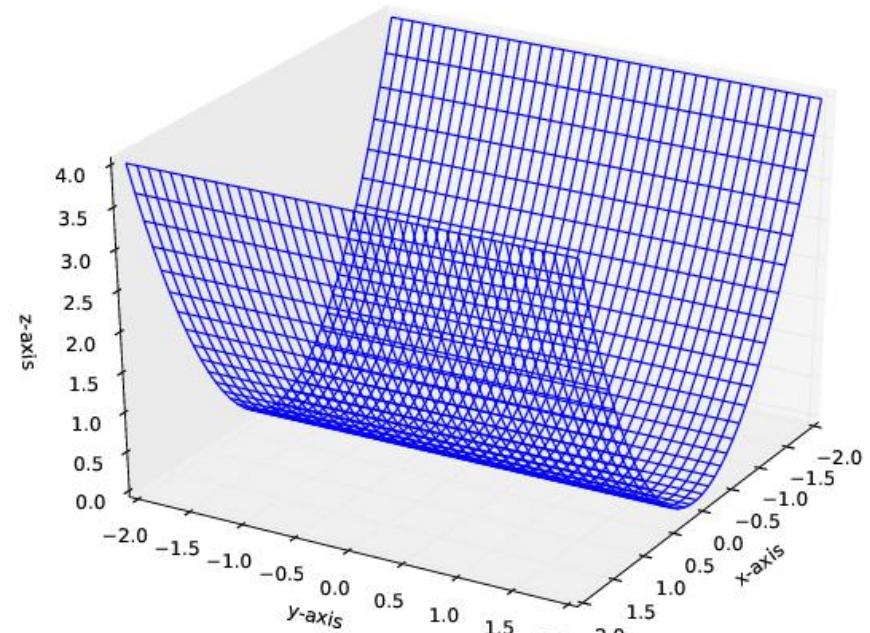
→  $\text{Piecewise}(\log(x), n == -1), (x^{n+1}/(n+1), \text{True})$

```
#  
#
simplify(ans2)
#
```

# Ex1 in Python

**EXAMPLE 1** Sketch the graph of the surface  $z = x^2$ .

```
from mpl_toolkits.mplot3d import axes3d  
import matplotlib.pyplot as plt  
import numpy as np  
  
fig=plt.figure()  
ax=axes3d.Axes3D(fig,azim=30,elev=30)  
  
x=np.linspace(-2,2,40)  
y=np.linspace(-2,2,40)  
  
X, Y=np.meshgrid(x,y)  
Z=X**2  
  
ax.plot_wireframe(X,Y,Z)  
ax.set_xlabel('x-axis')  
ax.set_ylabel('y-axis')  
ax.set_zlabel('z-axis')  
  
plt.savefig('ex1.ps')  
plt.show()
```



# Ex2 in Python

```
from mpl_toolkits.mplot3d import axes3d  
import matplotlib.pyplot as plt  
import numpy as np
```

```
fig=plt.figure()  
ax=axes3d.Axes3D(fig,azim=30,elev=30)
```

```
x=np.linspace(-1,1,40)  
z=np.linspace(-2,2,40)
```

```
X, Z=np.meshgrid(x,z)  
Y=np.sqrt(1-X**2)
```

```
ax.plot_wireframe(X,Y,Z)  
ax.plot_wireframe(X,-Y,Z)
```

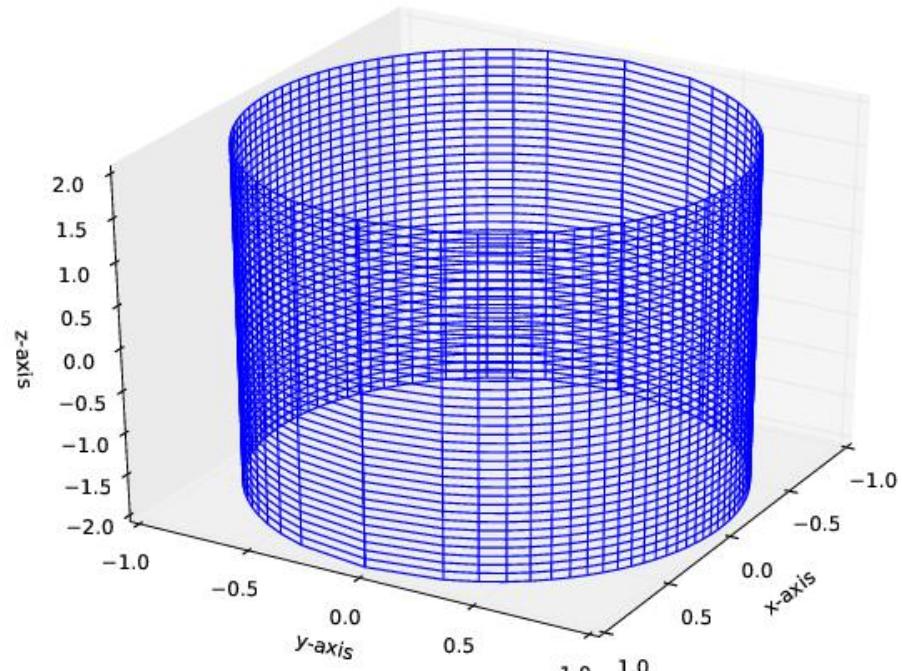
```
ax.set_xlabel('x-axis')  
ax.set_ylabel('y-axis')  
ax.set_zlabel('z-axis')
```

```
plt.savefig('ex2.ps')  
plt.show()
```

**EXAMPLE 2** Identify and sketch the surfaces.

(a)  $x^2 + y^2 = 1$

(b)  $y^2 + z^2 = 1$



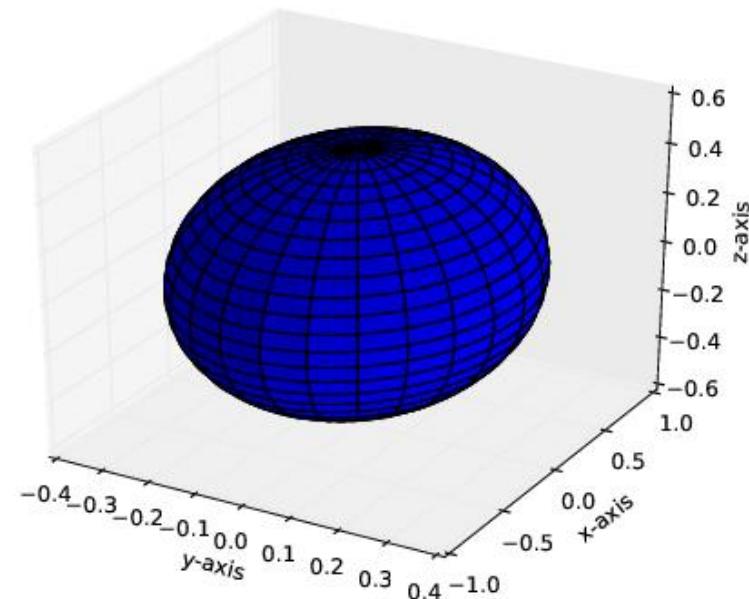
# Ex3 in Python

**EXAMPLE 3** Use traces to sketch the quadric surface with equation

$$x^2 + \frac{y^2}{9} + \frac{z^2}{4} = 1$$

```
from mpl_toolkits.mplot3d import Axes3D
import matplotlib.pyplot as plt
import numpy as np
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
u = np.linspace(0, 2 * np.pi, 100)      #theta
v = np.linspace(0, np.pi, 100)          #phi
x = 1. * np.outer(np.cos(u), np.sin(v))  #outer:
y = 1./3. * np.outer(np.sin(u), np.sin(v))
z = 1./2. * np.outer(np.ones(np.size(u)), np.cos(v))
#ax.plot_surface(x, y, z, rstride=4, cstride=4, color='b')
ax.plot_surface(y, x, z, rstride=4, cstride=4, color='b')

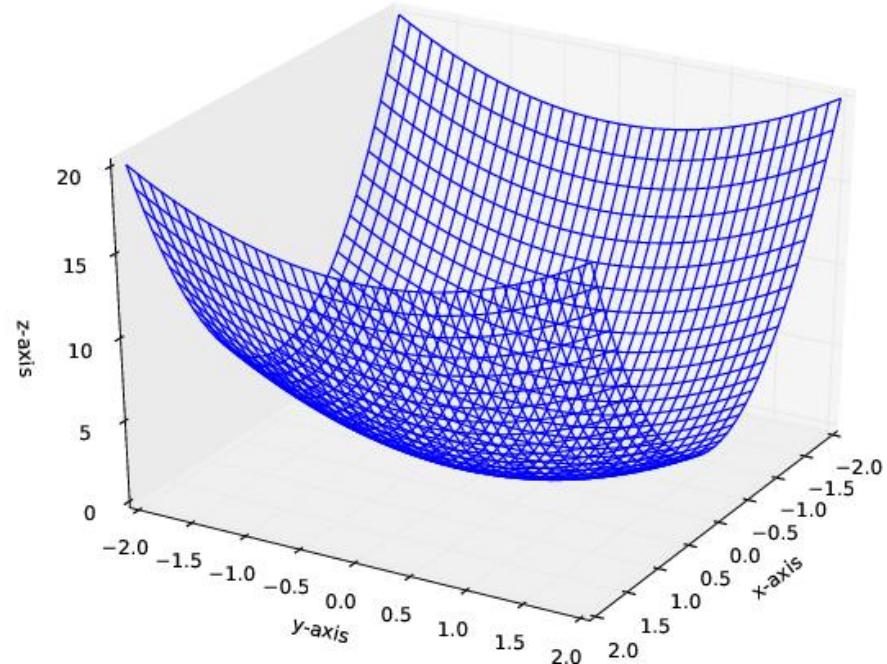
ax.set_xlabel('y-axis')
ax.set_ylabel('x-axis')
ax.set_zlabel('z-axis')
plt.savefig('ex3.ps')
plt.show()
```



# Ex4 in Python

**EXAMPLE 4** Use traces to sketch the surface  $z = 4x^2 + y^2$ .

```
from mpl_toolkits.mplot3d import axes3d  
import matplotlib.pyplot as plt  
import numpy as np  
  
fig=plt.figure()  
ax=axes3d.Axes3D(fig,azim=30,elev=30)  
  
x=np.linspace(-2,2,40)  
y=np.linspace(-2,2,40)  
  
X, Y=np.meshgrid(x,y)  
Z=4*X**2 + Y**2  
  
ax.plot_wireframe(X,Y,Z)  
ax.set_xlabel('x-axis')  
ax.set_ylabel('y-axis')  
ax.set_zlabel('z-axis')  
  
plt.savefig('ex4.ps')  
plt.show()
```



# Ex5 in Python

**EXAMPLE 5** Sketch the surface  $z = y^2 - x^2$ .

```
from mpl_toolkits.mplot3d import axes3d  
import matplotlib.pyplot as plt  
import numpy as np
```

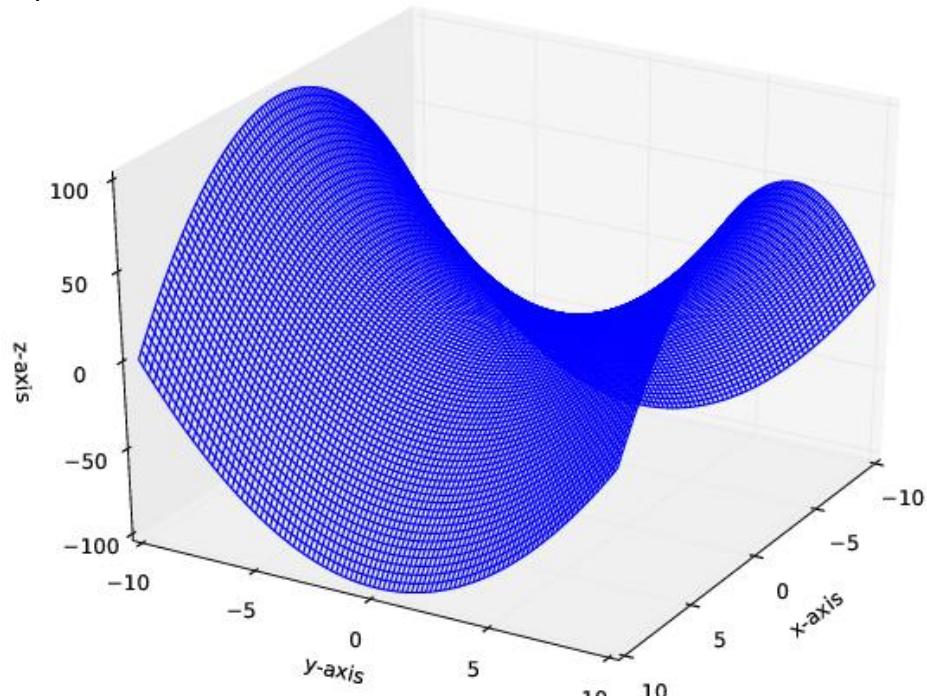
```
fig=plt.figure()  
ax=axes3d.Axes3D(fig,azim=30,elev=30)
```

```
x=np.linspace(-10,10,100)  
y=np.linspace(-10,10,100)
```

```
X, Y=np.meshgrid(x,y)  
Z= Y**2 - X**2
```

```
ax.plot_wireframe(X,Y,Z)  
ax.set_xlabel('x-axis')  
ax.set_ylabel('y-axis')  
ax.set_zlabel('z-axis')
```

```
plt.savefig('ex5.ps')  
plt.show()
```



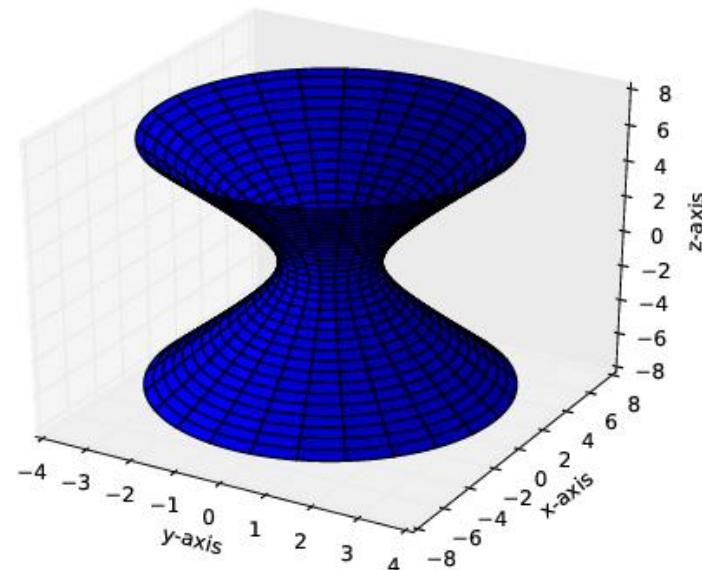
# Ex6 in Python

**EXAMPLE 6** Sketch the surface  $\frac{x^2}{4} + y^2 - \frac{z^2}{4} = 1$ .

```
from mpl_toolkits.mplot3d import Axes3D
import matplotlib.pyplot as plt
import numpy as np
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
u = np.linspace(0, 2 * np.pi, 100)      #theta
t = np.linspace(-7, 7, 140)            #t
x = 2. * np.outer(np.cos(u), np.sqrt(1+t**2/4))
y = 1. * np.outer(np.sin(u), np.sqrt(1+t**2/4))
z = 1. * np.outer(np.ones(np.size(u)), t)
ax.plot_surface(y, x, z, rstride=4, cstride=4, color='b')
#ax.plot_surface(x, y, z, rstride=4, cstride=4, color='b')

ax.set_xlabel('y-axis')
ax.set_ylabel('x-axis')
ax.set_zlabel('z-axis')

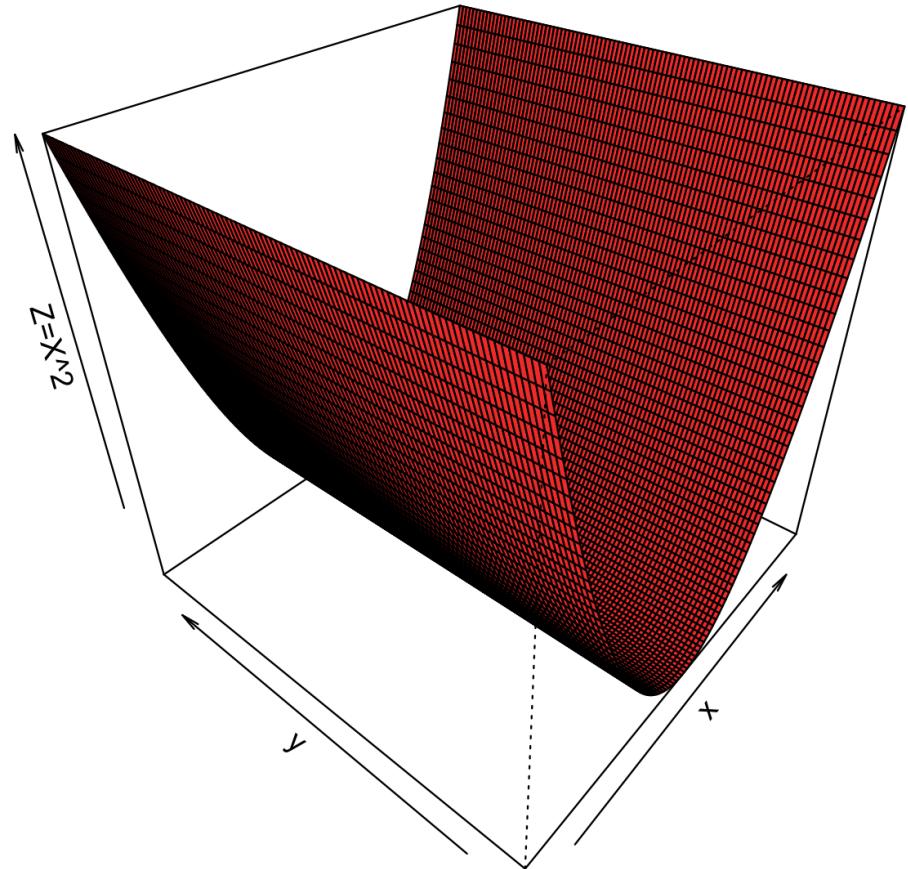
plt.savefig('ex6.ps')
plt.show()
```



# Ex1 in R

**EXAMPLE 1** Sketch the graph of the surface  $z = x^2$ .

```
library(package = "TDA")
x=seq(-5, 5, length=100)
y=seq(-5, 5, length=100)
z=outer(x,y, function(x,y) {x^2})
persp(x,y,z, xlab='x', ylab='y', zlab="Z=X^2"
theta=-50, phi=35, col='firebrick2')
dev.copy2pdf(file="ex1.pdf")
png("ex1.png")
```



## Ex2 in R

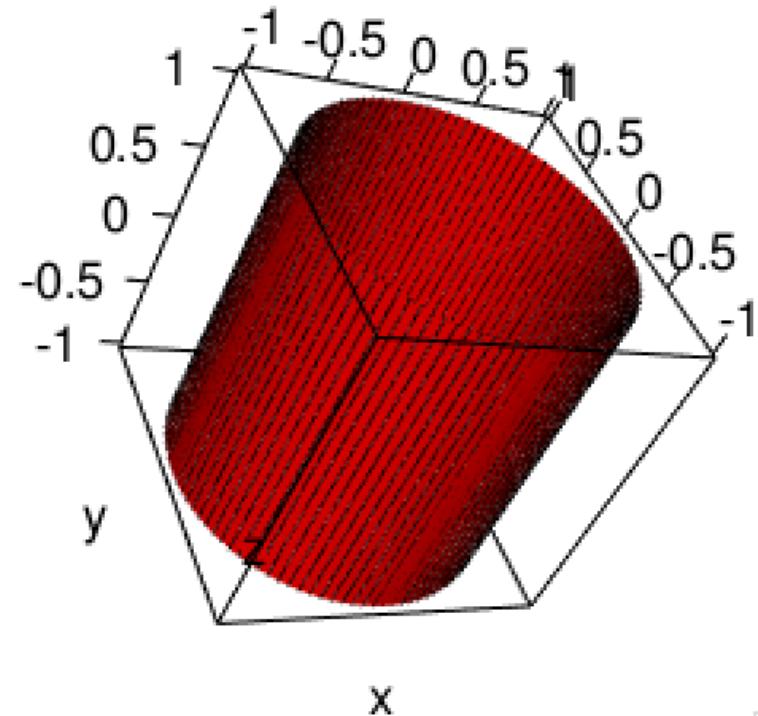
**EXAMPLE 2** Identify and sketch the surfaces.

(a)  $x^2 + y^2 = 1$       (b)  $y^2 + z^2 = 1$

```
library(package = "TDA")
library("rgl")

u = seq(0, 2 * pi, length=100)      #theta
ones = array(1, dim=length(u))
t = seq(-1, 1, length=100)      #phi
ones_t = array(1, dim=length(v))
x = 1. * outer(cos(u), ones_t)  #outer:
y = 1. * outer(sin(u), ones_t)
z = 1. * outer(ones, t)

plot3d(x, y, z,
xlab="x", ylab="y", zlab="z", type="s", xlim=c(-1,1),
ylim=c(-1,1), size=0.25, aspect=FALSE)
surface3d(x,y,z, color='red')
dev.copy2pdf(file="ex2.pdf")
png("ex2.png")
```



# Ex3 in R

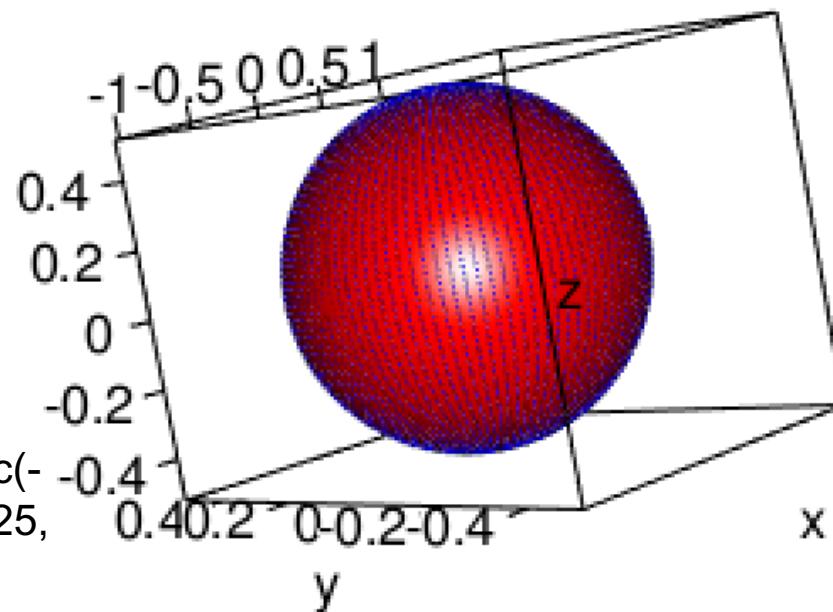
**EXAMPLE 3** Use traces to sketch the quadric surface with equation

$$x^2 + \frac{y^2}{9} + \frac{z^2}{4} = 1$$

```
library(package = "TDA")
library("rgl")
```

```
u = seq(0, 2 * pi, length=100)      #theta
ones = array(1, dim=length(u))
v = seq(0, pi, length=100)          #phi
x = 1. * outer(cos(u), sin(v))    #outer:
y = 1./3. * outer(sin(u), sin(v))
z = 1./2. * outer(ones, cos(v))

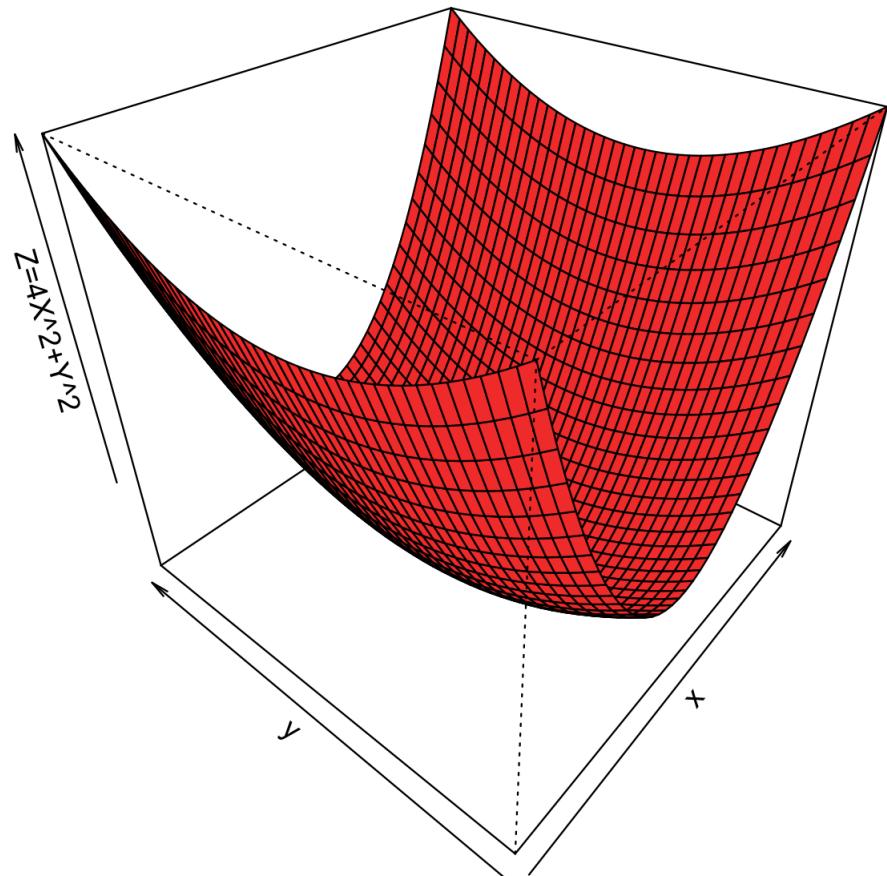
plot3d(x, y, z,
       xlab="x", ylab="y", zlab="z", type="s", xlim=c(-1,1),
       ylim=c(-0.5,0.5), col = "blue", size=0.25,
       aspect=FALSE)
surface3d(x,y,z, color='red')
dev.copy2pdf(file="ex3.pdf")
png("ex3.png")
```



# Ex4 in R

**EXAMPLE 4** Use traces to sketch the surface  $z = 4x^2 + y^2$ .

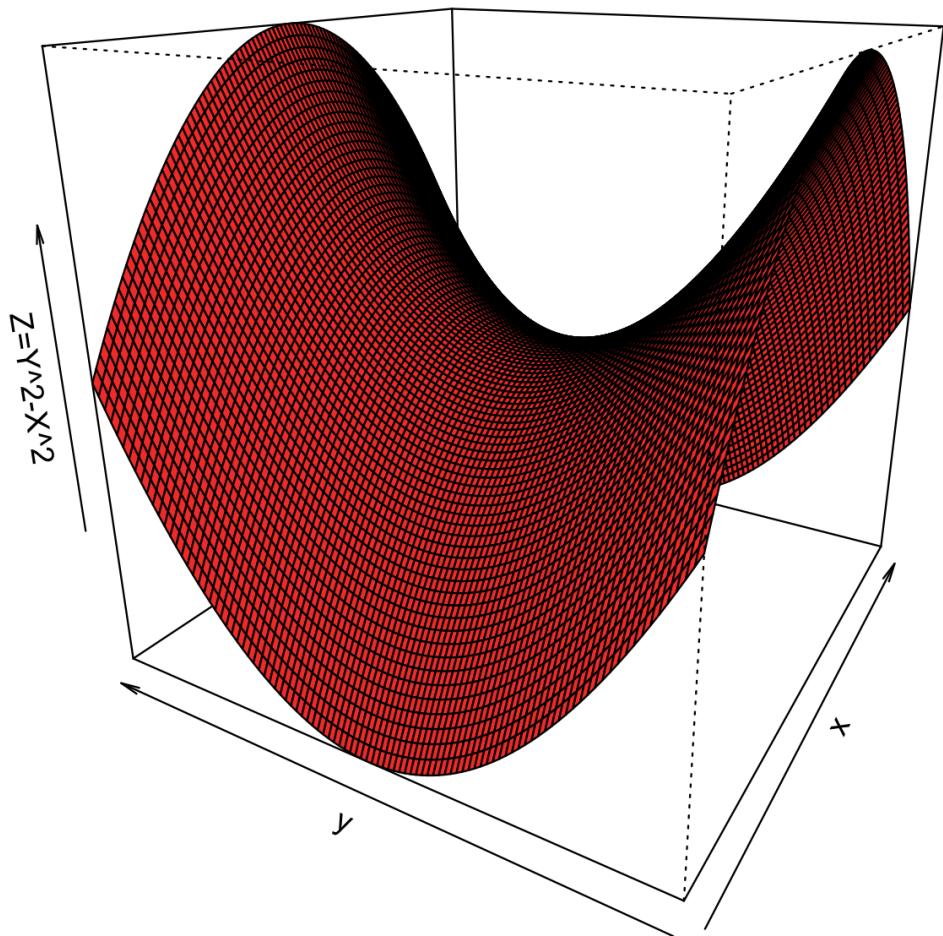
```
library(package = "TDA")
x=seq(-2, 2, length=40)
y=seq(-2, 2, length=40)
z=outer(x,y, function(x,y) {4*x^2+y^2})
persp(x,y,z, xlab='x', ylab='y',
      zlab="Z=4X^2+Y^2", theta=-50, phi=35,
      col='firebrick2')
dev.copy2pdf(file="ex4.pdf")
png("ex4.png")
```



# Ex5 in R

**EXAMPLE 5** Sketch the surface  $z = y^2 - x^2$ .

```
library(package = "TDA")
x=seq(-10, 10, length=100)
y=seq(-10, 10, length=100)
z=outer(x,y, function(x,y) {y^2-x^2})
persp(x,y,z, xlab='x', ylab='y',
zlab="Z=Y^2-X^2", theta=-60, phi=20,
col='firebrick2')
dev.copy2pdf(file="ex5.pdf")
png("ex5.png")
```



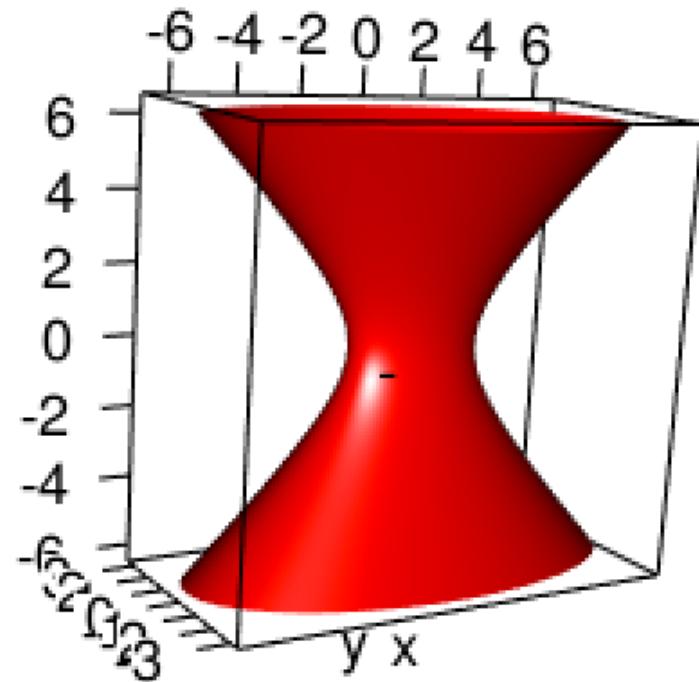
## Ex6 in R

**EXAMPLE 6** Sketch the surface  $\frac{x^2}{4} + y^2 - \frac{z^2}{4} = 1$ .

```
library(package = "TDA")
library("rgl")

u = seq(0, 2 * pi, length=100)      #theta
ones = array(1, dim=length(u))
t = seq(-2*pi, 2*pi, length=100)    #phi
x = 2. * outer(cos(u), sqrt(1+t^2/4)) #outer:
y = 1. * outer(sin(u), sqrt(1+t^2/4))
z = 1. * outer(ones, t)

plot3d(x, y, z,
       xlab="x", ylab="y", zlab="z", type="s", xlim=c(-1,1),
       ylim=c(-0.5,0.5), col = "blue", size=0.25,
       aspect=FALSE)
surface3d(x,y,z, color='red')
dev.copy2pdf(file="ex6.pdf")
png("ex6.png")
```

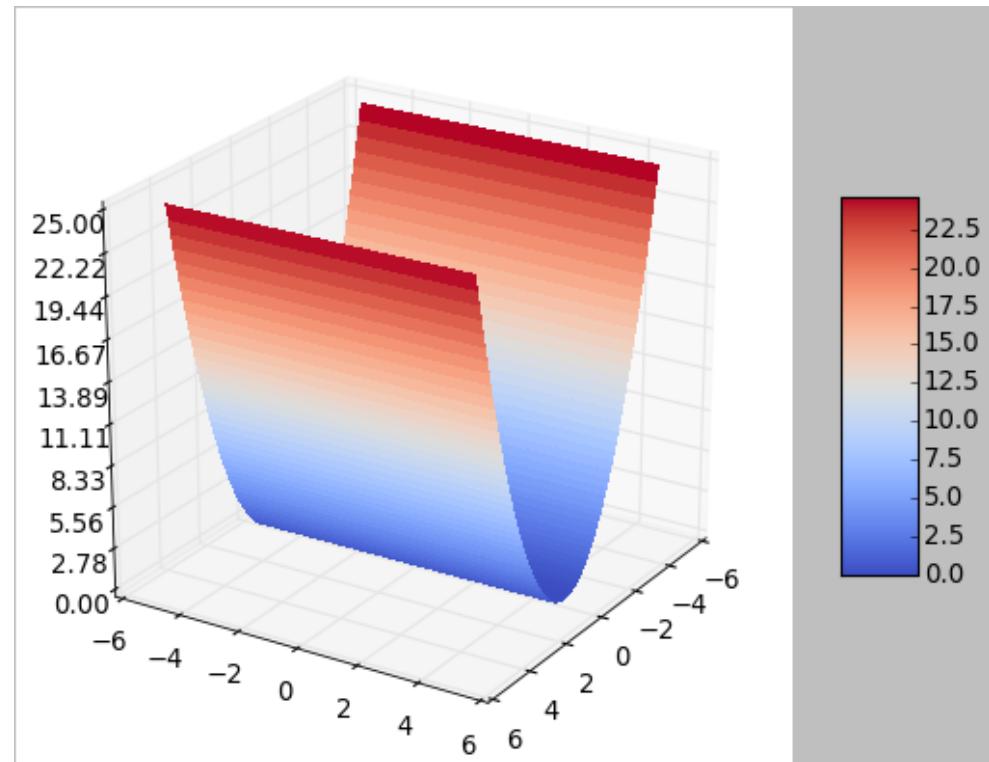


# Ex1 in Julia

**EXAMPLE 1** Sketch the graph of the surface  $z = x^2$ .

```
using PyPlot  
using QuantEcon
```

```
fig = figure()  
x = linspace(-5, 5, 100)  
y = linspace(-5, 5, 100)  
X, Y = meshgrid(collect(x), collect(y))  
Z = X.^2  
#surf = plot_surface(X, Y, Z, rstride=1, cstride=1,  
#    linewidth=0, antialiased=false,  
#    cmap="coolwarm")  
surf = plot_surface(x, y, Z, rstride=1, cstride=1,  
    linewidth=0, antialiased=false,  
    cmap="coolwarm")  
#zlim(-1.01,1.01)  
ax = gca()  
ax[:zaxis][:set_major_locator](matplotlib[:ticker][:  
    LinearLocator](10))  
ax[:zaxis][:set_major_formatter](matplotlib[:ticker]  
    [:FormatStrFormatter]("%,.02f"))  
fig[:colorbar](surf, shrink=0.5, aspect=5)  
  
savefig("ex1.pdf")
```

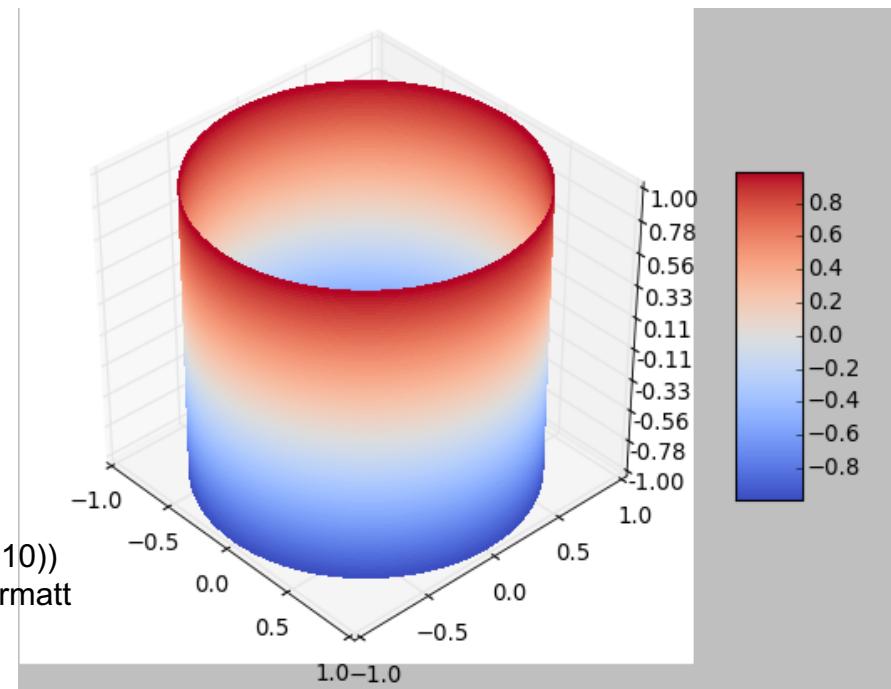


# Ex2 in Julia

```
using PyPlot
using QuantEcon
fig = figure()
n=100
u = linspace(0, 2pi, n)      #theta
v = linspace(-1, 1, n)

x = Array(Float64, n, n)
y = Array(Float64, n, n)
z = Array(Float64, n, n)
xf(xx, yy) = cos(xx)
yf(xx, yy) = sin(xx)
zf(xx, yy) = yy
for i in 1:n
    for j in 1:n
        x[j, i] = xf(u[i], v[j])
        y[j, i] = yf(u[i], v[j])
        z[j,i] = zf(u[i], v[j])
    end
end
surf = plot_surface(x, y, z, rstride=1, cstride=1, linewidth=0,
antialiased=false, cmap="coolwarm")
ax = gca()
ax[:zaxis][:set_major_locator](matplotlib[:ticker][:LinearLocator](10))
ax[:zaxis][:set_major_formatter](matplotlib[:ticker][:FormatStrFormatter]( "%.02f"))
fig[:colorbar](surf, shrink=0.5, aspect=5)

savefig("ex2.pdf")
```



# Ex3 in Julia

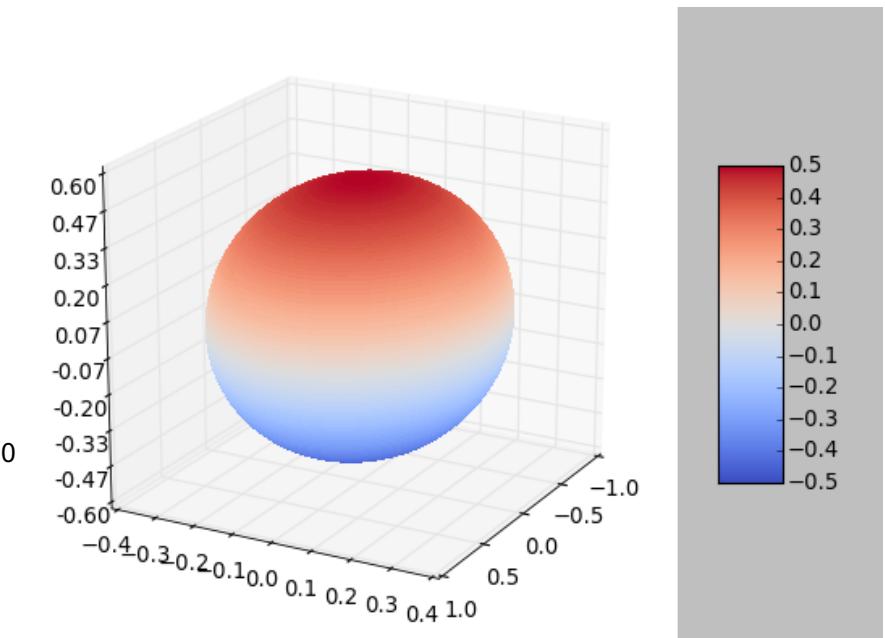
```
using PyPlot
using QuantEcon

fig = figure()
n=100
u = linspace(0, 2pi, n)      #theta
v = linspace(0, pi, n)        #phi

x = Array(Float64, n, n)
y = Array(Float64, n, n)
z = Array(Float64, n, n)
xf(xx, yy) = cos(xx)*sin(yy)
yf(xx, yy) = 1.0/3.0*sin(xx)*sin(yy)
zf(xx, yy) = 1.0/2.0*cos(yy)
for i in 1:n
    for j in 1:n
        x[j, i] = xf(u[i], v[j])
        y[j, i] = yf(u[i], v[j])
        z[j,i] = zf(u[i], v[j])
    end
end

surf = plot_surface(x, y, z, rstride=1, cstride=1, linewidth=0,
antialiased=false, cmap="coolwarm")
#zlim(-1.01,1.01)
ax = gca()
ax[:zaxis][:set_major_locator](matplotlib[:ticker][:LinearLocator](10))
ax[:zaxis][:set_major_formatter](matplotlib[:ticker][:FormatStrFormatter]("%.0
2f"))
fig[:colorbar](surf, shrink=0.5, aspect=5)

savefig("ex3.pdf")
```

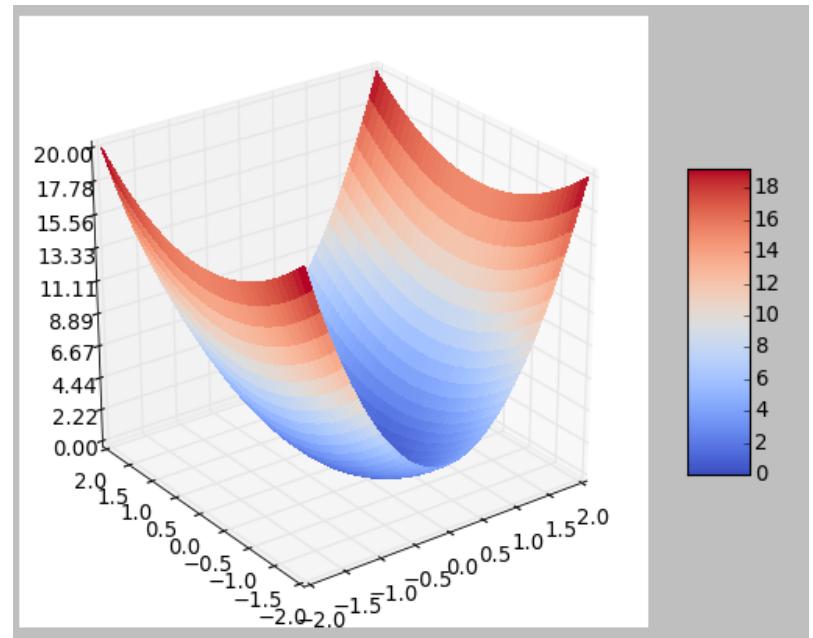


# Ex4 in Julia

```
using PyPlot
#using QuantEcon: meshgrid
using QuantEcon

fig = figure()
#x = linspace(-5, 5, 100)'
n = 40
x = linspace(-2, 2, n)
y = linspace(-2, 2, n)
X, Y = meshgrid(collect(x), collect(y))
Z = 4 * X.^2 + Y.^2
surf = plot_surface(x, y, Z, rstride=1, cstride=1,
linewidth=0, antialiased=false, cmap="coolwarm")
#zlim(-1.01,1.01)
ax = gca()
ax[:zaxis][:set_major_locator](matplotlib[:ticker][:Line
arLocator](10))
ax[:zaxis][:set_major_formatter](matplotlib[:ticker][:F
ormatStrFormatter]("%0.02f"))
fig[:colorbar](surf, shrink=0.5, aspect=5)

savefig("ex4.pdf")
```



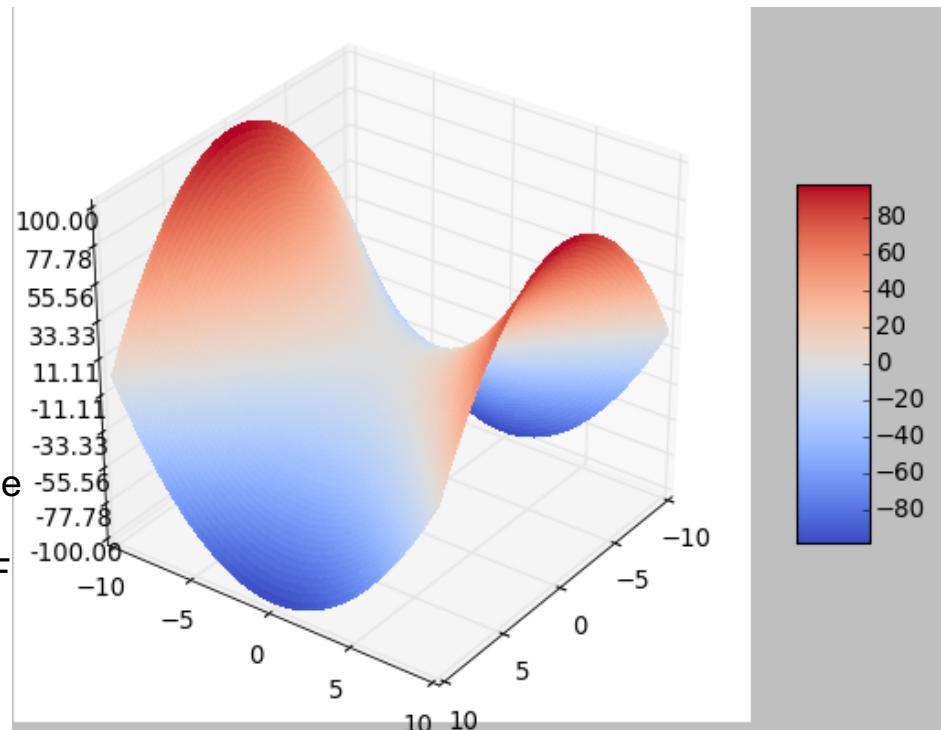
# Ex5 in Julia

---

```
using PyPlot
#using QuantEcon: meshgrid
using QuantEcon

fig = figure()
#x = linspace(-5, 5, 100)'
n = 100
x = linspace(-10, 10, n)
y = linspace(-10, 10, n)
X, Y = meshgrid(collect(x), collect(y))
Z = Y.^2 - X.^2
surf = plot_surface(x, y, Z, rstride=1, cstride=1,
linewidth=0, antialiased=false, cmap="coolwarm")
#zlim(-1.01,1.01)
ax = gca()
ax[:zaxis][:set_major_locator](matplotlib[:ticker][:Line
arLocator](10))
ax[:zaxis][:set_major_formatter](matplotlib[:ticker][:F
ormatStrFormatter]("%.02f"))
fig[:colorbar](surf, shrink=0.5, aspect=5)

savefig("ex5.pdf")
```



# Ex6 in Julia

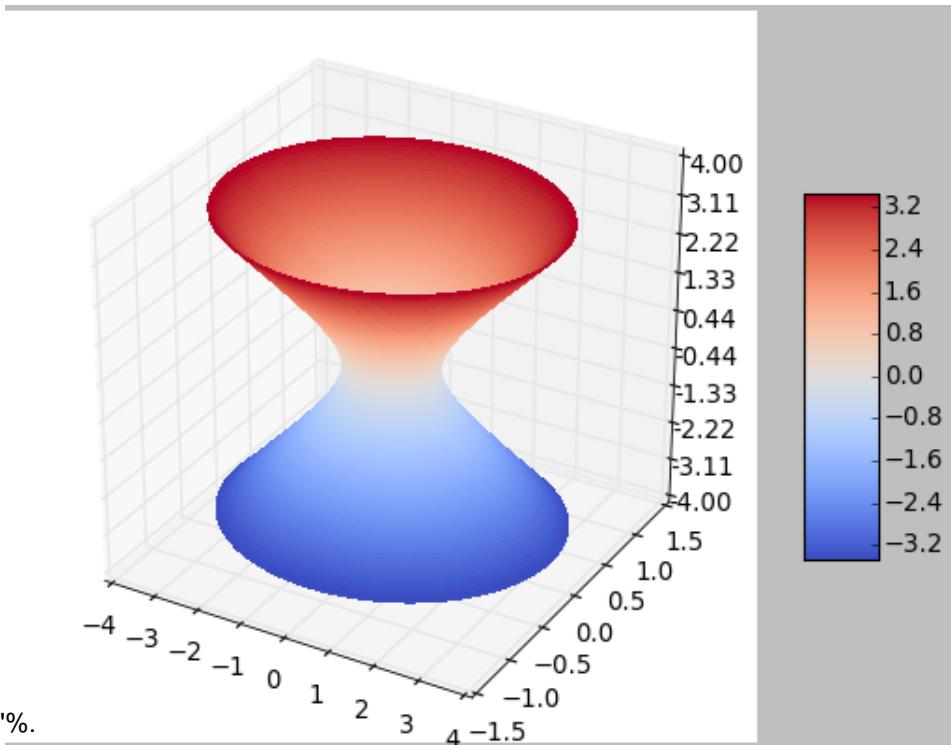
```
using PyPlot
using QuantEcon

fig = figure()
n=100
u = linspace(0, 2pi, n)      #theta
#v = linspace(0, pi, n)       #phi
v = linspace(-7, 7, n)

x = Array(Float64, n, n)
y = Array(Float64, n, n)
z = Array(Float64, n, n)
xf(xx, yy) = cos(xx)*sqrt(1+yy^2/4)
yf(xx, yy) = 1.0/3.0*sin(xx)*sqrt(1+yy^2/4)
zf(xx, yy) = 1.0/2.0*yy
for i in 1:n
    for j in 1:n
        x[j, i] = xf(u[i], v[j])
        y[j, i] = yf(u[i], v[j])
        z[j,i] = zf(u[i], v[j])
    end
end

surf = plot_surface(x, y, z, rstride=1, cstride=1, linewidth=0,
antialiased=false, cmap="coolwarm")
#zlim(-1.01,1.01)
ax = gca()
ax[:zaxis][:set_major_locator](matplotlib[:ticker][:LinearLocator](10))
ax[:zaxis][:set_major_formatter](matplotlib[:ticker][:FormatStrFormatter](("%.02f")))
fig[:colorbar](surf, shrink=0.5, aspect=5)

savefig("ex6.pdf")
```



# Performance



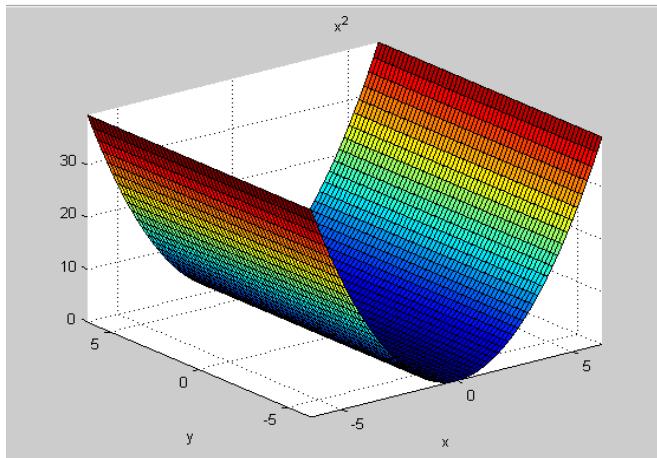
	Fortran	Julia	Python	R	Matlab	Octave	Mathematica	JavaScript	Go	LuaJIT	Java
	gcc 5.1.1	0.4.0	3.4.3	3.2.2	R2015b	4.0.0	10.2.0	V8 3.28.71.19	go1.5	gsl-shell 2.3.1	1.8.0_45
fib	0.70	2.11	77.76	533.52	26.89	9324.35	118.53	3.36	1.86	1.71	1.21
parse_int	5.05	1.45	17.02	45.73	802.52	9581.44	15.02	6.06	1.20	5.77	3.35
quicksort	1.31	1.15	32.89	264.54	4.92	1866.01	43.23	2.70	1.29	2.03	2.60
mandel	0.81	0.79	15.32	53.16	7.58	451.81	5.13	0.66	1.11	0.67	1.35
pi_sum	1.00	1.00	21.99	9.56	1.00	299.31	1.69	1.01	1.00	1.00	1.00
rand_mat_stat	1.45	1.66	17.93	14.56	14.52	30.93	5.95	2.30	2.96	3.27	3.92
rand_mat_mul	3.48	1.02	1.14	1.57	1.12	1.12	1.30	15.07	1.42	1.16	2.36

**Figure:** benchmark times relative to C (smaller is better, C performance = 1.0).

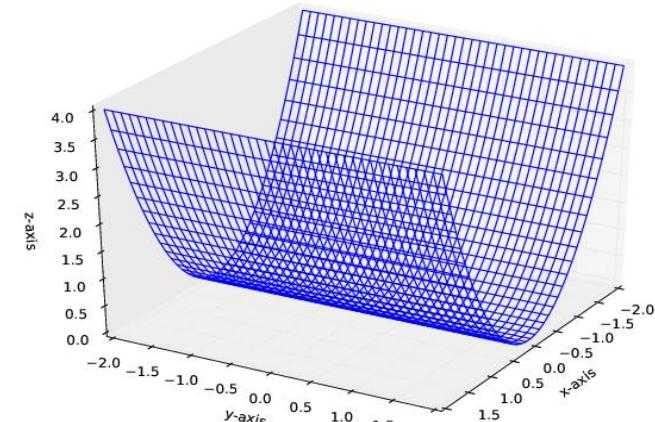
# EX-1

## Section 12.6: Surface plots

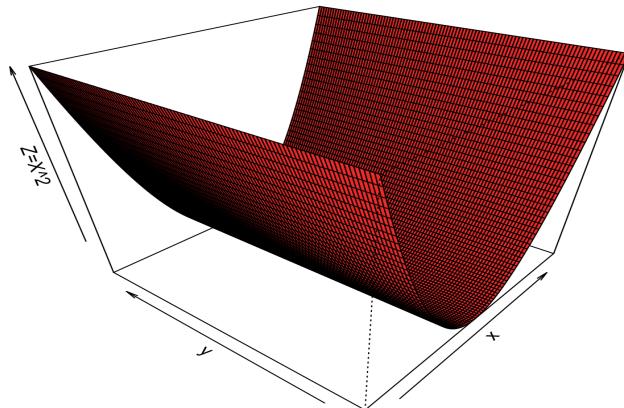
Matlab



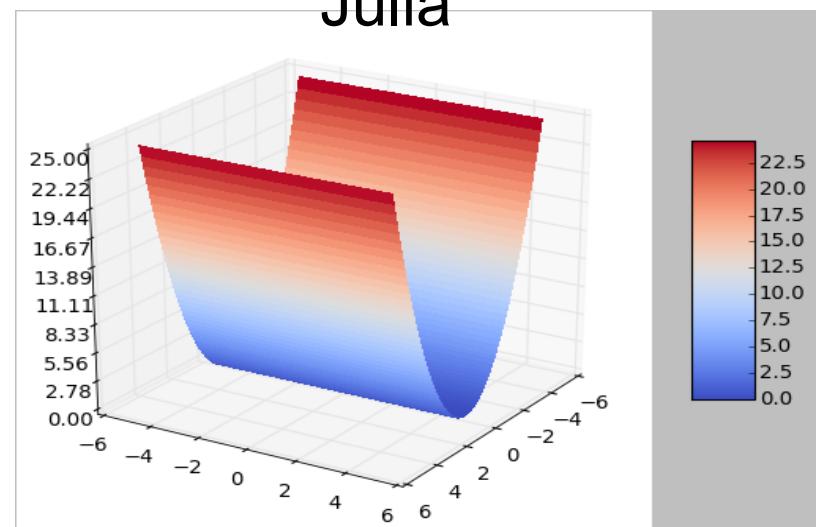
Python



R



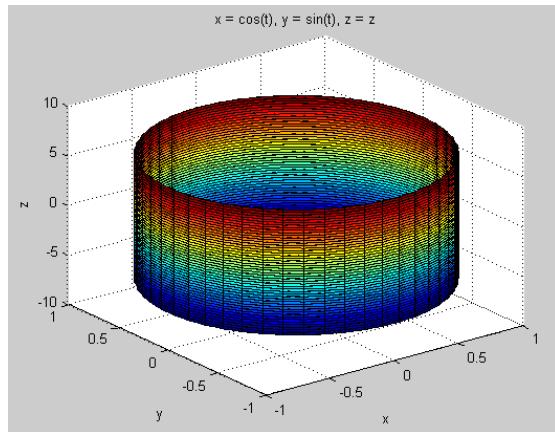
Julia



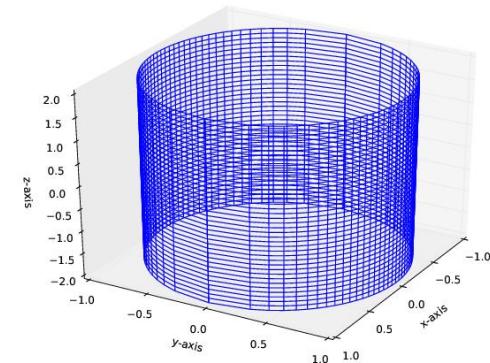
# EX-2

## Section 12.6: Surface plots

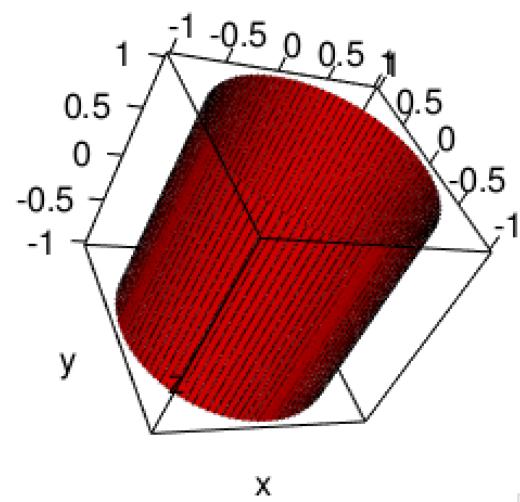
Matlab



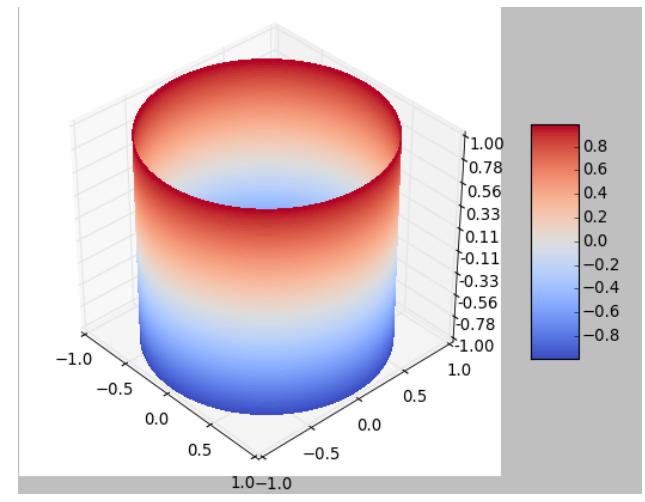
Python



R



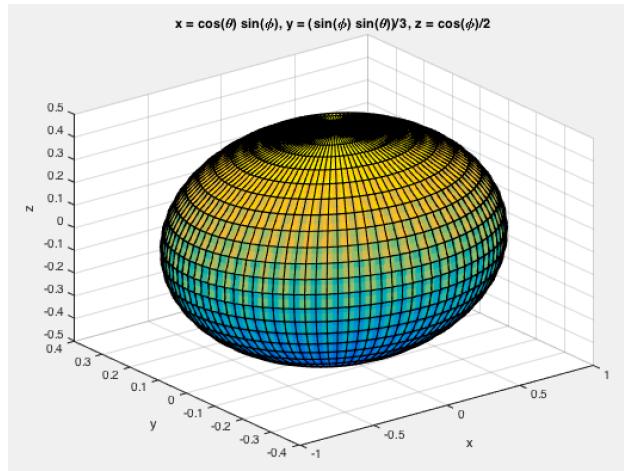
Julia



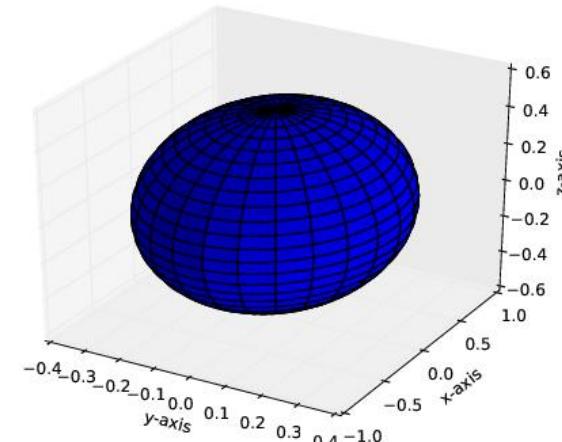
# EX-3

## Section 12.6: Surface plots

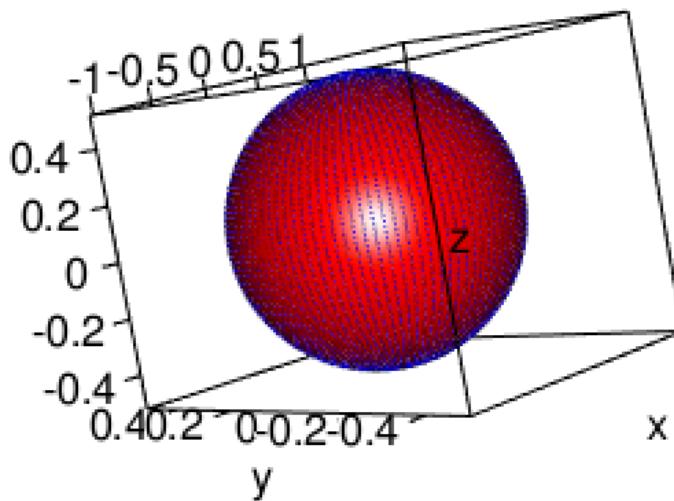
Matlab



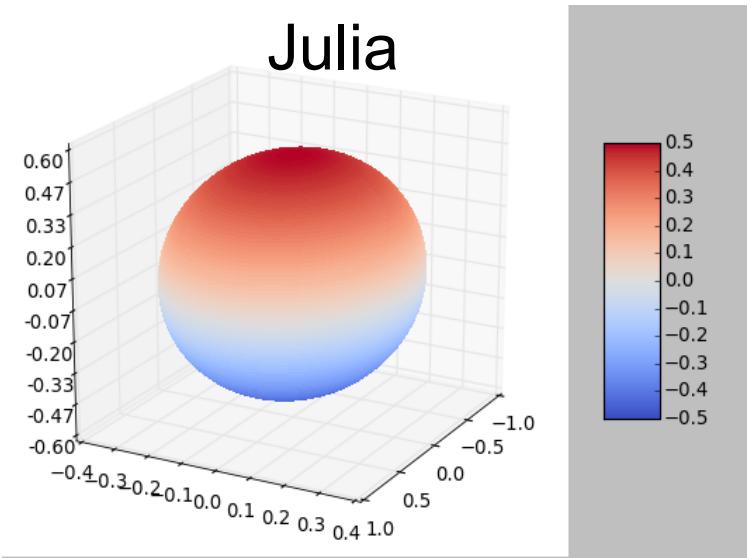
Python



R



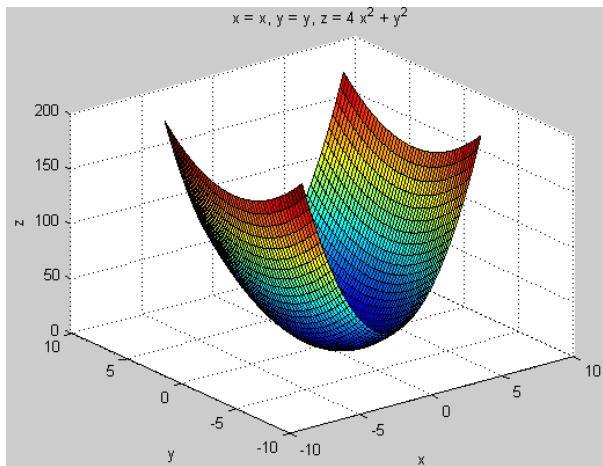
Julia



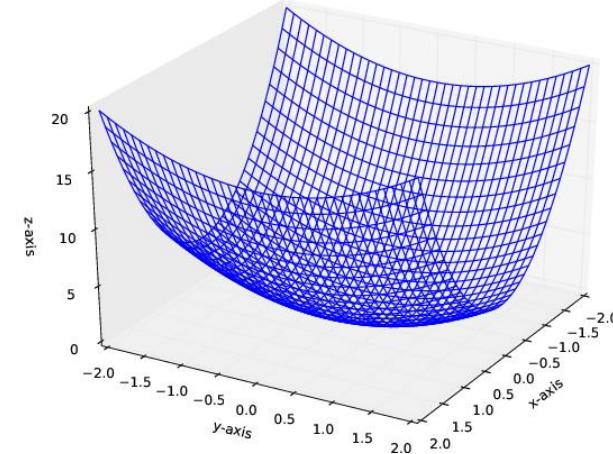
# EX-4

## Section 12.6: Surface plots

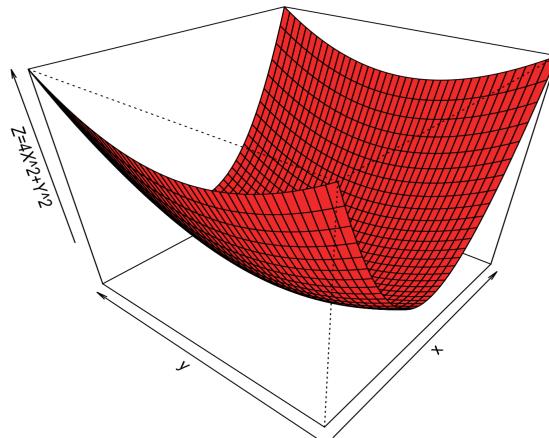
Matlab



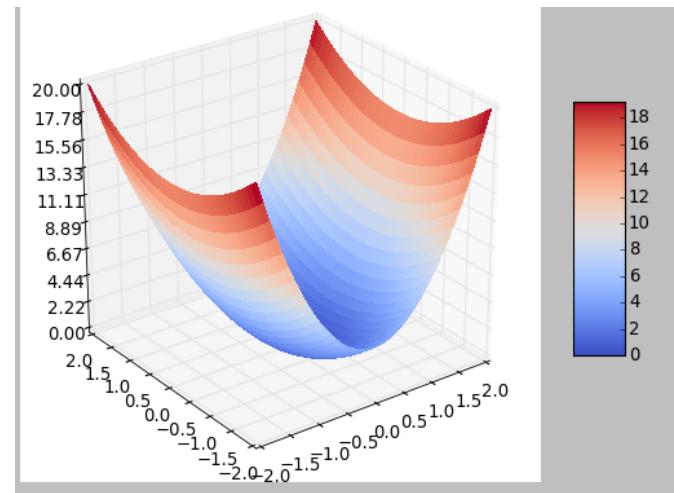
Python



R



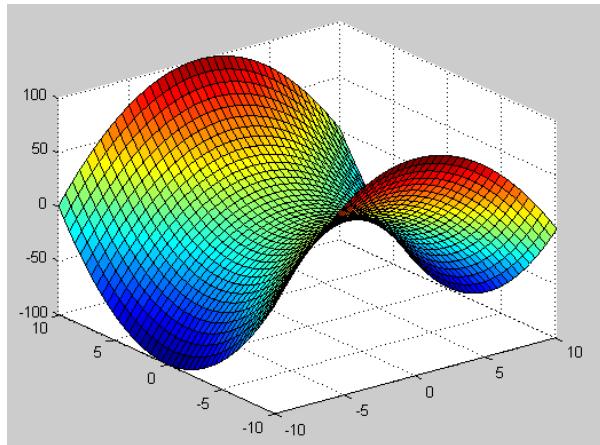
Julia



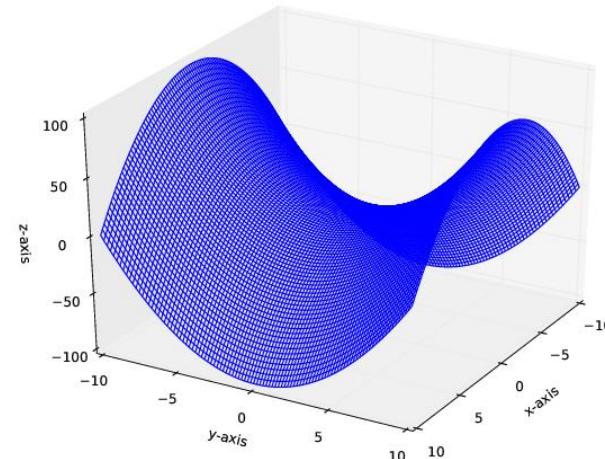
# EX-5

## Section 12.6: Surface plots

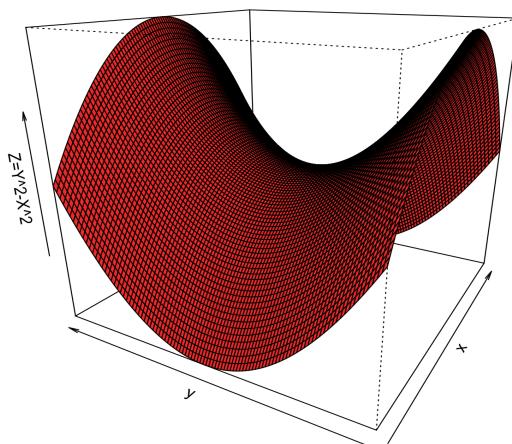
Matlab



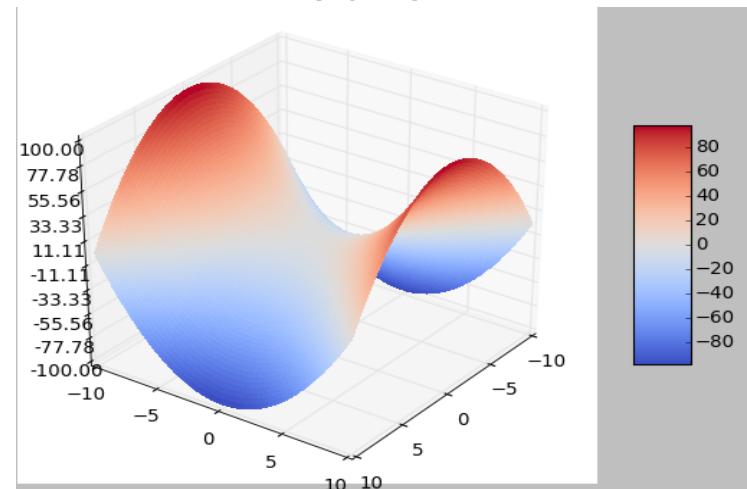
Python



R



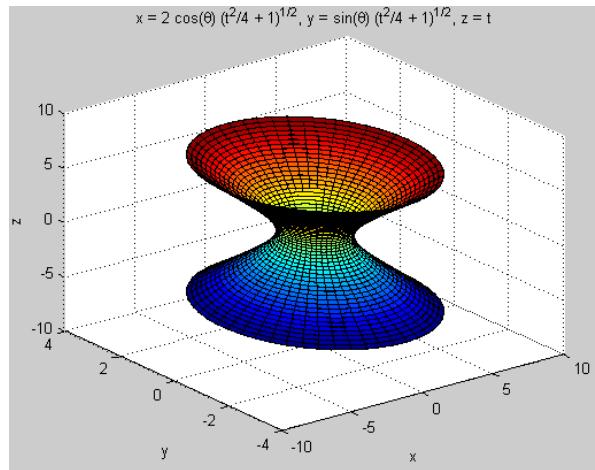
Julia



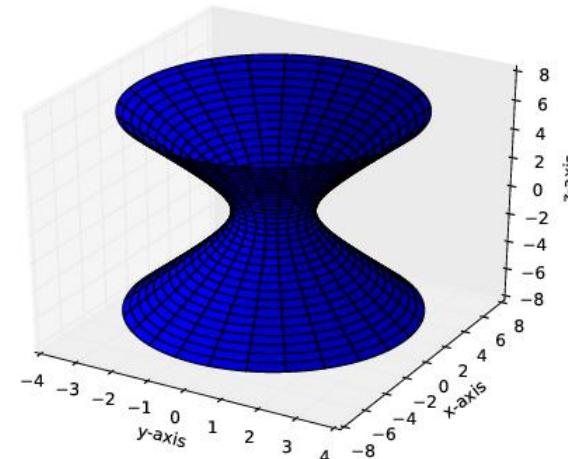
# EX-6

## Section 12.6: Surface plots

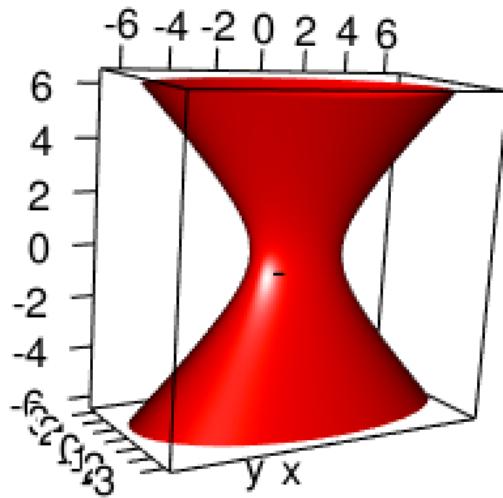
Matlab



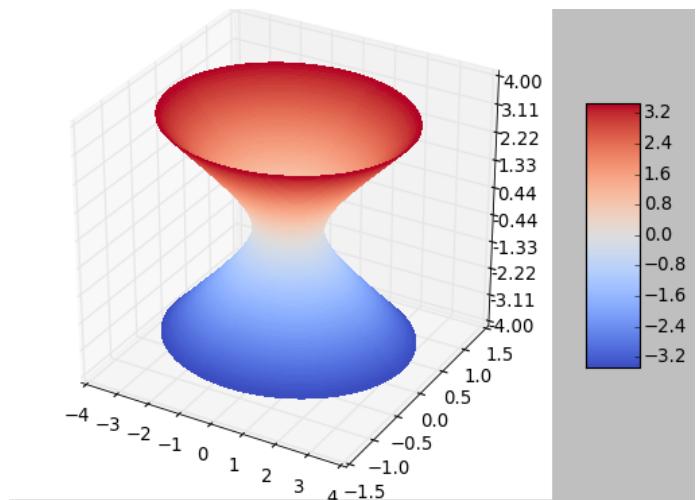
Python



R



Julia



# Performance



	Fortran	Julia	Python	R	Matlab	Octave	Mathematica	JavaScript	Go	LuaJIT	Java
	gcc 5.1.1	0.4.0	3.4.3	3.2.2	R2015b	4.0.0	10.2.0	V8 3.28.71.19	go1.5	gsl-shell 2.3.1	1.8.0_45
fib	0.70	2.11	77.76	533.52	26.89	9324.35	118.53	3.36	1.86	1.71	1.21
parse_int	5.05	1.45	17.02	45.73	802.52	9581.44	15.02	6.06	1.20	5.77	3.35
quicksort	1.31	1.15	32.89	264.54	4.92	1866.01	43.23	2.70	1.29	2.03	2.60
mandel	0.81	0.79	15.32	53.16	7.58	451.81	5.13	0.66	1.11	0.67	1.35
pi_sum	1.00	1.00	21.99	9.56	1.00	299.31	1.69	1.01	1.00	1.00	1.00
rand_mat_stat	1.45	1.66	17.93	14.56	14.52	30.93	5.95	2.30	2.96	3.27	3.92
rand_mat_mul	3.48	1.02	1.14	1.57	1.12	1.12	1.30	15.07	1.42	1.16	2.36

**Figure:** benchmark times relative to C (smaller is better, C performance = 1.0).

# Midterm Q4

```
syms x y t b r T N k dr dT real
assume (a>0)
assume (0<= t <= 2*pi)

x=cos(t)*a
y=sin(t)*a
% parameterization function is x=cos(t)*b y=sin(t)*b

r=[x, y]
dr=diff(r, t) % v(t)
d2r=diff(dr, t) % a(t)

dot1 = dot(r,dr) %value is 0, r and v(t) is orthogonal

dot2 = dot(r,d2r) %value is 0, r and a(t) is orthogonal

T=dr/norm(dr) % unit tangent vector

Tsim=simplify(T) % simplify the expression
dT=diff(Tsim,t) % dT/dt

k=norm(dT)/norm(dr) %curvature
pretty(simplify(k))
```

## Problem 4

- (a1)  $v(t) = \begin{pmatrix} -a \sin(t) \\ a \cos(t) \end{pmatrix}$   
(a2)  $a(t) = \begin{pmatrix} -a \cos(t) \\ -a \sin(t) \end{pmatrix}$
- (b)  $\dot{r} \cdot v(t) = 0$  so  $r$  and  $v(t)$  are orthogonal  
(c)  $\dot{r} \cdot a(t) = 0$  so  $r$  and  $a(t)$  are orthogonal
- (d) Unit tangent vector:  $\begin{pmatrix} -\sin(t) \\ \cos(t) \end{pmatrix}$   
(e) Curvature:  $\frac{1}{a}$