

# Homework 5

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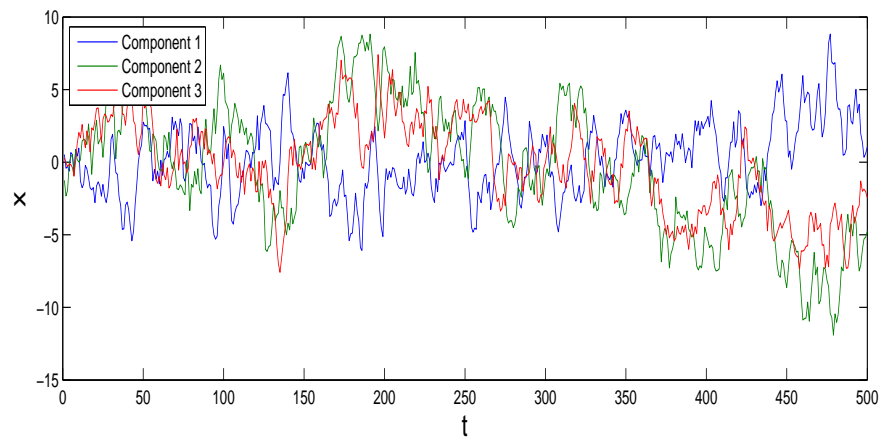


Figure 1: Answer of part (a), Plot of  $x_i$

## 0.1 Problem 1

### 0.1.1 (a)

### 0.1.2 (b)

The estimation of A,H,W,Q with  $x_i, y_i$  is:

K>> Ah

Ah =

0.9389	0.1146	-0.1880
-0.3236	0.8125	0.0553
0.2476	0.1298	0.9094

K>> Qh

Qh =

0.5121	0.0211
0.0211	0.5435

K>> Hh

Hh =

0.9796	0.4821	0.2033
0.4827	0.9973	0.0990

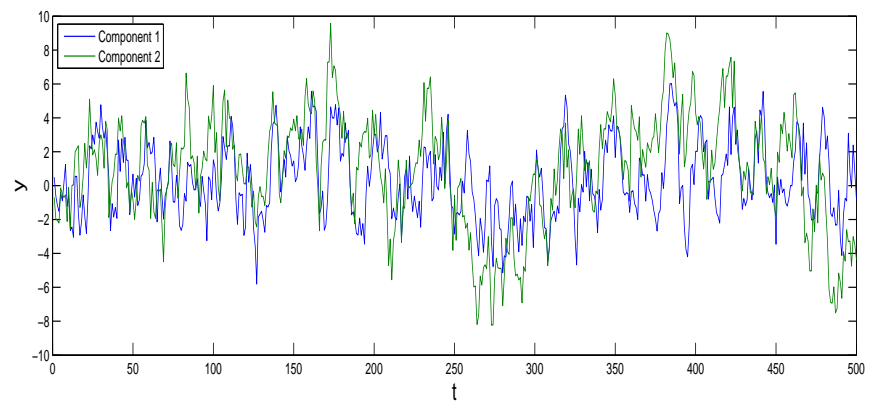


Figure 2: Answer of part (a), Plot of  $y_i$

```
K>> Wh
```

```
Wh =
```

```
    0.8637   -0.0313    0.0197
   -0.0313    1.0675   -0.0595
    0.0197   -0.0595    1.0448
```

```
K>> norm(Ah-A)/norm(A)
```

```
ans =
```

```
    0.0757
```

```
K>> norm(Qh-Q)/norm(Q)
```

```
ans =
```

```
    0.1081
```

```
K>> norm(Hh-H)/norm(H)
```

```
ans =
```

```
    0.0207
```

```
K>> norm(Wh-W)/norm(W)
```

```
ans =
```

```
    0.1416
```

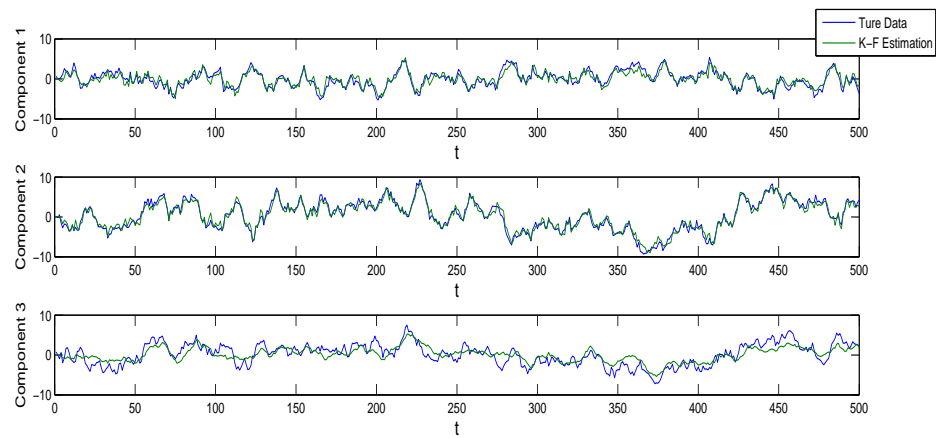


Figure 3: Answer of part (c), Plot of true data and estimation

### 0.1.3 (c)

We could not have the same accuracy for the third components. The reasons is: (1)  $x$  is a three dimensional data and  $y$  is a two dimensional data, we are using the two dimensional data to estimate three dimensional data, there must one dimension that is not correct enough. (2) From the matrix  $H$ , we can get that  $y_1 = x_1 + 0.5x_2 + 0.2x_3$ , and  $y_2 = 0.5x_1 + x_2 + 0.1x_3$ , we can see that  $x_1$  are dominated by  $y_1$ , similar as  $x_2$ , but  $x_3$  is just like a noise. So it could not be estimated well enough.

### 0.1.4 (d)

```
>> R2m
R2m =
    0.8323
    0.9501
    0.4549

>> R2p
R2p =
    0.6015
    0.8553
    0.4364
```

Compare the results: We can see that the  $R^2$ -Error for the filtering estimation is higher than the prediction estimation. Bigger  $R^2$  means higher estimation

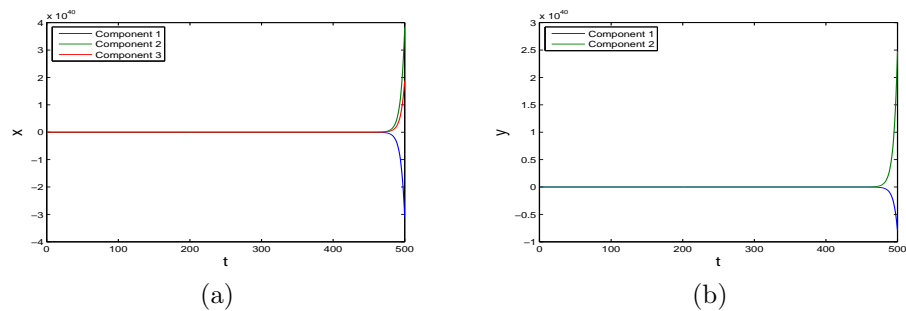


Figure 4: Answer of problem 3 (a) plot of  $x$  (b) plot of  $y$

accuracy.

## 0.2 Problem 2

If we change  $Q = 50I_2$ , the  $R^2$ -Error we get is:

```
R2m =
    0.1201
    0.3227
    0.1853

>> R2p

R2p =
    0.0907
    0.2620
    0.1875
```

We can see that the estimation accuracy decrease significantly. However, the  $R^2$  in the filtering estimation have no significant different with the ones in prediction estimation.

## 0.3 Problem 3

We can see that the process is very unstable. The reason is that the eigenvalues of the Matrix  $A$  is greater than 1.

```
K>> eig(A)

ans =
    1.2091
    0.7812
    0.4097
```

Because

$$X_k = A * X_{k-1} + W_k = A^{k-1} * X_1 + W_k$$

So if one of the eigenvalue of A greater than 1,  $X_k$  are going to be very big as k increase.