

2nd derivative

$$y_j'' = \delta^+ \delta^- y_j = \frac{y_{j+1} - 2y_j + y_{j-1}}{\Delta x^2}$$

$$y_j'' = \frac{-y_{j+2} + 16y_{j+1} - 30y_j + 16y_{j-1} - y_{j-2}}{12\Delta x^2} + O(\Delta x^4)$$

3.3.

2.7 Integration of odes

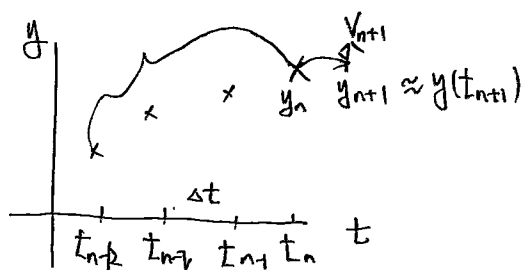
Initial Value Problem IVP

$$\begin{cases} \vec{y}' = \frac{d\vec{y}}{dt} = \vec{F}(t, \vec{y}) & t \geq 0 \\ \vec{y}(0) = \vec{y}_0 \end{cases}$$

EX: Continuous bond price
 $r(t)$ the interest rate
 $R(t)$ coupon payment.

$$\frac{dv}{dt} = r(t)V - R(t) \equiv F(t, V)$$

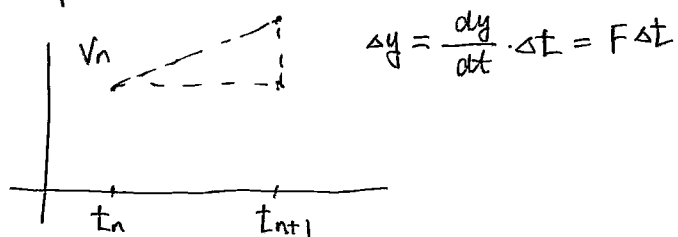
We will look at a class of step-by-step methods $t_n = n \cdot \Delta t$



if $k > 0$, the method is called multistep.

if $k = 0$, the method is called single step.

Example: Euler's method [Forward Euler]



Derivative 1:

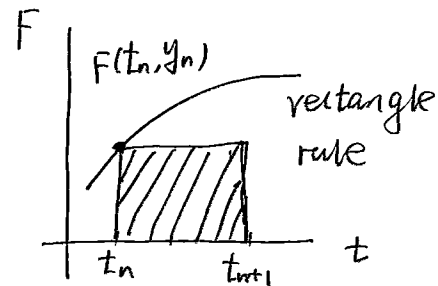
$$y' = F(t, y)$$

$$\int_{t_n}^{t_{n+1}} y' dt = \int_{t_n}^{t_{n+1}} F(t, y) dt$$

$$y_{n+1} - y_n = \int_{t_n}^{t_{n+1}} F(t, y) dt$$

$$y_n \equiv y(t_n)$$

$$y_{n+1} = y_n + \underbrace{\int_{t_n}^{t_{n+1}} F(t, y) dt}_{\text{approx. by quadrature.}}$$



$$F(t, y(t)) = \underbrace{F(t_n, y_n)}_{p_0} + \frac{F'(\xi)}{1!} (t - t_n)$$

$F'(\xi) = y''(\xi)$

$$F(t, y(t)) = \underbrace{F(t_n, y_n)}_{p_0} + \frac{F'(\xi)}{1!} (t - t_n)$$

$$y_{n+1} = y_n + \int_{t_n}^{t_{n+1}} F(t_n, y_n) dt + y''(\xi) \int_{t_n}^{t_{n+1}} (t - t_n) dt$$

$$y_{n+1} = y_n + F(t_n, y_n) \Delta t + y''(\xi) \cdot \frac{\Delta t^2}{2}$$

Drop Δt^2 term and let y_{n+1} satisfy

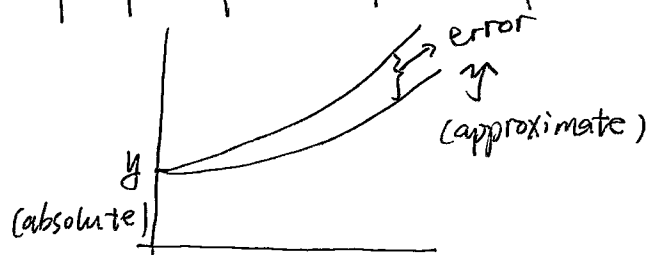
$$y_{n+1} = y_n + \Delta t F(t_n, y_n)$$

Example: $\begin{cases} y' = y \\ y(0) = 1 \end{cases} \quad y = e^t$

Euler: $y_{n+1} = y_n + \Delta t y_n = (1 + \Delta t) y_n$

choose $\Delta t = 0.1$, $y_{n+1} = 1.1 y_n$

(approx. of y_n)			
n	t_n	y_n	y_n
0	0	1	1
1	0.1	1.1	1.105
2	0.2	1.21	1.221
3	0.3	1.331	1.350
4	0.4	1.464	1.492



Derivation 2.

$$y_{n+1} = y_n + y'_n \Delta t + \frac{y''(\xi)}{2} \Delta t^2$$

$$y' = F(t_n, y_n)$$

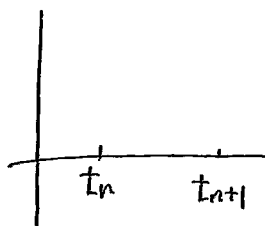
$$y_{n+1} = y_n + F(t_n, y_n) \Delta t + \frac{y''(\xi)}{2} \Delta t^2$$

$$\tilde{y}_{n+1} = y_n + F(t_n, y_n) \Delta t \quad \text{FE.}$$

Derivation 3.

$$y' = F(t, y)$$

$$S_t^r y_n = F(t_n, y_n) + \text{Error}$$



$$\frac{y_{n+1} - y_n}{\Delta t} = F(t_n, y_n) + E$$

$$y_{n+1} = y_n + \Delta t F(t_n, y_n) + (\Delta t E) \rightarrow \text{flow away}$$

$$\tilde{y}_{n+1} = y_n + \Delta t F(t_n, y_n)$$

we can find the error over one step a-posteriori

$$y_{n+1} = y_n + (\Delta t) F(t_n, y_n)$$

$$\tilde{y}_{n+1} = y_n + \Delta t F(t_n, y_n)$$

substitute exact solution.

$$y_{n+1} = y_n + \Delta t F(t_n, y_n) + \tau$$

$$y_{n+1} = y_n + y'_n \Delta t + \frac{y''(\xi)}{2} \Delta t^2$$

$$= y_n + \Delta t F(t_n, y_n) + \tau$$

$$\Rightarrow \tau = \frac{y''(\xi) \Delta t^2}{2}$$

↓

truncation error

Definition: The local truncation error is the error created over one time step.

Definition: A step by step method is of order r if $\tau = O(\Delta t^{r+1})$

Forward Euler is order 1, $\tau \approx O(\Delta t^2)$

Definition: A method is consistent if it is at least order 1.

Remark: Euler's Method

$$y_{n+1} = y_n + \Delta t F(t_n, y_n) + y''(\xi) \cdot \frac{\Delta t^2}{2}$$

$$\frac{y_{n+1} - y_n}{\Delta t} = F(t_n, y_n) + \frac{1}{\Delta t} \tau \quad \tau = y''(\xi) \cdot \frac{\Delta t^2}{2}$$

and limit, $\lim_{\Delta t \rightarrow 0} y' = F + 0$

Want to know.

$$e_n = y_n - \hat{y}_n$$

THM: let $\Delta t = \frac{T}{N}$, $t_n = n \Delta t$

$$\text{let } y_{n+1} = y_n + \Delta t F(t_n, y_n)$$

suppose $\left| \frac{\partial F}{\partial y} \right| \leq L$, $\left| \frac{\partial F}{\partial t} \right| \leq R$, $|F| \leq Z$.

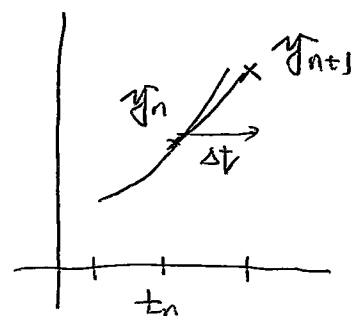
then $\hat{y}_N \rightarrow y(T)$ as $N \rightarrow \infty$ ($\Delta t \rightarrow 0$)

3.5.

$$y' = F(t, y)$$

Forward E.

$$y_{n+1} = y_n + \Delta t F(t_n, y_n)$$



Proof of THM:

$$y_{n+1} = y_n + \Delta t F(t_n, y_n) + \tau_n$$

$$- y_{n+1} = y_n + \Delta t F(t_n, y_n)$$

$$\cancel{e_{n+1} = y_{n+1}} \quad e_{n+1} = y_{n+1} - \hat{y}_{n+1}$$

$$= e_n + \Delta t [F(t_n, y_n) - F(t_n, \hat{y}_n)] + \tau_n$$

$$|e_{n+1}| \leq |e_n| + \Delta t |F(t_n, y_n) - F(t_n, \hat{y}_n)| + |\tau_n|$$

By MVT.

$$|F(t_n, y_n) - F(t_n, \hat{y}_n)| \leq \left(\frac{\partial F}{\partial y} \right) |y_n - \hat{y}_n|$$

$$\leq L$$

 $\tau_n \sim$ truncation error

$$|e_{n+1}| \leq |e_n| + \Delta t L |e_n| + |\tau_n|$$

$$(1 + \Delta t L) |e_n|$$

$$\tau = \max_n |\tau_n|$$

$$|e_{n+1}| \leq (1 + \Delta t L) |e_n| + \tau$$

$$\leq (1 + \Delta t L) \{ (1 + \Delta t L) |e_{n-1}| + \tau \} + \tau$$

$$\leq (1 + \Delta t L)^2 |e_{n-1}| + (1 + \Delta t L) \tau + \tau$$

$$\dots \leq (1 + \Delta t L)^{n+1} |e_0| + \tau \sum_{j=0}^{n+1} (1 + \Delta t L)^j$$

0

$$|e_n| \leq \tau \sum_{j=0}^{n+1} (1 + \Delta t L)^j$$

$$T = N \Delta t$$

Recall $\sum_{j=0}^{N-1} \epsilon^j = \frac{\epsilon^N - 1}{\epsilon - 1}$

so $|e_N| \leq \tau \frac{(1+\Delta t L)^N - 1}{\Delta t L - 1}$

~~$1+\Delta t L \leq e^{\Delta t L}$~~ $1+\Delta t L \leq e^{\Delta t L}$

$|e_N| \leq \frac{\tau}{\Delta t L} (e^{L T} - 1) / L \Rightarrow |e_N| \leq \frac{\tau}{\Delta t} \frac{e^{L T} - 1}{L}$

But $\tau = \max_z \frac{1}{2} |y''(z)| \Delta t^2$

$|e_N| \leq \frac{1}{2} \max |y''(z)| \Delta t \cdot \frac{e^{L T} - 1}{L}$

But $y'' = F' = \frac{dF}{dt} = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial y} \cdot \frac{dy}{dt} \quad (F = \frac{dy}{dt})$
 $= \frac{\partial F}{\partial t} + \frac{\partial F}{\partial y} \cdot F$

so, $y'' = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial y} F \leq K + LZ$ just a number

so, $|e_N| \leq \Delta t \left(\frac{1}{2} (K + LZ) \frac{e^{L T} - 1}{L} \right)$

$\lim_{\substack{N \rightarrow \infty \\ \Delta t \rightarrow \frac{T}{N}}} |e_N| = 0$

Also, $|e| = O(\Delta t)$

$(\tau = O(\Delta t^2))$

RMK: consistency is a necessary condition for convergence.

Except: we assume that

$(1+\Delta t L)^N \cdot |e_0| \equiv 0$

so, really, $|e_N| \leq e^{L T} |e_0| + O(\Delta t)$

if $L T$ is large, this doesn't tell us much.

need condition on growth of errors.

Test problem:

$$y' = \lambda y \quad \lambda \in \mathbb{C}$$

$$(\vec{y}' = \vec{F}(t, \vec{y}))$$

↓ linearize

$$\vec{y}' = A(t) * \vec{y}$$

↓ matrix

freeze t $\vec{y}' = A \vec{y}$

↓ diagonalize

~~$$A = S \Lambda S^{-1}$$~~
~~matrix~~

$$A = S \Lambda S^{-1}$$

$$\vec{y}' = S \Lambda S^{-1} \vec{y}$$

$$S^{-1} \vec{y}' = \Lambda S^{-1} \vec{y}$$

define $\vec{w} = S^{-1} \vec{y} \Rightarrow \vec{w}' = \Lambda \vec{w}$

$$w_i' = \lambda w_i$$

now let u = solution with no error initial

v = solution with initial error

$$u' = \lambda u$$

$$v' = \lambda v$$

$$\hat{y}' = (u - v)' = \lambda \hat{y}$$

↑

$u - v$ error

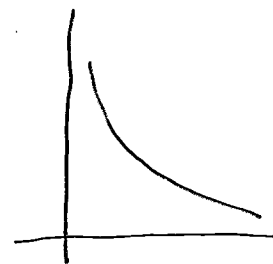
$$\hat{y}(0) = e_0$$

and scale $y = \frac{\hat{y}}{e_0}$

$$\begin{cases} y' = \lambda y \\ y(0) = 1 \end{cases} \rightarrow \text{the problem we have to test}$$

Apply Euler's method

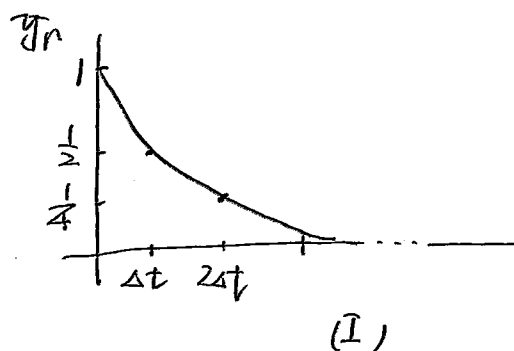
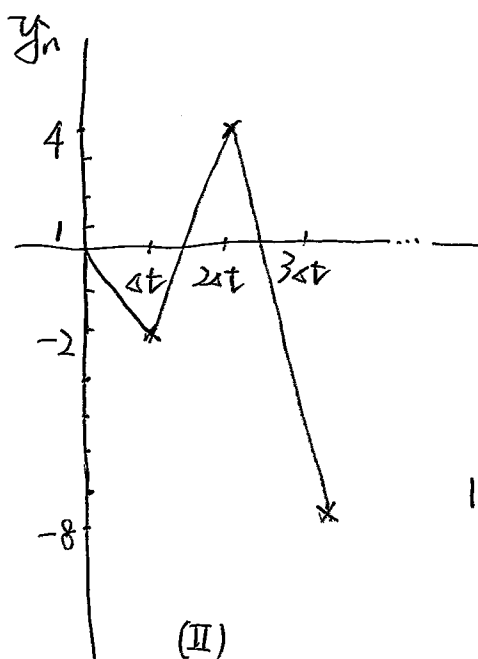
$$\begin{aligned} y_{n+1} &= y_n + \Delta t (\lambda y_n) \\ &= (1 + \lambda \Delta t) y_n \end{aligned}$$



Assume λ is real and negative ($\lambda < 0$)

CASE I: choose $\lambda \Delta t$, such that $1 + \lambda \Delta t = \frac{1}{2}$

CASE II: choose Δt , $\Rightarrow 1 + \lambda \Delta t = -2$



$n \rightarrow \infty$
 $|y_n| \rightarrow \infty$ blows up.

To Not blow up,

$$|1 + \lambda \Delta t| \leq 1$$

Definition: A step-by-step method is absolutely stable if

$$|y_{n+1}| \leq |y_n|$$

Forward Euler is absolutely stable if $|1 + \lambda \Delta t| \leq 1$

in
3.15
time

$$\frac{dy}{dt} = F(t, y)$$

$$t_n = n \cdot \Delta t$$

$$y_{n+1} = y_n + \Delta t \cdot F(t_n, y_n)$$

$$|y_N - y(T)| = O(\Delta t)$$

But Δt must satisfy $|1 + \lambda \Delta t| \leq 1$ for $y' = \lambda y$

$$|1 + \lambda \Delta t| \leq 1 \Leftrightarrow |1 + \lambda \Delta t|^2 \leq 1$$

let $x \equiv \text{Re}(\lambda \Delta t)$ Real

$y \equiv \text{Im}(\lambda \Delta t)$ Imagine

Then for absolute stability

$$|1 + x + iy|^2 \leq 1$$

$$(1+x)^2 + y^2 \leq 1$$

ie. $\lambda \Delta t$ must be inside the unit circle.

EX: $y' = -100y$

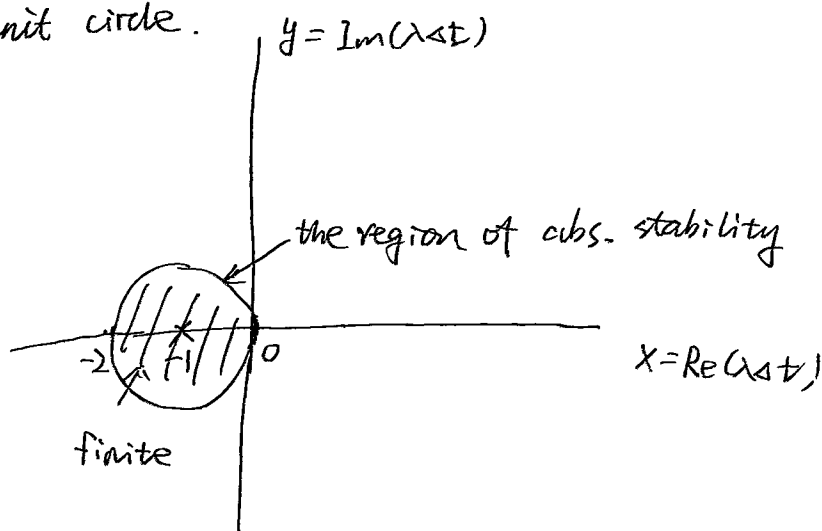
$y(0) = 1$

compute $t \in [0, 100]$

Δt is limited: $\lambda \Delta t \geq -2$

$-100 \Delta t \geq -2$

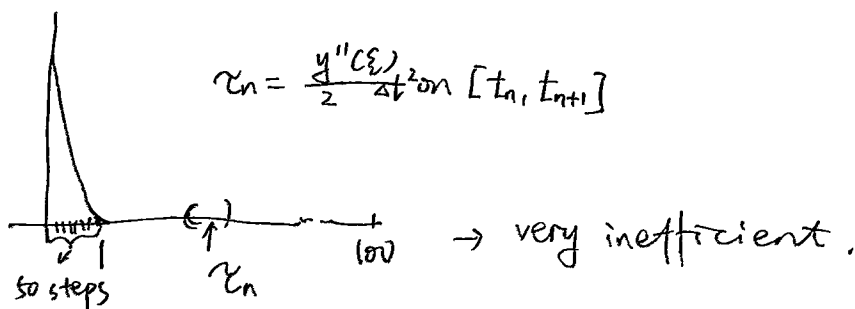
$\Delta t \leq \frac{1}{50}$



Need 5000 steps.

But

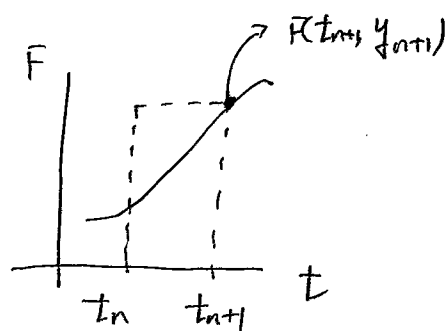
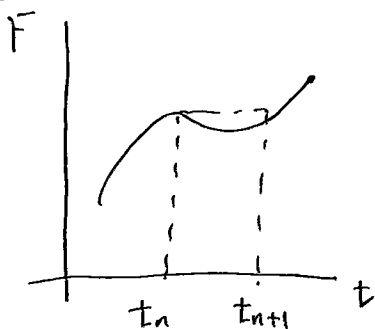
$$\tau_n = \frac{y''(\xi)}{2 \Delta t^2} \text{ on } [t_n, t_{n+1}]$$



2.7.2 Implicit Methods

70

Forward Euler:



alternately (alternately) choose right value

$$\left. \begin{aligned} y_{n+1} &= y_n + \int_{t_n}^{t_{n+1}} F(t, y) dt + \tau_n \\ y_{n+1} &= y_n + \Delta t F(t_{n+1}, y_{n+1}) \end{aligned} \right\}$$

Backward Euler: Example of Implicit method where

$$y_{n+1} = \underbrace{G(y_{n+1})}_{?}$$

Forward Euler: Example of Explicit method.

$$y_{n+1} = \hat{G}(y_n)$$

write as,

$$\phi(y) = y - G(y) = 0$$

i.e. A (non-linear) root-finding problem.

$$y_{n+1} = y_n + \Delta t F(t_{n+1}, y_{n+1})$$

$$y_{n+1} - y_n - \Delta t F(t_{n+1}, y_{n+1}) = 0$$

root-finding

A common approx. is 1 step of Newton-Raphson

$$F(t_{n+1}, y_{n+1}) = F(t_{n+1}, y_n) + \underbrace{\cancel{\Delta t}}_J \cdot \underbrace{\frac{\partial F}{\partial y}}_{\Delta y_n} (y_{n+1} - y_n) + O(\Delta t^2)$$

$$y_{n+1} - y_n = \Delta y_n$$

$$\Delta y_n - \Delta t (F(t_{n+1}, y_n) + \cancel{\Delta t} \cdot J \cdot \Delta y_n) = 0$$

$$(I - \Delta t J) \Delta y_n = \Delta t F(t_{n+1}, y_n)$$

↑
solve for Δy_n update $y_{n+1} = y_n + \Delta y_n$

why do the extra work?

z'

bring calculator
bring paper.

(error formula for
interpolation
formula for error for
interpolant.)

$$3.1) \quad y_{n+1} = y_n + \Delta t F(t_n, y_n) \quad \text{explicit}$$

$$E = O(\Delta t)$$

$$\tau = O(\Delta t^2)$$

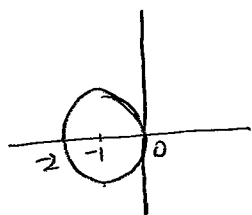
$$y_{n+1} = y_n + \Delta t F(t_{n+1}, y_{n+1}) \quad \text{implicit}$$

$$\tau = O(\Delta t^2) \quad \text{exercise}$$

$$E = O(\Delta t)$$

absolute stability.

For Euler



for Backward Euler

$$y_{n+1} = y_n + \lambda \Delta t y_{n+1}$$

$$(1 - \lambda \Delta t) y_{n+1} = y_n$$

$$y_{n+1} = \frac{y_n}{1 - \lambda \Delta t}$$

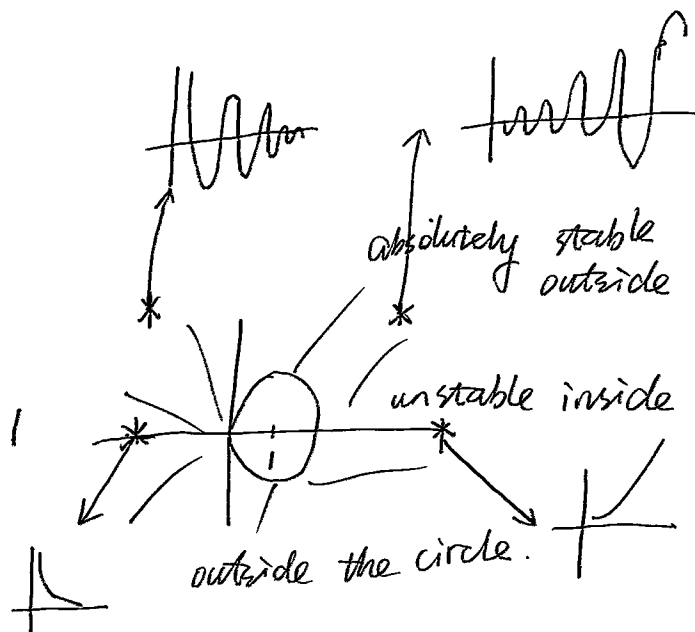
solution looks like.

then $\left| \frac{1}{1 - \lambda \Delta t} \right| \leq 1$

$$x = \operatorname{Re}(\lambda \Delta t) \quad \text{real}$$

$$y = \operatorname{Im}(\lambda \Delta t) \quad \text{imaginary}$$

$$\frac{1}{|1 - x - iy|^2} \leq 1 \quad \Rightarrow \quad \frac{1}{(1-x)^2 + y^2} \leq 1$$



Def: A method is A-stable if its region of absolute stability includes the entire left half of the complex plane.

EX:

Backward Euler is A-stable.

Another implicit method is the trapezoidal rule.

$$y_{n+1} = y_n + \int_{t_n}^{t_{n+1}} F(t, y_t) dt$$

$$y_{n+1} = y_n + \frac{\Delta t}{2} (F(t_n, y_n) + F(t_{n+1}, y_{n+1}))$$

EX 11) second order method

note: $S^0 y_{n+\frac{1}{2}} = \frac{1}{2} (F(t_n, y_n) + F(t_{n+1}, y_{n+1}))$

(2) A-stable

2.7.3 Higher Order Methods and Runge Kutta

Forward & Backward Euler are the 1st order

$$E = O(\Delta t)$$

$$\Rightarrow E_{rel} = O(\Delta t)$$

one significant figures requires 10x more work.

Need higher order, i.e. match the Taylor series for solution to higher order

$$y_{n+1} = y_n + \underbrace{\Delta t F_n}_{1^{st} \text{ order}} + \underbrace{\frac{\Delta t^2}{2} F'_n}_{2^{nd} \text{ order}} + \dots$$

$$y_{n+1} = y_n + \Delta t \bar{F}_n + \frac{\Delta t^2}{2} \bar{F}'_n \rightarrow 2^{\text{nd}} \text{ order Taylor Method.}$$

instead, we approximate the higher derivatives

eg. $F'_n = \delta F_n$

$$y_{n+1} = y_n + \Delta t \bar{F}_n + \frac{\Delta t^2}{2} \delta \bar{F}_n$$

$$y_{n+1} = y_n + \Delta t \left(\bar{F}_n + \frac{1}{2} (F_n - F_{n-1}) \right)$$

$$y_{n+1} = y_n + \Delta t \left(\frac{3}{2} \bar{F}_n - \frac{1}{2} \bar{F}_{n-1} \right)$$

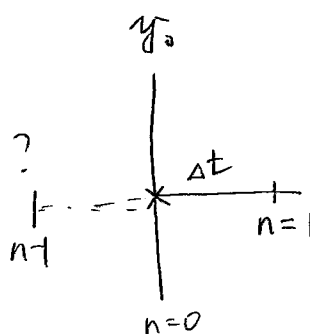
2nd order
adams-bashforth

requires step $n \rightarrow n+1$ to get $n+1$
2 steps

Example of a multistep method.



but it's not self starting



Runge-Kutta Methods Approximate

The derivations using the F values only in $[t_n, t_{n+1}]$.

General formula: (explicit)

$$y_{n+1} = y_n + \Delta t \Psi(t_n, y_n, \Delta t)$$

where $\Psi(t_n, y_n, \Delta t) = \sum_{j=0}^{s-1} \alpha_j k_j$

and $k_0 = F(t_n, y_n)$

$$k_j = F\left(t_n + n_j \Delta t, y_n + \Delta t \sum_{i=1}^{j-1} \alpha_{ji} k_i\right) = F\left(t_n + n_j \Delta t, y_n + \Delta t \sum_{i=1}^{j-1} \alpha_{ji} k_i\right)$$

EX: $s=1, \gamma_0=1$

$y_{n+1} = y_n + \Delta t F(t_n, y_n)$ ie. forward Euler

3.27

$$y_{n+1} = y_n + \Delta t \cdot \Psi(t_n, y_n, \Delta t)$$

$$\Psi(t_n, y_n, \Delta t) = \sum_{j=0}^{s-1} \delta_j k_j$$

$$k_0 = F(t_n, y_n)$$

$$k_j = F\left(t_n + n_j \cdot \Delta t, y_n + \Delta t \sum_{i=1}^{j-1} \alpha_i \cdot k_i\right)$$

Euler

$$\Psi = F(t_n, y_n)$$

$$s=1$$

$$n_0=0$$

$$\alpha_0=0$$

second order RK ($s=2$)

$$\Psi_n = \gamma_0 k_0 + \gamma_1 k_1$$

$$k_1 = F(t_n + n \cdot \Delta t, y_n + \Delta t \cdot \alpha \cdot k_0)$$

ie. $y_{n+1} = y_n + \Delta t \{ \gamma_0 F(t_n, y_n) + \gamma_1 F(t_n + n \Delta t, y_n + \Delta t \cdot \alpha \cdot F(t_n, y_n)) \}$

find γ_0 & γ_1 , so that $\tau_n = O(\Delta t^3)$

exact: $y_{n+1} = y_n + \Delta t F_n + \frac{\Delta t^2}{2} F'_n + O(\Delta t^3)$

$$= y_n + \Delta t F_n + \frac{\Delta t^2}{2} \left(\frac{\partial F}{\partial t} + \frac{\partial F}{\partial y} \cdot F \right)$$

$$F' = \frac{dF(t, y(t))}{dt}$$

$$\frac{dy}{dt} = F$$

$$y_{n+1} = y_n + \Delta t \left\{ \gamma_0 F_n + \gamma_1 \left(F_n + n \Delta t \frac{\partial F_n}{\partial t} + \alpha \Delta t \cdot \frac{\partial F_n}{\partial y} * F_n + O(\Delta t^2) \right) \right\} + \tau$$

$$= y_n + (\gamma_0 + \gamma_1) \Delta t F_n + \Delta t^2 \left(\frac{\partial F_n}{\partial t} \cdot n \gamma_1 + \gamma_1 \alpha \cdot \frac{\partial F_n}{\partial y} \right) + \tau + O(\Delta t^3)$$

Match

$$\begin{cases} \gamma_0 + \gamma_1 = 1 \\ \gamma_1 n = \frac{1}{2} \\ \gamma_1 \alpha = \frac{1}{2} \end{cases} \Rightarrow \begin{cases} \gamma_0 = 1 - \gamma_1 \\ n = \frac{1}{2\gamma_1} \\ \alpha = \frac{1}{2\gamma_1} \end{cases}$$

some old favorites

1) $\gamma_1 = 1$, modified Euler
 $\gamma_0 = 0$,
 $n = \alpha = \frac{1}{2}$

$$y_{n+1} = y_n + \Delta t F\left(t_n + \frac{\Delta t}{2}, y_n + \frac{\Delta t}{2} F_n\right)$$

(2) Heun $\gamma_1 = \frac{1}{2} \Rightarrow \gamma_0 = \frac{1}{2}, \alpha = n = 1$

$$y_{n+1} = y_n + \frac{\Delta t}{2} \left(F\left(t_n + \Delta t, y_n + \Delta t F_n\right) + F_n \right)$$

$$k_0 = F(t_n, y_n)$$

$$k_1 = F(t_n + \Delta t, y_n + \Delta t k_0)$$

$$y_{n+1} = \frac{1}{2} k_0 + \frac{1}{2} k_1$$

3.24

second order RK

$$\begin{cases} k_0 = F(t_n, y_n) \\ k_1 = F(t_n + \frac{\Delta t}{2}, y_n + \frac{\Delta t}{2} k_0) \\ \bar{y}_n = (1 - \gamma_1) k_0 + \gamma_1 k_1 \\ y_{n+1} = y_n + \Delta t \bar{y}_n \end{cases}$$

$$\tau_n = O(\Delta t^3)$$

$$E = O(\Delta t^2)$$

classic 4th order RK

$$k_0 = F(t_n, y_n)$$

$$k_1 = F(t_n + \frac{\Delta t}{2}, y_n + \frac{\Delta t}{2} k_0)$$

$$k_2 = F(t_n + \frac{\Delta t}{2}, y_n + \frac{\Delta t}{2} k_1)$$

$$k_3 = F(t_n + \frac{\Delta t}{1}, y_n + \Delta t k_2)$$

$$y_{n+1} = y_n + \frac{\Delta t}{6} (k_0 + 2k_1 + 2k_2 + k_3)$$

$$y' = F(t) \quad \text{Solve } \begin{cases} y' = F(t, y) & t \in (0, T) \\ y(0) = y_0 \end{cases}$$

$$N = \frac{T}{\Delta t}$$

procedure integrate

$$N = \frac{T}{\Delta t}$$

y = initial value

$$N = \frac{T}{\Delta t}$$

y = initial value

for $n=0$ to $N-1$

$$t = n \cdot \Delta t$$

$y = \text{take one step}(t, y, F, \Delta t)$

next n \nwarrow prime?

end procedure

take one step $(t, y, F, \Delta t)$ (HEUN)

$$k_0 = F(t, y)$$

$$k_1 = F(t + \Delta t, y + k_0 \Delta t)$$

$$y = y + \frac{\Delta t}{2} (k_0 + k_1)$$

return y

end

Error Estimate.

N steps w/ Δt

$$y_N(\Delta t) = y(T) + O(\Delta t^r)$$

redo

$$y_{2N}(\frac{\Delta t}{2}) = y(T) + O((\frac{\Delta t}{2})^r)$$

Assume: $E_{\Delta t} \approx C \Delta t^r$

$$y_N - y_{2N} \approx (1 - \frac{1}{2^r}) (C \Delta t^r)$$

$$\begin{cases} y_N(\Delta t) = y(T) + C \Delta t^r \\ y_{2N}(\frac{\Delta t}{2}) = y(T) + C (\frac{\Delta t}{2})^r \end{cases}$$

$$E_{\Delta t} \approx \frac{y_N - y_{2N}}{2^r - 1} \cdot 2^r$$

$$E_{\frac{\Delta t}{2}} \approx \frac{y_N - y_{2N}}{2^r}$$

Chapter 3: Introduction to Option Pricing.

79

simplest options are of value a european type. Two types.

(1) European Call

give the buyer the right but not the obligation to buy an asset S , at time T for price K .

$$\text{Payoff: } C(T) = (S(T) - K)^+ = \max(S(T) - K, 0)$$

(2) European Put

sell S at T for price K .

$$\text{payoff: } P(T) = \max(K - S(T), 0)$$

the American version

can exercise at any time up to T .

Want to know how to price, ie. value of option today.

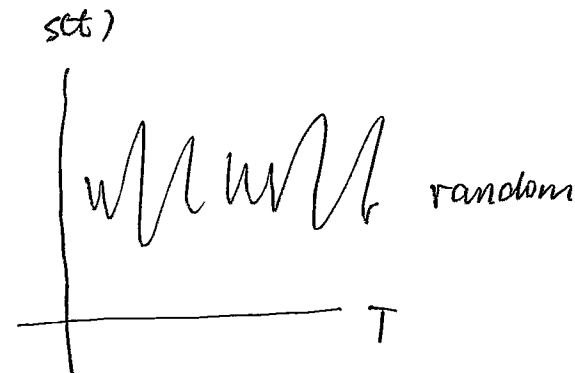
American adds: when to exercise.

3.1 The Black-Scholes Model

Problem is we don't know $S(t)$.

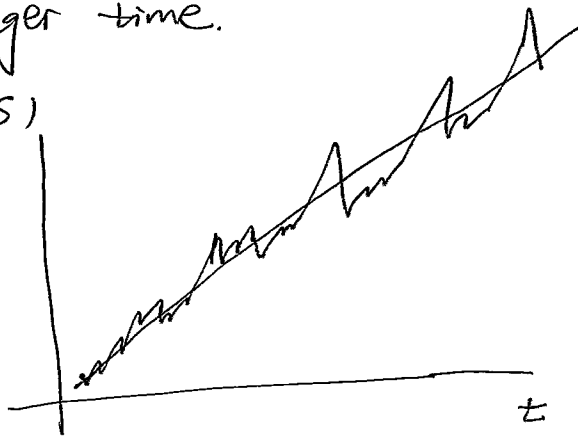
but we know that over short time:

→



over longer time.

$\log(S)$



exponential + random drift

without random, $\frac{ds}{s} = u(t)dt$
 \uparrow drift rate

if u is constant, $S(t) = e^{ut}$

B.S. Model.

$$\frac{ds}{s} = \underset{\uparrow}{u} dt + \underset{\uparrow}{\sigma} dz$$

constant volatility = const

dz is an increment of Wiener process.

Def: A scalar standard Brownian Motion AKA

a standard Wiener process over $[0, T]$ is a random variables $w(t)$ that depends continuously on $t \in [0, T]$ and satisfies

1. $w(0) = 0$ w/probability 1

2. for $0 \leq s \leq t \leq T$

$w(t) - w(s)$ is normally distributed.

w/ mean 0 & variance $t - s$

$$w(t) - w(s) \sim \sqrt{t-s} N(0, 1)$$

3. $0 \leq s < t < u \leq v \leq T$

$w(t) - w(s)$ and $w(u) - w(v)$ are independent.

property # 2. $\Rightarrow dz = \sqrt{t} \phi$

$$\frac{ds}{s} = \mu dt + \sigma \sqrt{t} \phi \text{ is a stochastic D.E.}$$

lets find $E\left[\frac{1}{s} \frac{ds}{dt}\right]$ and $\text{Var}\left[\frac{1}{s} \frac{ds}{dt}\right]$