Computer Vision: Representation and Recognition Assignment 2

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1 Edge Detection

1.1 design choices and parameters

- (i) Gaussian std=sigma=1
- (ii) The non-maxima suppression algorithm is based on my own estimates of the magnitude and orientation. The boundary scores can be rescaled to an exponent of 0.7, as the manual suggests for better visualization.

1.2 bank of filters

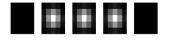


Figure 1: bank of filters(different orientations of Gaussian kernels).

1.3 Qualitative results

see figure 2 and figure 3.



Figure 2: result of gradient-based edge detector



Figure 3: result of oriented filters

1.4 Quantitative results

Method gradient: overall F-score = 0.565 average F-score = 0.589 Method oriented: overall F-score = 0.564 average F-score = 0.589





Figure 4: pr of gradient-based edge detector

Figure 5: pr of oriented filters

1.5 Ideas for improvement

The noise and the edge signal are both high frequency signals. Therefore, a simple Gaussian operation may erase edges while smoothing the whole image. As a result, we can use selective smoothing methods, which can preserve edges.

Furthermore, we can choose different kernels for gradient calculation, which may improve the accuracy of finding true edges.

2 Image segmentation with k-means

2.1 parameter values

winSize, numColorRegions, numT extureRegions=3, 10, 10

2.2 segmentation results

Results are as follows (figure 6-17). The upper one is the segmentation result of texture, while the other is the segmentation result of color.



Figure 6: coins



Figure 7: segmentation results



Figure 8: gumballs



Figure 9: segmentation results



Figure 10: planets



Figure 12: snake



Figure 11: segmentation results





Figure 13: segmentation results

2.3 window sizes

As we can see in figure 18 and figure 19, a smaller window size will have a more precise segamentation result, while a largers window size will have less noise.

2.4 run script

run segmentMain.m to get the result of a certain image and you may change target image and parameters in function compareSegmentations(line 17).



Figure 14: twins



Figure 15: segmentation results



Figure 16: my image





Figure 17: segmentation results



Figure 18: winSize=3



Figure 19: winSize=11