

ENGI 7854/9804 Image Processing and Applications

Laboratory 3

Frequency domain filtering

Due: July 17, 2020

Introduction

The objective of this laboratory exercise is to get familiarized with frequency domain filtering concepts.

Frequency Domain Procedure Review

The frequency domain image filtering process can be performed as follows:

1. Given the input image $f(x, y)$ of size $M \times N$, obtain the padding sizes $P = 2M$ and $Q = 2N$.
2. Form a padded image of size $P \times Q$ using zero padding.
3. Multiply $f(x, y)$ by $(-1)^{x+y}$ to centre the Fourier transform (FT) on the $P \times Q$ frequency rectangle.
4. Compute the DFT, $F(u, v)$ of the centred image
5. Construce a real, symmetric filter transfer function, $H(u, v)$, of size $P \times Q$ with centre at $(P/2, Q/2)$.
6. Form the product $G(u, v) = H(u, v)F(u, v)$ using element-wise multiplication.
7. Obtain the Inverse Fourier transform of $G(u, v)$, ignoring parasitic complex components:
$$g_p(x, y) = (\text{real}[\mathfrak{F}^{-1}G(u, v)])(-1)^{x+y}$$
8. Obtain the final result, $g(x, y)$, of the same size as the input image by extracting the $M \times N$ region from the top left quadrant of $g_p(x, y)$.

Note that centering the transform helps to visualize the filtering process and to generate the filter functions, but centering is not a fundamental requirement.

Part 1: Low pass and High pass filter design

1. Download the test image (puppy.jpg) and *lp_hp_filters.m* from D2L under *Lab 3* and save it in the MATLAB working directory. Read the file and understand the implementation.
2. Read the image and convert the image to a grayscale image. Obtain the padding parameters and FT the image.

```
F_rgb=imread('puppy.jpg'); % read the gs image
F=rgb2gray(F_rgb);
im_size=size(F); % Obtain the size of the image
P=2*im_size(1);Q=2*im_size(2); % Obtaining padding parameters
    as 2*image size
FTIm=fft2(double(F),P,Q); % FT with padded size
```

3. Design the ILPF

```
D0 = 0.1*im_size(1); %Cutoff frequency radius is 0.1 times the
    the hight of the image
n=0; %For use only in Butterworth filters. For BTW filters,
    Order(n)>0
    %Filter_type=('ideal' or 'btw' or 'gaussian')
    %lp_or_hp=('lp' or 'hp' for low pass or high pass),
Filter = lp_hp_filters('ideal','lp', P, Q, D0,n); % Calculate
    the LPF
```

4. Implement the filter by multiplying the FT of the image with filter. Undo padding.

```
Filtered_image=real(ifft2(Filter.*FTIm)); % multiply the FT of
    image by the filter and apply the IDFT
Filtered_image=Filtered_image(1:im_size(1), 1:im_size(2)); %
    Resize the image ( undo padding)
```

5. Move the origin of frequency spectrum to the center and display the results

```
Fim=fftshift(FTIm); % move the origin of the FT to the center
FTI=log(1+abs(Fim)); % compute the magnitude (log to brighten
    display)
Ff=fftshift(Filter); % move the origin of the FT to the center
FTF=log(1+abs(Ff)); % compute the magnitude (log to brighten
    display)

subplot(2,2,1), imshow(F,[]), title('Original Image'); % show
    the image
subplot(2,2,2), imshow(FTI,[]), title('FT of Original'); %
    show the image
subplot(2,2,3), imshow(FTF,[]), title('Filter in frequency
    domain'); % filter
subplot(2,2,4), imshow(Filtered_image,[]), title('Filtered
    Image'); % show the image
```

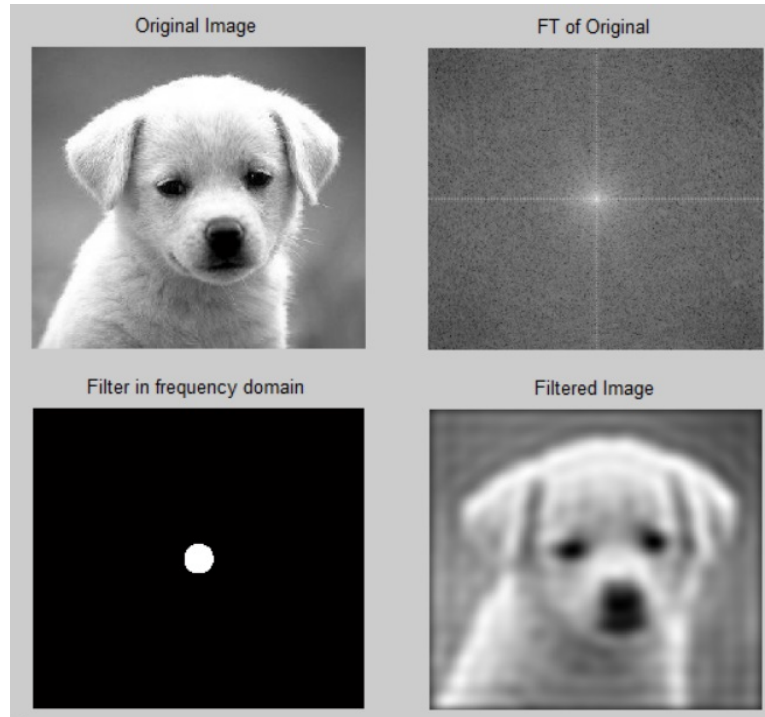


Figure 1: Result of ILPF the image

Part 2

1. Implement an *Ideal* low pass filter for cutoff frequencies (0.3 and 0.7 of image height).
2. Implement a *Butterworth* low pass filter for cutoff frequencies (0.1 and 0.5 of image height) and order $n = 1, 5, 20$.
3. Implement a *Gaussian* low pass filter for cutoff frequencies (0.1, 0.3 and 0.7 of image height) .
4. Implement an *Ideal* high-pass filter for cutoff frequencies (0.1, 0.3 and 0.7 of image height).
5. Implement a *Butterworth* high pass filter for cutoff frequencies (0.1 and 0.5 of image height) and order $n = 1, 5, 20$.
6. Perform a *Gaussian* high pass filtering for cutoff frequencies (0.1, 0.3 and 0.7 of image height).

Discussion

1. What can you observe when increasing the cut off frequency radius of the *Ideal* filter?
2. What can you observe when increasing the order of the *Butterworth* filter when the cut-off frequency remains the same?
3. Discuss the *general* performance of the *Gaussian* filters in comparison to the *Ideal* and *Butterworth* filters. You do not need to discuss each possible comparison case. Only discuss any interesting phenomenon or performance observations.

Note: Include your MATLAB code in your lab report along with your results.