

Algorithm Design and Analysis (H) cs216

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(slides edited from Prof. Shiqi Yu)



Divide and Conquer



Divide-and-Conquer Paradigm

Divide-and-conquer.

- Divide up problem into several subproblems (of the same kind).
- Solve (conquer) each subproblem recursively.
- Combine solutions to subproblems into overall solution.

Most common usage.

- \triangleright Divide problem of size *n* into two subproblems of size n/2.
- Solve (conquer) two subproblems recursively.
- Combine two solutions into overall solution.

Time complexity.

 \triangleright Brute force: $\Theta(n^2)$.

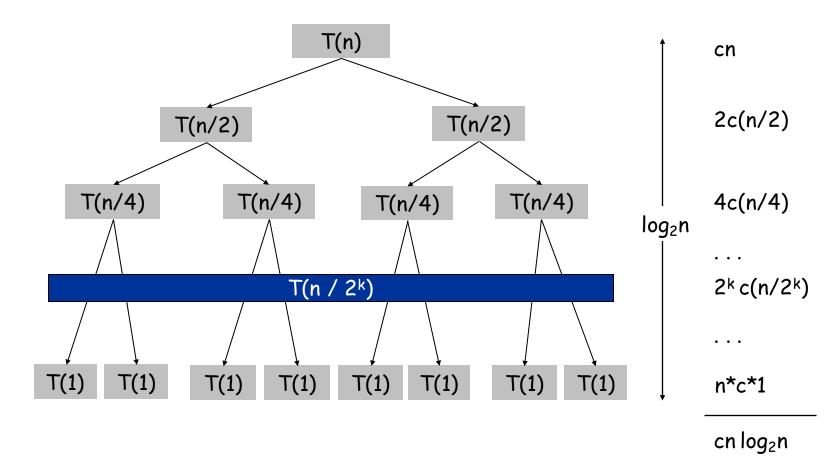
ightharpoonup Divide-and-conquer: $O(n \log n)$. \leftarrow T(n) = 2T(n/2) + O(n)

O(n) time



Divide-and-Conquer Recurrences

• Example: T(n) = 2T(n/2) + O(n) with T(1) = O(1)







Divide-and-Conquer Recurrences

• Divide-and-conquer recurrences: T(n) = aT(n/b) + f(n) with $T(1) = \Theta(1)$

• Master theorem. Let $a \ge 1$, $b \ge 2$, and $c \ge 0$ and suppose that T(n) is a function on the non-negative integers that satisfies the recurrence

$$T(n) = aT(n/b) + \Theta(n^c)$$

with $T(1) = \Theta(1)$, where n/b means either $\lfloor n/b \rfloor$ or $\lceil n/b \rceil$. Then,

- Case 1. If $c > \log_b a$, then $T(n) = \Theta(n^c)$.
- Case 2. If $c = \log_b a$, then $T(n) = \Theta(n^c \log n)$.
- Case 3. If $c < \log_b a$, then $T(n) = \Theta(n^{\log_b a})$.





1. Counting Inversions





Counting Inversions

- Match song preferences.
 - Every person ranks *n* songs.
 - Music site consults database to find people with similar tastes.
- Similarity metric: number of inversions between two rankings.
 - My rank: 1, 2, ..., n.
 - \triangleright Your rank: a_1 , a_2 , ..., a_n .
 - \triangleright Songs *i* and *j* are inverted if i < j but $a_i > a_j$.
- Brute force: check all $\Theta(n^2)$ pairs.
- Q. Can we count inversions faster?

	Α	В	С	D	Е
Me	1	2	3	4	5
You	1	3	4	2	5
		1	<u> </u>		

Inversions

3-2, 4-2

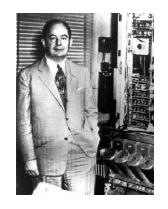
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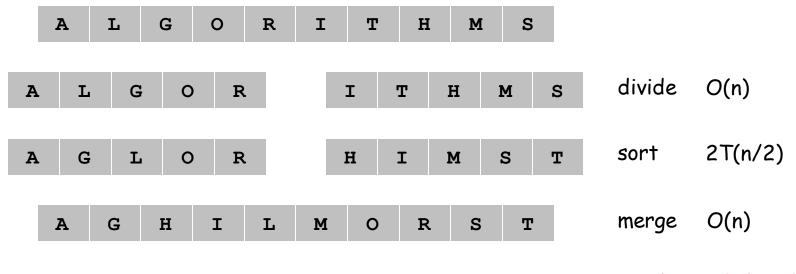
Recall: Mergesort

Mergesort.

- Divide array into two halves.
- Recursively sort each half.
- Merge two halves to make sorted whole.



Jon von Neumann (1945)



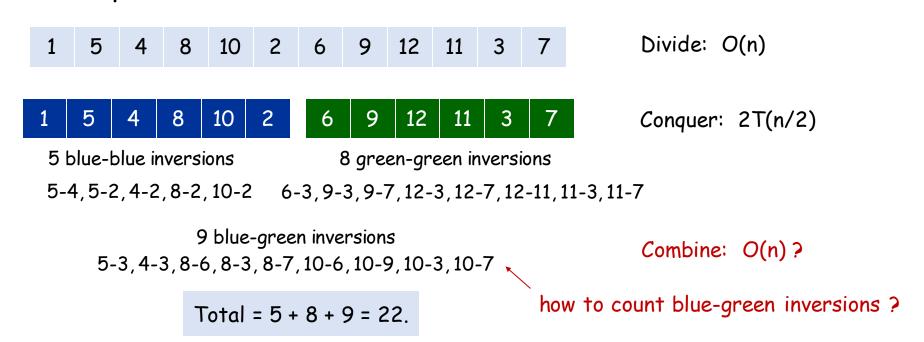
total O(n log n)



Counting Inversions: Divide-and-Conquer

Divide and conquer.

- Divide: separate list into two pieces.
- Conquer: recursively count inversions in each half.
- \triangleright Combine: count inversions where a_i and a_j are in different halves and return sum of three quantities.



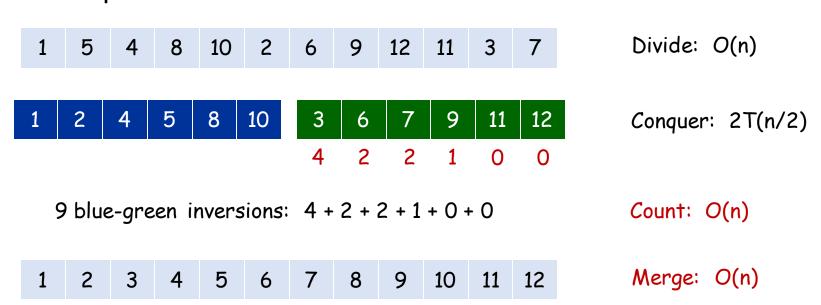
easy to count if both sorted



Counting Inversions: Divide-and-Conquer

Divide and conquer.

- Divide: separate list into two pieces.
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easy to count if both sorted



Counting Inversions: O(n log n) Algorithm

Divide-and-conquer algorithm:

```
Sort-and-Count(L) {
   if list L has one element
      return (0, L)

Divide the list into two halves A and B
      (r<sub>A</sub>, A) = Sort-and-Count(A)
      (r<sub>B</sub>, B) = Sort-and-Count(B)
      (r<sub>AB</sub>, L) = Merge-and-Count(A, B)
   return (r<sub>A</sub> + r<sub>B</sub> + r<sub>AB</sub>, L)
}
```

- Pre-condition. [Sort-and-Count] A and B are sorted.
- Post-condition. [Merge-and-Count] L is sorted.





2. Median and Selection



Median and Selection

- Median and selection. Given *n* elements from a totally ordered universe, find the median element or in general the *k*-th smallest.
 - \blacktriangleright Minimum or maximum: k = 1 or k = n.
 - \rightarrow Median: k = [(n + 1) / 2].
 - \triangleright O(n) compares for min or max.
 - \triangleright $O(n \log n)$ compares by sorting.
 - \triangleright $O(n \log k)$ compares with a binary heap.
- Applications. Order statistics, find the "top k", bottleneck paths, etc.

- Q. Can we do it with O(n) compares?
- A. Yes! Selection is easier than sorting.



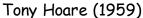


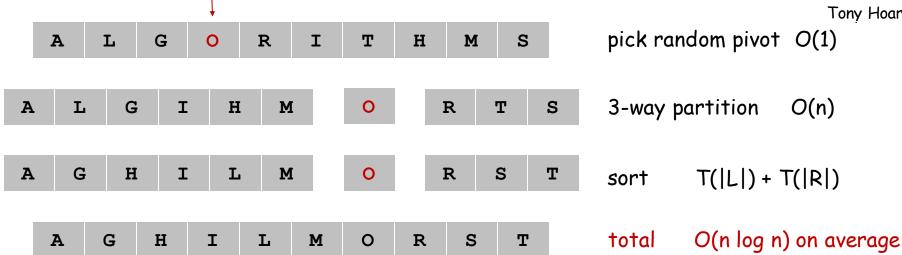
Recall: Randomized Quicksort

Randomized quicksort.

- Pick a random pivot element p.
- \triangleright 3-way partition the array into L, M, and R.
 - ✓ L elements < p, M elements = p, R elements > p.
- Recursively sort both L and R.





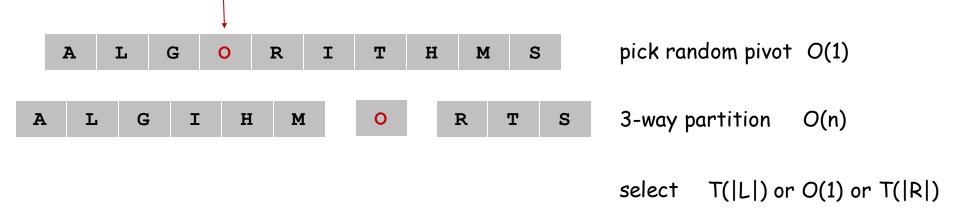




Median and Selection: Divide-and-Conquer

Divide and conquer.

- Pick a random pivot element p.
- \triangleright 3-way partition the array into L, M, and R.
 - ✓ L elements < p, M elements = p, R elements > p.
- \triangleright Recursively select in one subarray: the one containing the k-th smallest element.





Randomized Quickselect

Divide and conquer.

- Pick a random pivot element p.
- \triangleright 3-way partition the array into L, M, and R.
 - ✓L elements < p, M elements = p, R elements > p.
- \triangleright Recursively select in one subarray: the one containing the k-th smallest element.

```
Quick-Select(A, k) { // 1 ≤ k ≤ |A|
  Pick pivot p uniformly at random from A
  Partition the list into two three parts L, M and R
  if k ≤ |L|
    return Quick-Select(L, k)
  else if k > |L| + |M|
    return Quick-Select(R, k - |L| - |M|)
  else
    return p
}
```





Randomized Quickselect: Time Complexity

- Randomized quickselect.
 - Pick a random pivot element p.
 - \triangleright 3-way partition the array into L, M, and R.
 - ✓L elements < p, M elements = p, R elements > p.
 - \triangleright Recursively select in one subarray: the one containing the k-th smallest element.
- Intuition. Split length-n array uniformly \Rightarrow expected larger size $\sim 3n/4$.
 - $ightharpoonup T(n) \le T(3n/4) + n \Rightarrow T(n) \le 4n$
 - \triangleright However, not rigorous because we cannot assume $\mathbf{E}(T(k)) \le T(\mathbf{E}(k))$.

- Q. What is the expected time complexity of randomized quickselect?
 - > Time complexity is measured by the number of compares.





Randomized Quickselect: Time Complexity

- Def. T(n, k) = expected number of compares to select the k-th smallest element in an array of length $\leq n$.
- Def. $T(n) = \max_k T(n, k)$.

- Claim. $T(n) \leq 4n$.
- Pf. (by strong induction on *n*)

can assume always recur in larger subarrays since T(n) is monotone non-decreasing

$$T(n) \le n + 1/n \left[2T(n/2) + ... + 2T(n-3) + 2T(n-2) + 2T(n-1) \right]$$

 $\le n + 1/n \left[8(n/2) + ... + 8(n-3) + 8(n-2) + 8(n-1) \right]$
 $\le n + 1/n (3n^2)$
 $= 4n$. inductive hypothesis





More on Median and Selection

• We learned that randomized quickselection runs in O(n) on average.

- [Blum–Floyd–Pratt–Rivest–Tarjan 1973] There exists a compare-based deterministic selection algorithm whose worst-case running time is O(n).
 - > This algorithm is also known as the median of medians.
 - \triangleright Optimized version requires ≤ 5.4305*n* compares.

- In practice, we use randomized selection algorithms since deterministic algorithms have too large constants.
 - However, deterministic algorithms can be used as a fallback for pivot selection.





3. Closest Pair of Points



Closest Pair of Points

- Closest pair problem. Given n points in the plane, find a pair with smallest Euclidean distance between them.
- Fundamental geometric primitive.
 - Widely used in graphics, computer vision, geographic information systems, molecular modeling, air traffic control, etc.
 - Special case of nearest neighbor, Euclidean MST, Voronoi diagram, etc.

fast closest pair inspired fast algorithms for these problems

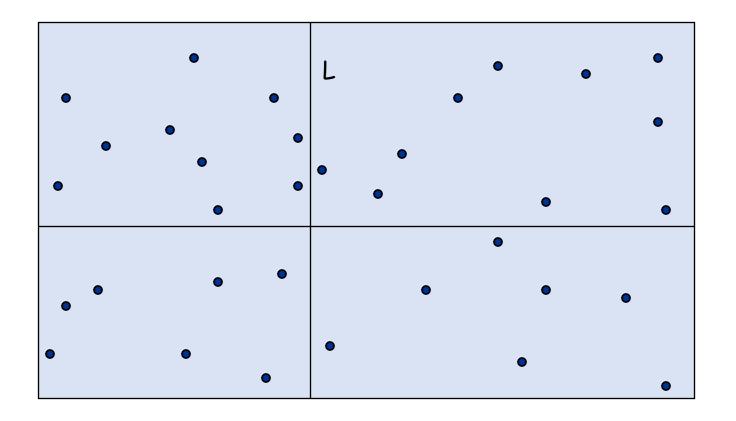
- Brute force. Check all pairs with $\Theta(n^2)$ distance calculations.
- 1-D version. Easy $O(n \log n)$ algorithm if points are on a line.





Closest Pair of Points: First Attempt

• Divide. Sub-divide region into 4 quadrants.

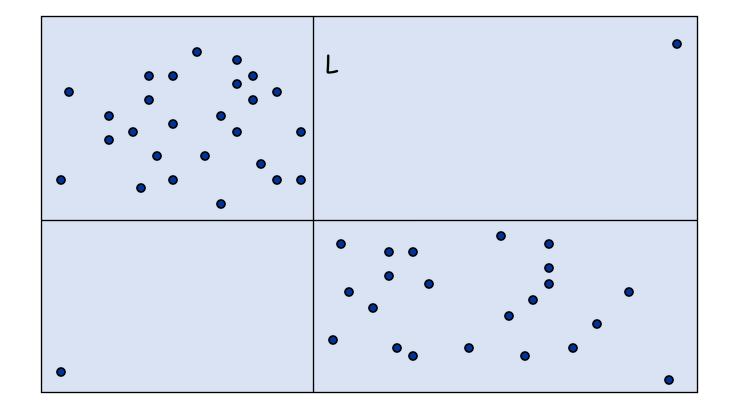






Closest Pair of Points: First Attempt

- Divide. Sub-divide region into 4 quadrants.
- Obstacle. Impossible to ensure n/4 points in each piece.





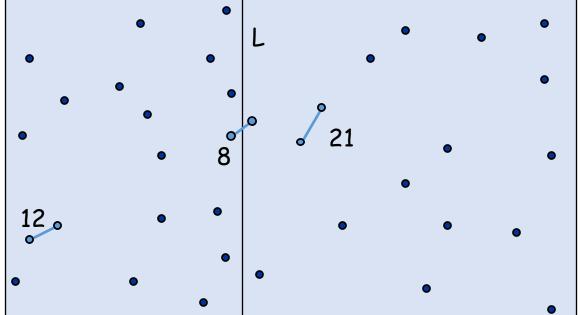


Closest Pair of Points: Divide and Conquer

Divide and conquer.

- ➤ Divide: draw vertical line L so that roughly n/2 points lie in each side.
- Conquer: find closest pair in each side recursively.
- Combine: find closest pair with one point in each side.
- Return best of 3 solutions.

of 3 solutions. Can we beat $\Theta(n^2)$?

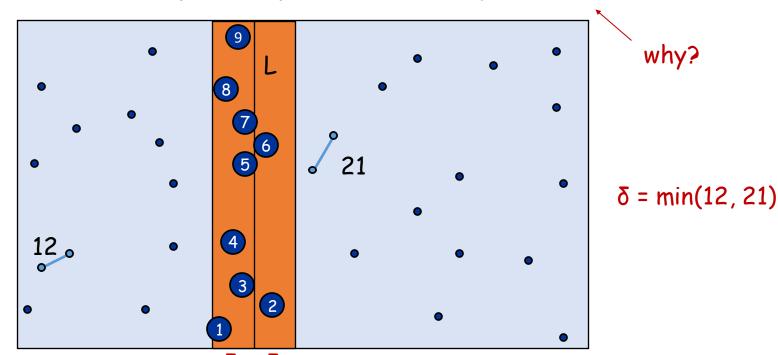






Closest Pair of Points: Divide and Conquer

- Combine: Find closest pair with one point in each side.
 - Problem Observation: suffices to consider only points within δ of line L, where δ is the distance of closest pair with both points in one side.
 - \triangleright Sort points in 2 δ -strip by their *y*-coordinate.
 - Check distances of only those points within 7 positions in sorted list!



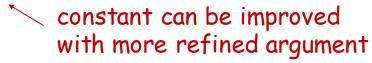


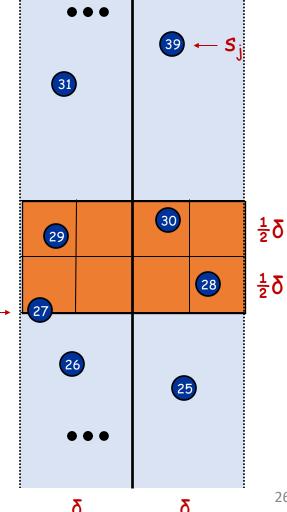
known from recursion



Closest Pair of Points: Divide and Conquer

- Def. Let s_i be the point in the 2δ -strip, with the *i*-th smallest *y*-coordinate.
- Claim. If |i-j| > 7, then the distance between s_i and s_i is at least δ .
- Pf.
 - Consider the 2δ -by- δ rectangle R in strip whose min y-coordinate is y-coordinate of s_i .
 - \triangleright Distance between s_i and any point s_i above R is ≥ δ.
 - > Subdivide R into 8 squares.
 - square diameter $< \delta$ At most 1 point per square.
 - ➤ At most 7 other points can be in R. •







Closest Pair of Points: O(n log n) Algorithm

Divide-and-conquer algorithm: [sort by x-axis and y-axis beforehand]

```
Closest-Pair (p_1, \ldots, p_n) {
   Compute vertical line L such that half the points
   are on one side and half on the other side.
   \delta_1 = Closest-Pair(left half)
   \delta_2 = Closest-Pair(right half)
   \delta = \min(\delta_1, \delta_2)
   Delete all points further than \delta from line L
   Sort remaining points by y-coordinate.
   Scan points in y-order and compare distance between
   each point and next 7 neighbors. If any of these
   distances is less than \delta, update \delta.
   return \delta.
```

```
use x-sorted list
O(n)
2T(n/2)
O(n)
O(n)
```





More on Closest Pair of Points

• [Rabin 1976] There exists an algorithm to find the closest pair of points in the plane whose expected running time is O(n).

- There are divide-and-conquer algorithms that solve the following core 2D geometric problems in $O(n \log n)$ time:
 - Farthest pair
 - Convex hull
 - Delaunay/Voronoi
 - Euclidean MST

