

# Further Studies on Heuristics

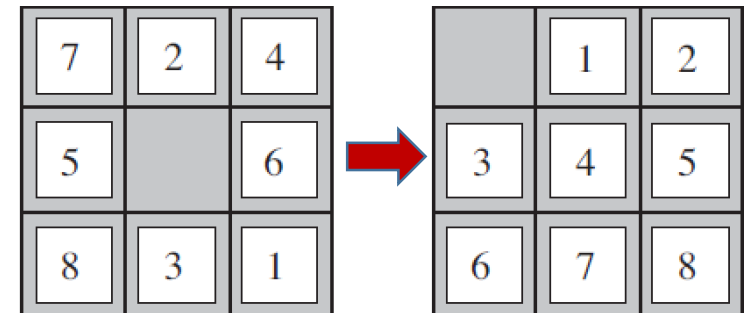
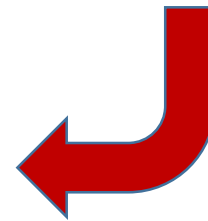
# **I. Search Efficiency of Heuristics**

# Recall: Heuristics for 8-puzzle

- $h_{mis}(s) = \# \text{misplaced tiles} \in [0,8]$ : **Admissible**.
- $h_{1stp}(s) = \#(1\text{-step move})$  to reach the goal configuration: **Admissible**.

➤  $h_{1stp}(s) \geq h_{mis}(s) \Rightarrow h_{1stp}(s)$  is '**better**' than  $h_{mis}(s)$ .

What does 'better' mean?



# Dominance

- For **admissible**  $h_1$  and  $h_2$ , if  $h_1(s) \geq h_2(s)$  for  $\forall s$   
 $\Rightarrow h_1$  **dominates**  $h_2$  and is **more efficient** for search.

- **Theorem**: For any admissible heuristics  $h_1$  and  $h_2$ , define

$$h(s) = \max\{h_1(s), h_2(s)\}$$

$h(s)$  is admissible and dominates both  $h_1$  and  $h_2$ .

- **‘Better’ heuristic = dominance = better search efficiency.**

# Even Better Dominance

- **Question:** Which one to choose from a collection of admissible heuristics  $h_1, \dots, h_m$  & none dominates any other?
- **Answer:**  $h(s) = \max\{h_1(s), \dots, h_m(s)\}$  dominates all the others.

# Quantify Search Efficiency

- **Effective Branching Factor  $b^*$** : For a solution from A\*, calculate  $b^*$  satisfying: 
$$N = b^* + (b^*)^2 + \dots + (b^*)^d$$
  - $N$ : #nodes of the solution,
  - $d$ : depth of the solution tree.
  - E.g., A\* finds a solution at depth 5 using 52 nodes  $\Rightarrow b^* = 1.92$ .
- Good heuristics have  $b^*$  close to 1  $\Rightarrow$  large problems solved at reasonable computational cost.
- **$b^*$  quantifies search efficiency of heuristics.**

# Empirical: Factor $b^*$

- **Aim**: Compare  $h_1$  and  $h_2$  regarding the search efficiency.
- **Setting**: Generate 1200 random problems with  $d = \{2, \dots, 24\}$  and solve them with IDS and A\* with  $h_1$  &  $h_2$ .
- **Note**: IDS – a baseline.

# Empirical: Factor $b^*$

	Search Cost (nodes generated)			Effective Branching Factor		
$d$	IDS	$A^*(h_1)$	$A^*(h_2)$	IDS	$A^*(h_1)$	$A^*(h_2)$
2	10	6	6	2.45	1.79	1.79
4	112	13	12	2.87	1.48	1.45
6	680	20	18	2.73	1.34	1.30
8	6384	39	25	2.80	1.33	1.24
10	47127	93	39	2.79	1.38	1.22
12	3644035	227	73	2.78	1.42	1.24
14	–	539	113	–	1.44	1.23
16	–	1301	211	–	1.45	1.25
18	–	3056	363	–	1.46	1.26
20	–	7276	676	–	1.47	1.27
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6	—	—	—	—	—	—
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10	—	—	—	—	—	—
12	—	—	—	—	—	—
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- $h_2$  is '**better**' than  $h_1$  regarding **search efficiency**.
- This **goodness** is reflected by  **$b^*$  being closer to 1**.
- A\* with  $h_2$  performs much better than IDS.

## **II. Generate Admissible Heuristics**

# We Know about Heuristics ...

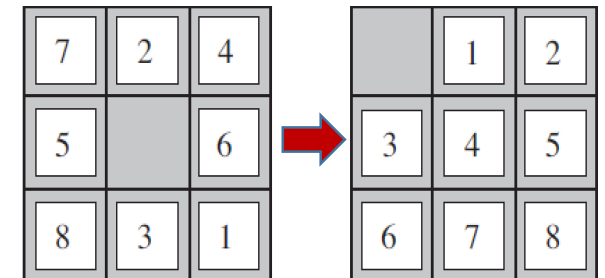
- We know:
  - How to judge their admissibility.
  - How to compare their goodness regarding searching efficiency.
- **Question:** How to produce such 'good' heuristics?

# ***(1) Generate from Relaxed Problems***

# Where are $h_{mis}$ & $h_{1stp}$ from?

For 8-puzzle problem:

- **Real Rule:** A tile can only move to the **adjacent empty** square.
- **Relaxed rules:**  $h_{mis}$  and  $h_{1stp}$  are admissible
  - R1: A tile can move **anywhere**  $\Rightarrow h_{mis}(s) = \#(\text{misplaced tiles})$ .
  - R2: A tile can move one step in **any direction** regardless of an occupied neighbour  $\Rightarrow h_{1stp}(s) = \#(1\text{-step move})$  to reach goal.
- **Optimal solutions to problems with R1, R2 are easier to find.**



# Relaxed Problem

- **Relaxed problem**: a problem with **relaxed rules** on the action.
- E.g. 8-puzzle problems with R1 and R2.
- **Theorem**: The cost of an optimal solution to **a relaxed problem** is an **admissible heuristic** for the original problem.
- No wonder  $h_{mis}$  and  $h_{1stp}$  are admissible.

## ***(2) Generate from Sub-problems***

# Subproblem

- **Subproblem**

- **Task**: get tiles 1, 2, 3 and 4 into their correct positions.
- **Relaxation**: move them disregarding the others.

- **Theory**:  $\text{cost}^*(\text{subproblem}) < \text{cost}^*(\text{original})$ .

- $\text{cost}^*(\text{subproblem})$ : the cost of the optimal solution of this subproblem.

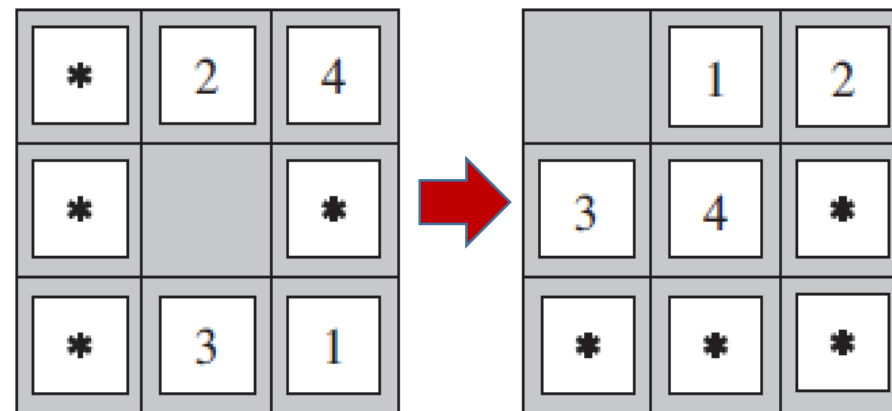


Fig.1. A subproblem of 8-puzzle.



# Subproblem and Admissible Heuristics

- **Admissible  $h_{sub}^*(s)$** : estimate the cost from  $s$  to the subproblem goal.
  - E.g.  $h_{sub}^{(1,2,3,4)}$  is the cost to solve the 1-2-3-4 subproblem.
- **Theorem**:  $h_{sub}(s)$  dominates  $h_{1stp}(s)$ ,
  - $h_{sub}(s) = \max\{h_{sub}^{(1,2,3,4)}(s), h_{sub}^{(2,3,4,5)}(s), \dots\}$ .

# Disjoint Subproblems

- **Question:** Will the **addition of heuristics** from subproblem (1-2-3-4) and (5-6-7-8) give an **admissible heuristic**, considering the two subproblems are not overlapped?
- **Answer:** No, since they always **share some moves**.
- **Question:** What if **not count** those shared moves?
- **Answer:**  $h_{sub}^{(1,2,3,4)}(s) + h_{sub}^{(5,6,7,8)}(s) \leq c^*(s) \Rightarrow$  admissible.
  - Disjoint pattern database

## ***(3) Generate from Experiences***

# ‘Experience’ Formulation

For 8-puzzle problem:

- Solve many 8-puzzles to obtain **many examples**.
- Each **example** consists of a state from the solution path and the actual cost of the solution from that point.
- These **examples** are our ‘**experience**’ for this problem.
- **Question**: How to learn  $h(s)$  from these **experience**?

# Learn Heuristics from Experience

- **Question:** What are the **good experience features**?
- **Answer:** **Relevant** to predicting the states' cost to Goal, e.g.
  - $x_1(s)$ : #(displaced tiles).
  - $x_2(s)$ : #(pairs of adjacent tiles) that are not adjacent in Goal state.
- **Question:** How to learn  $h$  from those **relevant experience features**?
- **Answer:** (e.g.) Construct model as

$$h(s) = w_1 x_1(s) + w_2 x_2(s),$$

where  $w_1, w_2$  are model parameters to learn from training data by a learning method such as neural networks and decision trees.