基于图形处理器的并行计算及CUDA编程

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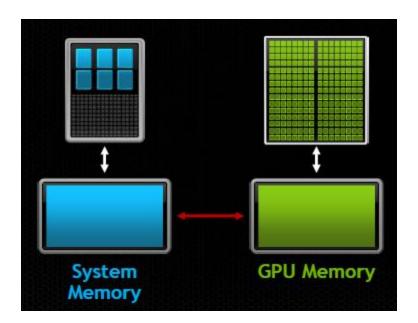
Recent Release

- Unified memory
- Dynamic parallelism
- Hyper-Q

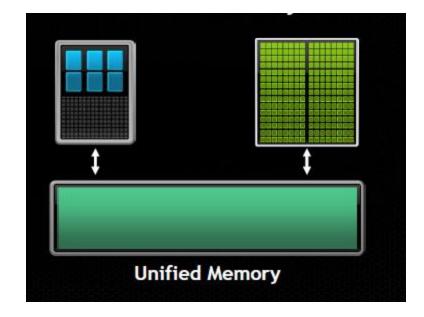
Unified Memory (Capability 2.0+, CUDA 6+)

A single address space is used for the host and all the devices

Developer view without unified memory



Developer view with unified memory



```
global__ void AplusB( int *ret, int a, int b) {
   ret[threadIdx.x] = a + b + threadIdx.x;
int main() {
   int *ret;
   cudaMalloc(&ret, 1000 * sizeof(int));
   AplusB<<< 1, 1000 >>>(ret, 10, 100);
   int *host_ret = (int *)malloc(1000 * sizeof(int));
   cudaMemcpy(host_ret, ret, 1000 * sizeof(int),
                 cudaMemcpyDeviceToHost);
   for(int i=0; i<1000; i++)
       printf("%d: A+B = %d\n", i, host_ret[i]);
   free(host_ret);
   cudaFree(ret);
    return 0;
```

Program written without use of unified memory

```
global__ void AplusB(int *ret, int a, int b) {
    ret[threadIdx.x] = a + b + threadIdx.x;
int main() {
   int *ret;
   cudaMallocManaged(&ret, 1000 * sizeof(int));
   AplusB<<< 1, 1000 >>>(ret, 10, 100);
   cudaDeviceSynchronize();
   for(int i=0; i<1000; i++)
      printf("%d: A+B = %d\n", i, ret[i]);
   cudaFree(ret);
   return 0;
```

Program written with use of unified memory (use cudaMallocManaged() routine)

```
_device___ __managed___ int ret[1000];
  global___ void AplusB(int a, int b) {
   ret[threadIdx.x] = a + b + threadIdx.x;
int main() {
   AplusB<<< 1, 1000 >>>(10, 100);
   cudaDeviceSynchronize();
   for(int i=0; i<1000; i++)
      printf("%d: A+B = %d\n", i, ret[i]);
   return 0;
```

Program written with use of unified memory (use direct reference of a GPU-declared __managed_variable)

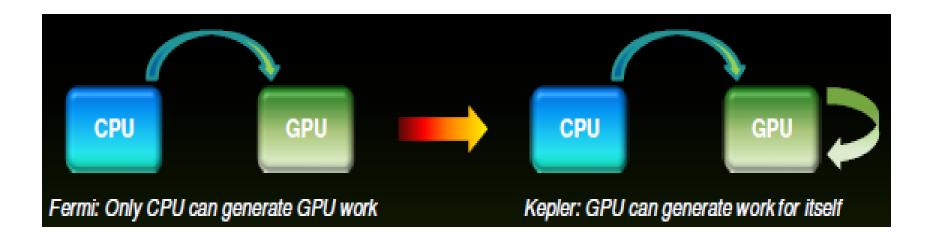
- __managed__ qualifier
- A variable that can be directly referenced from host code

- Simpler programming & memory model
 - Single pointer to data, accessible anywhere
 - Tight language integration
 - Greatly simplifies code porting
- Performance through data locality
 - Migrate data to accessing processor
 - Guarantee global coherency
 - Overlap data transfer with kernel execution

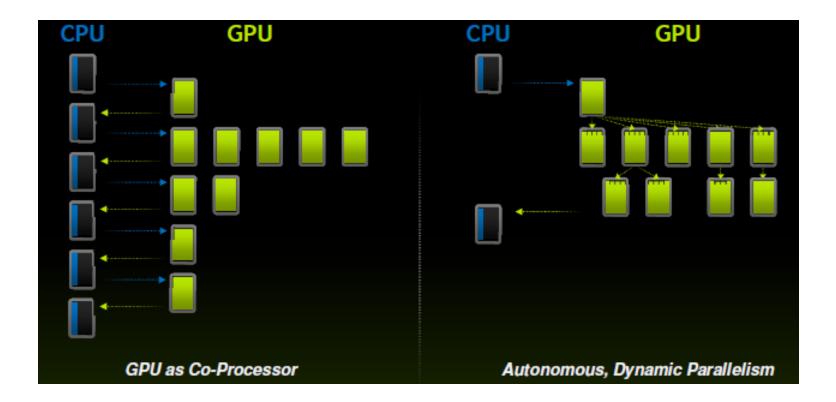
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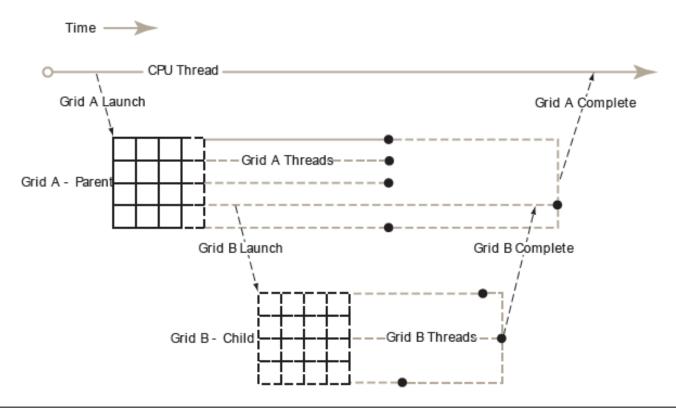
- Launch new grids from the GPU
 - Dynamically
 - Simultaneously
 - Independently



Reduce the need to transfer execution control and data between host and device



- Parent-Child launch nesting
 - The runtime guarantees an implicit synchronization between the parent and the child



- Parent and child grids share the same global and constant memory storage
- Parent and child grids have distinct local and shared memory
- All the device-side kernel launches are asynchronous with the launching thread
- Restrictions and limitations
 - Memory is reserved by the device runtime system for saving parent-grid state, tracking pending and launches
 - The max nesting depth is 24
 - The device runtime invokes malloc() and free() to allocate space for device-side launched kernels

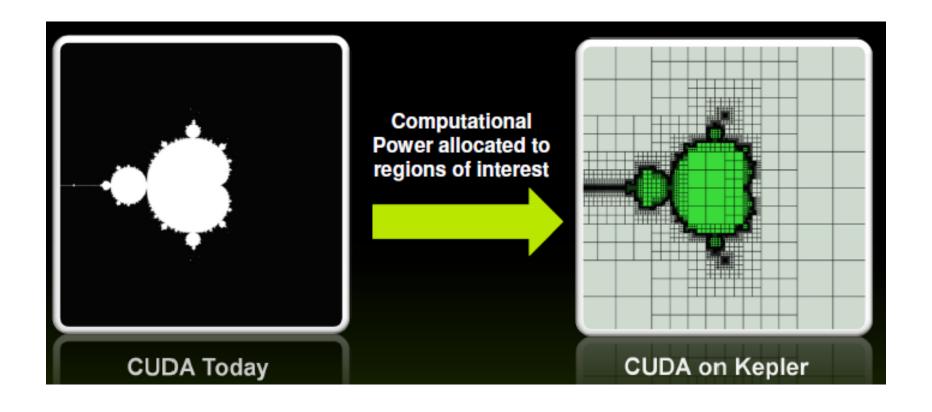
Program with Dynamic Parallelism

```
global__ void child_launch (int *data) {
   data[threadldx.x] = data[threadldx.x]+1;
  global__ void parent_launch (int *data) {
   data[threadldx.x] = threadldx.x;
    _syncthreads();
   if (threadIdx.x == 0) {
      child_launch<<< 1, 256 >>>(data);
      cudaDeviceSynchronize();
     _syncthreads();
void host_launch(int *data) {
   parent_launch<<< 1, 256 >>>(data);
```

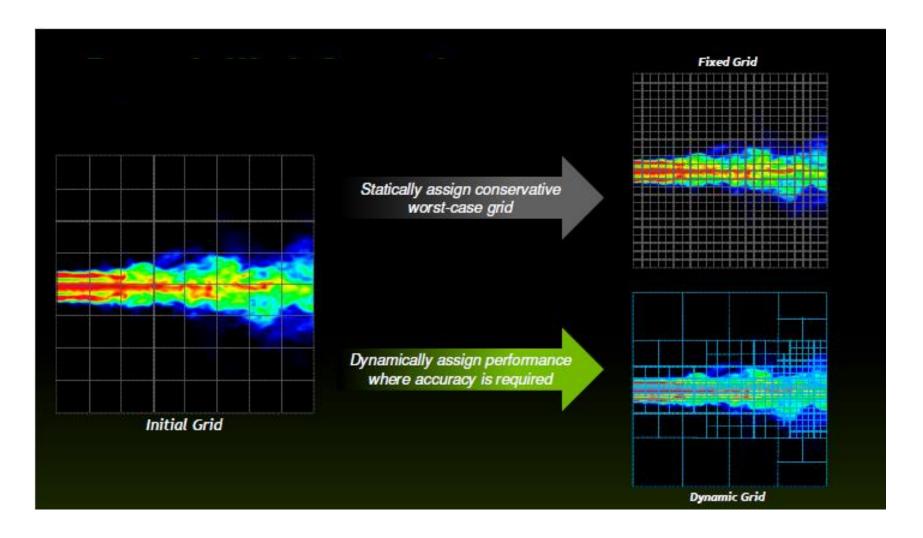
Program with Dynamic Parallelism

```
_global___ void permute (int n, int *data) {
   extern __shared__ int smem[];
   if (n <= 1)
      return;
   smem[threadIdx.x] = data[threadIdx.x];
   __syncthreads();
   permute_data(smem, n);
   __syncthreads();
   data[threadldx.x] = smem[threadldx.x];
                                                         // Write back to GMEM
                                                         since we can't pass
   __syncthreads();
                                                         SMEM to children.
   if (threadIdx.x == 0) {
      permute <<< 1, 256, n/2*size of (int) >>> (n/2, data);
      permute <<<1, 256, n/2*size of (int) >>> (n/2, data+n/2);
void host_launch (int *data) {
   permute <<< 1, 256, 256*sizeof(int) >>>(256, data);
                                                                         14
```

Data-Dependent Parallelism



Dynamic Work Generation

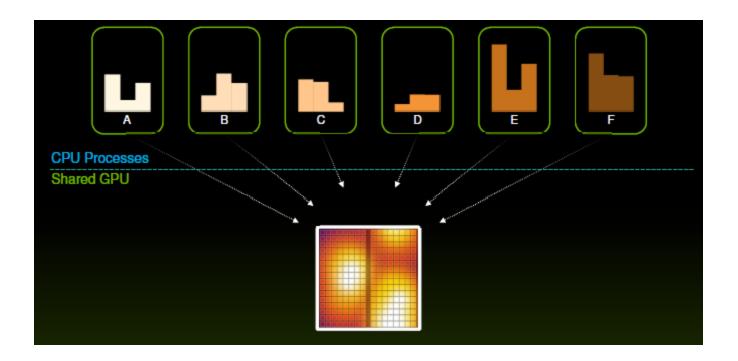


Recent Release

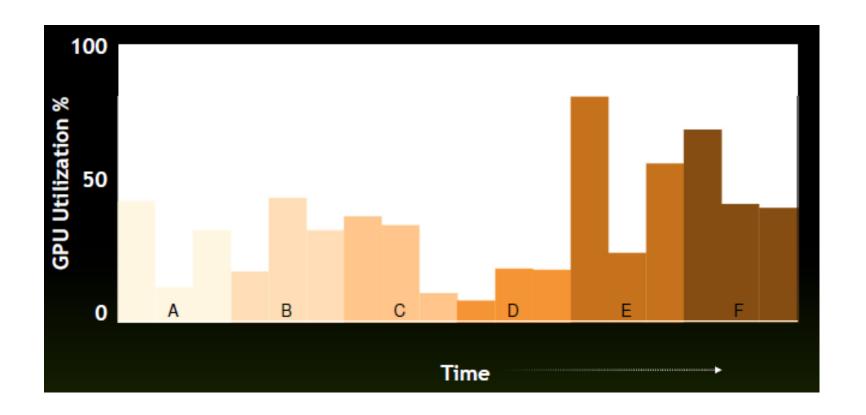
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Hyper-Q: Simultaneous Multiprocess

- Enable multiple CPU threads or processes to launch work on a single GPU simultaneously
 - Increase GPU utilization
 - Reduce CPU idle time



Without Hyper-Q



With Hyper-Q

