



ELEC3441 HW1

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Part A

A.1 Iron Law

A.1.1 ✓

Accodring to the definition of Cycle Per Instruction(CPI),

$$CPI = \frac{CycleCount}{InstructionCount}$$

while according to the diagram provided:

- **program P:**

- processor A

$$CPI = \frac{1000000 \times 1 + 300000 \times 4 + 500000 \times 20}{1000000 + 300000 + 500000} = \frac{12200000}{1800000} = 6.7778$$

- processor B

$$CPI = \frac{1000000 \times 1 + 300000 \times 20 + 500000 \times 12}{1000000 + 300000 + 500000} = \frac{13000000}{1800000} = 7.2222$$

- **program Q:**

- processor A

$$CPI = \frac{500000 \times 1 + 250000 \times 4 + 125000 \times 20}{500000 + 250000 + 125000} = \frac{4000000}{875000} = 4.5714$$

- processor B

$$CPI = \frac{500000 \times 1 + 250000 \times 20 + 125000 \times 12}{500000 + 250000 + 125000} = \frac{7000000}{875000} = 8$$

- **program R:**

- processor A

$$CPI = \frac{1000 \times 1 + 3000 \times 4 + 2000 \times 20}{1000 + 3000 + 2000} = \frac{53000}{6000} = 8.8333$$

- processor B

$$CPI = \frac{1000 \times 1 + 3000 \times 20 + 2000 \times 12}{1000 + 3000 + 2000} = \frac{85000}{6000} = 14.1667$$

A.1.2 ✓

Accodring to the definition of CPU time,

$CPU\ time_{B,P} = Count\ of\ cycles \times clock\ period$

For processor A, it runs at 1.5 GHz, which has the clock period of $\frac{1}{1.5 \times 10^9} = 6.667 \times 10^{-10}$

For processor B, it runs at 1.2 GHz, which has the clock period of $\frac{1}{1.2 \times 10^9} = 8.333 \times 10^{-10}$

- **For program P**

$$CPU\ time_{A,P} = (1000000 \times 1 + 300000 \times 4 + 500000 \times 20) \times 6.67 \times 10^{-10} = 8.13ms$$

$$CPU\ time_{B,P} = (1000000 \times 1 + 300000 \times 20 + 500000 \times 12) \times 8.83 \times 10^{-10} = 10.83ms$$

Therefore, $\frac{CPUTime_{B,P}}{CPUTime_{A,P}} = 1.332$. Processor A is 1.332× faster than processor B.

- **For program Q**

$$CPU\ time_{A,Q} = (500000 \times 1 + 250000 \times 4 + 125000 \times 20) \times 6.67 \times 10^{-10} = 2.667ms$$

$$CPU\ time_{B,Q} = (500000 \times 1 + 250000 \times 20 + 125000 \times 12) \times 8.83 \times 10^{-10} = 5.833ms$$

Therefore, $\frac{CPUTime_{B,P}}{CPUTime_{A,P}} = 2.188$. Processor A is 2.188× faster than processor B.

- **For program R**

$$CPU\ time_{A,R} = (1000 \times 1 + 3000 \times 4 + 2000 \times 20) \times 6.67 \times 10^{-8} = 0.035ms$$

$$CPU\ time_{B,R} = (1000 \times 1 + 3000 \times 20 + 2000 \times 12) \times 8.83 \times 10^{-8} = 0.071ms$$

Therefore, $\frac{CPUTime_{B,P}}{CPUTime_{A,P}} = 2.005$. Processor A is 2.005× faster than processor B.

A.1.3

- When considering the total runtime of these 3 programs on processor A and B, for the geometric mean:

$$Average(geometricmean_A) = (8.13 \times 2.667 \times 0.035)^{\frac{1}{3}} = 0.912,$$

$$Average(geometricmean_B) = (10.83 \times 5.833 \times 0.071)^{\frac{1}{3}} = 1.649$$

A is $\frac{1.649}{0.912} = 1.808$ times faster.

A.1.4

Consider the total runtime of these 3 programs on processor A and B:

$$CPUTime_{A,total} = CPUTime_{A,P} + CPUTime_{A,Q} + CPUTime_{A,R} = 10.832ms$$

$$CPUTime_{B,total} = CPUTime_{B,P} + CPUTime_{B,Q} + CPUTime_{B,R} = 16.734ms$$

Processor A is faster than processor B when considering the whole running time, which indicates we should improve on processor B. For processor B, the number of cycles spent on each class of instruction are:

ALU	Branch/Jumps	Load/Store
1501000	11060000	7524000

According to Amdahl's law, $speedup = \frac{1}{(1-P) + \frac{P}{S}}$, we should try to improve the performance of Branch/Jumps instructions. Assuming the Branch/Jumps instruction can be infinitely fast, the the maximum speed up should be: $\frac{1501000+11060000+7524000}{1501000+7524000} = \frac{20085000}{9025000} = 2.225$

A.1.5

In this case, we should focus on the instruction type that has the highest CPI on the slower processor, since reducing its cycle time will have the largest impact on the overall performance of the processor.

In this case, the CPI for Branch/Jumps instructions is the highest on processor B (20 cycles per instruction) compared to processor A (4 cycles per instruction).

Therefore, improving the cycle time of Branch/Jumps instructions on processor B would have the largest impact on the overall performance of the processor

A.2 Benchmark Performance

A.2.1 ✓

1. Arithmetic mean of raw CPU time:
 $A : 46666.667$
 $B : 46666.667$
 $C : 46666.667$
2. Geometric mean of raw CPU time:
 $A : 40000.000$
 $B : 40000.000$
 $C : 40000.000$
3. Arithmetic mean of normalized CPU time:
 $A : 1.0$
 $B : 1.417$
 $C : 1.667$
4. Geometric Mean of Normalized CPU Time:
 $A : 1.0$
 $B : 1.0$
 $C : 1.0$
5. Total raw CPU time:
 $A : 140000$
 $B : 140000$
 $C : 140000$
6. Total normalized CPU time:
 $A : 3.0$
 $B : 4.25$
 $C : 5.0$

A.2.2 ✓

1. When considering about metrics (1),(2),(4),(5), all the processors are equally fast.
When considering about metrics (3),(6), processor A is the fastest.
2. (1),(2),(4),(5)
3. For fair comparison, arithmetic mean has the limitation, thus metric (2) and (4) should be used.

A.2.3

1. Arithmetic mean of raw CPU time:
 $A : 35300$
 $B : 35600$
 $C : 35150$
2. Geometric mean of raw CPU time:
 $A : 16647.166$
 $B : 19796.928$
 $C : 13998.542$
3. Arithmetic mean of normalized CPU time:
 $A : 1.0$
 $B : 1.563$
 $C : 1.375$
4. Geometric Mean of Normalized CPU Time:
 $A : 1.0$
 $B : 1.189$
 $C : 0.841$
5. Total raw CPU time:
 $A : 141200$
 $B : 142400$
 $C : 140600$
6. Total normalized CPU time:
 $A : 4.0$
 $B : 6.25$
 $C : 5.5$

Metrics (1),(2),(4),(5) shows C is the fastest. When considering about (3) and (6), A is the second and overall B is the slowest one.

A.2.4

Consider only P1 to P3 and P5:

1. Arithmetic mean of raw CPU time:
 $A : 3035000$
 $B : 6035000$
 $C : 1535000$

2. Geometric mean of raw CPU time:
 $A : 166471.658$
 $B : 197969.280$
 $C : 139985.420$
3. Arithmetic mean of normalized CPU time:
 $A : 1.0$
 $B : 1.563$
 $C : 1.375$
4. Geometric Mean of Normalized CPU Time:
 $A : 1.0$
 $B : 1.189$
 $C : 0.841$
5. Total raw CPU time:
 $A : 12140000$
 $B : 24140000$
 $C : 6140000$
6. Total normalized CPU time:
 $A : 4.0$
 $B : 6.25$
 $C : 5.5$

Metrics (1),(2),(4),(5) remain the conclusion, while C is the second one in (3) and (6), it's still the fastest one.

A.2.5

I would like to use the metric (2).

It's possible if t_A, t_B, t_C of P6 equals to `[1000000000, 1, 1000000000]`, at this time,

Arithmetic Mean:

Proc.A: 168690200.0

Proc.B: 4023733.5

Proc.C: 167690100.0

Geometric Mean:

Proc.A: 311953.89391571033

Proc.B: 12428.930023815428

Proc.C: 247597.96968368735

This will make processor B the fastest.

A.3 RISC-V Assembly Programming¹

A.3.1 Arithmetic and logic operations²

- $z = z + (x - (y \ll 1))$

```
slli a1, a1, 1 // Shift y left by 1 bit, equivalent to y*2
sub t0, a0, a1 // Subtract result from x
add a2, a2, t0 // Add the result to z
```

- $y = x + 0x757$

```
addi a1, a0, 0x757
```

- $y = x + 0x7800A757$

```
lui t0, 07800A
addi t0, t0, 0xA
add a1, a0, t0
```

- $a[3] = a[2] + 1$

```
// since each int is 4 bytes
lw t0, 8(a3) // Load word from array index 2 (offset by 8 bytes)
addi t0, t0, 1 // Add 1 to the value
sw t0, 12(a3) // Store word to array index 3 (offset by 12 bytes)
```

- $a[x \& 0xF] = y \% 16$ (Assume a size less than 4byte counts as 4byte, a[16] is an array of ints)

```
andi t0, a0, 0xF // And x with 0xF
slli t0, t0, 2 // Multiply the result by 4 to get the byte offset
add t0, t0, a3 // Add the base address of the array to the offset
andi t1, a1, 0xF // y % 16 is equivalent to y & 0xF
sw t1, 0(t0) // Store the result at the computed address
```

- $z = 4*y + 2*x$


```
slli a2, a1, 2      // Shift y left by 2 bits
slli t0, a0, 1      // Shift x left by 1 bit
add a2, a2, t0       // Add
```

A.3.2 Branches and Jumps

- if-else

```
# if (x > y) then z = x - y else z = y - x

        bge a1, a0, ELSE      # jump if y>=x
        sub a2, a0, a1        # x-y
        j    END

ELSE:    sub a2, a1, a0        # y-x
END:     nop
```

- Nested Conditional if-else

```
# if (x < y && x > z) {

        # jump if any of condition not satisfied
        bgeu a0, a1, END      # x>=y
        bgeu a2, a0, END      # z>=x

        slli t0, a0, 2        # calculate the address offset
        add t0, t0, a3        # compute address
        lw t1, 0(t0)          # load a[x] in t1
        add a0, a0, t1        # a[x]+x
END:     add t0, a1, a2        # y+z
        add a0, a0, t0        # x+(y+z)
```

- For-loop

```

# for (x = 0; x < 10; x++)
    addi a0, zero, 0      # initialize x to 0
    addi t0, zero, 10

FOR:  bge a0, t0, END      # end if x>=10
      slli t1, a0, 2      # calculate the address offset
      add  t1, t1, a3      # compute address
      sw   a0, 0(t1)      # store the value of a0 at address t1

      addi a0, a0, 1 # x+=1
      j    FOR          # iteration
END:  nop

```

- While-loop

```

# x = 0;
# while(x <= 10) { a[x] = y; y++; x++; }

    addi a0, zero, 0      # initialize x to 0
    addi t0, zero, 10

FOR:  blt t0, a0, END      # end if x > 10
      slli t1, a0, 2      # calculate the address offset
      add  t1, t1, a3      # compute address
      sw   a1, 0(t1)      # store the value of a1 at address t1

      addi a1, a1, 1      # y++
      addi a0, a0, 1      # x++
      j    FOR          # iteration
END:  nop

```

A.4 Fibonacci Numbers

A.4.1 Branches and Jumps

Assume `n` is stored in `a0` and `F` is stored in `a1`

```

fib:
    sw        zero,0(a1)           # store F[0] = 0
    li        a5,1
    sw        a5,4(a1)            # store F[1] = 1
    ble       a0,a5,.L2           # base case, jump to .L2 if n <= 1

    mv        a5,a1
    slli      a2,a0,2
    add       a2,a2,a1
    addi      a2,a2,-4

.L3:                                # entrance of the loop
    lw        a4,4(a5)            # Read the value of
    lw        a3,0(a5)
    add       a4,a4,a3
    sw        a4,8(a5)
    addi      a5,a5,4
    bne       a5,a2,.L3           # Check if a5 is equal to a2; if not, continue

.L2:
    slli      a0,a0,2
    add       a1,a1,a0
    lw        a0,0(a1)            # Read the value of F[n] from a1 and store it in a0
    ret                               # return the value
.size fib, .-fib
.align 2

main:
    addi      sp,sp,-416
    sw        ra,412(sp)
    mv        a1,sp

    # load the value of n into a0, here suppose n = 10
    li        a0,10
    call      fib

    li        a0,0
    lw        ra,412(sp)
    addi      sp,sp,416

```

```
jr      ra
```

A.4.2 Recursive

Assume `n` is stored in `a0`, return value `r` in `a0`

```

.fib:
    addi sp,sp,-16      # Adjusts the stack pointer
    sw    ra,12(sp)     # Saves the return address on the stack
    sw    s0,8(sp)      # Saves the value of register s0 in the stack
    sw    s1,4(sp)      # Save the value of register s1 in the stack

    # Base Cases
    mv     s0,a0
    li     a5,2          # Load immediate count
    blt    a0,a5,.L1     # If a0 < 2, return r

    # Recurive cases
    addi   a0,a0,-1
    call   fib           # call fib(n-1)
    mv     s1,a0
    addi   a0,s0,-2
    call   fib           # call fib(n-2)
    add    a0,s1,a0

.L1: # this is the base case
    lw     ra,12(sp)
    lw     s0,8(sp)
    lw     s1,4(sp)
    addi   sp,sp,16
    jr     ra

main:
    addi   sp,sp,-16
    sw     ra,12(sp)
    li     a0,15          # suppose n=15
    call   fib
    li     a0,0
    lw     ra,12(sp)
    addi   sp,sp,16
    jr     ra

```


A.5.3 SUBLEQ RISC-V implementation

```
subleq:
    sub a1, a1, a0    # memory[b] = memory[b] - memory[a]
    bgtz a1, skip     # branch to skip if memory[b] > 0
    jalr zero, a2     # goto c
skip:
    # Continue with the rest of the program
```